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**COURSE TITLE : PRACTICAL MACHINE LEARNING LAB**

### LAB.10 Patient Physical Activities Prediction using Boosting2

```
In [1]: import pandas as pan
```

#### Step-I

```
In [2]: human=pan.read_csv("C:\\Users\\user\\Downloads\\dataset_pm1\\Human_Activity_Data.csv")
```

```
In [3]: human.head()
```

```
Out[3]:
```

	tBodyAcc-mean()-X	tBodyAcc-mean()-Y	tBodyAcc-mean()-Z	tBodyAcc-std()-X	tBodyAcc-std()-Y	tBodyAcc-std()-Z	tBodyAcc-mad()-X	tBodyAcc-mad()-Y	tBodyAcc-mad()-Z	tBodyAcc-max()-X	...	fBodyBodyGyroJerkMag-skewness()
0	0.288585	-0.020294	-0.132905	-0.995279	-0.983111	-0.913526	-0.995112	-0.983185	-0.923527	-0.934724	...	-0.298676
1	0.278419	-0.016411	-0.123520	-0.998245	-0.975300	-0.960322	-0.998807	-0.974914	-0.957686	-0.943068	...	-0.595051
2	0.279653	-0.019467	-0.113462	-0.995380	-0.967187	-0.978944	-0.996520	-0.963668	-0.977469	-0.938692	...	-0.390748
3	0.279174	-0.026201	-0.123283	-0.996091	-0.983403	-0.990675	-0.997099	-0.982750	-0.989302	-0.938692	...	-0.117290
4	0.276629	-0.016570	-0.115362	-0.998139	-0.980817	-0.990482	-0.998321	-0.979672	-0.990441	-0.942469	...	-0.351471

5 rows × 562 columns

```
In [4]: human.shape
```

```
Out[4]: (10299, 562)
```

```
In [5]: human.columns
```

```
Out[5]: Index(['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 'tBodyAcc-mean()-Z',
              'tBodyAcc-std()-X', 'tBodyAcc-std()-Y', 'tBodyAcc-std()-Z',
              'tBodyAcc-mad()-X', 'tBodyAcc-mad()-Y', 'tBodyAcc-mad()-Z',
              'tBodyAcc-max()-X',
              ...,
              'fBodyBodyGyroJerkMag-skewness()', 'fBodyBodyGyroJerkMag-kurtosis()',
              'angle(tBodyAccMean,gravity)', 'angle(tBodyAccJerkMean,gravityMean)',
              'angle(tBodyGyroMean,gravityMean)',
              'angle(tBodyGyroJerkMean,gravityMean)', 'angle(X,gravityMean)',
              'angle(Y,gravityMean)', 'angle(Z,gravityMean)', 'Activity'],
              dtype='object', length=562)
```

```
In [6]: human.dtypes
```

```
Out[6]: tBodyAcc-mean()-X      float64
        tBodyAcc-mean()-Y      float64
        tBodyAcc-mean()-Z      float64
        tBodyAcc-std()-X       float64
        tBodyAcc-std()-Y       float64
        ...
        angle(tBodyGyroJerkMean,gravityMean) float64
        angle(X,gravityMean)      float64
        angle(Y,gravityMean)      float64
        angle(Z,gravityMean)      float64
        Activity                  object
        Length: 562, dtype: object
```

```
In [7]: human.info()
```

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 10299 entries, 0 to 10298
Columns: 562 entries, tBodyAcc-mean()-X to Activity
dtypes: float64(561), object(1)
memory usage: 44.2+ MB
```

```
In [8]: human.value_counts
```

```

Out[8]: <bound method DataFrame.value_counts of
0          0.288585          -0.020294          -0.132905
1          0.278419          -0.016411          -0.123520
2          0.279653          -0.019467          -0.113462
3          0.279174          -0.026201          -0.123283
4          0.276629          -0.016570          -0.115362
...
10294       0.310155          -0.053391          -0.099109
10295       0.363385          -0.039214          -0.105915
10296       0.349966           0.030077          -0.115788
10297       0.237594           0.018467          -0.096499
10298       0.153627          -0.018437          -0.137018

```

