

Ludicrously Large-Scale Stochastic Energy Optimization in SMS++

Antonio Frangioni¹

Rafael Durbano Lobato²

... & many others

¹Dipartimento di Informatica, Università di Pisa, frangio@di.unipi.it

²Chamber of Electric Energy Commercialization of Brazil, rafael.lobato@gmail.com

The second HEXAGON workshop on power grids

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Outline

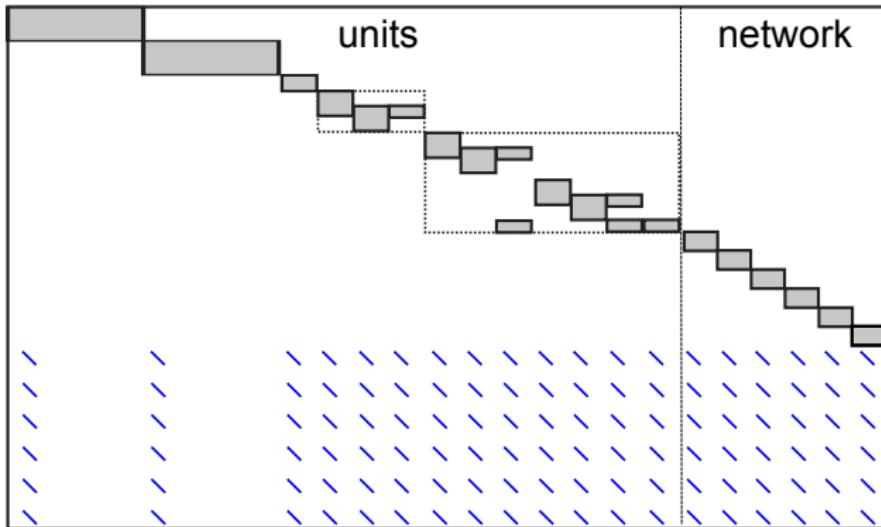
- 1 A View on (some) Energy Optimization Models
- 2 How on Earth do you solve THAT?!?
- 3 All the above in SMS++-speak
- 4 How on Earth do you model THAT?!?
- 5 Some Results
- 6 Conclusions

Energy Optimization bottom-up: Unit Commitment

- I don't need to convince you that energy optimization is important, but which of the many energy optimization problems??
- Operational level = Unit Commitment¹: schedule generating units over time horizon (hours / 15m in day / week) to satisfy (forecasted) demand
- Different types of production units, different constraints:
 - Thermal (comprised nuclear): min / max production, min up / down time, ramp rates on production increase / decrease, start-up cost depending on previous downtime, others (modulation, ...)
 - Hydro (valleys): min / max production, min / max reservoir volume, time delay to get to the downstream reservoir, others (pumping, ...)
 - Non programmable (ROR hydro) intermittent units (solar / wind, ...)
 - Fancy things (small-scale storage, demand response, smart grids, ...)
- Plus the interconnection network (AC / DC, transmission / distribution, OTS, ...) and reliability (primary / secondary reserve, $n - 1$ units, ...)

¹ van Ackooij, Danti Lopez, F., Lacalandra, Tahanan "Large-scale Unit Commitment Under Uncertainty [...]" AOR 2018

Many Different Structures Already



- **Many different structures:** thermal units², hydro units³, Energy Communities⁴, stochastic⁵, AC-OPF⁶, OTS⁷, ...

²Bacci, F., Gentile, Tavlaridis-Gyparakis "New MINLP Formulations for the Unit Commitment Problem [...]" *OR* 2024

³van Ackooij et. al. "Shortest path problem variants for the hydro unit commitment problem" *Elec. Notes Disc. Math.* 2018

⁴Fioriti, F., Poli "Optimal Sizing of Energy Communities with Fair Revenue Sharing [...]" *Applied Energy* 2021

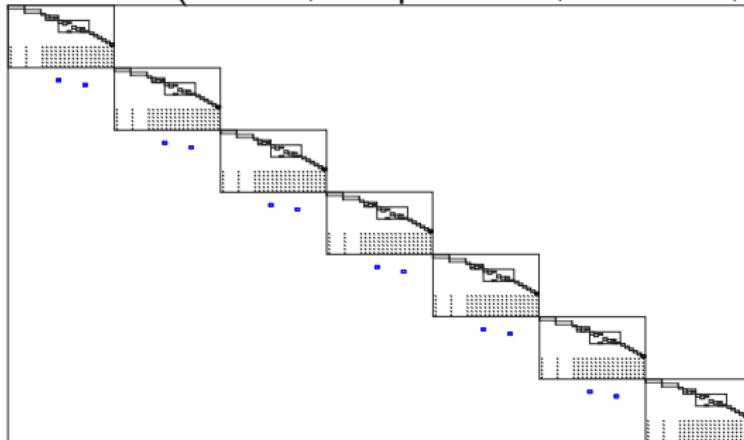
⁵Scuzziato, Finardi, F. "Comparing Spatial and Scenario Decomposition for Stochastic [...]" *IEEE Trans. Sust. En.* 2018

⁶Bienstock, Escobar, Gentile, Liberti "[...]" formulations for the alternating current optimal power flow" *Ann. O.R.*, 2022

⁷Numan et. al. "The role of optimal transmission switching in enhancing grid flexibility: A review" *IEEE Access*, 2023

The tactical level: Seasonal Storage Valuation

- Mid-term (1y) cost-optimal management of water levels in reservoirs considering **uncertainties** (inflows, temperatures, demands, ...)



- **Very large size, nested structure** (one UC per stage)
- Perfect structure for Stochastic Dual **Dynamic Programming**^{8,9}
- SDDP needs **dual variables**, but **Lagrangian dual convexifies**^{10,11}

⁸ Pereira, Pinto "Multi-stage stochastic optimization applied to energy planning" *Math. Prog.*, 1991

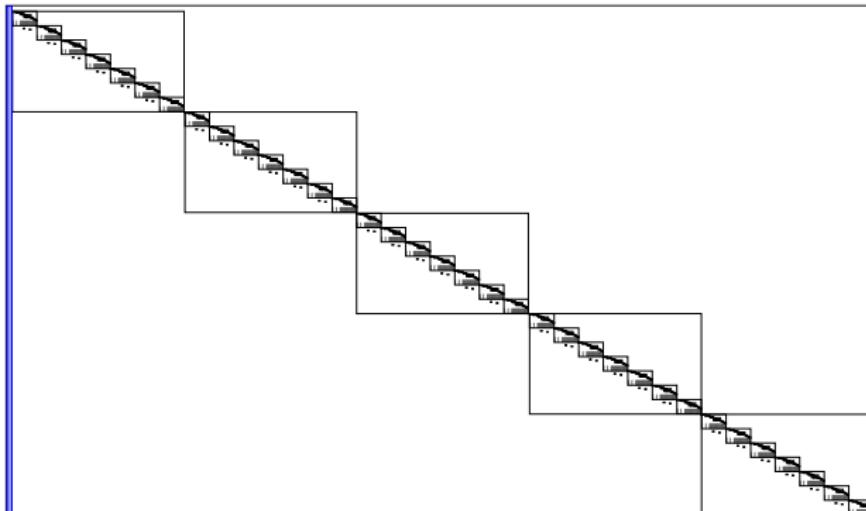
⁹ van-Ackooij, Warin "On conditional cuts for Stochastic Dual Dynamic Programming" *EURO J. on Comp. Opt.*, 2020

¹⁰ Lemaréchal, Renaud "A geometric study of duality gaps, with applications" *Math. Prog.* 2001

¹¹ F. "About Lagrangian Methods in Integer Optimization" *Annals of O.R.*, 2005

Energy System Investment

- Investment on generating units / transmission lines
- Using **stochastic independent representative years** to evaluate system cost



- Very few investment variables, can be taken continuous, identical copies
- Would be perfect for Benders'-like^{12,13}, if given dual information

¹²Geoffrion "Generalized Benders Decomposition" *JOTA*, 1972

¹³van Ackooij, F., de Oliveira "Inexact Stabilized Benders' Decomposition Approaches [...]" *COAP*, 2016

Mathematics of convex investment problems

- Set N of generation / distribution units, κ_i identical copies of each $i \in N$
- For $\kappa = [\kappa_i]_{i \in N}$, investment cost $F(\kappa)$ ("easy") and operational cost

$$\begin{aligned} O(\kappa) = \min & \sum_{i \in N} \sum_{j=1}^{\kappa_i} c_i(x_{i,j}) \\ \text{s.t. } & x_{i,j} \in X_i \quad j = 1, \dots, \kappa_i, i \in N \quad (1) \\ & \sum_{i \in N} \sum_{j=1}^{\kappa_i} A_i x_{i,j} \geq d \end{aligned}$$

