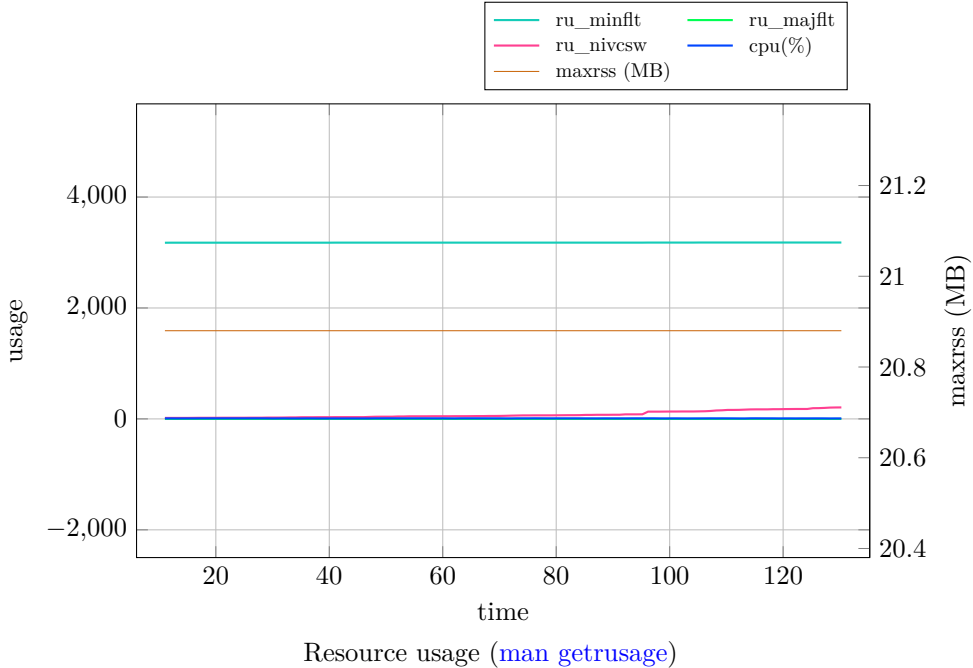
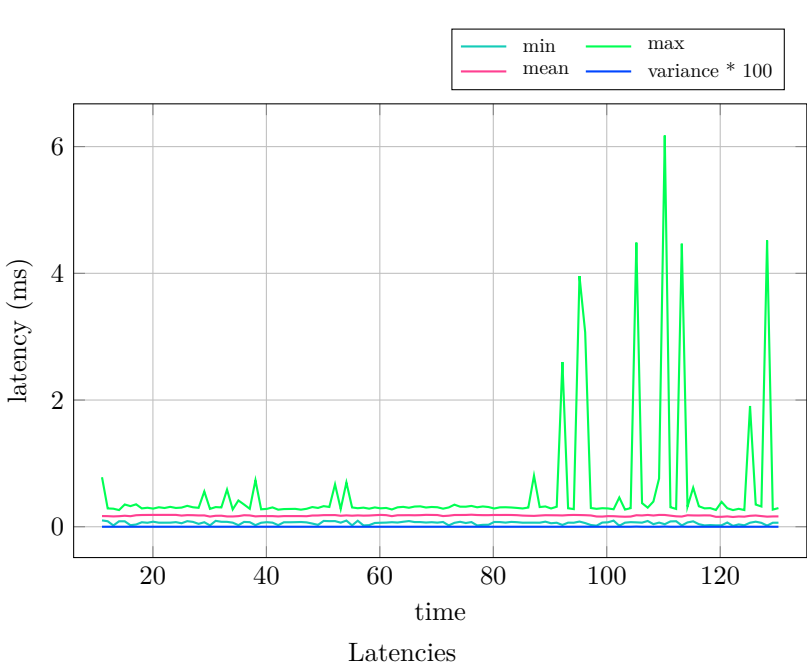


Performance

Logfile name	log_test_topic_30-11-2020_08-01-35
Experiment id	02ea8e1c-8449-42fe-b3c6-de426dc12651
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0017
received	4997.5
sent	999.4833
lost	0.0
relative_loss	0.0
data_received	399997.325
latency_min (ms)	0.0602
latency_max (ms)	0.5731
latency_mean (ms)	0.1756
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7297
pub_loop_res_max (ms)	0.8831
pub_loop_res_mean (ms)	0.808
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	9.467

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0