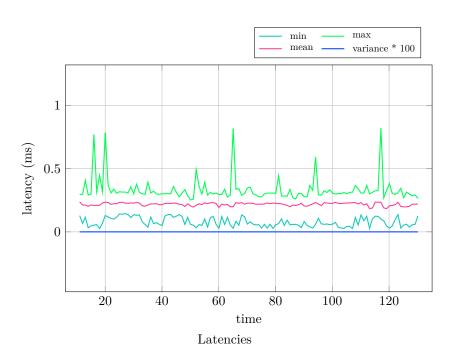
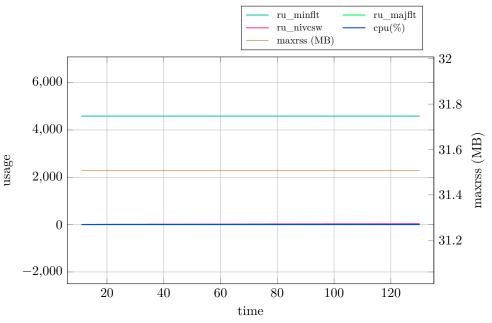
Performance

 Logfile name
 log_test_topic_27-11-2020_15-42-57

 Experiment id
 643441ae-d5e6-4896-ad63-af91c73fcfb4

 Communication mean
 ROS2





Resource usage (man getrusage)

test setup

Performance Test Version 80ff298 Publishing rate 1000 Topic name test_topic Number of publishers 1 Number of subscribers 3 Maximum runtime (sec) 130 DDS domain id 0 Single participant -

average results

Experiment Status	success
T_loop	1.0009
received	2998.55
sent	999.5
lost	0.0
relative_loss	0.0
data_received	239998.3333
latency_min (ms)	0.0775
latency_max (ms)	0.3334
latency_mean (ms)	0.2185
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.6988
pub_loop_res_max (ms)	0.9516
pub_loop_res_mean (ms)	0.8407
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	5.2576

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0