- Everything convex \Rightarrow all $i \in N$ produce identically at optimality \Rightarrow

$$\begin{aligned} O(\kappa) = \min & \sum_{i \in N} \kappa_i c_i(x_i) \\ \text{s.t. } & x_i \in X_i \quad i \in N \quad (2) \\ & \sum_{i \in N} \kappa_i A_i x_i \geq d \end{aligned}$$

- Extends to stochastic setting (S = scenarios, \mathcal{N} = nonanticipativity)

$$\begin{aligned} O(\kappa) = \min & \sum_{i \in N} \kappa_i \sum_{s \in S} \pi^s c_i^s(x_i^s) \\ \text{s.t. } & x_i^s \in X_i^s \quad i \in N, s \in S \quad (3) \\ & \sum_{i \in N} \kappa_i \sum_{s \in S} A_i^s x_i^s \geq d, x \in \mathcal{N} \end{aligned}$$

A triply clever trick

- Investment problem $\min\{ F(\kappa) + O(\kappa) : \kappa \in K \}$: extremely hard as even (2) / (3) hard ((1) harder), since convexity assumption untrue

- Lagrangian relaxation triply clever:

$$\phi(\lambda, \kappa) = \lambda d + \sum_{i \in N} \kappa_i \min\{ c_i(x_i) - \lambda A_i x_i : x_i \in X_i \}$$

- decomposes into (many, easier, smaller) independent subproblems
- automatically convexifies c and X ¹¹
- $\phi(\lambda, \kappa)$ is concave in λ and affine in κ

- Convexified version: $\underline{O}(\kappa) = \max\{ \phi(\lambda, \kappa) : \lambda \geq 0 \} = \phi(\lambda^*(\kappa), \kappa)$

- Convexified Investment Problem: $\min\{ F(\kappa) + \underline{O}(\kappa) : \kappa \in K \}$ possibly the best trade-off between computability and accuracy

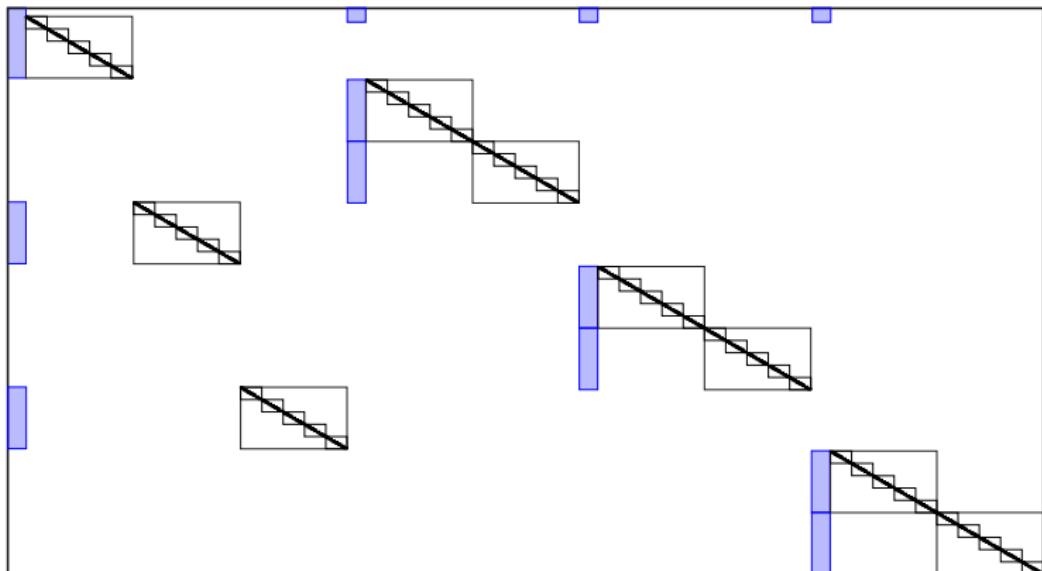
- Crucial: $[c_i(x_i^*(\lambda^*(\kappa))) - \lambda^*(\kappa) A_i x_i^*(\lambda^*(\kappa))]_{i \in N} \in \partial \underline{O}(\kappa)$ ¹⁴
 \implies can use bundle methods^{??} or stabilised Benders' ones¹⁵

¹⁴ van Ackooij, Oudjane "On supply and network investment in power systems" 4OR, 2024

¹⁵ van Ackooij, F., de Oliveira "Inexact Stabilized Benders' Decomposition Approaches [...]" COAP, 2016

Strategic Energy System Investment (“the Big Kahuna”)

- Long-term (30y) optimal (cost, pollution, CO₂ emissions, ...) planning of production/transmission investments considering multi-level **uncertainties scenarios** (technology, economy, politics, ...)



- Many scenarios, huge size, multiple nested structure \Rightarrow multiple nested Benders' or Lagrangian decomposition and/or SDDP??

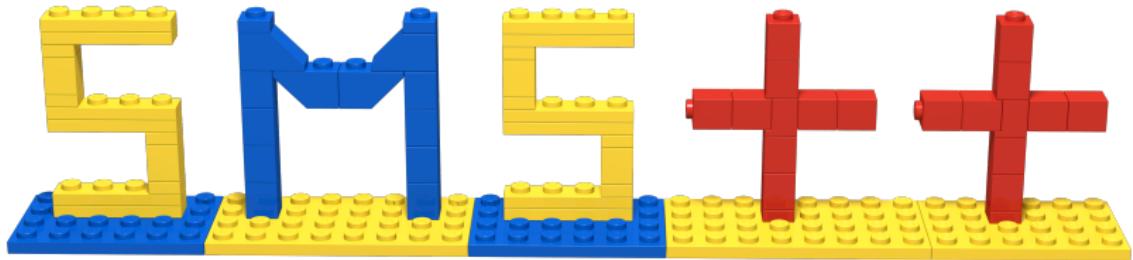
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A HUGE LOT OF
ELBOW GREASE,
BLODSHED AND TEARS

or

Quite a lot of elbow grease and



<https://gitlab.com/smspp/smspp-project>

“For algorithm developers, from algorithm developers”

- Open source (LGPL3)
- 1 “core” repo, 1 “umbrella” repo, 12+ problem and/or algorithmic-specific repos (public, more in development), tests & tools
- Extensive Doxygen documentation <https://smspp.gitlab.io>
- But no real user manual as yet (except myself)

What SMS++ is

- A core set of C++-20 classes implementing a **modelling system** that:
 - explicitly supports the notion of **Block** \equiv nested structure
 - separately provides “semantic” information from “syntactic” details (list of constraints/variables \equiv **one specific** formulation among many)
 - allows exploiting **specialised Solver** on Block with specific structure
 - manages **any dynamic change in the Block** beyond “just” generation of constraints/variables
 - supports **reformulation/restriction/relaxation** of Block
 - has built-in **parallel processing** capabilities
 - **should** be able to deal with almost anything (bilevel, PDE, ...)
- An **hopefully growing** set of specialized **Block** and **Solver**
- **In perspective** an ecosystem fostering collaboration and code sharing:
a community-building effort as much as a (suite of) software product(s)

What SMS++ is not

- **An algebraic modelling language:** Block are C++ code
(although it provides some modelling-language-like functionalities)
- **For the faint of heart:** primarily written for algorithmic experts
(although users may benefit from having many pre-defined Block)
- **Stable:** only version 0.5.2, lots of further development ahead,
significant changes in (parts) of interfaces actually expected
(although current Block / Solver very thoroughly tested)
- **Interfaced with many existing solvers:** Cplex, SCIP, MCFClass, StOpt
(but the list recently grew with Guorbi, HiGHS and LEMON)
- **Ripe with native structure-exploiting solvers:** LagrangianDualSolver and
SDDPSolver for now (although the list should hopefully grow)

