مدار تریستوری

(ص ۳-۱)

$$i_D = \alpha v_D + \beta v_D^3 + \gamma v_D^5$$

$$g_D(t) = \left.\frac{\partial i_D}{\partial v_D}\right|_{v_D = V_1 \cos\omega_0 t} = \alpha + 3\beta v_D^2 + 5\gamma v_D^4$$

$$g_D(t) = \alpha + 3\beta V_1^2 \cos^2\omega_0 t + 5\gamma V_1^4 \cos^4 \omega_0 t$$

$$g_D(t) = \alpha + 3\beta V_1^2 \left(\frac{1+\cos 2\omega_0 t}{2}\right) + 5\gamma V_1^4 \left(\frac{1+\cos 2\omega_0 t}{2}\right)^2$$

$$\left\{\frac{1}{4} + \cos 2\omega_0 t + \frac{1}{4}\left(\frac{1+\cos 4\omega_0 t}{2}\right)\right\}$$

$$g_D(t) = \underbrace{\left(\alpha + \frac{3\beta V_1^2}{2} + \frac{15}{8}\gamma V_1^4\right)}_{A} + \underbrace{\left(\frac{3}{2}\beta V_1^2 + 5\gamma V_1^4\right)}_{B}\cos 2\omega_0 t + \underbrace{\frac{5}{8}\gamma V_1^4}_{C}\cos 4\omega_0 t$$

از رابطه کیرشهف ولتاژ

$$v_D = V_{s1}\cos\omega_{s1} t + V_{s2}\cos\omega_{s2} t - v_{IF}(t)$$

$$i_d(t) = g_D(t) \cdot v_d(t)$$

$$i_d(t) = \left(A + B\cos 2\omega_0 t + C\cos 4\omega_0 t\right) \times$$

$$\left(V_{s1}\cos\omega_{s1} t + V_{s2}\cos\omega_{s2} t - V_{IF}\cos(2\omega_0 + \omega_{s1})t\right.$$

$$i_d(t) = A(V_{s1}\cos\omega_{s1}t + V_{s2}\cos\omega_{s2}t) - AV_{IF}\cos(2\omega_0+\omega_{s1})t$$

$$+ B(V_{s1}\cos 2\omega_0 t.\cos\omega_{s1}t + V_{s2}\cos 2\omega_0 t\cos\omega_{s2}t)$$

$$- B V_{IF}\cos 2\omega_0 t\cos(2\omega_0+\omega_{s1})t$$

$$+ C V_{s1}\cos 4\omega_0 t\cos\omega_{s1}t + \overset{CV_{s2}}{\cos 4\omega_0 t\cos\omega_{s2}t})$$

$$- C V_{IF}\cos 4\omega_0 t\cos(2\omega_0+\omega_{s1})t$$

$$i_{dIF}(t) = -AV_{IF}\cos(2\omega_0+\omega_{s1})t$$

$$+ \frac{B}{2}V_{s1}\cos(2\omega_0+\omega_{s1})t$$

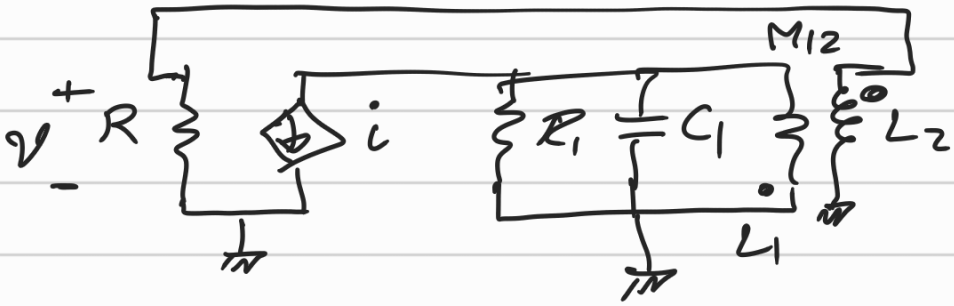
$$V_{IF}(t) = i_{dIF}(t)\,R_L$$

$$V_{IF} = \left(-AV_{IF} + \frac{B}{2}V_{s1}\right)R_L$$

$$V_{IF} = \frac{B/2\,(V_{s1})R_L}{1+AR_L}$$

$B/2\,V_{s2}R_L\cos(2\omega_0+\omega_{s2})$ توقف بازرسی

$$i = \alpha v + \beta v^2 + \gamma v^3 \qquad (۳.۳$$

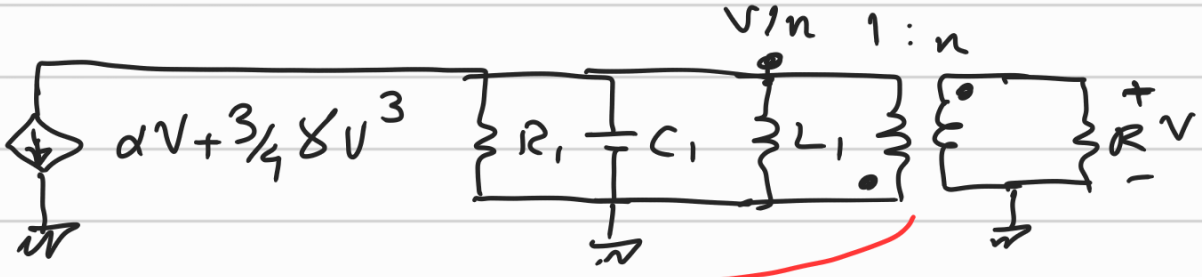


$$V(t) = V\cos\omega_0 t$$

$$i(t) = \alpha V\cos\omega_0 t + \beta(V\cos\omega_0 t)^2 + \gamma(V\cos\omega_0 t)^3$$

