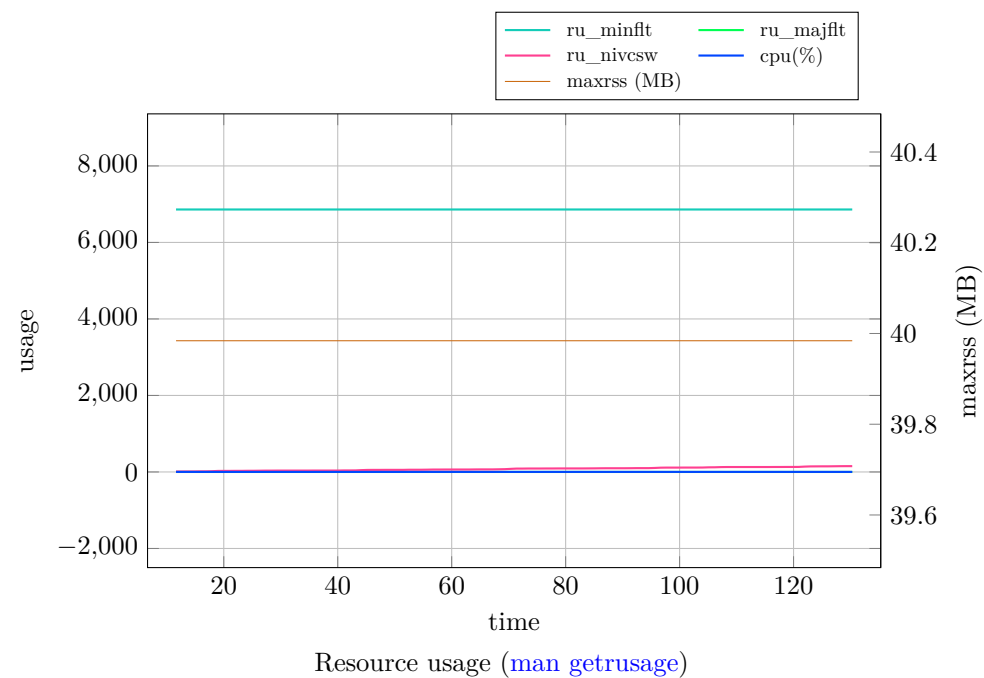
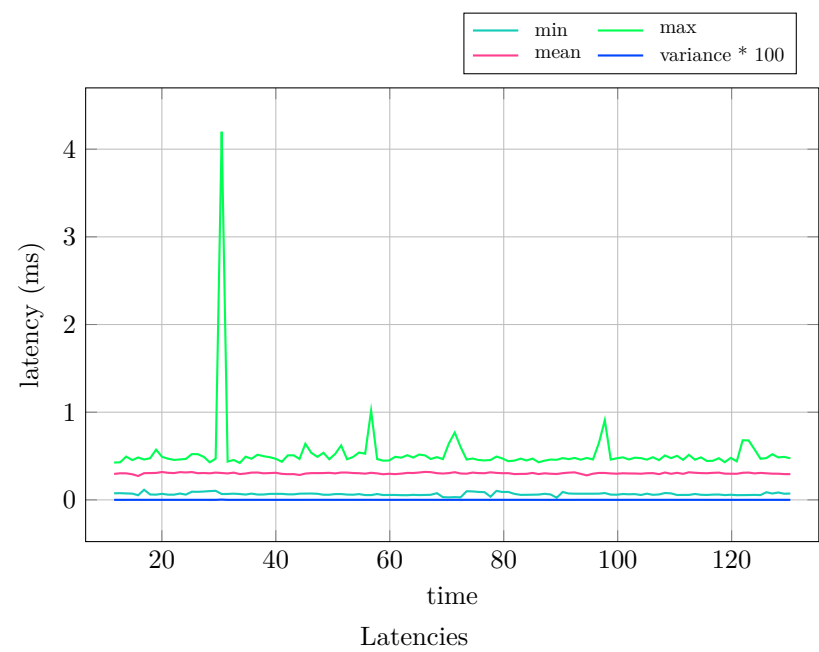


Performance

Logfile name	log_test_topic_01-12-2020_12-35-46
Experiment id	ed5ca563-2346-47ef-bb6f-c672f4ea923a
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.05
received	494.7895
sent	49.4825
lost	0.0
relative_loss	0.0
data_received	84002.5965
latency_min (ms)	0.0662
latency_max (ms)	0.5304
latency_mean (ms)	0.3034
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.4313
pub_loop_res_max (ms)	19.8959
pub_loop_res_mean (ms)	19.5396
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.5949

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0