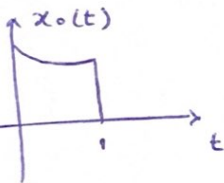


#1 $x_0(t) = \begin{cases} e^{-t} & ; 0 \leq t \leq 1 \\ 0 & ; \text{other} \end{cases} \Rightarrow \bar{X}(j\omega)$ سینه هارزیه

ابداً سینه فوریه سینه $x_0(t)$ رابست می آیدیم پس با استفاده از خواص سینه فوریه، سینه فوریه سینه سینه هارزیه می آیدیم.

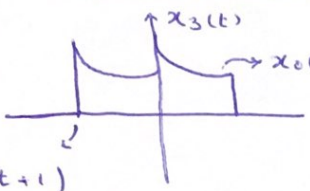


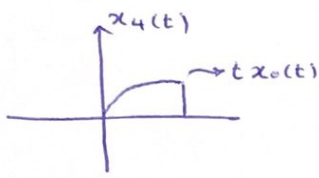
رابطه سینه فوریه: $x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \bar{X}(j\omega) e^{j\omega t} d\omega$
 رابطه سینه فوریه: $\bar{X}(j\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt$

$x_0(t) \xrightarrow{F} \bar{X}_0(j\omega) = \int_{-\infty}^{+\infty} x_0(t) e^{-j\omega t} dt = \int_0^1 e^{-t} e^{-j\omega t} dt = \int_0^1 e^{-(1+j\omega)t} dt$
 $= \frac{-1}{1+j\omega} e^{-(1+j\omega)t} \Big|_0^1 = \frac{1}{1+j\omega} (1 - e^{-(1+j\omega)})$

a) $x_1(t) = x_0(t) + x_0(-t) \xrightarrow{F} \bar{X}_1(j\omega) = \bar{X}_0(j\omega) + \bar{X}_0(-j\omega)$
 $\Rightarrow \bar{X}_1(j\omega) = \frac{1}{1+j\omega} (1 - e^{-(1+j\omega)}) + \frac{1}{1-j\omega} (1 - e^{-(1-j\omega)})$

b) $x_2(t) = x_0(t) - x_0(-t) \xrightarrow{F} \bar{X}_2(j\omega) = \bar{X}_0(j\omega) - \bar{X}_0(-j\omega)$
 $\Rightarrow \bar{X}_2(j\omega) = \frac{1}{1+j\omega} (1 - e^{-(1+j\omega)}) - \frac{1}{1-j\omega} (1 - e^{-(1-j\omega)})$

c)  $x_3(t) = x_0(t) + x_0(t+1) \xrightarrow{F} \bar{X}_0(j\omega) + \bar{X}_0(j\omega)e^{j\omega}$
 $\Rightarrow \bar{X}_3(j\omega) = \frac{1}{1+j\omega}(1-e^{-(1+j\omega)}) + \frac{1}{1+j\omega}(1-e^{-(1+j\omega)})e^{j\omega}$
 خاصیت منتقلی : $x(t-t_0) \xrightarrow{F} \bar{X}(j\omega)e^{-j\omega t_0}$ $= \frac{1}{j\omega+1}(1-e^{-(1+j\omega)}) \cdot [1+e^{j\omega}]$

d)  $x_4(t) = t x_0(t) \xrightarrow{F} \bar{X}_4(j\omega) = j \frac{d}{d\omega} \bar{X}_0(j\omega)$
 $\Rightarrow \bar{X}_4(j\omega) = j \frac{d}{d\omega} \left[\frac{1}{1+j\omega}(1-e^{-(1+j\omega)}) \right] = \frac{1 \cdot 2e^{-1-j\omega} - j\omega e^{-1-j\omega}}{(1+j\omega)^2}$
 خاصیت مشتق : $-jt x(t) \xrightarrow{F} \frac{d}{d\omega} \bar{X}(j\omega) \xrightarrow{\times j} t x(t) \xrightarrow{F} j \frac{d}{d\omega} \bar{X}(j\omega)$

