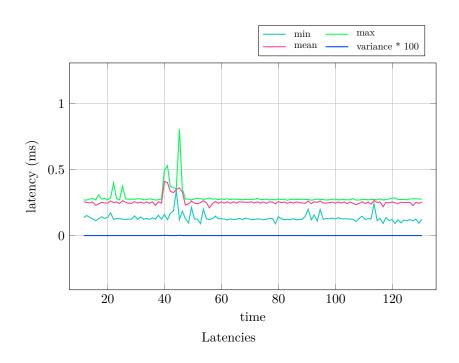
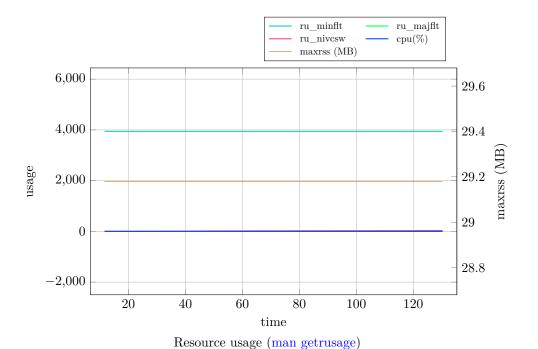
Performance

 Logfile name
 log_test_topic_30-11-2020_20-07-15

 Experiment id
 ff114939-8626-42b3-a345-c098fa8b8b41

 Communication mean
 ROS2





test setup average results environment

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T loop	1.0507
received	9.5088
sent	9.5175
	9.5175
lost	0.0
relative_loss	0.0
data_received	803.0088
latency_min (ms)	0.1326
latency_max (ms)	0.2889
latency_mean (ms)	0.2557
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.5007
pub_loop_res_max (ms)	99.7501
pub_loop_res_mean (ms)	99.5475
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub loop res variance (ms)	0.0
cpu_usage (%)	0.4151

Ignore seconds from beginning	10
Memory check enabled	(
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	(
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	(