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It starts deceptively simple

```
ThermalUnitBlock : Block
min  $\sum_{i \in P} c^i(\mathbf{p}^i, \mathbf{u}^i) = \sum_{i \in P} \left( c^i(\mathbf{u}^i) + \sum_{t \in \mathcal{T}} c_t^i(p_t^i) \right)$ 
 $\bar{p}_{\min}^i \leq p_t^i \leq \bar{p}_{\max}^i \quad t \in \mathcal{T}$ 
 $p_t^i \leq p_{t-1}^i + u_{t-1}^i \Delta_+^i + (1 - u_{t-1}^i) \bar{l}^i \quad t \in \mathcal{T}$ 
 $p_{t-1}^i \leq p_t^i + u_t^i \Delta_-^i + (1 - u_t^i) \bar{u}^i \quad t \in \mathcal{T}$ 
 $u_t^i \geq u_r^i - u_{r-1}^i \quad t \in \mathcal{T}, \quad r \in [t - \tau_+, t - 1]$ 
 $u_t^i \geq 1 - u_{r-1}^i - u_r^i \quad t \in \mathcal{T}, \quad r \in [t - \tau_-, t - 1]$ 
 $u_t^i \in \{0, 1\} \quad t \in \mathcal{T}$ 

T  a[] b[] c[]  Dp[]
p_min[] p_max[] Dm[]
```

