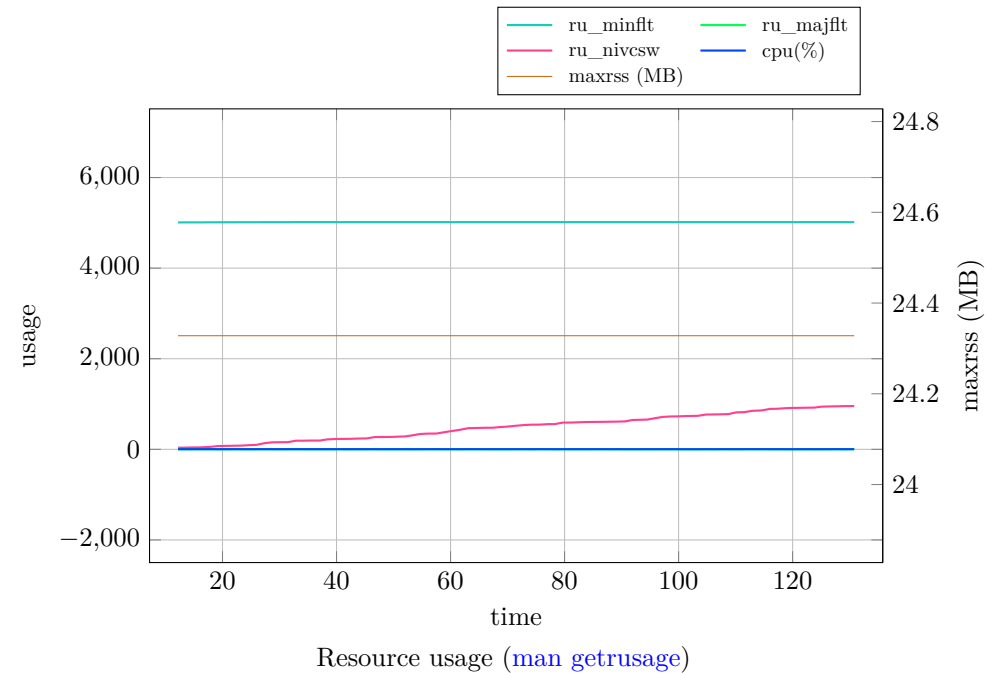
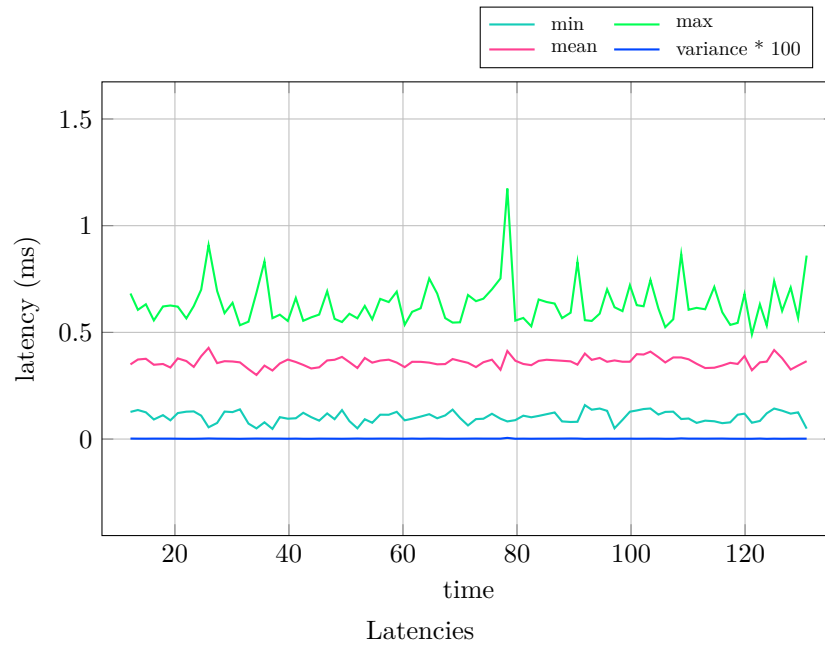


Performance

Logfile name	log_test_topic_28-11-2020_19-49-29
Experiment id	101a1c45-8a86-4696-9223-ea039d1ac107
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.3635
received	95.1136
sent	9.4886
lost	0.0
relative_loss	0.0
data_received	84108.8409
latency_min (ms)	0.104
latency_max (ms)	0.6342
latency_mean (ms)	0.3618
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.554
pub_loop_res_max (ms)	99.8997
pub_loop_res_mean (ms)	99.7465
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	3.5177

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0