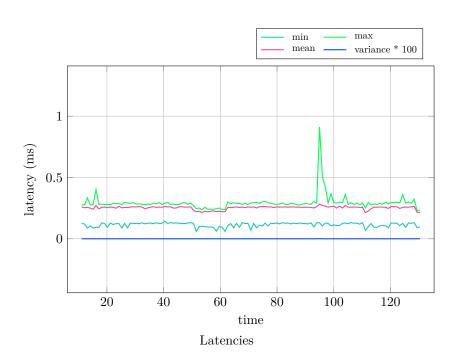
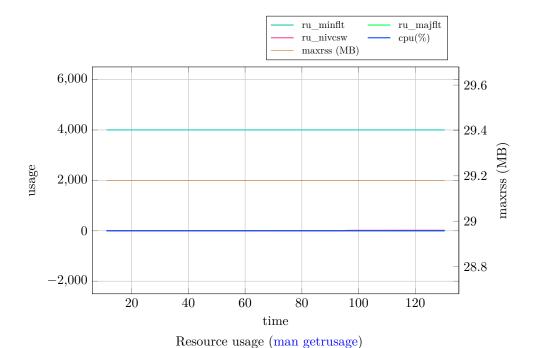
Performance

 Logfile name
 log_test_topic_28-11-2020_23-39-29

 Experiment id
 99faef00-79c1-4b8b-824d-416e83f217dc

 Communication mean
 ROS2





test setup	average results	environment
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Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

E Ct.t	
Experiment Status	success
T_loop	1.0105
received	49.5294
sent	49.5294
lost	0.0
relative_loss	0.0
data_received	41999.2689
latency_min (ms)	0.1146
latency_max (ms)	0.2938
latency_mean (ms)	0.2533
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.4276
pub_loop_res_max (ms)	19.8966
pub_loop_res_mean (ms)	19.5718
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.2396

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP ALL
QOS Reliability	BEST EFFORT
QOS Sync. pub/sub	_ 0
RMW Implementation	rmw fastrtps cpp
Roundtrip Mode	NONE
With security	0
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