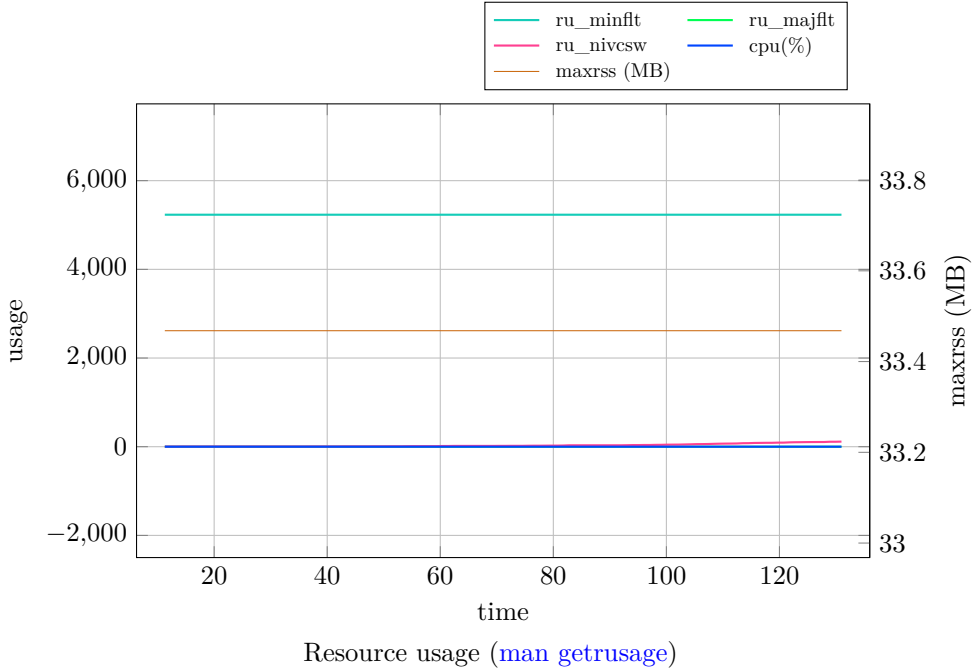
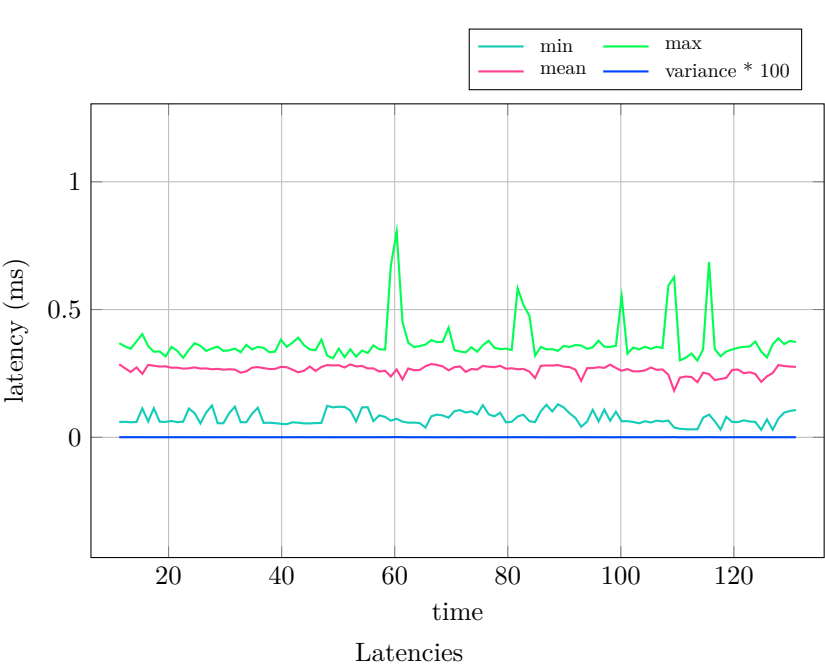


# Performance

Logfile name	log_test_topic_29-11-2020_12-03-20
Experiment id	26c6acbc-efb8-4455-b4e5-92a75f87ab0a
Communication mean	ROS2



## test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

## average results

Experiment Status	success
T_loop	1.023
received	247.6356
sent	49.5339
lost	0.0
relative_loss	0.0
data_received	20000.8051
latency_min (ms)	0.0754
latency_max (ms)	0.3703
latency_mean (ms)	0.2642
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.431
pub_loop_res_max (ms)	19.8809
pub_loop_res_mean (ms)	19.5402
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.6675

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0