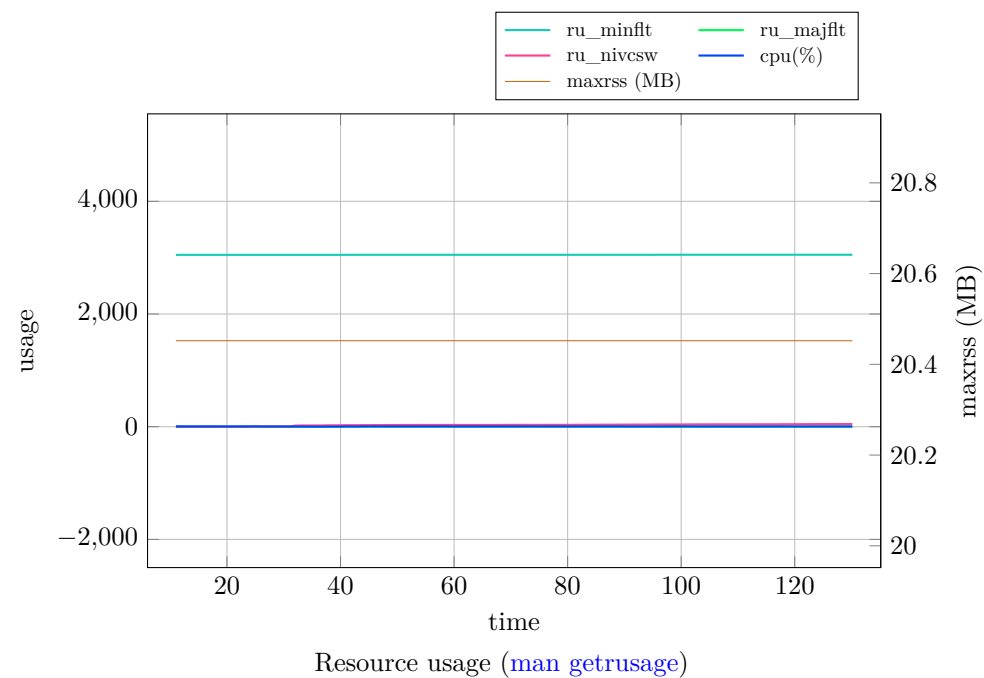
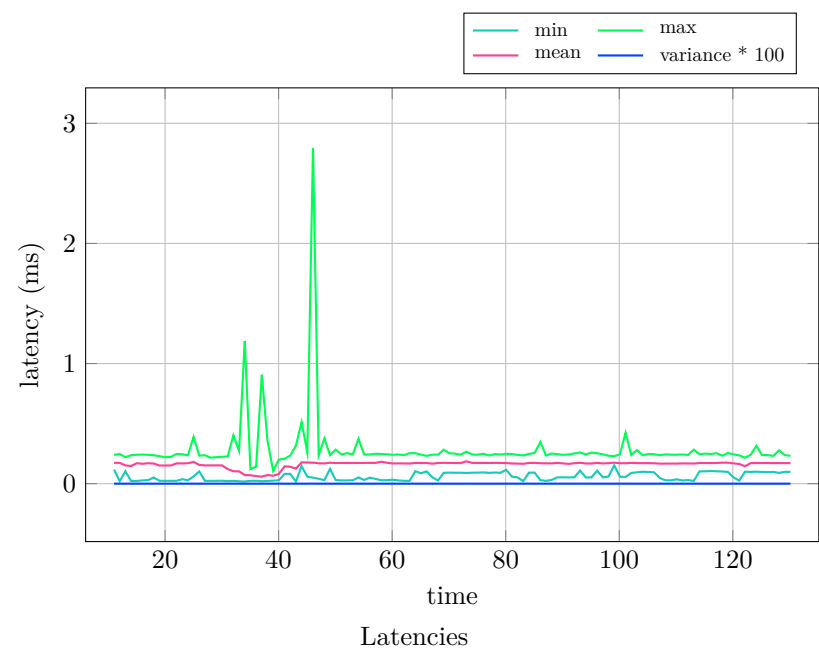


Performance

Logfile name	log_test_topic_27-11-2020_14-48-38
Experiment id	fcf34479-f922-4ef7-9c9b-306e3b4c781d
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	3
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0009
received	2998.55
sent	999.475
lost	0.0
relative_loss	0.0
data_received	2519997.225
latency_min (ms)	0.0599
latency_max (ms)	0.2862
latency_mean (ms)	0.1611
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7474
pub_loop_res_max (ms)	0.8984
pub_loop_res_mean (ms)	0.8192
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	4.9055

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0