```

          tBodyAcc-std()-X tBodyAcc-std()-Y tBodyAcc-std()-Z tBodyAcc-mad()-X \
0          -0.995279          -0.983111          -0.913526          -0.995112
1          -0.998245          -0.975300          -0.960322          -0.998807
2          -0.995380          -0.967187          -0.978944          -0.996520
3          -0.996091          -0.983403          -0.990675          -0.997099
4          -0.998139          -0.980817          -0.990482          -0.998321
...
10294       -0.287866          -0.140589          -0.215088          -0.356083
10295       -0.305388           0.028148          -0.196373          -0.373540
10296       -0.329638          -0.042143          -0.250181          -0.388017
10297       -0.323114          -0.229775          -0.207574          -0.392380
10298       -0.330046          -0.195253          -0.164339          -0.430974

```

```

          tBodyAcc-mad()-Y tBodyAcc-mad()-Z tBodyAcc-max()-X ... \
0          -0.983185          -0.923527          -0.934724 ...
1          -0.974914          -0.957686          -0.943068 ...
2          -0.963668          -0.977469          -0.938692 ...
3          -0.982750          -0.989302          -0.938692 ...
4          -0.979672          -0.990441          -0.942469 ...
...
10294       -0.148775          -0.232057           0.185361 ...
10295       -0.030036          -0.270237           0.185361 ...
10296       -0.133257          -0.347029           0.007471 ...
10297       -0.279610          -0.289477           0.007471 ...
10298       -0.218295          -0.229933          -0.111527 ...

```

```

          fBodyBodyGyroJerkMag-skewness() fBodyBodyGyroJerkMag-kurtosis() \
0          -0.298676          -0.710304
1          -0.595051          -0.861499
2          -0.390748          -0.760104
3          -0.117290          -0.482845
4          -0.351471          -0.699205
...
10294       -0.376278          -0.750809

```

10295	-0.320418	-0.700274
10296	-0.118854	-0.467179
10297	-0.205445	-0.617737
10298	-0.072237	-0.436940

	angle(tBodyAccMean,gravity)	angle(tBodyAccJerkMean),gravityMean)	\
0	-0.112754	0.030400	
1	0.053477	-0.007435	
2	-0.118559	0.177899	
3	-0.036788	-0.012892	
4	0.123320	0.122542	
...	...	...	
10294	-0.337422	0.346295	
10295	-0.736701	-0.372889	
10296	-0.181560	0.088574	
10297	0.444558	-0.819188	
10298	0.598808	-0.287951	

	angle(tBodyGyroMean,gravityMean)	angle(tBodyGyroJerkMean,gravityMean)	\
0	-0.464761	-0.018446	
1	-0.732626	0.703511	
2	0.100699	0.808529	
3	0.640011	-0.485366	
4	0.693578	-0.615971	
...	...	...	
10294	0.884904	-0.698885	
10295	-0.657421	0.322549	
10296	0.696663	0.363139	
10297	0.929294	-0.008398	
10298	0.876030	-0.024965	

	angle(X,gravityMean)	angle(Y,gravityMean)	angle(Z,gravityMean)	\
0	-0.841247	0.179941	-0.058627	
1	-0.844788	0.180289	-0.054317	
2	-0.848933	0.180637	-0.049118	
3	-0.848649	0.181935	-0.047663	
4	-0.847865	0.185151	-0.043892	
...	...	...	...	
10294	-0.651732	0.274627	0.184784	
10295	-0.655181	0.273578	0.182412	
10296	-0.655357	0.274479	0.181184	
10297	-0.659719	0.264782	0.187563	
10298	-0.660080	0.263936	0.188103	

	Activity
0	STANDING
1	STANDING
2	STANDING

