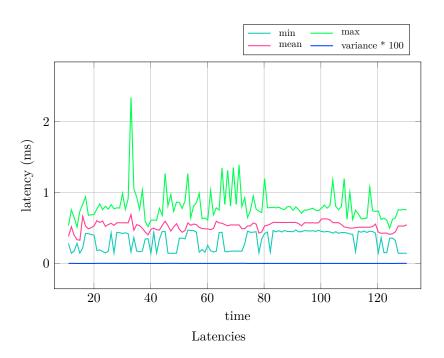
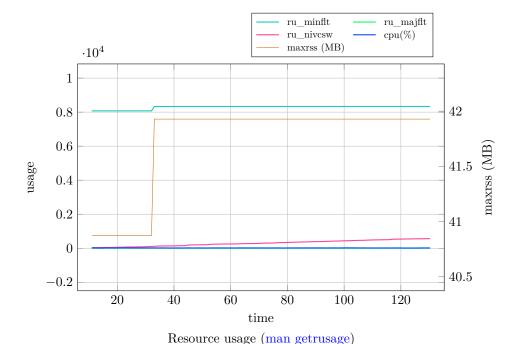
Performance

 Logfile name
 log_test_topic_30-11-2020_07-50-10

 Experiment id
 ddc43f7c-83b2-453b-86f1-8bf175c961ac

 Communication mean
 ROS2





test setup

Performance Test Version 80ff298
Publishing rate 1000
Topic name test_topic
Number of publishers 1
Number of subscribers 5
Maximum runtime (sec) 130
DDS domain id 0
Single participant -

average results

Experiment Status success T_loop 1.0021 received 4997.5999.4667 sent lost 0.0 0.0 relative loss data_received 5245181725.1333latency min (ms) 0.3276latency_max (ms) 0.8136 latency_mean (ms) 0.5264latency variance (ms) 0.0 pub_loop_res_min (ms) 0.5599pub loop res max (ms) 0.7642pub loop res mean (ms) 0.6752pub_loop_res_variance (ms) 0.0 sub_loop_res_min (ms) 0.0 sub loop res max (ms) 0.0 sub_loop_res_mean (ms) 0.0 sub loop res variance (ms) 0.0 18.128 cpu_usage (%)

environment

Ignore seconds from beginning 10 Memory check enabled 0 Msg name PointCloud1m QOS Durability VOLATILE QOS History depth 1000 QOS History kind KEEP ALL QOS Reliability BEST_EFFORT QOS Sync. pub/sub RMW Implementation $rmw_cyclonedds_cpp$ Roundtrip Mode NONE With security