

Modeling of the third order system example using Python

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$$\text{Transfer function} = \frac{3}{s^3 + 2s^2 + 3s + 1}$$

```
### Import Required Libraries
```

```
# Install the required libraries in your Python environment
!pip install -q numpy scipy matplotlib
```

```
# Import the require libraries
import numpy as np
from scipy import signal
import matplotlib.pyplot as plt
from scipy.integrate import odeint
```

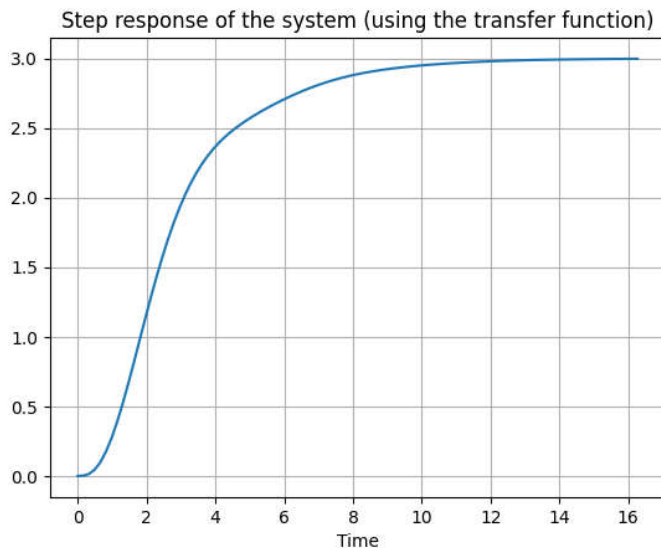
Using the transfer function directly

```
# Define the transfer function numerator and denominator polynomial
num = [3]
den = [1, 2, 3, 1]

# Define the transfer function
tf = signal.TransferFunction(num, den)

# Obtain the step response
t, y_s = signal.step(tf)

# Plot the step response
plt.plot(t, y_s)
plt.xlabel("Time")
plt.title("Step response of the system (using the transfer function)")
plt.grid(True)
plt.show()
```



Using the time domain representation

Convert the system from s-domain to t-domain by taking the inverse Laplace transform:

$$\frac{Y(s)}{U(s)} = \frac{3}{s^3 + 2s^2 + 3s + 1}$$

$$s^3 \cdot Y(s) + 2s^2 \cdot Y(s) + 3s \cdot Y(s) + Y(s) = 3 \cdot U(s)$$

Taking the inverse Laplace transform of both sides assuming zero initial conditions i.e. $y(0) = 0, y'(0) = 0, y''(0) = 0$:

$$\frac{d^3 y(t)}{dt^3} + 2 \cdot \frac{d^2 y(t)}{dt^2} + 3 \cdot \frac{dy(t)}{dt} + y(t) = 3 \cdot u(t)$$

$$y''' + 2y'' + 3y' + y = 3u$$

$$y''' = 3u - 2y'' - 3y' - y$$

Define the initial values of the system

```
y0 = [0, 0, 0]
```

Define the simulation time span

```
# t = np.linspace(0, 10, 1000)
```

Define the step function

```
def step(t):
    return 1*(t > 0)
```

Define the system's ODE

```
def sys(y_init: tuple, t: np.ndarray):
    u = step(t)
    dydt = [y_init[1], y_init[2], (3*u - y_init[0] - 3*y_init[1] - 2*y_init[2])]
    return dydt
```

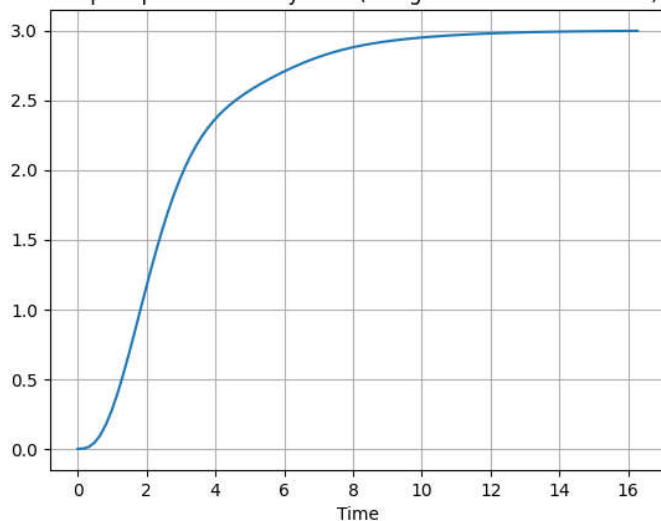
Numerical integration

```
y_t = odeint(sys, y0, t)
```

```
plt.plot(t, y_t[:, 0])
plt.xlabel("Time")
plt.title("Step response of the system (using the ODE i.e. t-domain)")
plt.grid(True)
plt.show()
```



Step response of the system (using the ODE i.e. t-domain)



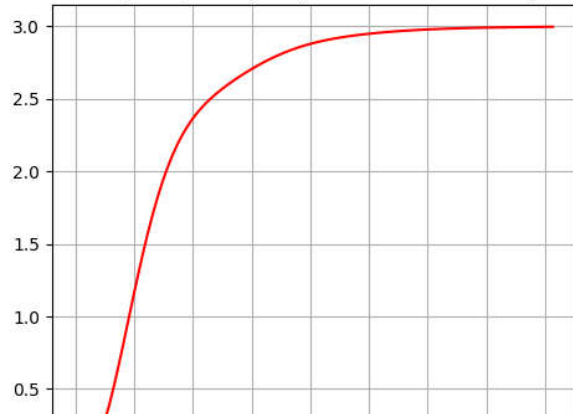
▼ Comparing the response using the transfer function and the t-domain representation (ODEs)

```
fig, ax = plt.subplots(
    nrows = 1,
    ncols = 2,
    figsize = (12, 5)
)

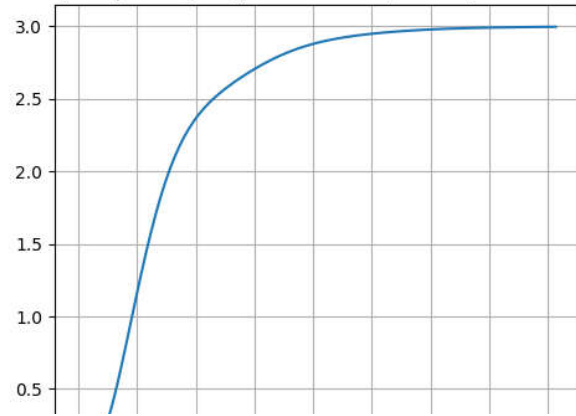
ax[0].plot(t, y_s, 'r')
ax[0].set_title("Step response (using the transfer function)")
ax[0].grid(True)

ax[1].plot(t, y_t[:, 0])
ax[1].set_title("Step response (using the t-domain/ODE representation)")
ax[1].grid(True)
```

Step response (using the transfer function)



Step response (using the t-domain/ODE representation)



The responses are observed to be similar as expected.

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