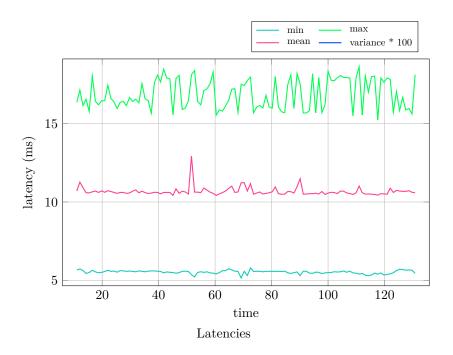
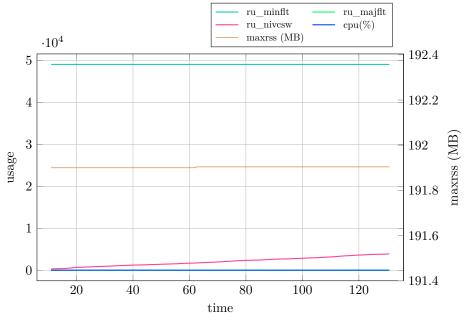
Performance

 Logfile name
 log_test_topic_30-11-2020_09-56-07

 Experiment id
 a2b6b3f9-951b-4780-8b1a-0b32283e52a1

 Communication mean
 ROS2





Resource usage (man getrusage)

test setup

Performance Test Version 80ff298
Publishing rate 1000
Topic name test_topic
Number of publishers 1
Number of subscribers 10
Maximum runtime (sec) 130
DDS domain id 0
Single participant -

average results

Experiment Status success T_loop 1.099 received 869.3727 sent 348.2909 lost 2607.5 relative loss 7.4855data_received 3671539593.1545latency min (ms) 5.5282latency_max (ms) 16.8811 latency_mean (ms) 10.6736 latency variance (ms) 0.0093 pub_loop_res_min (ms) -45576.4364 pub_loop_res_max (ms) -44862.7455 pub_loop_res_mean (ms) -45219.5091 pub_loop_res_variance (ms) 42.5666 sub_loop_res_min (ms) 0.0 sub loop res max (ms) 0.0 sub_loop_res_mean (ms) 0.0 sub loop res variance (ms) 0.0 cpu_usage (%) 28.814

environment

Ignore seconds from beginni	ng 10
Memory check enabled	0
Msg name	PointCloud4m
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0