

DATA STRUCTURE AND ALGORITHM

CLASS 3

Seongjin Lee

Updated by Songsub Kim

insight@gnu.ac.kr

<http://resourceful.github.io>

Systems Research Lab.

GNU



Table of contents

1. Array
2. Structures and Unions
3. Sparse Matrices
 - 3.1 The Abstract Data Type
 - 3.2 Sparse Matrix Representation
 - 3.3 Transposing A Matrix
 - 3.4 Fast Transpose Algorithm

ARRAY



Array I

an **array** is a set of pairs, **<index, value>**, such that each index that is defined has a value associated with it

- “a consecutive set of memory locations” in C
- logical order is the same as physical order

operations

- creating a new array
- retrieves a value
- stores a value
- insert a value into array - delete a value at the array

Array II

ADT: Array

- **Object:** A set of pairs $\langle index, value \rangle$ where for each value of *index* there is a value from the set *item*. *Index* is a finite ordered set of one or more dimensions.
- **Functions:** for all $a \in Array, i \in index, x \in item, j, size \in integer$
 - *Array* create(*j*, *list*): **return** an array of *j* dimension
 - *Item* Retrieve(*A*, *i*): **if** (*i* $\in index$) **return** the item in index value *i* in array *A* **else return** error
 - *Array* Store(*A*, *i*, *x*): **if** (*i* $\in index$) **return** an array that is identical to array *A* except the new pair $\langle i, x \rangle$ has been inserted **else return** error

Array III

An one-dimensional array in C is declared implicitly by appending brackets to the name of a variable

```
int list[5], int *plist[5];
```

Always remember that starting index of array is 0 in C

Array IV

Let's consider implementing an one-dimensional arrays

```
int list[5];
```

- allocates five consecutive memory locations
- each memory location is large enough to hold a single integer
- base address is address of the first element

```
list = &list[0]
```

list[0]	list[1]	list[2]	list[3]	list[4]
trash value	trash value	trash value	trash value	trash value

Array V

Variable	Memory Address
<code>&list[0]</code>	base address = α
<code>&list[1]</code>	$\alpha + \text{sizeof}(\text{int})$
<code>&list[2]</code>	$\alpha + 2 \cdot \text{sizeof}(\text{int})$
<code>&list[3]</code>	$\alpha + 3 \cdot \text{sizeof}(\text{int})$
<code>&list[4]</code>	$\alpha + 4 \cdot \text{sizeof}(\text{int})$

- Because different architectures have different int sizes, we have to use “sizeof”

`&list[i]` in a C programs

- C interprets it as a pointer to an integer or its value

Array VI

```
int *list1; // pointer variable to an int
```

```
int *list2[5]; // list2 : pointer constant to an int,  
               // and five memory locations for holding  
               // integers are reserved
```

```
int list[] = { 0,1,2,3,4,5 };  
^^I  
printf("%d\n", list[3]); // 3  
printf("%d\n", *(&list[0]+3)); // 3  
printf("%d\n", *(list+3)); // 3 ...All is the same expression
```

$(list2+i)$ equals $\&list2[i]$, and $*(list2+i)$ equals $list2[i]$

- regardless of the type of the array `list2`

Array VII

How about this ?

```
printf("%d\n", ++list[0]);
```

- ☐ ++list[0] -> list[0]+1
- ☐ the result is same as list[1]

Array VIII

consider the way C treats an array when it is a parameter to a function

- the parameter passing is done using call-by-value in C
- but array parameters have their values altered

Practice Problem (5 min)

Array: Ex. 2.1 Analyze and comprehend the code before running it

```
#define MAX_SIZE 100
float sum(float [], int);
float input[MAX_SIZE], answer;
int i;
void main(void) {
    for(i = 0; i < MAX_SIZE; i++)
        input[i] = i;
    answer = sum(input, MAX_SIZE);
    printf("The sum is: %f\n", answer);
}

float sum(float list[], int n) {
    int i;
    float tempsum = 0;
    for(i = 0; i < n; i++)
        tempsum += list[i];
    return tempsum;
}
```

Recap: On Pointer I

Pointer Variable stores address

- `&` : Starting address of allocated variable
- `*` : Value stored on the address of the pointer variable

```
1 // pointer_variable.c
2 #include <stdio.h>
3
4 int main(){
5     int nNum, *pNum;
6
7     nNum = 10;
8     pNum = &nNum;
9
10    printf("nNum = %d, &nNum = %d \n", nNum, (int)&nNum);
11    printf("pNum = %d, pNum = %d, &pNum = %d \n",
12           *pNum, (int)pNum, (int)&pNum);
13 }
```

Recap: On Pointer II

Do Not!

