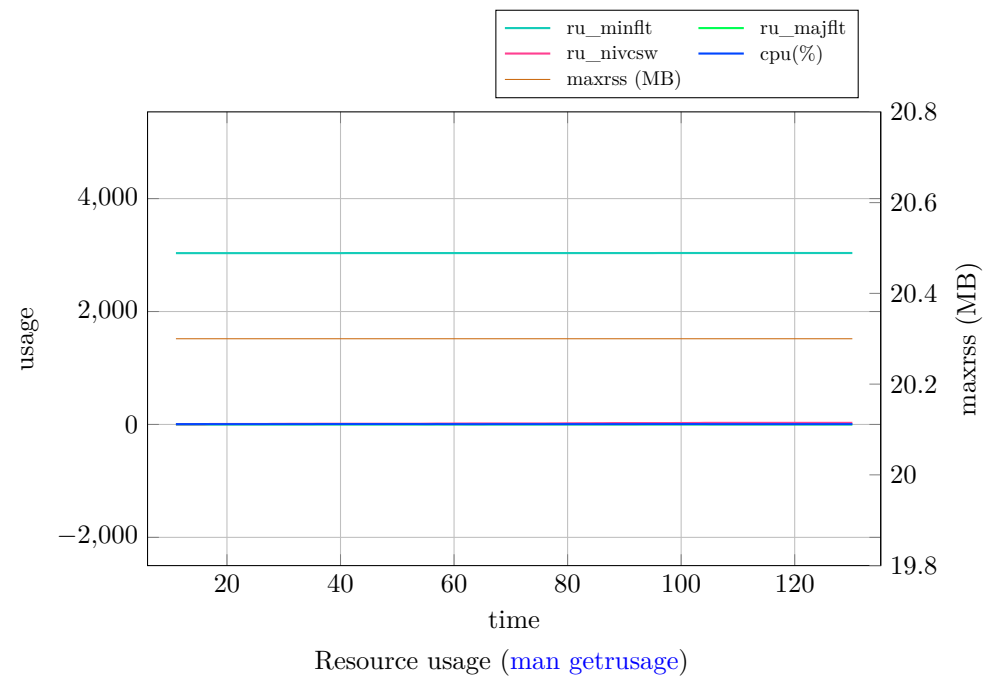
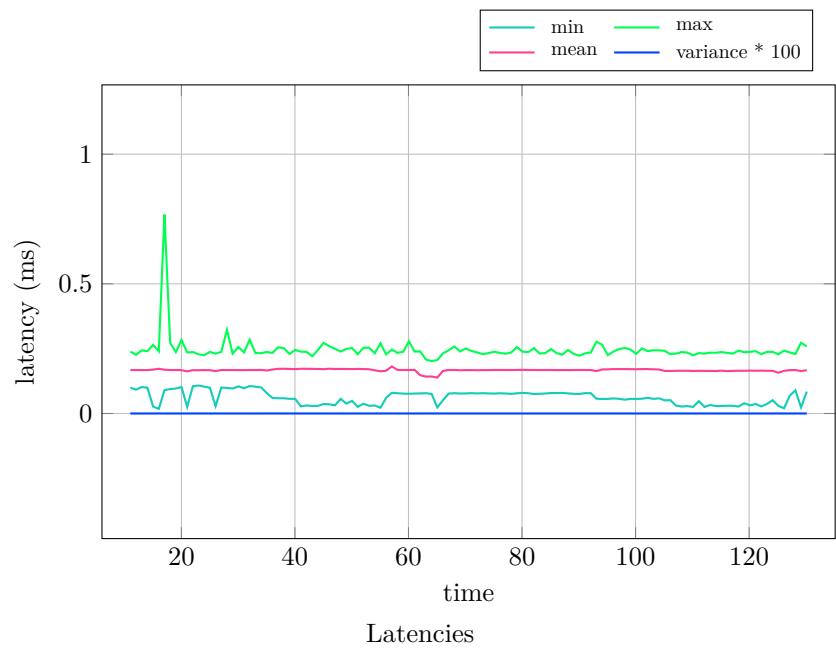


Performance

Logfile name	log_test_topic_27-11-2020_14-44-05
Experiment id	546c4fa3-1a58-47e7-b1db-f79e2a99442f
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	3
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0009
received	2998.45
sent	999.4833
lost	0.0
relative_loss	0.0
data_received	503999.9
latency_min (ms)	0.0619
latency_max (ms)	0.2455
latency_mean (ms)	0.167
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7364
pub_loop_res_max (ms)	0.9021
pub_loop_res_mean (ms)	0.8172
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	5.3596

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0