

Electric and Magnetic field equations

$$\begin{aligned} \vec{E}(\vec{r}) &= \int_{c'} \frac{\rho_l(\vec{r}') d\vec{l}'}{4\pi\epsilon R^2} \hat{a}_R & \vec{E}(\vec{r}) &= \int_{s'} \frac{\rho_s(\vec{r}') ds'}{4\pi\epsilon R^2} \hat{a}_R & \vec{E}(\vec{r}) &= \int_{v'} \frac{\rho_v(\vec{r}') dv'}{4\pi\epsilon R^2} \hat{a}_R \\ V(\vec{r}) &= \int_{c'} \frac{\rho_l(\vec{r}') d\vec{l}'}{4\pi\epsilon R} & V(\vec{r}) &= \int_{s'} \frac{\rho_s(\vec{r}') ds'}{4\pi\epsilon R} & V(\vec{r}) &= \int_{v'} \frac{\rho_v(\vec{r}') dv'}{4\pi\epsilon R} \\ \oint_s \vec{E} \cdot d\vec{s} &= \frac{1}{\epsilon_0} \int_v \rho_v dv & \nabla \cdot \vec{E} &= \rho/\epsilon_0 & \nabla \times \vec{E} &= 0 & \nabla^2 V &= -\rho_v/\epsilon_0 & \nabla \cdot \vec{D} &= \rho_v & \vec{D} &= \epsilon \vec{E} \\ \oint_s \vec{D} \cdot d\vec{s} &= Q & V &= \int_L \vec{E} \cdot d\vec{l} & C &= \frac{Q}{V} & \rho_{ps} &= \vec{P} \cdot \hat{a}_n & \rho_{pv} &= -\nabla \cdot \vec{P} & \vec{D} &= \epsilon_0 \vec{E} + \vec{P} & \vec{P} &= \epsilon_0 \chi_e \vec{E} \\ \vec{B}(\vec{r}) &= \int_{c'} \frac{\mu_0 I d\vec{l}' \times \vec{R}}{4\pi R^3} & \vec{B}(\vec{r}) &= \int_{s'} \frac{\mu_0 \vec{J}_s(\vec{r}') \times \vec{R} ds'}{4\pi R^3} & \vec{B}(\vec{r}) &= \int_{v'} \frac{\mu_0 \vec{J}_v(\vec{r}') \times \vec{R} dv'}{4\pi R^3} \\ \vec{A}(\vec{r}) &= \int_{c'} \frac{\mu_0 I d\vec{l}'}{4\pi R} & \vec{A}(\vec{r}) &= \int_{s'} \frac{\mu_0 \vec{J}_s(\vec{r}') ds'}{4\pi R} & \vec{A}(\vec{r}) &= \int_{v'} \frac{\mu_0 \vec{J}_v(\vec{r}') dv'}{4\pi R} \\ \oint_s \vec{B} \cdot d\vec{s} &= 0 & \nabla \cdot \vec{B} &= 0 & \nabla \times \vec{B} &= \mu_0 \vec{J}_v & \nabla^2 \vec{A} &= -\mu_0 \vec{J}_v & \nabla \times \vec{H} &= \vec{J}_v & \vec{B} &= \mu_0 \vec{H} \\ \oint_L \vec{H} \cdot d\vec{L} &= I & L &= \frac{\Psi}{I} & \vec{J}_{ms} &= \vec{M} \times \hat{a}_n & \vec{J}_{mv} &= \nabla \times \vec{M} & \vec{H} &= \frac{1}{\mu_0} \vec{B} - \vec{M} & \vec{M} &= \frac{\chi_m}{\mu_0} \vec{B} \end{aligned}$$

Boundary conditions

$$\begin{aligned} \hat{a}_{n21} \times (\vec{E}_1 - \vec{E}_2) &= 0 & \hat{a}_{n21} \cdot (\vec{D}_1 - \vec{D}_2) &= \rho_s \\ \hat{a}_{n21} \times (\vec{H}_1 - \vec{H}_2) &= \vec{J}_s & \hat{a}_{n21} \cdot (\vec{B}_1 - \vec{B}_2) &= 0 \end{aligned}$$

Some useful integrals

$$\int \frac{dx}{(x^2 + a^2)^{3/2}} = \frac{x}{a^2 (x^2 + a^2)^{1/2}} \quad \int \frac{xdx}{(x^2 + a^2)^{3/2}} = \frac{-1}{(x^2 + a^2)^{1/2}}$$

Cylindrical to Cartesian coordinate transforms

Inner product (.)	\hat{a}_x	\hat{a}_y	\hat{a}_z
\hat{a}_r	$\cos\phi$	$\sin\phi$	0
\hat{a}_ϕ	$-\sin\phi$	$\cos\phi$	0
\hat{a}_z	0	0	1

