

$$x_1 \xleftrightarrow{f.s} a_k \quad \text{periodic with } T_1 \left(\frac{2\pi}{\omega_1} \right)$$

سوال 5

$$x_2(t) = \underbrace{2x_1(1-t)}_{(I)} - \frac{1}{3}x_1(2t-1) \rightarrow \begin{cases} T=? \\ b_k=? \end{cases}$$

$$\oint x_1(t) \xleftrightarrow{f.s} a_k \Rightarrow x_1(t+1) \xleftrightarrow{f.s} a_k e^{+jk\omega_1 T_1}$$

$$\oint x(t) \xleftrightarrow{f.s} a_k \Rightarrow x_1(-t+1) = x(1-t) \xleftrightarrow{f.s} a_{-k} e^{+jk\omega_1 T_1}$$

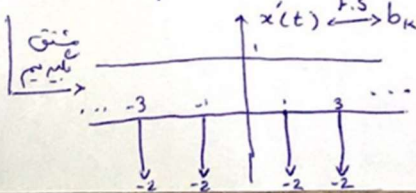
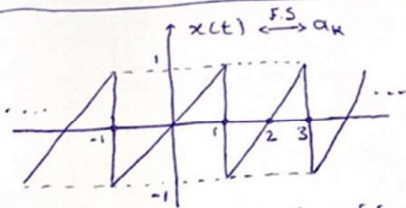
$$x(t-1) \xleftrightarrow{f.s} a_k e^{-jk\omega_1 T_1}, \quad x(2t-1) \xleftrightarrow{f.s} a_k e^{-jk2\omega_1 T_1}$$

ضرایب تغییر می کند

نقد ω ، 2 برابر می شود \leftarrow (T نصف می شود)

$$\Rightarrow a_k = 2a_{-k} e^{+jk\omega_1 T_1} - \frac{1}{3}a_k e^{-jk2\omega_1 T_1}$$

$$\begin{cases} 2x_1(1-t) \rightarrow T_1 \\ -\frac{1}{3}x_1(2t-1) \rightarrow \frac{T_1}{2} \end{cases} \Rightarrow \text{Kmm} \left\{ T_1, \frac{T_1}{2} \right\} = T_1$$



استفاده از فواصل \rightarrow روش اول

سوال 6

$$s(t) \xleftrightarrow{f.s} d_k = \frac{1}{T} = \frac{1}{2}$$



$$\begin{aligned}
 & x'(t) = -2\delta(t-1) + 1 \\
 & \rightarrow (jk\omega_0) a_k = -2e^{-jk\omega_0 \times 1} \times \underbrace{\frac{1}{2}}_{=d_k} \rightarrow a_k = \frac{-1}{jk\omega_0} e^{-jk\omega_0} \xrightarrow{\omega_0 = \frac{2\pi}{T} = \pi} a_k = \frac{-1}{jk\pi} \\
 & a_k = \frac{-1}{jk\pi} e^{-jk\pi} = \frac{j}{k\pi} (-1)^k \text{ for } k \neq 0
 \end{aligned}$$

$$\text{P2) } \oint_{\gamma} \rightarrow \text{Fourier: } a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt \xrightarrow{T=2} a_k = \frac{1}{2} \int_{-1}^{+1} t e^{-jk\omega_0 t} dt$$

$$= \frac{1}{2} \left[\frac{-t}{jk\omega_0} e^{-jk\omega_0 t} \Big|_{-1}^{+1} + \frac{1}{(jk\omega_0)^2} e^{-jk\omega_0 t} \Big|_{-1}^{+1} \right]$$

$$= \frac{1}{2} \left[e^{-jk\omega_0} \left(\frac{1}{(k\omega_0)^2} - \frac{1}{jk\omega_0} \right) - e^{jk\omega_0} \left(\frac{1}{(k\omega_0)^2} + \frac{1}{jk\omega_0} \right) \right]$$

$$= -\frac{1}{2} \left[\frac{1}{(k\omega_0)^2} (e^{jk\omega_0} - e^{-jk\omega_0}) + (e^{jk\omega_0} + e^{-jk\omega_0}) \frac{1}{jk\omega_0} \right]$$

مت	دالة
t	$e^{-jk\omega_0 t}$
1	$\frac{1}{jk\omega_0} e^{-jk\omega_0}$
0	$\frac{1}{(jk\omega_0)^2} e^{-jk\omega_0}$

