

$$n(x, y, z, t)$$

$$\frac{dn}{dt}, \quad \frac{dP}{dt}$$

دسته بارها : حرارت، تولید، بازتریب
متغیرات

$$\frac{dn}{dt} = \frac{\partial n}{\partial t} \cdot \frac{dt}{dt} + \frac{\partial n}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial n}{\partial y} \cdot \frac{dy}{dt} + \frac{\partial n}{\partial z} \cdot \frac{dz}{dt}$$

$$= \frac{\partial n}{\partial t} + \frac{\partial n}{\partial x} \cdot v_x + \frac{\partial n}{\partial y} \cdot v_y + \frac{\partial n}{\partial z} \cdot v_z$$

$$\vec{\nabla} = \frac{\partial n}{\partial x} \hat{i} + \frac{\partial n}{\partial y} \hat{j} + \frac{\partial n}{\partial z} \hat{k}$$

$$\boxed{\frac{dn}{dt} = \frac{\partial n}{\partial t} + \vec{\nabla} \cdot \vec{\nabla} n}$$

مغاره سوچنی

عنی

جذب و خروج

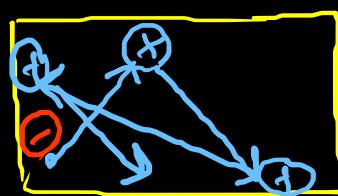
E_f, E_i, P, n

حریان و رسالت

حرکت بارها

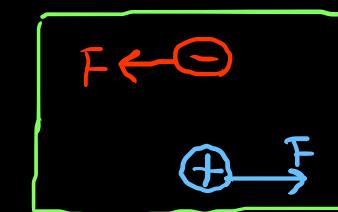
$\times \sigma$ سلسله
 $\times \mu$ کاهش تحریر
D نفوذ

به دلیل



$$\langle \vec{v} \rangle = 0 \quad J = 0$$

میدان الکتری



$$\langle v_n \rangle \neq 0 \quad J_n \neq 0$$

$$\langle v_p \rangle \neq 0 \quad J_p \neq 0$$

اصل بعای نهاد

$$F = ma = m \frac{dv}{dt} = \frac{d(mv)}{dt} = \frac{dP}{dt}$$

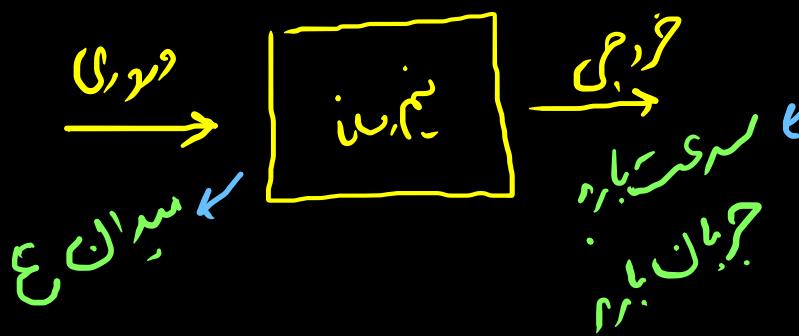
$$F = \epsilon q$$

$$\boxed{\frac{dP}{dt}} = \frac{dP}{dt}_{\text{gain}} + \frac{dP}{dt}_{\text{loss}}$$

$$= \epsilon q + -\frac{\langle P \rangle}{2}$$

سے زمان مورکٹر خروج

$$\rightarrow \langle P \rangle = \epsilon q Z N$$



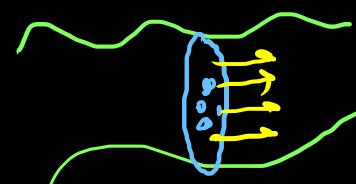
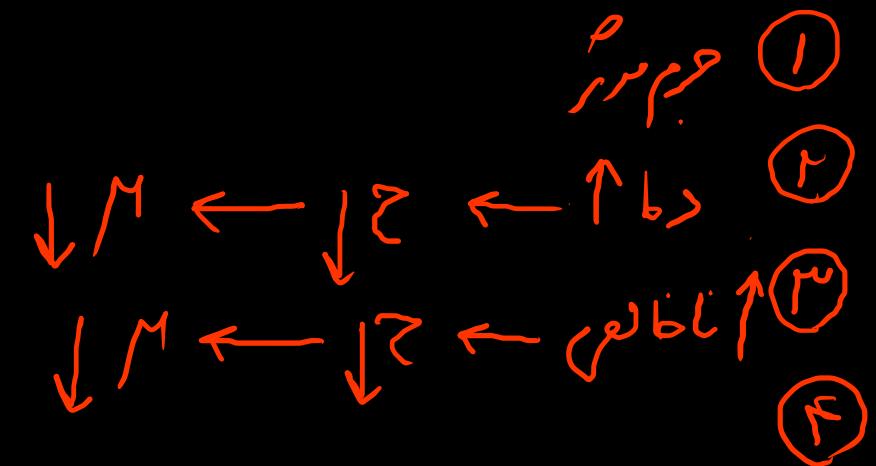
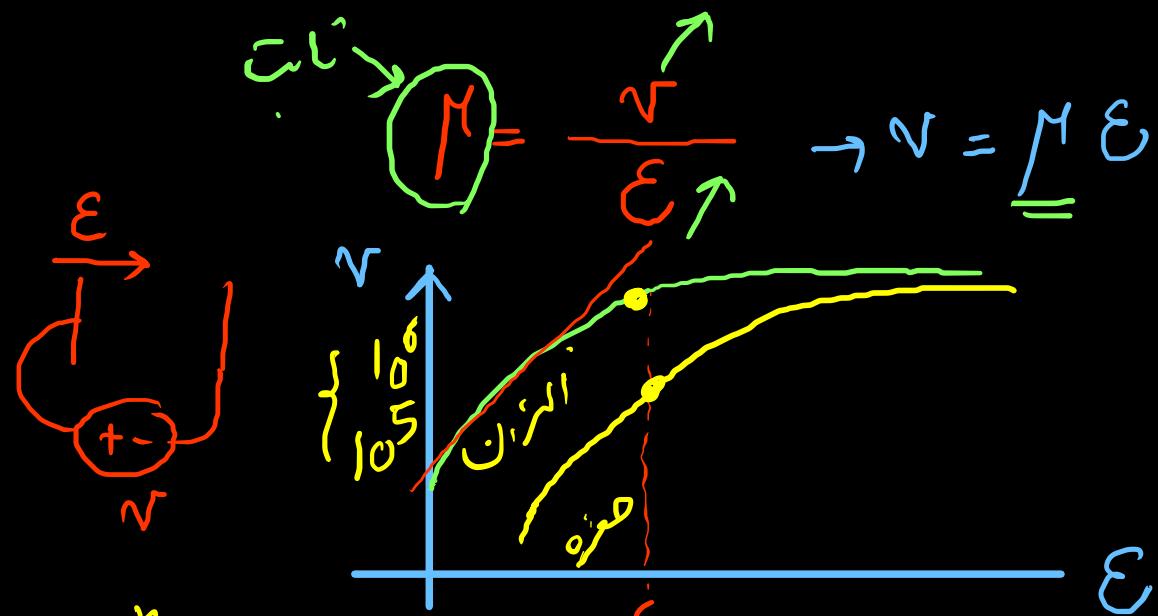
$$\langle P \rangle = m^* \langle v \rangle = \epsilon q Z$$

$$\frac{v}{\epsilon} = \frac{current}{m^*} = \mu$$

$$\frac{J}{\epsilon} = \sigma$$

$$\langle v \rangle = \frac{\epsilon Z}{m^*}$$

$$\left\{ \begin{array}{l} M_n = \frac{|q|z}{m_n^*} \\ M_P = \frac{|q|z}{m_P^*} \end{array} \right.$$



