

# Massively Parallel Task-Based Programming with HPX

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## Parallelism in C++

State of the Art

The HPX Parallel Runtime System

The Future, async and dataflow

Concepts of Parallelism

Parallel Algorithms

## Parallel Programming with HPX

The HPX Programming Model

Examples:

Fibonacci

Simple Loop Parallelization

SAXPY routine with data locality

Hello Distributed World!

Matrix Transpose

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- And many others...



# Parallelism in C++



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## State of the Art

- Modern architectures impose massive challenges on programmability in the context of performance portability
  - Massive increase in on-node parallelism
  - Deep memory hierarchies
- Only portable parallelization solution for C++ programmers (today): OpenMP and MPI
  - Hugely successful for years
  - Widely used and supported
  - Simple use for simple use cases
  - Very portable
  - Highly optimized



## The C++ Standard

- C++11 introduced lower level abstractions
  - std::thread, std::mutex, std::future, etc.
  - Fairly limited (low level), more is needed
  - C++ needs stronger support for higher-level parallelism
- New standard: C++17:
  - Parallel versions of STL algorithms (P0024R2)
- Several proposals to the Standardization Committee are accepted or under consideration
  - Technical Specification: Concurrency (N4577)
  - Other proposals: Coroutines (P0057R2), task blocks (N4411), executors (P0058R1)



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## The C++ Standard – Our Vision

Currently there is no overarching vision related to higher-level parallelism

- Goal is to standardize a ‘big story’ by 2020
- No need for OpenMP, OpenACC, OpenCL, etc.
- This tutorial tries to show results of our take on this

## HPX – A general purpose parallel Runtime System

- Solidly based on a theoretical foundation – a well defined, new execution model (ParalleX)
- Exposes a coherent and uniform, standards-oriented API for ease of programming parallel and distributed applications.
  - Enables to write fully asynchronous code using hundreds of millions of threads.
  - Provides unified syntax and semantics for local and remote operations.
- Developed to run at any scale
- Compliant C++ Standard implementation (and more)
- Open Source: Published under the Boost Software License

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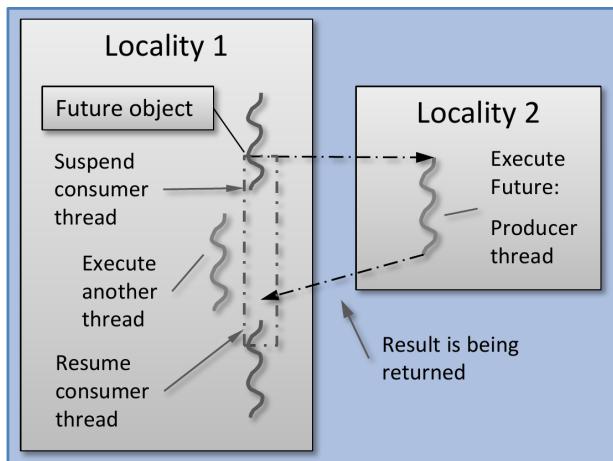
## HPX – A general purpose parallel Runtime System

HPX represents an innovative mixture of

- A global system-wide address space (AGAS - Active Global Address Space)
- Fine grain parallelism and lightweight synchronization
- Combined with implicit, work queue based, message driven computation
- Full semantic equivalence of local and remote execution, and
- Explicit support for hardware accelerators (through percolation)

## What is a (the) future

A future is an object representing a result which has not been calculated yet



- Enables transparent synchronization with producer
- Hides notion of dealing with threads
- Makes asynchrony manageable
- Allows for composition of several asynchronous operations
- Turns concurrency into parallelism

## What is a (the) future

Many ways to get hold of a future, simplest way is to use (std) `async`:

```
int universal_answer() { return 42; }
void deep_thought() {
    future<int> promised_answer
        = async(&universal_answer);
    // do other things for 7.5 million years
    cout << promised_answer.get() << endl;
    // prints 42, eventually
}
```



## Compositional facilities

Sequential composition of futures:

```
future<string> make_string() {  
    future<int> f1 =  
        async([]() -> int { return 123; });  
    future<string> f2 = f1.then(  
        [](future<int> f) -> string  
    {  
        // here .get() won't block  
        return to_string(f.get());  
    });  
    return f2;  
}
```



## Compositional facilities

### Parallel composition of futures

```
future<int> test_when_all() {
    future<int> future1 =
        async([]() -> int { return 125; });
    future<string> future2 =
        async([]() -> string { return string("hi"); });
    auto all_f = when_all(future1, future2);
    future<int> result = all_f.then(
        [](auto f) -> int {
            return do_work(f.get());
        });
    return result;
}
```

## Dataflow – The new 'async' (HPX)

- What if one or more arguments to 'async' are futures themselves?
- Normal behavior: pass futures through to function
- Extended behavior: wait for futures to become ready before invoking the function:

```
template <typename F, typename... Arg>
future<result_of_t<F(Args...)>>
// requires(is_callable<F(Arg...)>)
dataflow(F && f, Arg &&... arg);
```

- If ArgN is a future, then the invocation of F will be delayed
- Non-future arguments are passed through

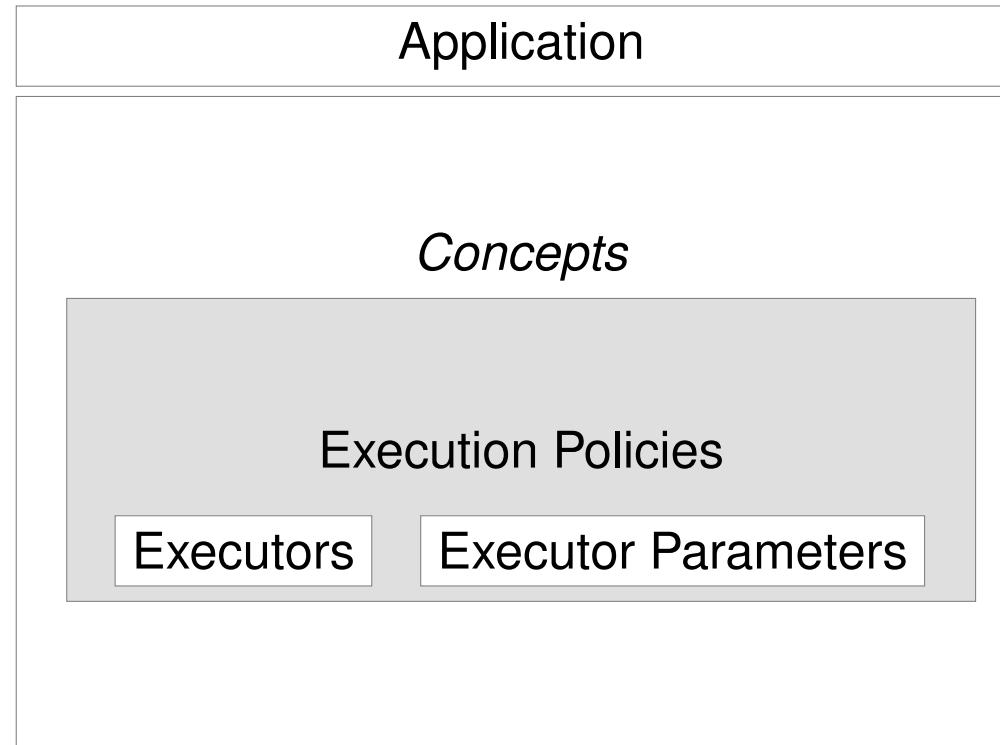
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## Concepts of Parallelism – Parallel Execution Properties

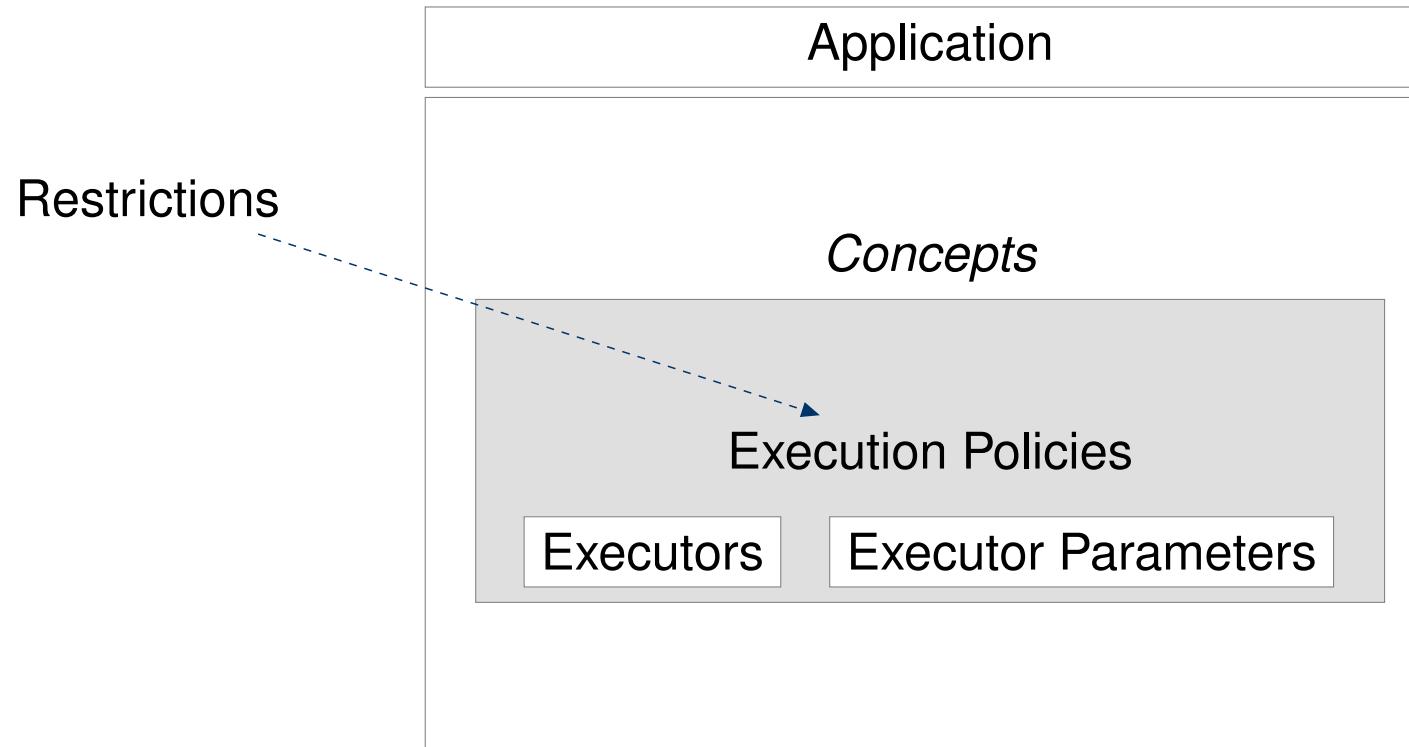
- The ***execution restrictions*** applicable for the work items
- In what ***sequence*** the work items have to be executed
- ***Where*** the work items should be executed
- The ***parameters*** of the execution environment



