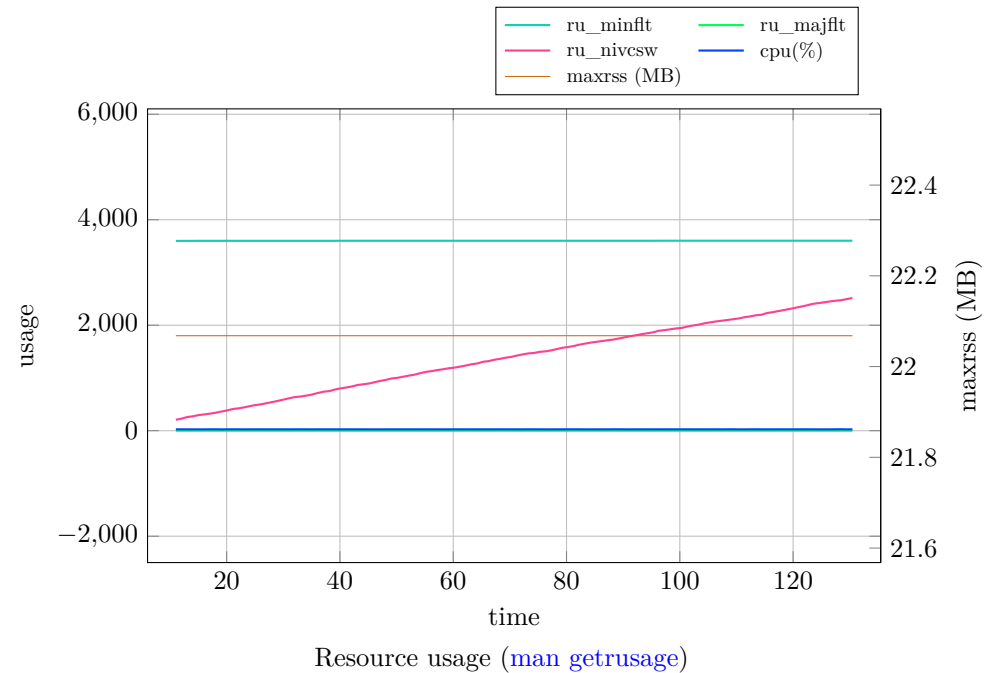
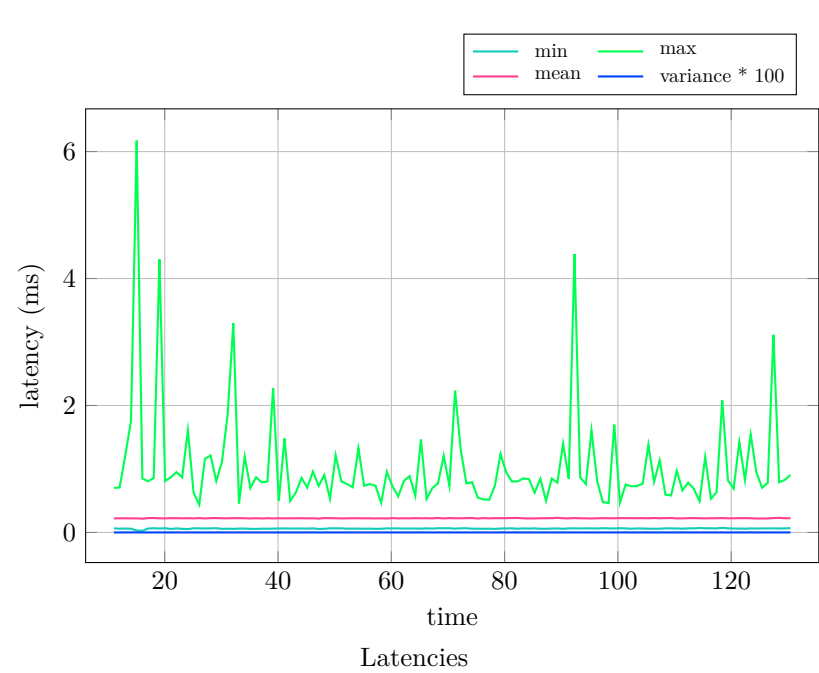


Performance

Logfile name	log_test_topic_30-11-2020_10-48-47
Experiment id	cdcbe7ba-3bf2-44d4-8eb6-5e650dc4f8e8
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0033
received	9994.975
sent	999.4667
lost	0.0
relative_loss	0.0
data_received	8400006.925
latency_min (ms)	0.0614
latency_max (ms)	1.0373
latency_mean (ms)	0.2236
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.5238
pub_loop_res_max (ms)	0.8478
pub_loop_res_mean (ms)	0.7672
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	26.027

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0