#2

LTI:

$$\frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt} + 3x(t)$$

Choosing this

in $Y_{(jw)} + Y_{(jw)} + Y_{(jw)} = y(y_{(jw)}) + 3\tilde{X}_{(w)}$

$$\Rightarrow Y_{(jw)} \left(jw+1\right) = \tilde{X}_{(jw)} \left(jw+3\right) = y(y_{(jw)}) + \frac{3\tilde{X}_{(jw)}}{\tilde{X}_{(jw)}} = \frac{3+jw}{\tilde{X}_{(jw)}}$$

$$\pi(t): 2e \ u(t) \stackrel{f}{=} \overline{I(j\omega)} = \frac{2}{1+j\omega}$$

$$= y(t) = \chi(t) * h(t) \xrightarrow{F} Y(j\omega) = \tilde{\chi}(j\omega) \cdot H(j\omega) = \frac{2}{1+j\omega} \cdot \frac{3+j\omega}{1+j\omega}$$

$$= y(j\omega) = \frac{2(3+j\omega)}{(1+j\omega)(1+j\omega)} = \frac{2(3+j\omega)}{(1+j\omega)^2} = \frac{A}{(1+j\omega)^2} \cdot \frac{13}{(1+j\omega)^2}$$

$$\begin{cases} A^{2} (1+jw)^{2} Y_{(jw)} \Big|_{jw=1} = 4 \\ B = \frac{d}{dw} (1+jw)^{2} Y_{(jw)} \Big|_{jw=1} = 8 \end{cases}$$

$$= Y_{(jw)} = \frac{4}{(1+jw)^{2}} + \frac{8}{(1+jw)}$$

$$= -t \qquad -t$$

=, y(t)=tte u(t) + 8e u(t)

(a)
$$H_i(jw) = \frac{1}{H(jw)} = \frac{1}{3+jw} = \frac{1}{3+jw} + \frac{jw}{3+jw} = \frac{5^{-1}}{3+jw} + \frac{-3t}{3+jw} = -3t$$
+ S(0)