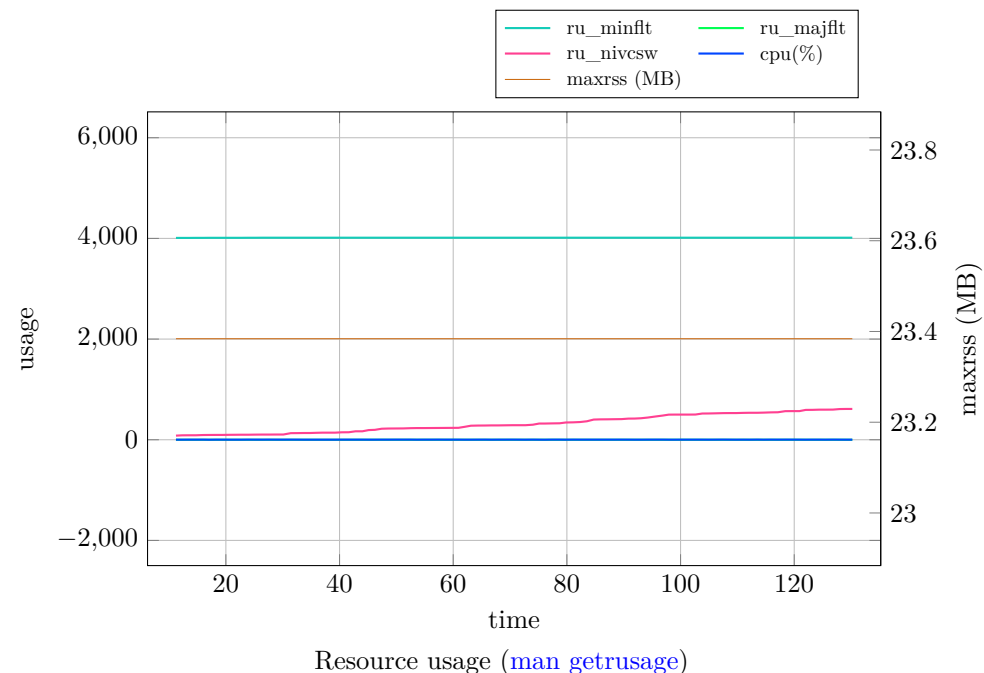
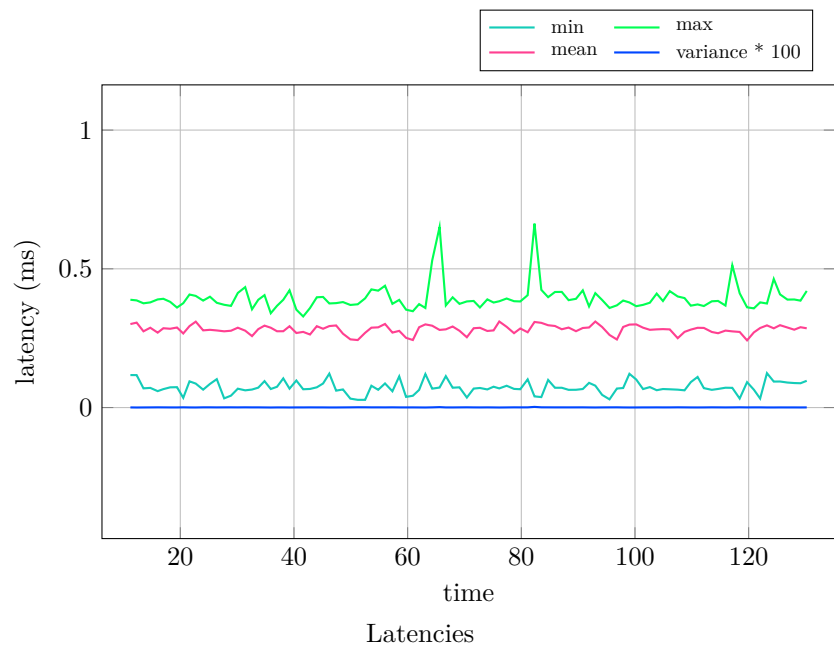


Performance

Logfile name	log_test_topic_28-11-2020_11-00-01
Experiment id	4c1a8bc1-7fd7-4665-97c5-b41e585fdbd5
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.189
received	47.5941
sent	9.5248
lost	0.0
relative_loss	0.0
data_received	8406.3762
latency_min (ms)	0.0731
latency_max (ms)	0.3939
latency_mean (ms)	0.2815
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.7286
pub_loop_res_max (ms)	99.8936
pub_loop_res_mean (ms)	99.8077
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	2.1766

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0