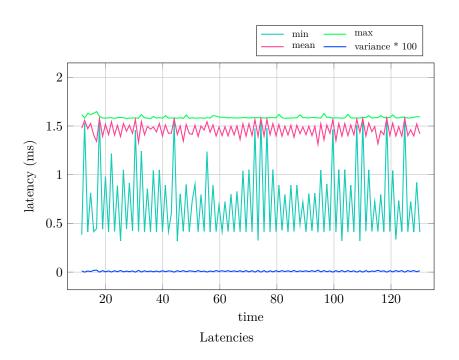
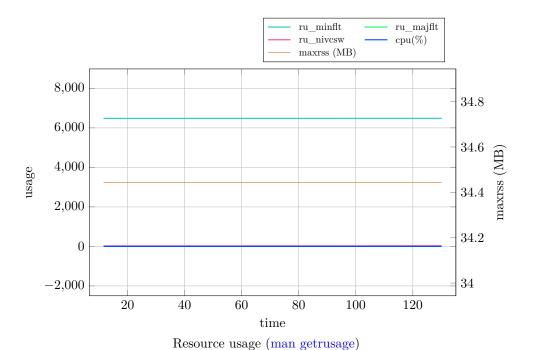
Performance

Logfile name log_test_topic_12-12-2020_10-46-14
Experiment id a27a0c78-aaea-40bb-8c14-4d5d8ddde632
Communication mean ROS2





test setup	average results	environment

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status success T_loop 1.0489 received 9.4912 sent 9.4825 lost 0.0 relative_loss 0.0 data_received 21082567.5175 latency_min (ms) 0.722 latency max (ms) 1.5895
received 9.4912 sent 9.4825 lost 0.0 relative_loss 0.0 data_received 21082567.5175 latency_min (ms) 0.722
sent 9.4825 lost 0.0 relative_loss 0.0 data_received 21082567.5175 latency_min (ms) 0.722
lost 0.0 relative_loss 0.0 data_received 21082567.5175 latency_min (ms) 0.722
relative_loss 0.0 data_received 21082567.5175 latency_min (ms) 0.722
data_received 21082567.5175 latency_min (ms) 0.722
latency_min (ms) 0.722
latency may (me) 1 5805
latelicy_max (ms)
latency mean (ms) 1.4613
latency_variance (ms) 0.0001
pub_loop_res_min (ms) 98.8261
pub_loop_res_max (ms) 99.4314
pub_loop_res_mean (ms) 98.9317
pub_loop_res_variance (ms) 0.0
sub_loop_res_min (ms) 0.0
sub_loop_res_max (ms) 0.0
sub loop res mean (ms) 0.0
sub loop res variance (ms) 0.0
cpu_usage (%) 0.503

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	PointCloud2m
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0
-	