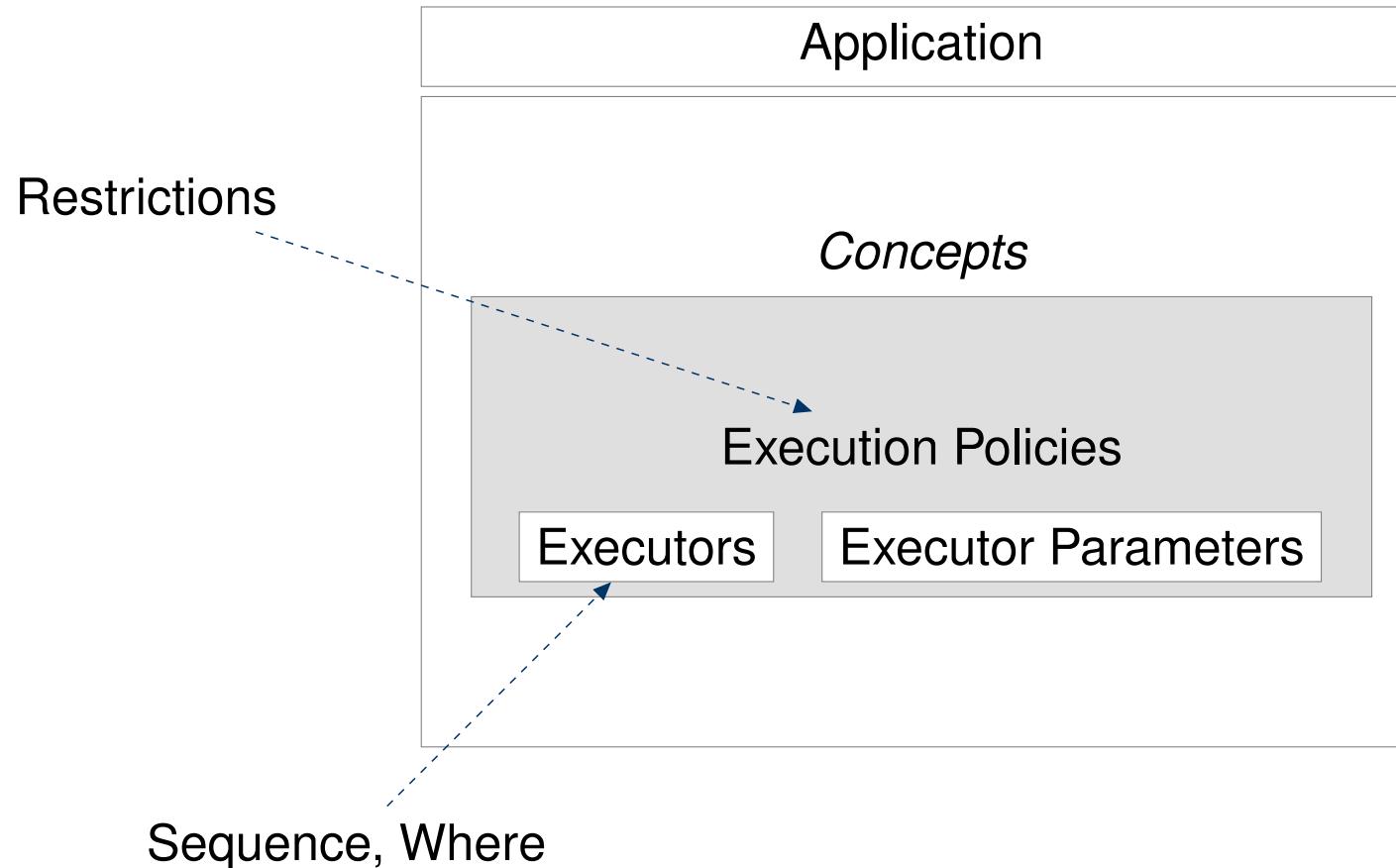
# Concepts and Types of Parallelism



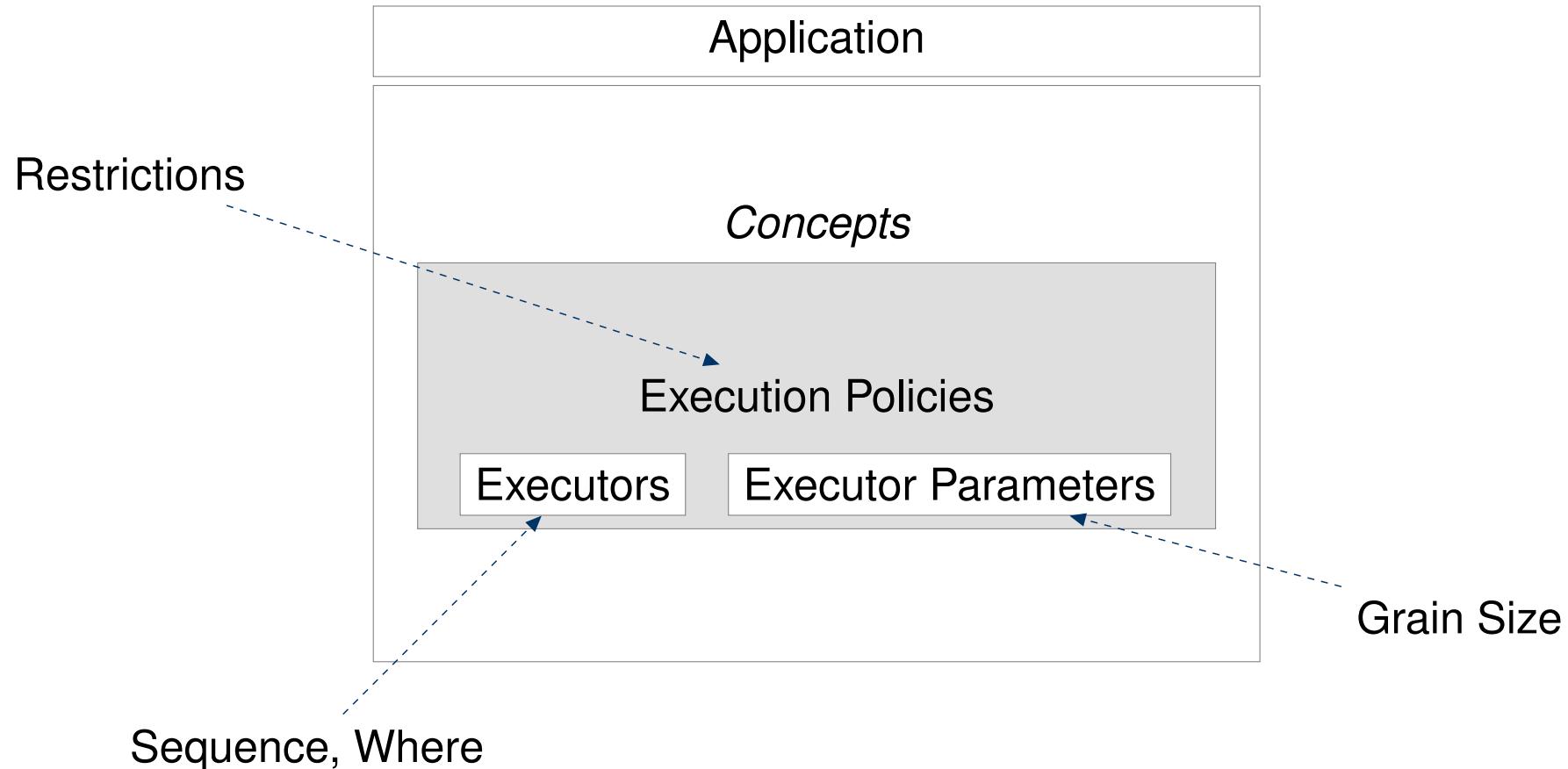
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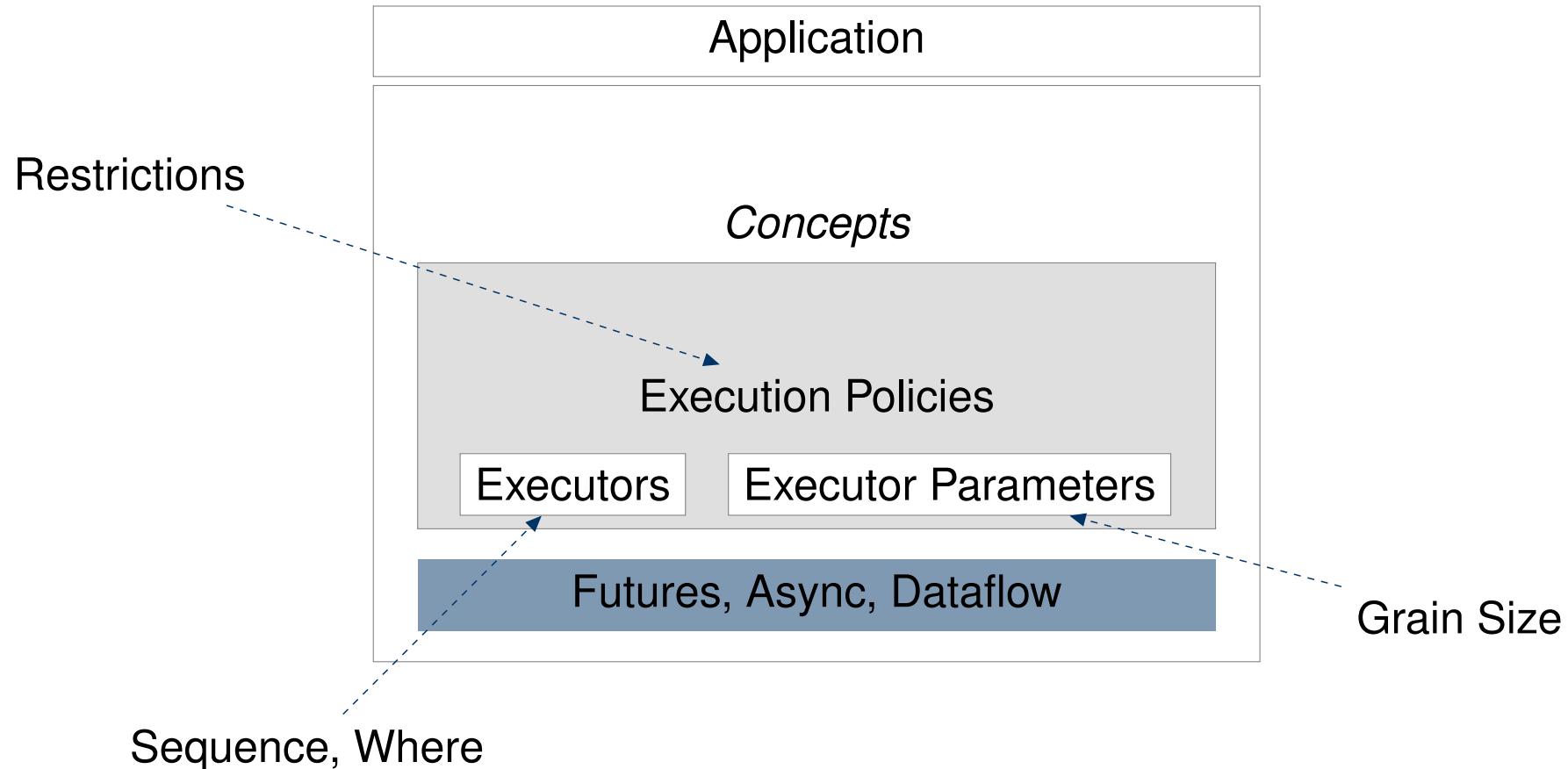
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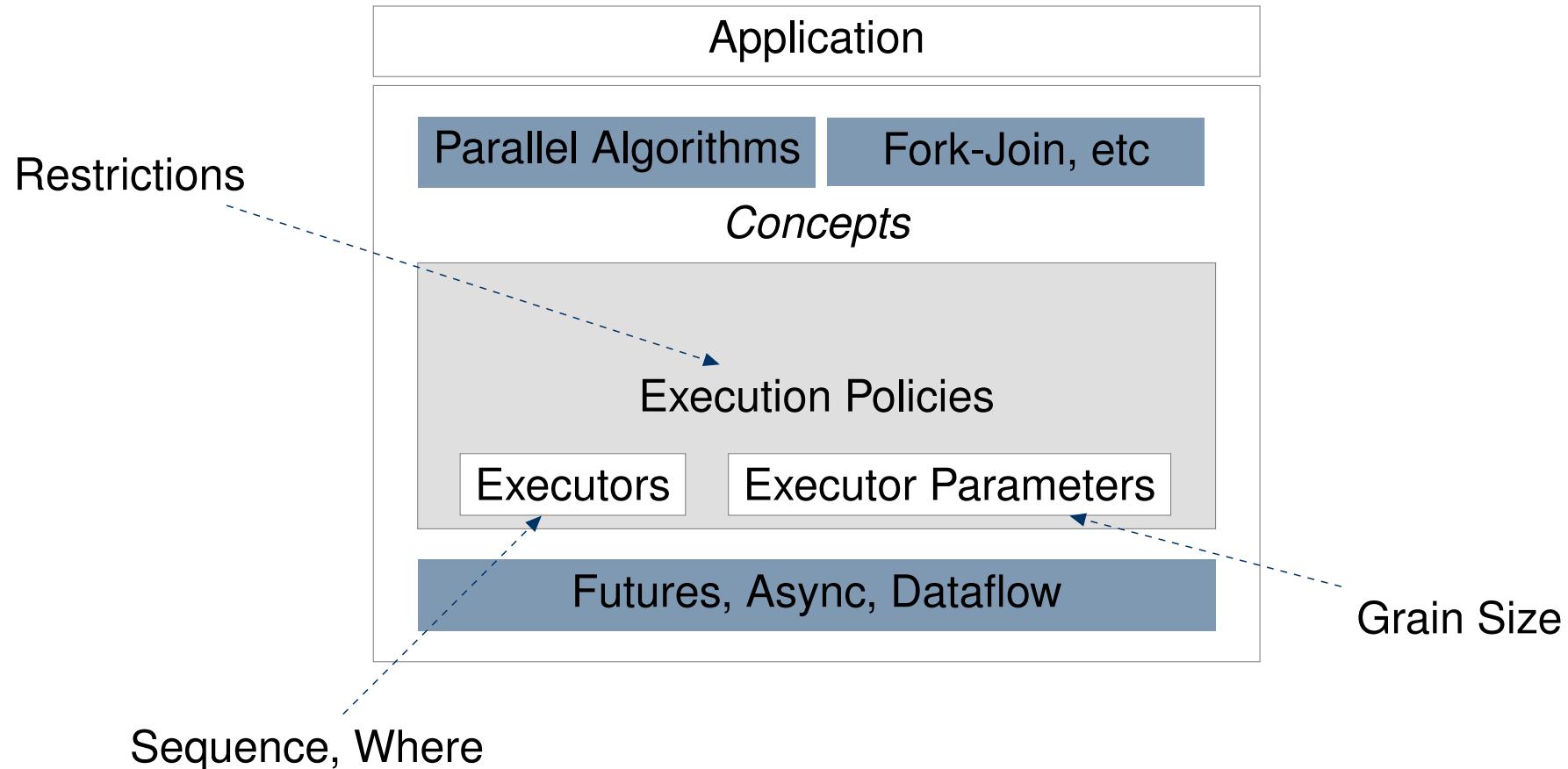
# Concepts and Types of Parallelism



# Concepts and Types of Parallelism



# Concepts and Types of Parallelism



## Execution Policies (std)

- Specify execution guarantees (in terms of thread-safety) for executed parallel tasks:
  - sequential\_execution\_policy: seq
  - parallel\_execution\_policy: par
  - parallel\_vector\_execution\_policy: par\_vec
- In parallelism TS used for parallel algorithms only

## Execution Policies (Extensions)

- Asynchronous Execution Policies:
  - `sequential_task_execution_policy`: `seq(task)`
  - `parallel_task_execution_policy`: `par(task)`
- In both cases the formerly synchronous functions return a `future<R>`
- Instruct the parallel construct to be executed asynchronously
- Allows integration with asynchronous control flow

## Executors

- Executor are objects responsible for
  - Creating execution agents on which work is performed (N4466)
  - In N4466 this is limited to parallel algorithms, here much broader use
- Abstraction of the (potentially platform-specific) mechanisms for launching work
- Responsible for defining the **Where** and **How** of the execution of tasks

## Executors

- Executors must implement one function:  
`async_execute(F&& f, Args&&... args)`
- Invocation of executors happens through `executor_traits` which exposes (emulates) additional functionality:  

```
executor_traits<my_executor_type>::  
    execute(  
        my_executor,  
        [](size_t i){ // perform task i }, n)  
    ;
```
- Four modes of invocation: single async, single sync, bulk async and bulk sync
- The async calls return a future

## Executor Examples

- sequential\_executor, parallel\_executor:
  - Default executors corresponding to par, seq
- this\_thread\_executor
- thread\_pool\_executor
  - Specify core(s) to run on (NUMA aware)
- distribution\_policy\_executor
  - Use one of HPX's (distributed) distribution policies, specify node(s) to run on
- cuda::default\_executor
  - Use for running things on GPU
- Etc.

