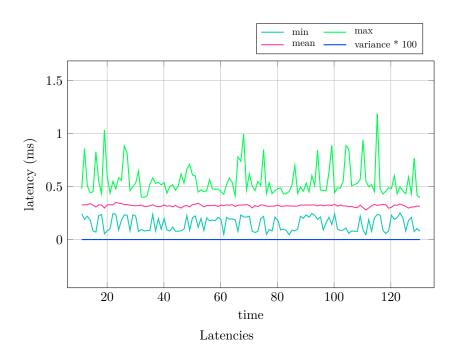
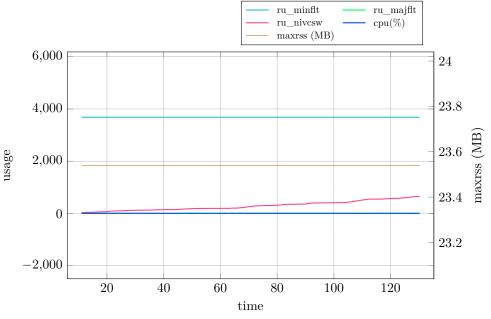
# Performance

 Logfile name
 log\_test\_topic\_27-11-2020\_14-05-21

 Experiment id
 f378dd0d-80df-4591-b5ed-26089f7dd350

 Communication mean
 ROS2





Resource usage (man getrusage)

## test setup

# Performance Test Version 80ff298 Publishing rate 1000 Topic name test\_topic Number of publishers 1 Number of subscribers 3 Maximum runtime (sec) 130 DDS domain id 0 Single participant -

# average results

Experiment Status	success
T_loop	1.0016
received	2998.475
sent	999.5167
lost	0.0
relative_loss	0.0
data_received	2519997.925
latency_min (ms)	0.1488
latency_max (ms)	0.5532
latency_mean (ms)	0.3198
latency_variance (ms)	0.0
pub_loop_res_min (ms)	0.7338
pub_loop_res_max (ms)	0.9061
pub_loop_res_mean (ms)	0.8154
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	7.4112

## environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1000
QOS History kind	KEEP_ALL
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_ecal_dynamic_cpp
Roundtrip Mode	NONE
With security	0