```
3          STANDING
4          STANDING
...
10294  WALKING_UPSTAIRS
10295  WALKING_UPSTAIRS
10296  WALKING_UPSTAIRS
10297  WALKING_UPSTAIRS
10298  WALKING_UPSTAIRS
```

```
[10299 rows x 562 columns]>
```

## Step-2 [Build a small dataset]

```
In [9]: human["Activity"].unique()
```

```
Out[9]: array(['STANDING', 'SITTING', 'LAYING', 'WALKING', 'WALKING_DOWNSTAIRS',
              'WALKING_UPSTAIRS'], dtype=object)
```

```
In [10]: df = human.loc[human["Activity"].isin(["WALKING", "SITTING", "LAYING"])]
```

```
In [11]: walk= human.loc[human["Activity"] == "WALKING"].sample(500)
sit= human.loc[human["Activity"] == "SITTING"].sample(500)
lay=human.loc[human["Activity"] == "LAYING"].sample(500)
```

```
In [12]: nd= pan.concat([walk, sit, lay])
```

```
In [13]: nd.to_csv("Human.csv",index=False)
```

## Step-3 [Build GradientBoostingClassifier]

```
In [14]: Data=pan.read_csv("Human.csv")
Data.head()
```

Out[14]:

	tBodyAcc-mean()-X	tBodyAcc-mean()-Y	tBodyAcc-mean()-Z	tBodyAcc-std()-X	tBodyAcc-std()-Y	tBodyAcc-std()-Z	tBodyAcc-mad()-X	tBodyAcc-mad()-Y	tBodyAcc-mad()-Z	tBodyAcc-max()-X	...	fBodyBodyGyroJerkMag-skewness()
0	0.223498	-0.004764	-0.054825	-0.298798	-0.115901	-0.317805	-0.336247	-0.124901	-0.333654	0.022884	...	0.550369
1	0.331556	-0.037826	-0.125532	-0.399544	-0.254734	-0.151447	-0.391599	-0.291021	-0.124841	-0.399624	...	-0.159240
2	0.249343	-0.003411	-0.056042	-0.399476	-0.137845	-0.461271	-0.437246	-0.198605	-0.453340	-0.179696	...	-0.495646
3	0.271651	-0.015662	-0.144156	-0.350667	-0.231905	-0.325115	-0.397051	-0.240116	-0.328589	-0.137797	...	-0.326996
4	0.315267	0.016745	-0.138095	-0.382439	-0.157401	-0.563687	-0.403496	-0.147394	-0.568735	-0.228827	...	-0.575934

5 rows × 562 columns

```
In [15]: Data.shape
```

Out[15]: (1500, 562)

```
In [16]: Data.dtypes
```

Out[16]: tBodyAcc-mean()-X float64  
tBodyAcc-mean()-Y float64  
tBodyAcc-mean()-Z float64  
tBodyAcc-std()-X float64  
tBodyAcc-std()-Y float64  
...  
angle(tBodyGyroJerkMean,gravityMean) float64  
angle(X,gravityMean) float64  
angle(Y,gravityMean) float64  
angle(Z,gravityMean) float64  
Activity object  
Length: 562, dtype: object

In [17]: Data.value\_counts



```
Out[17]: <bound method DataFrame.value_counts of
0          0.223498          -0.004764          -0.054825
1          0.331556          -0.037826          -0.125532
2          0.249343          -0.003411          -0.056042
3          0.271651          -0.015662          -0.144156
4          0.315267          0.016745          -0.138095
...
1495        0.284841          -0.019201          -0.107611
1496        0.278778          0.001278          -0.129886
1497       -0.503823          -0.594207          0.264804
1498        0.273700          -0.012533          -0.114728
1499        0.264384          -0.017022          -0.107920
```