$$J = \sum_{i=1}^n v_i \quad J = \bar{v} e^{\frac{eT}{k}}$$

$$\bar{v} = n \times \sum_{i=1}^n \frac{v_i}{h} = n \langle v \rangle$$

$$J = n q \langle v \rangle \quad , \quad \langle v \rangle = E/M$$

$$J = n q M$$

$$\left\{ \begin{array}{l} J_n = n q M_n \\ J_P = P q M_P \end{array} \right.$$

$$J = J_n + J_P = q (n_0 M_n + P_0 M_P) E$$

$$J = \sigma E \rightarrow \boxed{\sigma = q (n_0 M_n + P_0 M_P)}$$

$$\text{J}_{\text{drift}} = J_n + J_p$$

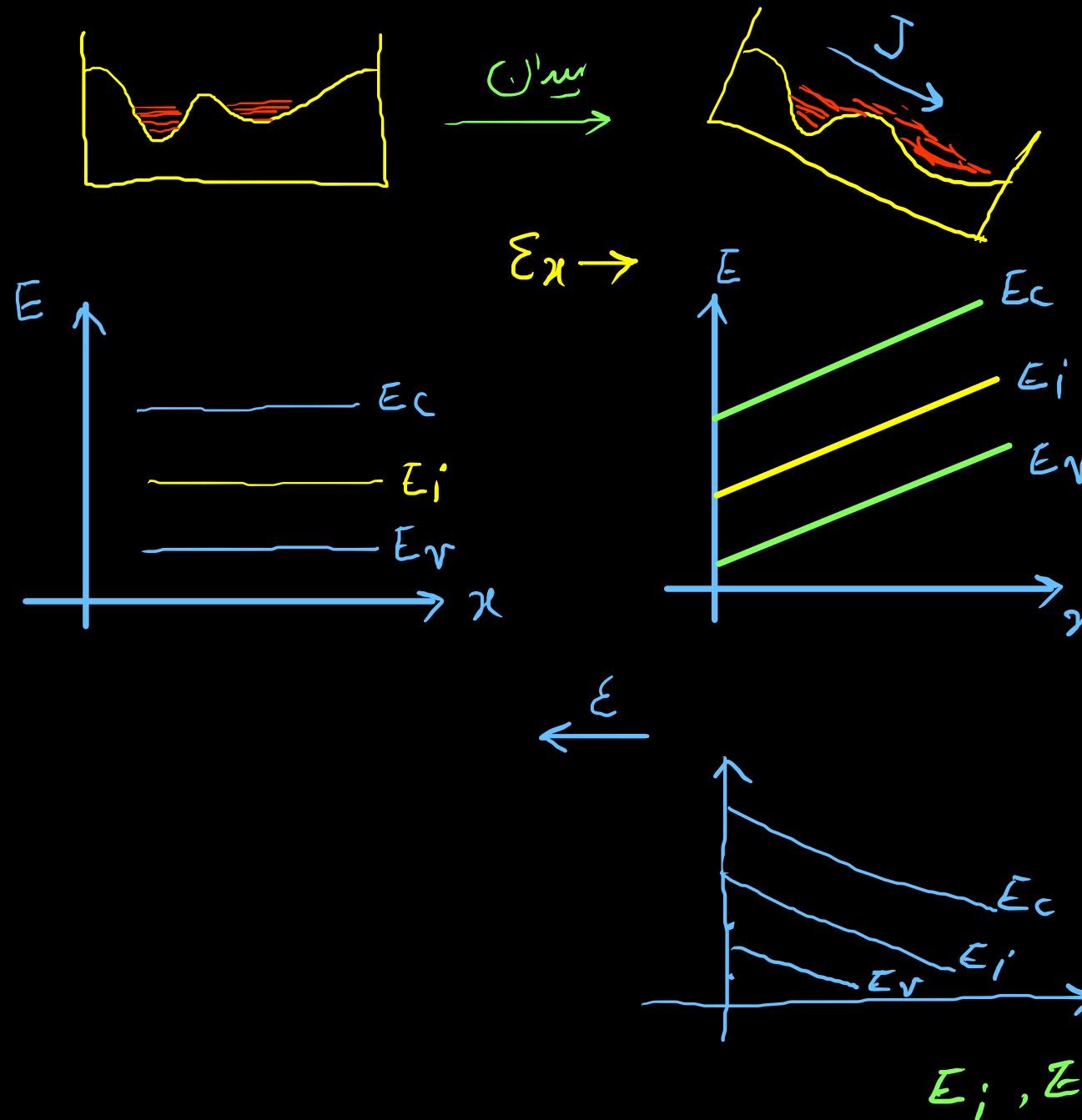
$$\underline{\sigma} = n_0 q \mu_n + p_0 q \mu_p$$

$$R = f \frac{l}{A}, \quad \sigma = \frac{1}{f}$$

$$\begin{aligned} J_n &= n_0 q \mu_n \epsilon \\ J_p &= p_0 q \mu_p \epsilon \end{aligned}$$

$$\begin{aligned} \mu &= \frac{\nu}{\epsilon} \\ \sigma &= \frac{J}{\epsilon} \end{aligned}$$

$$\boxed{n_0, p_0, \mu_n, \mu_p} \rightarrow \underline{\sigma} = \underline{l} \underline{\frac{1}{f}}$$



$$\mathcal{E} = -\nabla V = -\frac{\partial}{\partial x} V$$

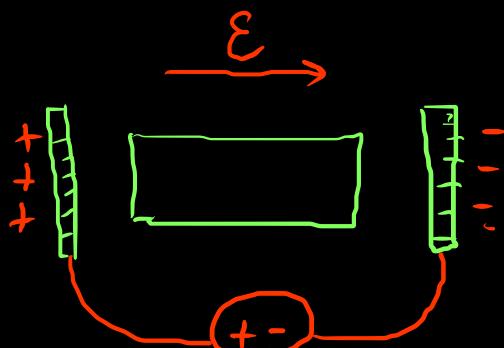
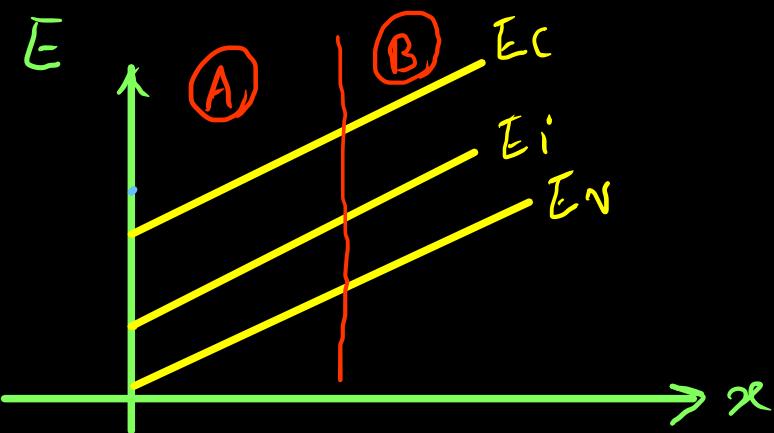
$$PE = E_{ref} - E_v$$

$$PE = E_c - E_{ref} = -qV_x$$

$$V_x = -\frac{1}{q} (E_c - E_{ref})$$

$$\left\{ \begin{array}{l} \mathcal{E}_x = -\frac{\partial}{\partial x} \left[-\frac{1}{q} (E_c - E_{ref}) \right] \\ \mathcal{E}_x = \frac{1}{q} \frac{\partial}{\partial x} E_c \\ \mathcal{E}_x = \frac{1}{q} \frac{\partial}{\partial x} E_v \end{array} \right.$$

اعمال میان امدادهای جمجمه نوارهای امدادهای سود
 E_i, E_v, E_c

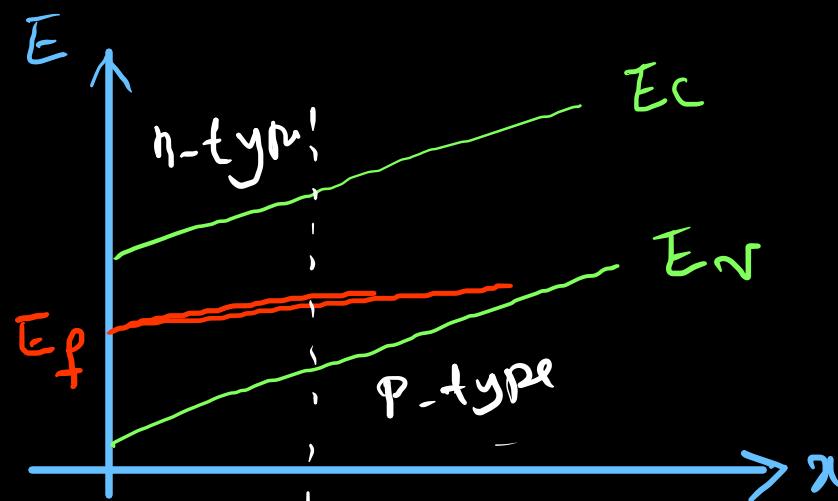


$$R_{AB} = N_A f_A(E) \times N_B (1 - f_B(E))$$

$$R_{BA} = N_B f_B(E) \times N_A (1 - f_A(E))$$

$$J = 0 \rightarrow R_{AB} = R_{BA}$$

$$N_A N_B f_A - N_A N_B f_A f_B = N_A N_B f_B - N_A N_B f_A f_B$$



$$f_A(E) = f_B(E)$$

$$\frac{1}{1 + e^{\frac{E - E_{FA}}{k_B T}}} = \frac{1}{1 + e^{\frac{E - E_{FB}}{k_B T}}}$$

