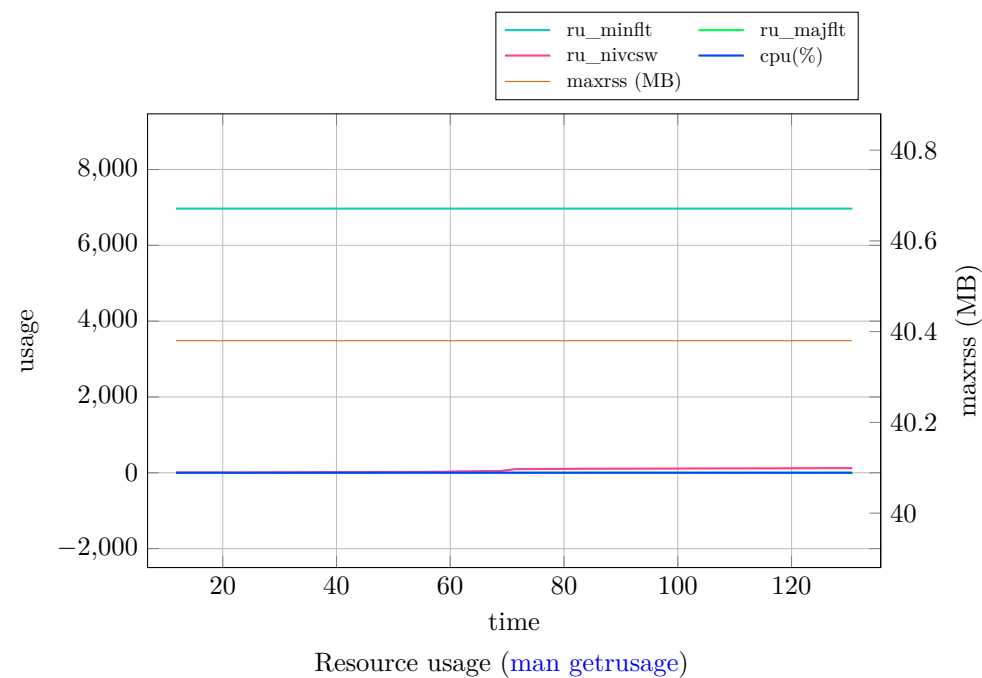
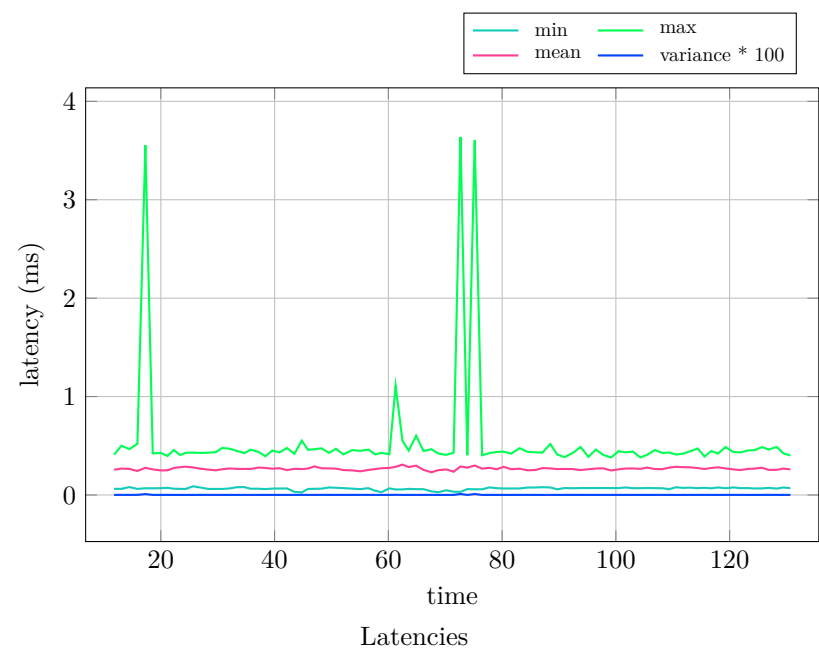


Performance

Logfile name	log_test_topic_12-12-2020_19-38-59
Experiment id	c598f9d1-14c2-48a5-834f-cb88218e9748
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.2786
received	94.734
sent	9.4574
lost	0.0
relative_loss	0.0
data_received	16808.8936
latency_min (ms)	0.0648
latency_max (ms)	0.5505
latency_mean (ms)	0.2671
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.5456
pub_loop_res_max (ms)	99.8944
pub_loop_res_mean (ms)	99.6718
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.9889

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0