Welcome to SDC Fundamentals: Featuring Apollo

Identify the key parts of self-driving cars, and get to know the Apollo team and architecture.





HD Maps

High-definition maps underpin almost every other part of the software stack. Learn how these maps work!



VIEW LESSON →

Localization

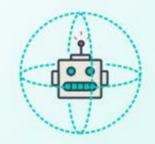
Learn how the vehicle localizes itself with single-digit-centimeter-level accuracy.



VIEW LESSON →

Perception

Identify different perception tasks such as classification, detection, and segmentation. Also, learn about convolutional neural networks, which are critical to perception.







Prediction

Study different ways to predict how other vehicles or pedestrians might interact with Apollo self-driving cars.





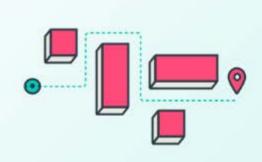
Planning

Identify several different approaches Apollo uses to develop trajectories for autonomous vehicles.





SHRINK CARD



Control

Understand how to use steering, throttle, and brake to execute our planned trajectory and master different types of controllers in Apollo.



VIEW LESSON →

100% VIEWED

IRINK CARD

Congratulations

Congratulations on completing the course! Here, you'll receive some suggestions for future learning to pursue a self-driving car engineering career.



