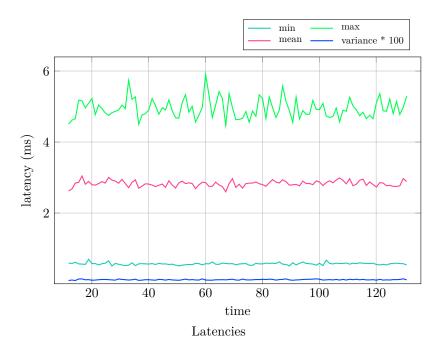
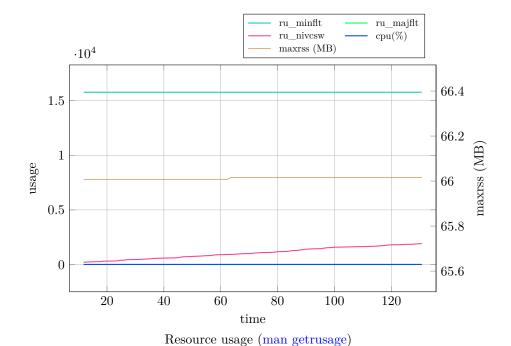
Performance

Logfile name log_test_topic_29-11-2020_12-36-25 Experiment id 7d6c0d4b-66fb-417f-aff0-29379dbba7a8 ROS2Communication mean





average results

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	_

test setup

Experiment Status	success
T loop	1.1774
received	495.049
sent	49.5
lost	0.0
relative loss	0.0
data received	524541444.402
_	
latency_min (ms)	0.5699
latency_max (ms)	4.942
latency mean (ms)	2.8303
latency_variance (ms)	0.0012
pub_loop_res_min (ms)	18.8695
pub_loop_res_max (ms)	19.6691
pub_loop_res_mean (ms)	19.1114
pub_loop_res_variance (ms)	0.0001
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub loop res mean (ms)	0.0
sub loop res variance (ms)	0.0
cpu usage (%)	6.2409
11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	PointCloud1m
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0

environment