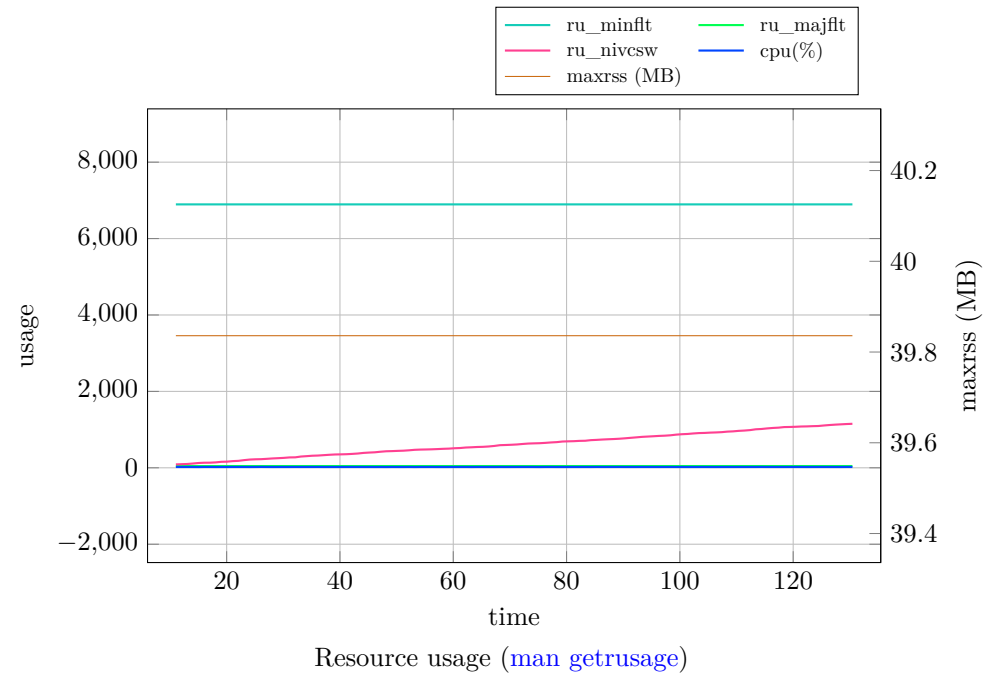
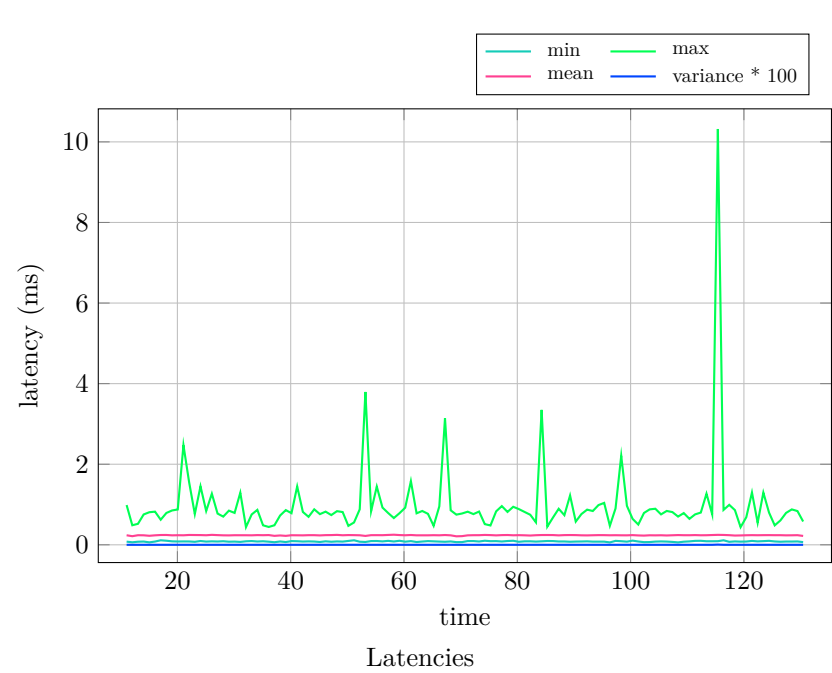


Performance

Logfile name	log_test_topic_30-11-2020_13-28-29
Experiment id	7fbf8d3e-abc6-43ca-a61e-2553c2fe1bee
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0032
received	9994.9833
sent	999.475
lost	0.0
relative_loss	0.0
data_received	799994.825
latency_min (ms)	0.0837
latency_max (ms)	0.9829
latency_mean (ms)	0.2372
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.8001
pub_loop_res_max (ms)	0.9211
pub_loop_res_mean (ms)	0.8756
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	21.2851

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0