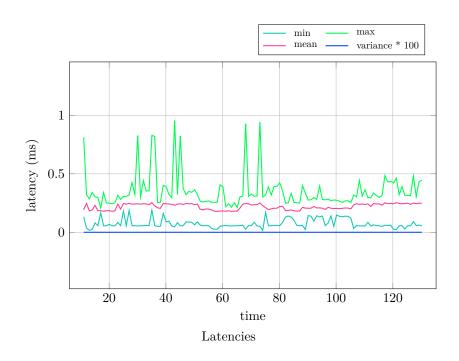
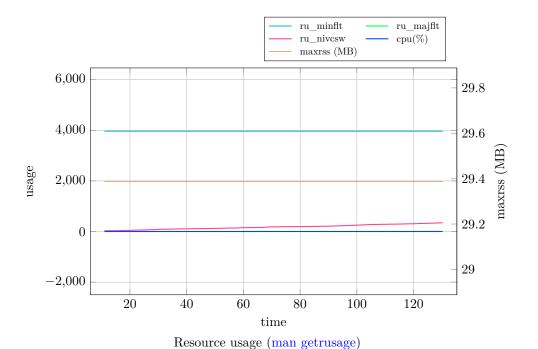
Performance

 Logfile name
 log_test_topic_29-11-2020_18-02-57

 Experiment id
 afb2aa14-44f4-4a11-9c83-5ef12f911017

 Communication mean
 ROS2





test setup average results environment

Performance Test Version	80ff298
Publishing rate	500
Topic name	$test_topic$
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T_loop	1.0017
received	499.4917
sent	499.4917
lost	0.0
relative_loss	0.0
data_received	39999.375
latency_min (ms)	0.0738
latency_max (ms)	0.3549
latency_mean (ms)	0.2193
latency_variance (ms)	0.0
pub_loop_res_min (ms)	1.6334
pub_loop_res_max (ms)	1.9195
pub_loop_res_mean (ms)	1.7422
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.3639

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0