- pointer variable is not referencing an address, so cannot store a value

```
int *ptr;  
*ptr = 100;
```

It is better to handle NULL for the pointer that do not refer to address right away

Recap: On Pointer III

Do Not!

- the data type must equal

```
double Pi = 3.14;  
int *pPi = &Pi;
```

- cannot dereference a non-pointer variable

```
int num;  
*num = 100;
```

Recap: On Pointer IV

Do!

- it is recommended to initialize a pointer value with NULL ('\0')
- See the example

```
1 // null_pointer.c
2 #include <stdio.h>
3
4 int main(){
5     int *pNum = NULL, Num=103;
6     if (pNum == '\0')
7         pNum = &Num;
8     else
9         *pNum = 100;
10    printf("pNum %d", (int)*pNum);
11    return 0;
12 }
```


Recap: On Pointer V

```
#include <stdlib.h>
```

```
void *malloc(size_t size); // allocates size bytes of memory and returns  
    a pointer to the allocated memory
```

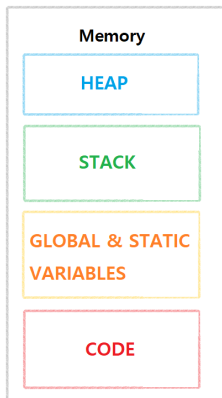
```
void *free(void *ptr); // frees allocation that were created via the  
    preceding allocation function
```

```
void *calloc(size_t count, size_t size); // contiguously allocates  
    enough space for count objects that are size bytes of memory each  
    and returns a pointer to the allocated memory. The allocated memory  
    is filled with bytes of value zero.
```

```
void *realloc(void *ptr, size_t size); // change the size of the  
    allocation pointed to by ptr to size, and returns ptr
```

Recap: On Pointer VI

if the memory is not freed after being allocated, a memory leak will occur



Practice Problem (5 Min)

Array: Ex 2.2, 1-dimensional array addressing

```
int one[] = {0, 1, 2, 3, 4};
```

write a function that prints out both the address of the i^{th} element of the array and the value found at this address

Practice Problem (Solution) I

Array: Ex 2.2, 1-dimensional array addressing

```
1 // codes/array_address.c
2 #include <stdio.h>
3
4 void print1(int *ptr,int rows) {
5     int i;
6     printf("Address\t\tContents\n");
7     for(i=0;i<rows;i++)
8         printf("%8u\t%5d\n", (unsigned int)ptr+i, *(ptr+i));
9     printf("\n");
10 }
11
12 int main() {
13     int one[] = {0, 1, 2, 3, 4};
14     print1(one, 5);
15     return 0;
16 }
```

One-dimensional array accessed by address

- address of i^{th} element $\text{ptr} + i$
- obtain the value of the i^{th} value $\text{*(ptr} + i)$

Practice Problem (Solution) II

Address	Contents
1518325632	0
1518325633	1
1518325634	2
1518325635	3
1518325636	4

One-dimensional array addressing

- the addresses increase by two on an Intel 386 machine
- Example shown is the result of Mac OS X on Intel Core i5 Machine

STRUCTURES AND UNIONS

Structures and Unions: struct I

struct

- structure or record
- the mechanism of grouping data
- permits the data to vary in type

collection of data items where

- each item is identified as to its type and name

Structures and Unions: struct II

```
struct {  
    char name[10];  
    int age;  
    float salary;  
} person;
```

creating a variable

- whose name is person and
- has three fields
 1. a name that is a character array
 2. an integer value representing the age of the person
 3. a float value representing the salary of the individual

