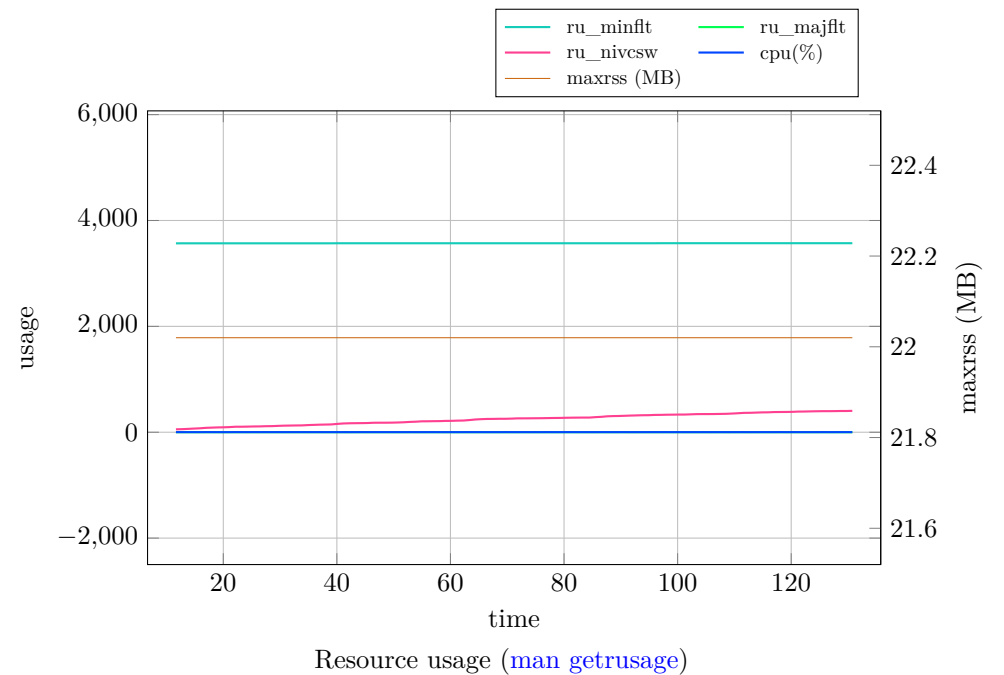
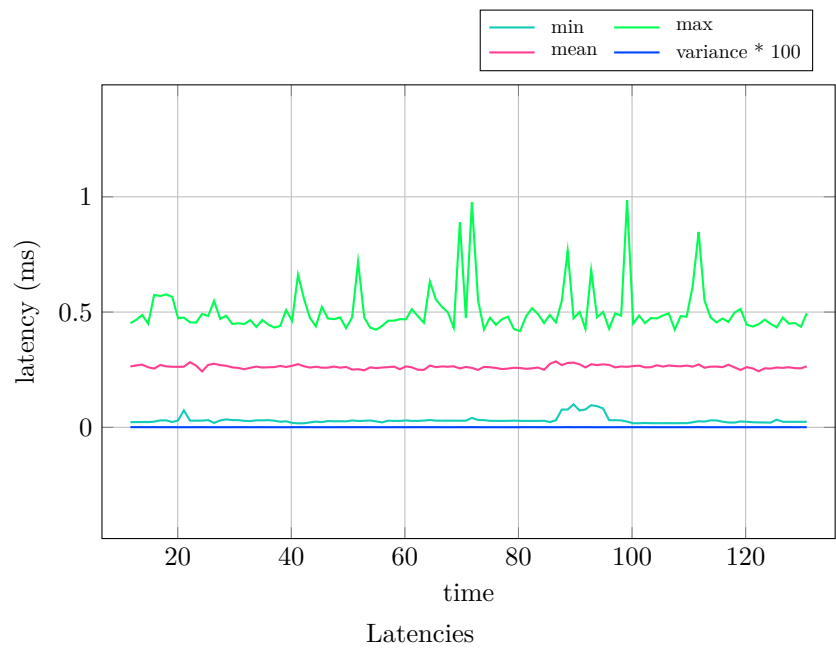


Performance

Logfile name	log_test_topic_29-11-2020_13-29-11
Experiment id	12a52a4e-9962-4aef-85e0-97f08e0e62b5
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0539
received	494.8246
sent	49.4737
lost	0.0
relative_loss	0.0
data_received	83996.3246
latency_min (ms)	0.0305
latency_max (ms)	0.5013
latency_mean (ms)	0.2621
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.278
pub_loop_res_max (ms)	19.8809
pub_loop_res_mean (ms)	19.4389
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.8843

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0