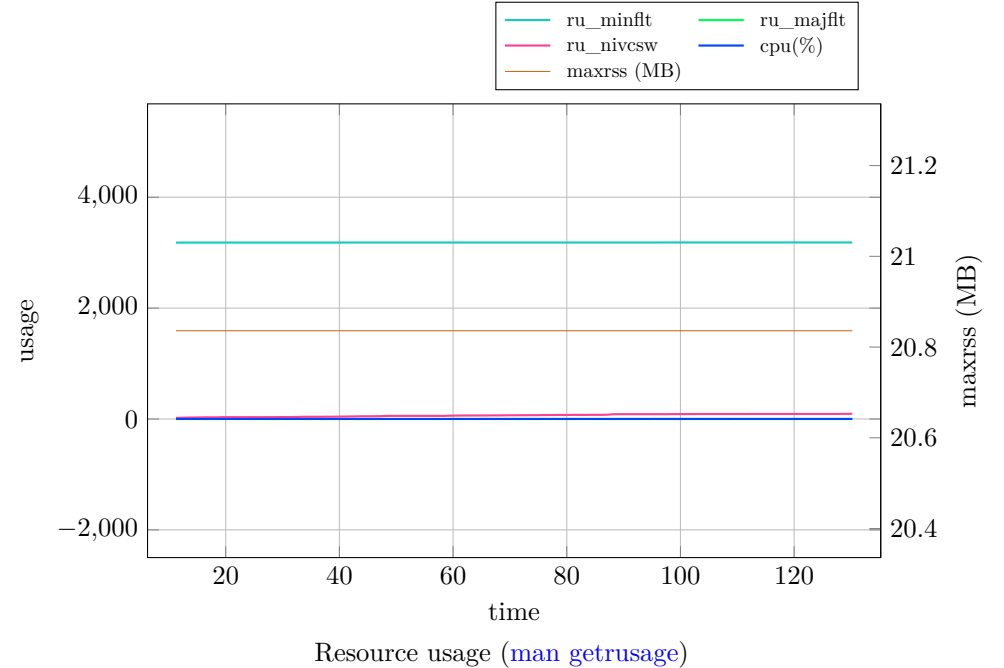
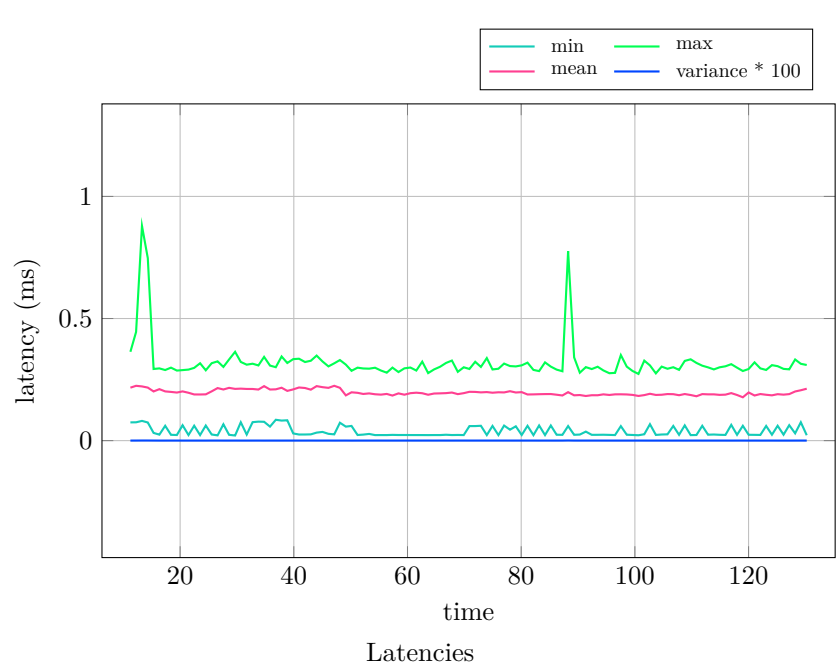


Performance

Logfile name	log_test_topic_01-12-2020_09-56-52
Experiment id	87ecddf3-c9b8-4580-9c92-d0b0cbbf1427
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0254
received	247.4274
sent	49.4701
lost	0.0
relative_loss	0.0
data_received	19999.3248
latency_min (ms)	0.0393
latency_max (ms)	0.3197
latency_mean (ms)	0.1972
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.3738
pub_loop_res_max (ms)	19.8626
pub_loop_res_mean (ms)	19.4747
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.7018

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0