$E_{FA} = E_{FB}$

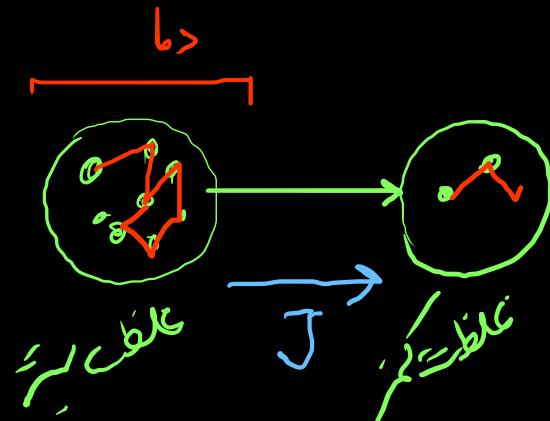
ترابعی می باشد.

فرموده

$$\frac{J}{dr} = \frac{J_N}{dr} + \frac{J_P}{dr}$$

$$J_N = n_0 q \mu_n E$$

$$J_P = P_0 q \mu_P E$$

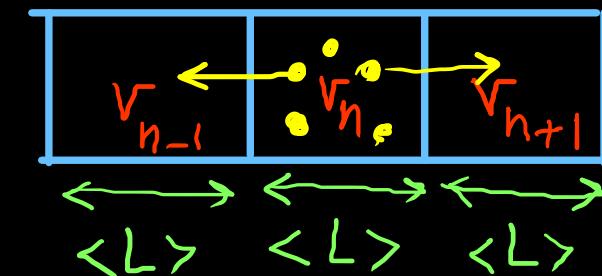


$$\frac{J}{dr_{\text{diffusion}}} = ?$$

$$J = \nabla e$$

Diffusion

- نفود



$$J = \frac{\frac{1}{2} n \times A_n \times \langle L \rangle}{z}$$

$$v_n \rightarrow v_{n+1} = \frac{1}{2} n_n \frac{\langle L \rangle}{z}$$

$$v_n \leftarrow v_{n+1} = \frac{1}{2} n_n \frac{\langle L \rangle}{z} - \frac{1}{2} n_{n+1} \frac{\langle L \rangle}{z} = \frac{1}{2} (n_n - n_{n+1}) \frac{\langle L \rangle}{z} = \frac{1}{2} \left[-\langle L \rangle \frac{\partial n}{\partial x} \right] \frac{\langle L \rangle}{z} =$$

$$J = -\frac{1}{2} \frac{\langle L \rangle^2}{z} \nabla n = -D \nabla n$$

$$\frac{\partial n}{\partial x} = \frac{n_{n+1} - n_n}{\langle L \rangle} = \frac{n_n - n_{n+1}}{\langle L \rangle} \rightarrow n_n - n_{n+1} = -\langle L \rangle \frac{\partial n}{\partial x}$$

$$J_n = -D_n \nabla n$$

$$J_p = -D_p \nabla p$$

$$J_n = -q J_n = q D_n \nabla n$$

$$J_p = +q J_p = -q D_p \nabla p$$

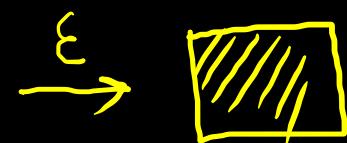
$$\left\{ \begin{array}{l} J_{\text{diffusion}} = J_{\text{drift}} + J_{\text{diff}} \\ J_n = q D_n \nabla n \\ J_p = -q D_p \nabla p \end{array} \right.$$

$$J_{\text{drift}} = J_n + J_p$$

$$J_{\text{diff}} = J_n + J_p$$

$$\boxed{J = J_{\text{drift}} + J_{\text{diff}}}$$

وطاب اسْتَسْنَ:



$$J_p = 0$$

$$J_n = 0$$

$$J_n = J_{n_{\text{drift}}} + J_{n_{\text{diff}}} = n q \mu_n \mathcal{E} + q D_n \nabla n = 0$$

$$\rightarrow \mathcal{E} = -\frac{D_n \nabla n}{n \mu_n}$$

$$\mathcal{E} = \frac{D_p \nabla p}{\mu_p} = \frac{\nabla(-\varepsilon_i)}{k_B T} = -\frac{n}{k_B T} \varepsilon_q$$

$$\nabla n = \nabla \left(n_i e^{\frac{E_f - \varepsilon_i}{k_B T}} \right) = \frac{n_i}{k_B T} \nabla (E_f - \varepsilon_i) e^{\frac{E_f - \varepsilon_i}{k_B T}}$$

$$\left\{ \begin{array}{l} \mathcal{E} = -\frac{D_n \nabla n}{n \mu_n} \\ \nabla n = -\frac{n}{k_B T} \varepsilon_q \end{array} \right. \rightarrow \boxed{\frac{D_n}{\mu_n} = \frac{k_B T}{q}}$$

$$\boxed{\frac{D_p}{\mu_p} = \frac{k_B T}{q}}$$

$$\frac{dn}{dt} = \frac{\partial n}{\partial t} + \frac{1}{q} \vec{\nabla} \cdot \vec{J}$$

$$\frac{dn}{dt} = \frac{\partial n}{\partial t} + \vec{\nabla} \cdot \vec{\nabla} n$$

جواب مکانیکی

$$v = \sum v_i = n \langle v \rangle$$

$$J = q v$$

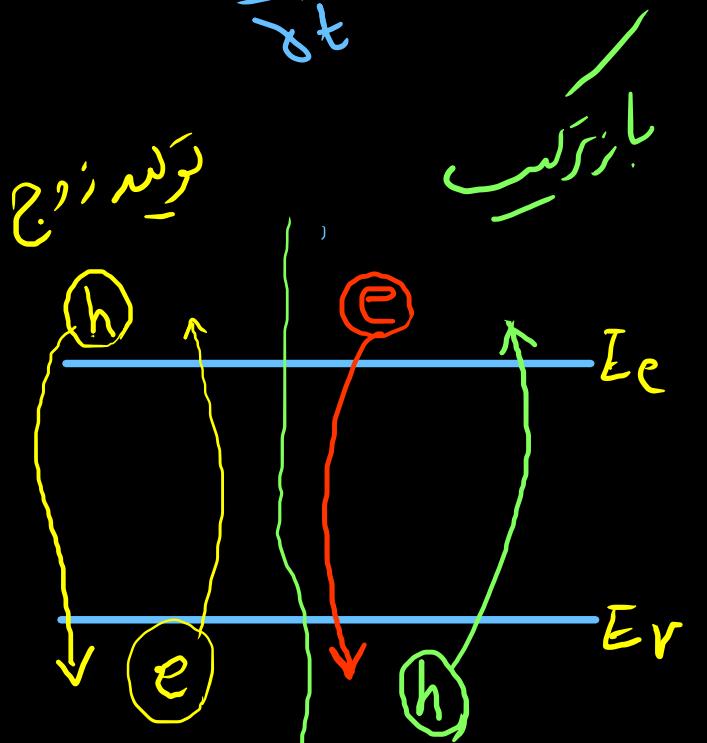
$$J = n q \langle v \rangle$$

$$\frac{1}{q} (\vec{\nabla} \cdot q \vec{v})$$

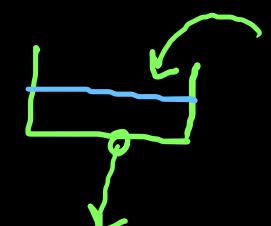
$$\frac{1}{q} (\vec{\nabla} \cdot \vec{J})$$

$$\vec{\nabla} = \frac{\partial}{\partial x} i + \frac{\partial}{\partial y} j + \frac{\partial}{\partial z} k$$