- For a man with a hammer everything is a nail

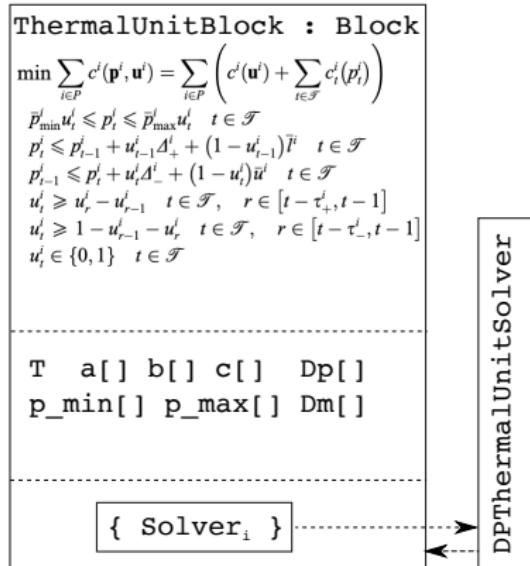
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T  a[] b[] c[]  Dp[]
p_min[] p_max[] Dm[]
```

- For a man with a solver everything is a **Block** (call me **blockhead** - Block** = abstract class representing the general concept of “(fragment of) mathematical model with a well-understood semantic”
- Each **:Block** a model with **specific structure**: ThermalUnitBlock : Block = a single-(thermal)-unit commitment problem

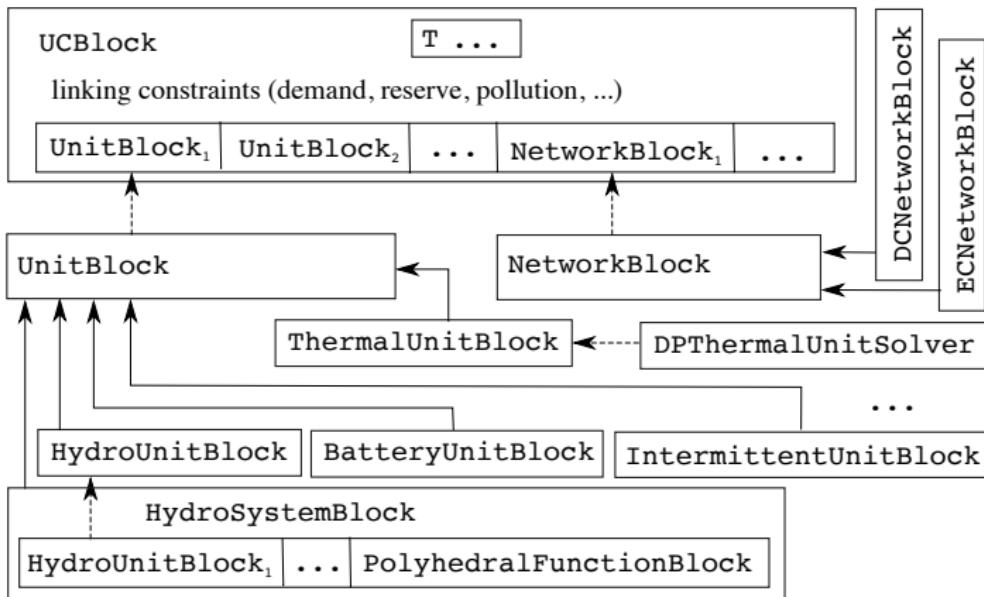
A Block \exists (\approx) because a (specialised) Solver \exists



- Any number of Solver can be attached to a Block
- Any specific :Block (e.g., `ThermalUnitBlock`) can have specialised \Rightarrow fast :Solver (e.g., `DPThermalUnitSolver`¹⁶)
- Can be wrapper classes to efficient existing (C++) libraries

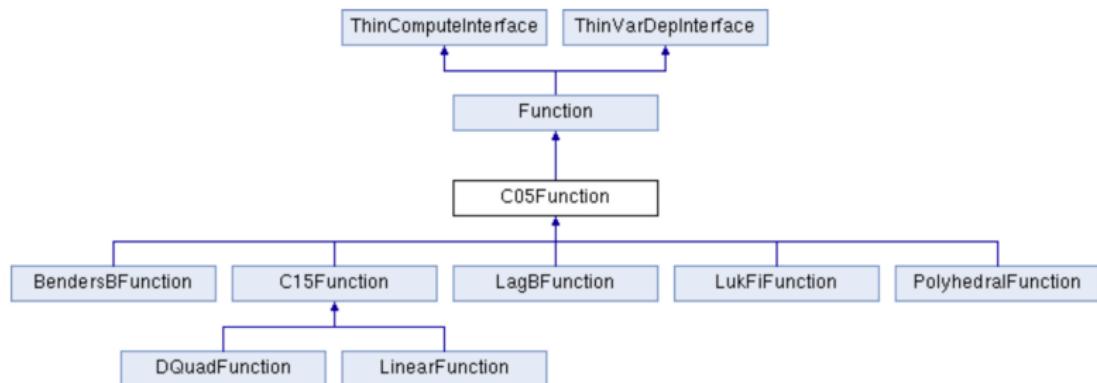
¹⁶ F., Gentile "Solving Nonlinear Single-Unit Commitment Problems with Ramping Constraints" *Op. Res.*, 2006

A Block is (almost) always just a (small) part



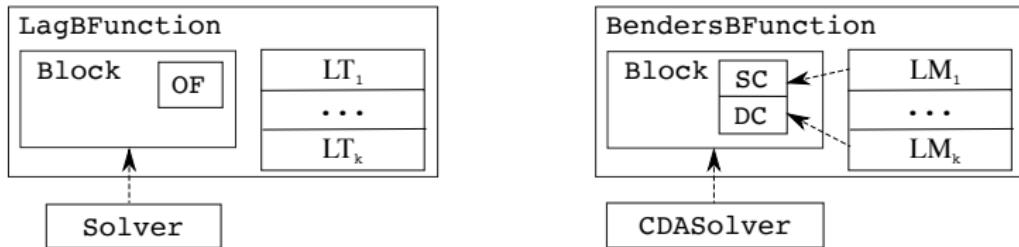
- A Block can have **any # of sub-Block, recursively** (Block *); e.g., UCBLOCK : Block has k :UnitBlock and T :NetworkBlock **recursively**
- Problem data split between them (energy constraints only in UCBLOCK)

Another necessary step: Function



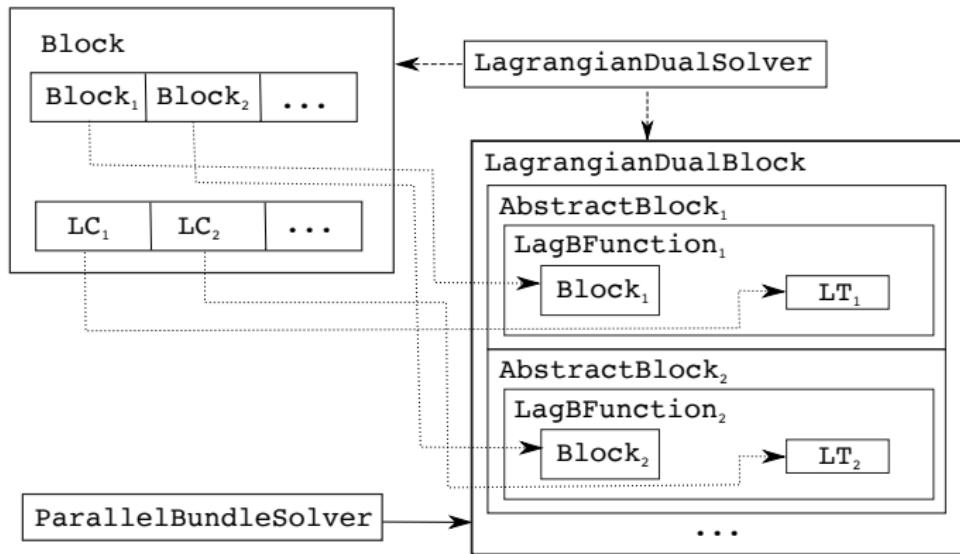
- Real-valued Function of a set of [Col]Variable (a single \mathbb{R} / \mathbb{Z})
- Must be `compute()`-d w.r.t. the current value of the [Col]Variable, **possibly a costly operation** (:`ThinComputeInterface`)
- `C05Function` / `C15Function` have (**not necessarily continuous**) 1st / 2nd order information (vertical / diagonal linearizations)
- **Local / global pools** of linearizations
- “Easy” Function (linear, quadratic, polyhedral, ...) with no overhead

LagBFunction & BendersBFunction



- LagBFunction \equiv dual function $\varphi(\lambda) = \min\{ f(x) + (\lambda LT)x : x \in X \}$ for (almost) any Block (B) $\min\{ f(x) : x \in X \}$
- BendersBFunction \equiv value function
 $v(y) = \min\{ f(x) : g(x) \leq LMy : x \in X \}$ for (almost) any Block (B) $\min\{ f(x) : g(x) \leq 0, x \in X \}$
- Both are :Block and :C05Function, with (B) being the only sub-Block
- Use generic [CDA]Solver to compute() (\approx just call its compute())
- Store pools of primal / dual Solution corresponding to linearizations
- Any change in (B) is mapped in changes of F-values / the pools

All this \mapsto LagrangianDualSolver



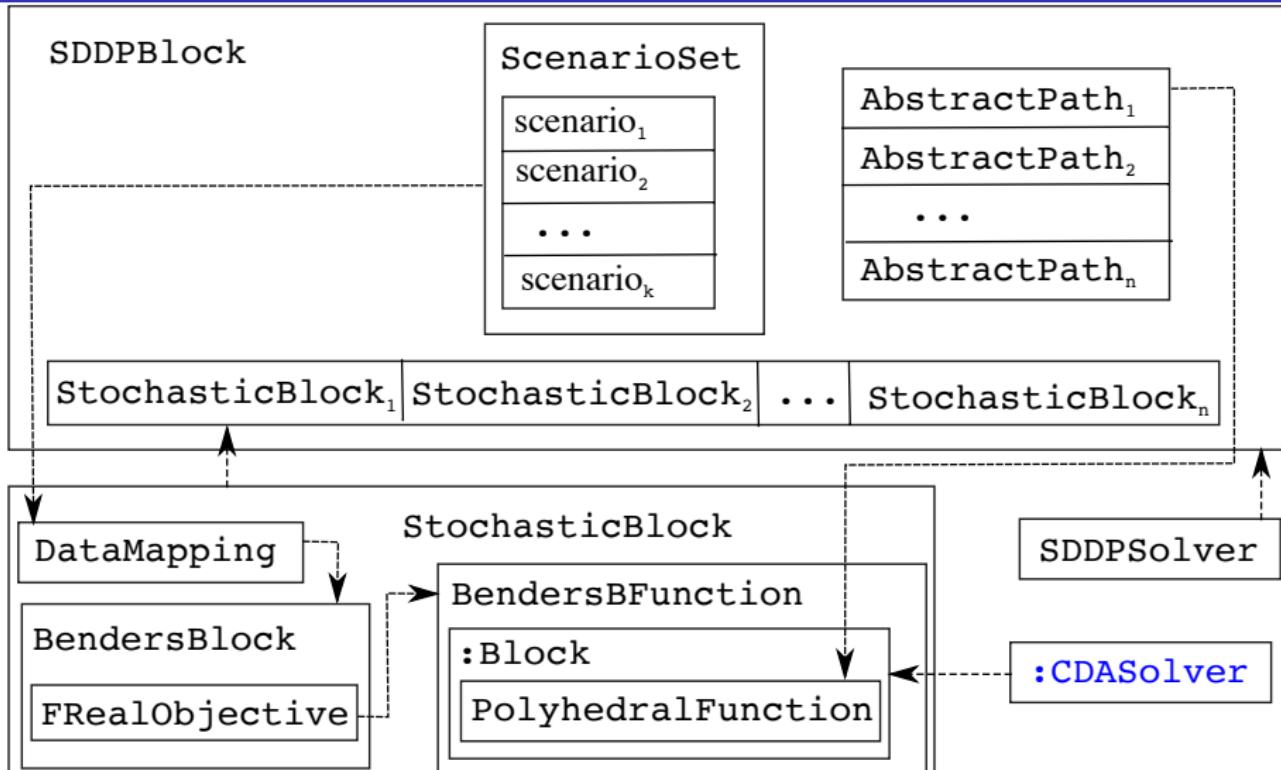
- Forms (hidden) LagrangianDualBlock, attaches parallel¹⁷ Solver
- Provides primal (convexified \equiv "better"^{10,11}) and dual solutions
- Good foundations for heuristic approaches^{18,19} & the next steps

¹⁷ Cappanera, F. "[...] Parallelization of [...] Algorithm for Multi-Commodity Flow Problems" *INFORMS JoC*, 2003

¹⁸ Borghetti, F., Lacalandra, Nucci "Lagrangian [...] for Hydrothermal Unit Commitment", *IEEE Trans. Power Sys.* 2003

¹⁹ Scuzziato, Finardi, F. "Solving Stochastic [...] Unit Commitment with [...] Lagrangian Solutions" *IJEPES*, 2021

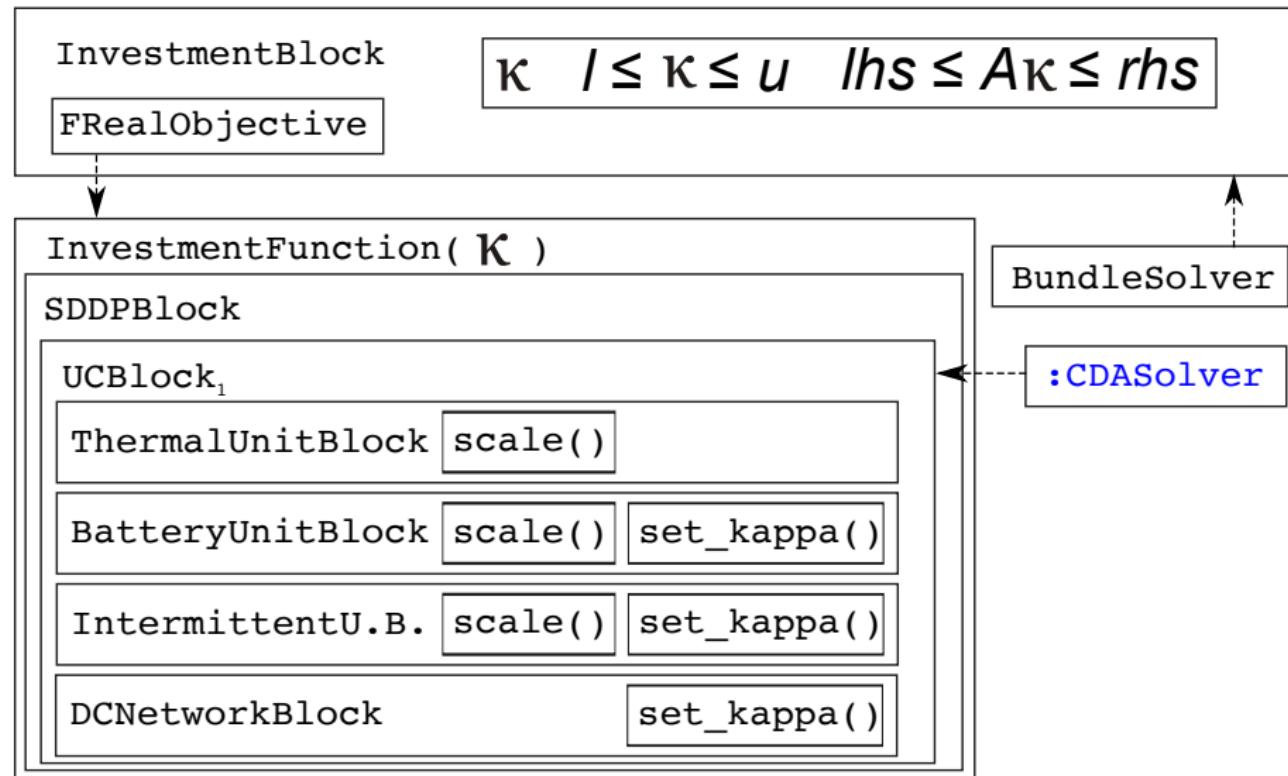
