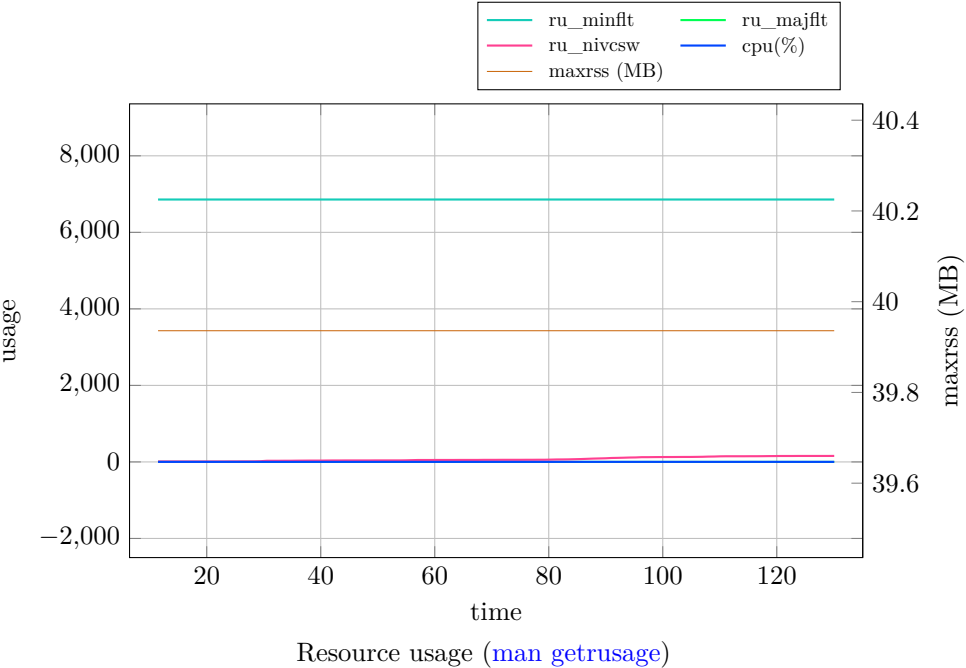
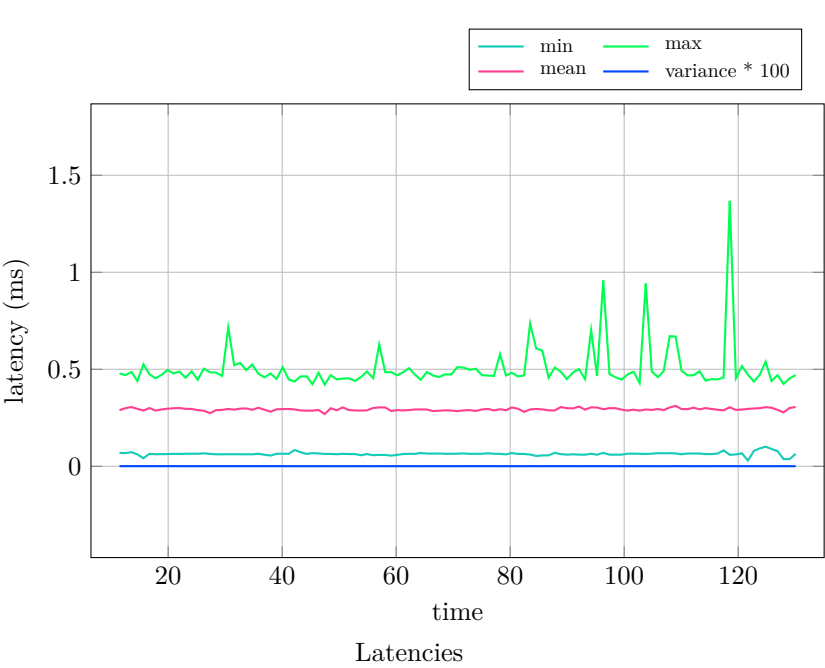


# Performance

Logfile name	log_test_topic_01-12-2020_12-38-03
Experiment id	f04a5c81-bdab-4990-8dbe-4b0414a4181b
Communication mean	ROS2



## test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

## average results

Experiment Status	success
T_loop	1.0588
received	494.8407
sent	49.4602
lost	0.0
relative_loss	0.0
data_received	39996.3097
latency_min (ms)	0.0639
latency_max (ms)	0.5035
latency_mean (ms)	0.2934
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.446
pub_loop_res_max (ms)	19.8974
pub_loop_res_mean (ms)	19.5688
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.6196

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0