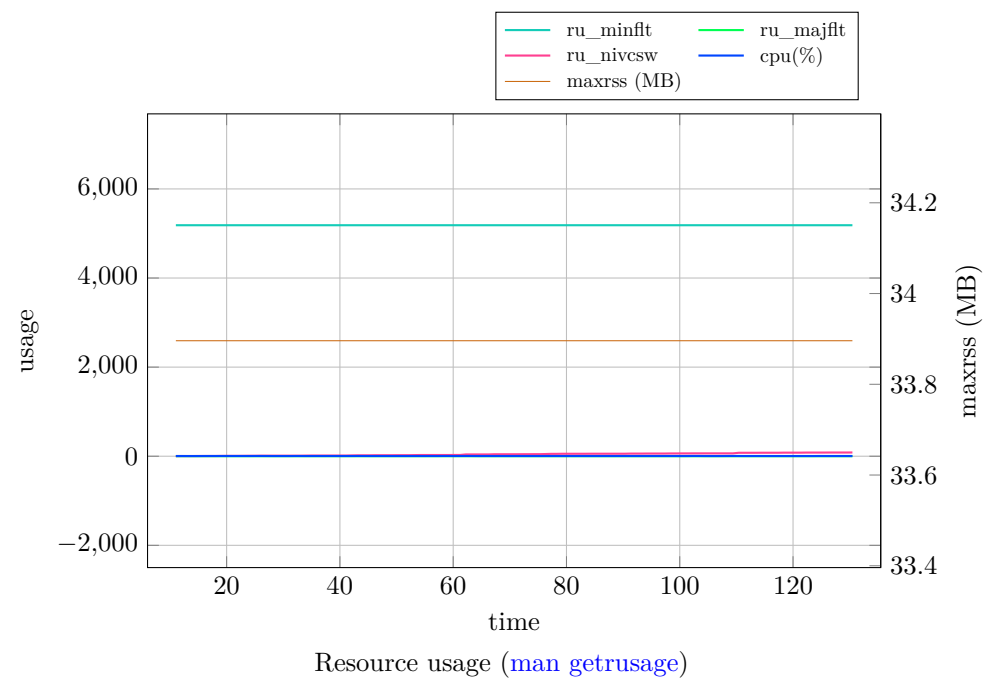
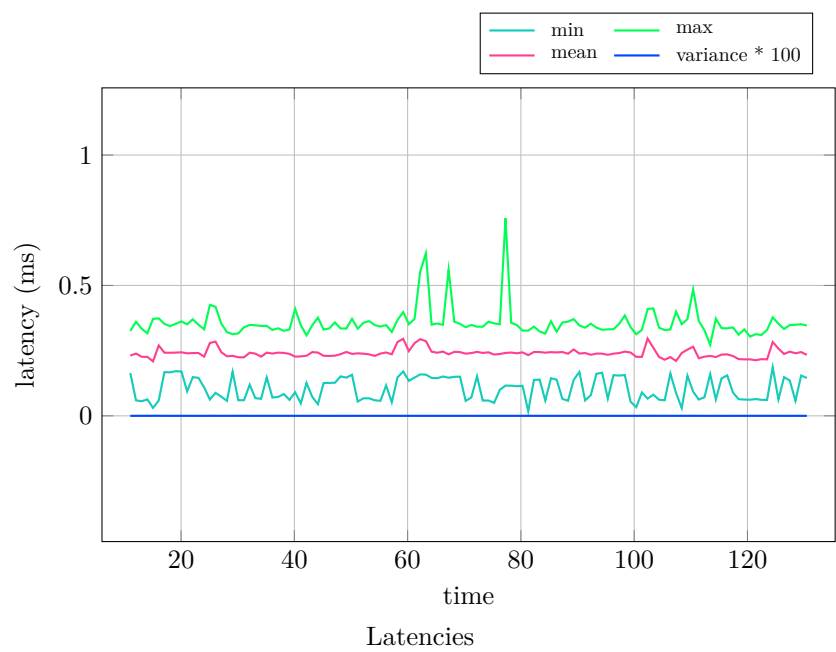


Performance

Logfile name	log_test_topic_01-12-2020_15-54-50
Experiment id	5fbb5bdb-d4b5-4ff1-bccf-29f24600c2a8
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	500
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0035
received	2497.7
sent	499.575
lost	0.0
relative_loss	0.0
data_received	419998.8083
latency_min (ms)	0.1034
latency_max (ms)	0.3574
latency_mean (ms)	0.2405
latency_variance (ms)	0.0
pub_loop_res_min (ms)	1.7427
pub_loop_res_max (ms)	1.9213
pub_loop_res_mean (ms)	1.8424
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	4.6229

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0