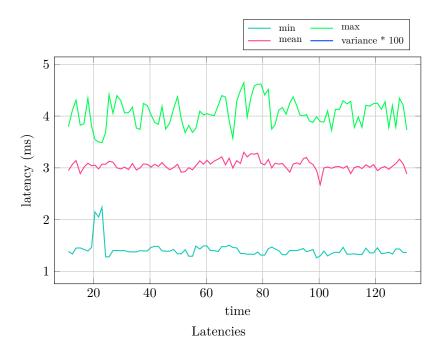
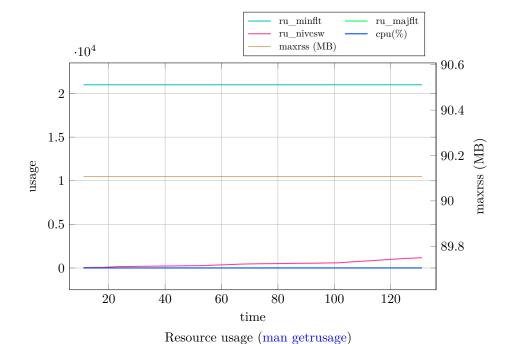
## Performance

Logfile name log\_test\_topic\_30-11-2020\_22-12-40
Experiment id 075ecadd-8cd3-44c8-bc49-14dbef42206a
Communication mean ROS2





test	setup

## Performance Test Version 80ff298 Publishing rate 10 Topic name test\_topic Number of publishers 1 Number of subscribers 10 Maximum runtime (sec) 130 DDS domain id 0 Single participant -

## average results

Experiment Status	success
T_loop	1.304
received	95.1183
sent	9.5161
lost	0.0
relative_loss	0.0
data_received	209878442.7849
latency_min (ms)	1.4144
latency_max (ms)	4.0633
latency_mean (ms)	3.052
latency_variance (ms)	0.0005
pub_loop_res_min (ms)	98.7623
pub_loop_res_max (ms)	99.6756
pub_loop_res_mean (ms)	99.0576
pub_loop_res_variance (ms)	0.0001
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	4.1452

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	PointCloud2m
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0