```
#include <stdio.h>
#include <stdint.h>
// Filter Code Definitions
// maximum number of inputs that can be handled
// in one function call
#define MAX INPUT LEN 80
// maximum length of filter than can be handled
#define MAX FLT LEN
                     63
// buffer to hold all of the input samples
#define BUFFER LEN
                     (MAX FLT LEN - 1 + MAX INPUT LEN)
// array to hold input samples
double insamp[ BUFFER LEN ];
// FIR init
void firFloatInit( void )
   memset( insamp, 0, sizeof( insamp ) );
// the FIR filter function
void firFloat ( double *coeffs, double *input, double *output,
      int length, int filterLength )
{
                // accumulator for MACs
   double acc;
   double *coeffp; // pointer to coefficients
   double *inputp; // pointer to input samples
   int n;
   int k;
   // put the new samples at the high end of the buffer
   memcpy( &insamp[filterLength - 1], input,
           length * sizeof(double) );
   // apply the filter to each input sample
   for ( n = 0; n < length; n++ ) {
       // calculate output n
       coeffp = coeffs;
       inputp = &insamp[filterLength - 1 + n];
       acc = 0;
       for ( k = 0; k < filterLength; k++ ) {
           acc += (*coeffp++) * (*inputp--);
       output[n] = acc;
   // shift input samples back in time for next time
   memmove( &insamp[0], &insamp[length],
           (filterLength - 1) * sizeof(double) );
}
```

```
// Test program
// bandpass filter centred around 1000 Hz
// sampling rate = 8000 Hz
#define FILTER LEN 63
double coeffs[ FILTER LEN ] =
 -0.0448093, 0.0322875,
                         0.0181163,
                                     0.0087615,
                                                 0.0056797,
  0.0086685, 0.0148049,
                         0.0187190,
                                    0.0151019,
                                                 0.0027594,
 -0.0132676, -0.0232561,
                       -0.0187804,
                                    0.0006382,
                                                0.0250536,
  0.0387214, 0.0299817,
                        0.0002609,
                                    -0.0345546,
                                                -0.0525282,
 -0.0395620, 0.0000246,
                        0.0440998,
                                     0.0651867,
                                                0.0479110,
  0.0000135, -0.0508558,
                       -0.0736313,
                                    -0.0529380,
                                                -0.0000709,
  0.0540186, 0.0766746,
                       0.0540186,
                                    -0.0000709,
                                                -0.0529380,
 -0.0736313, -0.0508558,
                        0.0000135,
                                    0.0479110,
                                                0.0651867,
  0.0440998, 0.0000246, -0.0395620,
                                    -0.0525282,
                                                -0.0345546,
  0.0002609, 0.0299817,
                        0.0387214,
                                    0.0250536,
                                                0.0006382,
 -0.0187804, -0.0232561,
                       -0.0132676,
                                     0.0027594,
                                                 0.0151019,
  0.0187190, 0.0148049,
                        0.0086685,
                                     0.0056797,
                                                 0.0087615,
  0.0181163, 0.0322875,
                       -0.0448093
};
void intToFloat( int16 t *input, double *output, int length )
{
   int i;
   for ( i = 0; i < length; i++ ) {
       output[i] = (double)input[i];
   }
}
void floatToInt( double *input, int16 t *output, int length )
   int i;
   for ( i = 0; i < length; i++ ) {
       // add rounding constant
       input[i] += 0.5;
       // bound the values to 16 bits
       if (input[i] > 32767.0) {
           input[i] = 32767.0;
       } else if (input[i] < -32768.0) {
           input[i] = -32768.0;
       // convert
       output[i] = (int16 t)input[i];
   }
}
```

```
// number of samples to read per loop
#define SAMPLES
                 80
int main( void )
   int size;
   int16 t input[SAMPLES];
    int16 t output[SAMPLES];
   double floatInput[SAMPLES];
   double floatOutput[SAMPLES];
   FILE *in fid;
         *out fid;
   FILE
    // open the input waveform file
    in fid = fopen( "input.pcm", "rb" );
    if ( in fid == 0 ) {
       printf("couldn't open input.pcm");
       return;
    // open the output waveform file
    out_fid = fopen( "outputFloat.pcm", "wb" );
    if ( out fid == 0 ) {
        printf("couldn't open outputFloat.pcm");
       return;
    }
    // initialize the filter
    firFloatInit();
    // process all of the samples
   do {
        // read samples from file
        size = fread( input, sizeof(int16 t), SAMPLES, in fid );
        // convert to doubles
        intToFloat( input, floatInput, size );
        // perform the filtering
        firFloat( coeffs, floatInput, floatOutput, size,
               FILTER LEN );
        // convert to ints
        floatToInt( floatOutput, output, size );
        // write samples to file
        fwrite( output, sizeof(int16_t), size, out_fid );
    } while ( size != 0 );
    fclose( in fid );
    fclose( out fid );
   return 0;
}
```