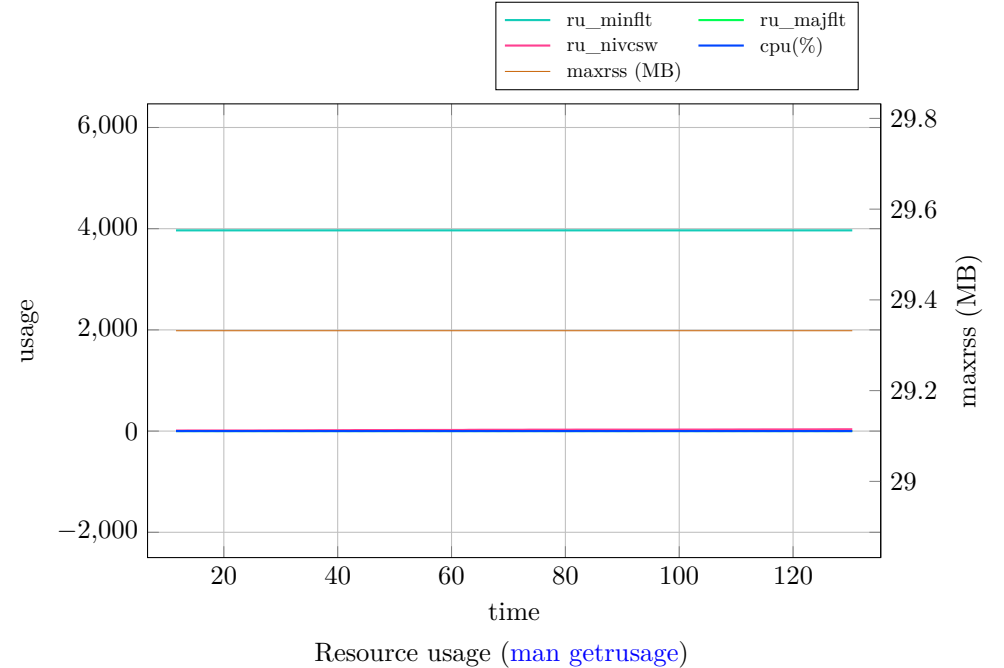
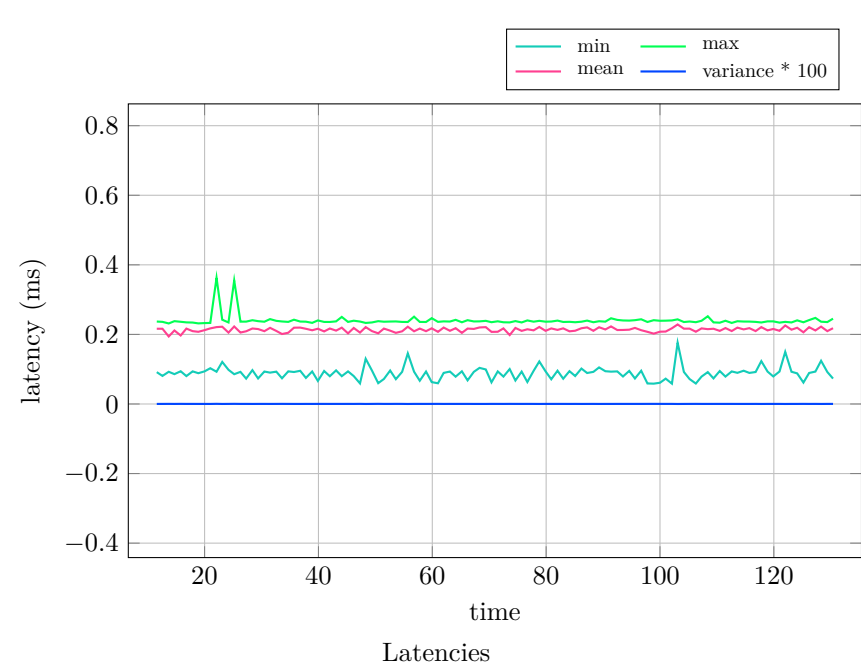


# Performance

Logfile name	log_test_topic_28-11-2020_10-12-59
Experiment id	5057dc1d-ef97-4e7d-b6f1-907b80d79396
Communication mean	ROS2



test setup		average results		environment	
Performance Test Version	80ff298	Experiment Status	success	Ignore seconds from beginning	10
Publishing rate	10	T_loop	1.0515	Memory check enabled	0
Topic name	test_topic	received	9.5088	Msg name	NavSatFix
Number of publishers	1	sent	9.5	QOS Durability	VOLATILE
Number of subscribers	1	lost	0.0	QOS History depth	1000
Maximum runtime (sec)	130	relative_loss	0.0	QOS History kind	KEEP_ALL
DDS domain id	0	data_received	1686.7456	QOS Reliability	BEST_EFFORT
Single participant	-	latency_min (ms)	0.0884	QOS Sync. pub/sub	0
		latency_max (ms)	0.24	RMW Implementation	rmw_fastrtps_cpp
		latency_mean (ms)	0.2135	Roundtrip Mode	NONE
		latency_variance (ms)	0.0	With security	0
		pub_loop_res_min (ms)	99.483		
		pub_loop_res_max (ms)	99.749		
		pub_loop_res_mean (ms)	99.5332		
		pub_loop_res_variance (ms)	0.0		
		sub_loop_res_min (ms)	0.0		
		sub_loop_res_max (ms)	0.0		
		sub_loop_res_mean (ms)	0.0		
		sub_loop_res_variance (ms)	0.0		
		cpu_usage (%)	0.4188		