SDDPBlock, StochasticBlock and their Solver



- **SDDPSolver**: wrapper for **StOpt**²⁰ + **SDDPGreedySolver** (simulator)

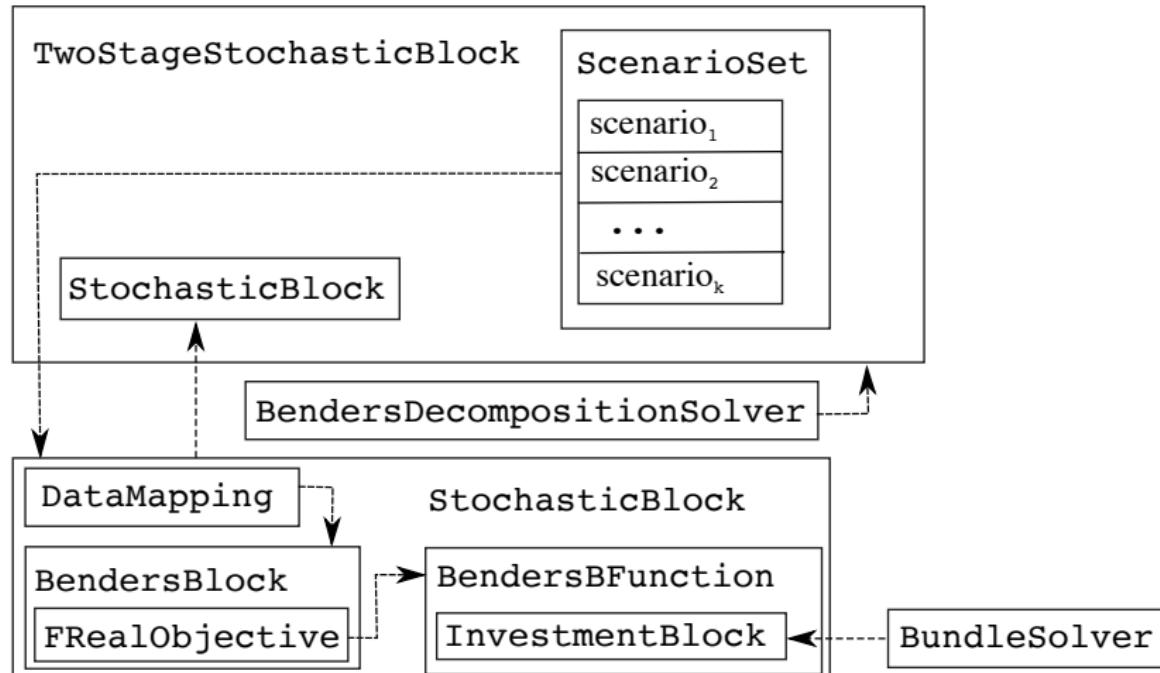
²⁰ <https://gitlab.com/stochastic-control/StOpt>

InvestmentBlock



- Scaling a `:Block` a general concept, may be upcasted to base Block

Strategic Investment Problem in SMS++-speak



- Not all here yet, TwoStageStochasticBlock still under active development, BendersDecompositionSolver yet to come
- Clearly extremely challenging problem, need all the help we can get

SMS++ support to (coarse-grained) parallel computations

- Block can be (write) lock()-ed to ensure atomic changes
- lock()-ing a Block automatically lock()s all inner Block (recursively)
- Analogously for `read_lock()`, any # of concurrent reads
- `lock()` (but not `read_lock()`) sets an `owner` and records its `std::thread::id`; other `lock()` from the same thread fail (`std::mutex` would not work there)
- Write starvation not handled yet
- Solver's `compute()` must be thread-safe (`std::recursive_mutex`)
- Solver/ThinComputeInterface can be “lent ID” (solving a sub-Block)
- Solver's `list<Modification>` under an “active guard” (`std::atomic`)
- General `State` of Solver for checkpointing (and reoptimization)
- New `Change` concept: Modification + data, automatic `undo_Change`, can be de/serialize-d on netCDF file as everything \Rightarrow message-passing distributed Solver available one day (soon-ish?)

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QUITE SOME
ELBOW GREASE AND
netCDF FILES MANGLING

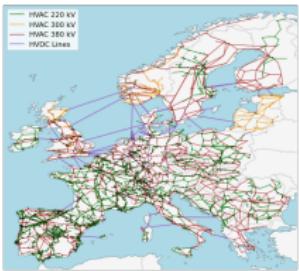
or

Some elbow grease and

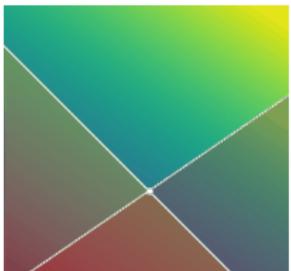
PyPSA



PyPSA-Eur



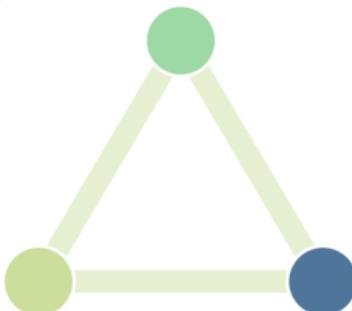
Linopy



<https://pypsa.org>

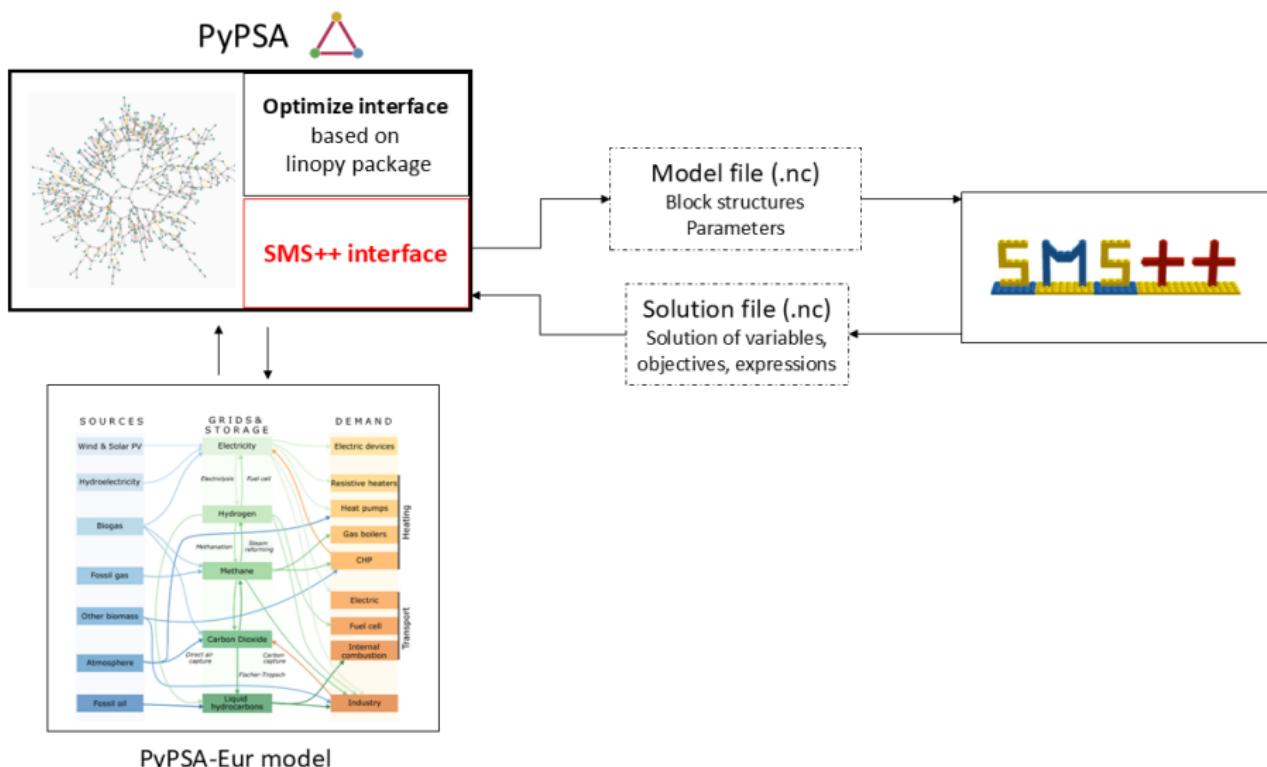


RESILIENT



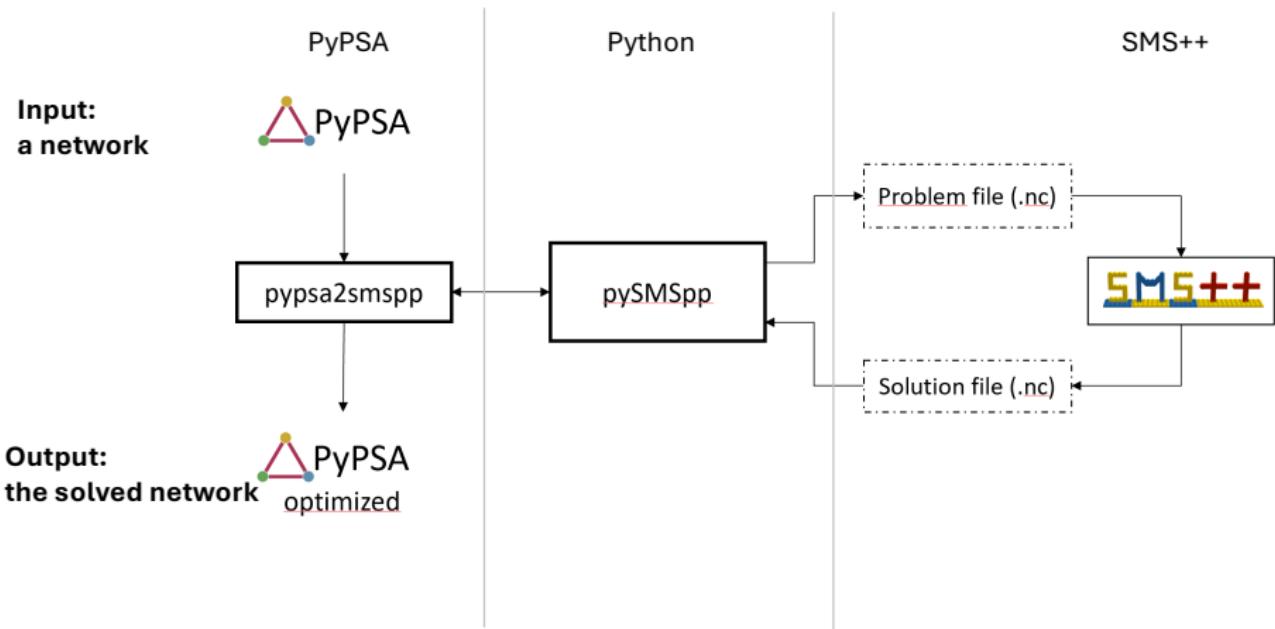
<https://resilient-project.github.io>

What the project wants to do



- Modelling prowess of PyPSA + solution prowess of SMS++

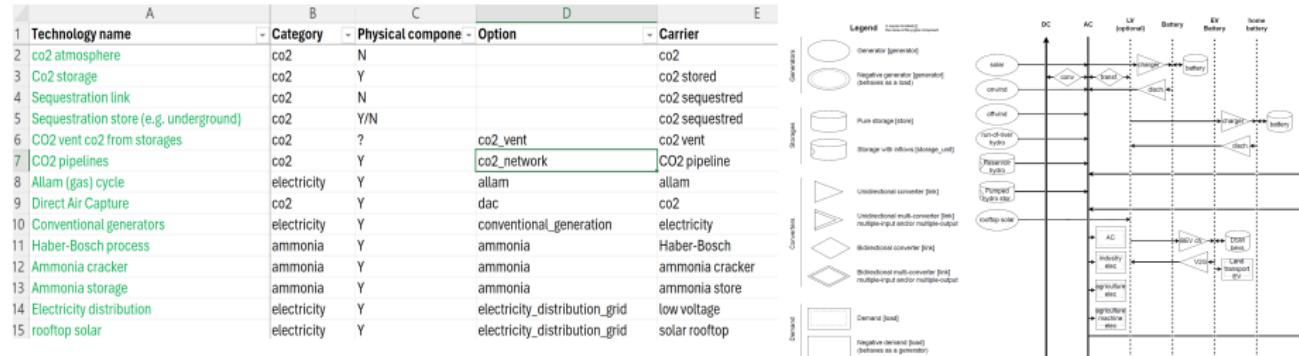
A bit more in details



- Requires careful mapping of PyPSA network \mapsto SMS++:Block
- Especially important for freshly developed PyPSA stochastic extension

A glimpse of the mapping

Equation	Symbol	Generator	Link	Line	Storage unit	Store	Condition	Example
Size bound	SB	X	X	X	X	X		$G_{i,r} \leq G_{i,r} \leq G_{i,r}$
Modularity	MD	X	X	X	X	X		$G_{i,r} = \underline{G}_{i,r}^{\text{mod}} n_{i,r}$
Power bound	PB	X	X	X	X	X		$\underline{g}_{i,r,t} G_{i,r} \leq g_{i,r,t} \leq \bar{g}_{i,r,t} G_{i,r}$
Power unit commitment	PB _{UC}	X	X				committable	$\delta_{i,r,t} g_{i,r,t} G_{i,r} \leq g_{i,r,t} \leq \delta_{i,r,t} \bar{g}_{i,r,t} G_{i,r}$
Minimum time	MT	X	X					$\sum_{t'=1}^{T-\text{minup}} \delta_{k,t'} \geq T_{\text{minup}} (\delta_{k,t} - \delta_{k,t-1})$
Total energy produced	PSUM	X	X					$E_{\text{max}}^{\text{sum}} \leq \sum_{t=1}^T w_t^T g_{i,r,t} \leq E_{\text{max}}^{\text{sum}}$
Start up/shut down cost	SC	X	X					$\text{stuc}_{i,t} \geq \text{stuc}_k (\delta_{k,t} - \delta_{k,t-1})$
Rump up/down	RUD	X	X					$(g_{i,r,t} - g_{i,r,t-1}) \leq r u_{i,r} G_{i,r}$
Kirchhoff's law	KL			X				$\sum_i C_{L,i} x_{p_{i,L}} = 0$
Line losses	LL			X				$P_i^{\text{losses}} = \alpha_1 + \beta_1 p_{i,L}$
