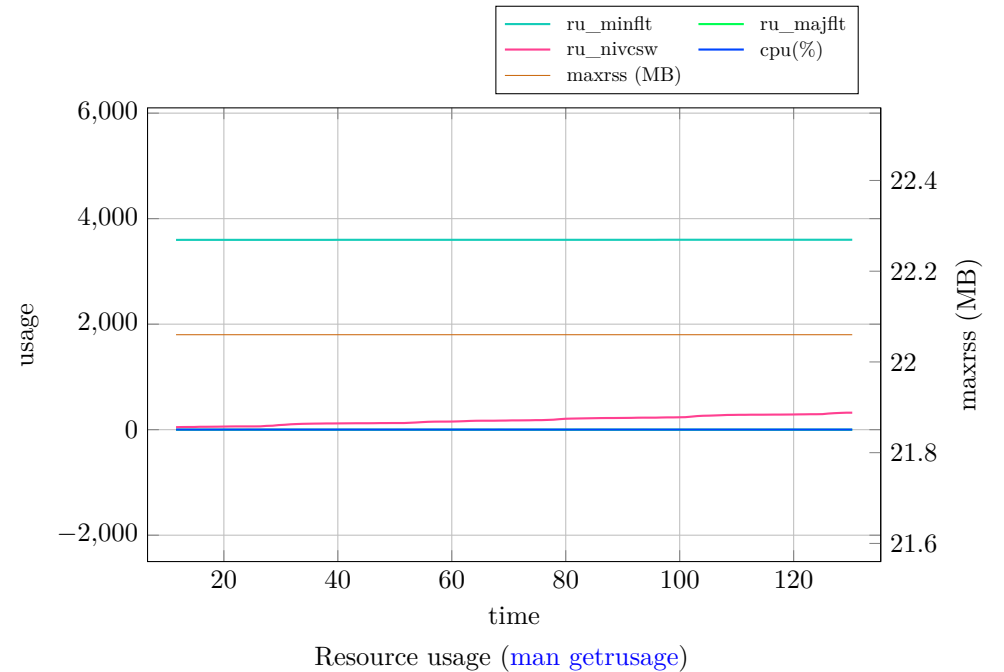
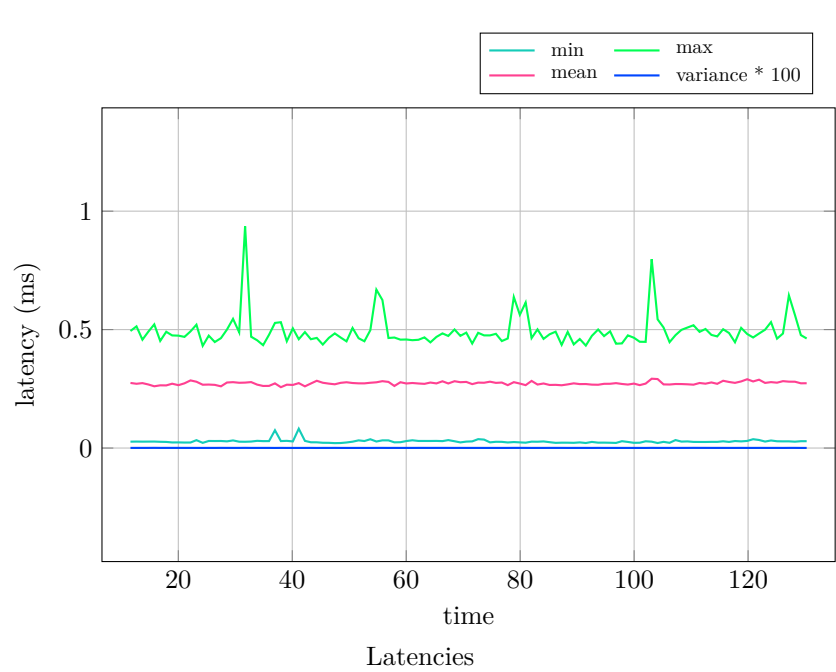


Performance

Logfile name	log_test_topic_01-12-2020_11-56-53
Experiment id	273460c0-20a9-4c92-a902-c0a03f68446c
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	50
Topic name	test_topic
Number of publishers	1
Number of subscribers	10
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.05
received	495.0965
sent	49.5263
lost	0.0
relative_loss	0.0
data_received	420007.1228
latency_min (ms)	0.028
latency_max (ms)	0.4919
latency_mean (ms)	0.2733
latency_variance (ms)	0.0
pub_loop_res_min (ms)	19.2683
pub_loop_res_max (ms)	19.8761
pub_loop_res_mean (ms)	19.4273
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.8755

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_cyclonedds_cpp
Roundtrip Mode	NONE
With security	0