Structures and Unions: struct III

use of the .(period) as the structure member operator

```
strcpy(person.name, "james");  
person.age = 30;  
person.salaray = 35000;
```

- select a particular member of the structure

Structures and Unions: struct IV

typedef statement

- create our own structure data type

type 1

```
typedef struct human_being {  
    char name[10];  
    int age;  
    float salary;  
} human;
```

type 2

```
typedef struct {  
    char name[10];  
    int age;  
    float salary;  
} human_being;
```

Structures and Unions: struct V

human_being

- the name of the type defined by the structure definition

```
human_being person1, person2;

if(strcmp(person1.name, person2.name))
    printf("The two people do not have the same name\n");
else
    printf("The two people have the same name\n");
```

Structures and Unions: Assignment

assignment

- permits structure assignment in ANSI C

```
person1 = person2;
```

- but, in most earlier versions of C assignment of structures is not permitted

```
strcpy(person1.name, person2.name);  
person1.age = person2.age;  
person1.salary = person2.salary;
```

Structures and Unions: Equality or Inequality

equality or inequality

- cannot be directly checked
- Example function to check equality of struct

```
int humans_equal(human_being person1, human_being person2) {  
    if(strcmp(person1.name, person2.name))  
        return FALSE;  
    if(person1.age != person2.age)  
        return FALSE;  
    if(person1.salary != person2.salary)  
        return FALSE;  
    return TRUE;  
}
```

Structures and Unions: Embedding Structure I

Embedding of a structure within a structure

```
typedef struct {  
    int month;  
    int day;  
    int year;  
} date;  
  
typedef struct human_being {  
    char name[10];  
    int age;  
    float salary;  
    date dob; // embedded structure  
};
```

Structures and Unions: Embedding Structure II

Ex. A person born on Feb 14 1992

```
human_being person1;  
person1.dob.month = 2;  
person1.dob.day = 14;  
person1.dob.year = 1992;
```

Structures and Unions: Unions I

Unions

- similar to a structure, but
- the fields of a union must share their memory space
- only one field of the union is “active” at any given time

Structures and Unions: Unions II

```
typedef struct sex_type {
    enum tag_field {female,male} sex;
    union {
        int children;
        int beard; } u;
};

typedef struct human_being {
    char name[10];
    int age;
    float salary;
    date dob;
    sex_type sex_info;
};

human_being person1,person2;
```

Structures and Unions: Unions III

Assign values to person1 and person2

```
person1.sex_info.sex = male;  
person1.sex_info.u.beard = FALSE; /* FALSE: 0 */
```

and

```
person2.sex_info.sex = female;  
person2.sex_info.u.children = 4;
```

Differences between structure and union I

What are differences between structure and union ?

- Structure

```
typedef struct example{  
    ^Iint x, y;  
    ^Idouble d;  
}struct_example;  
  
struct_example se;  
  
printf("%d\n", sizeof(se));  
printf("%p %p %p\n", &se.x, &se.y, &se.d);
```

» 16

» 0x7ff0 0x7ff4 0x7ff8

- 16byte size, different address

Differences between structure and union II

○ Union

```
^^Itypedef union example{  
^^I^^Iint x, y;  
^^I^^Idouble d;  
^^I}union_example;  
  
^^Iunion_example ue;  
^^I  
^^Iprintf("%d\n", sizeof(ue));  
^^Iprintf("%p %p %p\n", &ue.x, &ue.y, &ue.d);
```

» 8

» 0x7ff0 0x7ff0 0x7ff0

○ 8byte size, same address

Differences between structure and union III

```
struct {  
    int i, j; float a, b;  
}
```

or

```
struct {  
    int i; int j; float a; float b;  
};
```

stored in the same way

- increasing address locations in the order specified in the structure definition

size of an object of a struct or union type

- the amount of storage necessary to represent the largest component

Structures and Unions: Self-referential structures I

- one or more of its components is a pointer to itself
- usually require dynamic storage management routines to explicitly obtain and release memory

```
typedef struct list {  
    char data;  
    list *link;  
};
```

the value of link

- address in memory of an instance of list or null pointer

Structures and Unions: Self-referential structures II

```
list item1, item2, item3;  
item1.data = 'a';  
item2.data = 'b';  
item3.data = 'c';  
item1.link = item2.link = item3.link = NULL;
```

