

Operating Systems

Deadlocks-Part2

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Outline

- Liveness
- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance



Methods for Handling Deadlocks

- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidance

Allow the system to enter a deadlock state and then recover.

Ignore it and pretend that deadlocks never occur in the system.

Deadlock Prevention

Invalidate one of the four necessary conditions for deadlock



Deadlock Prevention-Mutual Exclusion

Not required for sharable resources (e.g., read-only files)

Must hold for non-sharable resources



Deadlock Prevention- Hold and Wait

 Must guarantee that whenever a process requests a resource, it does not hold any other resources.

 Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none allocated to it.

Low resource utilization; starvation possible.



Deadlock Prevention-No Preemption

• If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released.

 Preempted resources are added to the list of resources for which the process is waiting.

 Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting.



Deadlock Prevention- Circular Wait

 Impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration.

- Invalidating the circular wait condition is most common.
- Simply assign each resource (i.e., mutex locks) a unique number.
- Resources must be acquired in order.

Circular Wait

• If:
 first_mutex = 1
 second_mutex = 5

```
code for thread_two could not be written as follows:
```

```
/* thread_two runs in this function */
/* thread_one runs in this function
                                          void *do_work_two(void *param)
void *do_work_one(void *param)
                                             pthread_mutex_lock(&second_mutex);
   pthread_mutex_lock(&first_mutex);
                                             pthread_mutex_lock(&first_mutex);
   pthread_mutex_lock(&second_mutex);
   /**
                                              * Do some work
    * Do some work
                                             pthread_mutex_unlock(&first_mutex);
   pthread_mutex_unlock(&second_mutex);
                                             pthread_mutex_unlock(&second_mutex);
   pthread_mutex_unlock(&first_mutex);
                                             pthread_exit(0);
   pthread_exit(0);
```

From Don Porter's Slides

Lock Ordering

- A program code convention
- Developers get together, have lunch, plan the order of locks
- In general, nothing at compile time or run-time prevents you
 from violating this convention
 - Research topics on making this better:
 - Finding locking bugs
 - Automatically locking things properly



mm/filemap.c lock ordering

```
* Lock ordering:
  ->i mmap_lock
                                (vmtruncate)
     ->private lock
                                ( free pte-> set page dirty buffers)
       ->swap lock
                                (exclusive swap page, others)
         ->mapping->tree lock
  ->i mutex
                                (truncate->unmap_mapping_range)
     ->i mmap lock
  ->mmap sem
     ->i mmap lock
       ->page table lock or pte lock
                                      (various, mainly in memory.c)
         ->mapping->tree lock (arch-dependent flush dcache mmap lock)
  ->mmap sem
     ->lock page
                                (access_process_vm)
  ->mmap_sem
     ->i mutex
                                (msync)
  ->i mutex
     ->i alloc_sem
                                (various)
  ->inode lock
     ->sb lock
                                (fs/fs-writeback.c)
     ->mapping->tree lock
                                ( sync single inode)
  ->i mmap lock
     ->anon vma.lock
                                (vma adjust)
  ->anon vma.lock
     ->page table lock or pte lock
                                        (anon vma prepare and various)
   ->page table lock or pte lock
     ->swap lock
                                (try_to_unmap_one)
     ->private lock
                                (try to unmap one)
     ->tree lock
                                (try to unmap one)
     ->zone.lru lock
                                (follow page->mark page accessed)
     ->zone.lru lock
                                (check pte range->isolate lru page)
     ->private lock
                                (page remove rmap->set page dirty)
     ->tree lock
                                (page remove rmap->set page dirty)
     ->inode lock
                                (page remove rmap->set page dirty)
     ->inode lock
                                (zap pte range->set page dirty)
     ->private lock
                                (zap pte range-> set page dirty buffers)
   ->task->proc lock
     ->dcache lock
                                (proc pid lookup)
```



Back to Silberschatz

Deadlock Avoidance

Requires that the system has some additional *a priori* information available.