$$i(t) = \alpha V\cos\omega_0 t + \beta V^2\left(\frac{1+\cos 2\omega_0 t}{2}\right) + \gamma V^3\cos\omega_0 t\left(\frac{1+\cos 2\omega_0 t}{2}\right)$$

$$i(t) = \left(\alpha V + \frac{3}{4}\gamma V^3\right)\cos\omega_0 t + \frac{\beta}{2}V^2\cos 2\omega_0 t + \frac{\gamma}{4}V^3\cos 3\omega_0 t$$



با توجه به سرهای نقطه دار

$$\text{kcl}: -\left(\alpha V + \tfrac{3}{4}\gamma V^3\right) + V/n\left(G_1 + j\omega C_1 + \frac{1}{j\omega L_1} + n^2 G\right) = 0$$

$$-\alpha + \frac{1}{n}\left(G_1 + j\left(\omega C_1 - \frac{1}{\omega L_1}\right) + n^2 G\right) = \frac{3}{4}\gamma V^2$$

مرکز توسعه خانگی بخش بوهوی صفر شود.

$$\omega_0 = \frac{1}{\sqrt{L_1 C_1}}$$

شرط نوسان :

$$-\alpha + \frac{1}{n}(G_1 + n^2 G) = 3/4\, \gamma V^2$$

$$V = \sqrt{\frac{4}{3\gamma}\left(\frac{1}{n}(G_1 + n^2 G) - \alpha\right)}$$

دامنه ولتاژ اسیلاتور محلی

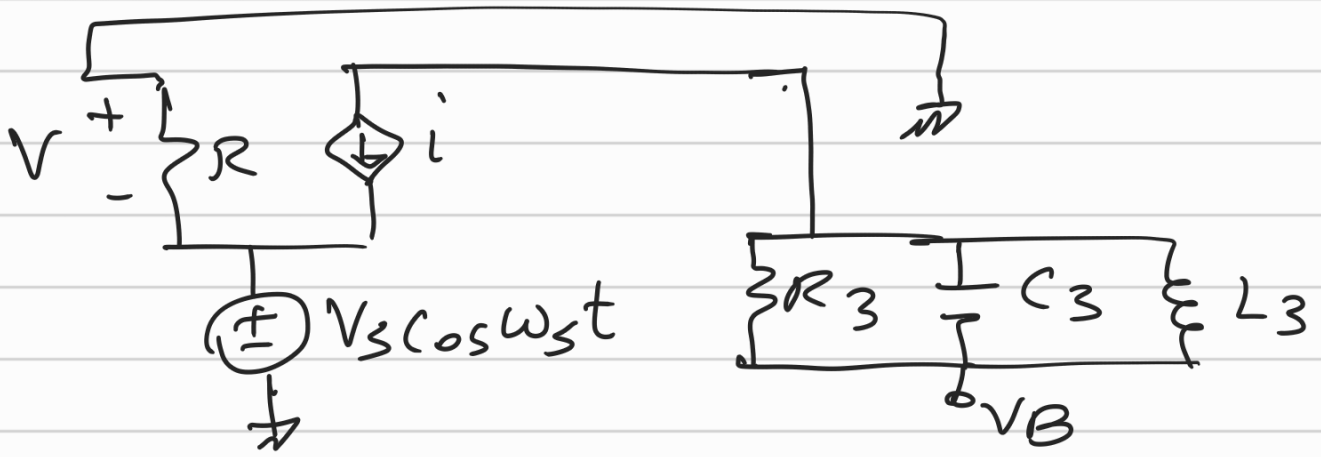
$$G_1 = 1/R_1 \,, \quad G = 1/R \,, \quad n = \frac{M_{12}}{L_1}$$

تحلیل مدار

$$i(t) = \alpha V + \beta V^2 + \gamma V^3$$

$$g_d(t) = \frac{\partial i}{\partial V} = \alpha + 2\beta V + 3\gamma V^2$$

هدایت انتقالی عنصر غیرخطی



$V = -V_S \cos \omega_S t \Rightarrow i(t) = g_d(t)\, V_{signal}$

signal — small signal

$$i(t) = (\alpha + 2\beta V\cos\omega_0 t + 3\gamma V^2\cos^2\omega_0 t) \times (-V_s\cos\omega_s t)$$

small signal

$$i(t) = -\alpha V_s\cos\omega_s t - \beta V V_s\cos(\omega_0+\omega_s)t - \beta V V_s\cos(\omega_0-\omega_s)t - \frac{3\gamma}{2}V_s V^2\cos\omega_s t - \frac{3}{4}\gamma V_s V^2\cos(2\omega_0-\omega_s)t - \frac{3}{4}\gamma V_s V^2\cos(2\omega_0+\omega_s)t$$

