3. Construct Min and Max Heap using arrays, delete any element and display the content of the Heap.

```
#include <iostream>
using namespace std;
void heapifyMin(int arr[], int n, int i) {
   int smallest = i;
   int left = 2 * i + 1;
   int right = 2 * i + 2;
       if (left < n && arr[left] < arr[smallest])</pre>
               smallest = left;
       smallest = reft;
if (right < n && arr[right] < arr[smallest])
smallest = right;</pre>
       if (smallest != i) {
    swap(arr[i], arr[smallest]);
    heapifyMin(arr, n, smallest);
void buildMinHeap(int arr[], int n) { for (int i = n / 2 - 1; i >= 0; i--) heapifyMin(arr, n, i);
void deleteMin(int arr[], int &n, int key) {
       int index = -1;
for (int i = 0; i < n; i++) {
              if (arr[i] == key) {
  index = i;
                     break;
       }
       if (index == -1) {
   cout << "Key not found!" << endl;</pre>
       arr[index] = arr[n - 1];
       buildMinHeap(arr, n);
}
int main() {
       int arr[] = {10, 20, 15, 30, 40};
int n = sizeof(arr) / sizeof(arr[0]);
       buildMinHeap(arr, n);
cout << "Min Heap:" << endl;
for (int i = 0; i < n; i++)
    cout << arr[i] << " ";
cout << endl;</pre>
       deleteMin(arr, n, 10);
cout << "After deletion:" << endl;
for (int i = 0; i < n; i++)
    cout << arr[i] << " ";</pre>
       return 0;
```

9. Write a program to solve0/1Knapsack problem Using Dynamic Programming.

Code (Adjacency Matrix):

```
#include<iostream>
 #include<queue>
 #include<stack>
using namespace std;
void BFT(int graph[V][V], int start) {
  bool visited[V] = {false};
  queue<int> q;
  q.push(start);
  visited[start] = true;
       while (!q.empty()) {
   int node = q.front();
   q.pop();
   cout << node << " ";</pre>
               for (int i = 0; i < V; i++) {
   if (graph[node][i] == 1 && !visited[i]) {
      q.push(i);
      visited[i] = true;
}</pre>
              }
       }
}
void DFT(int graph[V][V], int start) {
  bool visited[V] = {false};
  stack<int> s;
  s.push(start);
        visited[start] = true;
       while (!s.empty()) {
   int node = s.top();
   s.pop();
   cout << node << " ";</pre>
                for (int i = 0; i < V; i++) {
    if (graph[node][i] == 1 && !visited[i]) {</pre>
                               s.push(i);
visited[i] = true;
               }
        }
}
int main() {
        main() {
  int graph[V][V] = {
    {0, 1, 1, 0, 0},
    {1, 0, 1, 1, 0},
    {1, 1, 0, 0, 1},

                {0, 1, 0, 0, 1},
{0, 0, 1, 1, 0}
        cout << "Breadth-First Traversal:" << endl;</pre>
        BFT(graph, 0);
        cout << "\nDepth-First Traversal:" << endl;</pre>
        DFT(graph, 0);
        return 0;
```

11. Use Backtracking strategy to solve 0/1Knapsack problem.

```
#include <iostream>
using namespace std;

int maxProfit = 0;

void knapSackBacktrack(int W, int wt[], int val[], int n, int idx, int currentWeight, int currentProfit) {
    if (idx == n) {
        if (currentProfit > maxProfit)
            maxProfit = currentProfit;
        return;
    }

    if (currentWeight + wt[idx] <= W)
        knapSackBacktrack(W, wt, val, n, idx + 1, currentWeight + wt[idx], currentProfit + val[idx]);

    knapSackBacktrack(W, wt, val, n, idx + 1, currentWeight, currentProfit);
}

int main() {
    int val[] = {60, 100, 120};
    int wt[] = {10, 20, 30};
    int W = 50;
    int n = sizeof(val) / sizeof(val[0]);

    knapSackBacktrack(W, wt, val, n, 0, 0, 0);
    cout << "Maximum value in Knapsack: " << maxProfit << endl;
    return 0;}</pre>
```