تولید مادوس با ربط



$$\left\{ \begin{array}{l} r = \alpha_r n_0 p_0 = \alpha_r n_i^2 \\ g_{\text{thermal}} = r = \alpha_r n_0 p_0 = \alpha_r n_i^2 \end{array} \right.$$

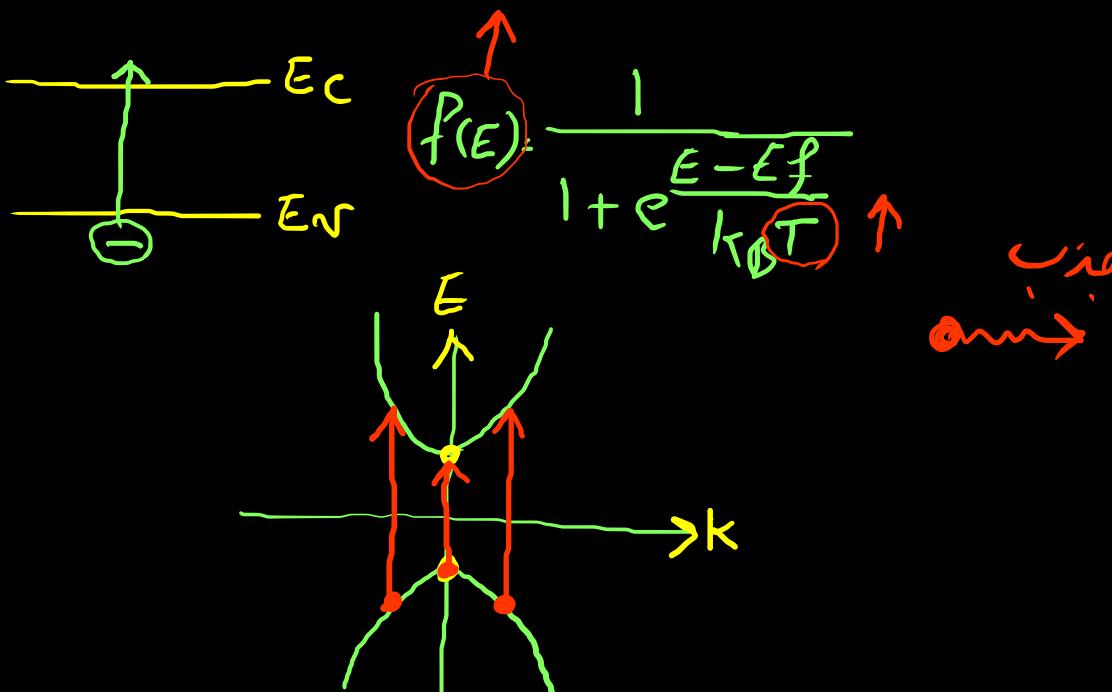


لوری

$$\left\{ \begin{array}{l} \frac{dn}{dt} = \frac{\partial n}{\partial t} - \frac{1}{q} \nabla \cdot J_n \\ \frac{dP}{dt} = \frac{\partial P}{\partial t} + \frac{1}{q} \nabla \cdot J_P \end{array} \right.$$

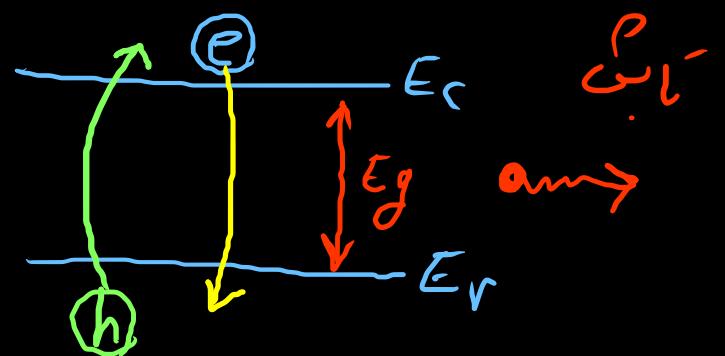
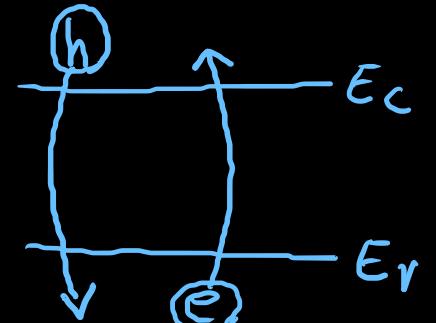
$$\frac{dn}{dt} = g_{\text{thermal}} = r = \alpha_r n_0 P_0 = \alpha_r n_i^2$$

$$\frac{dP}{dt} = g_{\text{thermal}} = r$$



$$r = g \leftarrow r_i \leftarrow T : \text{لوری} n_i$$

۱ خراشهای سیم (مانه بمانه)

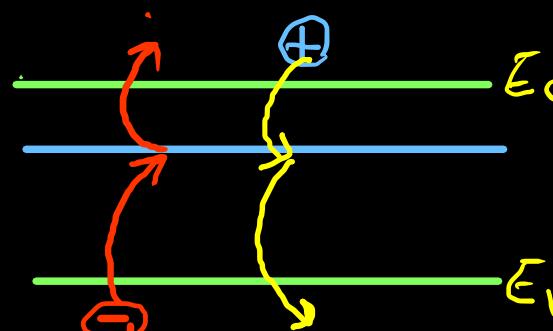
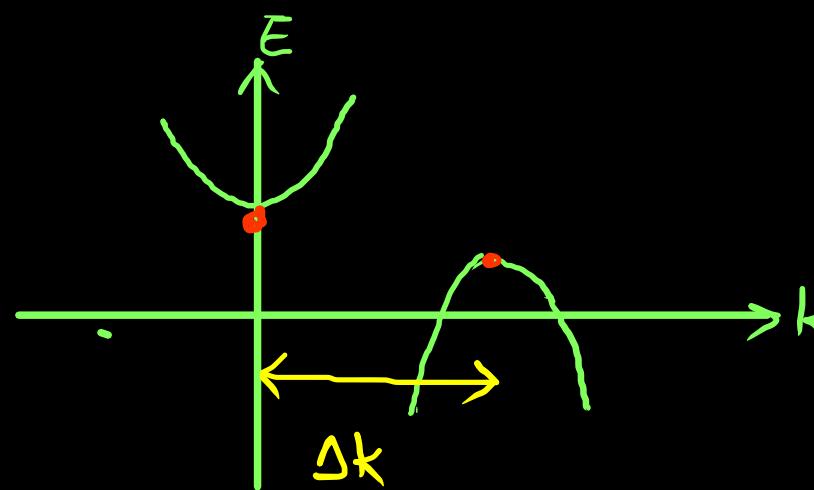


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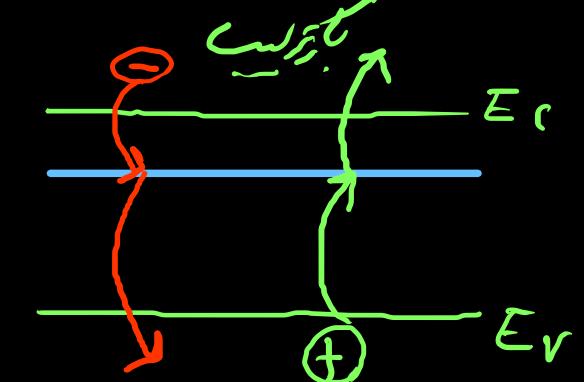
زاید های غریب میم:

مرکز نص - اورد

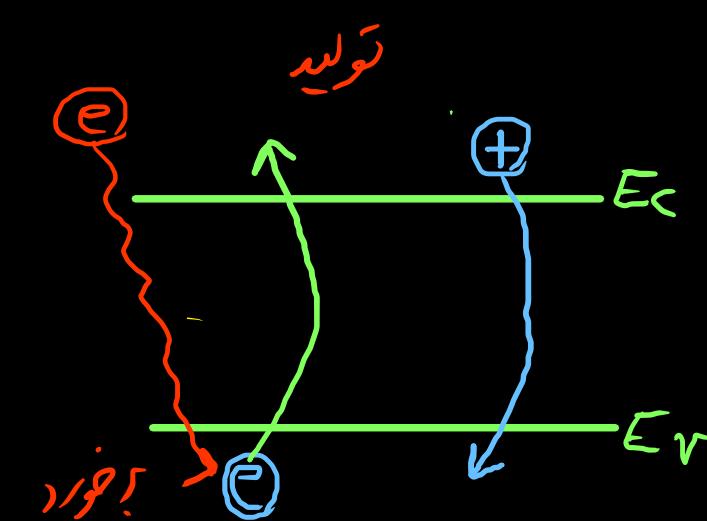
تولید



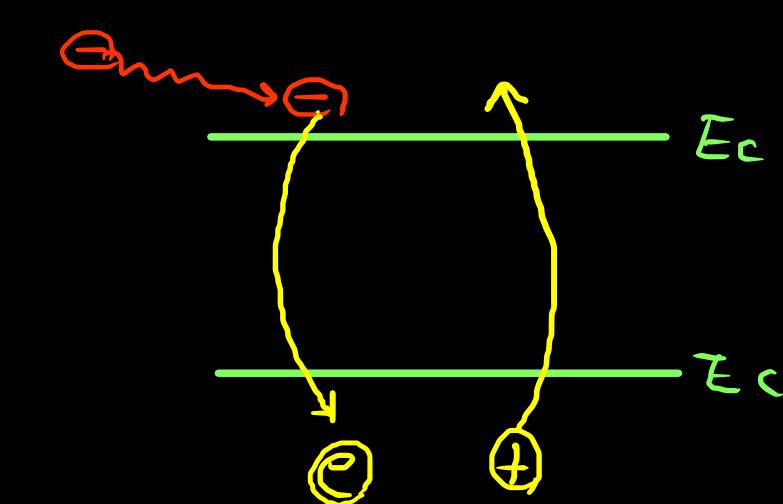
ترانزیس



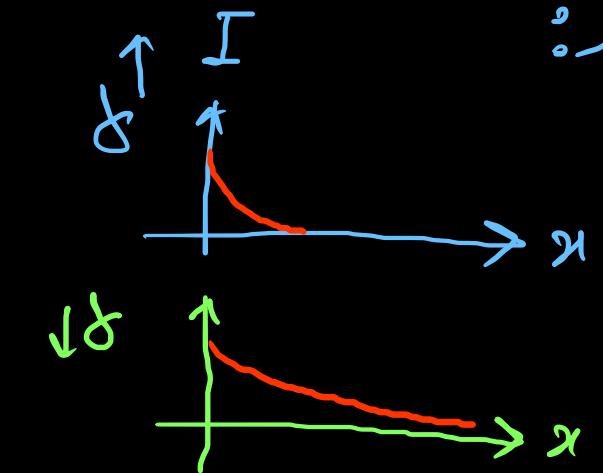
تولید



برخورد

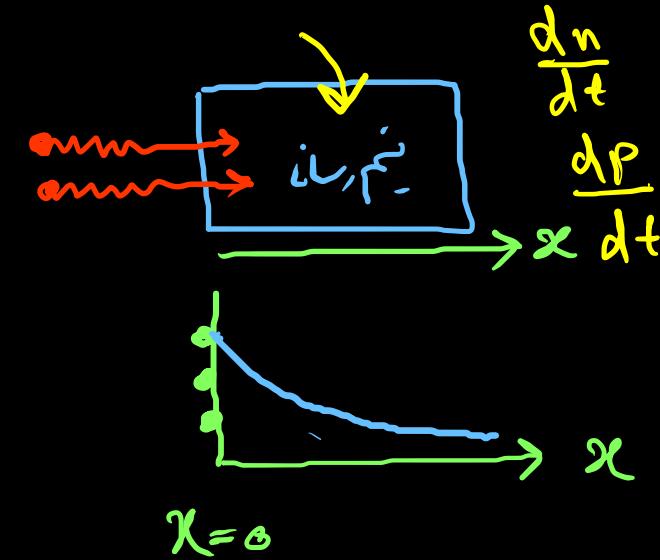


جذب نور:



$$I = I_0 e^{-\delta x}$$

کسر فوتون های ایجاد شده



$$\frac{dn}{dt}, \frac{dP}{dt} \quad h^+ + \bar{e} \longleftrightarrow C$$

$$\frac{dn}{dt} = \frac{dP}{dt} = \text{خرج نرمل} - \text{خرج بازتاب} = g - r$$

$$\left\{ \begin{array}{l} g - r = \frac{dn}{dt} = \frac{\partial n}{\partial t} - \frac{1}{q} \nabla \cdot J_n \\ g - r = \frac{dP}{dt} = \frac{\partial P}{\partial t} + \frac{1}{q} \nabla \cdot J_P \end{array} \right.$$

$$\left\{ \begin{array}{l} J_n = J_{n,\text{diff}} + J_{n,\text{drift}} \\ J_P = J_{P,\text{diff}} + J_{P,\text{drift}} \end{array} \right.$$

$$g = g_{\text{thermal}} + g_{\text{optical}}$$

① دلایل

$$n(x, y, z, t) \rightarrow n(x, t)$$

$$p(x, y, z, t) \rightarrow p(x, t)$$

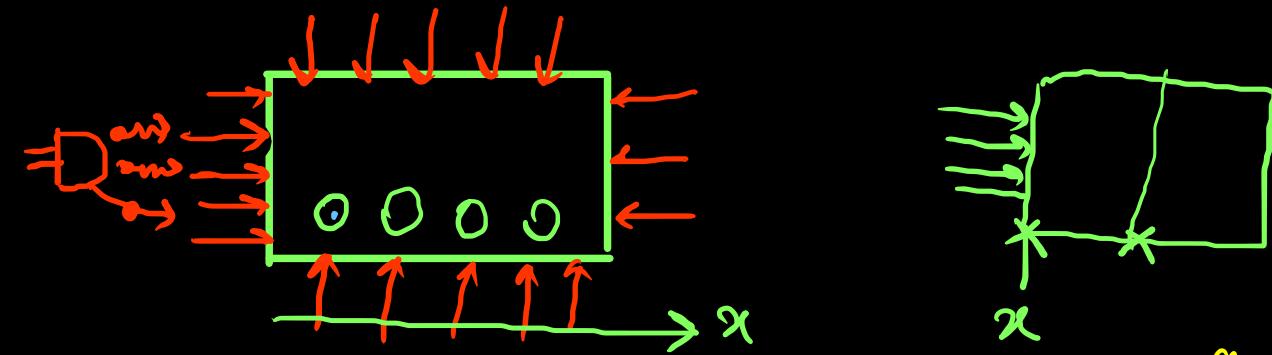
$$\frac{dn}{dt} = \frac{dp}{dt} = \frac{\partial n}{\partial t} - \frac{1}{q} \nabla \cdot \vec{J}$$

inj

$$\begin{cases} n(t) = \overline{n_0} + \overline{\delta n(t)} \\ p(t) = \overline{p_0} + \overline{\delta p(t)} \\ \delta n(t) = \delta p(t) \end{cases}$$

$$\begin{aligned} \frac{d}{dt} \delta n(t) &= \alpha_r n_i^2 - \alpha_r (\overline{n_0} + \delta n(t))(\overline{p_0} + \delta p(t)) \\ &= \cancel{\alpha_r n_i^2} - \cancel{\alpha_r n_0 p_0} - \alpha_r n_0 \delta p(t) - \alpha_r p_0 \delta n(t) - \alpha_r \delta n(t) \delta p(t) \end{aligned}$$

$$\begin{aligned} \frac{d}{dt} \delta n(t) &= -\alpha_r ((\overline{n_0} + \overline{p_0}) \delta n(t) + \cancel{\delta_n^2(t)}) \\ &\quad \underbrace{(\overline{n_0} + \overline{p_0})}_{\delta n \cdot \delta n} \delta n \end{aligned}$$



$$g_{\text{channel}} + g_{\text{opt}}$$

$$\begin{aligned} \frac{dn}{dt} &= \frac{d}{dt} (\overline{n_0} + \overline{\delta n(t)}) = \frac{\partial n}{\partial t} = g - r \\ \frac{d}{dt} \delta n(t) &= \alpha_r n_i^2 - \alpha_r n p \end{aligned}$$

فرض سریعه
low-level inj.