## Execution Parameters

Allows to control the grain size of work

- i.e. amount of iterations of a parallel `for_each` run on the same thread
- Similar to OpenMP scheduling policies: `static`, `guided`, `dynamic`
- Much more fine control



## Rebind Execution Policies

Execution policies have associated default executor and default executor parameters

- par: parallel executor, static chunk size
- seq: sequential executor, no chunking
- Rebind executor and executor parameters

```
numa_executor exec;
// rebind only executor
auto policy1 = par.on(exec);
static_chunk_size param;

// rebind only executor parameter
auto policy2 = par.with(param);
// rebind both
auto policy3 = par.on(exec).with(param);
```



# Parallel Algorithms

adjacent_difference	adjacent_find	all_of	any_of
copy	copy_if	copy_n	count
count_if	equal	exclusive_scan	fill
fill_n	find	find_end	find_first_of
find_if	find_if_not	for_each	for_each_n
generate	generate_n	includes	inclusive_scan
inner_product	inplace_merge	is_heap	is_heap_until
is_partitioned	is_sorted	is_sorted_until	lexicographical_compare
max_element	merge	min_element	minmax_element
mismatch	move	none_of	nth_element
partial_sort	partial_sort_copy	partition	partition_copy
reduce	remove	remove_copy	remove_copy_if
remove_if	replace	replace_copy	replace_copy_if
replace_if	reverse	reverse_copy	rotate
rotate_copy	search	search_n	set_difference
set_intersection	set_symmetric_difference	set_union	sort
stable_partition	stable_sort	swap_ranges	transform
transform_exclusive_scan	transform_inclusive_scan	transform_reduce	uninitialized_copy
uninitialized_copy_n	uninitialized_fill	uninitialized_fill_n	unique
unique_copy			



## Parallel Algorithms

```
std::vector<int> v = { 1, 2, 3, 4, 5, 6 };  
parallel::transform(  
    parallel::par, begin(v), end(v),  
    [](int i) -> int {  
        return i + 1;  
    });  
// prints: 2,3,4,5,6,7,  
for (int i : v) std::cout << i << ", ";
```



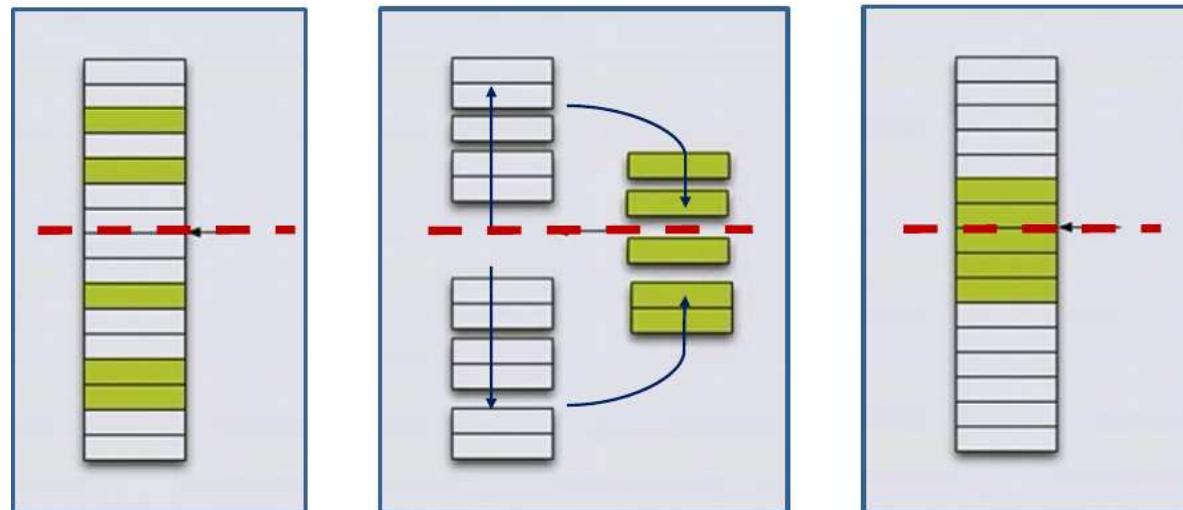
## Parallel Algorithms

```
// uses default executor: par
std::vector<double> d = { ... };
parallel::fill(par, begin(d), end(d), 0.0);
// rebind par to user-defined executor
my_executor my_exec = ...;

parallel::fill(par.on(my_exec),
    begin(d), end(d), 0.0);

// rebind par to user-defined executor and user
// defined executor parameters
my_params my_par = ...
parallel::fill(par.on(my_exec).with(my_par),
    begin(d), end(d), 0.0);
```

## Extending Parallel Algorithms



Sean Parent: C++ Seasoning, Going Native 2013



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## Extending Parallel Algorithms

```
template <typename BiIter, typename Pred>
pair<BiIter, BiIter> gather(BiIter f, BiIter l,
    BiIter p, Pred pred)
{
    BiIter it1 = stable_partition(f, p, not1(pred));
    BiIter it2 = stable_partition(p, l, pred);
    return make_pair(it1, it2);
}
```

## Extending Parallel Algorithms

```
template <typename BiIter, typename Pred>
future<pair<BiIter, BiIter>> gather_async(BiIter f,
                                              BiIter l, BiIter p, Pred pred)
{
    future<BiIter> f1 =
        parallel::stable_partition(par(task), f, p,
                                   not1(pred));
    future<BiIter> f2 =
        parallel::stable_partition(par(task), p, l,
                                   pred);
    return dataflow(
        unwrapped([](BiIter r1, BiIter r2) { return
            make_pair(r1, r2); }), f1, f2);
}
```

## Extending Parallel Algorithms (await: P0057R2)

```
template <typename BiIter, typename Pred>
future<pair<BiIter, BiIter>> gather_async(BiIter
    f, BiIter l, BiIter p, Pred pred)
{
    future<BiIter> f1 =
        parallel::stable_partition(par(task), f, p,
            not1(pred));
    future<BiIter> f2 =
        parallel::stable_partition(par(task), p, l,
            pred);
    return make_pair(await f1, await f2);
}
```

## More Information

- <https://github.com/STELLAR-GROUP/hpx>
- <http://stellar-group.org>
- <http://www.open-std.org/jtc1/sc22/wg21/docs/papers>
- <https://isocpp.org/std/the-standard>
- [hpx-users@stellar.cct.lsu.edu](mailto:hpx-users@stellar.cct.lsu.edu)
- [#STELLAR @ irc.freenode.org](#)

### Collaborations:

- FET-HPC (H2020): AllScale (<https://allscale.eu>)
- NSF: STORM (<http://storm.stellar-group.org>)
- DOE: Part of X-Stack



# Parallel Programming with HPX



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## What is HPX – A recap

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- Exposes a coherent and uniform, standards-oriented API for ease of programming parallel and distributed applications.
  - Enables to write fully asynchronous code using hundreds of millions of threads.
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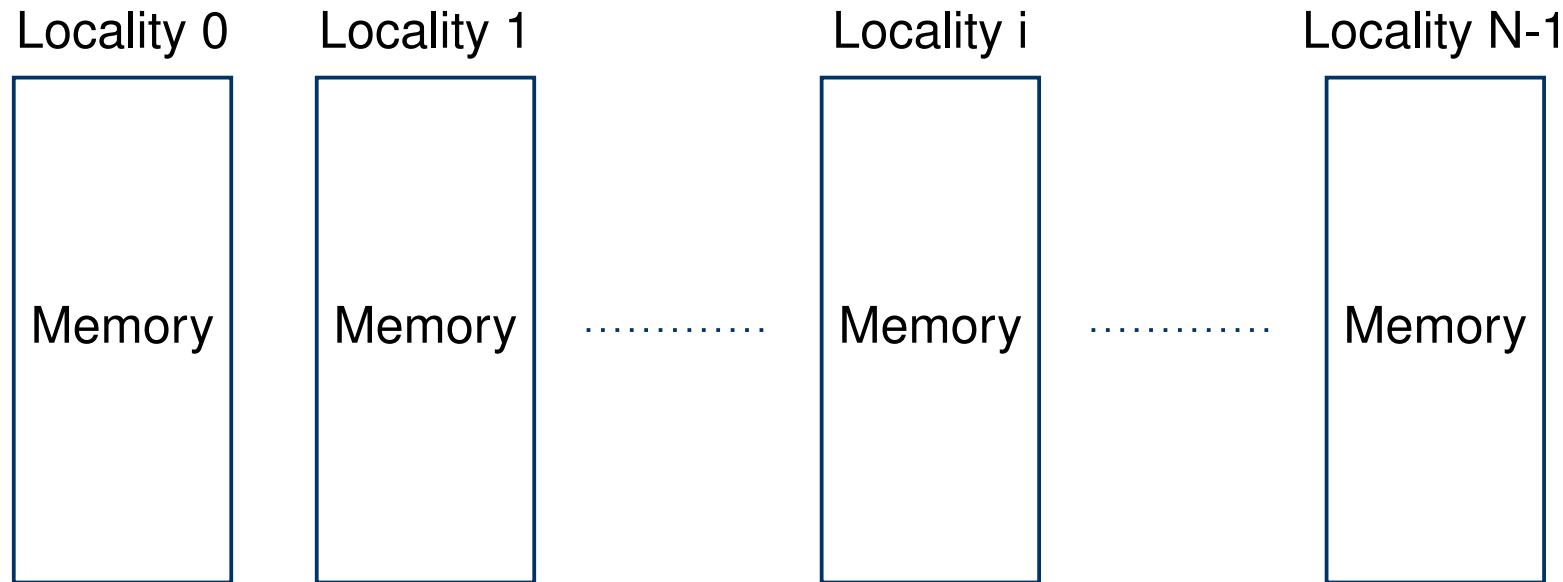
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## What is HPX – A recap