Energy storage level	ESL				X	X		$e_{i,s,t} = e_{i,s,t-1} + w_t^s h_{i,s,t}$
Energy storage bound	ESB				X	X		$0 \leq e_{i,s,t} \leq E_{i,s,t}^{\text{max}}$
Initial energy level	IELS				X	X		$e_{i,s,0} = e_{i,s,\text{init}}$
Cyclic energy level	IELCS				X	X	cyclic_state_of_charge	$e_{i,s,0} = e_{i,s, T }$



- ... but no-one needs bother besides us (or new features developers)

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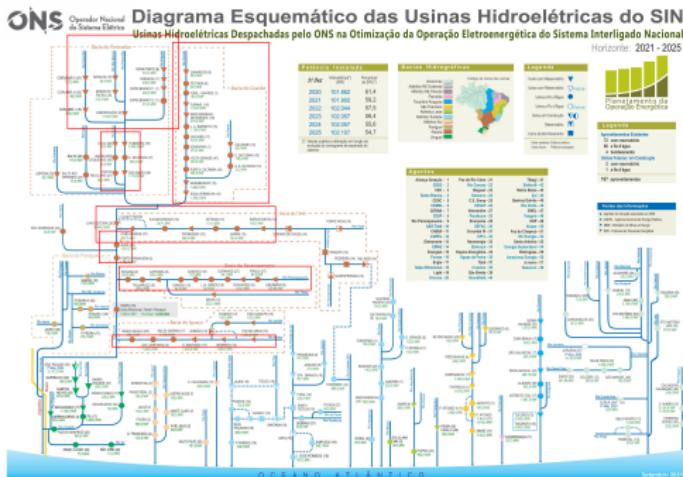
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Seasonal Storage Valuation – some results I

- SDDPSolver requires convex problem: any of the above \Rightarrow useful tricks
(continuous relaxation forward, Lagrangian relaxation backward)

- Brazilian hydro-heavy system:
53 hydro (3 cascade), 98 thermal
(coal, gas, nuclear), stochastic
inflows (20 scenarios)

- Out-of-sample simulation:
1000 scenarios



	Continuous	Lagrangian
Cost: Avg. / Std.	4.6023e+9 / 1.3608e+9	4.5860e+9 / 1.3556e+9

- Only 0.4% better, but just changing a few lines in the Configuration
(Lagrangian about 4 times slower, but can be improved)

Seasonal Storage Valuation – some results II

- Single node (Switzerland)
- 60 stages (1+ year), 37 scenarios, 168 time instants (weekly UC)
- Units: 3 intermittent, 5 thermals, 1 hydro
- Out-of-sample simulation: all 37 scenarios to integer optimality

	Continuous	Lagrangian
Cost: Avg. / Std.	1.3165e+11 / 2.194e+10	1.2644e+11 / 2.167e+10
time	25m	7h30m

- Much longer, but:
 - simulation cost \approx 30m per scenario, largely dominant
 - save 4% just changing a few lines in the configuration
 - LR time can be improved (ParallelBundleSolver not used)

Seasonal Storage Valuation – some results III

- A single node (France, guess why ...)
- 60 stages (1+ year), 37 scenarios, 168 time instants (weekly UC)
- 83 thermals, 3 intermittent, 2 batteries, 1 hydro
- Out-of-sample simulation: all 37 scenarios to integer optimality

	Continuous	Lagrangian
Cost: Avg. / Std.	3.951e+11 / 1.608e+11	3.459e+11 / 8.903e+10
time	5h43m	7h54m

- Time not so bad (and 3h20m on average simulation per scenario) using ParallelBundleSolver with 5 threads per scenario
- That's 14% just changing a few lines in the Configuration
- Starts happening regularly enough to be trusted

Seasonal Storage Valuation – some (recent) results IV

- Two dedicated top-level servers with (each) 2 AMD Epyc 9654 (2.4Ghz, 96 cores, 192 threads, 384MB cache) with **1.5TB RAM** (DDR5-4800)
- 78 stages, 37 scenarios (uncertainties in demand, inflow, intermittent generation), 84 time steps
- 23 nodes (Balkans, Baltics, Benelux, Britain, Eastern Europe, France, Germany, Italy, Portugal, Scandinavia, Switzerland, Spain, “outside”) + 49 lines, 98 thermals, 18 hydros, 60 intermittent, 22 batteries
- Deterministic equivalent would be $36^{78} \approx \text{2.5e+121}$ nodes, each 6.2e+5 variables (2.5e+5 binary) and 9.3e+5 constraints (do the math . . .)
- 37 processes (1 per scenario), ParallelBundleSolver with 5 threads

Seasonal Storage Valuation – a glimpse to the dynamic

- A sample of evolution, continuous VS Lagrangian relaxation
- Using generated SDDP cuts for future-value-of-water as iteration nature

