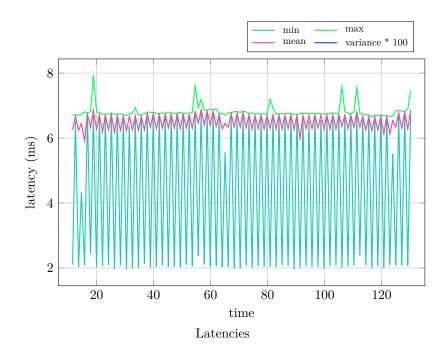
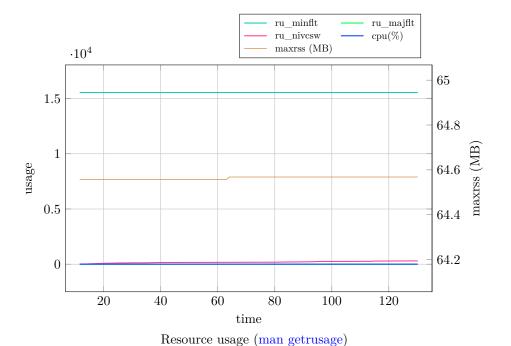
Performance

 Logfile name
 log_test_topic_28-11-2020_08-41-38

 Experiment id
 07baa537-d558-4bc1-b912-fb44596a1dd3

 Communication mean
 ROS2





Performance Test Version	80ff298
Publishing rate	10
Topic name	$test_topic$
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

test setup

Experiment Status	success
T loop	1.0498
received	9.5
sent	9.5
lost	0.0
relative loss	0.0
data received	42110340.9474
latency min (ms)	4.3225
latency max (ms)	6.8114
latency mean (ms)	6.4948
latency variance (ms)	0.0009
pub loop res min (ms)	96.5376
pub_loop_res_max (ms)	97.8436
pub loop res mean (ms)	96.73
pub_loop_res_variance (ms)	0.0002
sub_loop_res_min (ms)	0.0
sub loop res max (ms)	0.0
sub loop res mean (ms)	0.0
sub loop res variance (ms)	0.0
cpu_usage (%)	1.4833

average results

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	PointCloud4m
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0

environment