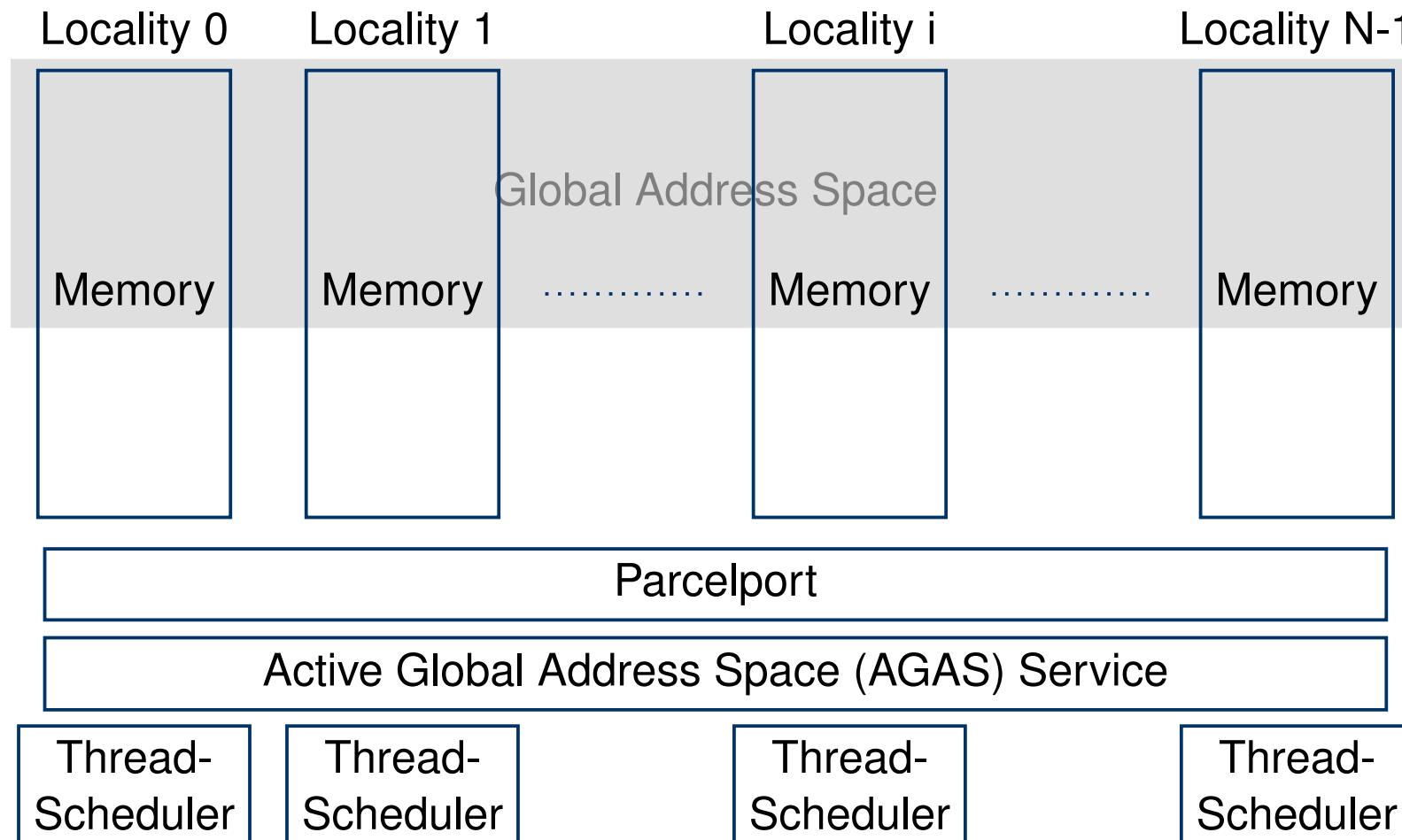
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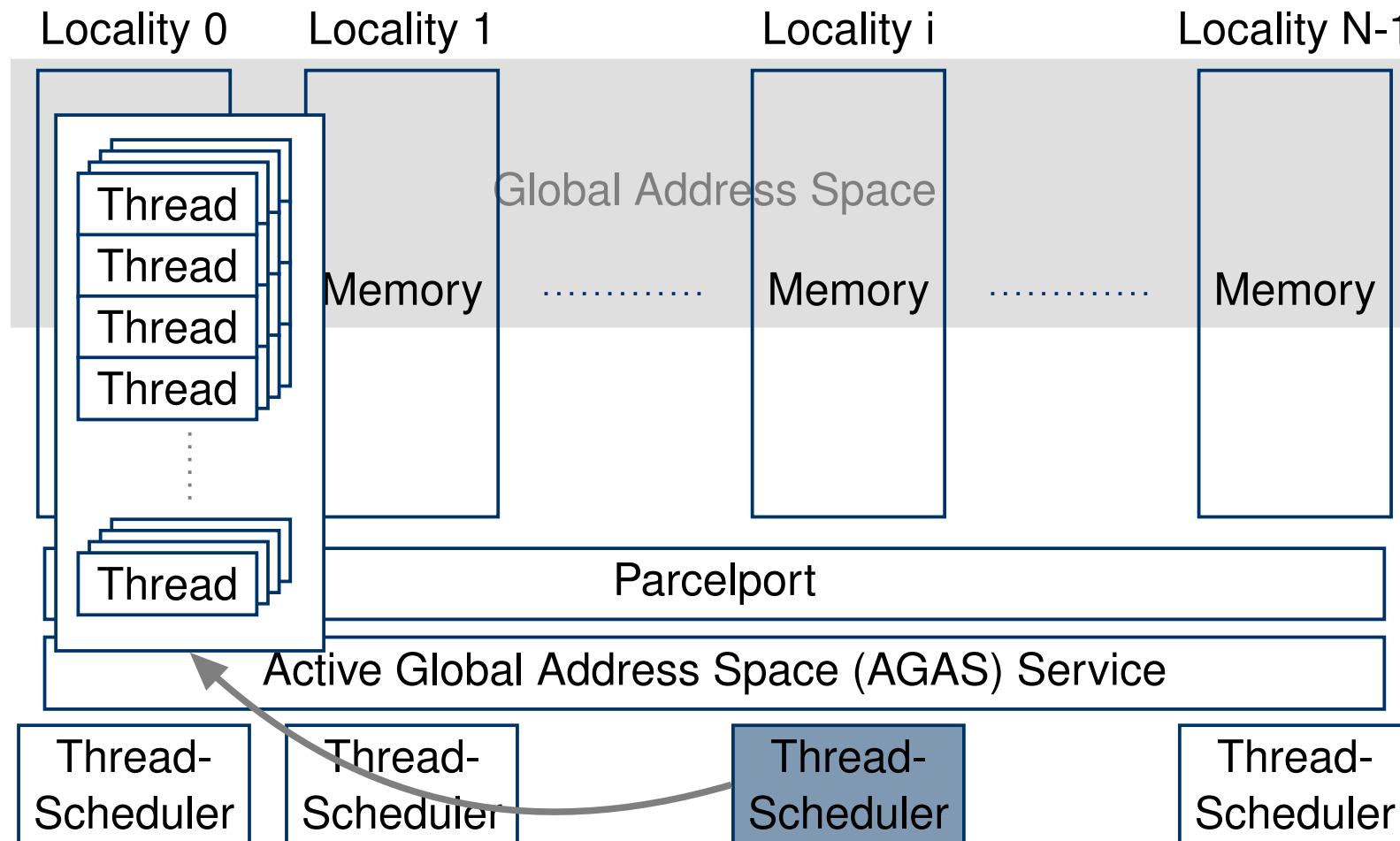
## HPX – The programming model



