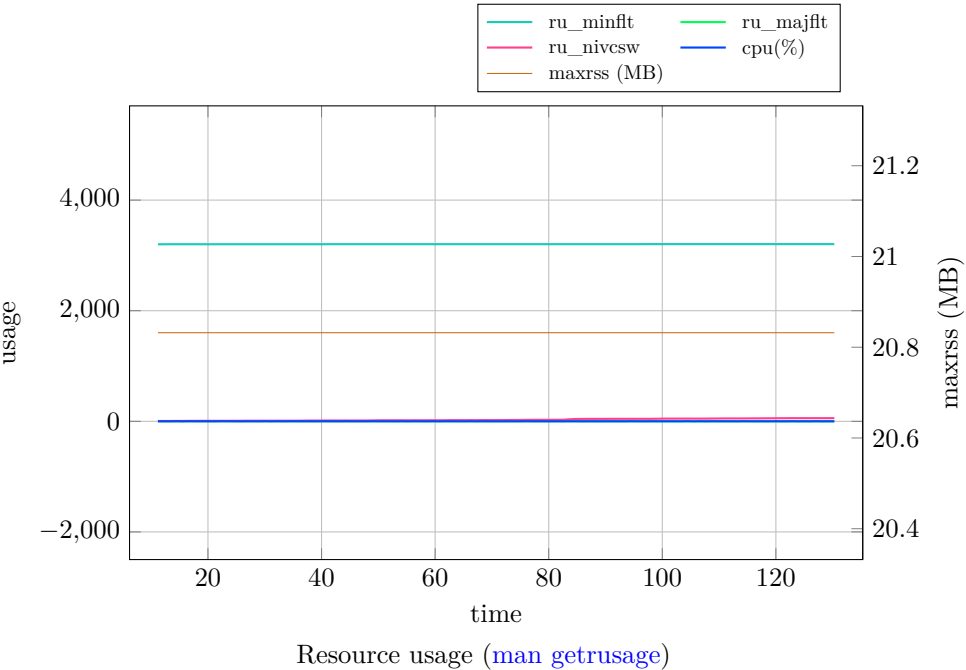
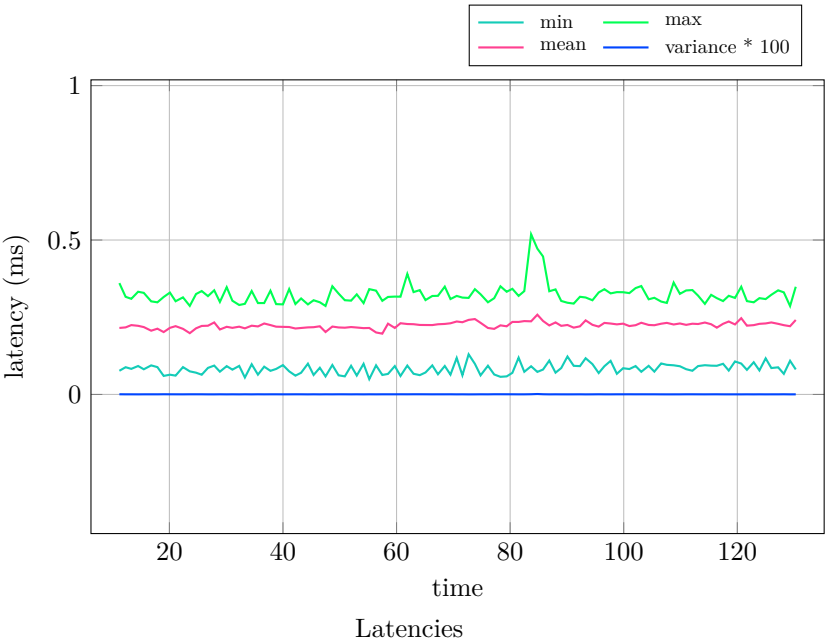


Performance

Logfile name	log_test_topic_28-11-2020_11-48-14
Experiment id	b4ea8034-93e4-41ae-af1a-04a14c843f9b
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0925
received	47.5273
sent	9.5182
lost	0.0
relative_loss	0.0
data_received	42031.1727
latency_min (ms)	0.0833
latency_max (ms)	0.3236
latency_mean (ms)	0.2238
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.4114
pub_loop_res_max (ms)	99.8193
pub_loop_res_mean (ms)	99.5126
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.774

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0