

RICHMOND ESSIEKU PS 3 & PS4

PART 3

```
Rich_Data_ = New_Concatenated_Data1
matrixData = table2array(New_Concatenated_Data1);
matrixData = repmat(matrixData, 15, 1);
% Extract submatrices from A
Export = matrixData(:, 1:15);           % First 15 columns
size(Export)
distance = matrixData(:, 16:30);        % Next 15 columns
size(distance)
GDP = matrixData(:, 31);                 % 31st column
size(GDP)
contiguity = matrixData(:, end-14:end);  % Last 15 columns
size(contiguity)
```

```
% % Take logs
log_(export) = log(X);
size(log_(export))
log_(distance) = log(distance);
size(log_(distance))
log_(contiguity) = log(contiguity);
size(log_(contiguity))
log_(GDP) = log(GDP);
size(log_(GDP))
```

Rich_Data_1_

Rich_Data_1_ = 3375x6 table

Rich_Data.Properties

```
ans =
    TableProperties with properties:

    Description: ''
    UserData: []
    DimensionNames: {'Row' 'Variables'}
    VariableNames: {'log_export_' 'log_distance_' 'log_contiguity_'
'log_Pi_' 'log_Pj_' 'log_GDP_'}
    VariableDescriptions: {}
    VariableUnits: {}
    VariableContinuity: []
    RowNames: {}
    CustomProperties: No custom properties are set.
    Use addprop and rmprop to modify CustomProperties.
```

```
summary(Rich_Data_1_)
```

Variables:

log_export_: 3375×1 double

Values:

Min	2.7391
Median	9.6268
Max	12.889

log_distance_: 3375×1 double

Values:

Min	1.8353
Median	3.7811
Max	11.655

log_contiguity_: 3375×1 double

Values:

Min	0
Median	0
Max	1

log_Pi_: 3375×1 double

Values:

Min	0
Median	0
Max	1

log_Pj_: 3375×1 double

Values:

Min	0
Median	0
Max	1

log_GDP_: 3375×1 double

Values:

Min	-4.5491
Median	1.2927
Max	13.287

```
% Define the gravity model formula
% Define the gravity model formula
gravity_model_formula = 'log_export_~ log_GDP_ + log_distance_ +
log_contiguity_ + log_Pi_ + log_Pj_';
```

```
%gravity_model_formula = 'Rich_Data.log_export_~ Rich_Data.log_GDP_ -
Rich_Data.log_distance_ + Rich_Data.log_contiguity_ + Rich_Data.log_Pi_ +
Rich_Data.log_Pj_';
```

```
% Estimate gravity model
```

```
gravity_model = fitlm(Rich_Data, gravity_model_formula);
```

```
% Display the regression results
```

```
disp(gravity_model);
```

Linear regression model:

log_export_ ~ 1 + log_distance_ + log_contiguity_ + log_Pi_ + log_Pj_ + log_GDP_

Estimated Coefficients:

	Estimate	SE	tStat	pValue
(Intercept)	12.973	0.055888	232.12	0
log_distance_	-0.90555	0.016625	-54.468	0
log_contiguity_	0.017231	0.039263	0.43886	0.66079
log_Pi_	0.16729	0.048556	3.4453	0.00057736
log_Pj_	0.16785	0.048767	3.4418	0.00058482
log_GDP_	-0.049556	0.008778	-5.6455	1.7835e-08

Number of observations: 3375, Error degrees of freedom: 3369

Root Mean Squared Error: 0.697

R-squared: 0.839, Adjusted R-Squared: 0.839

F-statistic vs. constant model: 3.51e+03, p-value = 0

```
% Step 3: Report Point Estimates and Standard Errors
```

```
disp('Point Estimates (Gravity Model):');
```

Point Estimates (Gravity Model):

```
disp(gravity_model.Coefficients.Estimate);
```

```
12.9726
-0.9055
0.0172
0.1673
0.1678
-0.0496
```

```
disp('Standard Errors (Gravity Model):');
```

Standard Errors (Gravity Model):

```
disp(gravity_model.Coefficients.SE);
```

```
0.0559
0.0166
0.0393
0.0486
0.0488
0.0088
```

```
% Extract structural parameters
structural_parameters = table2array(gravity_model.Coefficients(2:end, 1));

% Display structural parameters
disp('Structural Parameters:');
```

Structural Parameters:

```
disp(structural_parameters);
```

```
-0.9055
0.0172
0.1673
0.1678
-0.0496
```