#2 $x(t) = \frac{t^{n-1}}{(n-1)!} e^{-at} u(t) \xrightarrow{F} \bar{X}(j\omega) = \frac{1}{(a+j\omega)^n}$

$n=1$: $\frac{t^{1-1}}{(1-1)!} e^{-at} u(t) = 1 e^{-at} u(t) \xrightarrow{F} \bar{X}_0(j\omega) = \frac{1}{a+j\omega}$
 سیگنال واحد $x_0(t)$

$n=2$: $\frac{t^{2-1}}{(2-1)!} e^{-at} u(t) = t e^{-at} u(t) \xrightarrow{F} j \frac{d}{d\omega} \bar{X}_0(j\omega) = \frac{1}{(a+j\omega)^2}$
 طبق خاصیت مشتق زمانی $x_1(t)$

$n=3$: $\frac{t^2}{2} e^{-at} u(t) = \frac{t}{2} x_1(t) \xrightarrow{F} \frac{j}{2} \frac{d}{d\omega} \bar{X}_1(j\omega) = \frac{j}{2} \left[\frac{-2j(a+j\omega)}{(a+j\omega)^4} \right] = \frac{1}{(a+j\omega)^3}$

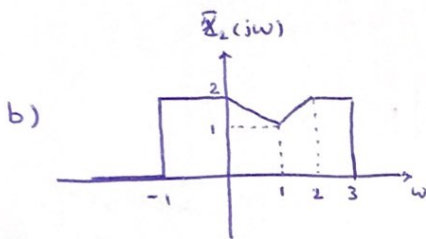
$\Rightarrow \frac{t^{n-1}}{(n-1)!} e^{-at} u(t) = \frac{t}{(n-1)} x_{n-1} \xrightarrow{F} \frac{j}{(n-1)} \frac{d}{d\omega} \bar{X}_{n-1}(j\omega) = j \left[\frac{-(n-1)j \cdot (a+j\omega)^{n-2}}{(n-1) \cdot (a+j\omega)^{2n-1}} \right]$
 $= \frac{e^{-at} u(t)}{(n-2)!} = x_{n-1}$

#3: سوال نمبر 3؟

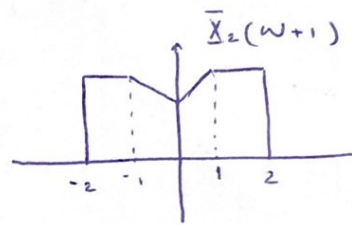
$$a) \bar{X}_1(j\omega) = \frac{2 \sin(3(\omega - 2\pi))}{\omega - 2\pi} \xleftrightarrow{F^{-1}} x_1(t) = ?$$

$\overset{= \alpha}{\omega - 2\pi}$

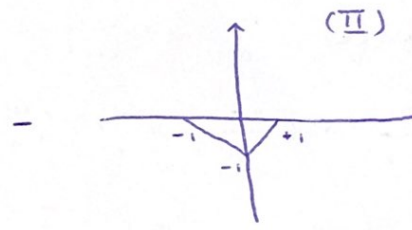
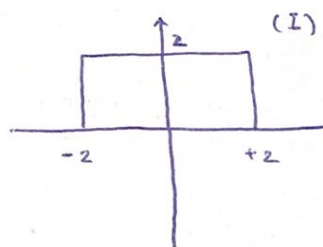
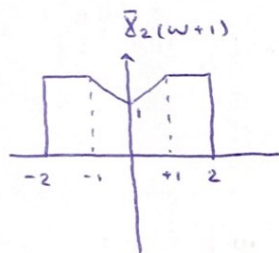
$$\Rightarrow \bar{X}_1(j\omega) = \frac{2 \sin 3\alpha}{\alpha} \xleftrightarrow{F^{-1}} x_1(t) = \begin{cases} 1 & ; |t| < 3 \\ 0 & ; \text{other} \end{cases} \xrightarrow{\alpha = \omega - 2\pi} x_1(t) = \begin{cases} e^{j2\pi t} & ; |t| < 3 \\ 0 & ; 0 \end{cases}$$



