

Chap 23 – Minimum Spanning Trees

23.1 Growing a minimum spanning tree

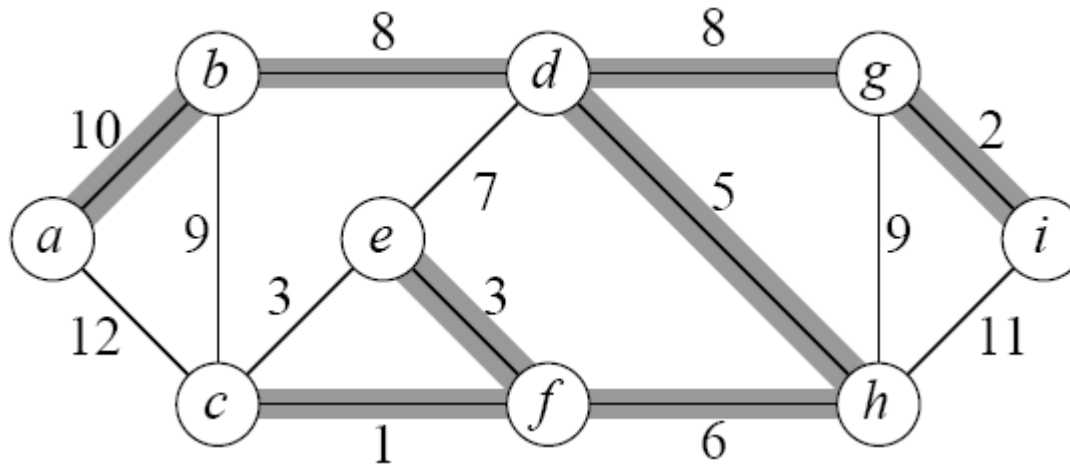
23.2 The algorithms of Kruskal and Prim

Minimum spanning tree

- Minimum spanning tree
 - An undirected graph $G = (V, E)$ with **weight** $w(u, v)$ on each edge $(u, v) \in E$
 - Find an MST $T \subseteq E$ such that
 - 1 T connects all vertices (T is a **spanning tree**), and
 - 2 $w(T) = \sum_{(u,v) \in T} w(u, v)$ is minimized
 - A **minimum spanning tree**, or **MST**, is a spanning tree whose weight is minimum over all spanning trees.

Minimum spanning tree

- Minimum spanning tree
 - Some Properties of an MST
 - It has $|V| - 1$ edges.
 - It has no cycles
 - It might not be unique.
 - Example : Replacing (e, f) by (c, e) yields another MST.



23.1 Growing a minimum spanning tree

- Generic MST algorithm (Greedy strategy)
 - Initially, $A = \emptyset$ has no edges.
 - As we add edges to A , maintain a loop invariant
Loop invariant
 A is a subset of some MST
 - Add only **safe** edges to maintain the loop invariant:
If A is a subset of some MST, an edge (u, v) is safe iff
 $A \cup \{(u, v)\}$ is also a subset of some MST.

23.1 Growing a minimum spanning tree

- Generic MST algorithm

- $\text{GENERIC-MST}(G = (V, E), w)$

- $A = \emptyset$

- while** A is not a spanning tree

- find an edge $(u, v) \in E$ that is safe for A

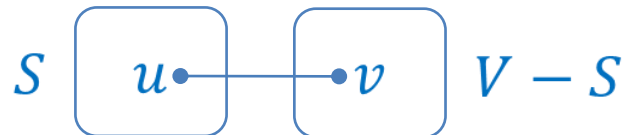
- $A = A \cup \{(u, v)\}$

- return** A

- $G_A = (V, A)$ is a forest containing connected components. Each component is a tree. ($\because A$ is a subset of some MST.)
 - Initially, each component is a single vertex.
 - Any safe edge merges two components into one.
 - The loop iterates $|V| - 1$ times.