Where $b = 0.1673$, $\rho = 0.0172$ and $\sigma = 0.822$

```
% Step 4: Recover Standard Errors using Delta Method
% Assuming you have a function g(theta) representing the gravity model
% This is a simplified example; you'll need to adapt it to your specific model

% Define the Jacobian matrix of g(theta) with respect to the parameters
%Jacobian = [diff(g(theta), theta(1)), diff(g(theta), theta(2)), diff(g(theta),
theta(3)), diff(g(theta), theta(4)), diff(g(theta), theta(5))];
% Calculate the standard errors using the Delta Method formula

%cov_matrix = gravity_model.CoefficientCovariance; % Covariance matrix from
fitlm

%se_delta_method = sqrt(diag(Jacobian * cov_matrix * Jacobian'));

%disp('Standard Errors (Delta Method):');
%disp(se_delta_method);
num_obs = 3375;

% Step 4: Recover Point Estimates and Standard Errors using Delta Method
% Define the Jacobian matrix of the gravity model equation with respect to
parameters

Jacobian = [ones(num_obs, 1), Rich_Data.log_GDP_, Rich_Data.log_distance_,
Rich_Data.log_contiguity_, Rich_Data.log_Pi_, Rich_Data.log_Pj_];
```

```

% Calculate the point estimates using the Delta Method formula
point_estimates_delta_method = gravity_model.Coefficients.Estimate;

% Calculate the standard errors using the Delta Method formula
cov_matrix = gravity_model.CoefficientCovariance;

se_delta_method = sqrt(diag(Jacobian * cov_matrix * Jacobian'));
disp('Point Estimates (Delta Method):');

```

Point Estimates (Delta Method):

```
disp(point_estimates_delta_method);
```

```

12.9726
-0.9055
 0.0172
 0.1673
 0.1678
-0.0496

```

```
disp('Standard Errors (Delta Method):');
```

Standard Errors (Delta Method):

```
disp(se_delta_method);
```

```

0.4644
0.3692
0.3531
0.3741
0.3978
0.3731
0.3917
0.3507
0.3837
0.3863
0.4075
0.3813
0.3481
0.3636
0.3971
0.4644
0.3692
0.3531
0.3741
0.3978
0.3731
.....

```

PART 4

```
% Import the data
IV_Data = readtable("/Users/richmondessieku/Downloads/IV_Data.xlsx", opts2,
"UseExcel", false);

% Clear temporary variables
clear opts2

% Display results
IV_Data
```

```
IV_Data = 65535x7 table
```

```
size(IV_Data)
```

```
ans = 1x2
      65535      7
```

```
% PS 4
% First stage regression
model_formula1 = 'log_distance_ ~ Log_pop_pwt_o_';
first_stage_model = fitlm(IV_Data, model_formula1);
```

```

IV_Data.predicted_DIST = predict(first_stage_model, IV_Data);
IV_Data
%n_obs = 65535;
%IV_Data.predicted_DIST = IV_Data.predicted_DIST + randn(n_obs, 1);
%IV_Data
% Display results
disp('First Stage Regression:');

```

First Stage Regression:

```
disp(first_stage_model);
```

Linear regression model:
 $\log_distance_ \sim 1 + \log_pop_pwt_o_$

Estimated Coefficients:

	Estimate	SE	tStat	pValue
(Intercept)	3.9149	0.0049124	796.94	0
Log_pop_pwt_o_	5.6769e-05	0.00060231	0.094253	0.92491

Number of observations: 65535, Error degrees of freedom: 65533
Root Mean Squared Error: 0.364
R-squared: 1.36e-07, Adjusted R-Squared: -1.51e-05
F-statistic vs. constant model: 0.00888, p-value = 0.925

```

% Second stage regression (2SLS)
model_formula2 = 'log_export_ ~ - predicted_DIST + log_GDP_ + log_contiguity_ + log_Pi_ + log_Pj_';
second_stage_model = fitlm(IV_Data, model_formula2);

% Display results
disp('Second Stage Regression (2SLS):');

```

Second Stage Regression (2SLS):

```
disp(second_stage_model);
```

Linear regression model:
 $\log_export_ \sim 1 + \log_contiguity_ + \log_Pi_ + \log_Pj_ + \log_GDP_$

Estimated Coefficients:

	Estimate	SE	tStat	pValue
(Intercept)	10.026	0.0022485	4458.9	0
log_contiguity_	-0.21084	0.012139	-17.369	2.0029e-67
log_Pi_	-0.0409	0.01452	-2.8168	0.0048512
log_Pj_	-0.085548	0.014558	-5.8763	4.216e-09
log_GDP_	-0.47624	0.0012295	-387.34	0

Number of observations: 65535, Error degrees of freedom: 65530

Root Mean Squared Error: 0.217
R-squared: 0.697, Adjusted R-Squared: 0.697
F-statistic vs. constant model: 3.78e+04, p-value = 0

```
% The Minimum Chi-Square Estimator (MCSE)
```

```
% Define the structural equation model
```

```
model_formula3 = 'log_export_~ log_GDP_ + log_distance_ + log_contiguity_ +  
log_Pi_ + log_Pj_';
```

```
% Fit the model using the Minimum Chi-Square Estimator
```

```
options = statset('MaxIter', 100); % Increase max iterations if needed
```

```
fitResult = fit(IV_Data, model_formula3, 'mcest', 'Options', options);
```

```
Error using fit>iFit
```

```
X must be a matrix with one or two columns.
```

```
Error in fit (line 116)
```

```
[fitobj, goodness, output, convmsg] = iFit( xdatain, ydatain, fittypeobj, ...
```

```
% Display results
```

```
%disp(fitResult);
```