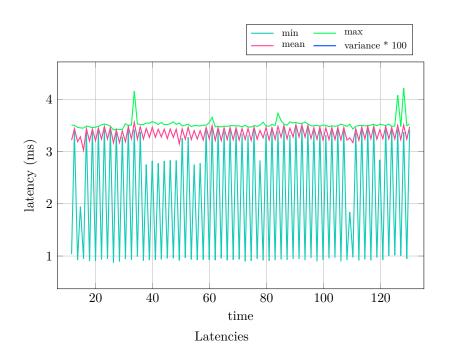
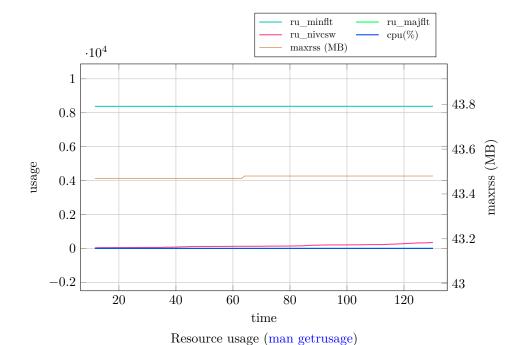
## Performance

 Logfile name
 log\_test\_topic\_28-11-2020\_08-39-20

 Experiment id
 bedb0047-8288-4fb2-8105-4dbce205d278

 Communication mean
 ROS2





test setup	average results	environment

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	_

Experiment Status	success
T loop	1.0498
received	9.5
sent	9.5
lost	0.0
relative loss	0.0
<del>_</del>	
data_received	21063270.5526
latency_min (ms)	2.0888
latency_max (ms)	3.5221
latency mean (ms)	3.3386
latency_variance (ms)	0.0003
pub_loop_res_min (ms)	97.995
pub_loop_res_max (ms)	98.8368
pub loop res mean (ms)	98.1375
pub_loop_res_variance (ms)	0.0001
sub_loop_res_min (ms)	0.0
sub loop res max (ms)	0.0
sub loop res mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.2217

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	PointCloud2m
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0