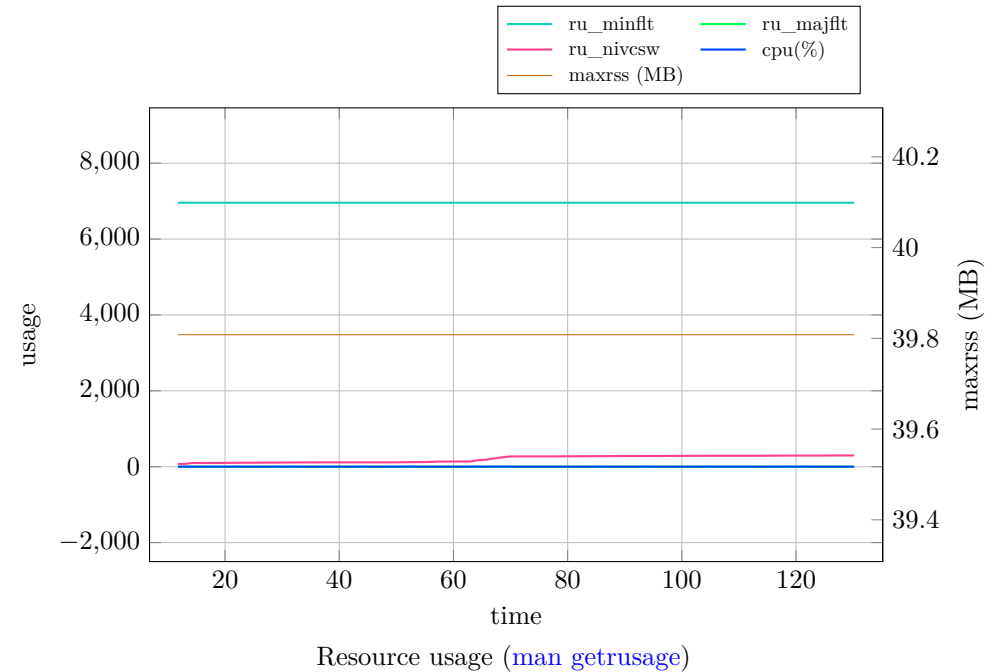
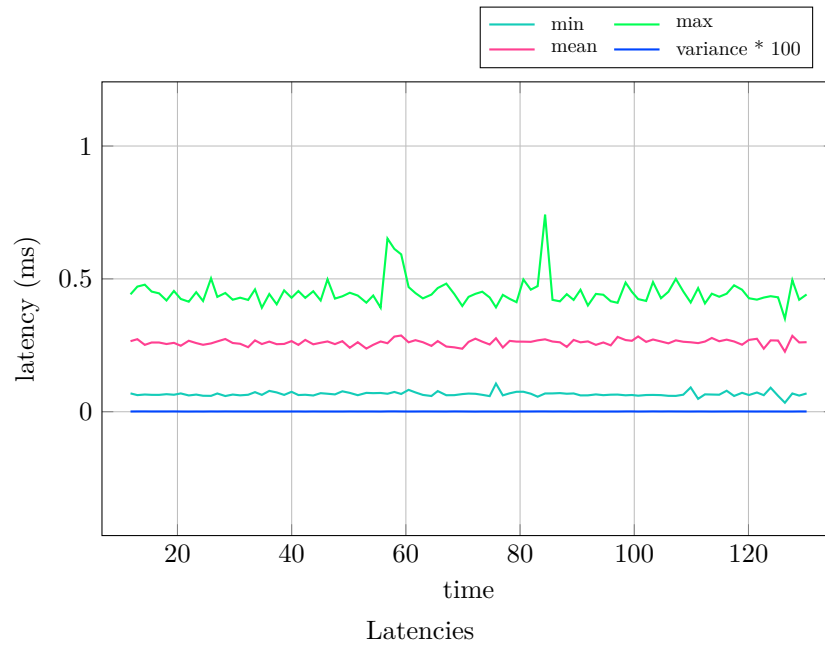


Performance

Logfile name	log_test_topic_28-11-2020_21-14-42
Experiment id	555a220a-a1d6-489b-9efa-db1c818ab282
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.2722
received	94.8191
sent	9.5106
lost	0.0
relative_loss	0.0
data_received	8002.1383
latency_min (ms)	0.0665
latency_max (ms)	0.4481
latency_mean (ms)	0.2612
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.5168
pub_loop_res_max (ms)	99.898
pub_loop_res_mean (ms)	99.6387
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.9607

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0