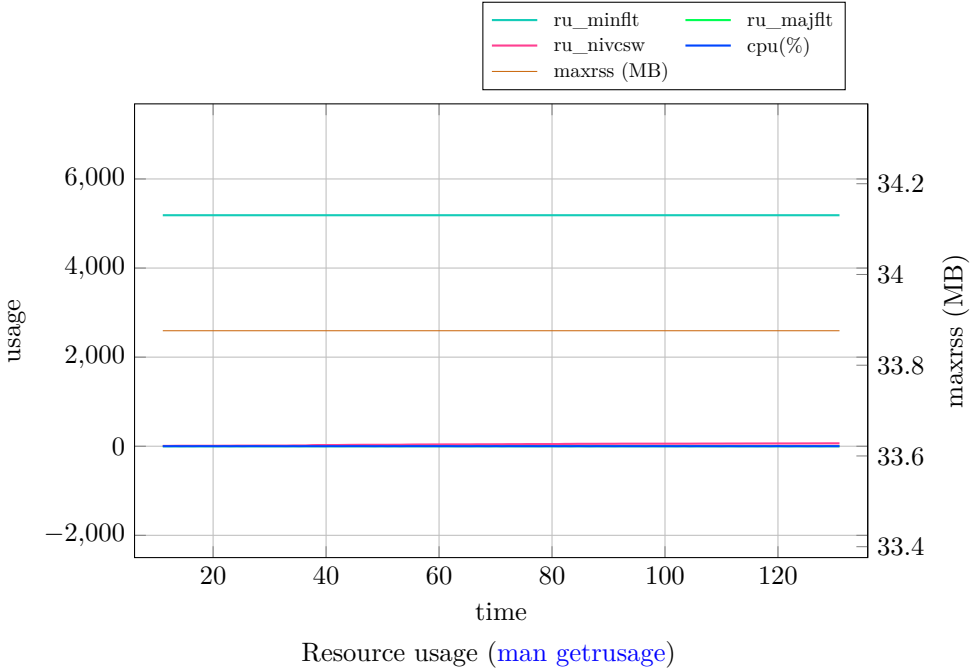
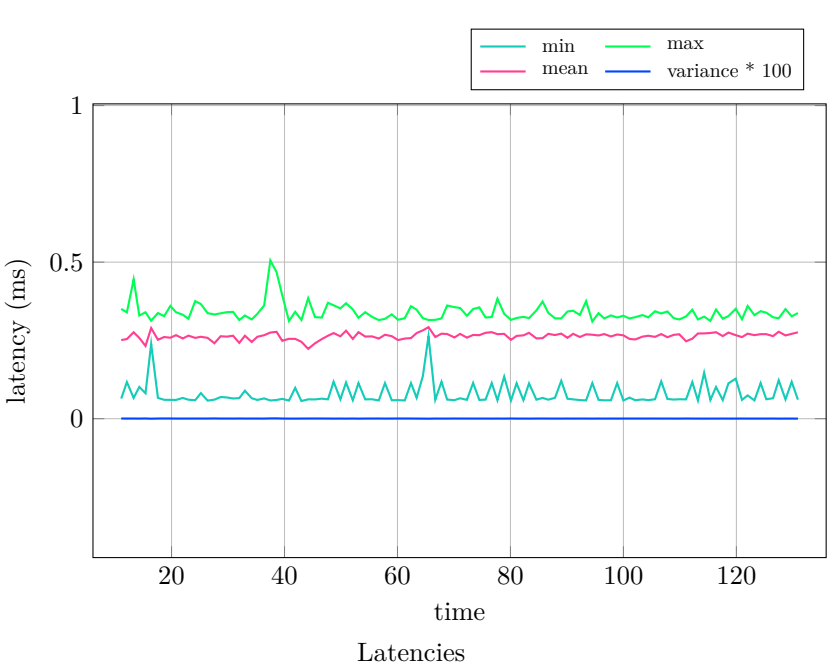


# Performance

Logfile name	log_test_topic_30-11-2020_21-34-19
Experiment id	46fe2e69-0ba6-495c-afa6-a9716fe81333
Communication mean	ROS2



## test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

## average results

Experiment Status	success
T_loop	1.109
received	47.5963
sent	9.4679
lost	0.0
relative_loss	0.0
data_received	8409.6055
latency_min (ms)	0.0794
latency_max (ms)	0.3398
latency_mean (ms)	0.2637
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.489
pub_loop_res_max (ms)	99.8218
pub_loop_res_mean (ms)	99.5631
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.8698

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0