SPARSE MATRICES



SPARSE MATRICES : THE ABSTRACT DATA TYPE



The Abstract Data Type I

Matrix is a mathematical object that is used to solve many problems in the natural sciences

- our interest centers not only on the specification of an appropriate ADT
- but also in finding representations that let us efficiently perform the operations described in specification

The Abstract Data Type II

A matrix contains m rows and n columns of elements

- write as $m \times n$ and read as m by n (m rows, n columns)
- use two-dimensional array
- space complexity
 $S(m, n) = m * n$

	<i>col0</i>	<i>col1</i>	<i>col2</i>
<i>row0</i>	-27	3	4
<i>row1</i>	6	82	-2
<i>row2</i>	109	-64	11
<i>row3</i>	12	8	9
<i>row4</i>	48	27	47

The Abstract Data Type III

When a matrix is represented as a two-dimensional array defined as `a[MAX_ROWS][MAX_COLS]`

- we can locate quickly any element by writing `a[i][j]`
- i is the row index, j is the column index

The Abstract Data Type IV

There are some problems with $a[i][j]$ notation.

- a matrix with many zero's: *sparse matrix*

$A[6,6]$

	<i>col0</i>	<i>col1</i>	<i>col2</i>	<i>col3</i>	<i>col4</i>	<i>col5</i>
<i>row0</i>	15	0	0	22	0	15
<i>row1</i>	0	11	3	0	0	0
<i>row2</i>	0	0	0	-6	0	0
<i>row3</i>	0	0	0	0	0	0
<i>row4</i>	91	0	0	0	0	0
<i>row5</i>	0	0	28	0	0	0

The Abstract Data Type V

common characteristics of a sparse matrix

- most elements are zero's
- inefficient memory utilization

solutions

- store only nonzero elements
- using the triple $\langle \text{row}, \text{col}, \text{value} \rangle$
- must know
 - the number of rows
 - the number of columns
 - the number of non-zero elements

The Abstract Data Type VI

We first must consider the operations that we want to perform on these Matrices

- matrix creation
- addition
- multiplication
- transpose

The Abstract Data Type VII

ADT: *Sparse Matrix*

- objects: a set of triples $\langle row, column, value \rangle$, where row and $column$ are integers and form a unique combination, and $value$ comes from the set $item$
- Functions: for all
 $a, b \in SparseMatrix, x \in item, i, j, maxCol, maxRow \in index$

The Abstract Data Type VIII

- *SparseMatrix Create(maxRow, maxCol)*
 - Return: a *SparseMatrix* that can hold up to $maxItems = maxRow \times maxCol$ and whose maximum row size is $maxRow$ and whose maximum column size is $maxCol$
- *Sparse Matrix Transpose*
 - Return: the matrix produced by interchanging the row and column value of every triple
- *SparseMatrix Add(a, b)*
 - Return: if the dimensions of a and b are the same return the matrix produced by adding corresponding items, namely those with identical *row* and *column* values else return error
- *SparseMatrix Multiply(a,b)*
 - Return: if number of columns in a equals number of rows in b return the matrix d produced by multiplying a by b according to the formula: $d[i][j] = \sum(a[i][k] \cdot b[k][j])$ where $d(i, j)$ is the (i, j) th element else return error

SPARSE MATRICES : SPARSE MATRIX REPRESENTATION

Sparse Matrix Representation I

Before implementing any of the ADT operations

- we must establish the representation of the sparse matrix
- We can characterize uniquely any element within a matrix by using the triple $\langle row, col, value \rangle$

Other considerations

- We want transpose operation to work efficiently, we should organize the triples so that the row indices are in ascending order
- Also requiring that all the triples for any row be stored so that the column indices are in ascending order
- To ensure that the operations terminate, we must know the number of rows and columns, and the number of nonzero elements in the matrix

