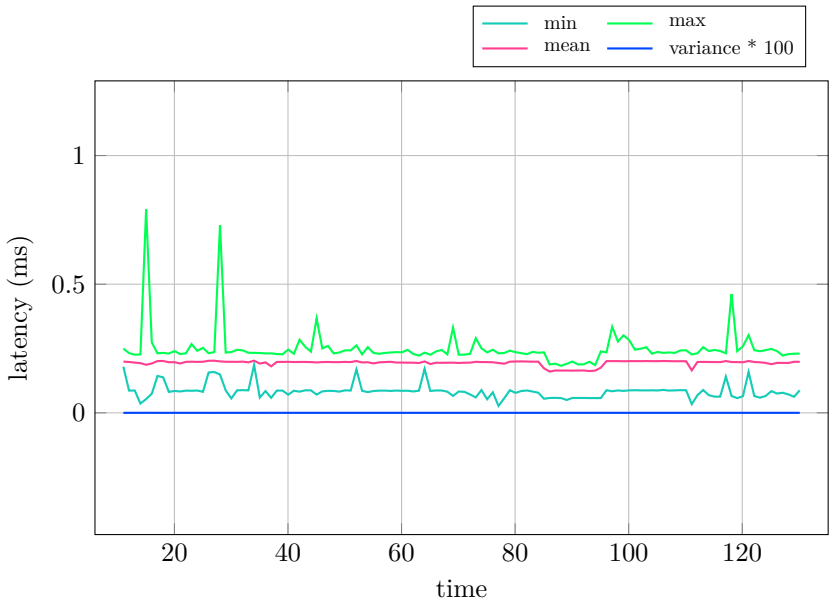
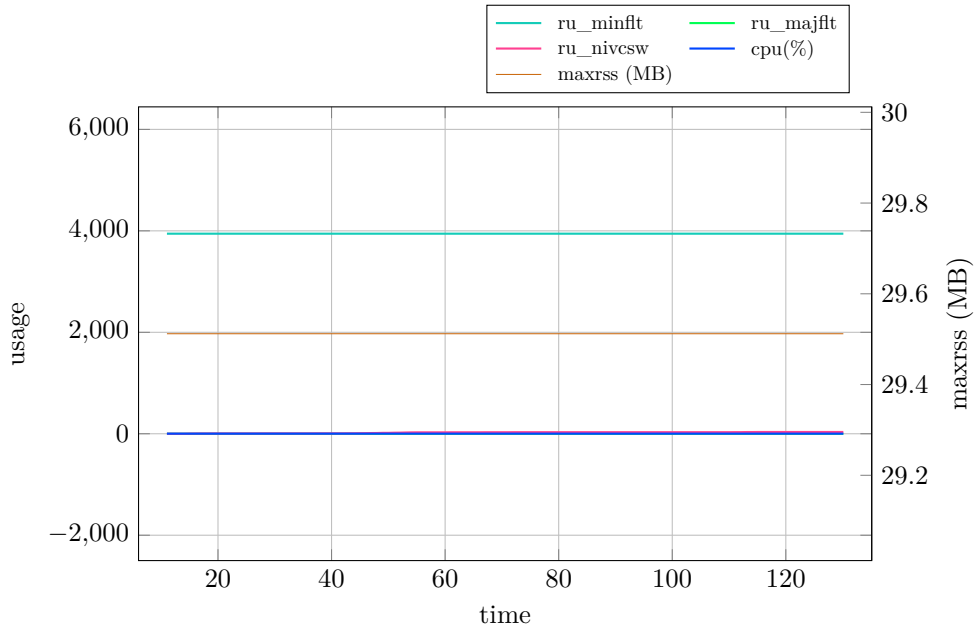
Performance

Logfile name	log_test_topic_01-12-2020_19-55-03
Experiment id	9075f43a-1ae1-4b28-b7ce-e7c76aaf80ff
Communication mean	ROS2



Latencies



Resource usage (man getrusage)

test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0007
received	999.5167
sent	999.5167
lost	0.0
relative_loss	0.0
data_received	167999.075
latency_min (ms)	0.0838
latency_max (ms)	0.25
latency_mean (ms)	0.1941
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7213
pub_loop_res_max (ms)	0.9128
pub_loop_res_mean (ms)	0.8429
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	2.2873

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0