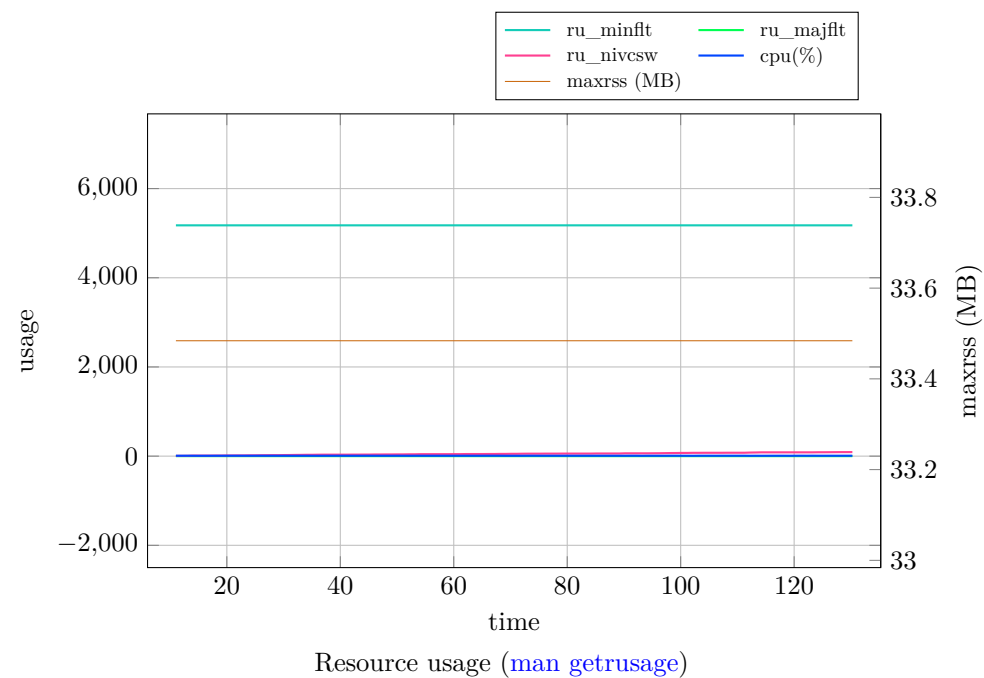
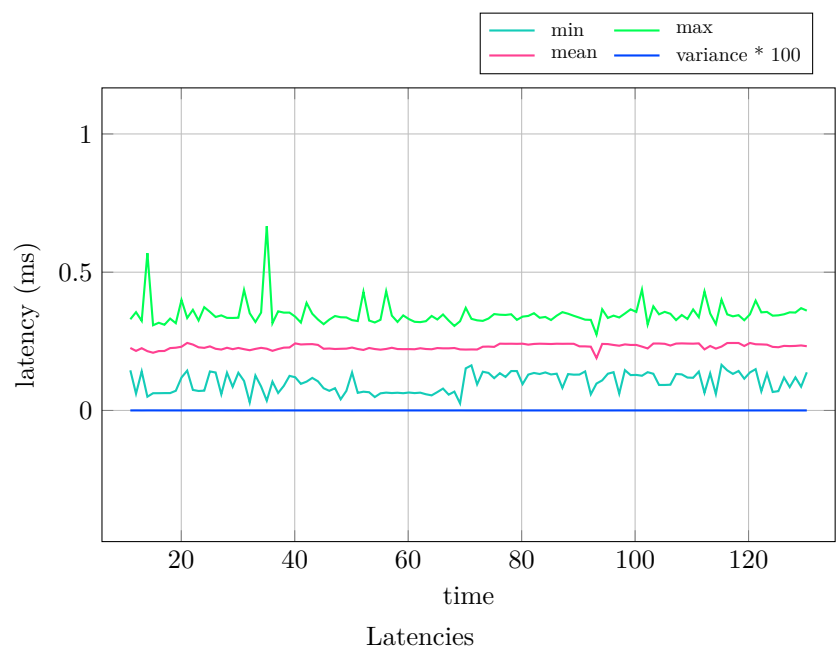


Performance

Logfile name	log_test_topic_01-12-2020_21-36-55
Experiment id	bbb2a39e-70e1-4335-b628-02c96b7e4d44
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0018
received	4997.4083
sent	999.4917
lost	0.0
relative_loss	0.0
data_received	839998.7417
latency_min (ms)	0.1011
latency_max (ms)	0.3488
latency_mean (ms)	0.2302
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.8097
pub_loop_res_max (ms)	0.9163
pub_loop_res_mean (ms)	0.8552
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	8.968

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0