```
          tBodyAcc-std()-X tBodyAcc-std()-Y tBodyAcc-std()-Z tBodyAcc-mad()-X \
0          -0.298798          -0.115901          -0.317805          -0.336247
1          -0.399544          -0.254734          -0.151447          -0.391599
2          -0.399476          -0.137845          -0.461271          -0.437246
3          -0.350667          -0.231905          -0.325115          -0.397051
4          -0.382439          -0.157401          -0.563687          -0.403496
...
1495        -0.972128          -0.995757          -0.991906          -0.972685
1496        -0.993938          -0.957732          -0.975728          -0.994663
1497        -0.703402          0.672487          -0.464985          -0.704548
1498        -0.983734          -0.970662          -0.981009          -0.986951
1499        -0.949239          -0.971667          -0.971883          -0.947305
```

```
          tBodyAcc-mad()-Y tBodyAcc-mad()-Z tBodyAcc-max()-X ... \
0          -0.124901          -0.333654          0.022884 ...
1          -0.291021          -0.124841          -0.399624 ...
2          -0.198605          -0.453340          -0.179696 ...
3          -0.240116          -0.328589          -0.137797 ...
4          -0.147394          -0.568735          -0.228827 ...
...
1495        -0.994660          -0.992572          -0.912239 ...
1496        -0.952886          -0.972024          -0.934344 ...
1497         0.967664          -0.401827          -0.948813 ...
1498        -0.974966          -0.981606          -0.908698 ...
1499        -0.968391          -0.970534          -0.904388 ...
```

```
          fBodyBodyGyroJerkMag-skewness() fBodyBodyGyroJerkMag-kurtosis() \
0          0.550369          0.344301
1          -0.159240          -0.604960
2          -0.495646          -0.808660
3          -0.326996          -0.706172
4          -0.575934          -0.884190
...
1495        -0.851367          -0.981048
```

1496	-0.640985	-0.894815
1497	-0.412991	-0.718527
1498	0.617445	0.439463
1499	-0.284005	-0.700522

	angle(tBodyAccMean,gravity)	angle(tBodyAccJerkMean),gravityMean)	\
0	0.476859	0.083179	
1	-0.645232	-0.647860	
2	0.258529	0.038298	
3	-0.047375	0.927682	
4	-0.069911	-0.250392	
...	...	...	
1495	0.205729	-0.211422	
1496	0.027342	0.020652	
1497	0.249525	0.440171	
1498	0.043347	-0.532228	
1499	0.002422	-0.365710	

	angle(tBodyGyroMean,gravityMean)	angle(tBodyGyroJerkMean,gravityMean)	\
0	-0.093855	-0.775732	
1	0.489015	-0.798114	
2	0.904697	-0.421875	
3	0.933117	0.216304	
4	-0.412534	0.603081	
...	...	...	
1495	0.395310	-0.229736	
1496	0.110563	0.167558	
1497	-0.007508	0.343715	
1498	0.542719	-0.023971	
1499	0.554906	0.262370	

	angle(X,gravityMean)	angle(Y,gravityMean)	angle(Z,gravityMean)	\
0	-0.721141	0.265173	0.116227	
1	-0.675771	0.231274	0.203654	
2	-0.670009	0.325729	0.004459	
3	-0.716721	0.235446	0.161681	
4	-0.750986	0.257155	-0.049705	
...	...	...	...	
1495	0.539980	-0.488183	-0.517488	
1496	0.407937	-0.315549	-0.673453	
1497	0.683948	-0.505728	-0.495238	
1498	0.612304	-0.363663	-0.648593	
1499	0.545731	-0.234862	-0.780867	

	Activity
0	WALKING
1	WALKING
2	WALKING