# cuts	Continuous	Lagrangian	gap (%)
50	95030821478	94327497967	0.75
100	92798901757	92381611565	0.45
200	92857020055	93146422115	-0.31
300	92500105416	92231190639	0.29
400	92434329595	92297148794	0.15
500	92446972425	92572975779	-0.14
best	92434329595	92231190639	0.22
Time	18h20m	9d19h	

- ...but gap is $2e+8$ €: not a bad gain for 10 days' work
- Time to boldly take the last step

Energy System Investment Problem – some results I

- Simplified version: solve SDDP only once, run optimization with fixed value-of-water function + simulation (`SDDPGreedySolver`)
- EdF EU scenario: 11 nodes (France, Germany, Italy, Switzerland, Eastern Europe, Benelux, Iberia, Britain, Balkans, Baltics, Scandinavia), 20 lines
- Units: 1183 battery, 7 hydro, 518 thermal, 40 intermittent
- 78 weeks hourly (168h), 37 scenarios (demand, inflow, RES generation)
- Investments: 3 thermal units + 2 transmission lines.
- Average cost: original (operational) $6.510e+12$
optimized (investment + operational) $5.643e+12$
- This is ≈ 1 Trillion Euro, 15%
- Running time: ??? hours for value-of-water functions (EdF provided)
+ 10 hours (4 scenarios in parallel + `ParallelBundleSolver` with 6 threads) for the investment problem

Energy System Investment Problem – some results II

- Simplified version (fixed value-of-water with continuous relaxation)
- Same 11 nodes, 19 lines
- Less units: 7 hydros, 44 thermals, 24 batteries, and 42 intermittent
- More investments: 82 units + 19 transmission lines.
- 78 weeks hourly (168h), 37 scenarios (demand, inflow, RES generation)
- Average cost: original (operational) 3.312e+12
optimized (investment + operational) 1.397e+12
- This is ≈ 2 Trillion Euro, 137%
- Running time: 48 hours for value-of-water functions (2 nodes = 96 cores)
+ 5h 20m to solve the investment problem (1 nodes = 48 core)

Energy System Investment Problem

- The true version: value-of-water recomputed anew for each investment
- Still simplified: only one scenario (long way to go, but `TwoStageStochasticBlock` and `BendersDecompositionSolver` currently under active development, we'll get there eventually)
- EU scenario: 14 nodes (France, Germany, Italy, Switzerland, Eastern EU, Benelux, Iberia, Britain, Balkans, Baltics, Denmark, Finland, Sweden, Norway), 28 lines, 62 thermals, 54 intermittent, 8 hydros, 39 batteries
- 78 weeks hourly (168h), 37 scenarios (demand, inflow, RES generation)
- Investments: 99 units of all kinds + all transmission lines
- Requires extensive support for `checkpointing` and `restarts` (but `less` than on CINECA machines that had 24h time limit)

Energy System Investment Problem: first steps

- Huge problem, so **three steps approach**
 - solve the Seasonal Storage Valuation with initial system (no investment)
 - solve Energy System Investment Problem with fixed value-of-water function out of SDDP (simulation-based optimization)
 - improve investment by dynamically recomputing value-of-water at every iteration
- Original system cost: (operational) $3.467e+12$
Optimized cost: operational $4.505e+11$ + investment $2.284e+11$ =
total $6.789e+11$
- Half an order of magnitude saving (suspect most value of lost load),
