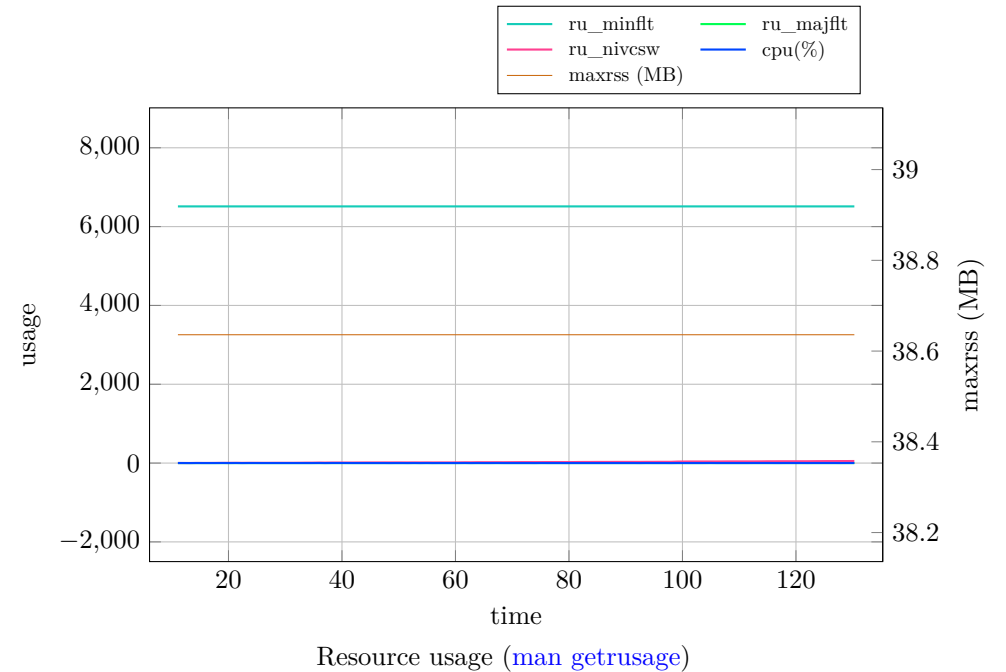
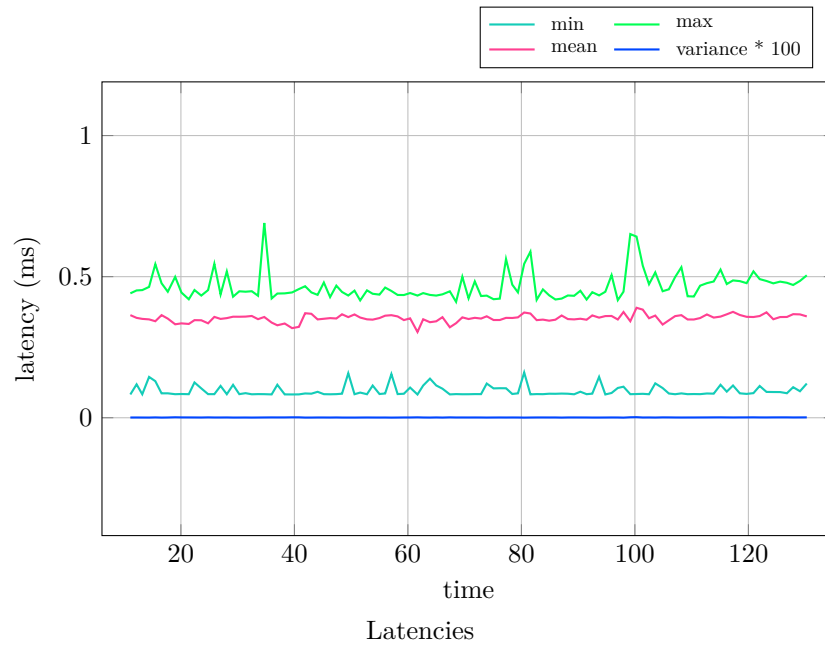


Performance

Logfile name	log_test_topic_28-11-2020_12-11-09
Experiment id	d3d89bc6-12ea-4b85-9c63-44cbb0364edc
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.1251
received	47.5701
sent	9.5607
lost	0.0
relative_loss	0.0
data_received	423694.9439
latency_min (ms)	0.0953
latency_max (ms)	0.4656
latency_mean (ms)	0.3528
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.4664
pub_loop_res_max (ms)	99.8553
pub_loop_res_mean (ms)	99.5521
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.012

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Struct4k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0