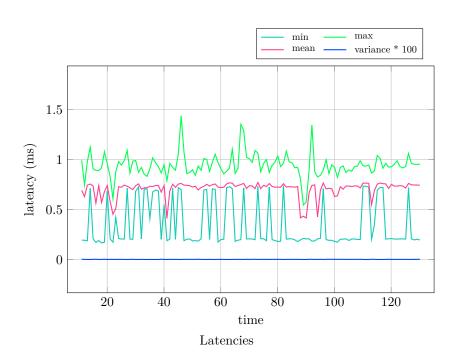
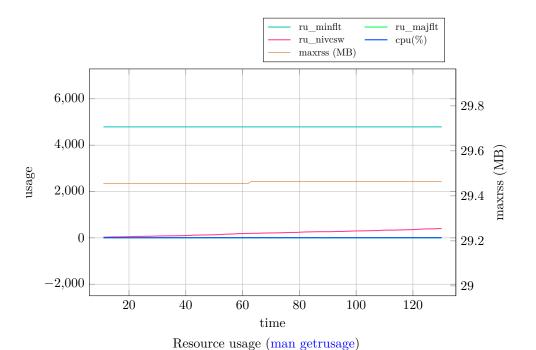
Performance

 Logfile name
 log_test_topic_30-11-2020_03-42-53

 Experiment id
 6844a5fc-4a4c-4e29-9416-ca4bca113ec5

 Communication mean
 ROS2





test setup average results environment

Performance Test Version	80ff298
Publishing rate	1000
Topic name	$test_topic$
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T_loop	1.0007
received	999.5083
sent	999.5167
lost	0.0
relative_loss	0.0
data_received	524751344.15
latency_min (ms)	0.3423
latency_max (ms)	0.9442
latency_mean (ms)	0.7083
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.4894
pub_loop_res_max (ms)	0.8258
pub_loop_res_mean (ms)	0.6241
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	7.037

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	PointCloud512k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0