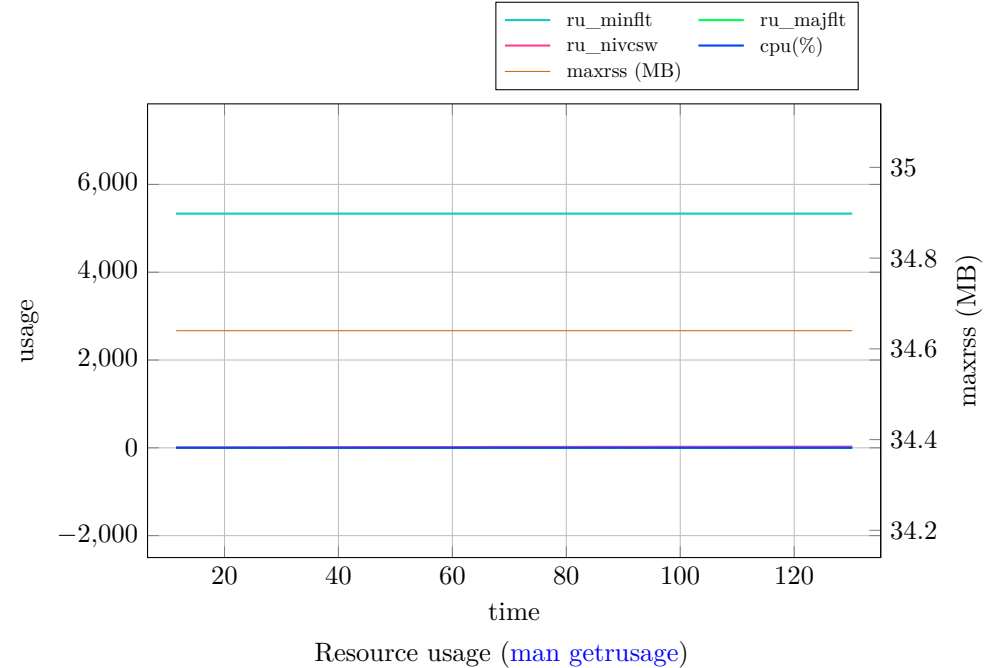
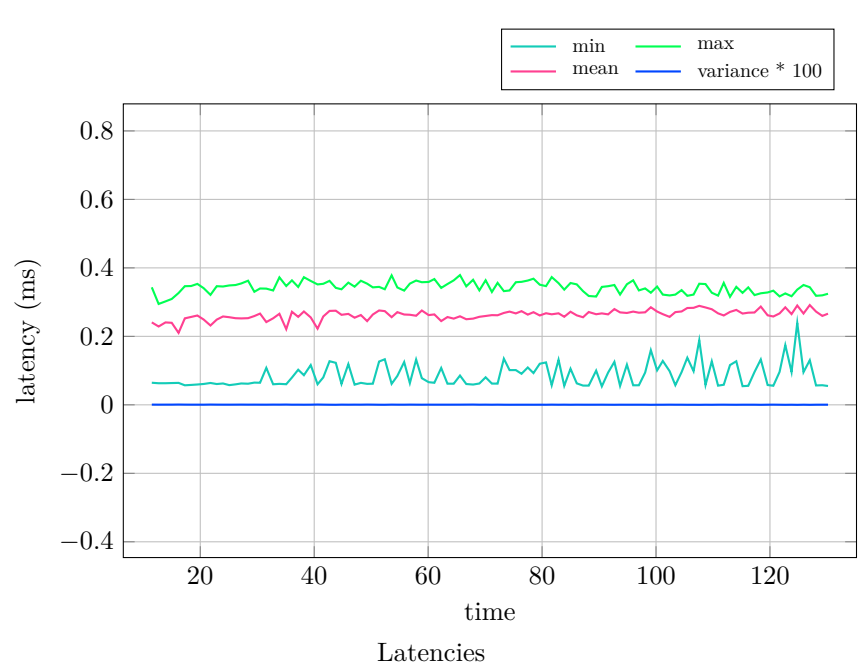


Performance

Logfile name	log_test_topic_12-12-2020_14-41-29
Experiment id	b46e0466-caf6-4484-9125-9b5c10ecf70b
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0898
received	47.5273
sent	9.5273
lost	0.0
relative_loss	0.0
data_received	8404.8545
latency_min (ms)	0.086
latency_max (ms)	0.3426
latency_mean (ms)	0.2628
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.4758
pub_loop_res_max (ms)	99.8278
pub_loop_res_mean (ms)	99.5559
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.7535

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0