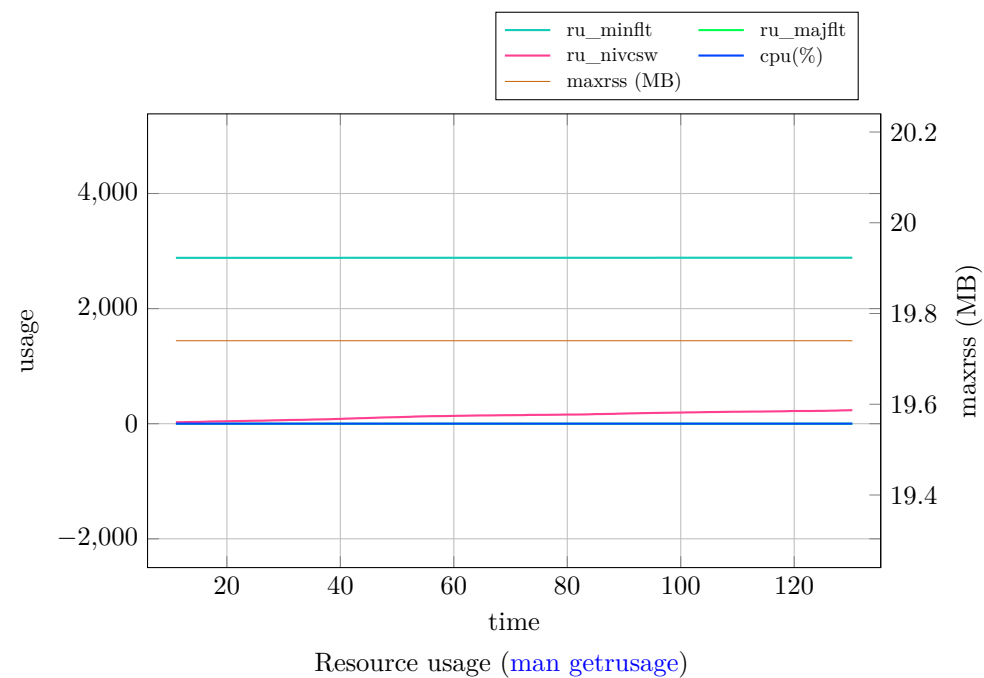
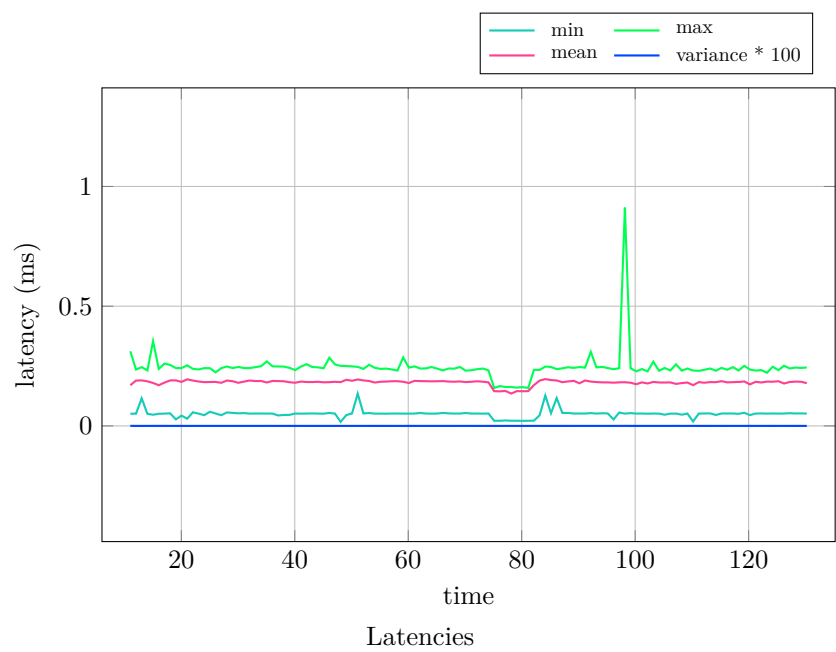


Performance

Logfile name	log_test_topic_29-11-2020_17-17-23
Experiment id	8db974a7-f67f-4f3b-8ff4-b968fab44641
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	500
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0017
received	499.5667
sent	499.5583
lost	0.0
relative_loss	0.0
data_received	84000.6917
latency_min (ms)	0.0507
latency_max (ms)	0.2452
latency_mean (ms)	0.1816
latency_variance (ms)	0.0
pub_loop_res_min (ms)	1.61
pub_loop_res_max (ms)	1.9304
pub_loop_res_mean (ms)	1.687
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.1947

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0