23.1 Growing a minimum spanning tree

- Generic MST algorithm: some definitions
 - Let $G = (V, E)$, $S \subseteq V$ and $A \subseteq E$
 - A **cut** $(S, V - S)$ is a partition of V .
 - An edge $(u, v) \in E$ **crosses** the cut $(S, V - S)$ if one endpoint $\in S$ and the other $\in V - S$.



- A cut **respects** A if and only if no edge in A crosses the cut.
- An edge is a **light edge** crossing the cut iff its weight is minimum over all edges crossing the cut.
For a given cut, there can be > 1 light edge crossing it.

23.1 Growing a minimum spanning tree

- Generic MST algorithm

- **THEOREM**

Let A be a subset of some MST, $(S, V - S)$ be a cut that respects A , and (u, v) be a light edge crossing the cut. Then, (u, v) is safe for A .

Proof

Let T be an MST that includes A .

If T contains (u, v) , done.

If T doesn't contain (u, v) , we'll construct a different MST T' that includes $A \cup \{(u, v)\}$.

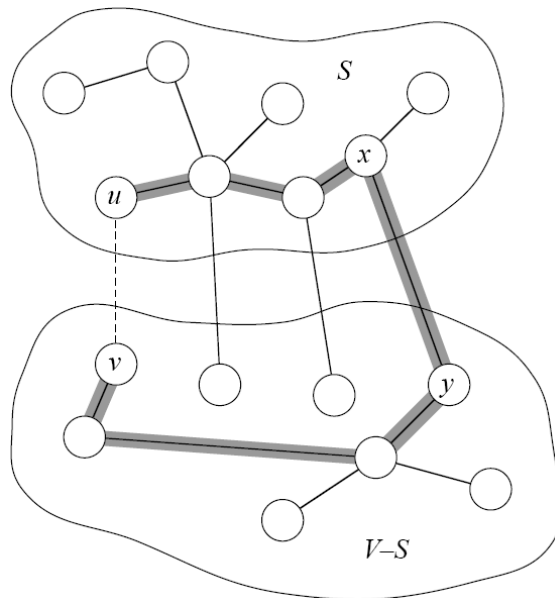
Recall: A tree has unique path between each pair of vertices

23.1 Growing a minimum spanning tree

- Generic MST algorithm

- **THEOREM** (Cont'd)

Since T is an MST, it contains a unique path p between u and v . Path p must cross the cut $(S, V - S)$ at least once. Let (x, y) be an edge of p that crosses the cut.



All edges shown are in T .

A is some subset of T , but it doesn't contain any edges that cross the cut.

23.1 Growing a minimum spanning tree

- Generic MST algorithm

- **THEOREM** (Cont'd)

Then, $w(u, v) \leq w(x, y) \because (u, v)$ is a light edge crossing the cut.

Also, $(x, y) \notin A$, \because the cut respects A .

Now, let

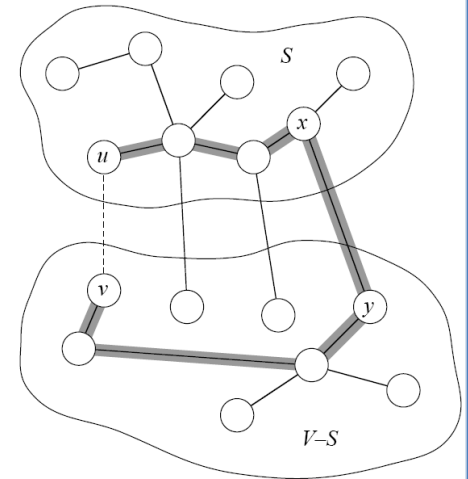
$$T' = T - \{(x, y)\} \cup \{(u, v)\}$$

Then, T' is a spanning tree.

Since T is an MST and

$$w(T') = w(T) - w(x, y) + w(u, v) \leq W(T)$$

It follows that T' is an MST, too.



