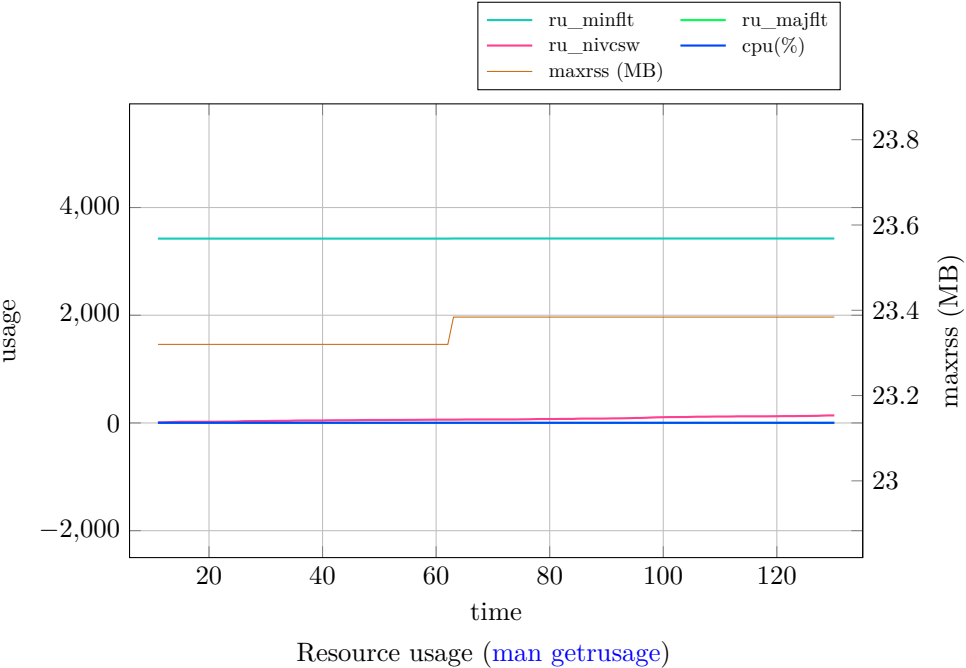
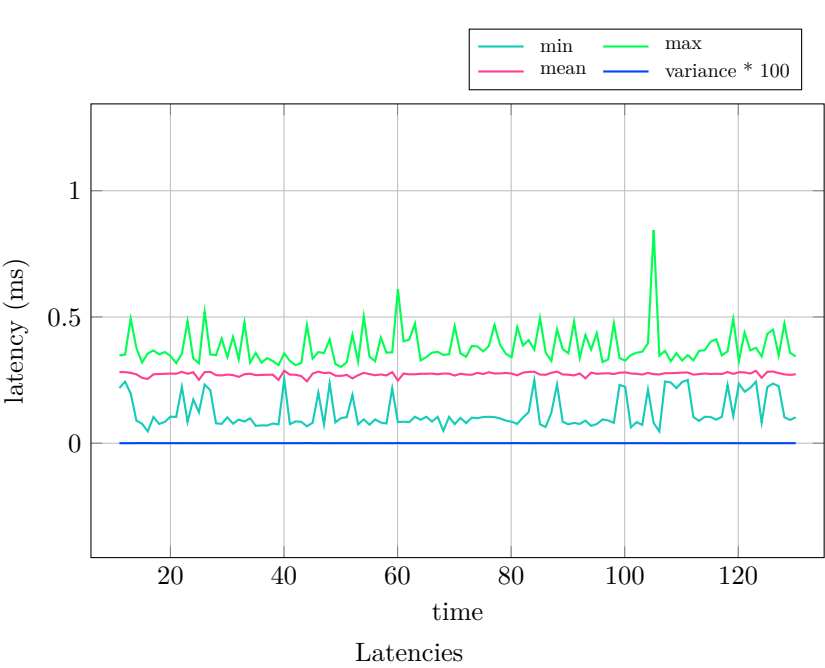


Performance

Logfile name	log_test_topic_30-11-2020_03-26-49
Experiment id	11dc11cb-8267-4e4c-bf14-731ec9227429
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0007
received	999.4583
sent	999.475
lost	0.0
relative_loss	0.0
data_received	61455372.9667
latency_min (ms)	0.1218
latency_max (ms)	0.3804
latency_mean (ms)	0.2737
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7251
pub_loop_res_max (ms)	0.9145
pub_loop_res_mean (ms)	0.8103
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	3.3981

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Array60k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0