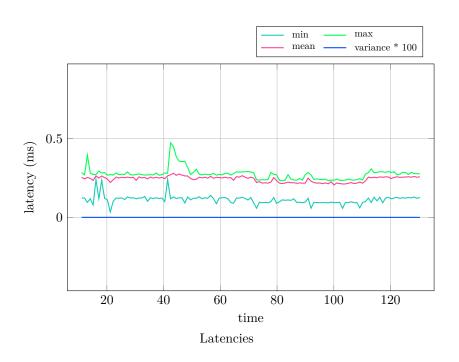
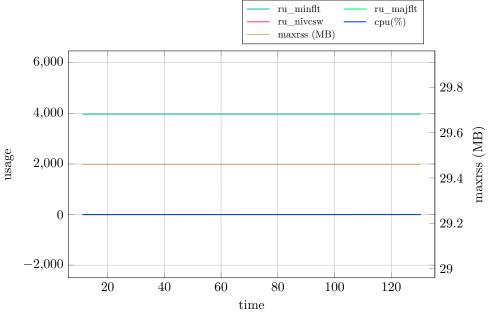
## Performance

 Logfile name
 log\_test\_topic\_28-11-2020\_23-37-13

 Experiment id
 65ff19f3-a9d4-45c9-ad00-73f22eaebc25

 Communication mean
 ROS2





Resource usage (man getrusage)

## Performance Test Version 80ff298 Publishing rate 50 Topic name test\_topic Number of publishers 1 Number of subscribers 1 Maximum runtime (sec) 130 DDS domain id 0 Single participant -

## average results

Experiment Status	success
T_loop	1.0104
received	49.5294
sent	49.5378
lost	0.0
relative_loss	0.0
data_received	4000.1176
latency_min (ms)	0.1126
latency_max (ms)	0.2751
latency_mean (ms)	0.2424
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.4455
pub_loop_res_max (ms)	19.8664
pub_loop_res_mean (ms)	19.549
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.2328

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0