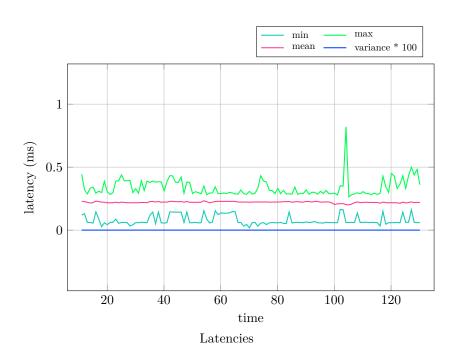
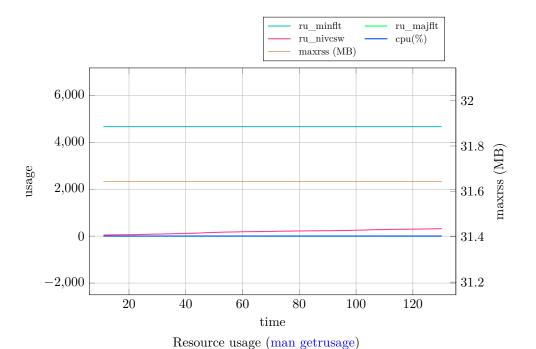
## Performance

 Logfile name
 log\_test\_topic\_27-11-2020\_15-45-14

 Experiment id
 404df0b5-dca0-4fc3-b9bd-e91ea0602719

 Communication mean
 ROS2





test setup	average results	environment

Performance Test Version	80ff298
Publishing rate	1000
Topic name	test_topic
Number of publishers	1
Number of subscribers	3
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

Experiment Status	success
T loop	1.001
received	2998.4667
sent	999.475
lost	0.0
relative loss	0.0
data received	2520002.4167
latency_min (ms)	0.0776
latency_max (ms)	0.3376
latency mean (ms)	0.2216
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7934
pub_loop_res_max (ms)	0.9221
pub_loop_res_mean (ms)	0.8427
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	4.9488

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	$rmw\_fastrtps\_cpp$
Roundtrip Mode	NONE
With security	0