Spherical to Cartesian coordinate transforms

Inner product (.)	\hat{a}_x	\hat{a}_y	\hat{a}_z
\hat{a}_r	$\sin\theta \cos\phi$	$\sin\theta \sin\phi$	$\cos\theta$
\hat{a}_θ	$\cos\theta \cos\phi$	$\cos\theta \sin\phi$	$-\sin\theta$
\hat{a}_ϕ	$-\sin\phi$	$\cos\phi$	0

$$\begin{aligned} \nabla \cdot \vec{A} &= \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u_1} (h_2 h_3 A_1) + \frac{\partial}{\partial u_2} (h_1 h_3 A_2) + \frac{\partial}{\partial u_3} (h_1 h_2 A_3) \right] \\ \nabla \times \vec{A} &= \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \hat{a}_{u_1} & h_2 \hat{a}_{u_2} & h_3 \hat{a}_{u_3} \\ \frac{\partial}{\partial u_1} & \frac{\partial}{\partial u_2} & \frac{\partial}{\partial u_3} \\ h_1 A_1 & h_2 A_2 & h_3 A_3 \end{vmatrix} \\ \nabla f &= \frac{1}{h_1} \frac{\partial f}{\partial u_1} \hat{a}_{u_1} + \frac{1}{h_2} \frac{\partial f}{\partial u_2} \hat{a}_{u_2} + \frac{1}{h_3} \frac{\partial f}{\partial u_3} \hat{a}_{u_3} \\ \nabla^2 f &= \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u_1} \left(\frac{h_2 h_3}{h_1} \frac{\partial f}{\partial u_1} \right) + \frac{\partial}{\partial u_2} \left(\frac{h_1 h_3}{h_2} \frac{\partial f}{\partial u_2} \right) + \frac{\partial}{\partial u_3} \left(\frac{h_1 h_2}{h_3} \frac{\partial f}{\partial u_3} \right) \right] \end{aligned}$$

Cartesian coordinate

$$\begin{aligned} d\vec{l}_x &= dx \hat{a}_x, & d\vec{l}_y &= dy \hat{a}_y, & d\vec{l}_z &= dz \hat{a}_z \\ d\vec{l} &= dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z \\ d\vec{s}_x &= dydz \hat{a}_x, & d\vec{s}_y &= dx dz \hat{a}_y, & d\vec{s}_z &= dx dy \hat{a}_z \\ dv &= dx dy dz \\ \vec{r} &= x \hat{a}_x + y \hat{a}_y + z \hat{a}_z \end{aligned}$$

Cylindrical coordinate

$$\begin{aligned} d\vec{l}_r &= dr \hat{a}_r, & d\vec{l}_\phi &= r d\phi \hat{a}_\phi, & d\vec{l}_z &= dz \hat{a}_z \\ d\vec{l} &= dr \hat{a}_r + r d\phi \hat{a}_\phi + dz \hat{a}_z \\ d\vec{s}_r &= r d\phi dz \hat{a}_r, & d\vec{s}_\phi &= dr dz \hat{a}_\phi, & d\vec{s}_z &= r dr d\phi \hat{a}_z \\ dv &= r dr d\phi dz \\ \vec{r} &= r \hat{a}_r + z \hat{a}_z \end{aligned}$$

Spherical coordinate

$$\begin{aligned} d\vec{l}_r &= dr \hat{a}_r, & d\vec{l}_\theta &= r d\theta \hat{a}_\theta, & d\vec{l}_\phi &= r \sin\theta d\phi \hat{a}_\phi \\ d\vec{l} &= dr \hat{a}_r + r d\theta \hat{a}_\theta + r \sin\theta d\phi \hat{a}_\phi \\ d\vec{s}_r &= r^2 \sin\theta d\theta d\phi \hat{a}_r, & d\vec{s}_\theta &= r \sin\theta dr d\phi \hat{a}_\theta, & d\vec{s}_\phi &= r dr d\theta \hat{a}_\phi \\ dv &= r^2 \sin\theta dr d\theta d\phi \\ \vec{r} &= r \hat{a}_r \end{aligned}$$

Trigonometric Identities

$$\begin{aligned} \sin^2 x &= \frac{1 - \cos(2x)}{2}, & \cos^2 x &= \frac{1 + \cos(2x)}{2} \\ \sin^3 x &= \frac{1}{4} (-\sin(3x) + 3\sin x) \\ \cos^3 x &= \frac{1}{4} (\cos(3x) + 3\cos x) \end{aligned}$$