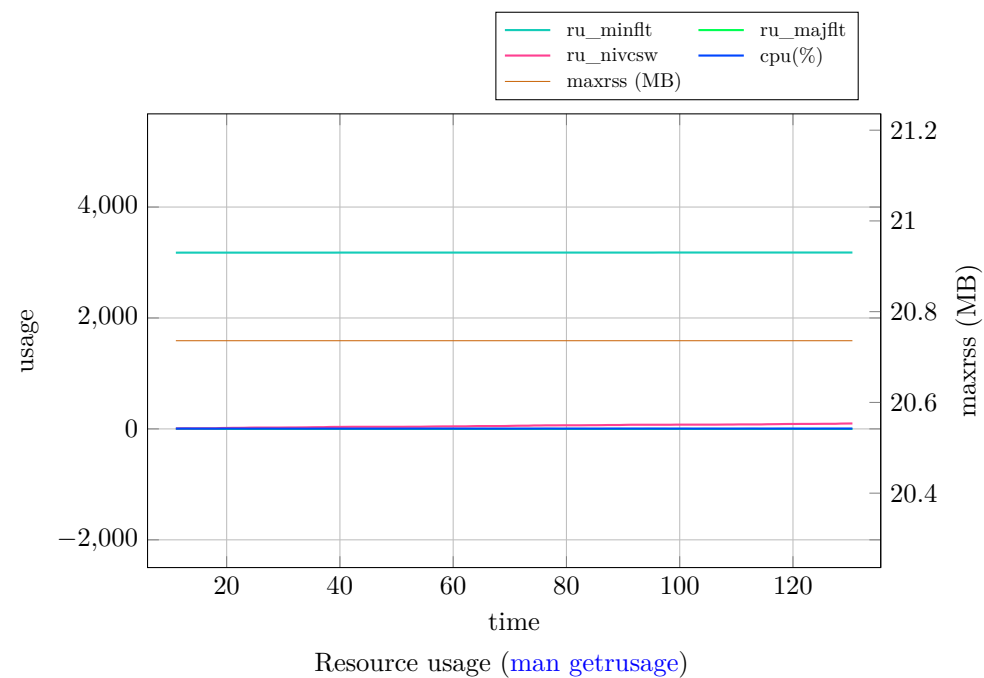
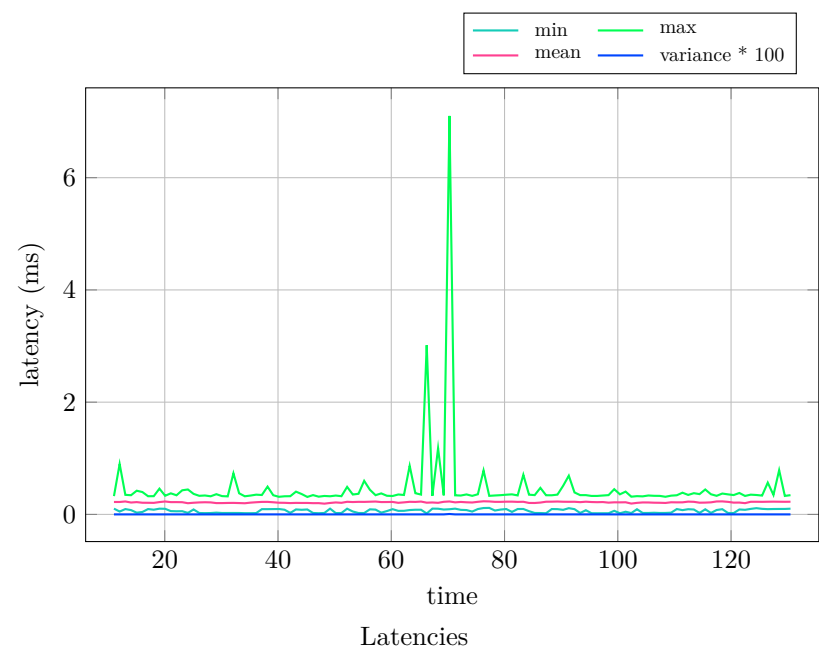


Performance

Logfile name	log_test_topic_29-11-2020_19-32-29
Experiment id	f9659ed3-88b2-498b-aa28-c04d09e3b739
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	500
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0036
received	2497.575
sent	499.5
lost	0.0
relative_loss	0.0
data_received	199997.5083
latency_min (ms)	0.0635
latency_max (ms)	0.4698
latency_mean (ms)	0.2161
latency_variance (ms)	0.0
pub_loop_res_min (ms)	1.565
pub_loop_res_max (ms)	1.8843
pub_loop_res_mean (ms)	1.719
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	5.5055

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0