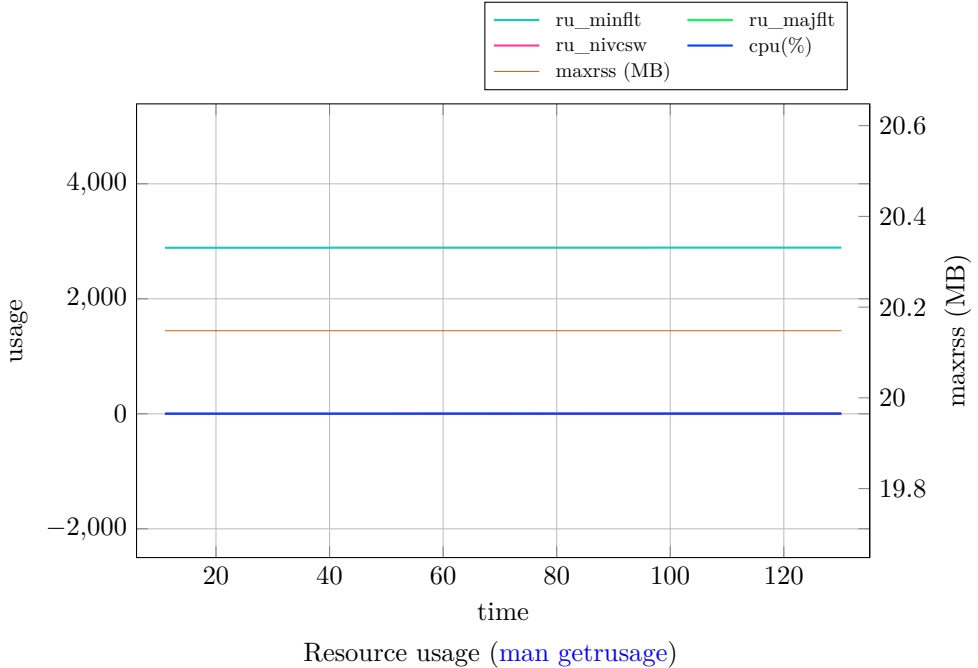
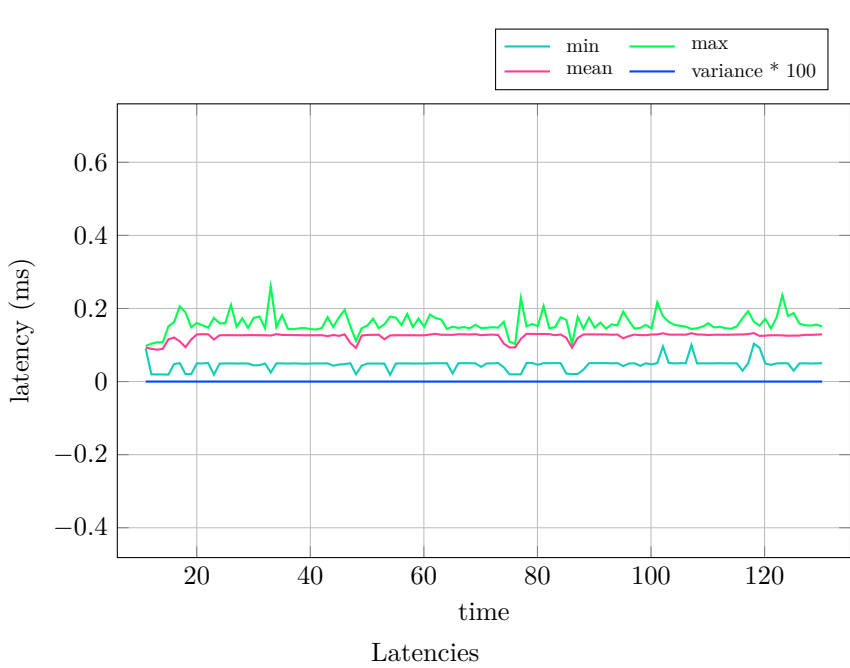


Performance

Logfile name	log_test_topic_01-12-2020_19-14-05
Experiment id	c07310e6-6487-4601-88f4-b34b26f41405
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0007
received	999.4667
sent	999.4667
lost	0.0
relative_loss	0.0
data_received	79999.275
latency_min (ms)	0.0465
latency_max (ms)	0.1587
latency_mean (ms)	0.1239
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.683
pub_loop_res_max (ms)	0.9105
pub_loop_res_mean (ms)	0.83
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.6379

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0