$\rightarrow \delta n, \delta p \ll \overline{n_0} + \overline{p_0}$

$\delta n^2, \delta p^2 \ll \delta n (\overline{n_0} + \overline{p_0})$

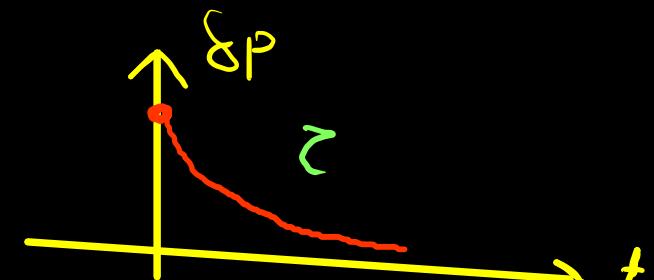
$$\begin{cases} \frac{d\delta_n(t)}{dt} = -\alpha_r(n_0 + P_0) \delta_n(t) \\ \frac{d\delta_P(t)}{dt} = -\alpha_r(n_0 + P_0) \delta_P(t) \end{cases} \rightarrow \begin{aligned} \delta_n(t) &= \delta_n(t=0) e^{-\frac{t}{\tau}} & \tau &= \frac{1}{\alpha_r(n_0 + P_0)} \\ \delta_P(t) &= \delta_P(t=0) e^{-\frac{t}{\tau}} \end{aligned}$$

$$n(t) = n_0 + \overset{\circ}{\delta_n(t)} \approx n_0$$

$$P(t) = P_0 + \overset{\circ}{\delta_P(t)} \approx \delta_P(t)$$

$\leftarrow \tau_p = \frac{1}{\alpha_r n_0}$ $\leftarrow n_0 \gg P_0 : n$ معنی

$$\delta_P(t) = \delta_P(t=0) e^{-\frac{t}{\tau_p}}$$

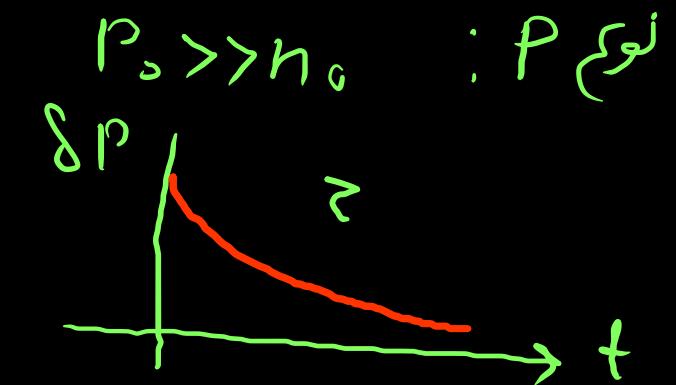


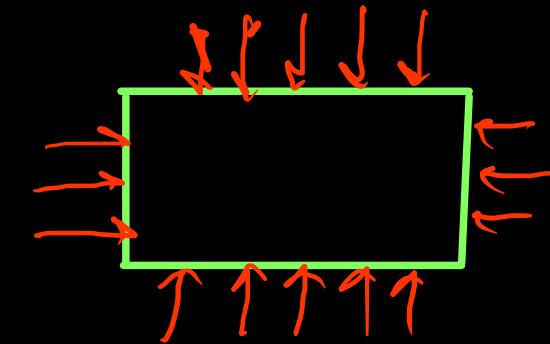
$$n(t) = n_0 + \delta_n(t) \approx \delta_n(t)$$

$$P(t) = P_0 + \delta_P(t) \approx P_0$$

$$\tau_n = \frac{1}{\alpha_r P_0}$$

for $\tau \rightarrow \delta_n(t) = 0$
 $\delta_P(t) = 0$





(Steady state) حالت ثابت $\frac{dn}{dt} = \frac{dp}{dt} = 0$

$$\frac{dn}{dt} = g_{opt} + g_{th} - r = 0$$

$$\frac{dn}{dt} = g_{opt} - r = g_{opt} + g_{th} - r$$

$$0 = g_{opt} + \alpha_r n_i^2 - \alpha_r n(t) p(t)$$

$$0 = g_{opt} + \alpha_r n_i^2 - \alpha_r (n_0 + \delta n(t)) (P_0 + \delta p(t))$$

$$0 = g_{opt} - \alpha_r [(n_0 + P_0) \delta n(t) + \cancel{\delta n(t)}] \quad \text{low inj}$$

$$0 = g_{opt} - \alpha_r (n_0 + P_0) \delta n(t) \rightarrow \delta n(t) = \frac{g_{opt}}{\alpha_r (n_0 + P_0)} = g_{opt} \zeta$$

$$\boxed{\delta n(t) = \delta p(t) = g_{opt} \zeta}$$

$$\zeta = \frac{1}{\alpha_r (n_0 + P_0)}$$

n_0, P_0 تغیرات میزان نور سبل میان برابر تغیر داده اند \rightarrow اندیشه Equilibrium : تغایر حریق \rightarrow نور با معنی Steady State تغایر با معنی ثابت

Equilibrium

 E_C E_F E_V n_0, P_0, E_F $P_0 = n_i e^{\frac{E_i - E_F}{k_B T}}$ $n_0 = n_i e^{\frac{E_F - E_i}{k_B T}}$

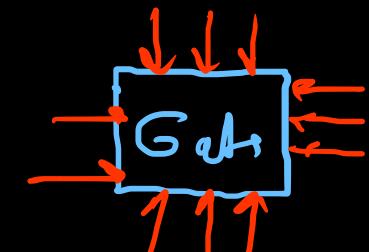
$$\left\{ \begin{array}{l} P_0 = n_i e^{\frac{E_i - E_F}{k_B T}} \\ n_0 = n_i e^{\frac{E_F - E_i}{k_B T}} \end{array} \right. \rightarrow \begin{array}{l} P = P_0 + \delta P = n_i e^{\frac{E_i - E_F}{k_B T}} + \delta P = n_i e^{\frac{E_i - E_F}{k_B T}} \\ n = n_0 + \delta n = n_i e^{\frac{E_F - E_i}{k_B T}} + \delta n = n_i e^{\frac{E_F - E_i}{k_B T}} \end{array}$$

E_C
 E_{Fn}
 E_{FP}
 E_V

$$E_g = 1.43 \text{ eV}, N_a = 10^{14} \text{ cm}^{-3}, \tau_n = 10^{-8} \text{ sec}, n_i = 10^6 \text{ cm}^{-3}, g_{opt} = 10^{20} \text{ EH} \text{ cm}^3 \text{ s}^{-1}, \text{ GaAs}$$

$$\text{P-type } N_a = 10^{14} \gg 10^6 \rightarrow P_0 = N_a = 10^{14} \text{ cm}^{-3}$$

$$n_0 = \frac{n_i^2}{P_0} = \frac{(10^6)^2}{10^{14}} = 10^{-2} \text{ cm}^{-3}$$



$$\alpha_r = \frac{1}{\alpha_r(n_0 + P_0)} \rightarrow \alpha_r = \frac{1}{\tau(n_0 + P_0)} = \frac{1}{10^{-8}(10^{14} + 10^{-2})} = 10^6 \text{ cm}^{-3} \text{ s}^{-1}$$

$$g_{opt} = \alpha_r (\delta n(n_0 + P_0) + \delta n^2) \rightarrow \alpha_r \delta n^2 + \alpha_r (n_0 + P_0) - g_{opt} = 0$$

$$\rightarrow \alpha_r \delta n^2 + \frac{1}{2} \delta n - g_{opt} = 0 \quad 10^6 \delta n^2 + 10^8 \delta n - 10^{20} = 0 \quad \delta n = \delta P = 10^{12} \text{ cm}^{-3}$$