سوال 7

$T=3$

a) $a_k = a_{k+2}$

b) $a_k = a_{-k}$

c) $\int_{-0.5}^{0.5} x(t) dt = 1$

d) $\int_{-0.5}^{1.5} x(t) dt = 2$

$x(t) = ?$

طبق خواص a_{k+2} و a_{-k} می دانیم

$x(t) = x(-t)$ پس از خاصیت b می توان فهمید که

طبق خاصیت جابجایی در فرایب: $x(t) \xrightarrow{F.S} a_{k-M}$

از خاصیت a می توان فهمید که $x(t) = x(t) e^{-j \frac{4\pi}{3} t}$

فقط در فرایب $t = 0, \pm 1.5, \pm 3, \pm 4.5, \pm 6, \dots$

در $t = \pm 1.5$ مقدار دارد به طوریکه شرط a را ارضا کند

باید $e^{-j \frac{4\pi}{3} t} = 1$ شود تا a صحیح باشد

از خاصیت c می توان فهمید که: $x(t) = \delta(t)$; $-\frac{1}{2} < t < \frac{1}{2}$

همچنین از خاصیت d می توان فهمید: $x(t) = 2\delta(t-1.5)$; $0.5 < t < 1.5$

بنابراین می توان نوشت: $x(t) = \sum_{k=-\infty}^{+\infty} \delta(t-3k) + 2 \sum_{k=-\infty}^{+\infty} \delta(t-1.5-3k)$

if $x(t) \xleftrightarrow{f.s} a_k$

8 د'ا

$$Z(t) = \underbrace{\cos(M\omega_0 t)}_{(III)} \cdot \underbrace{\frac{d}{dt}(x(t-t_0))}_{(CI)} \xleftrightarrow{f.s} ?$$

I) $x(t-t_0) \xleftrightarrow{f.s} a_k e^{-jk\omega_0 t_0}$ (II)

II) $\frac{d}{dt}(x(t-t_0)) \xleftrightarrow{f.s} jk\omega_0 (a_k e^{-jk\omega_0 t_0})$

III) $\cos(M\omega_0 t) \xleftrightarrow{f.s} \Rightarrow \frac{1}{2} (e^{jM\omega_0 t} + e^{-jM\omega_0 t})$

$$\cos x = \frac{1}{2} (e^{jx} + e^{-jx})$$

$$\cos(\omega_0 t) = \frac{1}{2} e^{j\omega_0 t} + e^{-j\omega_0 t} \Rightarrow b_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt = \frac{\omega_0}{2\pi} \int_0^{\frac{2\pi}{\omega_0}} (e^{j\omega_c t} + e^{-j\omega_c t}) e^{-jk\omega_0 t} dt$$

$$= \frac{\omega_0}{4\pi} \int_0^{\frac{2\pi}{\omega_0}} e^{j\omega_c t} e^{-jk\omega_0 t} dt + \int_0^{\frac{2\pi}{\omega_0}} e^{-j\omega_c t} e^{-jk\omega_0 t} dt$$

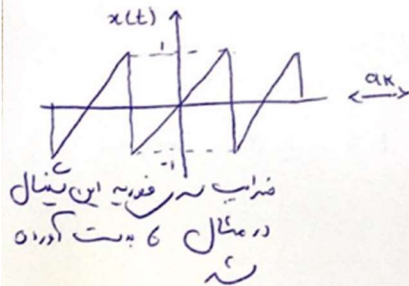
$$= \frac{\omega_0}{4\pi} \int_0^{\frac{2\pi}{\omega_0}} e^{j(\omega_c - k\omega_0)t} dt + \int_0^{\frac{2\pi}{\omega_0}} e^{-j(\omega_c + k\omega_0)t} dt$$

$$= \frac{\omega_0}{4\pi} \left(\frac{2\pi}{\omega_c} e^{j(\omega_c - k\omega_0)t} + \frac{2\pi}{\omega_c} e^{-j(\omega_c + k\omega_0)t} \right) = \frac{1}{2} \left(e^{j(\omega_c - k\omega_0)t} + e^{-j(\omega_c + k\omega_0)t} \right)$$

$$\Rightarrow \cos(M\omega_0 t) \xleftrightarrow{f.s} \frac{1}{2} \left(e^{j(M\omega_0 - k\omega_0)t} + e^{-j(M\omega_0 + k\omega_0)t} \right)$$

$$\Rightarrow Z(t) \xleftrightarrow{f.s} C_k = \frac{jk\omega_0}{2} (a_k e^{-jk\omega_0 t_0}) \cdot \left(e^{jM(\omega_0 - k\omega_0)t} + e^{-jM(\omega_0 + k\omega_0)t} \right)$$

$$w(t) = \sum_{k=-\infty}^{+\infty} (\delta(t-0.5-2k) - \delta(t+0.5-2k))$$

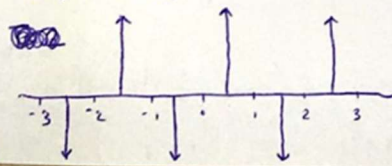


سوال 9
یا درس

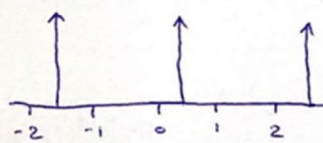
$$x(t) \otimes y(t) = \int_T x(\tau) y(t-\tau) d\tau$$