small signal

$$i_{IF}(t) = -3/4\,\gamma V_s V^2\cos(2\omega_0+\omega_s)t$$

صورت تنظیم شده $2\omega_0+\omega_s$ در خازن C_3 و L_3

$$g_c = \frac{I_{IF}}{V_{RF}} = \frac{3/4\,\gamma V_s V^2}{V_s} = 3/4\,\gamma V^2$$

$$v_0(t) = V_B - g_c V_s\cos(2\omega_0+\omega_s)t$$

$$v_0(t) = V_B - 3/4\,\gamma V^2 V_s\cos(2\omega_0+\omega_s)t$$

$$I_E(t) \simeq \frac{V_{bb} + 12 - V_{BE}}{R_B} \simeq$$

منبع جریان وابسته

$$= \cos(2\pi \times 10^7 t) + 2.06 \text{ mA}$$

mA

$$i_2(t) \simeq \frac{I_E(t)}{2}\left(1 - \tanh\left(\frac{x}{2}\cos\omega_0 t\right)\right)$$

$$x = \frac{V_s}{V_T}$$

$$i_2(t) \simeq \frac{I_E}{2}(t)\left[1 - 2a_1(x)\cos\omega_s t - 2a_3(x)\cos 3\omega_s t \ldots\right]$$

$$i_{2IF}(t) = -\frac{1}{2} \times 2a_1(x) \frac{\cos(6.59 - 6.28)\times 10^7 t}{2}$$

$$\omega_{IF} = \frac{1}{\sqrt{35\times10^{-6} \times 2.89\times10^{-9}}}$$

$$\omega_{IF} = 3.14 \times 10^6 \text{ rad/sec}$$

$$\omega_{IF} = \omega_0 - \omega_s$$

$$\omega_0 = 6.59 \times 10^7 \text{ rad/sec}$$

$$\omega_s = 6.28 \times 10^7 \text{ rad/sec}$$

$$g_c = \frac{I_{IF}}{V_s} \simeq \frac{\frac{1}{2}a_1(x)}{V_s}$$

$$V_0(t) = V_{CC} - R_2 g_c V_s (1 + m f(t)) \cos(3.14\times10^6 t)$$

$$V_o(t) = 12 - 2.2 \times \frac{1}{2} a(x) (1 + m f(t)) \cos(3.14 \times 10^6 t)$$

$$x = \frac{V_S}{V_T} = \frac{10m}{25m} = 0.4$$

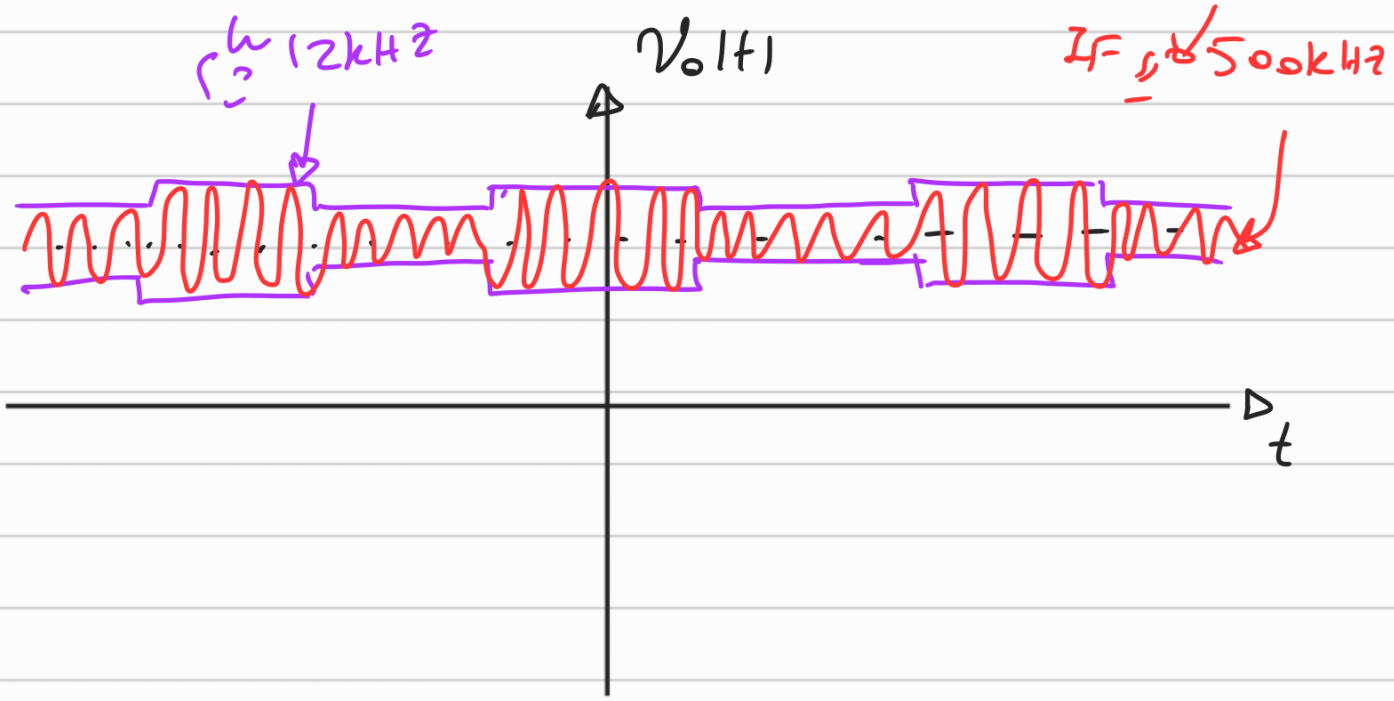
$V_S = I_S \times 5k\Omega = 2\mu A \times 5k\Omega$
$= 10 mVolt$

