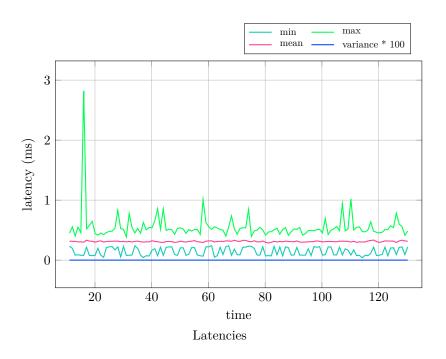
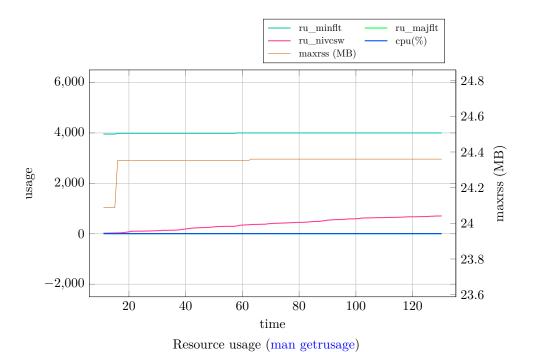
Performance

 Logfile name
 log_test_topic_27-11-2020_13-33-10

 Experiment id
 fd957df4-8906-4ca6-abc9-275abac3f25b

 Communication mean
 ROS2





test setup average results environment

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	3
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T loop	1.0016
received	2998.325
sent	999.4667
lost	0.125
relative loss	0.0001
data received	184358802.5583
latency min (ms)	0.1425
latency_max (ms)	0.553
latency mean (ms)	0.3108
latency variance (ms)	0.0
pub loop res min (ms)	0.7232
pub loop res max (ms)	0.9117
pub loop res mean (ms)	0.8238
pub_loop_res_variance (ms)	0.0200
sub loop res min (ms)	0.0
sub_loop_res_mm (ms)	0.0
sub_loop_res_max (ms) sub_loop_res_mean (ms)	0.0
sub_loop_res_mean (ms) sub_loop_res_variance (ms)	0.0
cpu usage (%)	7.1609
cpu_usage (70)	7.1009

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Array60k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0