23.1 Growing a minimum spanning tree

- Generic MST algorithm

- **THEOREM** (Cont'd)

We now show that (u, v) is safe for A .

- $A \subseteq T$ and $(x, y) \notin A \Rightarrow A \subseteq T'$
 - $A \cup \{(u, v)\} \subseteq T'$
 - Since T' is an MST, (u, v) is safe for A .

- **COROLLARY**

If $C = (V_c, E_c)$ is a connected component in the forest $G_A = (V, A)$ and (u, v) is a light edge connecting C to some other component in G_A , i.e. (u, v) crosses the cut $(V_c, V - V_c)$, then (u, v) is safe for A .

Proof Set $S = V_c$ in the theorem

23.2 The algorithms of Kruskal and Prim

- Kruskal's algorithm
 - Kruskal's algorithm immediately follows the corollary.
 - start with each vertex being its own component
 - repeatedly
 - merge two components into one by choosing the light edge that connects them, i.e. the light edge crossing the cut between them
 - For the light edge, scan the set of edges in monotonically increasing order by weight.
 - Use a disjoint-set data structure to determine whether an edge connects vertices in different components

23.2 The algorithms of Kruskal and Prim

- Kruskal's algorithm

- $\text{MST-KRUSKAL}(G, w)$

$A = \emptyset$

for each vertex $v \in G.V$... $|V|$ MAKE-SETS

MAKE-SET(v)

sort the edges of $G.E$ into nondecreasing order by w

for each (u, v) taken from the sorted list

if FIND-SET(u) \neq FIND-SET(v) **then**

$A = A \cup \{(u, v)\}$

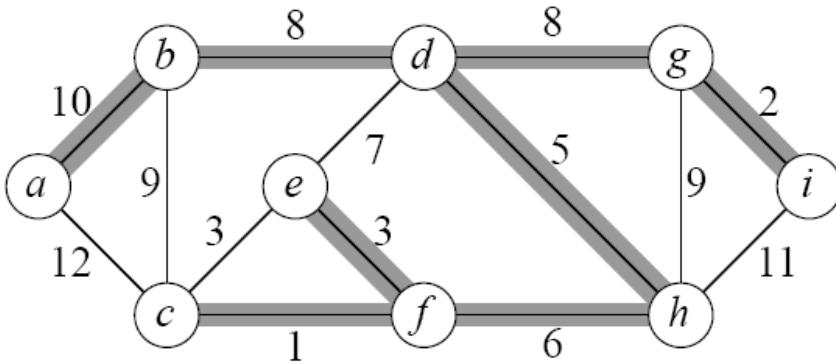
UNION(u, v) ... $O(E)$ FIND-SETS and UNIONS

