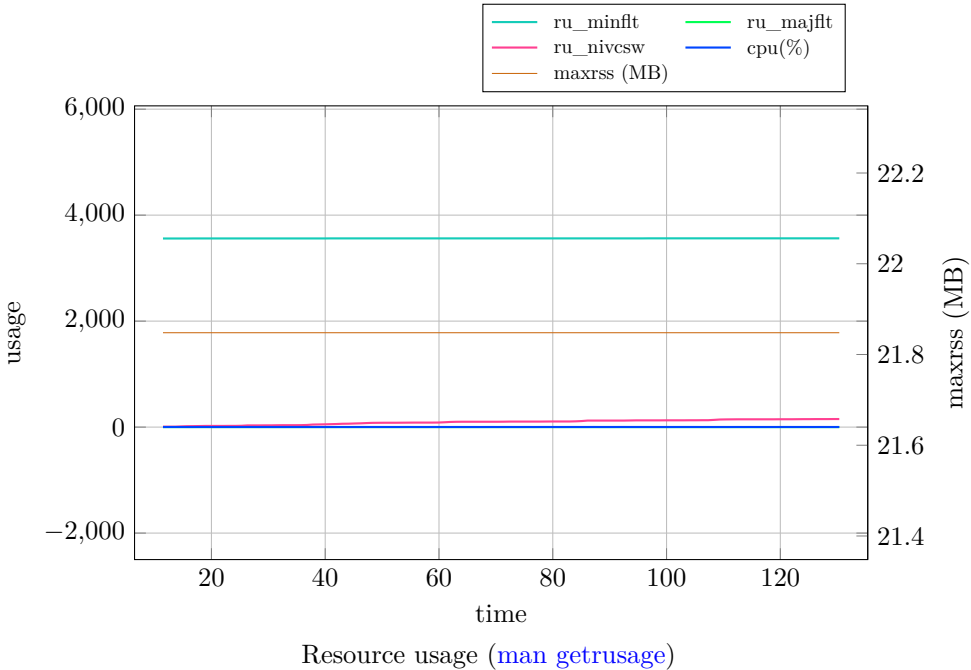
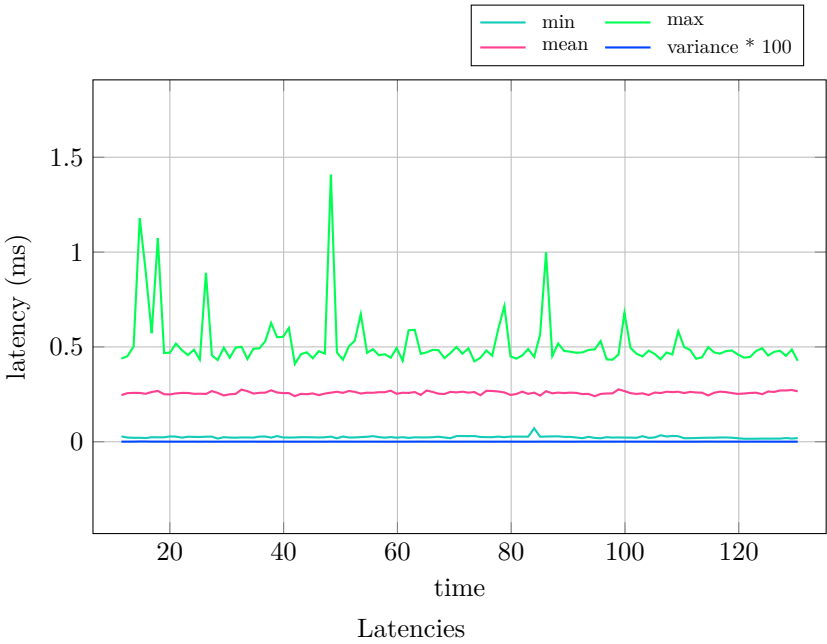


# Performance

Logfile name	log_test_topic_29-11-2020_13-31-28
Experiment id	208c7ca8-d268-4b64-91f2-65a31f061f48
Communication mean	ROS2



## test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

## average results

Experiment Status	success
T_loop	1.0518
received	494.9298
sent	49.4912
lost	0.0
relative_loss	0.0
data_received	39997.7544
latency_min (ms)	0.0239
latency_max (ms)	0.5161
latency_mean (ms)	0.2579
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.2779
pub_loop_res_max (ms)	19.8775
pub_loop_res_mean (ms)	19.4495
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.8454

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0