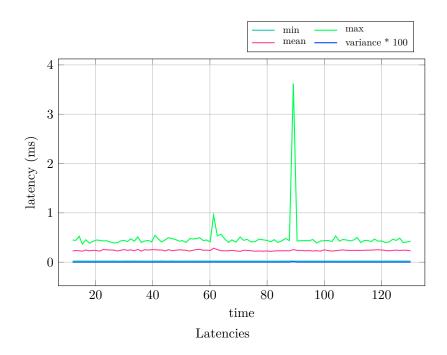
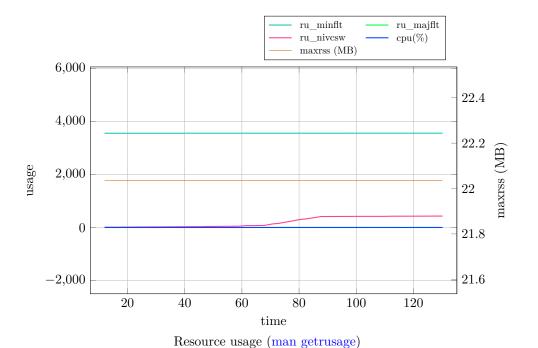
Performance

 Logfile name
 log_test_topic_12-12-2020_18-57-34

 Experiment id
 b7a9e604-8073-4464-b12e-977480cedd9a

 Communication mean
 ROS2





test setup average results environment

Performance Test Version	80ff298
Publishing rate	10
Topic name	$test_topic$
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T loop	1.2578
received	94.8211
sent	9.4842
lost	0.0
relative_loss	0.0
data_received	8002.2211
latency_min (ms)	0.0222
latency_max (ms)	0.4822
latency_mean (ms)	0.239
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.3432
pub_loop_res_max (ms)	99.8741
pub_loop_res_mean (ms)	99.5224
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.9226

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0