Sparse Matrix Representation II

SparseMatrix Create(maxRow, maxCol):

```
#define MAX_TERMS 101 /* max number of terms +1 */

typedef struct {
    int col;
    int row;
    int value;
} term;

term a[MAX_TERMS];
```

- a[o].row: the number of rows
- a[o].col: the number of columns
- a[o].value: the total number of non-zeros
- choose row-major order

Sparse Matrix Representation III

	row	col	value
a[0]	6	6	8
a[1]	0	0	15
a[2]	0	3	22
a[3]	0	5	-15
a[4]	1	1	11
a[5]	1	2	3
a[6]	2	3	-6
a[7]	4	0	91
a[8]	5	2	28

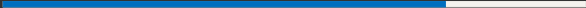
- space complexity (*variable space requirement)
 $S(m,n) = 3 * t$ where
t : the number of non-zero's
- independent of the size of rows and columns

Practice Problem (5 Min)

Write down how the following matrix is represented in our definition of sparse matrix

	<i>col0</i>	<i>col1</i>	<i>col2</i>	<i>col3</i>	<i>col4</i>	<i>col5</i>
<i>row0</i>	15	0	0	22	0	15
<i>row1</i>	0	11	3	0	0	0
<i>row2</i>	0	0	0	-6	0	0
<i>row3</i>	0	0	0	0	0	0
<i>row4</i>	91	0	0	0	0	0
<i>row5</i>	0	0	28	0	0	0

SPARSE MATRICES : TRANSPOSING A MATRIX



Transposing A Matrix I

Transposing the sample matrix

- interchange rows and columns
- move $a[i][j]$ to $a[j][i]$

sample matrix

	row	col	value
a[0]	6	6	8
a[1]	0	0	15
a[2]	0	3	22
a[3]	0	5	-15
a[4]	1	1	11
a[5]	1	2	3
a[6]	2	3	-6
a[7]	4	0	91
a[8]	5	2	28

transposed matrix

	row	col	value
b[0]	6	6	8
b[1]	0	0	15
b[2]	0	4	91
b[3]	1	1	11
b[4]	2	1	3
b[5]	2	5	28
b[6]	3	0	22
b[7]	3	2	-6
b[8]	5	0	-15

Transposing A Matrix II

Algorithm: BAD_TRANSPOSE

```
for each row i
    take element <i, j, value>;
    store it as element <j,i,value> of the transpose;
end;
```

The problem

We will not know exactly where to place element $\langle j, i, value \rangle$ in the transpose matrix until we have processed all the elements that precede

$(0, 0, 15),$	which becomes	$(0, 0, 15)$
$(0, 3, 22),$	which becomes	$(3, 0, 22)$
$(0, 5, -15),$	which becomes	$(5, 0, -15)$

If we place these triples consecutively in the transpose matrix, then, as we insert new triples we must move elements to maintain the correct order

Transposing A Matrix III

We can avoid this data movement by using the column indices to determine the placement of elements in the transpose matrix

Algorithm TRANSPOSE

```
for all elements in column j
    place element <i,j,value> in element <j,i,value>
end for;
```

Since the original matrix ordered the rows, the columns within each row of the transpose matrix will be arranged in ascending order as well

Transposing A Matrix IV

```
1 void transpose(term a[], term b[]) {
2     /* b is set to the transpose of a */
3     int n, i, j, currentb;
4     n = a[0].value; // total number of elements
5     b[0].row = a[0].col; // rows in b = columns in a
6     b[0].col = a[0].row; // columns in b = rows in a
7     b[0].value = n;
8     if(n > 0){ // non zero matrix
9         currentb = 1;
10        for (i = 0; i < a[0].col; i++)
11            /* transpose by the columns in a */
12                for(j = 1; j <= n; j++)
13                    /* find elements from the current column */
14                        if(a[j].col == i) {
15                            /* element is in current column, add it to b */
16                            b[currentb].row = a[j].col;
17                            b[currentb].col = a[j].row;
18                            b[currentb].value = a[j].value;
19                            currentb++;
20                        }
21        }
22    }
23 }
```

