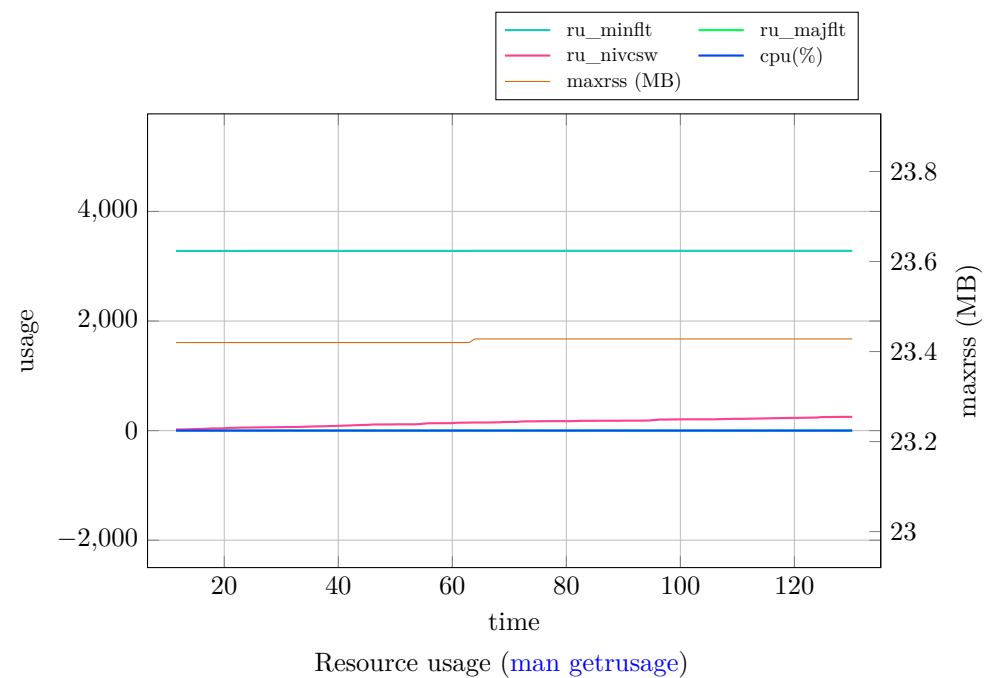
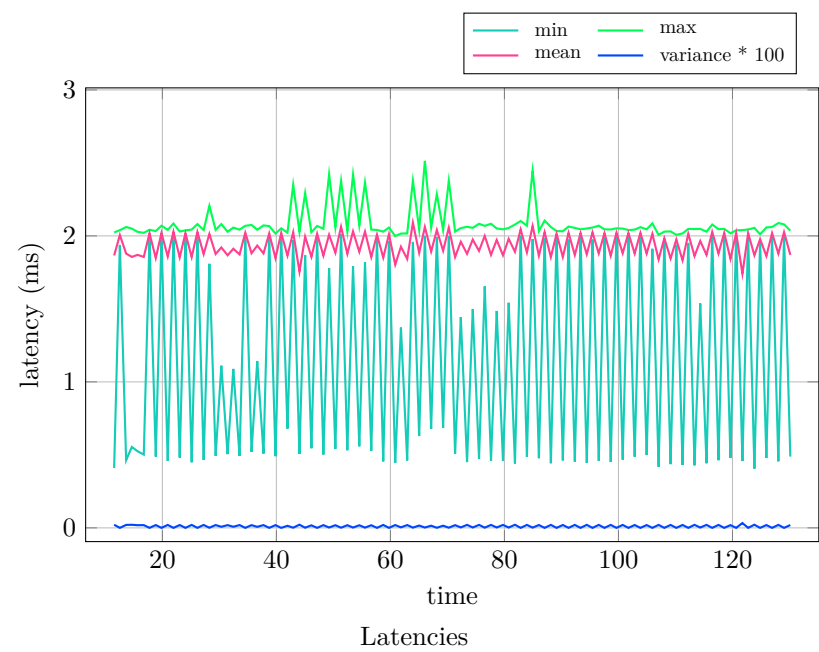


Performance

Logfile name	log_test_topic_28-11-2020_08-30-08
Experiment id	8a67a808-381c-4c08-a57a-375f007d3117
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0498
received	9.5
sent	9.4912
lost	0.0
relative_loss	0.0
data_received	85073.9825
latency_min (ms)	1.1507
latency_max (ms)	2.0822
latency_mean (ms)	1.9339
latency_variance (ms)	0.0001
pub_loop_res_min (ms)	98.8159
pub_loop_res_max (ms)	99.385
pub_loop_res_mean (ms)	98.9553
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.1045

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Struct4k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0