```
3      WALKING
4      WALKING
...
1495    LAYING
1496    LAYING
1497    LAYING
1498    LAYING
1499    LAYING
```

```
[1500 rows x 562 columns]>
```

```
In [18]: Data.info()
```

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 1500 entries, 0 to 1499
Columns: 562 entries, tBodyAcc-mean()-X to Activity
dtypes: float64(561), object(1)
memory usage: 6.4+ MB
```

```
In [19]: Data.columns
```

```
Out[19]: Index(['tBodyAcc-mean()-X', 'tBodyAcc-mean()-Y', 'tBodyAcc-mean()-Z',
               'tBodyAcc-std()-X', 'tBodyAcc-std()-Y', 'tBodyAcc-std()-Z',
               'tBodyAcc-mad()-X', 'tBodyAcc-mad()-Y', 'tBodyAcc-mad()-Z',
               'tBodyAcc-max()-X',
               ...
               'fBodyBodyGyroJerkMag-skewness()', 'fBodyBodyGyroJerkMag-kurtosis()',
               'angle(tBodyAccMean,gravity)', 'angle(tBodyAccJerkMean,gravityMean)',
               'angle(tBodyGyroMean,gravityMean)',
               'angle(tBodyGyroJerkMean,gravityMean)', 'angle(X,gravityMean)',
               'angle(Y,gravityMean)', 'angle(Z,gravityMean)', 'Activity'],
              dtype='object', length=562)
```

```
In [20]: from sklearn.model_selection import train_test_split as tts
         from sklearn.ensemble import GradientBoostingClassifier as GBC
         from sklearn.metrics import *
```

```
In [21]: X=Data.drop("Activity",axis=1)
         y=Data["Activity"]
```

```
In [22]: X_train,X_test,y_train,y_test=tts(X,y,test_size=.3,random_state=42)
len(X_train)
len(y_train)
```

Out[22]: 1050

```
In [23]: gbc=GBC(n_estimators=100, learning_rate=0.1, max_depth=3,random_state=42)
```

```
In [24]: gbc.fit(X_train,y_train)
```

Out[24]: GradientBoostingClassifier(random\_state=42)

```
In [25]: y_pred=gbc.predict(X_test)
```

```
In [26]: accuracy_score(y_test,y_pred)
```

Out[26]: 1.0

```
In [27]: print(classification_report(y_test,y_pred), '/n')
```

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	161
SITTING	1.00	1.00	1.00	141
WALKING	1.00	1.00	1.00	148
accuracy			1.00	450
macro avg	1.00	1.00	1.00	450
weighted avg	1.00	1.00	1.00	450

/n

#### Step-4 [Find Best no. of Trees and Best Learning Rate using Grid Search and Cross Validation]

```
In [28]: # Create GridSearchCV model with GradientBoostingClassifier

from sklearn.model_selection import GridSearchCV as gsc
```

In [29]: *#parameters*

```
param_grid={'n_estimators':[50,100,200,400],'learning_rate':[0.1,0.01]}
```

In [30]: `grid= gsc(gbc, param_grid, cv=5,verbose=3, n_jobs=-1)`

In [31]: *# Fit the GridSearchCV model on the training data*

```
grid.fit(X_train, y_train)
```

Fitting 5 folds for each of 8 candidates, totalling 40 fits

Out[31]: GridSearchCV(cv=5, estimator=GradientBoostingClassifier(random\_state=42),  
n\_jobs=-1,  
param\_grid={'learning\_rate': [0.1, 0.01],  
'n\_estimators': [50, 100, 200, 400]},  
verbose=3)

In [32]: *#predict the data*

```
y1_pred=grid.predict(X_test)
```

In [33]: `accuracy_score(y_test,y1_pred)`

Out[33]: 1.0

In [34]: `print(classification_report(y_test,y1_pred), '/n')`

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	161
SITTING	1.00	1.00	1.00	141
WALKING	1.00	1.00	1.00	148
accuracy			1.00	450
macro avg	1.00	1.00	1.00	450
weighted avg	1.00	1.00	1.00	450

/n

In [35]: *# Retrieve the best hyperparameters*

```
best_params = grid.best_params_  
print("Best hyperparameters:", best_params)
```

