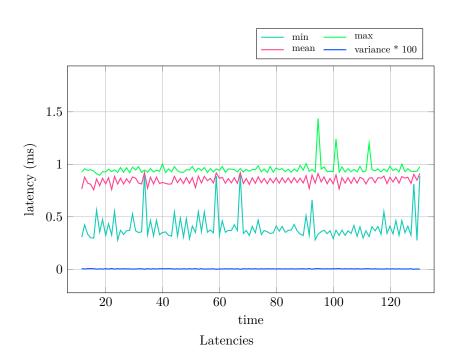
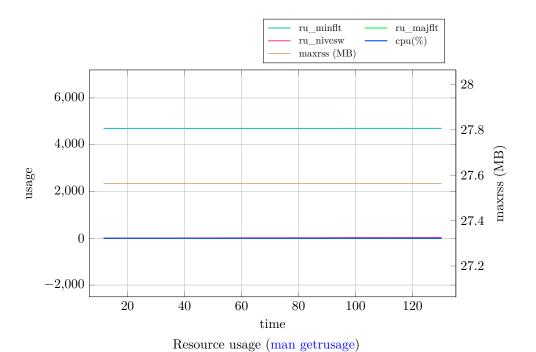
## Performance

 Logfile name
 log\_test\_topic\_28-11-2020\_09-20-31

 Experiment id
 5b870df9-f5b5-40e0-b52e-e156fd0790f2

 Communication mean
 ROS2





test setup	average results	environment
cost setup	avorago resamb	01111110111

Performance Test Version	80ff298
Publishing rate	10
Topic name	$test\_topic$
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T_loop	1.0498
received	9.5
sent	9.5
lost	0.0
relative_loss	0.0
data_received	10536966.114
latency_min (ms)	0.3997
latency_max (ms)	0.9548
latency_mean (ms)	0.8461
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.1204
pub_loop_res_max (ms)	99.5514
pub_loop_res_mean (ms)	99.2215
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage $(\%)$	0.4587

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	PointCloud1m
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0