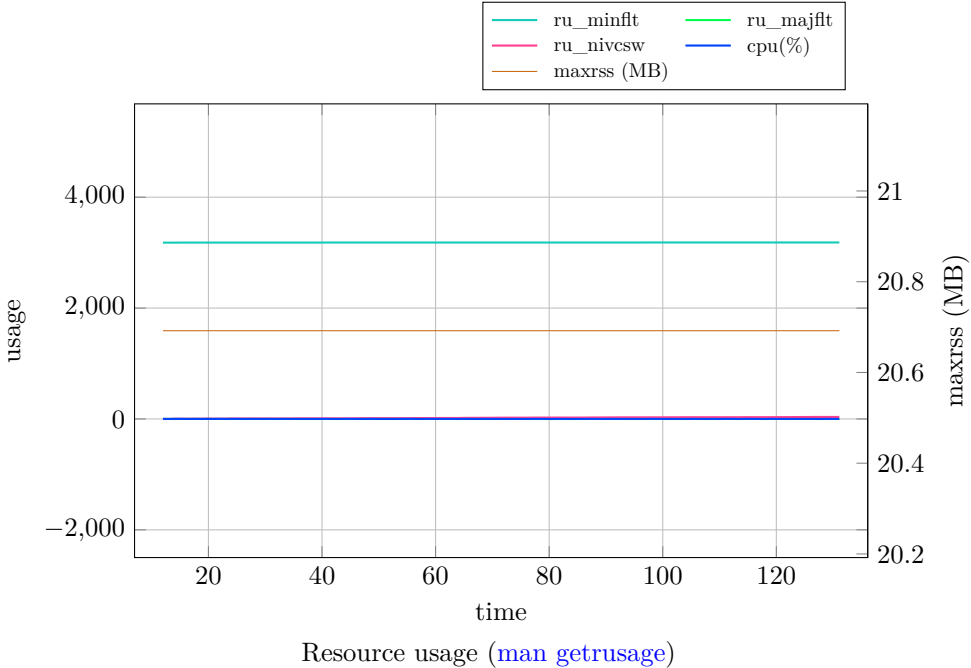
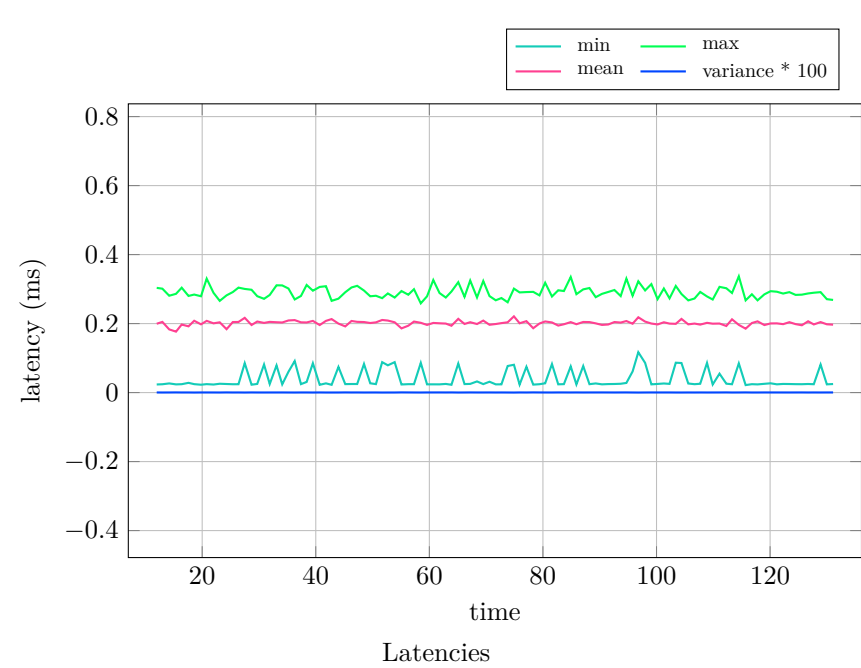


# Performance

Logfile name	log_test_topic_28-11-2020_11-43-38
Experiment id	b134b09a-56fc-48d1-8ba5-04bd142cf6a1
Communication mean	ROS2



test setup		average results		environment	
Performance Test Version	80ff298	Experiment Status	success	Ignore seconds from beginning	10
Publishing rate	10	T_loop	1.1035	Memory check enabled	0
Topic name	test_topic	received	47.5046	Msg name	NavSatFix
Number of publishers	1	sent	9.4679	QOS Durability	VOLATILE
Number of subscribers	5	lost	0.0	QOS History depth	1000
Maximum runtime (sec)	130	relative_loss	0.0	QOS History kind	KEEP_ALL
DDS domain id	0	data_received	8408.4587	QOS Reliability	BEST_EFFORT
Single participant	-	latency_min (ms)	0.0394	QOS Sync. pub/sub	0
		latency_max (ms)	0.2908	RMW Implementation	rmw_cyclonedds_cpp
		latency_mean (ms)	0.2015	Roundtrip Mode	NONE
		latency_variance (ms)	0.0	With security	0
		pub_loop_res_min (ms)	99.4146		
		pub_loop_res_max (ms)	99.8184		
		pub_loop_res_mean (ms)	99.5071		
		pub_loop_res_variance (ms)	0.0		
		sub_loop_res_min (ms)	0.0		
		sub_loop_res_max (ms)	0.0		
		sub_loop_res_mean (ms)	0.0		
		sub_loop_res_variance (ms)	0.0		
		cpu_usage (%)	0.8469		