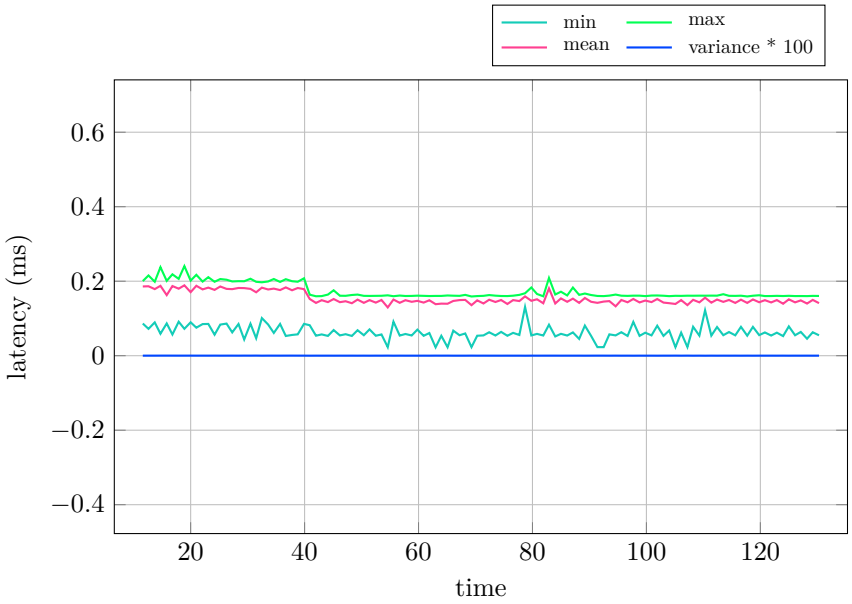
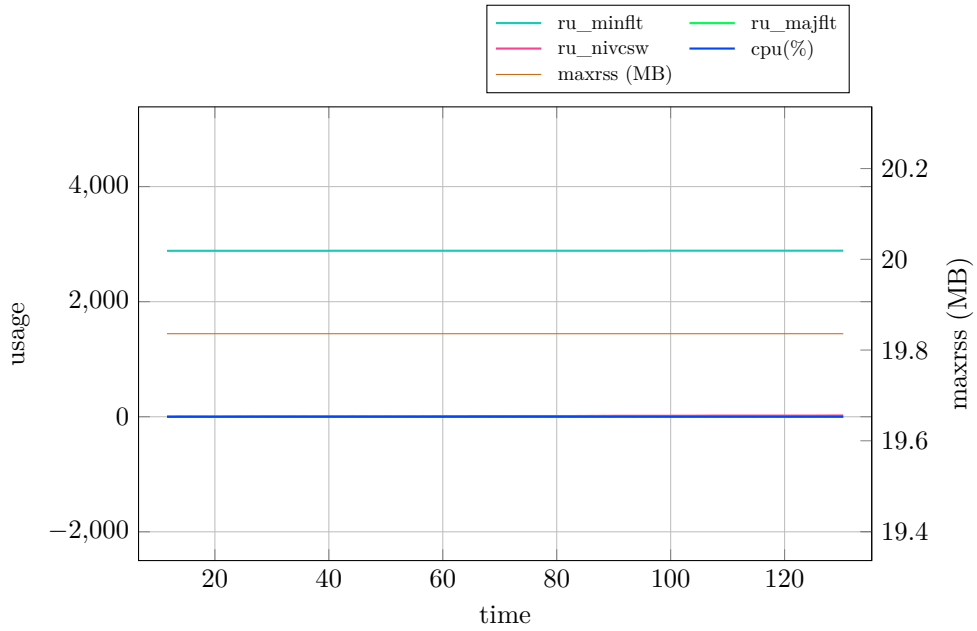
Performance

Logfile name	log_test_topic_28-11-2020_09-29-38
Experiment id	38978062-7a14-4334-aa18-442e7daf8d26
Communication mean	ROS2



Latencies



Resource usage (man getrusage)

test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0507
received	9.5088
sent	9.5
lost	0.0
relative_loss	0.0
data_received	1688.4474
latency_min (ms)	0.0626
latency_max (ms)	0.1734
latency_mean (ms)	0.1545
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.4594
pub_loop_res_max (ms)	99.7473
pub_loop_res_mean (ms)	99.5125
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.4047

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	NavSatFix
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0