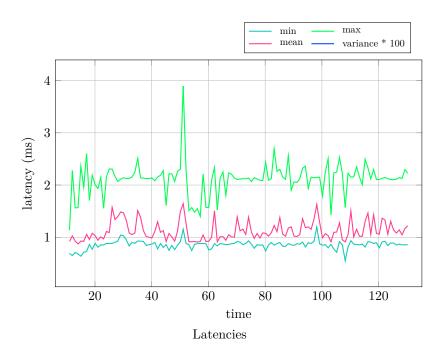
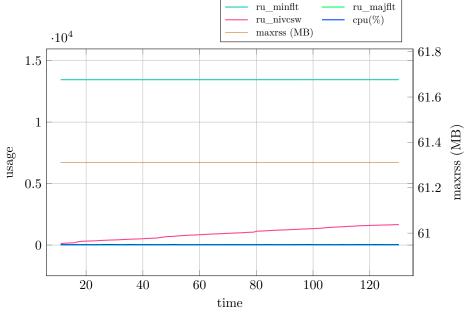
Performance

 Logfile name
 log_test_topic_01-12-2020_20-46-46

 Experiment id
 11383cb4-8cb6-4dc2-89be-4065618409ac

 Communication mean
 ROS2





Resource usage (man getrusage)

test setup

Performance Test Version 80ff298
Publishing rate 1000
Topic name test_topic
Number of publishers 1
Number of subscribers 5
Maximum runtime (sec) 130
DDS domain id 0
Single participant -

average results

Experiment Status success T_loop 1.0018 received 4997.5sent 999.5333 lost 0.025relative loss 0.0 10487922479.3417 data_received latency min (ms) 0.8566latency_max (ms) 2.1094latency_mean (ms) 1.1241 latency variance (ms) 0.0001 pub_loop_res_min (ms) -0.7633pub_loop_res_max (ms) 0.7144pub_loop_res_mean (ms) 0.4843pub_loop_res_variance (ms) 0.0002 sub_loop_res_min (ms) 0.0 sub loop res max (ms) 0.0 sub_loop_res_mean (ms) 0.0 sub loop res variance (ms) 0.0 cpu_usage (%) 36.1398

environment

| Ignore seconds from beginning | 10 |
|-------------------------------|--------------------|
| Memory check enabled | 0 |
| Msg name | PointCloud2m |
| QOS Durability | VOLATILE |
| QOS History depth | 1 |
| QOS History kind | KEEP LAST |
| QOS Reliability | BEST EFFORT |
| QOS Sync. pub/sub | _ 0 |
| RMW Implementation | rmw cyclonedds cpp |
| Roundtrip Mode | NONE |
| With security | 0 |
| | |