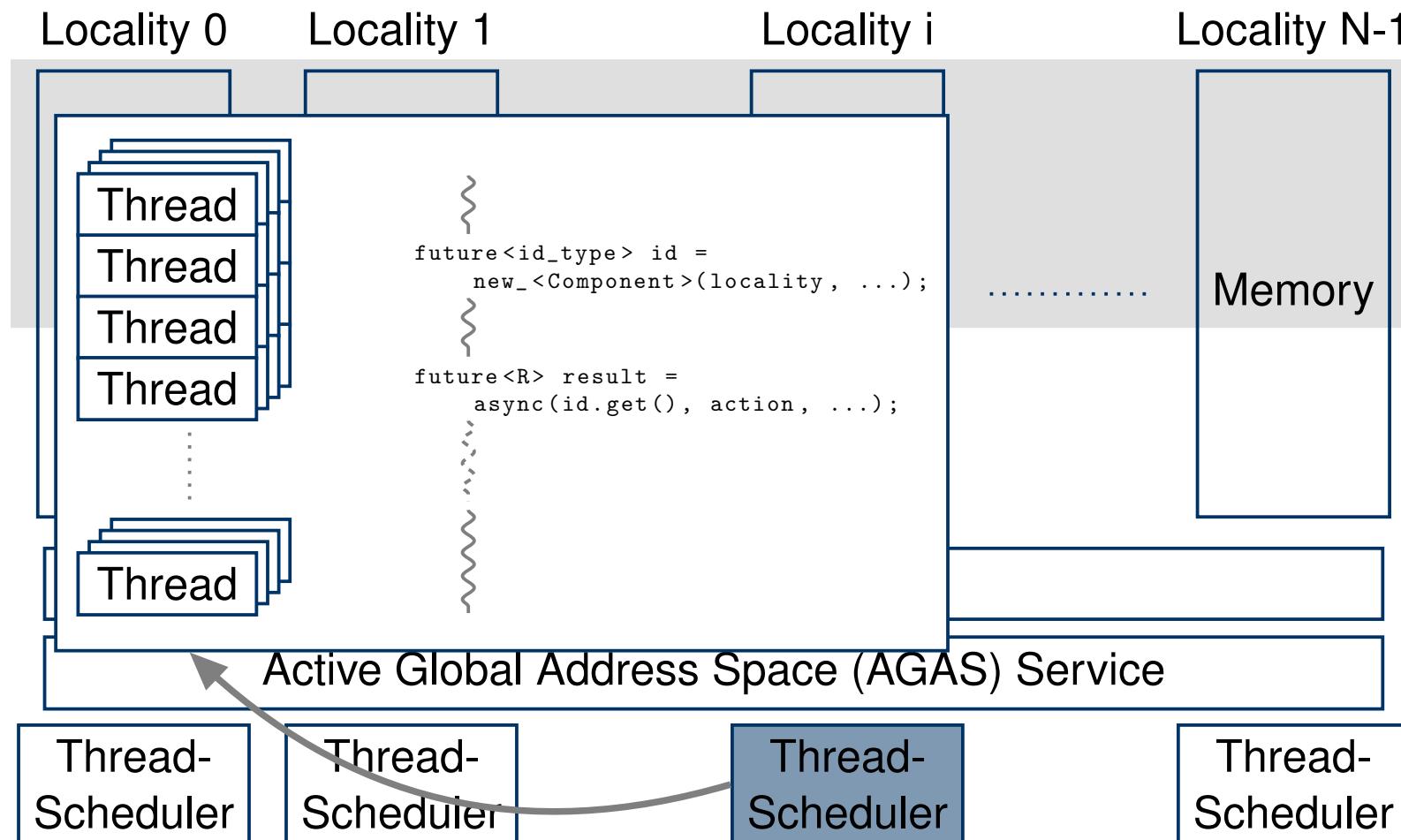
## HPX – The programming model



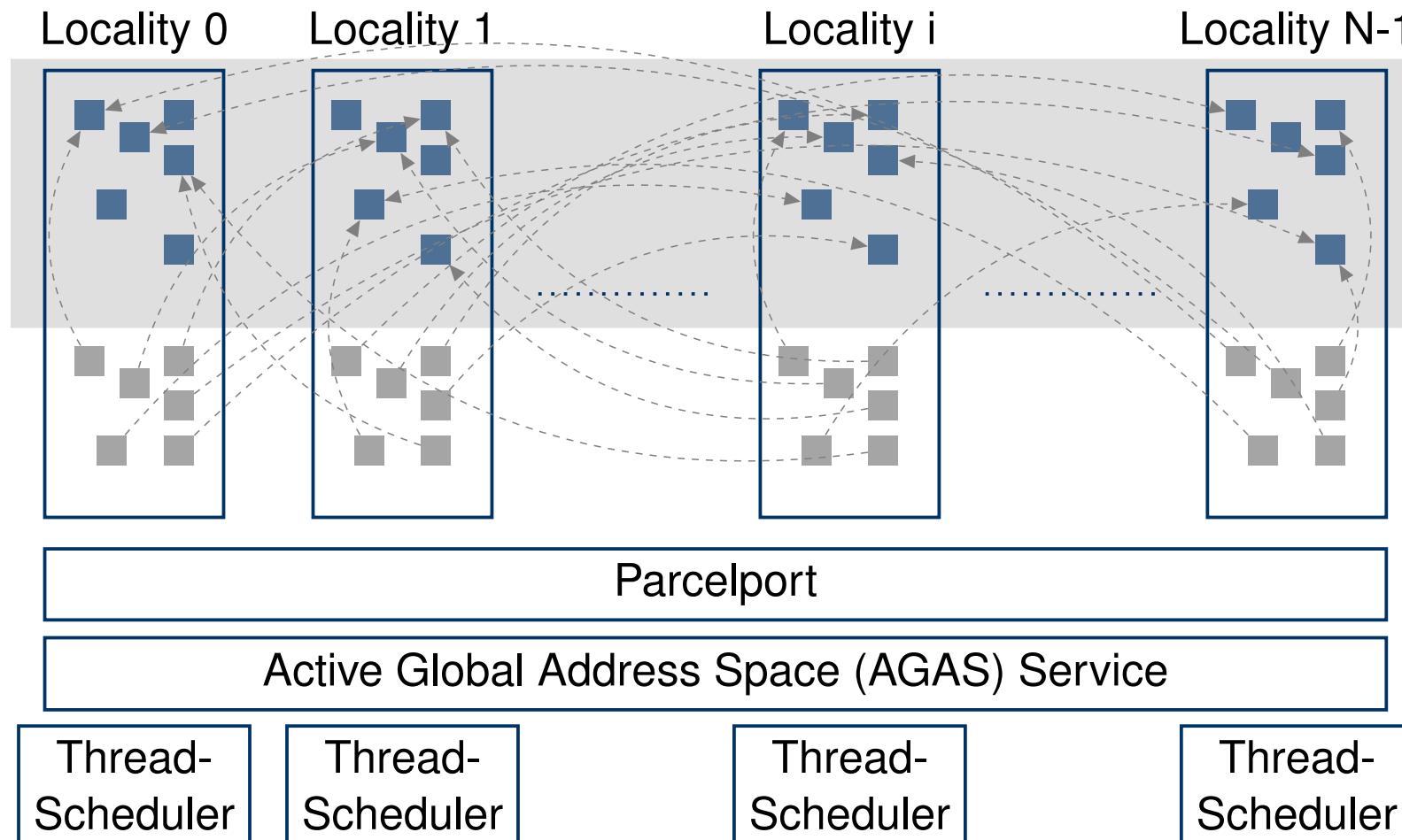
## HPX – The programming model



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## HPX – The programming model



# HPX 101 – API Overview

R f(p...)	Synchronous (returns R)	Asynchronous (returns future<R>)	Fire & Forget (returns void)
Functions (direct)	f(p...)  <b>C++</b>	async(f, p...)	apply(f, p...)
Functions (lazy)	bind(f, p...)(...)	async(bind(f, p...), ...)  <b>C++ Standard Library</b>	apply(bind(f, p...), ...)
Actions (direct)	HPX_ACTION(f, a) a()(id, p...)	HPX_ACTION(f, a) async(a(), id, p...)	HPX_ACTION(f, a) apply(a(), id, p...)
Actions (lazy)	HPX_ACTION(f, a) bind(a(), id, p...) (...)	HPX_ACTION(f, a) async(bind(a()), id, p...), ...	HPX_ACTION(f, a) apply(bind(a()), id, p...), ...

**HPX**

In Addition: `dataflow(func, f1, f2);`



---

## HPX 101 – Example

```
void hello_world(std::string msg)
{ std::cout << msg << '\n'; }
```

## HPX 101 – Example

```
void hello_world(std::string msg)
{ std::cout << msg << '\n'; }

// Asynchronously call hello_world: Returns a
// future
hpx::future<void> f1
= hpx::async(hello_world, "Hello HPX!");

// Asynchronously call hello_world: Fire &
// forget
hpx::apply(hello_world, "Forget me not!");
```



## HPX 101 – Example

```
void hello_world(std::string msg)
{ std::cout << msg << '\n'; }

// Register hello_world as an action
HPX_PLAIN_ACTION(hello_world);

// Asynchronously call hello_world_action
hpx::future<void> f2
= hpx::async(hello_world_action, hpx::
    find_here(), "Hello HPX!");
```



## HPX 101 – Future Composition

```
// Attach a Continuation to a future
future<R> ff = ...;
ff.then([](future<R> f){ do_work(f.get()) });

// All input futures become ready
hpx::when_all(...);

// N of the input futures become ready
hpx::when_some(...);

// One of the input futures become ready
hpx::when_any(...);

// Asynchronously call f after inputs are ready
hpx::future<void> f3
    = dataflow(f, ...);
```



## Fibonacci – serial

```
int fib(int n)
{
    if (n < 2) return n;
    return fib(n-1) + fib(n-2);
}
```



## Fibonacci – parallel

```
int fib(int n)
{
    if (n < 2) return n;

    future<int> fib1 = hpx::async(fib, n-1);
    future<int> fib2 = hpx::async(fib, n-2);
    return fib1.get() + fib2.get();
}
```

## Fibonacci – parallel, take 2

```
future<int> fib(int n)
{
    if(n < 2)
        return hpx::make_ready_future(n);

    if(n < 10)
        return hpx::make_ready_future(fib_serial(n));

    future<int> fib1 = hpx::async(fib, n-1);
    future<int> fib2 = hpx::async(fib, n-2);
    return
        dataflow(unwrapped([](int f1, int f2){
            return f1 + f2;
        }), fib1, fib2);
}
```

## Fibonacci – parallel, take 3

```
future<int> fib(int n)
{
    if(n < 2)
        return hpx::make_ready_future(n);

    if(n < 10)
        return hpx::make_ready_future(fib_serial(n))
    );

    future<int> fib1 = hpx::async(fib, n-1);
    future<int> fib2 = hpx::async(fib, n-2);
    return await fib1 + await fib2;
}
```

## Loop parallelization

```
// Serial version

int lo = 1;
int hi = 1000;
auto range
    = boost::irange(lo, hi);
for(int i : range)
{
    do_work(i);
}
```

## Loop parallelization

```
// Serial version           // Parallel version

int lo = 1;
int hi = 1000;
auto range
= boost::irange(lo
    , hi);
for(int i : range)
{
    do_work(i);
}

int lo = 1;
int hi = 1000;
auto range
= boost::irange(lo, hi)
;
for_each(
    par, begin(range), end(
        range),
    [](int i) {
        do_work(i);
    });
}
```

## Loop parallelization

```
// Serial version           // Task parallel version

int lo = 1;
int hi = 1000;
auto range
    = boost::irange(lo
                     , hi);
for(int i : range)
{
    do_work(i);
}

int lo = 1;
int hi = 1000;
auto range
    = boost::irange(lo, hi);
future<void> f = for_each(
    par(task), begin(range), end
    (range),
    [](int i) {
        do_work(i);
    });
other_expensive_work();
// Wait for loop to finish:
f.wait();
```



## SAXPY routine with data locality

- $a[i] = b[i] * x + c[i]$ , for  $i$  from 0 to  $N - 1$
- Using parallel algorithms
- Explicit Control over data locality
- No raw Loops



## SAXPY routine with data locality

Complete serial version:

```
std::vector<double> a = ...;
std::vector<double> b = ...;
std::vector<double> c = ...;
double x = ...;

std::transform(b.begin(), b.end(),
              c.begin(), c.end(),
              a.begin(),
              [x](double bb, double cc)
{
    return bb * x + cc;
});
```

