

$$x_2(t) = 2x_1(t-1) - \frac{1}{3}x_1(2t-1) \quad \begin{matrix} \xrightarrow{T_1} \\ \xrightarrow{T_{1/2}} \end{matrix} \quad \begin{matrix} x_1(t) \rightarrow 11 \rightarrow a_k \\ T_2? \quad a_k? \end{matrix} \quad -1$$

$$T_2 = \text{km} \{T_1, T_{1/2}\} = T_1$$

$$\Rightarrow T_2 = T_1$$

$$x_1(t) \rightarrow a_k$$

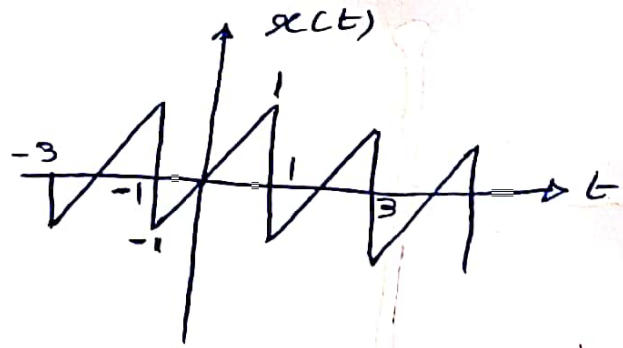
$$x(t+1) \rightarrow a_k e^{+jk\omega_0}$$

$$* x(-t+1) \rightarrow a_{-k} e^{+jk\omega_0}$$

$$x_1(t-1) \rightarrow a_k e^{-jk\omega_0}$$

$$* x_1(2t-1) \rightarrow a_k e^{-jk2\omega_0} \quad T' = T_{1/2} \Rightarrow \omega' = 2\omega_0$$

$$\text{خاصیت فیلٹر بول} \Rightarrow a_{k_2} = 2a_{-k_1} e^{-jk\omega_0} - \frac{1}{3}a_{k_1} e^{-jk2\omega_0} = \frac{2}{3}e^{-jk\omega_0}(-2a_{k_1} - \frac{1}{2}a_{k_1})$$



$$a_k = \begin{cases} 0 & k=0 \\ (j)^k \frac{\sin k\pi/4}{k\pi} & \text{o.w.} \end{cases}$$

$$a_k = \frac{1}{T_0} \int_{T_0} x(t) e^{-jk\omega_0 t} dt$$

$$a_k = \frac{1}{T} \int_{-1}^1 t e^{-jk\omega_0 t} dt$$

$$a_k = \frac{1}{T} \left[ -\frac{t}{jk\omega_0} e^{-jk\omega_0 t} + \frac{1}{(k\omega_0)^2} e^{-jk\omega_0 t} \right]_{-1}^1$$

$$a_k = \frac{1}{T} \left[ e^{-jk\omega_0} \left( \frac{1}{(k\omega_0)^2} - \frac{1}{jk\omega_0} \right) - e^{jk\omega_0} \left( \frac{1}{(k\omega_0)^2} + \frac{1}{jk\omega_0} \right) \right]$$

$$a_k = -\frac{1}{T} \left[ \frac{1}{(k\omega_0)^2} [e^{jk\omega_0} - e^{-jk\omega_0}] + [e^{jk\omega_0} + e^{-jk\omega_0}] \frac{1}{jk\omega_0} \right]$$

$$a_k = \frac{-j}{1(k\omega_0)^2} \left[ \frac{e^{jk\omega_0} - e^{-jk\omega_0}}{2j} \right] + \left[ \frac{e^{jk\omega_0} + e^{-jk\omega_0}}{2} \right] \frac{-j}{k\omega_0}$$

$$\Rightarrow a_k = \frac{-j}{(k\omega_0)^2} \sin k\omega_0 + \left( \frac{-j}{k\omega_0} \right) \cos k\omega_0$$

5.2.1.1:

	$t e^{-jk\omega_0 t}$
1	$\frac{-1}{jk\omega_0} e^{-jk\omega_0 t}$
0	$\frac{-1}{(k\omega_0)^2} e^{-jk\omega_0 t}$

