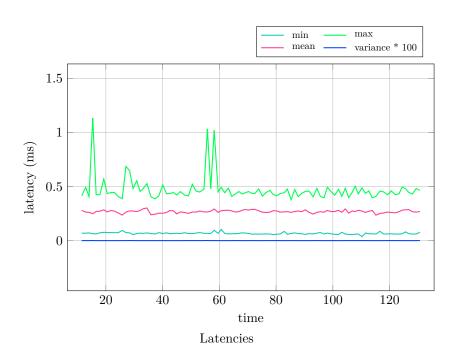
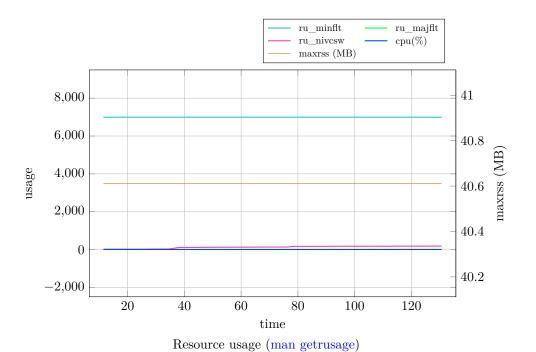
## Performance

 Logfile name
 log\_test\_topic\_12-12-2020\_19-43-36

 Experiment id
 52d1f124-2f2f-4ad8-88c2-f2aae4b49868

 Communication mean
 ROS2





test setup	average results	environment

Performance Test Version	80ff298
Publishing rate	10
Topic name	$test\_topic$
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T loop	1.2672
received	95.2737
sent	9.4842
lost	0.0
relative loss	0.0
data received	84076.9158
latency min (ms)	0.0675
	0.00.0
latency_max (ms)	0.4721
latency_mean (ms)	0.2692
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.5077
pub_loop_res_max (ms)	99.8939
pub_loop_res_mean (ms)	99.6234
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub loop res max (ms)	0.0
sub loop res mean (ms)	0.0
sub loop res variance (ms)	0.0
cpu_usage (%)	1.938

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0