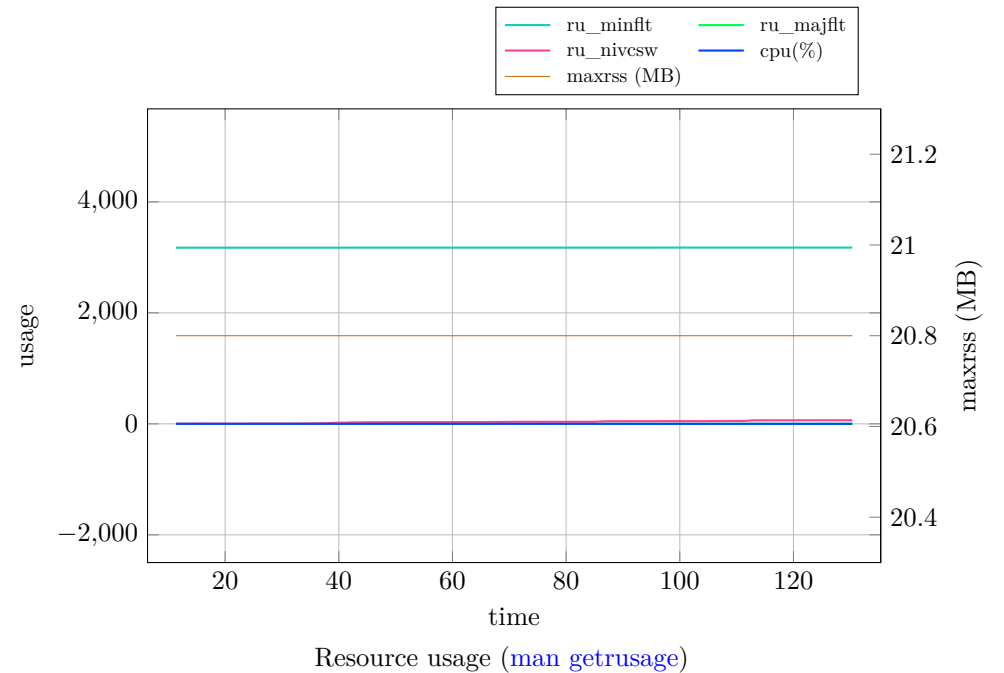
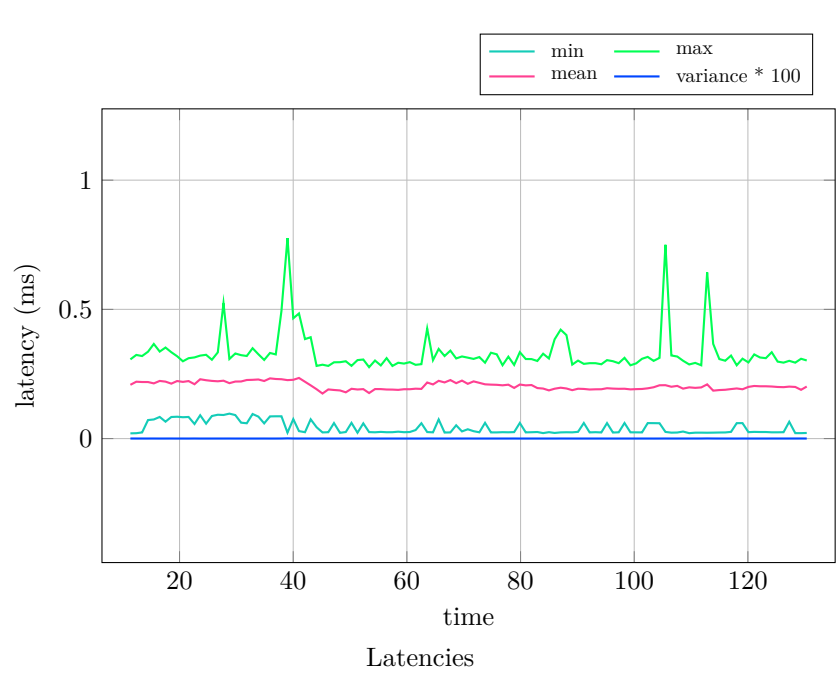


Performance

Logfile name	log_test_topic_29-11-2020_11-19-54
Experiment id	0f867d5c-24ae-4be1-b99a-c25bfe255fc6
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.026
received	247.5128
sent	49.5043
lost	0.0
relative_loss	0.0
data_received	19998.4103
latency_min (ms)	0.0421
latency_max (ms)	0.3303
latency_mean (ms)	0.2044
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.3756
pub_loop_res_max (ms)	19.8696
pub_loop_res_mean (ms)	19.5159
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.7211

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0