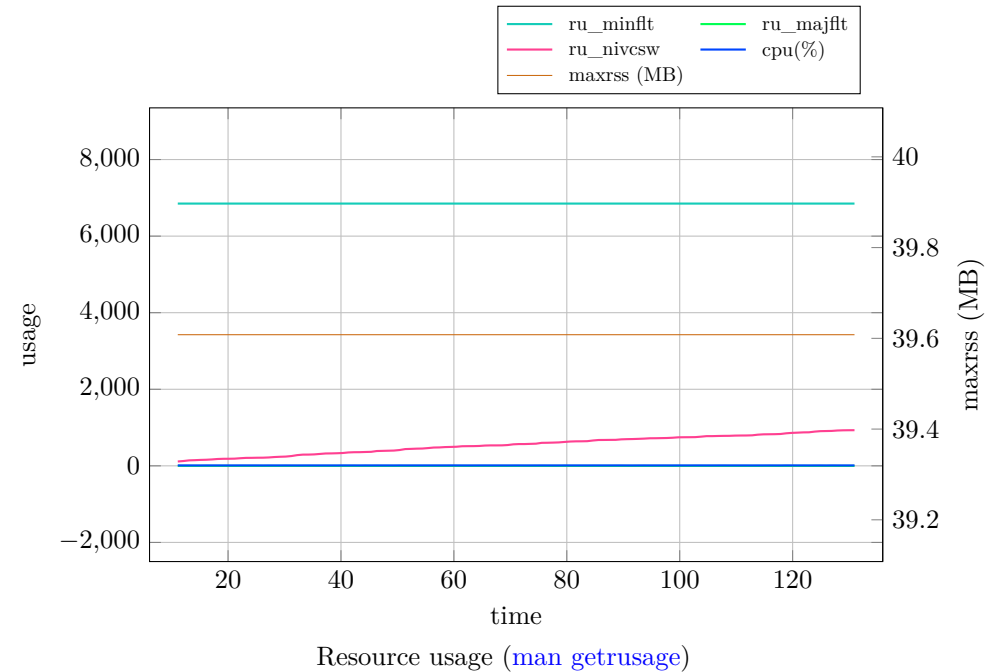
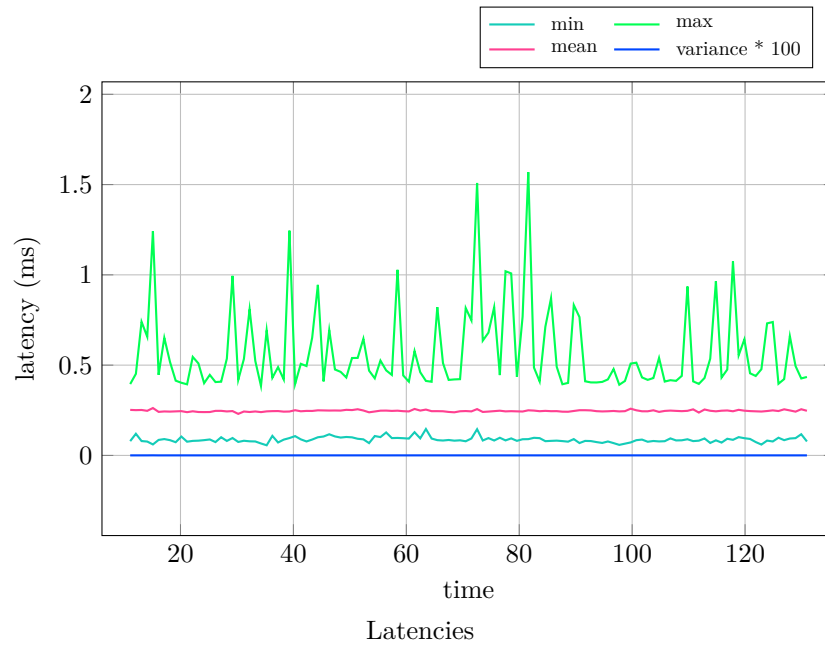


Performance

Logfile name	log_test_topic_01-12-2020_18-19-26
Experiment id	d82004b8-9eb3-4686-8514-30a775196dc1
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	500
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.007
received	4994.925
sent	499.4917
lost	0.0
relative_loss	0.0
data_received	399995.9
latency_min (ms)	0.0874
latency_max (ms)	0.5714
latency_mean (ms)	0.2463
latency_variance (ms)	0.0
pub_loop_res_min (ms)	1.8105
pub_loop_res_max (ms)	1.9202
pub_loop_res_mean (ms)	1.8553
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	10.8809

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0