Code (Adjacency List):

```
#include<iostream>
#include<list>
#include<queue>
#include<stack>
using namespace std;
class Graph {
   int V;
   list<int> *adj;
public:
        Graph(int V);
void addEdge(int v, int w);
void BFT(int s);
void DFT(int s);
};
Graph::Graph(int V) {
   this->V = V;
   adj = new list<int>[V];
void Graph::addEdge(int v, int w) {
   adj[v].push_back(w);
   adj[w].push_back(v);
void Graph::BFT(int s) {
  bool *visited = new bool[V];
  for (int i = 0; i < V; i++)
     visited[i] = false;</pre>
         queue<int> queue;
visited[s] = true;
queue.push(s);
         while (!queue.empty()) {
   int node = queue.front();
   cout << node << " ";
   ...</pre>
                   queue.pop();
                  for (auto adjNode : adj[node]) {
   if (!visited[adjNode]) {
      visited[adjNode] = true;
      queue.push(adjNode);
}
                 }
         }
}
void Graph::DFT(int s) {
         bool *visited = new bool[V];
for (int i = 0; i < V; i++)
    visited[i] = false;</pre>
         stack<int> stack;
visited[s] = true;
stack.push(s);
         while (!stack.empty()) {
  int node = stack.top();
  cout << node << " ";
  stack.pop();</pre>
                   for (auto adjNode : adj[node]) {
                           if (!visited[adjNode]) {
  visited[adjNode] = true;
  stack.push(adjNode);
                }
         }
int main() {
    Graph g(5);
    g.addEdge(0, 1);
    g.addEdge(0, 2);
    g.addEdge(1, 2);
    g.addEdge(1, 3);
    g.addEdge(2, 4);
         cout << "Breadth-First Traversal:" << endl;</pre>
         cout << "\nDepth-First Traversal:" << endl;
g.DFT(0);</pre>
         return 0;
```

10. Implement N-Queens Problem Using Backtracking

```
#include <iostream>
using namespace std;
#define N 8
void printSolution(int board[N][N]) {
     for (int i = 0; i < N; i++) {
   for (int j = 0; j < N; j++)
      cout << board[i][j] << " ";
   cout << endl;}}</pre>
bool isSafe(int board[N][N], int row, int col) {
   for (int i = 0; i < col; i++)
     if (board[row][i])
        return false;</pre>
     for (int i = row, j = col; i >= 0 && j >= 0; i--, j--)
    if (board[i][j])
        return false;
     for (int i = row, j = col; j >= 0 && i < N; i++, j--) if (board[i][j])
                 return false;
      return true;}
return true;
     for (int i = 0; i < N; i++)
           if (isSafe(board, i, col)) {
    board[i][col] = 1;
                 if (solveNQUtil(board, col + 1))
                       return true;
                board[i][col] = 0; }}
     return false;}
bool solveNQ()
     int board[N][N] = {0};
     if (!solveNQUtil(board, 0)) {
   cout << "Solution does not exist" << endl;
   return false;</pre>
     printSolution(board);
int main() {
      solveNQ();
```

12. Implement Travelling Sales Person problem using Branch and Bound approach Objective:

```
#include <iostream>
#include <vector>
#include <algorithm>
#include <climits>
using namespace std;

#define N 4

int tsp(int graph[N][N], vector<bool>& visited, int pos, int count, int cost, int& ans) {
    if (count == N && graph[pos][0]) {
        ans = min(ans, cost + graph[pos][0]);
        return ans;
    }

    for (int i = 0; i < N; i++) {
        if (!visited[i] && graph[pos][i]) {
            visited[i] = true;
            tsp(graph, visited, i, count + 1, cost + graph[pos][i], ans);
        visited[i] = false;
        } }

int main() {
    int graph[N][N] = {
        {0, 10, 15, 20},
        {10, 0, 35, 25},
        {15, 35, 0, 30},
        {20, 25, 30, 0},
    };

vector<bool> visited(N, false);
visited[0] = true;
int ans = INT_MAX;
    tsp(graph, visited, 0, 1, 0, ans);
    cout < "Minimum cost of TSP: " << ans << endl;
    return 0;}</pre>
```