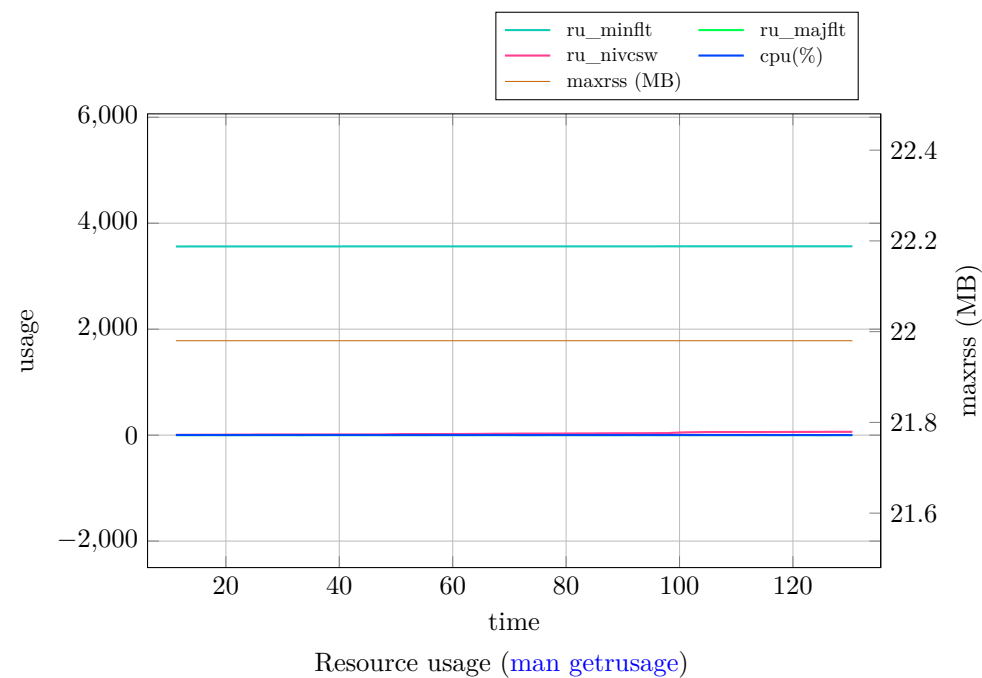
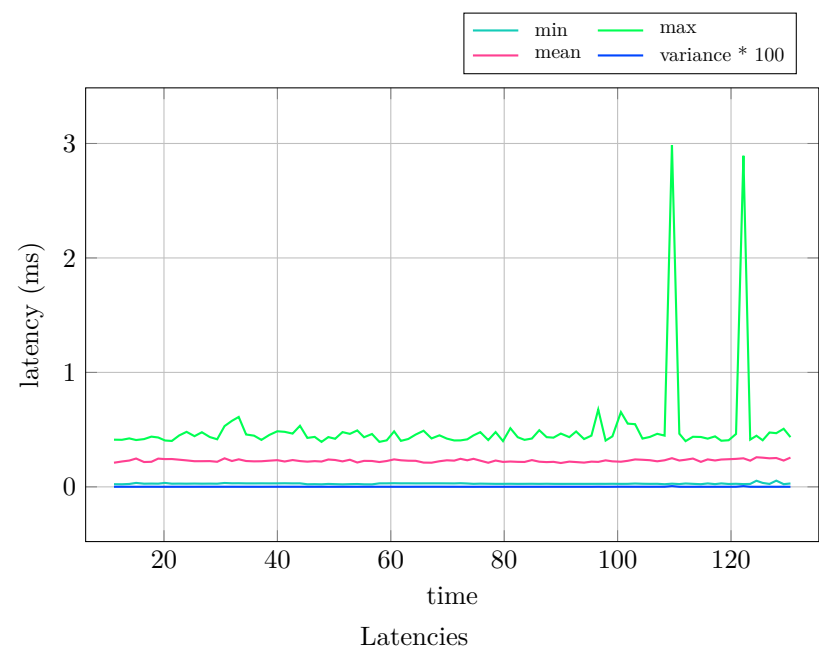


Performance

Logfile name	log_test_topic_30-11-2020_22-19-35
Experiment id	4a82cb6d-191e-409d-bbce-2437f7d76dd1
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.2828
received	95.0957
sent	9.5
lost	0.0
relative_loss	0.0
data_received	16805.8511
latency_min (ms)	0.0282
latency_max (ms)	0.505
latency_mean (ms)	0.2297
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.386
pub_loop_res_max (ms)	99.8779
pub_loop_res_mean (ms)	99.5628
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	2.0677

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0