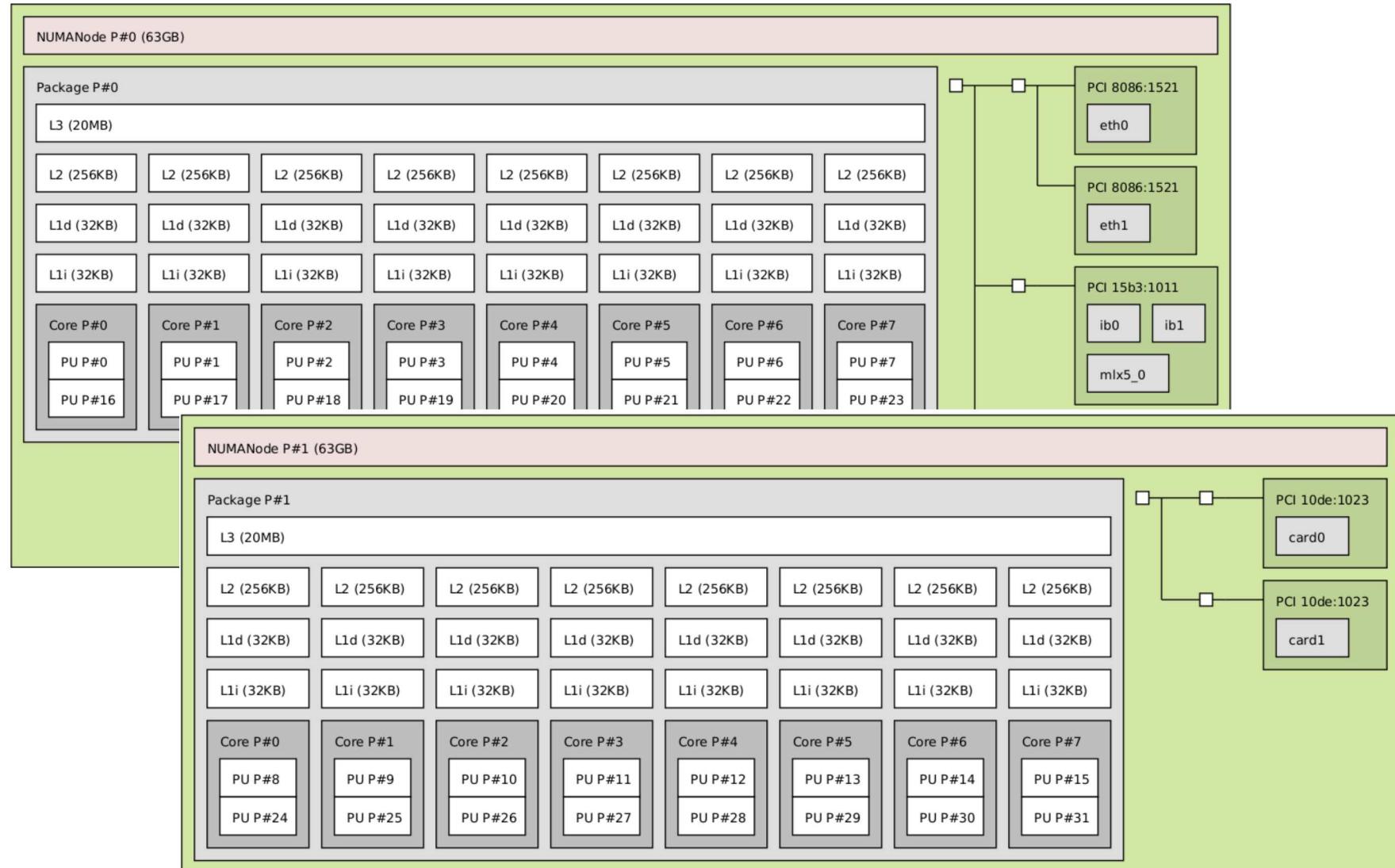


## SAXPY routine with data locality

Parallel version, no data locality:

```
std::vector<double> a = ...;
std::vector<double> b = ...;
std::vector<double> c = ...;
double x = ...;

parallel::transform(parallel::par,
    b.begin(), b.end(),
    c.begin(), c.end(), a.begin(),
    [x](double bb, double cc)
{
    return bb * x + cc;
});
```





## SAXPY routine

Parallel version, no data locality:

```
std::vector<hpx::compute::host::target> target =
    hpx::compute::host::get_numa_domains();

hpx::compute::host::block_allocator<double> alloc(
    targets);

hpx::compute::vector<double, block_allocator<double
    >> a(..., alloc);
hpx::compute::vector<double, block_allocator<double
    >> b(..., alloc);
hpx::compute::vector<double, block_allocator<double
    >> c(..., alloc);
double x = ...;
```



## SAXPY routine

Parallel version, running on the GPU:

```
hpx::compute::cuda::target target = hpx::compute::
    cuda::get_default_device();

hpx::compute::host::cuda_allocator<double> alloc(
    target);

hpx::compute::vector<double, block_allocator<double
    >> a(..., alloc);
hpx::compute::vector<double, block_allocator<double
    >> b(..., alloc);
hpx::compute::vector<double, block_allocator<double
    >> c(..., alloc);
double x = ...;
```



## More on HPX GPU support

- Executors to modify behavior of how the warps are scheduled
- Executor Parameters to modify chunking (partitioning) of parallel work
- Dynamic parallelism: `hpx::parallel::sort(...);`  
`hpx::async(cuda_exec, [&] ()`

## More on HPX data locality

- The goal is to be able to expose high level support for all kinds of memory:
  - Scratch Pads
  - High Bandwidth Memory (KNL)
  - Remote Targets (memory locations)
- Targets are the missing link between where data is executed, and where it is located



# Hello Distributed World!

```
struct hello_world_component;
struct hello_world;

int main()
{
    hello_world hw(hpx::find_here());

    hw.print();
}
```



## Components Interface: Writing a component

```
// Component implementation
struct hello_world_component
    : hpx::components::component_base<
        hello_world_component
    >
{
    // ...
};
```

## Components Interface: Writing a component

```
// Component implementation
struct hello_world_component
    : hpx::components::component_base<
        hello_world_component
    >
{
    void print() { std::cout << "Hello World!\n"
                  "";
    }
    // define print_action
    HPX_DEFINE_COMPONENT_ACTION(
        hello_world_component, print);
};
```

## Components Interface: Writing a component

```
// Component implementation
struct hello_world_component
    : hpx::components::component_base<
        hello_world_component
    >
{
    // ...
};

// Register component
typedef hpx::components::component<
    hello_world_component
> hello_world_type;
```

## Components Interface: Writing a component

```
// Component implementation
struct hello_world_component
    : hpx::components::component_base<
        hello_world_component
    >
{
    // ...
};

// Register component ...
// Register action
HPX_REGISTER_ACTION(print_action);
```

## Components Interface: Writing a component

```
struct hello_world_component;

// Client implementation
struct hello_world
    : hpx::components::client_base<hello_world,
      hello_world_component>
{
    // ...
};

int main()
{
    // ...
}
```

## Components Interface: Writing a component

```
struct hello_world_component ;  
  
// Client implementation  
struct hello_world  
: hpx::components::client_base<hello_world ,  
    hello_world_component>  
{  
    typedef  
        hpx::components::client_base<  
            hello_world , hello_world_component >  
    base_type ;  
  
    hello_world(hpx::id_type where)  
    : base_type(  
        hpx::new_<hello_world_component>(
```

## Components Interface: Writing a component

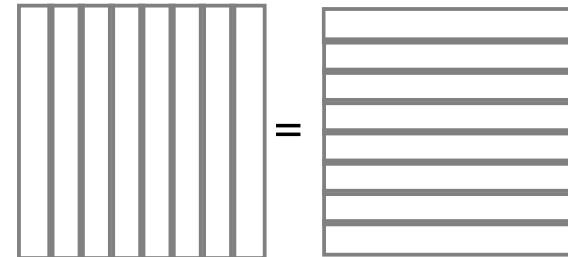
```
struct hello_world_component ;  
  
// Client implementation  
struct hello_world  
: hpx::components::client_base<hello_world,  
    hello_world_component>  
{  
    // base_type  
  
    hello_world(hpx::id_type where);  
  
    hpx::future<void> print()  
    {  
        hello_world_component::print_action act  
        .  
        return hpx::async(act_.get().id());  
    }  
};
```

## Components Interface: Writing a component

```
struct hello_world_component ;  
  
// Client implementation  
struct hello_world  
    : hpx::components::client_base<hello_world,  
      hello_world_component>  
{  
    hello_world(hpx::id_type where);  
    hpx::future<void> print();  
};  
  
int main()  
{  
    hello_world hw(hpx::find_here());  
    hw.print();  
}
```

## Matrix Transpose

$$B = A^T \Rightarrow$$



Inspired by the Intel Parallel Research Kernels  
(<https://github.com/ParRes/Kernels>)



## Matrix Transpose

```
std::vector<double> A(order * order);
std::vector<double> B(order * order);

for(std::size_t i = 0; i < order; ++i)
{
    for(std::size_t j = 0; j < order; ++j)
    {
        B[i + order * j] = A[j + order * i];
    }
}
```



## Example: Matrix Transpose

```
std::vector<double> A(order * order);
std::vector<double> B(order * order);

auto range = irange(0, order);
// parallel for
for_each(par, begin(range), end(range),
    [&](std::size_t i)
{
    for(std::size_t j = 0; j < order; ++j)
    {
        B[i + order * j] = A[j + order * i];
    }
});

```



## Example: Matrix Transpose

```
std::size_t my_id = hpx::get_locality_id();
std::size_t num_blocks = hpx::
    get_num_localities().get();
std::size_t block_order = order / num_blocks;
std::vector<block> A(num_blocks);
std::vector<block> B(num_blocks);
```

## Example: Matrix Transpose

```
for(std::size_t b = 0; b < num_blocks; ++b) {
    if(b == my_id) {
        A[b] = block(block_order * order);
        hpx::register_id_with_basename("A", get_gid
            (), b);
        B[b] = block(block_order * order);
        hpx::register_id_with_basename("B", get_gid
            (), b);
    }
    else {
        A[b] = hpx::find_id_from_basename("A", b);
        B[b] = hpx::find_id_from_basename("B", b);
    }
}
```

## Example: Matrix Transpose

```
std::vector<hpx::future<void>> phases(
    num_blocks);
auto range = irange(0, num_blocks);
for_each(par, begin(range), end(range),
    [&](std::size_t phase)
{
    std::size_t block_size = block_order *
        block_order;
    phases[b] = hpx::lcos::dataflow(
        transpose,
        A[phase].get_sub_block(my_id * block_size
            , block_size),
        B[my_id].get_sub_block(phase * block_size
            , block_size)
    );
}
```

Massively Parallel Task-Based Programming with HPX  
23.05.2016 | Thomas Heller | Computer Architecture – Department of Computer Science