مدار تشدید سری R_1

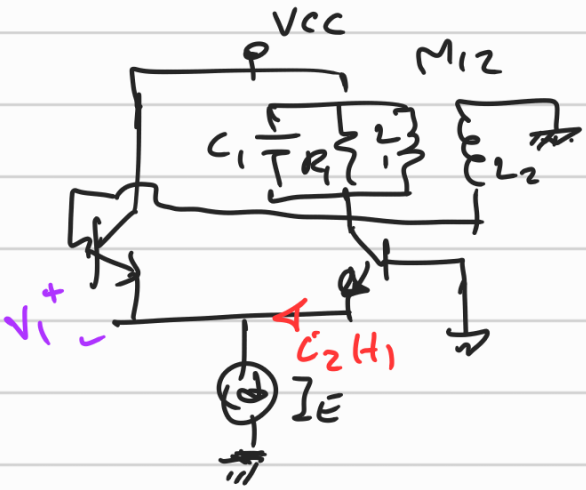
$$\frac{a_1(x)}{x} \simeq \frac{1}{4}$$

اگر $x < 1$

$$a_1(x) = \frac{x}{4} = 0.1$$



۳-۷ تحلیل نوسان ساز



فرکانس نوسان

$$\omega_0 = \frac{1}{\sqrt{L_1 C_1}}$$

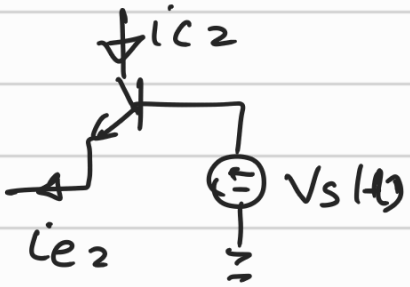
$$G_m = \frac{G_1}{n(1-n/\beta)} \qquad n = \frac{M_{12}}{L_1}$$

$$i_2(t) = \frac{I_E}{2}\left(1 - \tanh\left(\frac{V_1}{2V_T}\right)\right)$$

$$x = \frac{V_1}{V_T}$$

$$g_m(t) = \frac{\partial i_2(t)}{\partial V_1} = -\frac{I_E}{2}\left(\frac{1}{2V_T}\right)\left(1 - (\tanh(x))^2\right)$$

$$i_{2\,signal} = g_m(t).\, V_S(1+mf(t))\cos\omega_s t$$



$$i_{2\,signal}(t) = \frac{I_E}{4V_T} \times \left(2a_1(x)\cos\omega_0 t + 2a_3(x)\cos 3\omega_0 t + 2a_5(x)\cos 5\omega_0 t\right)^2 V_S(1+mf(t))\cos\omega_s t$$

$$i_{2\,signal}(t) = \frac{I_E}{4V_T} V_S(1+mf(t)) 4 \times \left(a_1^2(x)\cos^2\omega_0 t + a_3^2(x)\cos^2 3\omega_0 t + a_5^2(x)\cos^2 5\omega_0 t\right.$$

(۱) (۲) (۳)

$$+2a_1(x)a_3(x)\cos\omega_0 t\cos 3\omega_0 t \quad (۴)$$

$$+2a_1(x)a_5(x)\cos\omega_0 t\cos 5\omega_0 t \quad (۵)$$

$$\left. + 2a_3(x)a_5(x)\cos 3\omega_0 t\cos 5\omega_0 t \right) (1+mf(t)) \quad (۶)$$

$$\cos\omega_s t$$

فرکانس های تولید شده:

① $2\omega_0 \pm \omega_s$

② $6\omega_0 \pm \omega_s$

③ $10\omega_0 \pm \omega_s$

④ $2\omega_0 \pm \omega_s$, $4\omega_0 \pm \omega_s$

⑤ $16\omega_0 \pm \omega_s$, $4\omega_0 \pm \omega_s$

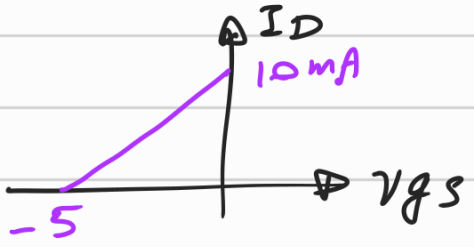
⑥ $8\omega_0 \pm \omega_s$, $2\omega_0 \pm \omega_s$

پایین ترین مولفه $\omega_s - 2\omega_0$ است که در خروجی ①، ④، ⑥ ظاهر می شود.

$$i'_{IF}(t) = \frac{I_E}{V_T} V_s(1 + mf(t)) \left\{ \frac{a_1^2(x)}{2} + \frac{a_1(x)a_3(x)}{2} + \frac{a_3(x)a_5(x)}{2} \right\} \cos(2\omega_0 - \omega_s)t$$

همانطور که ملاحظه می کنید در این مخلوط کننده در فرکانس های $\omega_s \pm \omega_0$ خروجی نداریم لذا مخلوط کننده ها رو بسته نامیده می شوند چون ω_s با هارمونیک های ω_0 مخلوط می شود.