یہ طرز میں
شیفت کی جائے گی



Real and
even



$$\bar{X}_2(w+1) = (I) - (II)$$

$$(I) \xleftrightarrow{F^{-1}} \frac{4}{2\pi} \text{Sinc}\left(\frac{4}{2\pi}t\right) = \frac{2}{\pi} \text{Sinc}\left(\frac{2}{\pi}t\right)$$

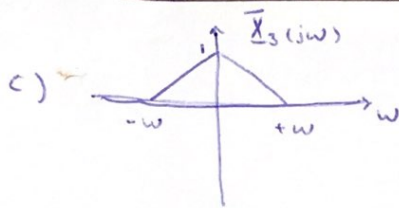
$$(II) \xleftrightarrow{F^{-1}} \frac{-2 \sin^2\left(\frac{t}{2}\right)}{\pi t^2}$$

$$\Rightarrow \bar{X}_2(w+1) \xleftrightarrow{F^{-1}} \frac{2}{\pi} \text{Sinc}\left(\frac{2t}{\pi}\right) + \frac{2 \sin^2\left(\frac{t}{2}\right)}{\pi t^2}$$

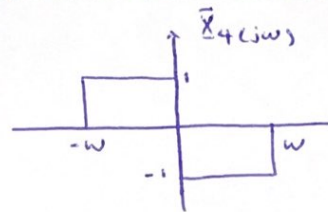
$$\Rightarrow \bar{X}_2(j\omega) = \left[\frac{2}{\pi} \text{Sinc}\left(\frac{2t}{\pi}\right) + \frac{2 \sin^2\left(\frac{t}{2}\right)}{\pi t^2} \right] e^{j\omega t}$$

$$\int_{-\infty}^{\infty} : \text{if } x(t) : \text{Real} \Leftrightarrow \begin{cases} x_{\text{even}}(t) \xleftrightarrow{F} \text{Re}\{\bar{X}(j\omega)\} \\ x_{\text{odd}}(t) \xleftrightarrow{F} j \text{Im}\{\bar{X}(j\omega)\} \end{cases}$$

$$\Rightarrow x(t) = x_{\text{even}}(t) + x_{\text{odd}}(t)$$



\Rightarrow



جواب: $\bar{X}(jw)$

$\xleftrightarrow{F} x(t) = \frac{w_c}{\pi} \text{Sinc}\left(\frac{w_c t}{\pi}\right)$

\Rightarrow

$\leftrightarrow x_4(t) = \frac{w}{2\pi} \text{Sinc}\left(\frac{wt}{2\pi}\right) \cdot e^{j\frac{w}{2}t}$

$\leftrightarrow x_4(t) = \frac{w}{2\pi} \text{Sinc}\left(\frac{wt}{2\pi}\right) \cdot e^{-j\frac{w}{2}t}$

$\Rightarrow x_4(t) = \frac{w}{2\pi} \text{Sinc}\left(\frac{wt}{2\pi}\right) \cdot e^{j\frac{w}{2}t} - \frac{w}{2\pi} \text{Sinc}\left(\frac{wt}{2\pi}\right) \cdot e^{-j\frac{w}{2}t} = \frac{w}{2\pi} \text{Sinc}\left(\frac{wt}{2\pi}\right) \left[e^{j\frac{w}{2}t} - e^{-j\frac{w}{2}t} \right]$

$= \frac{w}{2\pi} \text{Sinc}\left(\frac{wt}{2\pi}\right) \cdot 2 \cos\left(\frac{wt}{2}\right) = \frac{w}{\pi} \text{Sinc}\left(\frac{wt}{2\pi}\right) \cdot \cos\left(\frac{wt}{2}\right)$

$\Rightarrow \frac{d}{dw} \bar{X}_3(jw) = \bar{X}_4(jw) \xleftrightarrow{F} -jt x_4(t) \Rightarrow x_3(t) = -jt \frac{w}{\pi} \text{Sinc}\left(\frac{wt}{2\pi}\right) \cdot \cos\left(\frac{wt}{2}\right)$

جواب: \underline{b} من أجل \cos و \sin

#4 a)