Best hyperparameters: {'learning\_rate': 0.01, 'n\_estimators': 50}

## Step-5 [Build AdaBoostClassifier]

### Create AdaBoostClassifier with DecisionTreeClassifier

```
In [58]: from sklearn.tree import DecisionTreeClassifier  
from sklearn.ensemble import AdaBoostClassifier
```

```
In [59]: param_grid = {'n_estimators': [50, 10, 200, 400], 'learning_rate': [0.1, 0.01]}
```

```
In [60]: ada = AdaBoostClassifier(base_estimator=DecisionTreeClassifier())
```

```
In [62]: abc = gsc(estimator=ada, param_grid=param_grid, cv=5)
```

```
In [63]: # Fit the AdaBoostClassifier model on the training data  
abc.fit(X_train, y_train)
```

```
Out[63]: GridSearchCV(cv=5,  
                      estimator=AdaBoostClassifier(base_estimator=DecisionTreeClassifier()),  
                      param_grid={'learning_rate': [0.1, 0.01],  
                                'n_estimators': [50, 10, 200, 400]})
```

```
In [64]: # Use the AdaBoostClassifier model to make predictions on the testing data  
y2_pred = abc.predict(X_test)
```

```
In [65]: accuracy_score(y_test, y2_pred)
```

```
Out[65]: 1.0
```

```
In [66]: print(classification_report(y_test,y2_pred), '/n')
```

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	161
SITTING	1.00	1.00	1.00	141
WALKING	1.00	1.00	1.00	148
accuracy			1.00	450
macro avg	1.00	1.00	1.00	450
weighted avg	1.00	1.00	1.00	450

/n

```
In [70]: best_params = abc.best_estimator_  
print("Best hyperparameters:", best_params)
```

Best hyperparameters: AdaBoostClassifier(base\_estimator=DecisionTreeClassifier(), learning\_rate=0.01, n\_estimators=10)

#### Step-6 [ Build LogisticRegressionCV classifier]

```
In [48]: from sklearn.linear_model import LogisticRegressionCV as lr
```

```
In [73]: clf =lr(Cs=5, cv=4, penalty='l2')  
clf.fit(X_train, y_train)  
y_pred = clf.predict(X_test)
```

...

```
In [74]: print(classification_report(y_test, y_pred))
```

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	161
SITTING	1.00	0.99	1.00	141
WALKING	0.99	1.00	1.00	148
accuracy			1.00	450
macro avg	1.00	1.00	1.00	450
weighted avg	1.00	1.00	1.00	450

### Step-7[Build VotingClassifier]

```
In [108]: from sklearn.ensemble import VotingClassifier as vc
```

```
In [109]: gbc = GBC(n_estimators=100, learning_rate=0.1, random_state=42)
lrc = LogisticRegression(penalty='none', solver='saga')
vc = vc(estimators=[('gbc', gbc), ('lrc', lrc)], voting='soft')
```

```
In [110]: vc.fit(X_train, y_train)
```

C:\Users\user\anaconda3\lib\site-packages\sklearn\linear\_model\\_sag.py:352: ConvergenceWarning: The max\_iter was reached which means the coef\_ did not converge  
warnings.warn(

```
Out[110]: VotingClassifier(estimators=[('gbc',
                                         GradientBoostingClassifier(random_state=42)),
                                         ('lrc',
                                          LogisticRegression(penalty='none',
                                                                solver='saga'))],
                           voting='soft')
```

```
In [111]: vc_pred=vc.predict(X_test)
```



```
In [113]: print("Accuracy_Score", accuracy_score(y_test, vc_pred))
print("VotingClassifier:")
print(classification_report(y_test, vc_pred))
```

Accuracy\_Score 0.9977777777777778

VotingClassifier:

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	161
SITTING	1.00	0.99	1.00	141
WALKING	0.99	1.00	1.00	148
accuracy			1.00	450
macro avg	1.00	1.00	1.00	450
weighted avg	1.00	1.00	1.00	450

## Step-8[Interpret your result]

### Analyze your results

The models we have built have achieved decent accuracy and classification reports.