P32 Goblin Full - Complete Visual Build Guide

What You're Building

A mood-driven animatronic goblin head with:

- 3 Animated Displays (2 eyes + 1 mouth)
- Distance Sensing (proximity detection)
- Audio Output (sounds and speech)
- 9 Emotional States (automatic mood changes)

♥ Complete Wiring Diagram

Complete Wiring Diagram

P GPIO Pin Assignments Quick Reference

GPIO Component Function Wire Color

- Audio Amp I2S BCLK Red
- 5 Audio Amp I2S WS Black
- 6 Audio Amp I2S DATA White
- 9 HC-SR04 TRIG Gray
- 10 HC-SR04 ECHO
- 12 All Displays SPI MISO Blue
- 13 All Displays SPI MOSI Green
- 14 All Displays SPI CLK Yellow
- 15 Left Eye CS Orange
- 16 Right Eye CS Purple
- 17 Mouth CS Brown

♦ Power Distribution System

```
Power Rail Architecture:
5V Supply — ESP32 VIN
          - All Display VCC pins
          - Audio Amp VCC
          L Sensor VCC
Ground - ESP32 GND
          ├ All Display GND pins
          ├ Audio Amp GND
          └ Sensor GND
```

Critical: All components share common 5V and Ground rails

Assembly Order (Follow This Sequence!)

1 Power Setup First

```
Breadboard Setup:
 Red Rail [+5V from supply] •••••
 Main Area [Components here]
 Black Rail [GND from supply] •••••
```

2 ESP32 Connection

- $\bullet \quad VIN \to Red\ power\ rail$
- $GND \rightarrow Black power rail$
- Test: Verify 5V with multimeter before proceeding

3 \$PI Bus Wiring (Shared Lines)

```
ESP32 Shared SPI Bus:
   GPIO 12 (MISO) —
                             - All displays SDO
   GPIO 13 (MOSI) —
                       All displays SDA
   GPIO 14 (CLK) ---
                          All displays SCL
                 Left Right Mouth
                  Eye | Eye | Display
```

4 Individual Chip Selects

- GPIO 15 → Left eye CS (Orange wire)
- GPIO 16 \rightarrow Right eye CS (Purple wire)

• GPIO 17 \rightarrow Mouth CS (Brown wire)

5 Audio System

```
T2S Digital Audio:

ESP32 GPIO 4 —— MAX98357A BCLK
ESP32 GPIO 5 —— MAX98357A LRCK
ESP32 GPIO 6 —— MAX98357A DIN

MAX98357A + —— Speaker +
MAX98357A - —— Speaker -
```

6 Distance Sensor

```
HC-SR04 Connections:

ESP32 GPIO 9 —— TRIG pin

ESP32 GPIO 10 —— ECHO pin

5V power rail —— VCC pin

Ground rail —— GND pin
```

Testing Checklist

Power Verification (Use Multimeter)

- [] 5V present on ESP32 VIN
- [] 5V present on all display VCC pins
- [] 5V present on audio amp VCC
- [] 5V present on sensor VCC
- [] Continuity on all GND connections

Software Upload

- [] PlatformIO project opens without errors
- [] ENABLE_GOBLIN_COMPONENTS defined in config
- [] Build completes (~5.8% RAM, ~51.7% Flash)
- [] Upload successful to COM port
- [] Serial monitor shows loop messages

Component Function Tests

- [] All 3 displays show content
- [] Eye displays animate (blink cycle)
- [] Mouth display changes colors
- [] Speaker produces clear audio
- [] Distance sensor readings change with proximity
- [] Mood system cycles through emotions

Mood System Overview

Your goblin automatically cycles through 9 emotions:

Emotion	Visual Effect	Trigger Condition
	Pale colors, rapid blinks	Sudden proximity
⊗ ANGER	Red colors, intense stare	Sustained proximity
IRRITATION	Orange tints, narrow eyes	Repeated interaction
⊚ HAPPINESS	Bright colors, wide eyes	Positive interaction
⊕ CONTENTMENT	Soft blue, relaxed	Extended calm period
1 HUNGER	Green tints, searching	Time-based cycle
CURIOSITY	Blue tints, alert look	Motion detection
☼ AFFECTION	Pink tints, gentle gaze	Gentle interaction
EXCITEMENT	Rapid color changes	High activity

Troubleshooting Guide

No Display Output

Symptoms: Black screens on all displays **Check:**

- 5V power on display VCC pins
- SPI wiring (GPIO 12,13,14 connections)
- Individual CS pin connections (GPIO 15,16,17)

Build/Upload Errors

Symptoms: Compilation fails

Check:

- p32_component_config.h contains #define ENABLE_GOBLIN_COMPONENTS
- USB-C cable connected to ESP32
- Correct COM port detected

No Audio

Symptoms: Silent speaker

Check:

- I2S connections (GPIO 4,5,6)
- 5V power to audio amplifier
- Speaker polarity (+ and terminals)

Sensor Not Working

Symptoms: Fixed distance readings

Check:

- HC-SR04 requires full 5V (not 3.3V)
- GPIO 9,10 connections
- No obstructions in front of sensor

% Component Specifications

ESP32-S3-DevKitC-1

MCU: Dual-core 240MHzRAM: 512KB SRAM

• Flash: 8MB

• WiFi/Bluetooth: Built-in

• **GPIO:** 45 pins (11 used, 34+ available)

GC9A01 Round Displays (×3)

Size: 1.28" diameter
Resolution: 240×240 pixels
Interface: SPI (7-pin)
Colors: 65,536 (RGB565)
Voltage: 3.3V logic, 5V power

MAX98357A Audio Amplifier

• Interface: I2S digital input

Output: 3W @ 4Ω
 SNR: 92dB
 Voltage: 5V power

HC-SR04 Distance Sensor

Range: 2cm to 400cmAccuracy: ±3mm

Interface: Digital trigger/echoVoltage: 5V required

Expansion Ideas

With 34+ unused GPIO pins, add:

- Servo neck movement (PWM control)
- LED accent lighting (WS2812B strips)
- Camera module (ESP32-CAM integration)
- Microphone input (I2S or ADC)
- Wheeled mobility base (motor controllers)
- Additional displays (expand face features)

Support Resources

- GitHub Repository: p32-animatronic-bot (https://github.com/reussered/p32-animatronic-bot)
- Documentation: See /docs folder for technical specs
- Hardware Datasheets: Component manufacturer websites
- ESP32 Resources: Espressif official documentation

Congratulations! You've built a complete mood-driven animatronic system!

 $\textit{Print this guide in color for best results. The \, SVG \,\, diagram \textit{will scale perfectly on any printer}.$