 P_0, n_0 $\delta P, \delta n$ F_P, F_n

نور سوخته - جذب

100W

$$S_n = 10^{12} \text{ cm}^{-3} \ll n_{\text{tot}} P_s = 10^{14} \rightarrow \text{جزء من جزء} \quad \delta_n = g_{\text{opt}} \zeta = 10^{20} \times 10^{-8} = 10^{12}$$

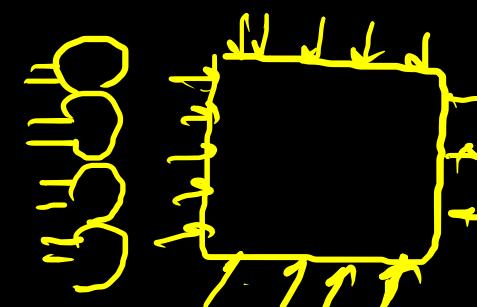
∴ $n = n_i e^{\frac{F_n - E_i}{k_B T}} \rightarrow F_n - E_i = -k_B T \ln\left(\frac{n_i}{n}\right) = -k_B T \ln\left(\frac{10^6}{10^{-2} + 10^{12}}\right) = 0.35 \text{ eV}$

$$P = n_i' e^{\frac{E_i - F_P}{k_B T}} \rightarrow E_i - F_P = k_B T \ln\left(\frac{10^{14} + 10^{12}}{10^6}\right) = 0.47 \text{ eV}$$

∴ $g_{\text{opt}} = 10^{20} \text{ cm}^{-3} \text{s}^{-1} \Rightarrow 10^{20} \frac{\text{EHP}}{\text{cm}^3 \cdot \text{s}} \times \frac{1.43 \text{ eV}}{\text{EHP}} \times 1.6 \times 10^{-19} \frac{\text{J}}{\text{eV}}$



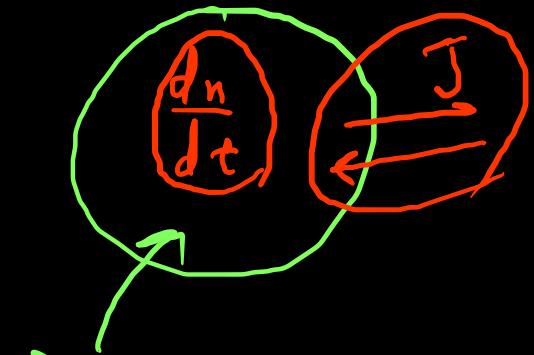
power = $23 \frac{\text{Watt}}{\text{cm}^{-3}}$
 $\frac{23}{5} \approx 5 \quad \approx 8$



جیسے تھا

$$g - r = \frac{dn}{dt} = \frac{\partial n}{\partial t} - \frac{1}{q} \nabla \cdot \bar{J}_n$$

$$g - r = \frac{dp}{dt} = \frac{\partial p}{\partial t} + \frac{1}{q} \nabla \cdot J_p$$



$$\begin{cases} \frac{\partial n}{\partial t} = \left(\frac{dn}{dt} \right) + \frac{1}{q} \nabla \cdot J_N = \underbrace{\alpha_r n_i^2 + g_{opt}}_g - \underbrace{\alpha_r n(x,t) p(x,t)}_r + \frac{1}{q} \nabla \cdot J_n \\ \frac{\partial p}{\partial t} = \frac{dp}{dt} - \frac{1}{q} \nabla \cdot J_P = \underbrace{\alpha_r n_i^2 + g_{opt}}_g - \underbrace{\alpha_r n(x,t) p(x,t)}_r - \frac{1}{q} \nabla \cdot J_P \end{cases}$$

خوبی کریں → $g - r = \alpha_r n_i^2 + g_{opt} - \alpha_r (n_0 + \delta n) (p_0 + \delta p)$
 $g - r = g_{opt} - \alpha_r (n_0 + p_0) \delta n = g_{opt} - \frac{\delta n}{\tau}$

$\frac{dn}{dt} \cdot g - r = g_{opt} - \frac{\delta n}{\tau}$
$\frac{dp}{dt} = g - r = g_{opt} - \frac{\delta p}{\tau}$

ماضي زنديم:

$$\begin{cases} \frac{\delta n}{\partial t} = g_{opt} - \frac{\delta n}{\tau} + \frac{1}{q} \nabla \cdot J_n \\ \frac{\delta P}{\partial t} = g_{opt} - \frac{\delta P}{\tau} - \frac{1}{q} \nabla \cdot J_P \end{cases}$$

$$\begin{cases} J_n = n q M_n \mathcal{E} + q D_n \nabla n \\ J_P = P q M_P \mathcal{E} - q D_P \nabla P \end{cases}$$

$$\frac{\delta n}{\partial t} = g_{opt} - \frac{\delta n}{\tau} + \frac{1}{q} \nabla \cdot (n q M_n \mathcal{E} + q D_n \nabla n)$$

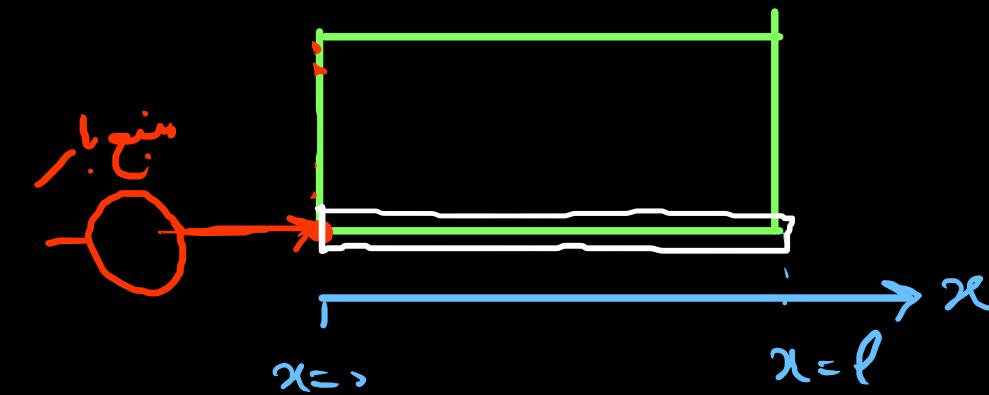
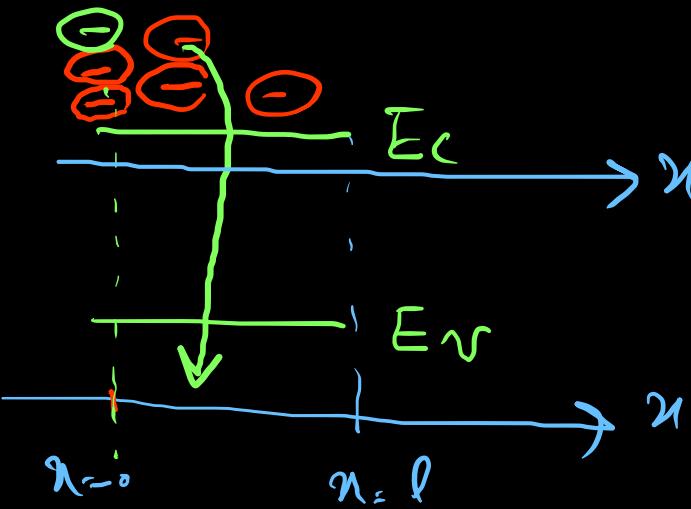
$$\begin{cases} \frac{\delta n}{\partial t} = g_{opt} - \frac{\delta n}{\tau} + n M_n \nabla \cdot \mathcal{E} + D_n \nabla^2 n \\ \frac{\delta P}{\partial t} = g_{opt} - \frac{\delta P}{\tau} - P M_P \nabla \cdot \mathcal{E} + D_P \nabla^2 P \end{cases}$$

$$\begin{cases} \nabla = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \\ \nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \end{cases}$$

$$\begin{array}{l} \xrightarrow{n = n_0 + \delta n(x, t)} \\ \xrightarrow{P = P_0 + \delta P(u, t)} \end{array}$$

$$\begin{cases} \frac{\partial \delta n}{\partial t} = g_{opt} - \frac{\delta n}{\tau} + n M_n \nabla \cdot \mathcal{E} + D_n \nabla^2 \delta n \\ \frac{\partial \delta P}{\partial t} = g_{opt} - \frac{\delta P}{\tau} - P M_P \nabla \cdot \mathcal{E} + D_P \nabla^2 \delta P \end{cases}$$

$$\begin{array}{l} \xrightarrow{\delta n(u, t)} \\ \xrightarrow{\delta P(u, t)} \end{array} \rightarrow n, P \rightarrow \begin{array}{l} J_n \\ J_P \end{array}$$



