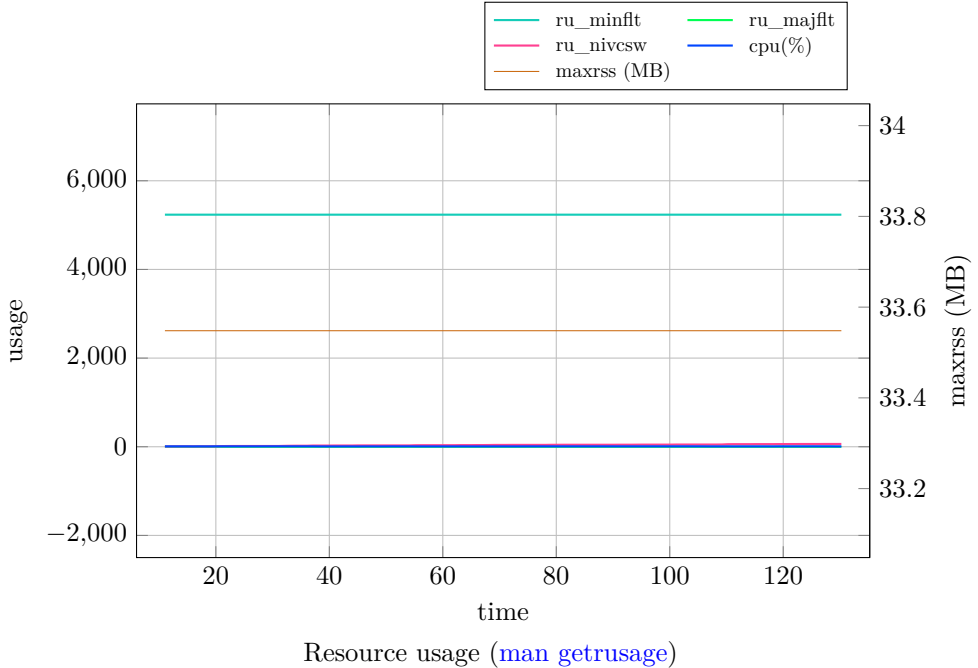
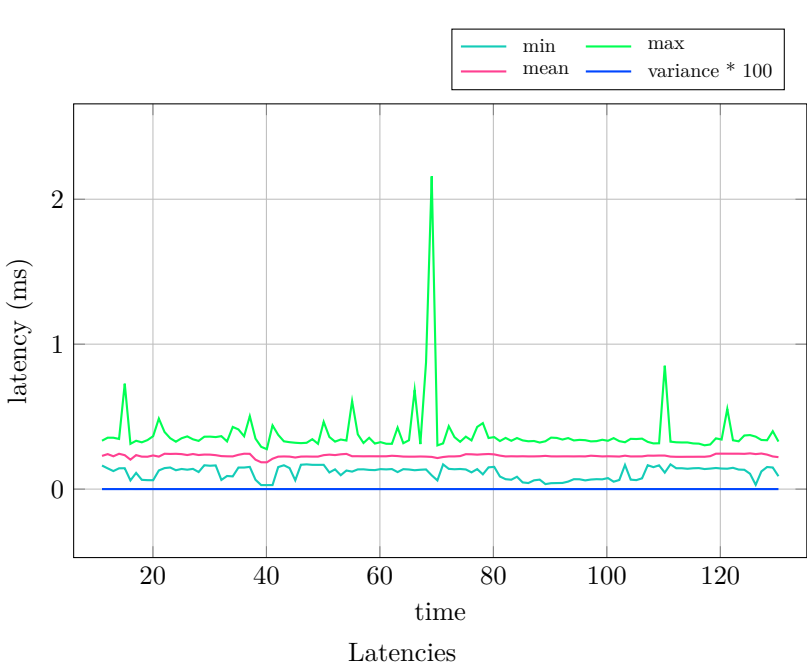


# Performance

Logfile name	log_test_topic_30-11-2020_09-02-53
Experiment id	fd08f06c-f650-49c2-a82a-ab6110260bf6
Communication mean	ROS2



## test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

## average results

Experiment Status	success
T_loop	1.0016
received	4997.5583
sent	999.475
lost	0.0
relative_loss	0.0
data_received	839997.2833
latency_min (ms)	0.1138
latency_max (ms)	0.3807
latency_mean (ms)	0.2292
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.8095
pub_loop_res_max (ms)	0.9175
pub_loop_res_mean (ms)	0.8535
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	8.7127

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0