Transposing A Matrix V

Analysis of transpose

Computing Time

- nested **for** loops are the decisive factor
- two **if** statements and several assignments statements requires on constant Time
- outer **for** loop is iterated $a[0].col$ times
- inner **for** loop requires $a[0].value$ times
- the total time for the nested **for** loop is $columns \cdot elements :$
 $O(columns \cdot elements)$

The problem

- unnecessary loop for each column

Transposing A Matrix VI

In essence

```
for (j = 0; j < columns; j++)  
    for (i = 0; i < rows; i++)  
        b[j][i] = a[i][j];
```

The $O(\text{columns} \cdot \text{elements})$ time for our transpose function becomes $O(\text{columns}^2 \cdot \text{rows})$

- when the number of elements is of the order $\text{columns} \cdot \text{rows}$

Solution:

- Use a bit more storage

Practice Problem (5 Min)

Find the pros and cons of the transpose algorithm introduced in slide

22

```
1 void transpose(term a[], term b[]) {
2     /* b is set to the transpose of a */
3     int n, i, j, currentb;
4     n = a[0].value; // total number of elements
5     b[0].row = a[0].col; // rows in b = columns in a
6     b[0].col = a[0].row; // columns in b = rows in a
7     b[0].value = n;
8     if(n > 0){ // non zero matrix
9         currentb = 1;
10        for (i = 0; i < a[0].col; i++)
11            /* transpose by the columns in a */
12            for(j = 1; j <= n; j++)
13                /* find elements from the current column */
14                if(a[j].col == i) {
15                    /* element is in current column, add it to b */
16                    b[currentb].row = a[j].col;
17                    b[currentb].col = a[j].row;
18                    b[currentb].value = a[j].value;
19                    currentb++;
20                }
21    }
22 }
```

SPARSE MATRICES : FAST TRANS- POSE ALGORITHM



Fast Transpose Algorithm I

Create better algorithm by using a little more storage

- row_terms the number of element in each row
- starting_pos the starting point of each row

We can transpose a matrix represented as a sequence of triples in $O(\text{columns} + \text{elements})$ time

- determining the number of elements in each column of original matrix (number of elements in each row)
- we can determine the starting position of each row in the transpose matrix
- we can move the elements in the original matrix one by one into their correct position

Fast Transpose Algorithm II

```
1 void fast_transpose(term a[], term b[]){
2
3     /* the transpose of a is placed in b */
4     int row_terms[MAX_COL]; // number of rows in column
5     int starting_pos[MAX_COL]; // column counts
6
7     int i, j;
8
9     // original matrix
10    int numCols = a[0].col; // number of columns
11    int numTerms = a[0].value; // number of elements
12
13    // transposed matrix
14    b[0].row = numCols; // number of rows
15    b[0].col = a[0].row; // number of columns
16    b[0].value = numTerms; // number of elements
17
18    // for non zero matrix
19    if(numTerms > 0) {
20        // initializing matrix
21        for(i = 0; i < numCols; i++)
22            row_terms[i] = 0;
23    }
```

Fast Transpose Algorithm III

```
24      // number of elements in a row
25      for(i = 1; i <= numTerms; i++)
26          row_terms[a[i].col]++;
27
28      starting_pos[0] = 1;
29
30      // accounting column position
31      for(i = 1; i < numCols; i++)
32          starting_pos[i] = starting_pos[i-1] + row_terms[i-1];
33
34      // transposing
35      for(i = 1; i <= numTerms; i++){
36          j = starting_pos[a[i].col]++;
37          b[j].row = a[i].col;
38          b[j].col = a[i].row;
39          b[j].value = a[i].value;
40      }
41  }
42 }
```

Fast Transpose Algorithm IV

Initial values:

```
numCols = a[0].col = 6  
numTerms = a[0].value = 8
```

```
b[0].row = numCols = 6  
b[0].col = a[0].row = 6  
b[0].value = numTerms = 8
```

	row	col	value
a[0]	6	6	8
a[1]	0	0	15
a[2]	0	3	22
a[3]	0	5	-15
a[4]	1	1	11
a[5]	1	2	3
a[6]	2	3	-6
a[7]	4	0	91
a[8]	5	2	28

