

```
root@zedboard-zynq7:/usr/bin# ls
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```
Gyroscope_Bias.mat
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IMUFusionSimulinkModel
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IMUFusionSimulinkModel.mat
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```
Orientation_Error.mat
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PID_run_file
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[
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[[
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```
apt-cache
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```
apt-cdrom
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```
apt-config
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```
apt-get
```

```
apt-key
```

```
awk
```

```
basename
```

```
bunzip2
```

```
bzcat
```

```
md5sum
```

```
mesg
```

```
mesg.sysvinit
```

```
microcom
```

```
mkfifo
```

```
mpicalc
```

```
nc
```

```
nettle-hash
```

```
nettle-lfib-stream
```

```
nettle-pbkdf2
```

```
newgidmap
```

```
newgrp
```

```
newgrp.shadow
```

```
newuidmap
```

```
nohup
```

```
nsproc
```