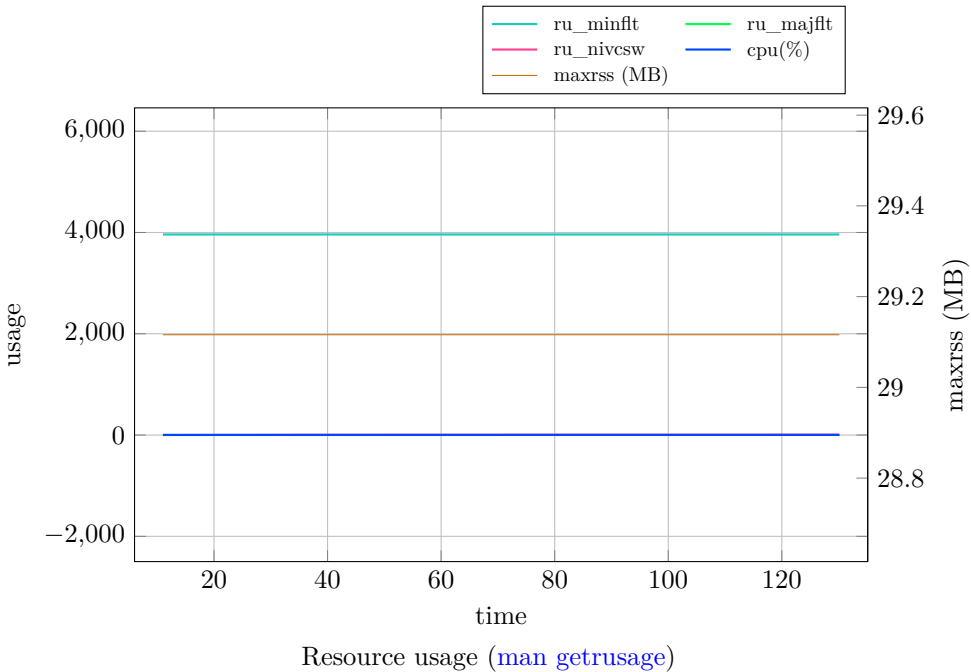
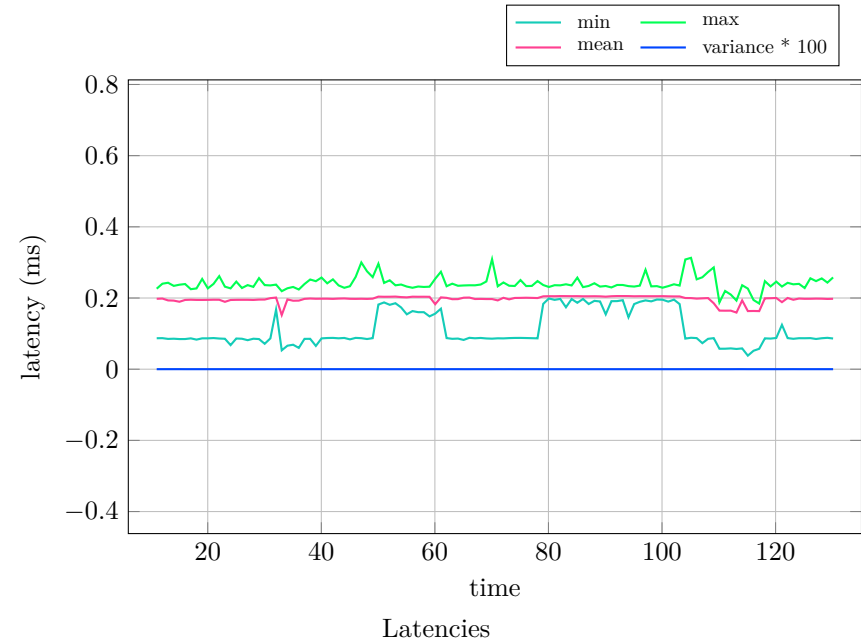


# Performance

Logfile name	log_test_topic_30-11-2020_05-21-00
Experiment id	321126c5-b1e7-4caf-a0e3-102c6738f1aa
Communication mean	ROS2



test setup		average results		environment	
Performance Test Version	80ff298	Experiment Status	success	Ignore seconds from beginning	10
Publishing rate	1000	T_loop	1.0007	Memory check enabled	0
Topic name	test_topic	received	999.4667	Msg name	NavSatFix
Number of publishers	1	sent	999.4667	QOS Durability	VOLATILE
Number of subscribers	1	lost	0.0	QOS History depth	1000
Maximum runtime (sec)	130	relative_loss	0.0	QOS History kind	KEEP_ALL
DDS domain id	0	data_received	167999.1167	QOS Reliability	BEST_EFFORT
Single participant	-	latency_min (ms)	0.1131	QOS Sync. pub/sub	0
		latency_max (ms)	0.2408	RMW Implementation	rmw_fastrtps_cpp
		latency_mean (ms)	0.1967	Roundtrip Mode	NONE
		latency_variance (ms)	0.0	With security	0
		pub_loop_res_min (ms)	0.7389		
		pub_loop_res_max (ms)	0.9233		
		pub_loop_res_mean (ms)	0.8429		
		pub_loop_res_variance (ms)	0.0		
		sub_loop_res_min (ms)	0.0		
		sub_loop_res_max (ms)	0.0		
		sub_loop_res_mean (ms)	0.0		
		sub_loop_res_variance (ms)	0.0		
		cpu_usage (%)	2.3095		