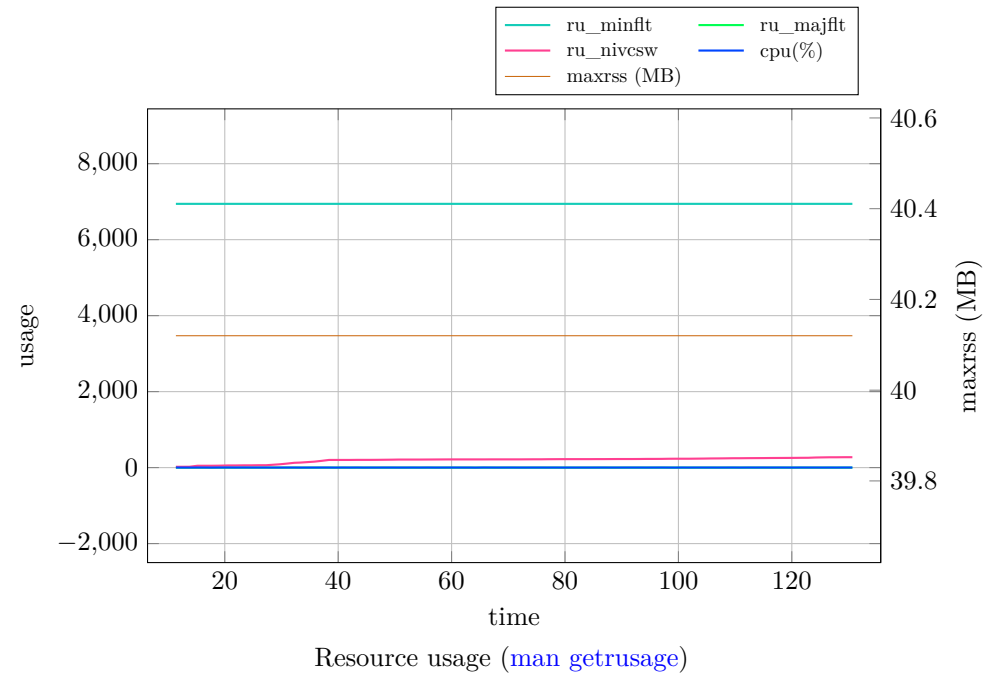
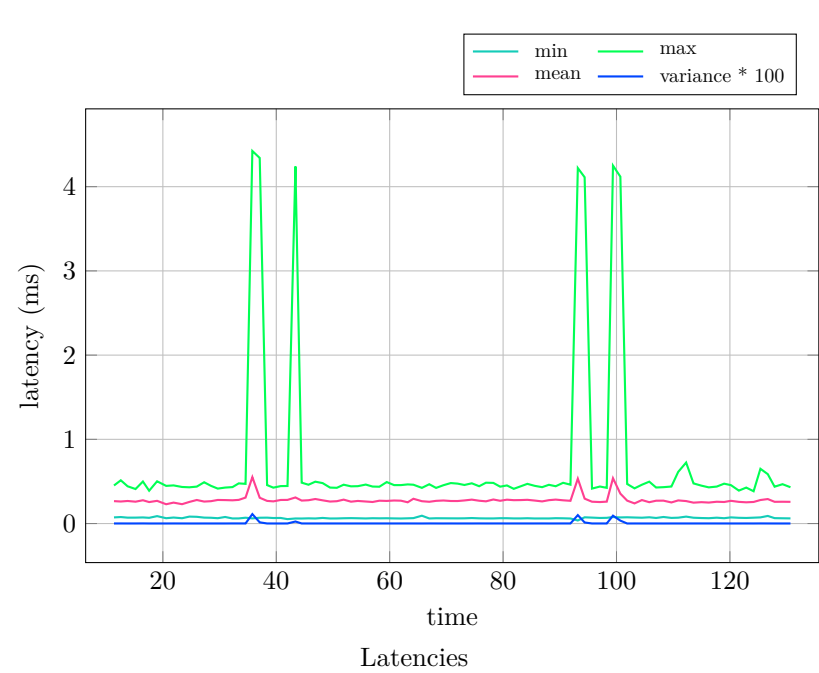


Performance

Logfile name	log_test_topic_12-12-2020_19-41-17
Experiment id	1c618d00-7c7b-4402-9706-202571db6bc7
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.2704
received	94.8316
sent	9.4632
lost	0.0
relative_loss	0.0
data_received	8004.3579
latency_min (ms)	0.0666
latency_max (ms)	0.7381
latency_mean (ms)	0.2785
latency_variance (ms)	0.0001
pub_loop_res_min (ms)	99.4887
pub_loop_res_max (ms)	99.8921
pub_loop_res_mean (ms)	99.6044
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.9491

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0