Fast Transpose Algorithm V

Number of elements in a row

```
20 // initializing matrix
21 for(i = 0; i < numcols; i++)
22     row_terms[i] = 0;
23
24 // number of elements in a row
25 for(i = 1; i <= numTerms; i++)
26     row_terms[a[i].col]++;
```

code	line 22	a[i].col	line 26
row_terms[0]	0	1+1	2
row_terms[1]	0	1	1
row_terms[2]	0	1+1	2
row_terms[3]	0	1+1	2
row_terms[4]	0	-	0
row_terms[5]	0	1	1

i	a[i].col	row_terms [a[i].col]++
1	0	1
2	3	1
3	5	1
4	1	1
5	2	1
6	3	2
7	0	2
8	2	2

Fast Transpose Algorithm VI

starting_pos caculation

```
28  starting_pos[0] = 1;
29
30  // accounting column position
31  for(i = 1; i < numcols; i++)
32      starting_pos[i] =
33      starting_pos[i-1]+row_terms[i-1];
```

start_pos[i]	start_pos[i-1] +rowterm[i-1]	result
start_pos[0]	1	1
start_pos[1]	1+2	3
start_pos[2]	3+1	4
start_pos[3]	4+2	6
start_pos[4]	6+2	8
start_pos[5]	8+0	8

Transposing routine

```
34  // transposing
35  for(i = 1; i <= numTerms; i++){
36      j = starting_pos[a[i].col]++;
37      b[j].row = a[i].col;
38      b[j].col = a[i].row;
39      b[j].value = a[i].value;
```

i	a[i].col	start_pos [a[i].col]++	a[i]	b[j]
1	0	1	a[1]	b[1]
2	3	6	a[2]	b[6]
3	5	8	a[3]	b[8]
4	1	3	a[4]	b[3]
5	2	4	a[5]	b[4]
6	3	7	a[6]	b[7]
7	0	2	a[7]	b[2]
8	2	5	a[8]	b[5]

Fast Transpose Algorithm VII

final form

ori	row	col	value	trans	row	col	value	final	row	col	value
a[0]	6	6	8	b[0]	6	6	8	b[0]	6	6	8
a[1]	0	0	15	b[1]	0	0	15	b[1]	0	0	15
a[2]	0	3	22	b[6]	0	3	22	b[2]	0	4	91
a[3]	0	5	-15	b[8]	0	5	-15	b[3]	1	1	11
a[4]	1	1	11	b[3]	1	1	11	b[4]	2	1	3
a[5]	1	2	3	b[4]	1	2	3	b[5]	2	5	28
a[6]	2	3	-6	b[7]	2	3	-6	b[6]	3	0	22
a[7]	4	0	91	b[2]	4	0	91	b[7]	3	2	-6
a[8]	5	2	28	b[5]	5	2	28	b[8]	5	0	-15

Fast Transpose Algorithm VIII

Analysis of `fast_transpose()`

- First two for loops compute the values for *rowTerms*
 - computing time: *numCols* and *numTerms*
- the third for loop carries out the computation of *startingPos*
 - computing time: *numCols* - 1
- the last for loop places the triples into the transpose matrix
 - computing time: *numTerms*
- Complexity of the algorithm : $O(\text{columns} + \text{elements})$
 - Worst case : $O(\text{columns} \cdot \text{elements})$ when number of elements is of the order $\text{columns} \cdot \text{elements}$

Practice Problem (5 Min)

Analyze and understand the algorithm of fast_transpose

```
void fast_transpose(term a[], term b[]){
    ...
    if(numTerms > 0) {
        for(i = 0; i < numcols; i++)
            row_terms[i] = 0;
        for(i = 1; i <= numTerms; i++)
            row_terms[a[i].col]++;
        starting_pos[0] = 1;
        for(i = 1; i < numcols; i++)
            starting_pos[i] = starting_pos[i-1] + row_terms[i-1];
        for(i = 1; i <= numTerms; i++){
            j = starting_pos[a[i].col]++;
            b[j].row = a[i].col;
            b[j].col = a[i].row;
            b[j].value = a[i].value;
        }
    }
}
```