$x(t) = t e^{-2t} u(t) \xleftrightarrow{F} \bar{X}(jw) = \frac{1}{(2+jw)^2}$

$h(t) = e^{-4t} u(t) \xleftrightarrow{F} H(jw) = \frac{1}{4+jw}$

جواب: $\begin{cases} x(t) = e^{-at} u(t) \xleftrightarrow{F} \bar{X}(jw) = \frac{1}{a+jw} \\ x(t) = t e^{-at} u(t) \xleftrightarrow{F} \bar{X}(jw) = \frac{1}{(a+jw)^2} \end{cases}$

$\Rightarrow y(t) = x(t) * h(t) \xleftrightarrow{F} Y(jw) = \bar{X}(jw) H(jw) = \frac{1}{(2+jw)^2} \times \frac{1}{4+jw} = \frac{1}{(2+jw)^2 (4+jw)}$

$\Rightarrow y(t) = F^{-1} \{ Y(jw) \}$

b) $\begin{cases} x(t) = e^{-t} u(t) \xrightarrow{F} \bar{X}(j\omega) = \frac{1}{1+j\omega} \\ h(t) = e^t u(-t) \xrightarrow{F} H(j\omega) = \frac{1}{1-j\omega} \end{cases}$
 $\hookrightarrow h(t) = x(-t) \xrightarrow{F} \bar{X}(-j\omega)$

$$\Rightarrow y(t) = x(t) * h(t) \xrightarrow{F} Y(j\omega) = \bar{X}(j\omega) H(j\omega) = \frac{1}{1+j\omega} * \frac{1}{1-j\omega} = \frac{1}{1+\omega^2}$$

$$\Rightarrow y(t) = F^{-1}\{Y(j\omega)\}$$

#5

if $x(t) = \cos(t) \longrightarrow$

$$\begin{cases} a) h_1(t) = u(t) \\ b) h_2(t) = -2\delta(t) + 5e^{-2t}u(t) \\ c) h_3(t) = 2te^{-t}u(t) \end{cases} \Rightarrow y_1(t) = y_2(t) = y_3(t)$$

$$x(t) = \cos(t) \xrightarrow{F} \bar{X}(j\omega) = \pi \delta(\omega - 1) + \pi \delta(\omega + 1)$$

a) $h_1(t) = u(t) \xrightarrow{F} H_1(j\omega) = \frac{1}{j\omega} + \pi\delta(\omega)$

$$\Rightarrow Y_1(j\omega) = \bar{X}(j\omega) H_1(j\omega) = (\pi \delta(\omega-1) + \pi \delta(\omega+1)) \cdot \left(\frac{1}{j\omega} + \pi \delta(\omega) \right)$$

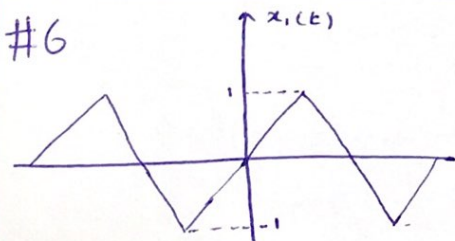
$$b) h_2(t) = -2\delta(t) + 5e^{-2t}u(t) \xrightarrow{F} H_2(j\omega) = -2 + \frac{5}{2+j\omega} = \frac{1-2j\omega}{2+j\omega}$$

$$\Rightarrow Y_2(j\omega) = \tilde{X}(j\omega) H_2(j\omega) = (\pi\delta(\omega-1) + \pi\delta(\omega+1)) \cdot \left(\frac{1-2j\omega}{2+j\omega} \right)$$

$$c) h_3(t) = 2te^{-t} u(t) \xrightarrow{F} H_3(j\omega) = \frac{2}{(1+j\omega)^2}$$

$$\Rightarrow Y_3(j\omega) = \bar{X}(j\omega) H_3(j\omega) = \left(\pi \delta(\omega-1) + \pi \delta(\omega+1) \right) \cdot \left(\frac{2}{(1+j\omega)^2} \right)$$

ب) ترکیب فعلی از h_1, h_2, h_3 خبری می باشد.



