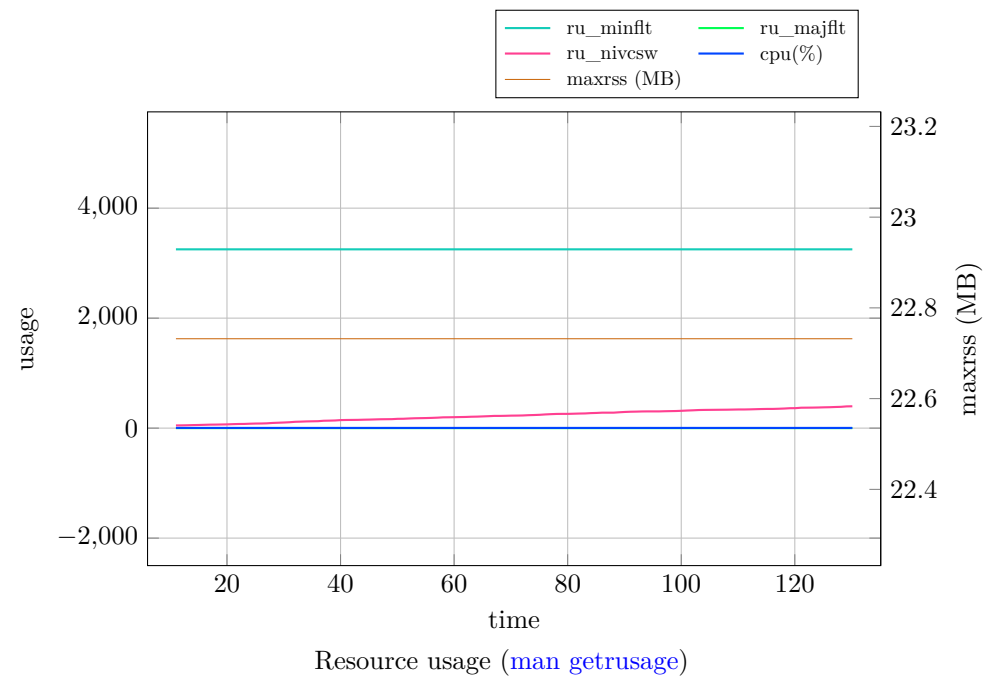
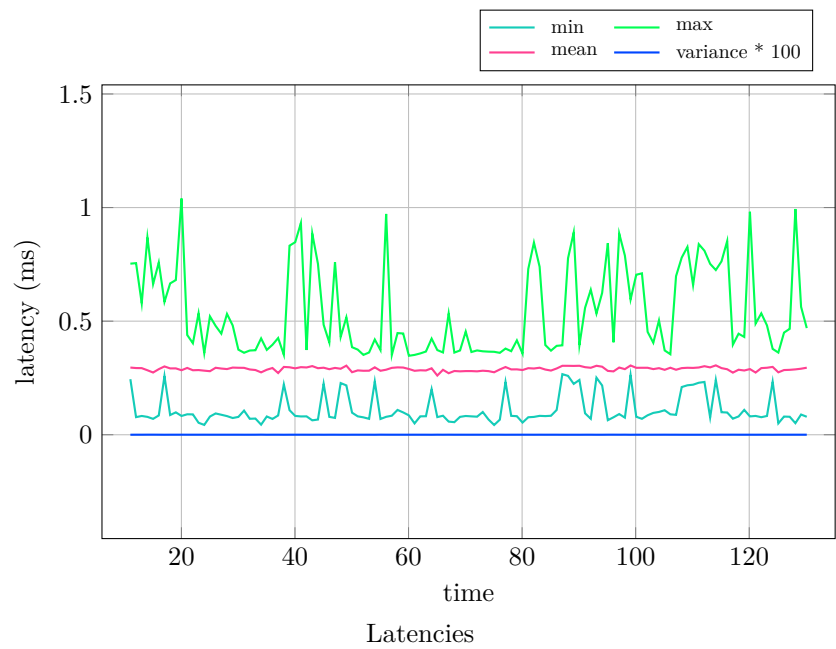


# Performance

Logfile name	log_test_topic_30-11-2020_03-58-56
Experiment id	70e55f9a-8a16-4511-8a06-7565c3d155da
Communication mean	ROS2



## test setup

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

## average results

Experiment Status	success
T_loop	1.0008
received	999.5167
sent	999.525
lost	0.0
relative_loss	0.0
data_received	839994.8333
latency_min (ms)	0.1092
latency_max (ms)	0.543
latency_mean (ms)	0.2895
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7251
pub_loop_res_max (ms)	0.9099
pub_loop_res_mean (ms)	0.802
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	3.4374

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0