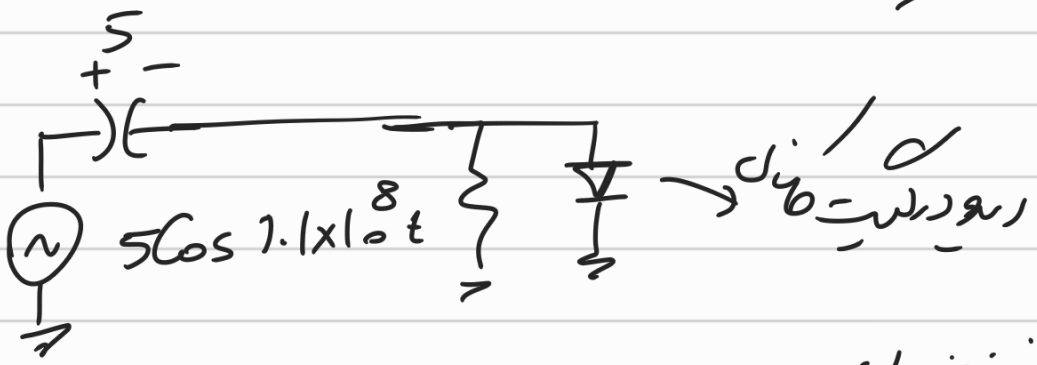
$$V_0(t) = V_{CC} - R_2 i_{IF}(t)$$



۳-۸) از شکل

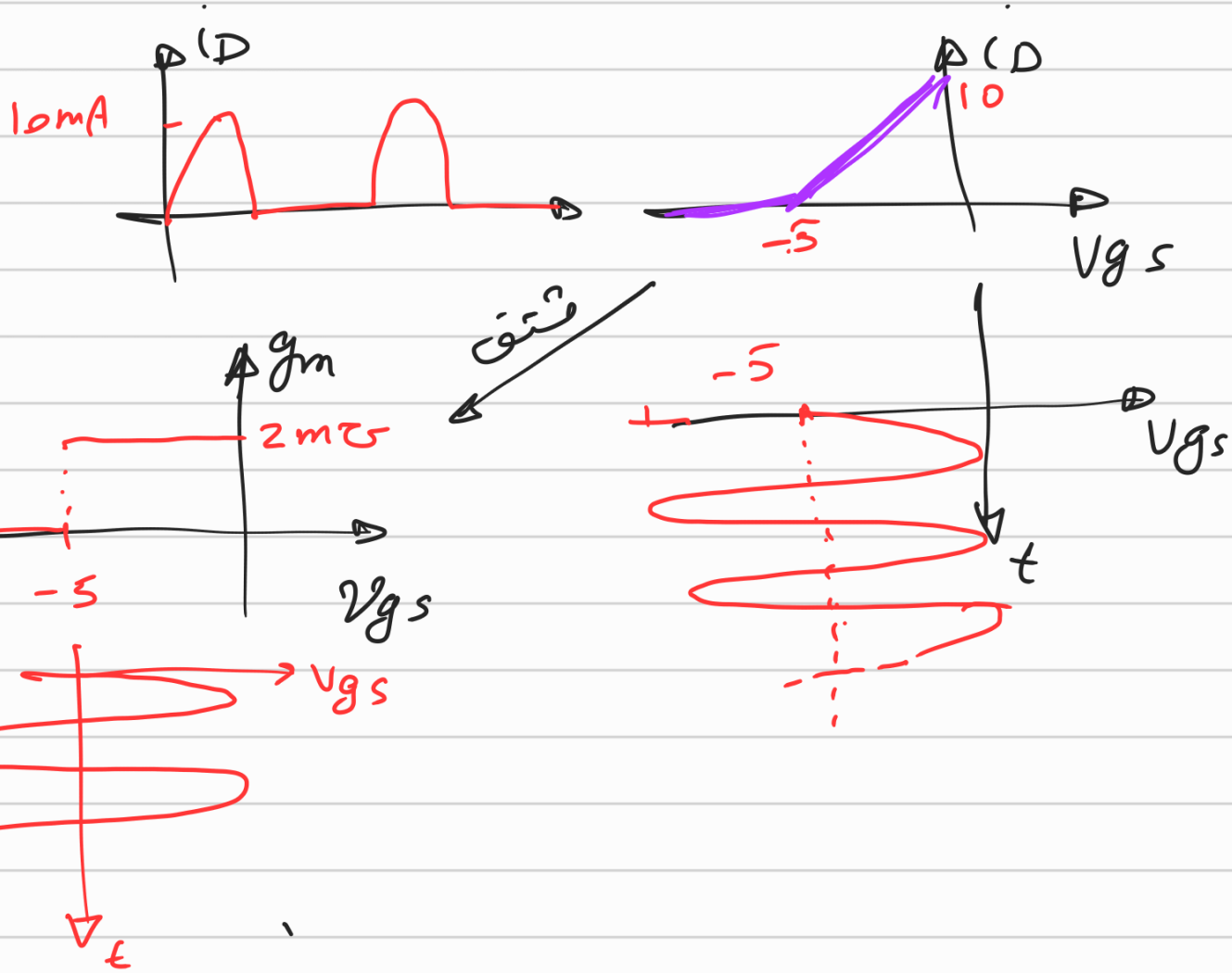
با توجه به وجود خازن 20pF

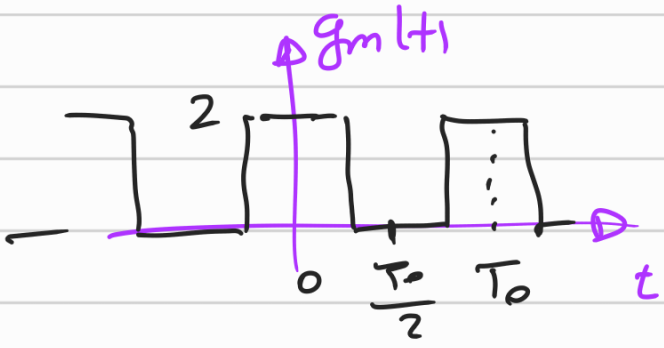
این خازن به اندازه یک ولتاژ اسلایدر محلی شارژ می‌شود (مثل مدار چسبان)



پس از شکل روی این خازن داریم:

$$Vgs = 5\cos 1.1\times10^{8} t - 5$$





$g_m(t) = 2\,S(t)$

تابع پنجره متناوب

$$S(t) = \frac{1}{2} + \sum_{n=1}^{\infty} \frac{\sin n\pi/2}{n\pi/2} \cos n\omega_0 t$$

$$g_m(t) = 1 + \frac{4}{\pi}\cos\omega_0 t - \frac{4}{3\pi}\cos 3\omega_0 t + \cdots$$

$$i_d(t) = g_m(t)\, v_s(t) = \left(1 + \frac{4}{\pi}\cos\omega_0 t + \cdots\right) V_s \cos\omega_s t$$

