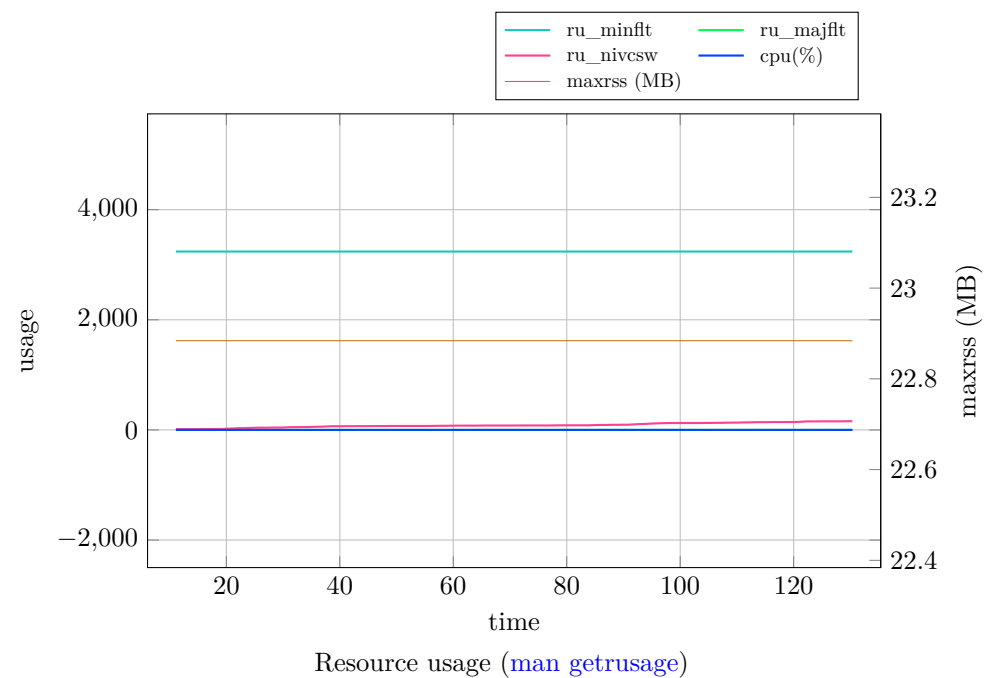
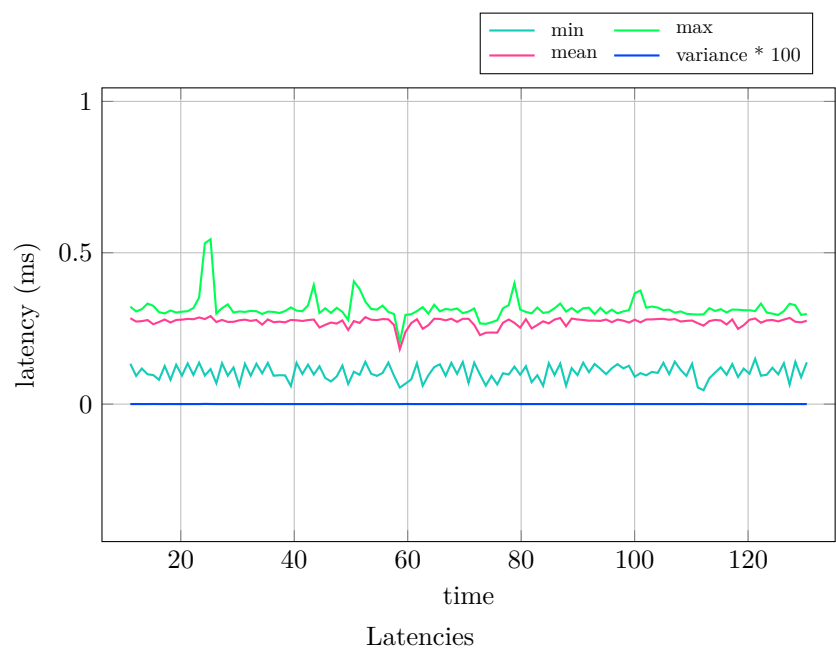


Performance

Logfile name	log_test_topic_28-11-2020_21-47-33
Experiment id	9d9e6c6f-0bd3-4279-a57c-21a1f54eef0e
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0102
received	49.521
sent	49.521
lost	0.0
relative_loss	0.0
data_received	1599.479
latency_min (ms)	0.1049
latency_max (ms)	0.3156
latency_mean (ms)	0.2714
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.606
pub_loop_res_max (ms)	19.8827
pub_loop_res_mean (ms)	19.6929
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.7755

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Struct16
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0