$$x(t) \otimes y(t) \xleftrightarrow{F.S} T a_n b_n$$

$$w(t) \xleftrightarrow{F.S} b_k$$



$$w_1(t)$$



$$w_2(t)$$



$$\Rightarrow w(t) = w_1(t) + w_2(t) \xleftrightarrow{F.S} b_k = c_k + d_k$$

$$w_1(t) \xleftrightarrow{F.S} \frac{1}{2} e^{-jk\frac{\pi}{2}} \Rightarrow b_k = \frac{1}{2} (e^{-jk\frac{\pi}{2}} - e^{jk\frac{\pi}{2}})$$

$$w_2(t) \xleftrightarrow{F.S} -\frac{1}{2} e^{jk\frac{\pi}{2}}$$

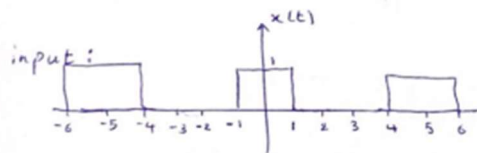
$$x(t) \xleftrightarrow{F.S} a_k = \frac{-1}{jk\pi} e^{-jk\pi} \Rightarrow T a_k b_k = 2 \times \frac{1}{2} (e^{-jk\frac{\pi}{2}} - e^{jk\frac{\pi}{2}}) \cdot \frac{-1}{jk\pi} e^{-jk\pi}$$

$$= \underbrace{\frac{-1}{jk\pi} e^{-jk\pi} (e^{-jk\frac{\pi}{2}} - e^{jk\frac{\pi}{2}})}_{(I)} \Rightarrow x(t) \otimes y(t) = F.S^{-1}\{I\}$$

$$\text{در سری دو: } x(t) \otimes y(t) = \int_T x(\tau) y(t-\tau) d\tau$$

تفاوت کانولوشن دیرک و کانولوشن فوريه
در بازه انتگرال گیری است.

$$\frac{d^2 y(t)}{dt^2} - 5 \frac{dy(t)}{dt} + 6 y(t) = 3 \frac{dx(t)}{dt}$$



$x(t) = e^{j\omega t} \rightarrow \boxed{\text{LTI}} \rightarrow H(j\omega) e^{j\omega t} = y(t)$



$$\Rightarrow \frac{d^2}{dt^2} (H(j\omega) e^{j\omega t}) - 5 \frac{d}{dt} (H(j\omega) e^{j\omega t}) + 6 H(j\omega) e^{j\omega t} = 3 e^{j\omega t}$$

$$= (j\omega)^2 H(j\omega) e^{j\omega t} - 5(j\omega) H(j\omega) e^{j\omega t} + 6 H(j\omega) e^{j\omega t} = 3 e^{j\omega t}$$

$$= -\omega^2 H(j\omega) e^{j\omega t} - 5j\omega H(j\omega) e^{j\omega t} + 6 H(j\omega) e^{j\omega t} = 3 e^{j\omega t}$$

$$\Rightarrow H(j\omega) (-\omega^2 e^{j\omega t} - 5j\omega e^{j\omega t} + 6 e^{j\omega t}) = 3 e^{j\omega t}$$

$$\Rightarrow H(j\omega) = \frac{3 e^{j\omega t}}{6 e^{j\omega t} - 5j\omega e^{j\omega t} - \omega^2 e^{j\omega t}} = \frac{3 e^{j\omega t}}{e^{j\omega t} (6 - 5j\omega - \omega^2)} = \frac{3}{-\omega^2 - 5j\omega + 6}$$

$$\Rightarrow y(t) = \sum_{k=-\infty}^{+\infty} a_k \underbrace{H(jk\omega)}_{= b_k} e^{jk\omega t}$$

$$x(t) \xrightarrow{\text{FS}} a_k = d \cdot \text{Sinc}(k d) = \frac{2}{5} \text{Sinc}\left(\frac{2k}{5}\right)$$

duty cycle

$\boxed{\text{for } t \gg 0: y(t) = x(t) * h(t) \xleftrightarrow{\text{FT}} Y(j\omega) = \bar{X}(j\omega) H(j\omega)}$

$$a_0 = \frac{2}{5}$$

$$a_2 = \frac{2}{5} \text{Sinc}\left(\frac{4}{5}\right)$$

$$a_1 = \frac{2}{5} \text{Sinc}\left(\frac{2}{5}\right)$$

$$a_3 = \frac{2}{5} \text{Sinc}\left(\frac{6}{5}\right)$$

$$\Rightarrow y(t) = \frac{2}{5} H(0) e^{j0t} + \frac{2}{5} \left(\text{Sinc}\left(\frac{2}{5}\right) H(j\omega) e^{j\omega t} + \text{Sinc}\left(\frac{4}{5}\right) H(2j\omega) e^{j2\omega t} + \dots \right)$$