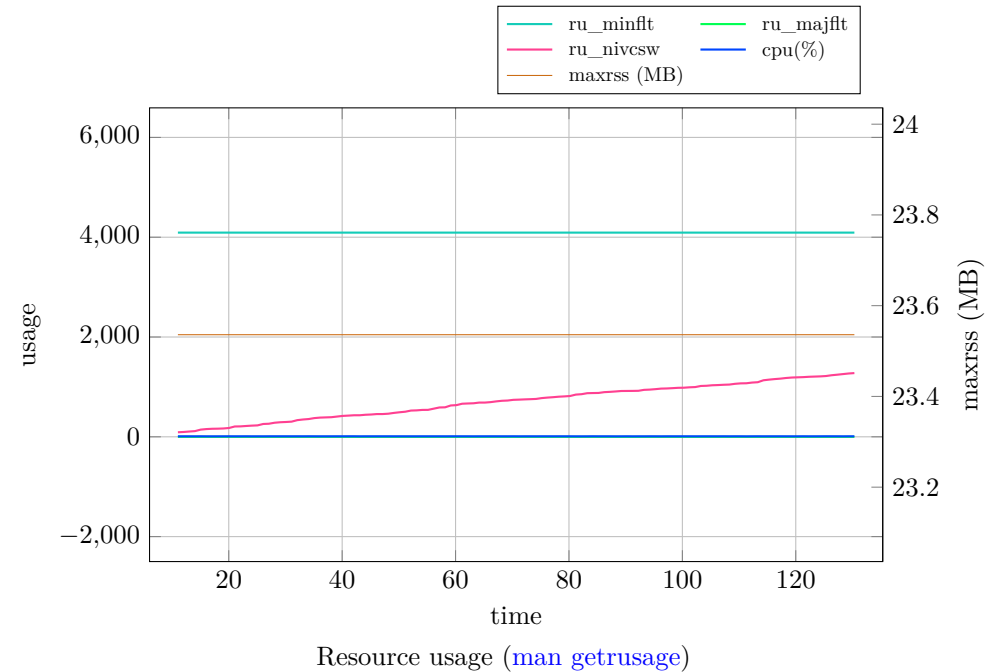
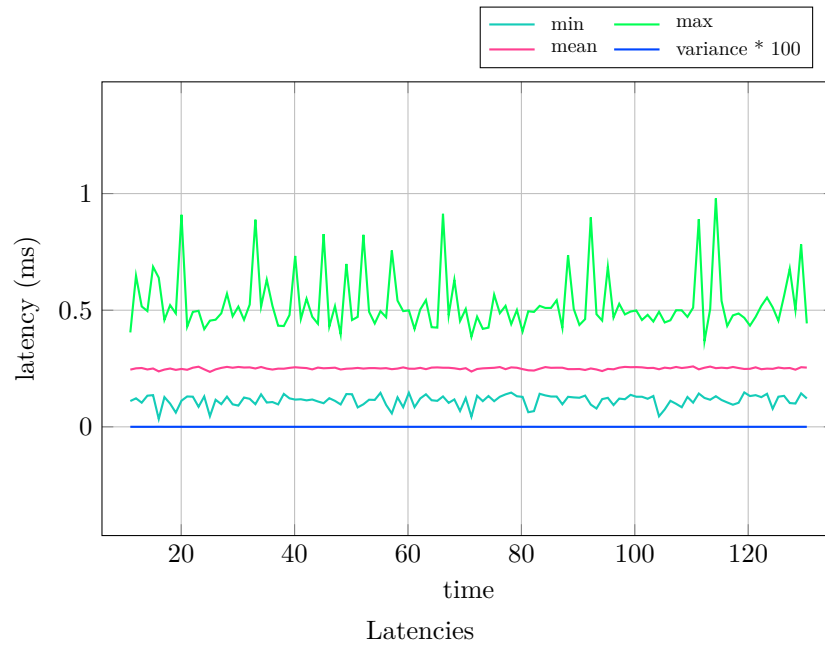


# Performance

Logfile name	log_test_topic_30-11-2020_07-18-13
Experiment id	ba68a8a3-e686-483c-9776-cc01a18d0c6a
Communication mean	ROS2



## test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

## average results

Experiment Status	success
T_loop	1.0023
received	4997.5833
sent	999.5083
lost	0.0
relative_loss	0.0
data_received	3999993.3417
latency_min (ms)	0.1129
latency_max (ms)	0.5275
latency_mean (ms)	0.2506
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7217
pub_loop_res_max (ms)	0.9143
pub_loop_res_mean (ms)	0.8367
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	10.0843

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0