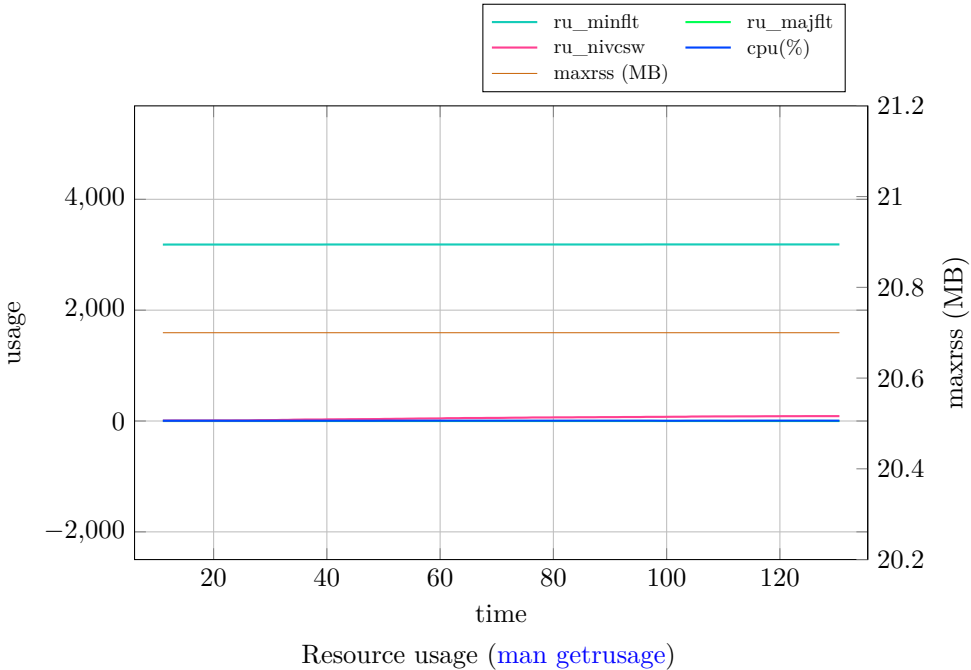
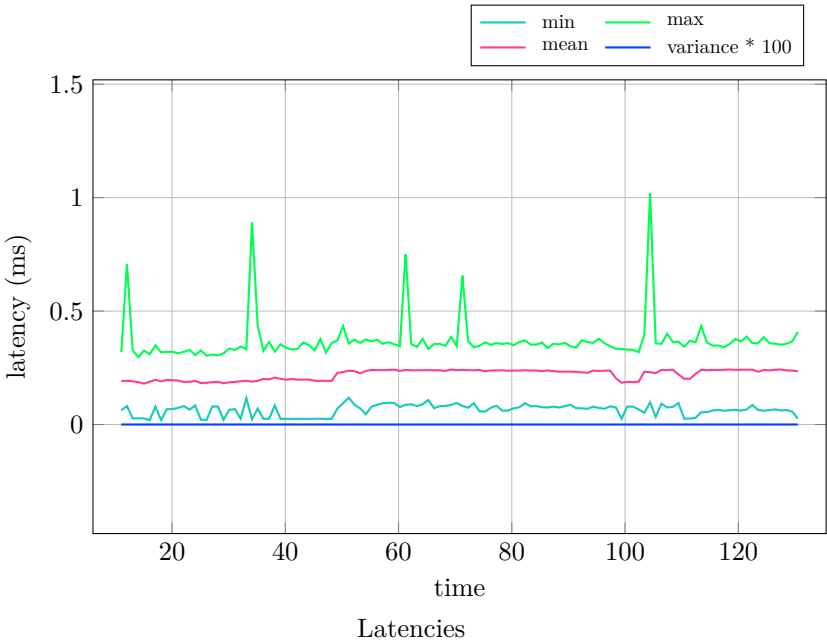


Performance

Logfile name	log_test_topic_01-12-2020_15-11-28
Experiment id	ca88e608-5606-4a4b-a326-1d862f91c356
Communication mean	ROS2



test setup		average results		environment	
Performance Test Version	80ff298	Experiment Status	success	Ignore seconds from beginning	10
Publishing rate	500	T_loop	1.0037	Memory check enabled	0
Topic name	test_topic	received	2497.3417	Msg name	NavSatFix
Number of publishers	1	sent	499.4583	QOS Durability	VOLATILE
Number of subscribers	5	lost	0.0	QOS History depth	1
Maximum runtime (sec)	130	relative_loss	0.0	QOS History kind	KEEP_LAST
DDS domain id	0	data_received	419998.7917	QOS Reliability	BEST_EFFORT
Single participant	-	latency_min (ms)	0.0642	QOS Sync. pub/sub	0
		latency_max (ms)	0.3702	RMW Implementation	rmw_cyclonedds_cpp
		latency_mean (ms)	0.2204	Roundtrip Mode	NONE
		latency_variance (ms)	0.0	With security	0
		pub_loop_res_min (ms)	1.5869		
		pub_loop_res_max (ms)	1.8753		
		pub_loop_res_mean (ms)	1.6657		
		pub_loop_res_variance (ms)	0.0		
		sub_loop_res_min (ms)	0.0		
		sub_loop_res_max (ms)	0.0		
		sub_loop_res_mean (ms)	0.0		
		sub_loop_res_variance (ms)	0.0		
		cpu_usage (%)	5.679		