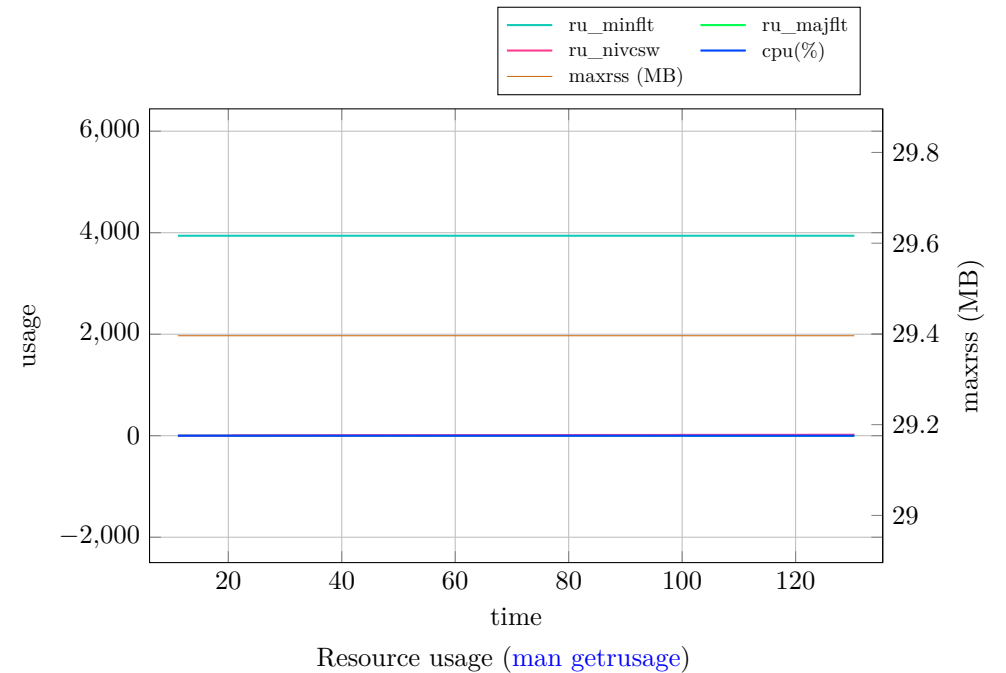
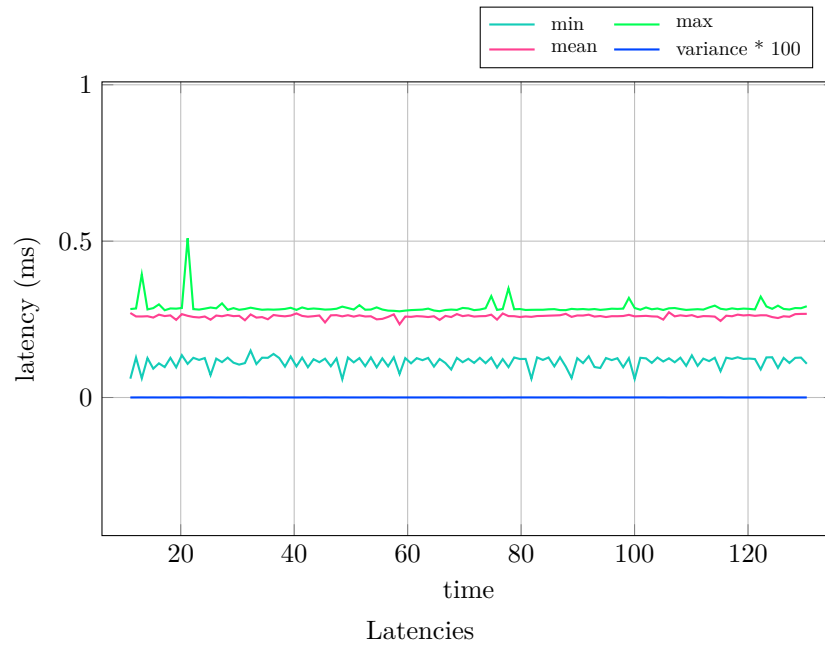


Performance

Logfile name	log_test_topic_01-12-2020_08-29-16
Experiment id	74d64c82-8e7c-4006-91f1-3210e1ca0372
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0103
received	49.5042
sent	49.4958
lost	0.0
relative_loss	0.0
data_received	42013.0336
latency_min (ms)	0.1136
latency_max (ms)	0.2877
latency_mean (ms)	0.2597
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.4431
pub_loop_res_max (ms)	19.8897
pub_loop_res_mean (ms)	19.5558
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.2418

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0