مکانیزم توزیع حالت ملائمه

$$\begin{cases} \frac{\partial \delta n}{\partial t} = 0 - \frac{\delta n}{\tau} + D_n \nabla^2 \delta n \\ \frac{\partial \delta p}{\partial t} = 0 - \frac{\delta p}{\tau} + D_p \nabla^2 \delta p \end{cases}$$

$$n = n_0 + \delta n(x, t) \quad \frac{\partial n}{\partial t} = 0$$

$$0 = D_n \frac{\partial^2}{\partial x^2} \delta n(x) - \frac{1}{\tau} \delta n(n)$$

$$0 = D_p \frac{\partial^2}{\partial x^2} \delta p(n) - \frac{1}{\tau} \delta p(n)$$

$$D_n \xi^2 - \frac{1}{\tau} \sim 0 \rightarrow \xi^2 = \pm \frac{1}{D_n \tau}$$

$$\xi_{1,2} = \pm \frac{1}{\sqrt{D_n \tau}}$$

$$\sqrt{D_n \tau} = L_n \quad \sqrt{D_p \tau} = L_p$$

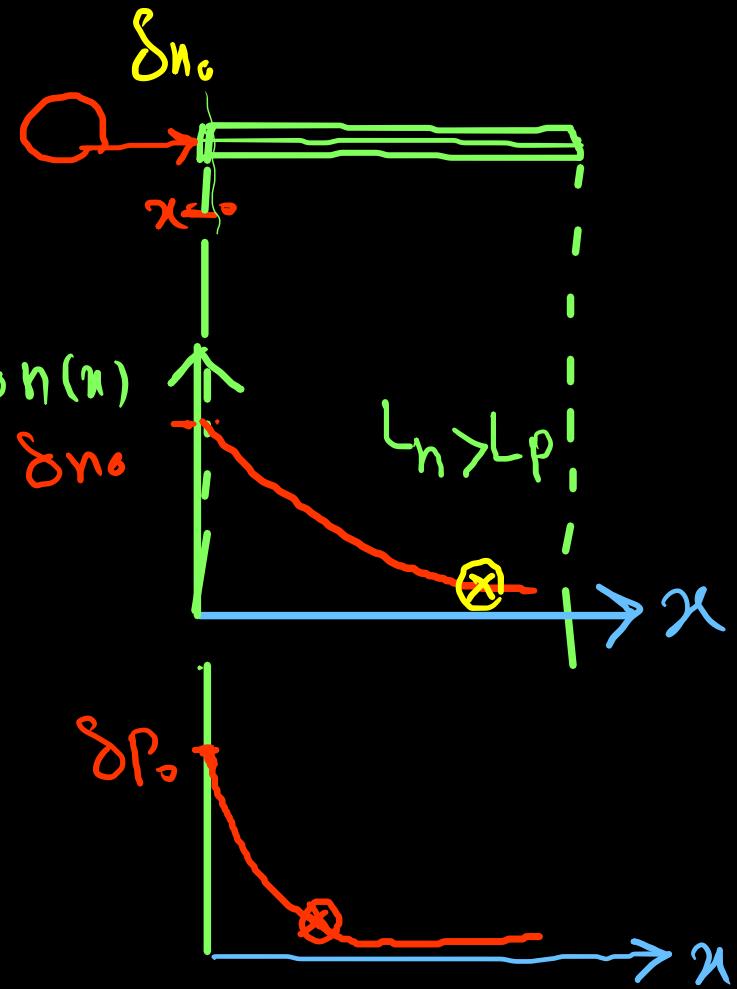
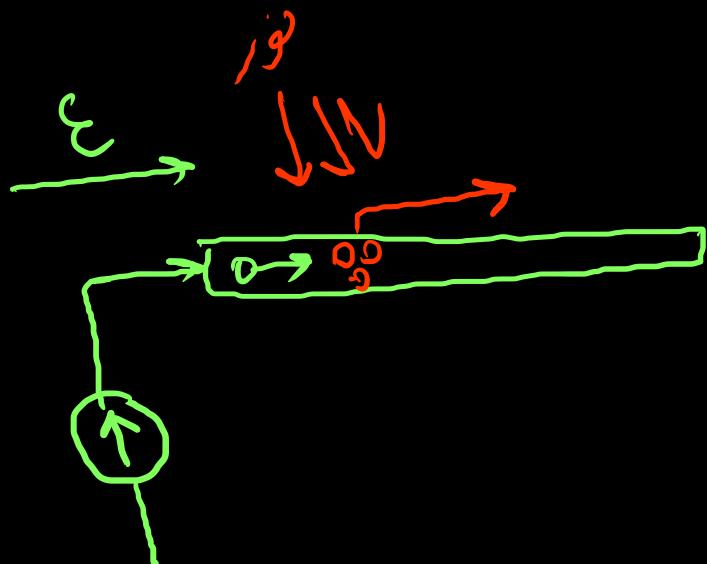
$$\delta n(n) = C_1 e^{\frac{1}{\sqrt{D_n \tau}} x} + C_2 e^{-\frac{1}{\sqrt{D_n \tau}} x}$$

$$\delta p(x) = C_3 e^{\frac{1}{\sqrt{D_p \tau}} x} + C_4 e^{-\frac{1}{\sqrt{D_p \tau}} x}$$

$$\delta n(x) = c_1 e^{\frac{x}{L_n}} + c_2 e^{-\frac{x}{L_n}}$$

$$\delta p(x) = c_3 e^{\frac{x}{L_p}} + c_4 e^{-\frac{x}{L_p}}$$

$$Z \rightarrow \rho, l, \mu, \nu$$



$$\delta n(x=0) = c_1 + c_2 = \delta n_0$$

$$\delta n(x \rightarrow \infty) = 0 \rightarrow c_1 = 0$$

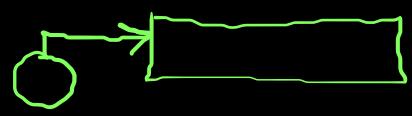
$$\delta n(x) = \delta n_0 e^{-\frac{x}{L_n}}$$

$$\delta p(x) = \delta p_0 e^{-\frac{x}{L_p}}$$

$$L_n = \sqrt{D_n Z}$$

$$L_p = \sqrt{D_p Z}$$

$$L_p \uparrow \rightarrow$$



$$J_n = q D_n \nabla n = q D_n \nabla (n_0 + \delta n_0 e^{-\frac{x}{L_n}})$$

$$= -\frac{q}{L_n} D_n \delta n_0 e^{-\frac{x}{L_n}}$$

$$J_n = -\frac{q}{L_n} D_n \delta n(x)$$

$$J_p = -q D_p \nabla p = -q D_p \nabla (p_0 + \delta p_0 e^{-\frac{x}{L_p}}) = -\frac{q}{L_p} D_p \delta p_0 e^{-\frac{x}{L_p}}$$

$$J_p = \frac{q}{L_p} D_p \delta p(x)$$

$$P = n_i e^{\frac{E_i - F_p}{k_B T}}$$

$$n = n_i e^{\frac{F_n - E_i}{k_B T}}$$

$$J_n = n q M_n \mathcal{E} + q D_n \nabla n$$

$$n q M_n \mathcal{E} + q D_n \nabla (n_i e^{\frac{F_n - E_i}{k_B T}}) = n q M_n \mathcal{E} + \frac{q D_n}{k_B T} \nabla (F_n - E_i) \cdot n$$

$$= \underline{n q M_n \mathcal{E}} + \underline{n M_n \nabla F_n} - \underline{n M_n \nabla E_i}$$

$$J_n = n M_n \nabla F_n$$

$$J_p = P M_p \nabla F_p$$

حالات جزئی مسائل

استحصال جزئی

$$\frac{D_n}{M_n} = \frac{k_B T}{q}$$

\mathcal{E}_q