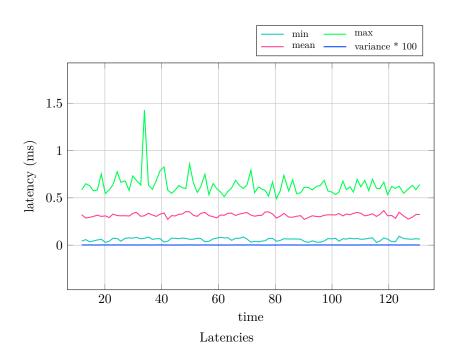
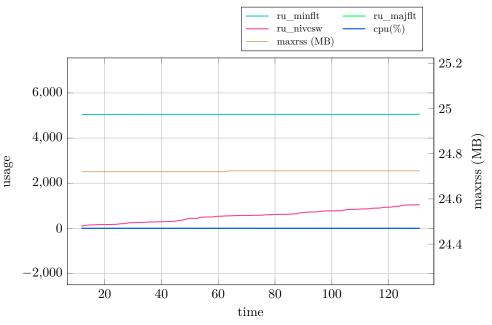
## Performance

 Logfile name
 log\_test\_topic\_28-11-2020\_19-09-55

 Experiment id
 4c48380b-4f6a-45af-946a-f5832fcfa82d

 Communication mean
 ROS2





Resource usage (man getrusage)

## test setup

Performance Test Version 80ff298
Publishing rate 10
Topic name test\_topic
Number of publishers 1
Number of subscribers 10
Maximum runtime (sec) 130
DDS domain id 0
Single participant -

## average results

Experiment Status success T\_loop 1.3538 received 94.77539.5281sent lost 0.0 relative loss 0.0 data\_received 411724.4831latency min (ms) 0.06 latency\_max (ms) 0.6317latency\_mean (ms) 0.3174latency variance (ms) 0.0 pub\_loop\_res\_min (ms) 99.6388 pub\_loop\_res\_max (ms) 99.9069 pub\_loop\_res\_mean (ms) 99.786pub\_loop\_res\_variance (ms) 0.0 sub\_loop\_res\_min (ms) 0.0 sub loop res max (ms) 0.0 sub\_loop\_res\_mean (ms) 0.0 sub loop res variance (ms) 0.0 cpu\_usage (%) 3.4722

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Array4k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0
-	