return A

23.2 The algorithms of Kruskal and Prim

- Kruskal's algorithm

- Example



(b, c) : reject

(g, h) : reject

(a, b) : safe

(c, f) : safe

(g, i) : safe

(e, f) : safe

(c, e) : reject

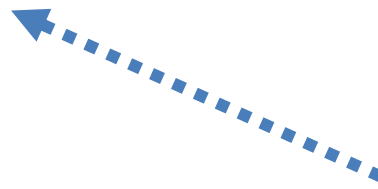
(d, h) : safe

(f, h) : safe

(d, e) : reject

(b, d) : safe

(d, g) : safe



23.2 The algorithms of Kruskal and Prim

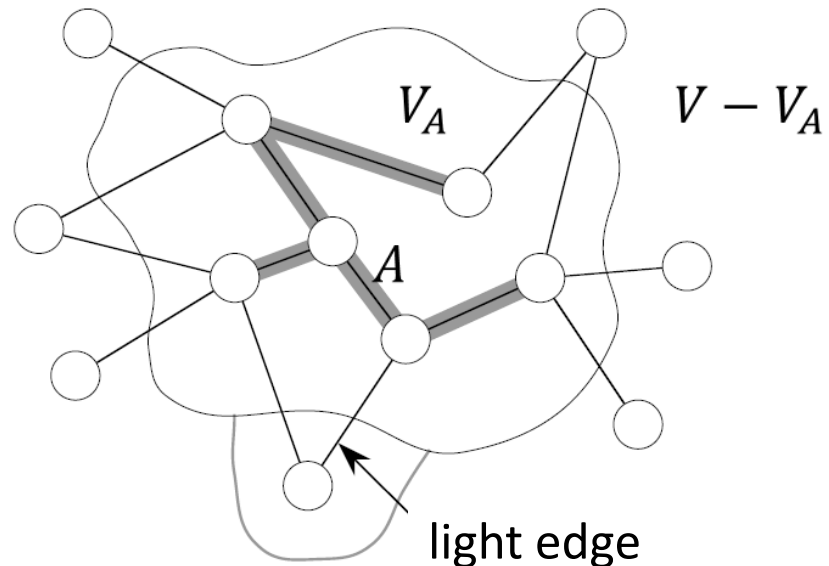
- Kruskal's algorithm
 - With union by rank and path compression, the sequence of $O(V + E)$ disjoint-set operations on $|V|$ elements takes a time in $O((V + E)\alpha(V))$.
 - Total time: $O((V + E)\alpha(V)) + O(E \lg E)$
 - Since the graph is connected, $|E| \geq |V| - 1$
Also, $\alpha(V) = O(\lg V) = O(\lg E)$
Total time: $O(E \lg E) + O(E \lg E) = O(E \lg E)$
 - Another result
 $|E| \leq |V|^2 \Rightarrow \lg E = O(\lg V)$
Total time: $O(E \lg V)$

23.2 The algorithms of Kruskal and Prim

- Prim's algorithm

- Build one tree, so A is always a tree
- Start from an arbitrary "root" r
- At each step, find a light edge crossing cut $(V_A, V - V_A)$, where $V_A =$ vertices that A is incident on.

Add this edge to A



23.2 The algorithms of Kruskal and Prim

- Prim's algorithm

- How to find the light edge quickly?

Use a priority queue Q

- Each object is a vertex u in $V - V_A$ (i.e. not in tree A)
 - $u.key$ is minimum weight of any edge $(u, v), v \in V_A$
 - Then, the vertex returned by EXTRACT-MIN is u such that there exists $v \in V_A$ and (u, v) is the light edge crossing $(V_A, V - V_A)$
 - $u.key = \infty$ if u is not adjacent to any vertices in V_A

23.2 The algorithms of Kruskal and Prim

- Prim's algorithm

- The edges of A will form a rooted tree with root r :

- r is given; it can be any vertex.

- $v.\pi = \text{parent of } v$

- As algorithm progress,

- $$A = \{(v, v.\pi : v \in V - \{r\} - Q)\}$$

- At termination, $Q = \emptyset$

- So, MST is
$$A = \{(v, v.\pi : v \in V - \{r\})\}$$

23.2 The algorithms of Kruskal and Prim

- Prim's algorithm

- MST-PRIM(G, w, r)

- $Q = \emptyset$

- for** each $u \in G.V$

- $u.key = \infty; u.\pi = \text{NIL}$

- INSERT(Q, u)

- ... $|V|$ INSERTS

- DECREASE-KEY($Q, r, 0$)