$$i_{dIF}(t) = \frac{4}{\pi} \times \frac{V_s}{2} \cos(\omega_0 - \omega_s)t$$

$$g_c = \frac{I_{IF}}{V_s} = \frac{4}{\pi}$$

$$v_{out}(t) = 15 - 5k\Omega \times \frac{4}{\pi} \times 50mV\,(1 + \cos 10^4 t)\cos 10^8 t$$

$$\omega_{IF} = \frac{1}{\sqrt{1\mu H \times 100pF}} = \frac{1}{\sqrt{10^{-16}}} = 10^8\ rad/sec$$

$$\omega_0 = 1.1 \times 10^8 \qquad \omega_0 - \omega_s = 10^8\ rad/sec$$

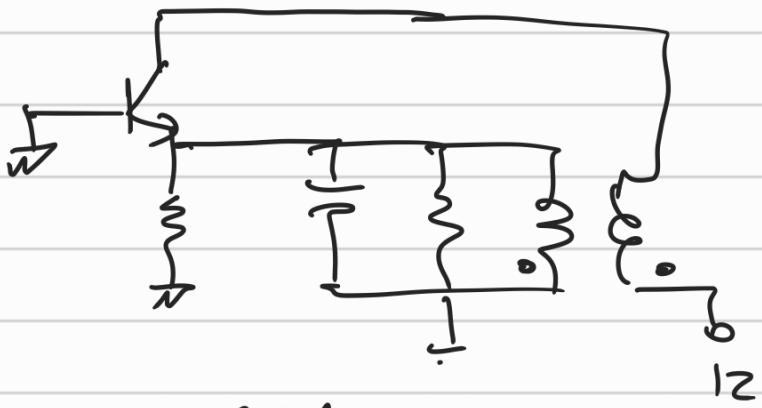
$$\omega_s = 10^7$$

در ورودی مدار خازن قرار گرفته است از سیگنال محلی $\frac{1}{\omega C} \simeq 500\Omega$ و مقاومت متصل به مدار $1M\Omega$ است با توجه به کوچکتر بودن امپدانس خازن نسبت به مقاومت

ولتاژ اسلیو محلی و R_F بصورتی بایاس کویل می‌شوند. خازن نقش جریان‌های ولتاژ را دارد.

