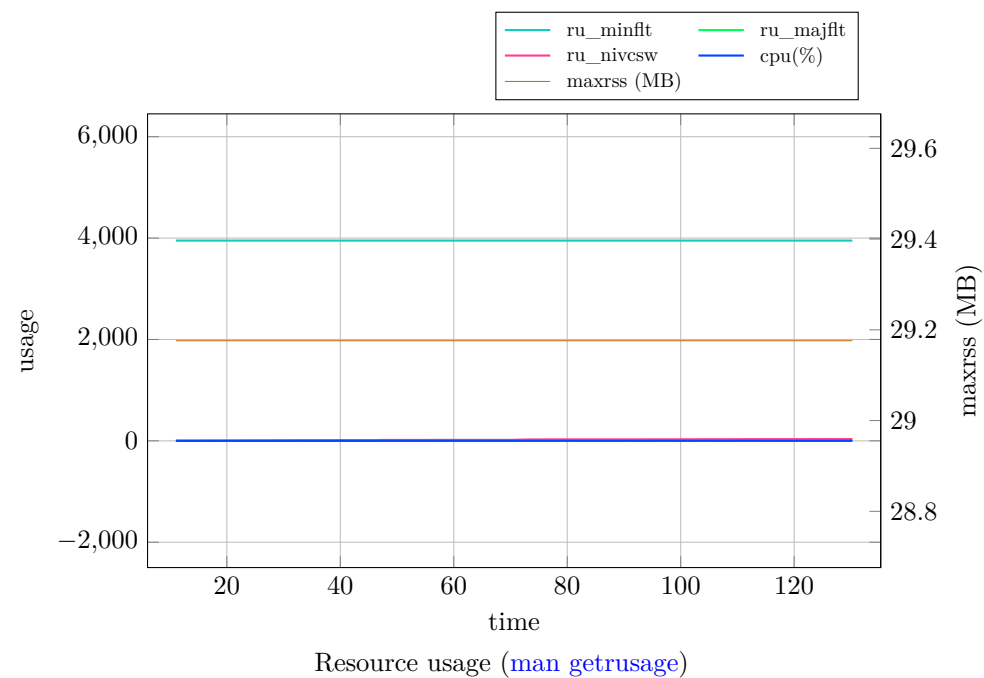
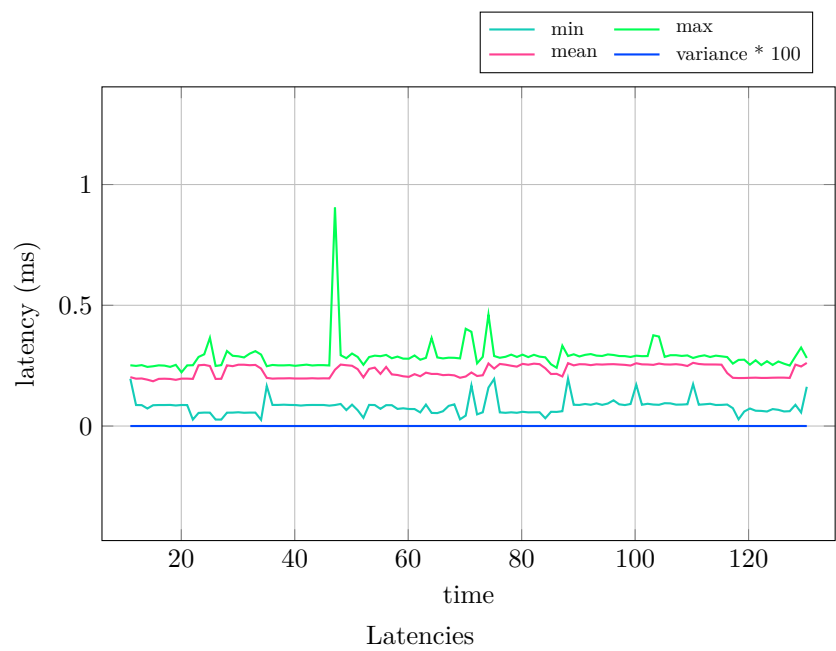


Performance

Logfile name	log_test_topic_01-12-2020_14-22-52
Experiment id	17ea41f1-81ed-48df-9334-daa4ae3ff067
Communication mean	ROS2



test setup

Performance Test Version	80ff298
Publishing rate	500
Topic name	test_topic
Number of publishers	1
Number of subscribers	1
Maximum runtime (sec)	130
DDS domain id	0
Single participant	-

average results

Experiment Status	success
T_loop	1.0017
received	499.475
sent	499.475
lost	0.0
relative_loss	0.0
data_received	419998.1667
latency_min (ms)	0.0803
latency_max (ms)	0.2886
latency_mean (ms)	0.2273
latency_variance (ms)	0.0
pub_loop_res_min (ms)	1.6718
pub_loop_res_max (ms)	1.9077
pub_loop_res_mean (ms)	1.7951
pub_loop_res_variance (ms)	0.0
sub_loop_res_min (ms)	0.0
sub_loop_res_max (ms)	0.0
sub_loop_res_mean (ms)	0.0
sub_loop_res_variance (ms)	0.0
cpu_usage (%)	1.3555

environment

Ignore seconds from beginning	10
Memory check enabled	0
Msg name	RadarTrack
QOS Durability	VOLATILE
QOS History depth	1
QOS History kind	KEEP_LAST
QOS Reliability	BEST_EFFORT
QOS Sync. pub/sub	0
RMW Implementation	rmw_fastrtps_cpp
Roundtrip Mode	NONE
With security	0