$$x(t) \rightarrow a_k, T=6$$

$$z(t) = 2x\left(\frac{1}{2}t-1\right) + 3x(2t)$$

$\hookrightarrow 2T$ 
 $\hookrightarrow T/2$

$$x(t) \rightarrow a_k$$

$$x(t-1) \rightarrow a_k e^{-jk\omega_0}$$

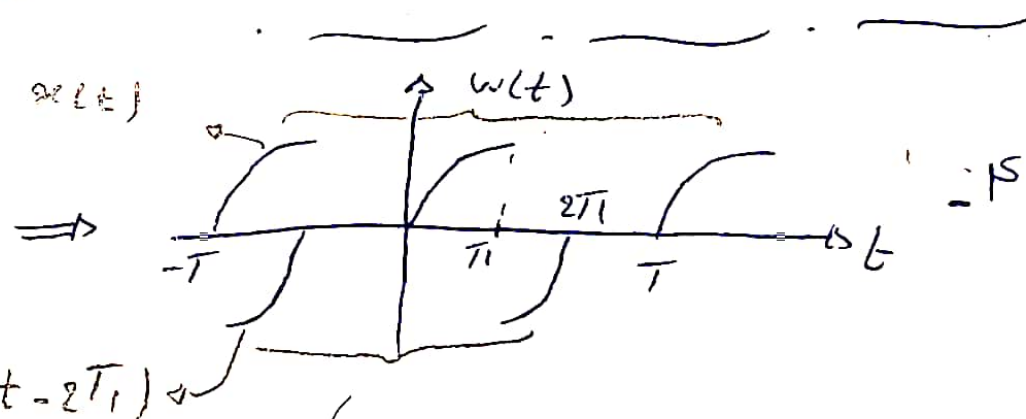
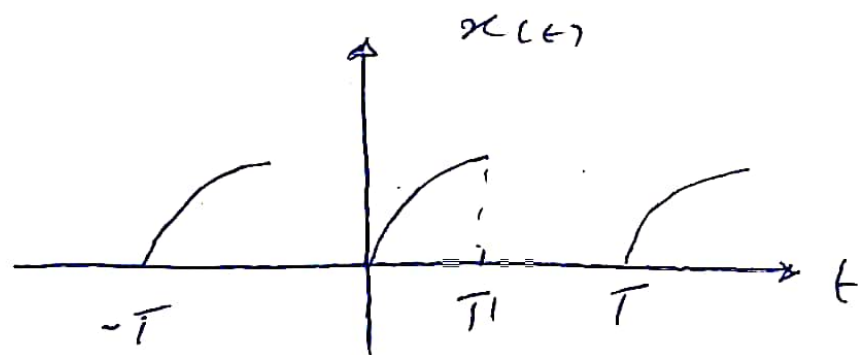
$$x\left(\frac{1}{2}t-1\right) \rightarrow a_k e^{-jk\frac{1}{2}\omega_0}$$

$$x(2t) \rightarrow a_k$$

$$\Rightarrow z(t) = 2a_k e^{-jk\frac{1}{2}\omega_0} + 3a_k$$

- "die"

$$T_2 = \text{lcm} \left\{ \overset{1}{2T}, \overset{12}{T/2} \right\} = 12 = 2T$$



$$w(t) = x(t) - x(-t - 2T_1) \rightarrow b_k$$

$$\begin{cases} x(t - 2T_1) \rightarrow a_k e^{-jk\omega_0 2T_1} \\ x(-t - 2T_1) \rightarrow a_{-k} e^{jk\omega_0 2T_1} \end{cases}$$

$$w(t) \rightarrow b_k = a_k - a_{-k} e^{jk\omega_0 2T_1}$$

$$a_k = a_{k+2} \quad a_k = a_{-k}$$

$$\int_{-0.5}^{0.5} x(t) dt = 1$$

$$\int_{0.5}^{1.5} x(t) dt = 2 \quad T=3$$

$$* \begin{cases} a_k = a_{-k} \Rightarrow x(t) = x(-t) \\ a_k = a_{k+2} \Rightarrow x(t) = x(t) e^{-j(\frac{4\pi}{3})t} \end{cases} \Rightarrow t = 0, \pm 1.5, \pm 3, \pm 4.5, \dots$$

$$* \int_{-0.5}^{0.5} x(t) dt = 1 \Rightarrow -0.5 < t < 0.5 \Rightarrow x(t) = \delta(t)$$

$$* \int_{0.5}^{1.5} x(t) dt = 2 \Rightarrow 0.5 < t < 1.5 \Rightarrow x(t) = 2\delta(t - \frac{3}{2})$$

$$\Rightarrow x(t) = \sum_{-\infty}^{+\infty} \delta(t - 3k) + 2 \sum_{-\infty}^{+\infty} \delta(t - 3k - \frac{3}{2})$$

$$x(t) \rightarrow a_k$$

$$T = 5$$

$$b_k = j^{(k+1)} \omega_0 e^{j k \omega_0} \times a_{k+1}$$

$$1. \frac{dx(t)}{dt} \rightarrow j k \omega_0 a_k$$

$$2. e^{-j \omega_0 t} \times \frac{dx(t)}{dt} \rightarrow j^{(k+1)} \omega_0 a_{k+1}$$

$$3. e^{-j \omega_0 (t+1)} \times \frac{dx(t+1)}{dt} \rightarrow j^{(k+1)} \omega_0 a_{k+1} e^{j k \omega_0}$$

$$y(t) = e^{-j \omega_0 (t+1)} \times \frac{dx(t+1)}{dt}$$