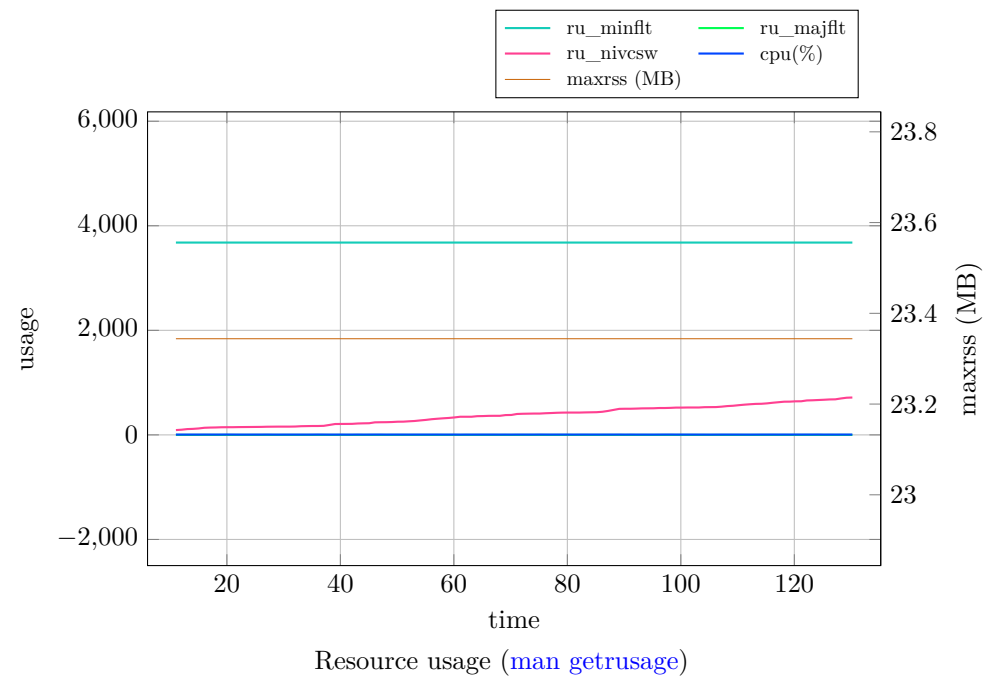
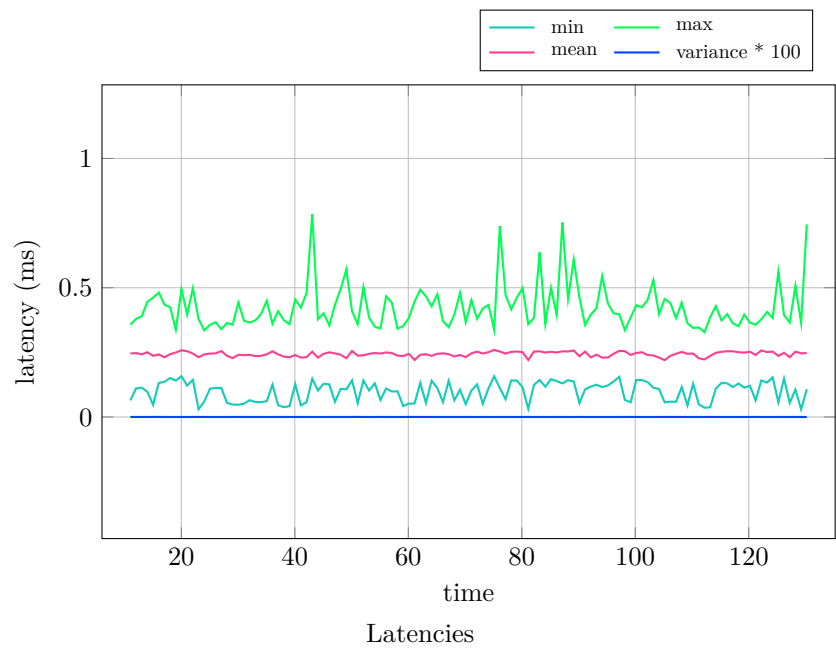


Performance

Logfile name	log_test_topic_27-11-2020_13-23-59
Experiment id	7137b96e-ee9b-45b6-a91f-3f37ac5ed2e5
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	3
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0015
received	2998.4667
sent	999.5167
lost	0.0
relative_loss	0.0
data_received	3119968.4417
latency_min (ms)	0.0989
latency_max (ms)	0.4245
latency_mean (ms)	0.2434
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.717
pub_loop_res_max (ms)	0.9186
pub_loop_res_mean (ms)	0.8351
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	6.1837

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Array1k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0