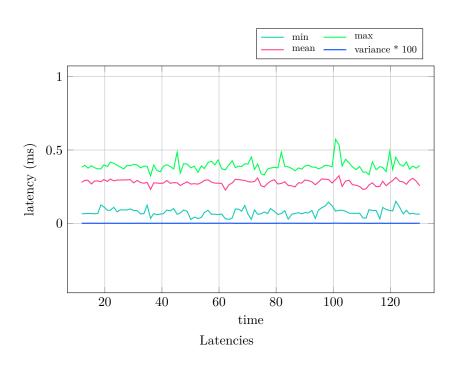
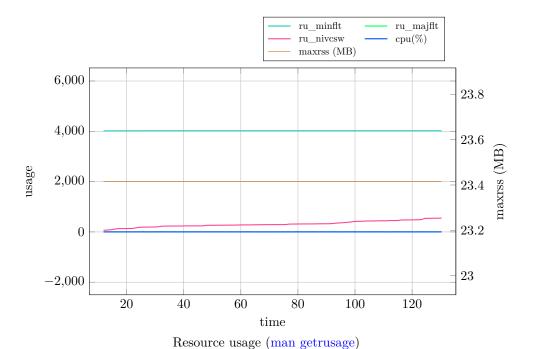
Performance

Logfile name log_test_topic_28-11-2020_10-39-13
Experiment id f52debe5-ec3e-4585-adab-2bea5c1faa77
Communication mean ROS2





test setup	average results	${f environment}$

Performance Test Version	80ff298
Publishing rate	10
Topic name	$test_topic$
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T loop	1.1724
received	47.6373
sent	9.5392
lost	0.0
relative loss	0.0
data received	1600.3431
latency min (ms)	0.0759
latency_max (ms)	0.3918
latency mean (ms)	0.2788
latency variance (ms)	0.0
pub loop res min (ms)	99.6822
pub loop res max (ms)	99.8991
pub loop res mean (ms)	99.7952
pub_loop_res_variance (ms)	0.0
sub loop res min (ms)	0.0
sub loop res max (ms)	0.0
sub loop res mean (ms)	0.0
sub loop res variance (ms)	0.0
cpu usage (%)	2.095
-F(, v,	2.000

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Struct16
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw ecal dynamic cpp
Roundtrip Mode	NONE
With security	0
-	