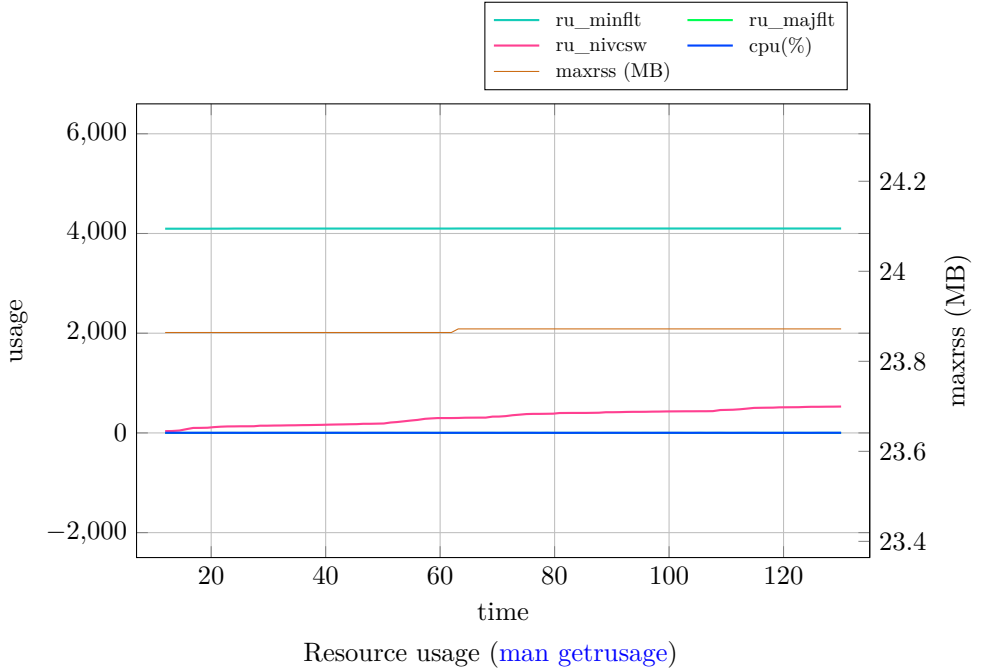
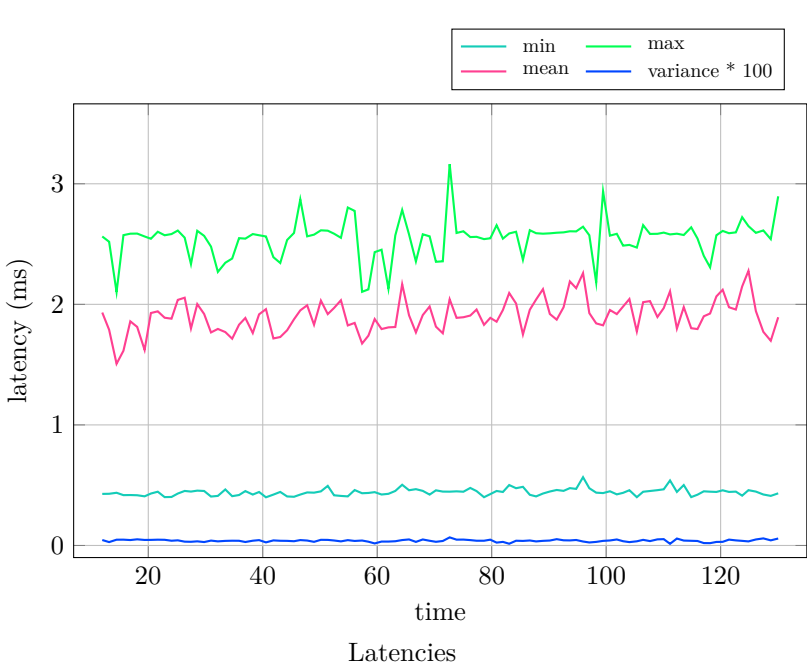


Performance

Logfile name	log_test_topic_28-11-2020_10-43-50
Experiment id	7900c279-1990-4006-91d3-786f45d3a6b4
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.1811
received	47.5446
sent	9.495
lost	0.0
relative_loss	0.0
data_received	423747.5842
latency_min (ms)	0.4419
latency_max (ms)	2.549
latency_mean (ms)	1.9049
latency_variance (ms)	0.0004
pub_loop_res_min (ms)	98.8179
pub_loop_res_max (ms)	99.741
pub_loop_res_mean (ms)	99.0569
pub_loop_res_variance (ms)	0.0001
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	2.6138

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Struct4k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0