## Example: Matrix Transpose

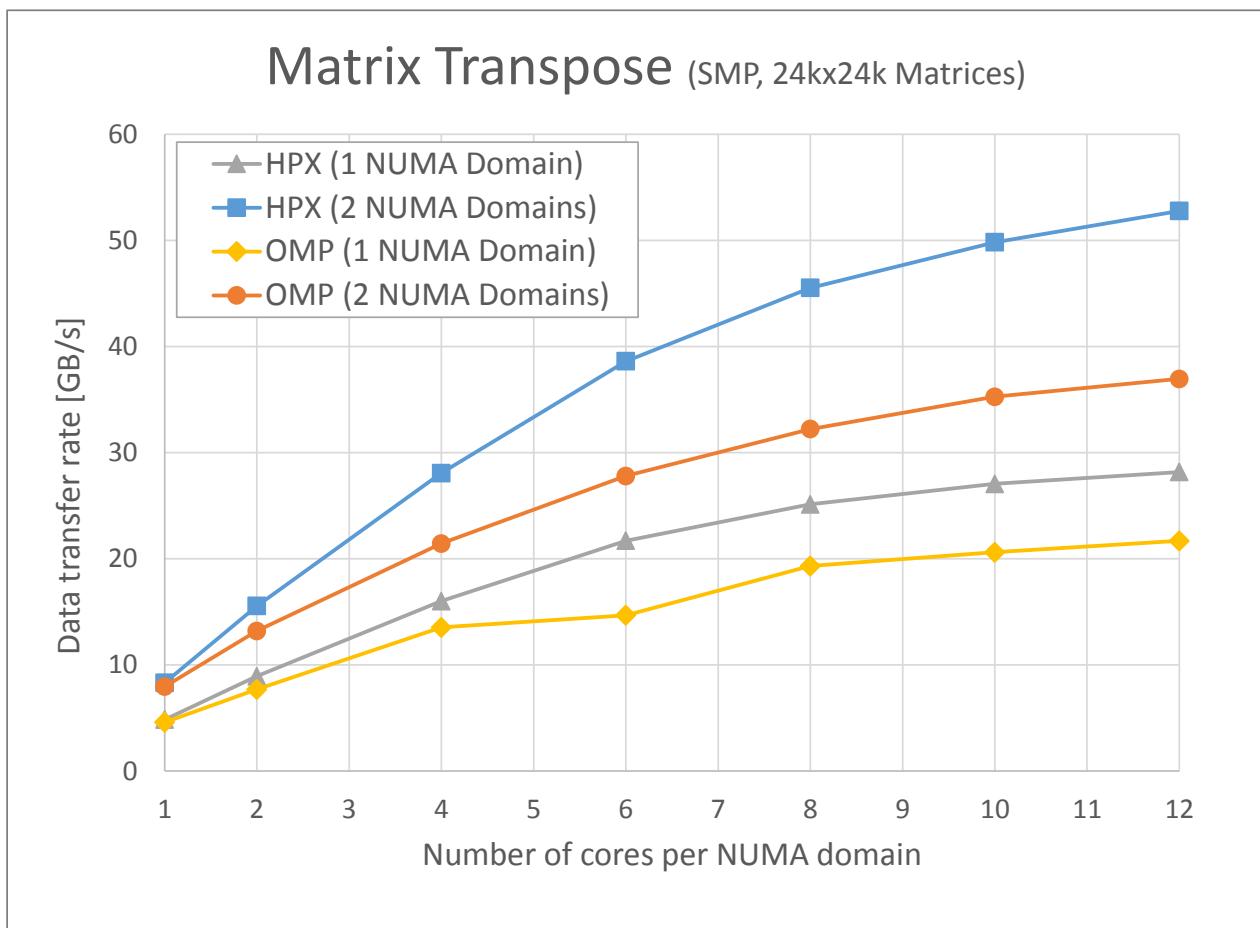
```
void transpose(hpx::future<sub_block> Af, hpx::  
    future<sub_block> Bf)  
{  
    sub_block A = Af.get();  
    sub_block B = Bf.get();  
    for(std::size_t i = 0; i < block_order; ++i)  
    {  
        for(std::size_t j = 0; j < block_order; ++j  
            )  
        {  
            B[i + block_order * j] = A[j +  
                block_order * i];  
        }  
    }  
}
```



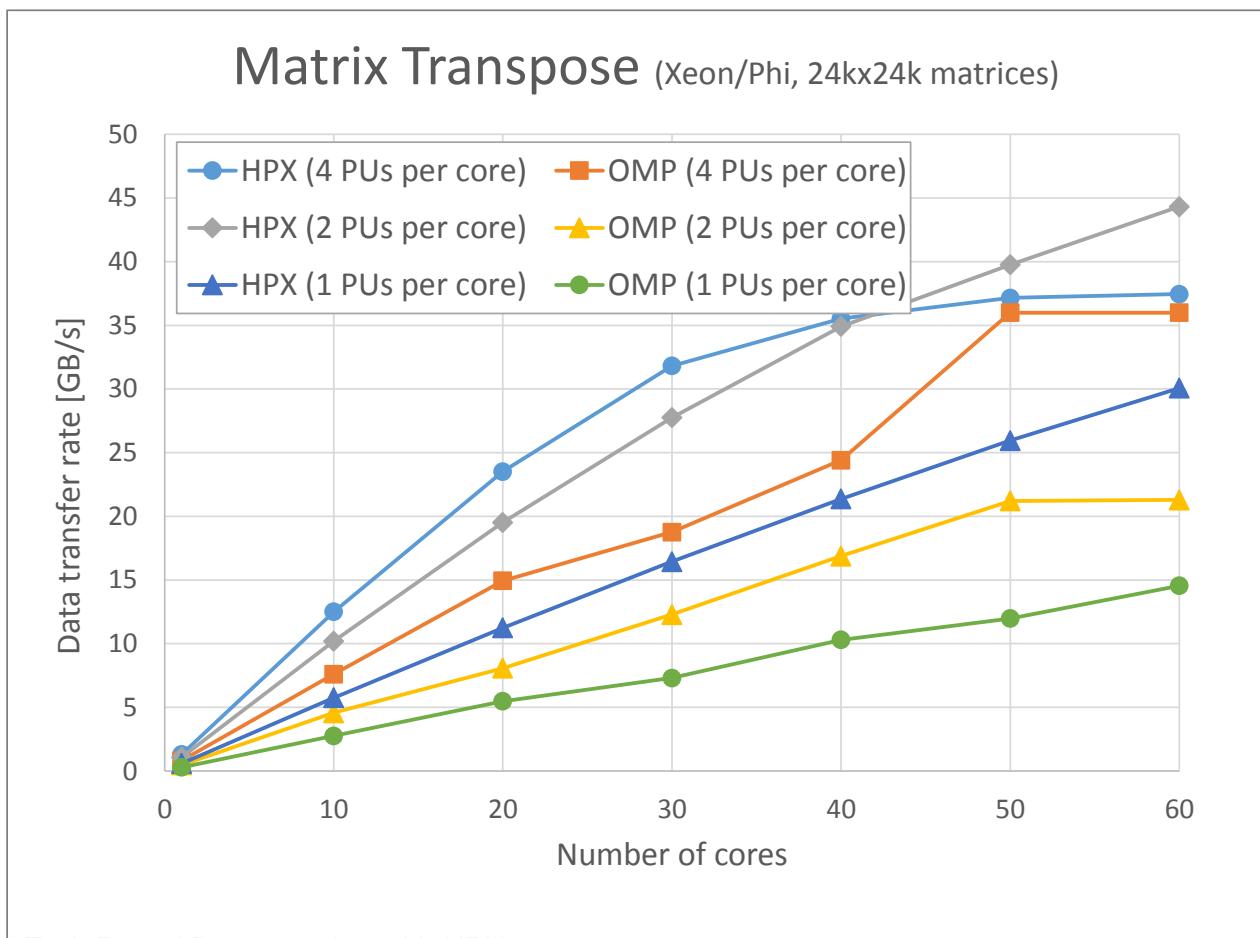
## Example: Matrix Transpose

```
struct block_component
    : hpx::components::component_base<
        block_component>
{
    block_component() {}
    block_component(std::size_t size)
        : data_(size) {}
    sub_block get_sub_block(std::size_t offset,
                           std::size_t size)
    {
        return sub_block(&data_[offset], size);
    }
    HPX_DEFINE_COMPONENT_ACTION(block_component,
                               get_sub_block);
    std::vector<double> data_;
};
```

## Matrix Transpose



## Matrix Transpose



---

## Hands-On Examples

- quicksort
- Matrix Multiplication
- Heat diffusion
- Numerical integrator
- To be found at [git@github.com:sithhell/LoOPS\\_Examples.git](git@github.com:sithhell/LoOPS_Examples.git)

---

## Conclusions

- Higher-level parallelization abstractions in C++:
  - uniform, versatile, and generic
  - All of this is enabled by use of modern C++ facilities
  - Runtime system (fine-grain, task-based schedulers)
  - Performant, portable implementation
- Asynchronous task based programming to efficiently express parallelism
- Seamless extensions for distributed computing



## Parallelism is here to stay!

- Massive Parallel Hardware is already part of our daily lives!
- Parallelism is observable everywhere:
  - ⇒ IoT: Massive amount devices existing in parallel
  - ⇒ Embedded: Meet massively parallel energy-aware systems (Embedded GPUs, Epiphany, DSPs, FPGAs)
  - ⇒ Automotive: Massive amount of parallel sensor data to process
- We all need solutions on how to deal with this, efficiently and pragmatically

## More Information

- <https://github.com/STELLAR-GROUP/hpx>
- <http://stellar-group.org>
- <http://www.open-std.org/jtc1/sc22/wg21/docs/papers>
- <https://isocpp.org/std/the-standard>
- [hpx-users@stellar.cct.lsu.edu](mailto:hpx-users@stellar.cct.lsu.edu)
- [#STELLAR @ irc.freenode.org](#)

### Collaborations:

- FET-HPC (H2020): AllScale (<https://allscale.eu>)
- NSF: STORM (<http://storm.stellar-group.org>)
- DOE: Part of X-Stack