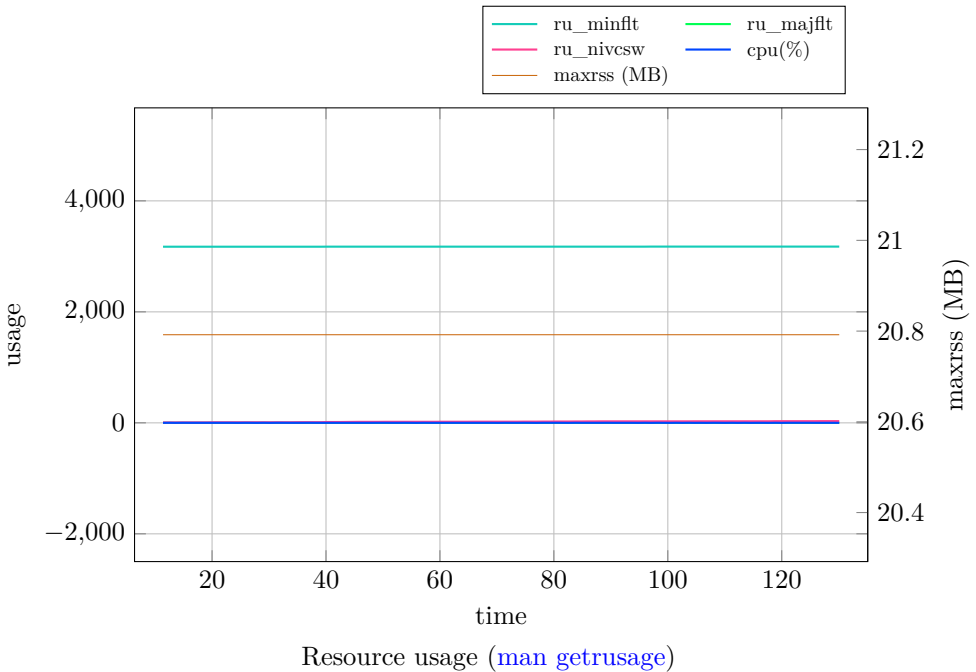
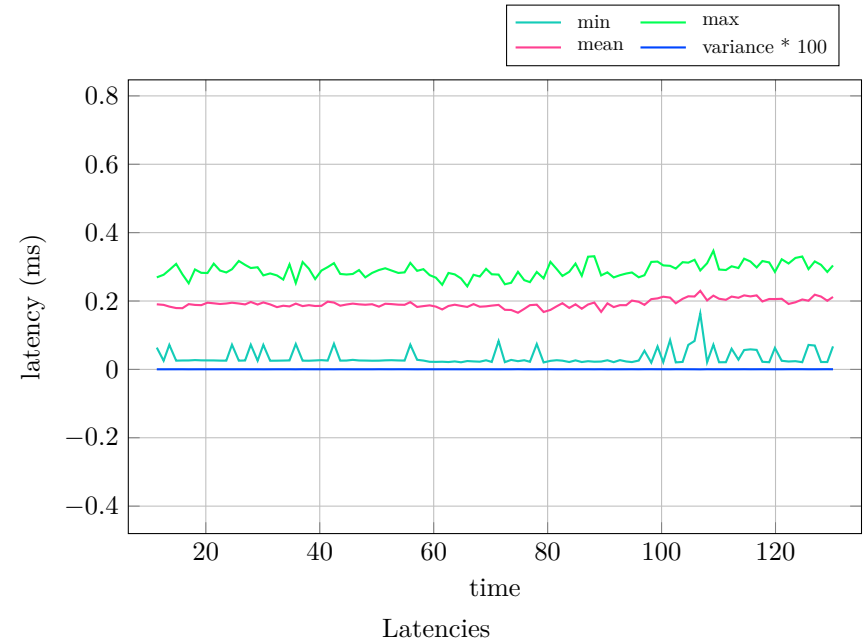


# Performance

Logfile name	log_test_topic_28-11-2020_11-45-56
Experiment id	342f586e-f922-43e4-9fed-b291e33603db
Communication mean	ROS2



test setup		average results		environment	
Performance Test Version	80ff298	Experiment Status	success	Ignore seconds from beginning	10
Publishing rate	10	T_loop	1.1082	Memory check enabled	0
Topic name	test_topic	received	47.3426	Msg name	RadarDetection
Number of publishers	1	sent	9.4815	QOS Durability	VOLATILE
Number of subscribers	5	lost	0.0	QOS History depth	1000
Maximum runtime (sec)	130	relative_loss	0.0	QOS History kind	KEEP_ALL
DDS domain id	0	data_received	4001.2037	QOS Reliability	BEST_EFFORT
Single participant	-	latency_min (ms)	0.0357	QOS Sync. pub/sub	0
		latency_max (ms)	0.2903	RMW Implementation	rmw_cyclonedds_cpp
		latency_mean (ms)	0.1929	Roundtrip Mode	NONE
		latency_variance (ms)	0.0	With security	0
		pub_loop_res_min (ms)	99.4274		
		pub_loop_res_max (ms)	99.8278		
		pub_loop_res_mean (ms)	99.5133		
		pub_loop_res_variance (ms)	0.0		
		sub_loop_res_min (ms)	0.0		
		sub_loop_res_max (ms)	0.0		
		sub_loop_res_mean (ms)	0.0		
		sub_loop_res_variance (ms)	0.0		
		cpu_usage (%)	0.8847		