511% better investing on just 4 lines and 10 hydrogen power plants
- Running time: 15h18m for future cost function of the original system,
5h18m simulation-based investment problem (74 threads max)

The Little-Big Kahuna results

- Starting from previous solution, optimize with variable value-of-water
 - iteration 0: op. $4.505\text{e+}11$ + inv. $2.284\text{e+}11$ = total $6.789\text{e+}11$ (1.8h)
(very sparse investment decision)

The Little-Big Kahuna results

- Starting from previous solution, optimize with variable value-of-water
 - iteration 0: op. 4.505e+11 + inv. 2.284e+11 = total 6.789e+11 (1.8h)
(very sparse investment decision)
 - iteration 1: op. 6.670e+10 + inv. 5.635e+12 = total 5.702e+12 (22h)
(almost completely dense investment decision)

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 - iteration 4:

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(less dense investment decision)
 - iteration 4: **nope, sorry, still running**
- Already a factor of 2 better than original system (no investment)
- Using LPs in SDDP (many numerical issues), Lagrangian will be better and will be able to use way more threads (ParallelBundleSolver)
- Will improve over the fixed value-of-water, just not there as yet

The Big Kahuna results

The Big Kahuna results

- Roll of drums ...

The Big Kahuna results

- Roll of drums . . . suspenseful pause . . .

The Big Kahuna results

- Roll of drums . . . suspenseful pause . . .
- JUST KIDDING: still in the design phase, forget about it (for today)
- Clearly extremely challenging problem, need all the help we can get
- But we are getting there, thanks to SMS++

Outline

- 1 A View on (some) Energy Optimization Models
- 2 How on Earth do you solve THAT?!?
- 3 All the above in SMS++-speak
- 4 How on Earth do you model THAT?!?
- 5 Some Results
- 6 Conclusions

Conclusions

- Want to solve ludicrously large problem? SMS++ is here for you
- Allows exploiting multiple nested heterogeneous structure, \approx the only framework designed for huge-scale (stochastic or not) problems
- Could become really useful after having attracted mindshare, self-reinforcing loop very hard to start

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 - improve collaboration and code reuse, reduce huge code waste (I ❤ coding, breaks my ❤)
 - significantly increase the addressable market of decomposition
 - a much-needed step towards higher uptake of parallel methods
 - the missing marketplace for specialised solution methods

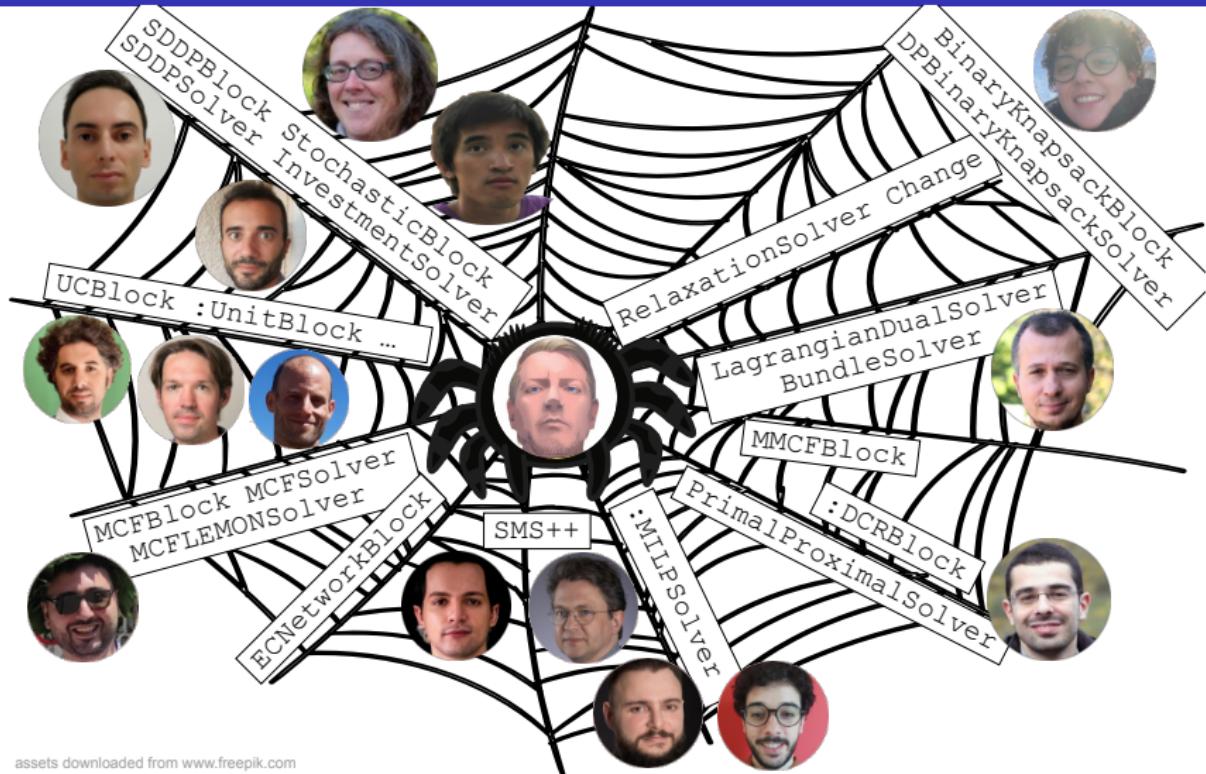
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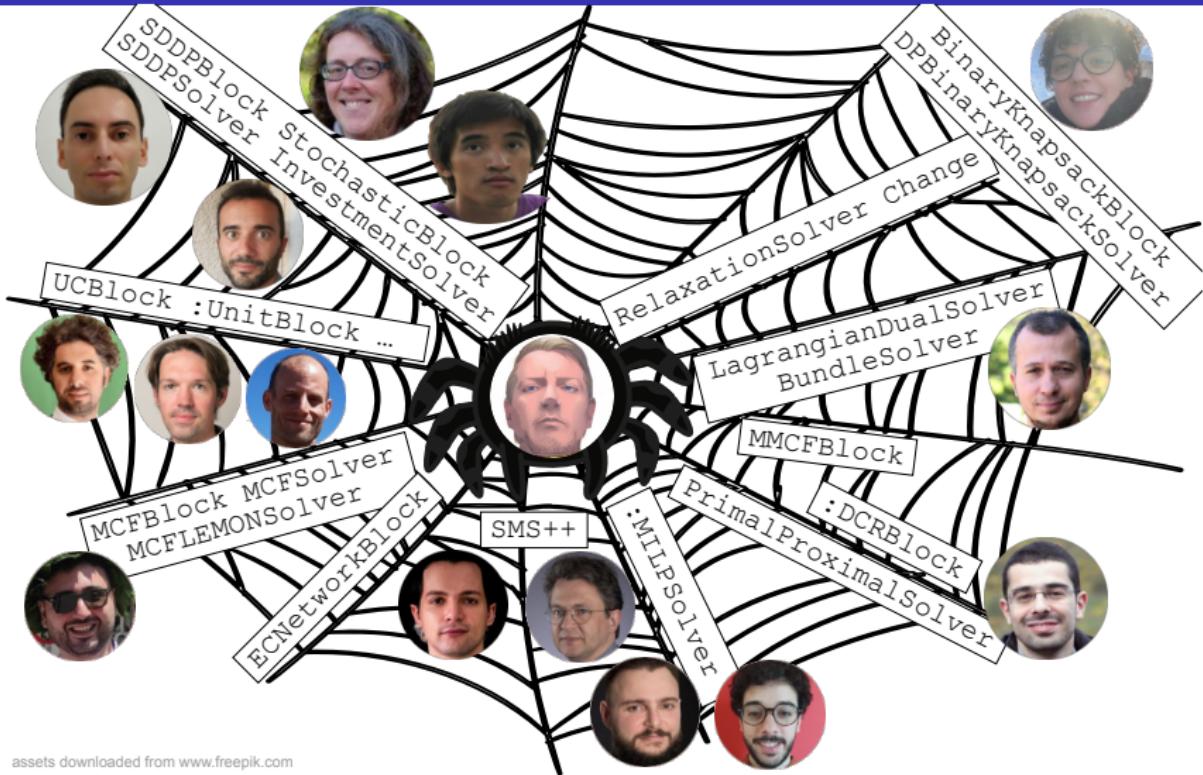
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... see it for yourself



- Not yet a thriving community, but labouring to reach critical mass

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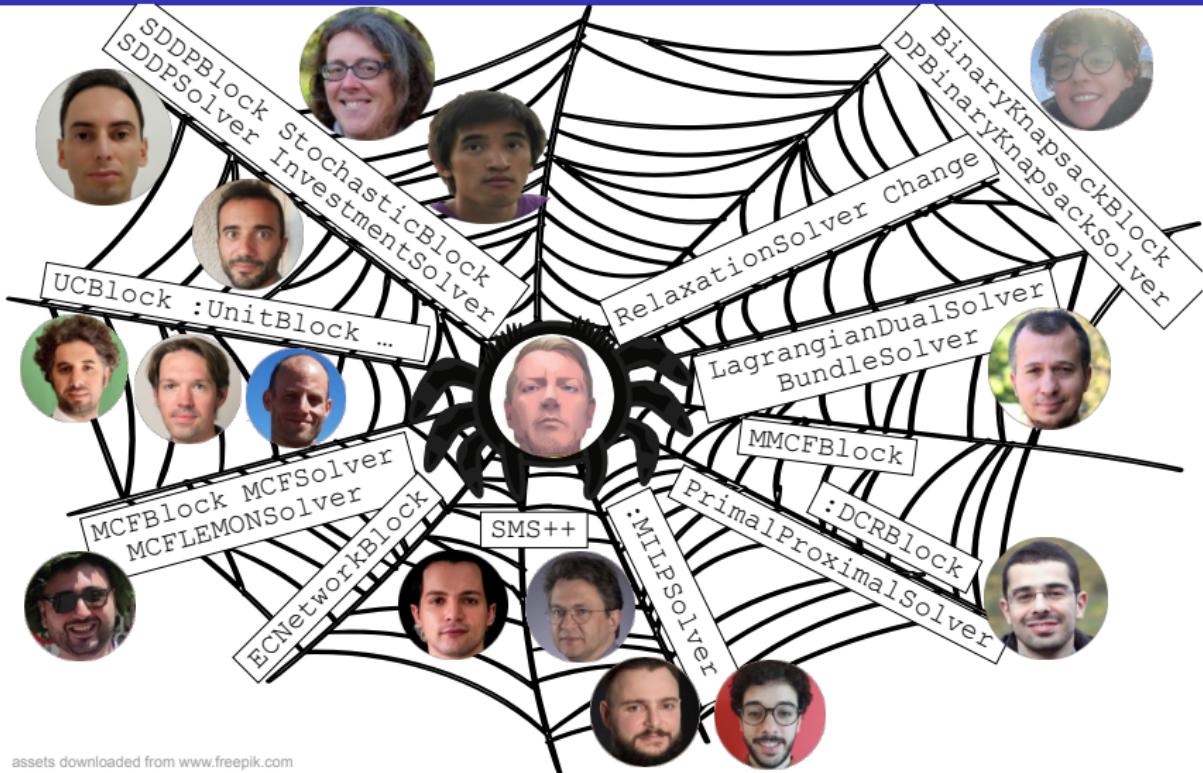


assets downloaded from www.freepik.com

- Not yet a thriving community, but labouring to reach critical mass
- Plenty of room in the Hotel California



... see it for yourself



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- Not yet a thriving community, but labouring to reach critical mass
- Plenty of room in the spiderweb, be my guest

