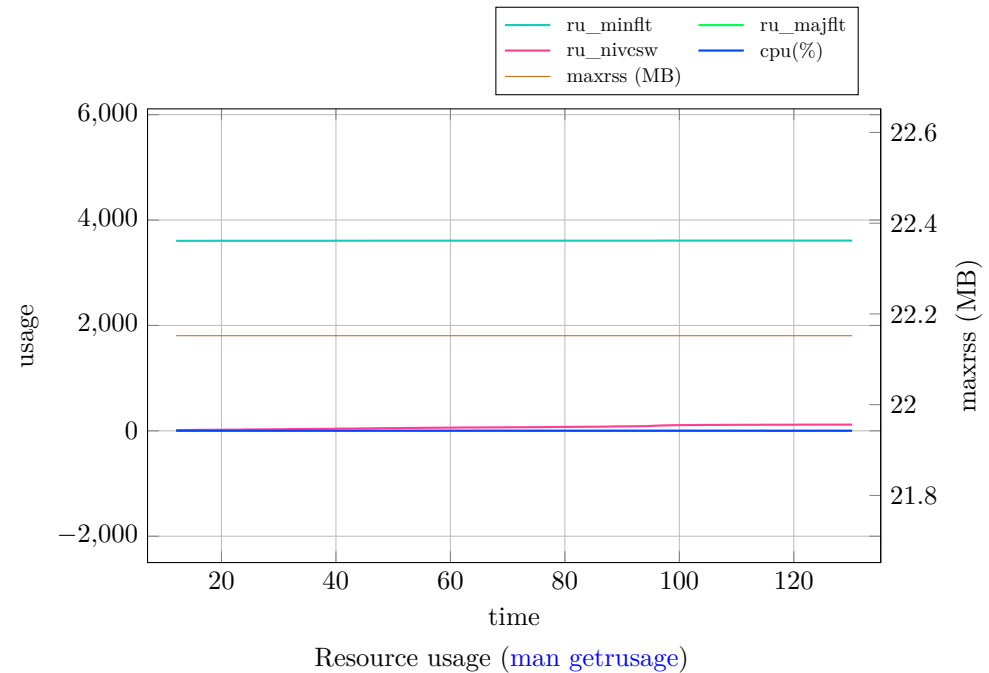
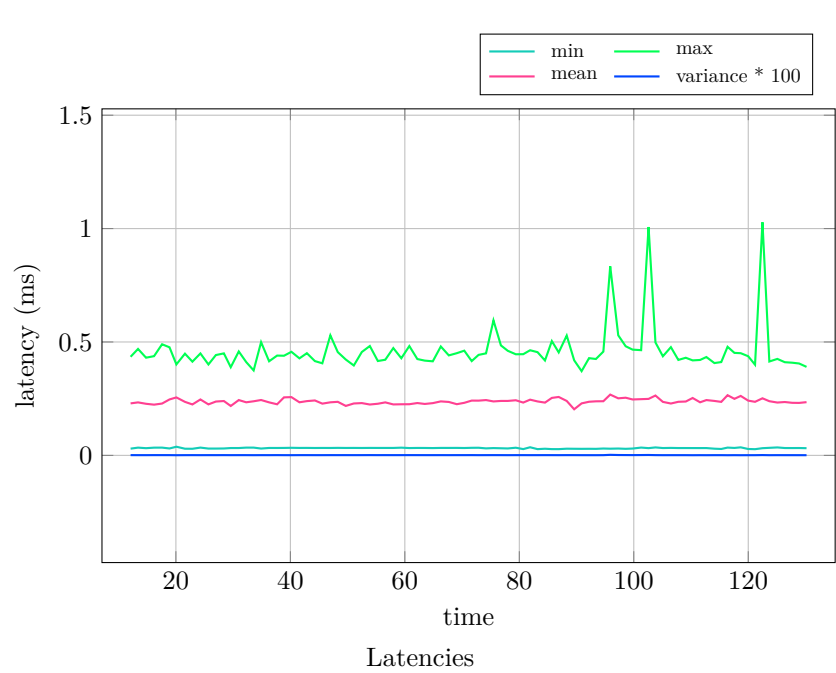


Performance

Logfile name	log_test_topic_12-12-2020_18-59-51
Experiment id	27413749-3964-4148-8c14-6668edf5deae
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.3141
received	95.0549
sent	9.4505
lost	0.0
relative_loss	0.0
data_received	84047.8901
latency_min (ms)	0.0318
latency_max (ms)	0.4602
latency_mean (ms)	0.2378
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.3585
pub_loop_res_max (ms)	99.8791
pub_loop_res_mean (ms)	99.5331
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	2.2331

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0