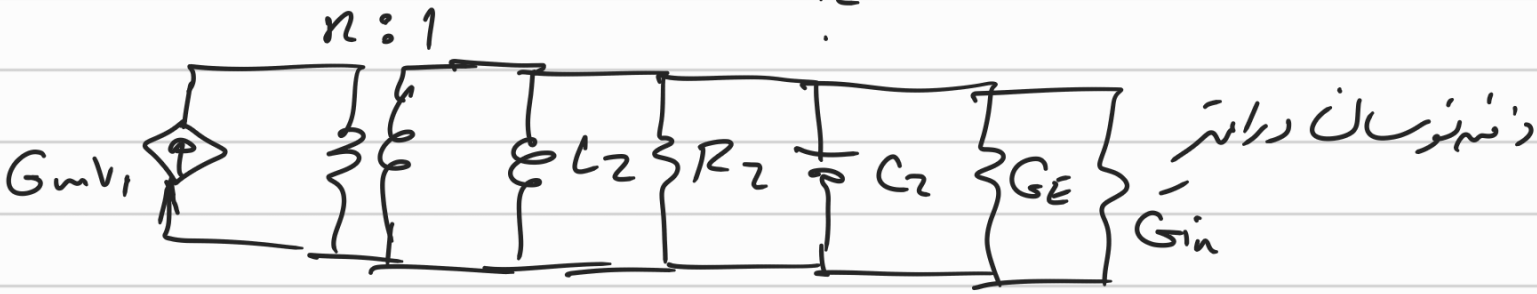
(۹-۴

تحلیل نوسان ساز



$$\omega_0 = \frac{1}{\sqrt{L_2 C_2}} = 3.141 \times 10^7 \ rad/sec$$

$$f_0 \simeq 5MHz$$



دامنه نوسان در این

$$n = \frac{M_{12}}{L_2} = 30 \qquad G_{in} = \frac{1}{\alpha} G_m$$

$$I_C = \frac{3.75 - 0.7}{3k\Omega} = 1mA \rightarrow V_A = I_{EQ}(R_E + (1-\alpha)r_B)$$

جریان نقطه کار

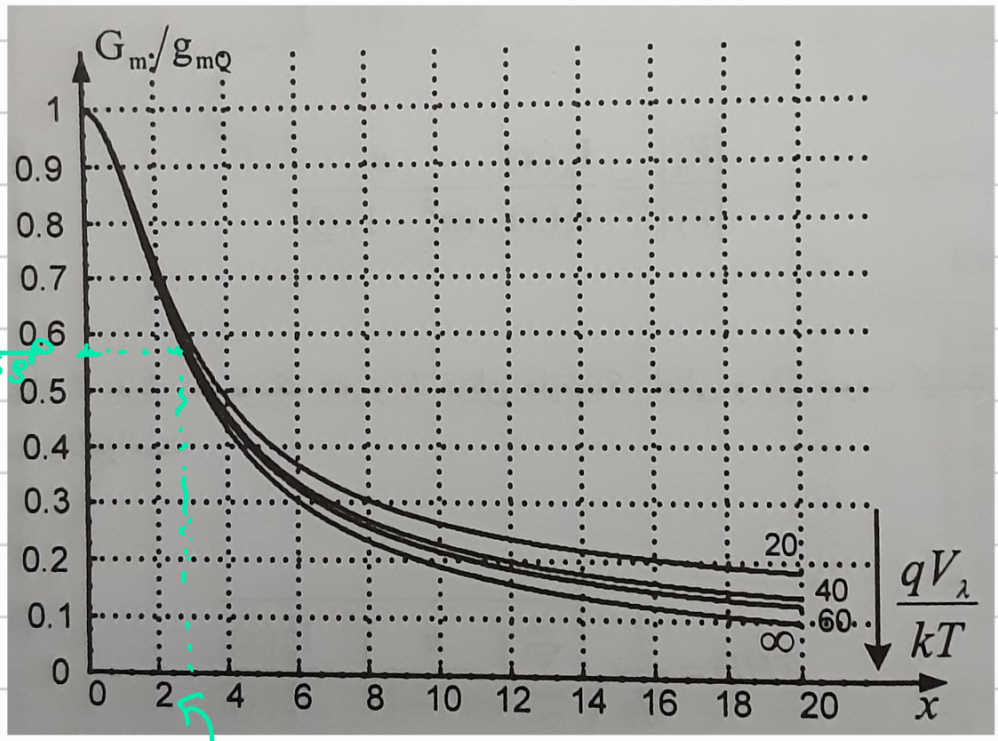
$$V_A = 1mA \times 3k\Omega = 3 Volt$$

$$g_{mQ} = \frac{I_C}{V_T} = \frac{1}{25} = 40m\mho$$

kcl: $\frac{1}{n} G_m V_1 = (G_2 + G_E + \frac{G_m}{\alpha}) V_1 \Rightarrow G_m = \frac{G_2 + G_E}{\frac{1}{n} - \frac{1}{\alpha}}$