- // $r.key = 0$

- while** $Q \neq \emptyset$

- $u = \text{EXTRACT-MIN}(Q)$

- ... $|V|$ EXTRACT-MINS

- for** each $v \in G.Adj[u]$

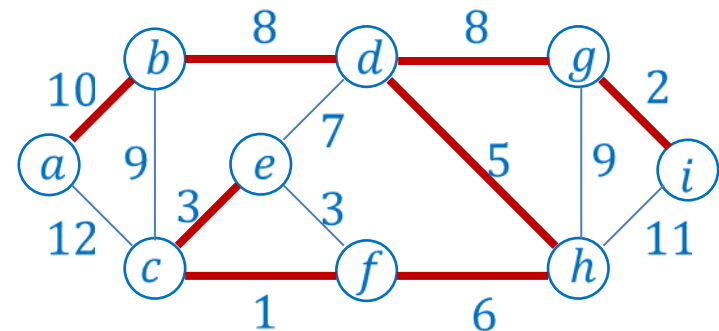
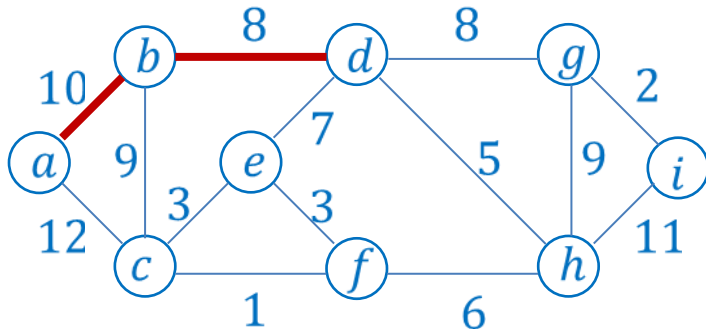
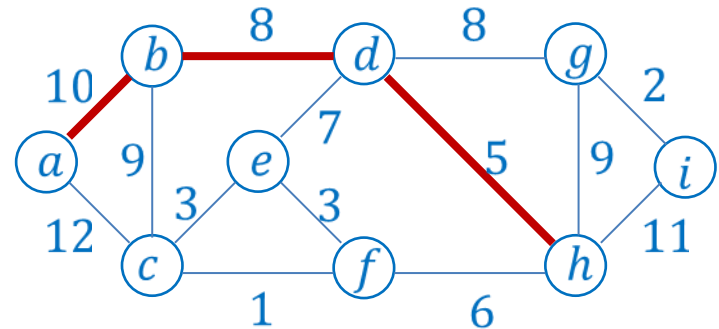
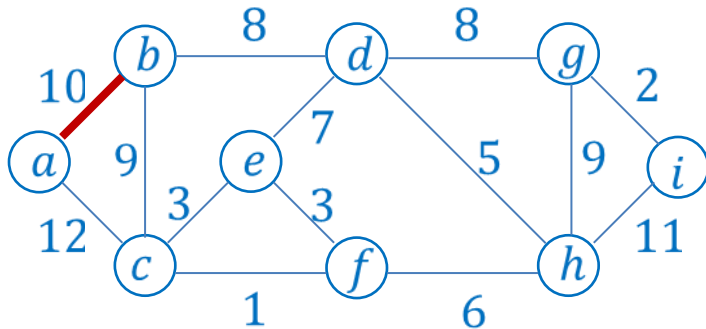
- if** $v \in Q$ and $w(u, v) < v.key$

- $v.\pi = u$

- DECREASE-KEY($Q, v, w(u, v)$) ... $\leq |E|$ DECREASE-KEY

23.2 The algorithms of Kruskal and Prim

- Example on Prim's algorithm



23.2 The algorithms of Kruskal and Prim

- Analysis of Prim's algorithm
 - Depend on how the priority queue Q is implemented
 - Suppose Q is a binary heap
$$|V| \text{ INSERTS} + |V| \text{ EXTRACT-MINS} + (\leq |E| \text{ DECREASE-KEYS})$$
take a time in
$$O(V \lg V) + O(V \lg V) + O(E \lg V) = O(E \lg V)$$
$$\because \text{the graph is connected} \Rightarrow |E| \geq |V| - 1$$
 - Suppose Q is a Fibonacci heap (Chap. 19)
DECREASE-KEY can be done in $O(1)$ amortized time.
Then, the operations take a time in
$$O(V \lg V) + O(V \lg V) + O(E) = O(E + V \lg V)$$