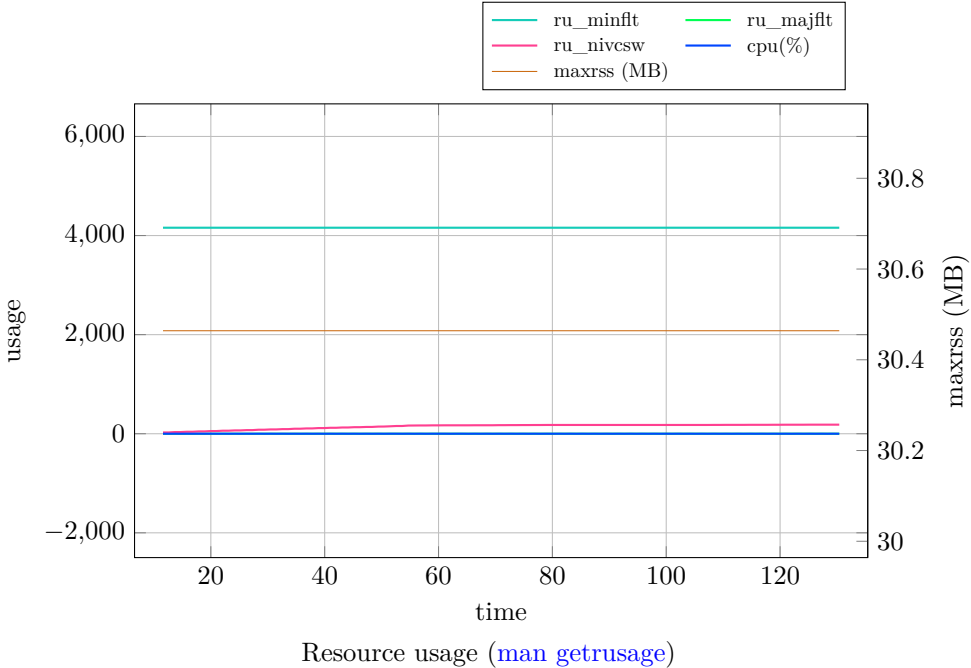
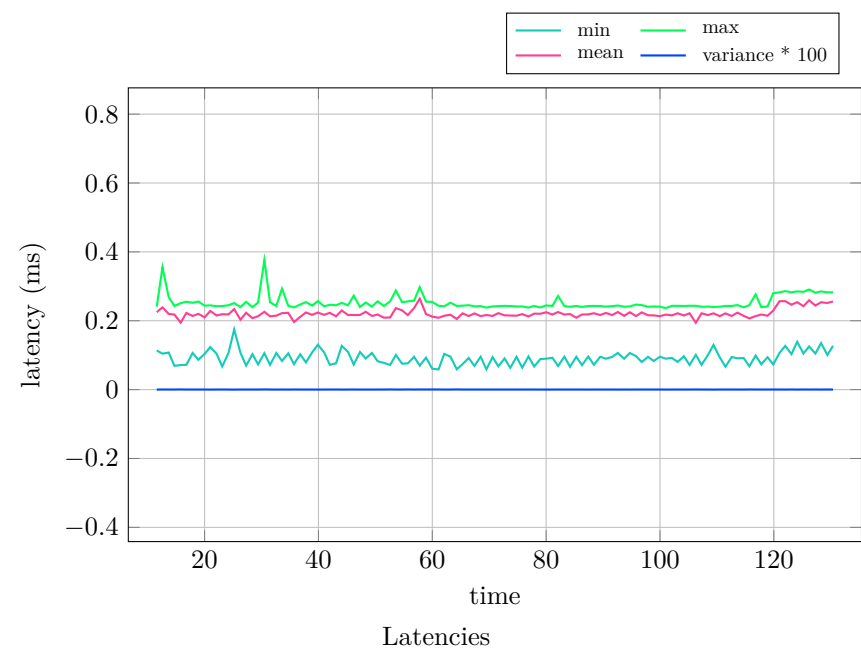


Performance

| | |
|--------------------|--------------------------------------|
| Logfile name | log_test_topic_12-12-2020_11-36-25 |
| Experiment id | fce6d4ea-3e5c-42d7-ba13-bf81375497d6 |
| Communication mean | ROS2 |



| test setup | | average results | | environment | |
|--------------------------|------------|----------------------------|----------|-------------------------------|------------------|
| Performance Test Version | 80ff298 | Experiment Status | success | Ignore seconds from beginning | 10 |
| Publishing rate | 10 | T_loop | 1.0515 | Memory check enabled | 0 |
| Topic name | test_topic | received | 9.5175 | Msg name | NavSatFix |
| Number of publishers | 1 | sent | 9.5 | QOS Durability | VOLATILE |
| Number of subscribers | 1 | lost | 0.0 | QOS History depth | 1 |
| Maximum runtime (sec) | 130 | relative_loss | 0.0 | QOS History kind | KEEP_LAST |
| DDS domain id | 0 | data_received | 1687.386 | QOS Reliability | BEST_EFFORT |
| Single participant | - | latency_min (ms) | 0.0918 | QOS Sync. pub/sub | 0 |
| | | latency_max (ms) | 0.253 | RMW Implementation | rmw_fastrtps_cpp |
| | | latency_mean (ms) | 0.2212 | Roundtrip Mode | NONE |
| | | latency_variance (ms) | 0.0 | With security | 0 |
| | | pub_loop_res_min (ms) | 99.483 | | |
| | | pub_loop_res_max (ms) | 99.7743 | | |
| | | pub_loop_res_mean (ms) | 99.5402 | | |
| | | pub_loop_res_variance (ms) | 0.0 | | |
| | | sub_loop_res_min (ms) | 0.0 | | |
| | | sub_loop_res_max (ms) | 0.0 | | |
| | | sub_loop_res_mean (ms) | 0.0 | | |
| | | sub_loop_res_variance (ms) | 0.0 | | |
| | | cpu_usage (%) | 0.4235 | | |