در نتیجه

$$G_m = \frac{1/2.27 + 1/3}{1/30} = 23.21 \ m\mho$$

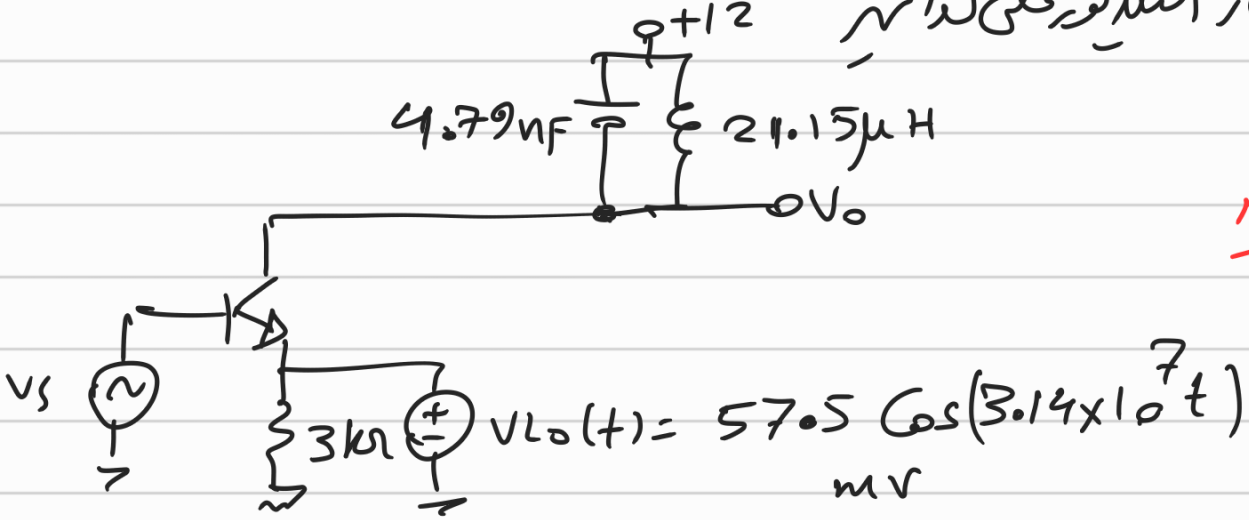


$$\frac{V_\lambda}{V_T} = \frac{3}{25mV} = 120$$

$$\frac{G_m}{g_m} = \frac{23.21}{40} = 0.58$$

$x \simeq 2.3 \longrightarrow V_1 = V_T \cdot x = 57.5\,mV$

دامنه ولتاژ اسیلاتور محلی برابر

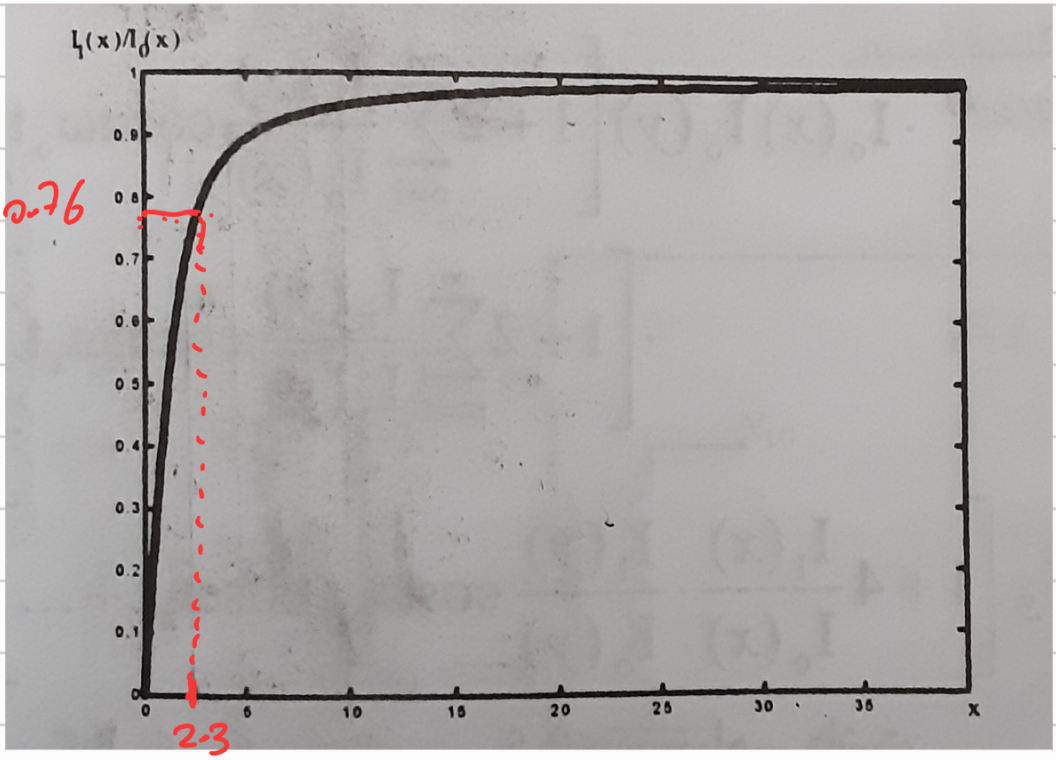


محل صد

چون سیگنال اسیلاتور محلی به امیتر و گیت بیس داده شده از تحلیل انجام شده در بالا می‌توان استفاده کرد

$$g_c = g_m \frac{I_1(x)}{I_0(x)} = 40 \times 0.76 = 30.4\,m\Omega$$

$$x = \frac{V_1}{V_T} = 2.3$$



$$V_{out}(t) = 12 - 30.4 m_v x$$

m_v ↑ g_c

$L_3 = 21.15 \mu H$

$Q_{L_3} = 30$ $\Rightarrow \omega_{IF} = 3.14 \times 10^6$ rad/sec

$C_3 = 4.79 nF$

$$Q_{L_3} = \frac{R_L}{\omega_{IF} L_3} \Rightarrow R_L = Q_{L_3} \cdot \omega_{IF} L_3$$

$$R_L = 30 \times 3.14 \times 10^6 \times 21.15 \times 10^{-6}$$

$R_L \simeq 2 k\Omega$

$$V_{out}(t) = 12 - 2 \times 30.4 \times 0.010 (1 + 0.8 f(t)) \cos \omega_{IF} t$$

↑ g_c V_s ↑

$$V_{out} = 12 - 0.6(1 + 0.8 f(t)) \cos \omega_{IF} t$$