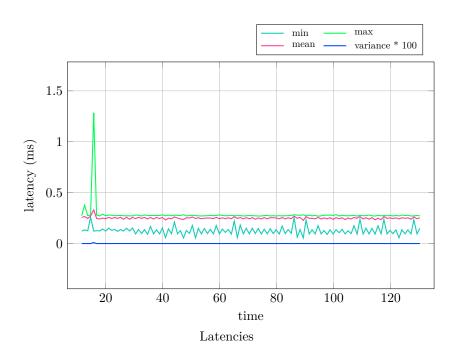
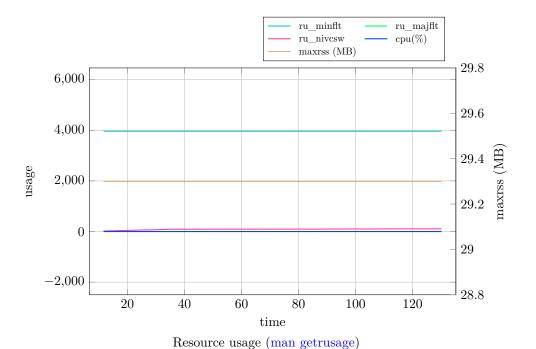
Performance

 Logfile name
 log_test_topic_28-11-2020_10-15-16

 Experiment id
 d54b8d4a-3d43-4272-9086-2cff722123fb

 Communication mean
 ROS2





test setup	average results		${f environment}$
		_	

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

E-manineant Status	
Experiment Status	success
T_loop	1.0498
received	9.5
sent	9.5
lost	0.0
relative_loss	0.0
data_received	803.0
latency_min (ms)	0.127
latency_max (ms)	0.2851
latency_mean (ms)	0.2503
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.4905
pub_loop_res_max (ms)	99.7609
pub_loop_res_mean (ms)	99.5371
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.4099

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP ALL
QOS Reliability	BEST EFFORT
QOS Sync. pub/sub	_ 0
RMW Implementation	rmw fastrtps cpp
Roundtrip Mode	NONE
With security	0