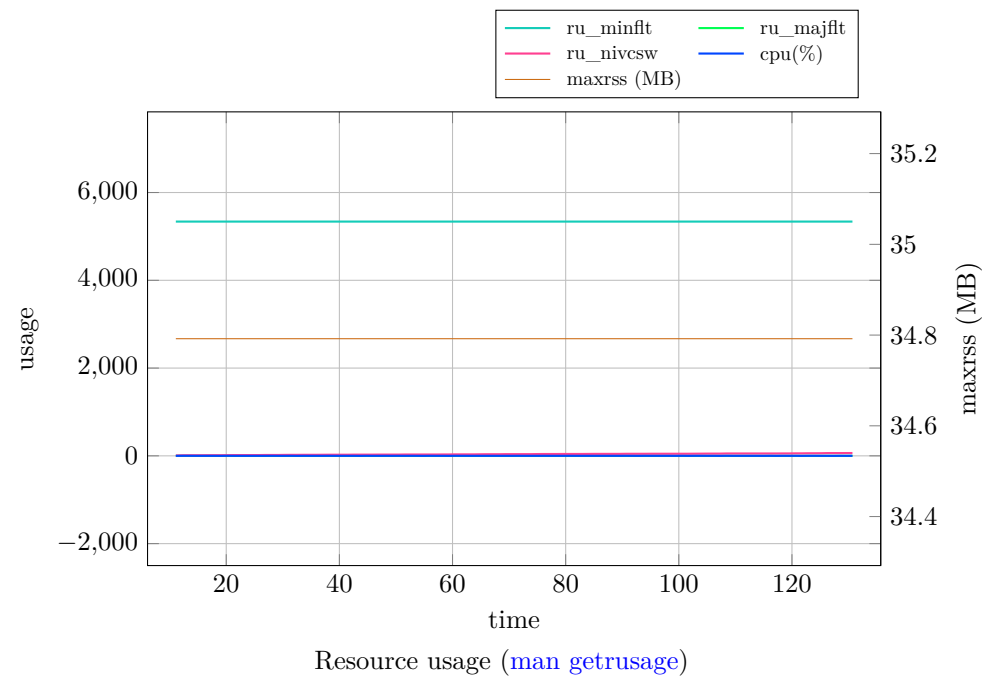
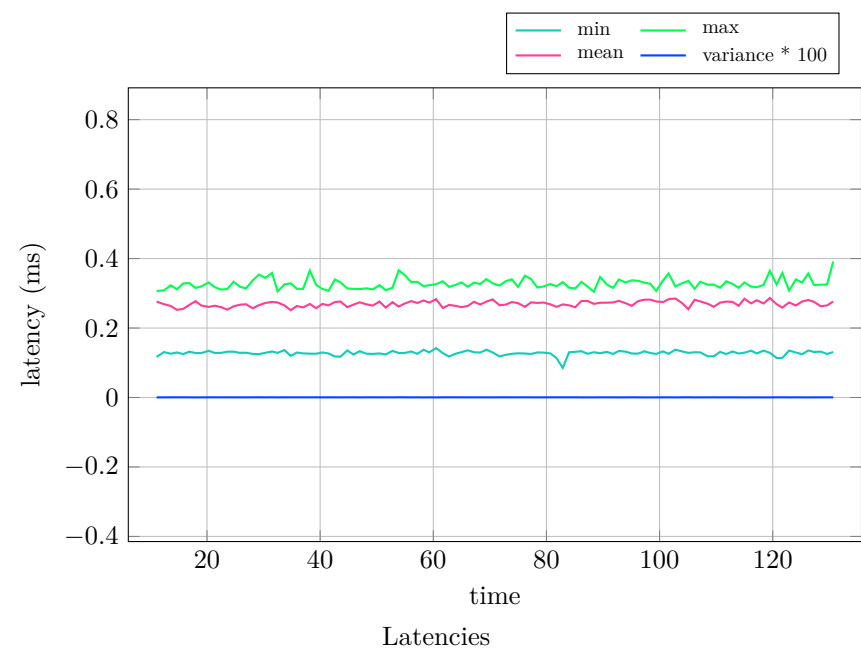


Performance

Logfile name	log_test_topic_12-12-2020_14-43-46
Experiment id	52c9d641-f4c1-4c5d-99aa-049cd2e15cb2
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	10
Topic name	test_topic
Number of publishers	1
Number of subscribers	5
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.1165
received	47.5463
sent	9.4907
lost	0.0
relative_loss	0.0
data_received	4002.4259
latency_min (ms)	0.1279
latency_max (ms)	0.3276
latency_mean (ms)	0.2697
latency_variance (ms)	0.0
pub_loop_res_min (ms)	99.4975
pub_loop_res_max (ms)	99.9131
pub_loop_res_mean (ms)	99.6031
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	0.9549

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarDetection
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0