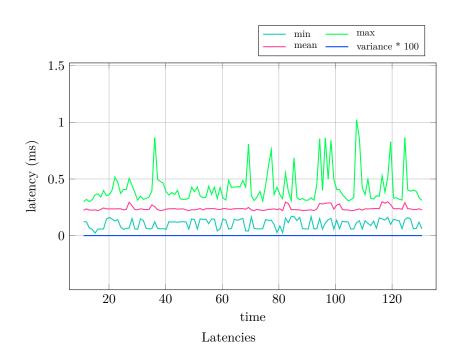
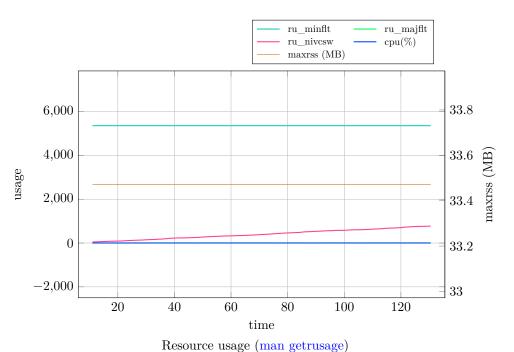
Performance

 Logfile name
 log_test_topic_29-11-2020_20-33-13

 Experiment id
 02499f60-da40-48ae-b03b-0b6ec08c64f0

 Communication mean
 ROS2





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test setup

Performance Test Version 80ff298 Publishing rate 500 Topic name test_topic Number of publishers 1 Number of subscribers 55 Maximum runtime (sec) 130 DDS domain id 0 Single participant -

average results

Experiment Status	success
T_loop	1.0039
received	2497.4417
sent	499.4917
lost	0.0
relative_loss	0.0
data_received	2099999.075
latency_min (ms)	0.1035
latency_max (ms)	0.4244
latency_mean (ms)	0.2394
latency_variance (ms)	0.0
pub_loop_res_min (ms)	1.7321
pub_loop_res_max (ms)	1.9213
pub_loop_res_mean (ms)	1.8246
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	4.2068

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0