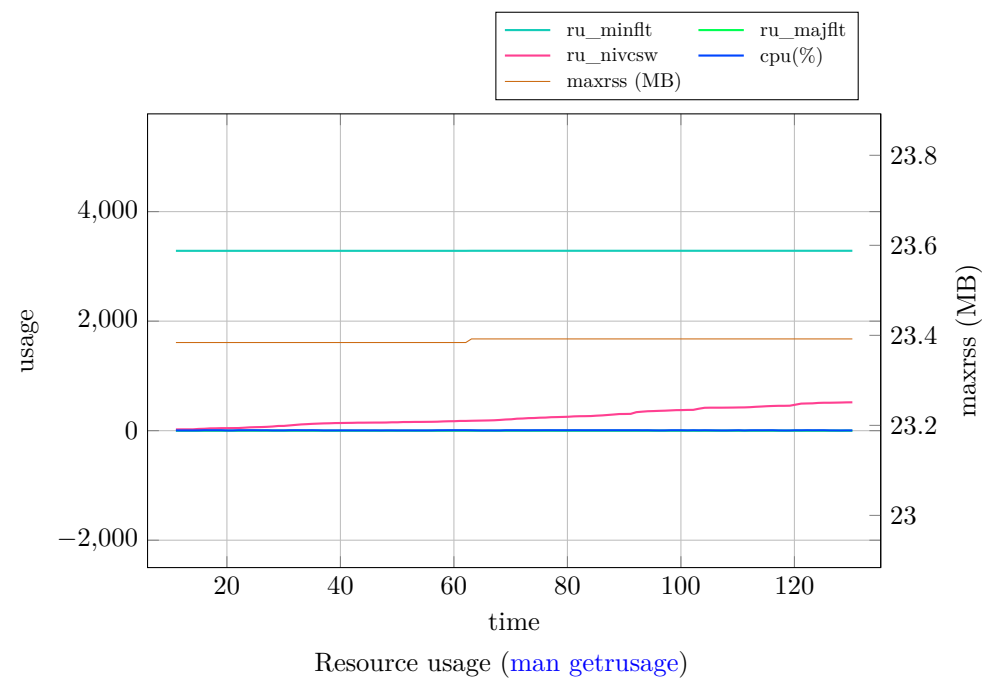
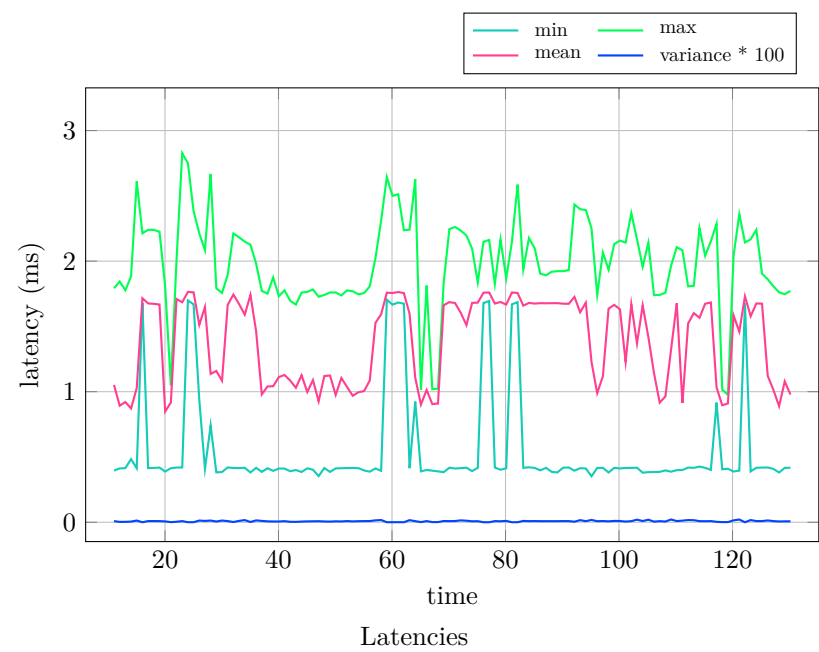


Performance

Logfile name	log_test_topic_29-11-2020_16-17-58
Experiment id	6a9a4f2e-a22f-465b-b821-7ee976909851
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	500
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0014
received	499.525
sent	499.525
lost	0.0
relative_loss	0.0
data_received	4231992.8833
latency_min (ms)	0.5489
latency_max (ms)	1.9912
latency_mean (ms)	1.3835
latency_variance (ms)	0.0001
pub_loop_res_min (ms)	0.949
pub_loop_res_max (ms)	1.7064
pub_loop_res_mean (ms)	1.2877
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	6.3812

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	Struct4k
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0