| for | those who handed 1st huk late (lateromers to the class (on 16/7) |
|--|--|
| 1.2.10 | In augmented form, the system Corresponds to [2 h 2] \[\bigcup \left\ \left\ \left\ \right\ \left\ \left\ \left\ \right\ \left\ \right\ \left\ \right\ \ri |
| | (a) if $h=2$, $k \neq 8 \Rightarrow$ inconsistent |
| | (i) $8-4k=1=$ $=$ $=$ $=$ $=$ $=$ $=$ $=$ $=$ $=$ |
| | and as long as $h \neq 2$, $\forall h \in \mathbb{R}$ (2) This is a solution to the system |
| | (c) $h=2$, $k=8$ gives $\begin{bmatrix} 1 & 2 & 2 \\ 0 & 0 & 0 \end{bmatrix}$ |
| err (1,000 depende de glocke par per pri tra (1,000 de de de de pri general) en esta de la principa de principa La companya de la companya de | gives infinitely many rolutions. |
| | We just need a vow of zeros in the 2nd vow of the meeting. |
| | (8; (a): 3 for general solutions (b): 3 for general solutions (c): 2 for correct numbers) |
| | |

1.3.22 When we have an $A \in M_{3\times3}$ without the 3 linearly independent column vectors, C(A) does not span R^3 . Hence, we can always find $b \in R^3$ s.t. $b \notin co C(A)$. (6; 2 for "vealization that A needs 3

linearly independent column vectors, I for
attempt at example, It for correct examples, I for
all of the above)

1.4.21 Only a set of 4 linearly
independent vectors ER spans R4. There are 3 linearly independent vectors in this ret — so this cannot form a basis for R4.

I for attempting the problem; (6; 2 for realization above, 2 for Correct subsequent explanations, I all of the above)

1.5.23 (a) TRUE the trivial solution is always
a robution

(b) FALSE the volution ret is given S= { ep+le : ler} Wheve Sp is particular solution and La is homogenous solution description of The equation gives an implicit solution set to Ax = b. (c) FALSE the trivial solution is always to Are = 0 (d) FALSE the line goes through p. their is parallel to v. (e) FALSE this relatione; this is only true if p is a particular robotion, ie. of Ap = b. holds. (10; 2 each, 1 for T/F, 1 for Correct explanation)

1.7.22 (a) TRUE if 2 points lie on the same line through the origin passing

then the vectors are scalar multiples of one another. (b) FALSE counterexample: \[\begin{bmatrix} \frac{1}{2}, & \begin{bmatrix} -2\\ 3\\ \end{bmatrix}, & \begin{bmatrix} \frac{1}{3}\\ \end{bmatrix}. \]
(c) TRUE by def: independent, but has fewer vectors
rectors
than there are vectors. (8; 2 each, 1 for T/Fg 1 for correct explanation)

Proof let T(x1, or2) = (2x1-3x2, x1, +4, 5x2) 1-8-33 To ree T is not a linear transformation we need just one counterexample. ie let &= (1,1). 8 y== (1,0). .. Then T(2,1a) =(1,6,5)but T(x) + T(y) = (-1, 5, 5) +(2,5,6) =(1,10,5)10 T(x+y) + T(x) + T(y) => Tis not a linear men. (8; I for attempting the problem,
2 for wealizing exactly what to do,
4 for a correct Counterexample &
subsequent justification, I for all of
the above

1.9.24 (a) FALSE For a linear transformation, we see the image of Bi= {E1,..., en} (b) TRUE. By def. (c) TRUE. Cheek matise multiplication! (d) FALSE injective function $f: X \mapsto Y$ is where f(se) = f(y) = 0 so every vector $x \in \mathbb{R}^m$ is mapped.

(e) HABE TRUE the map from $\mathbb{R}^n \mapsto \mathbb{R}^n$ Connot be onto (surjective) (10; 2 each, 1 for T/F, 1 for Correct explanation)