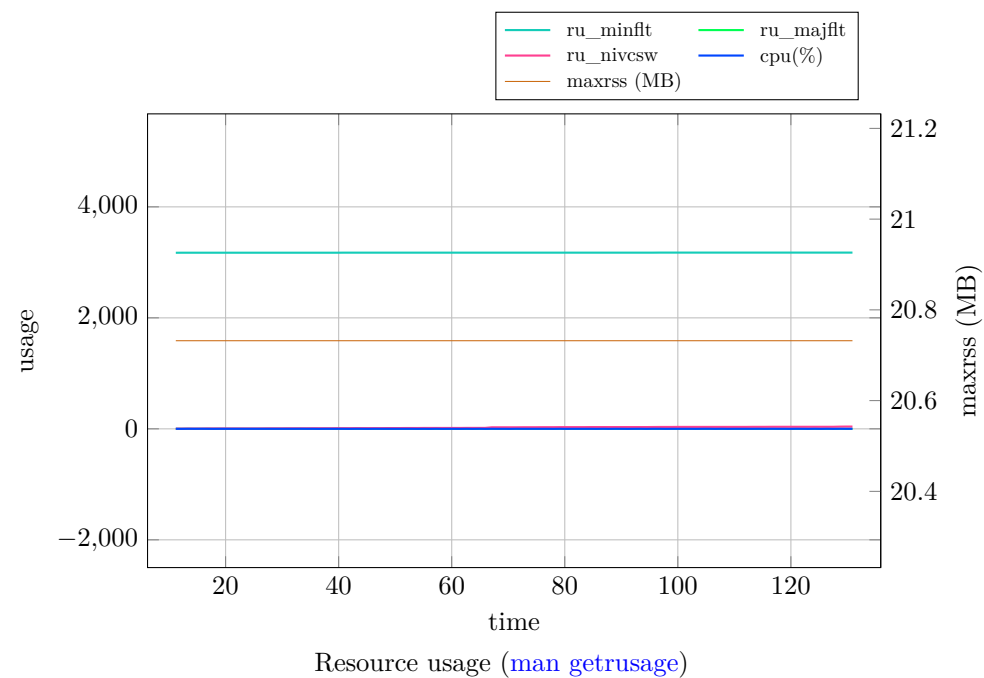
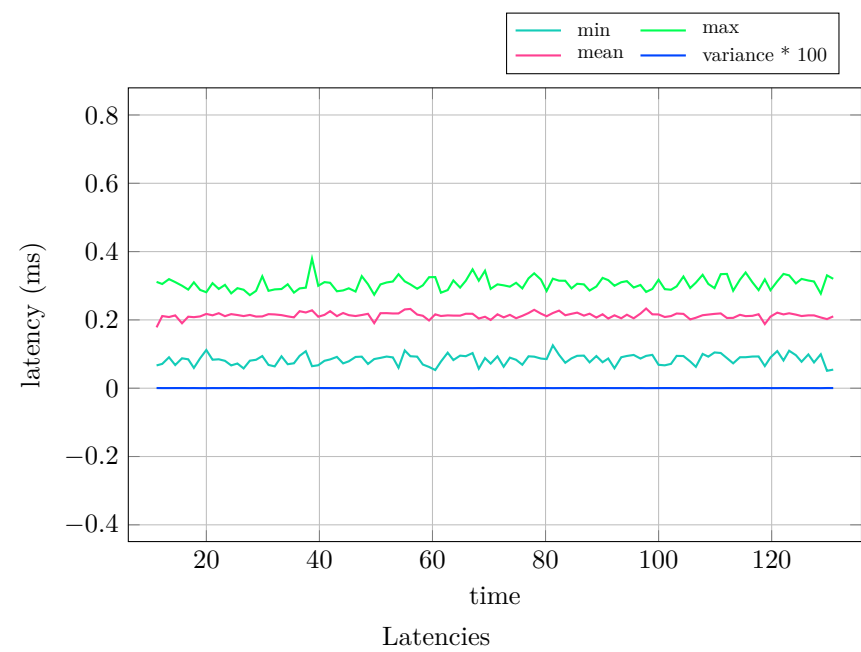


# Performance

Logfile name	log_test_topic_12-12-2020_14-00-11
Experiment id	2bf9085a-896f-4985-a51c-f153ed4641af
Communication mean	ROS2



test setup		average results		environment	
Performance Test Version	80ff298	Experiment Status	success	Ignore seconds from beginning	10
Publishing rate	10	T_loop	1.098	Memory check enabled	0
Topic name	test_topic	received	47.5364	Msg name	RadarDetection
Number of publishers	1	sent	9.4727	QOS Durability	VOLATILE
Number of subscribers	5	lost	0.0	QOS History depth	1
Maximum runtime (sec)	130	relative_loss	0.0	QOS History kind	KEEP_LAST
DDS domain id	0	data_received	4002.3273	QOS Reliability	BEST_EFFORT
Single participant	-	latency_min (ms)	0.0839	QOS Sync. pub/sub	0
		latency_max (ms)	0.3056	RMW Implementation	rmw_cyclonedds_cpp
		latency_mean (ms)	0.2132	Roundtrip Mode	NONE
		latency_variance (ms)	0.0	With security	0
		pub_loop_res_min (ms)	99.4175		
		pub_loop_res_max (ms)	99.8476		
		pub_loop_res_mean (ms)	99.5135		
		pub_loop_res_variance (ms)	0.0		
		sub_loop_res_min (ms)	0.0		
		sub_loop_res_max (ms)	0.0		
		sub_loop_res_mean (ms)	0.0		
		sub_loop_res_variance (ms)	0.0		
		cpu_usage (%)	0.8209		