ب) $x_1(t)$: Real and odd $\Rightarrow \bar{X}_1(j\omega)$ محض خالص
 $\Rightarrow \text{Re}\{\bar{X}_1(j\omega)\} = 0$, $\text{Im}\{\bar{X}_1(j\omega)\} \neq 0$

طریق قیمت الف قیمت موهومی $\lambda(z)$ مندرجست (پ)

$$\text{jaw} \rightarrow \text{jaw} \quad \text{به اینها می‌گویند} \quad \text{ز} = \text{ع} \quad \text{نود نینال حقیقی می‌شود}$$

$$\text{ع} \quad \text{اسنای} \quad \text{موجودی خالص}$$

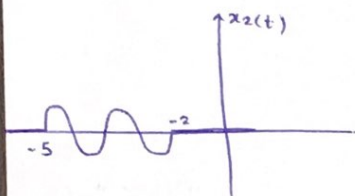
c) $\int_{-\infty}^{+\infty} \bar{X}(j\omega) d\omega = ?$ \Rightarrow ~~$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \bar{X}(j\omega) e^{j\omega t} d\omega$~~

~~$\bar{X}(j\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt$~~

سطح زیر منحنی است \Rightarrow چون سیگنال نرد است این فرض درست است

c) $\int_{-\infty}^{+\infty} \omega \bar{X}(j\omega) d\omega = ?$
 متن ~~در زمان~~

برقرار نیست



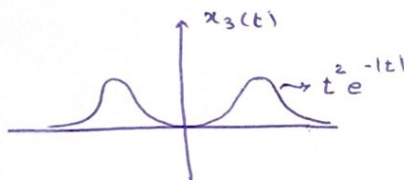
a) \times

b) \times

c) \checkmark : $x_2(t-3.5) \Rightarrow$ حقیقی در دمج $\alpha = -3.5$

d) \checkmark

e) \checkmark



a) \times

c) \checkmark

b) \checkmark

d) \times

c) $\alpha = 0$ به امان



a) \times

c) \checkmark

b) \times

d) \checkmark

c) $x_4(t+1) \Rightarrow \alpha = -1$

\rightarrow چون تبدیل فوریه $x_4(t)$ یک پالس مستطی است

$|H(j\omega)| = \begin{cases} \frac{1}{2000\pi} & ; |\omega| < 2000\pi \\ 4000\pi & ; 2000\pi \leq |\omega| \leq 3000\pi \\ 0 & ; \text{other} \end{cases}$

$\Delta H(j\omega) = -\Delta H(j\omega)$

$\Delta H(j\omega) = \begin{cases} \frac{\pi}{2} & ; 0 < \omega < 2000\pi \\ \frac{\omega}{6000} & ; 2000\pi \leq \omega \leq 3000\pi \\ 0 & ; \omega > 3000\pi \end{cases}$

$x(t) = \frac{1}{2} + 2\sin(1000\pi t + \frac{\pi}{4}) - 3\cos(2500\pi t - \frac{\pi}{4}) + 4\sin(4000\pi t)$

$\bar{X}(j\omega) = (\frac{1}{2} \times 2\pi \delta(\omega)) + \left[\frac{2\pi}{j} \delta(\omega - 1000\pi) + \frac{2\pi}{j} \delta(\omega + 1000\pi) \right] e^{j\frac{\pi}{4}t}$

$+ \left[-3\pi (\delta(\omega - 2500\pi) + \delta(\omega + 2500\pi)) e^{-j\frac{\pi}{4}t} \right] + \left[4\pi (\delta(\omega - 4000\pi) - \delta(\omega + 4000\pi)) \right]$

$Y(j\omega) = \bar{X}(j\omega) H(j\omega) \Rightarrow |Y(j\omega)| = \begin{cases} \frac{1}{2000\pi} \bar{X}(j\omega) & ; |\omega| < 2000\pi \\ 4000\pi \bar{X}(j\omega) & ; 2000\pi \leq |\omega| \leq 3000\pi \\ 0 & ; \text{other} \end{cases}$