Deadlock Avoidance

 Simplest and most useful model requires that each process declare the maximum number of resources of each type that it may need.

The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition.

Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes.



Safe State

 When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state

System is in **safe state** if there exists a sequence $\langle P_1, P_2, ..., P_n \rangle$ of ALL the processes in the systems such that for each P_i , the resources that P_i can still request can be satisfied by currently available resources + resources held by all the P_i , with j < i

Safe State (cont.)

That is:

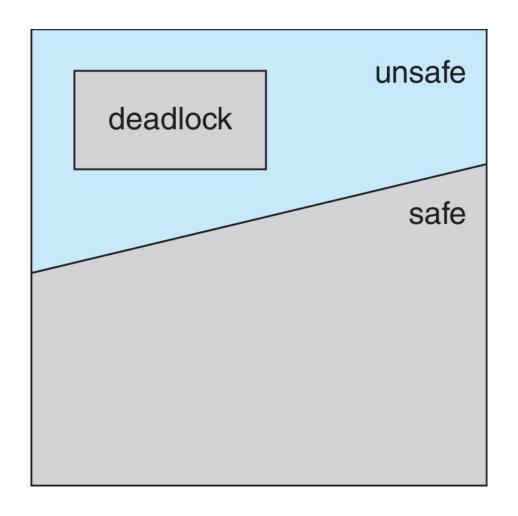
- If P_i resource needs are not immediately available, then P_i can wait until all P_i have finished
- When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
- When P_i terminates, P_{i+1} can obtain its needed resources, and so on

Basic Facts

- If a system is in safe state \Rightarrow no deadlocks
- If a system is in unsafe state ⇒ possibility of deadlock
- Avoidance \Rightarrow ensure that a system will never enter an unsafe state.



Safe, Unsafe, Deadlock State



Avoidance Algorithms

- Single instance of a resource type
 - Use a resource-allocation graph

- Multiple instances of a resource type
 - Use the Banker's Algorithm



Resource-Allocation Graph Scheme

■ Claim edge $P_i \rightarrow R_j$ indicated that process P_j may request resource R_i ; represented by a dashed line.

Claim edge converts to request edge when a process requests a resource.

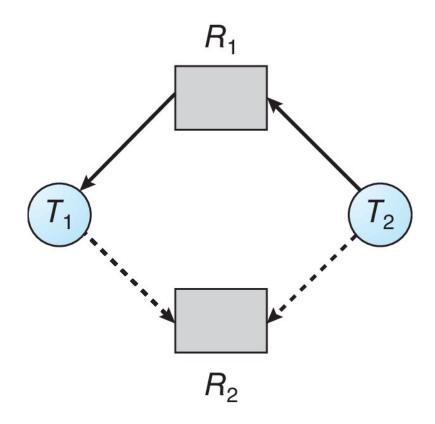
 Request edge converted to an assignment edge when the resource is allocated to the process.

Resource-Allocation Graph Scheme (cont.)

 When a resource is released by a process, assignment edge reconverts to a claim edge.

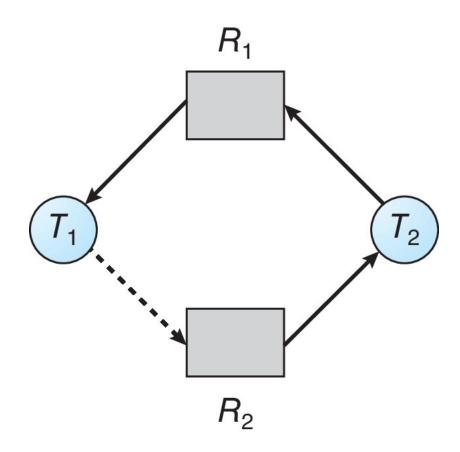
Resources must be claimed a priori in the system.

Resource-Allocation Graph





Unsafe State In Resource-Allocation Graph





Resource-Allocation Graph Algorithm

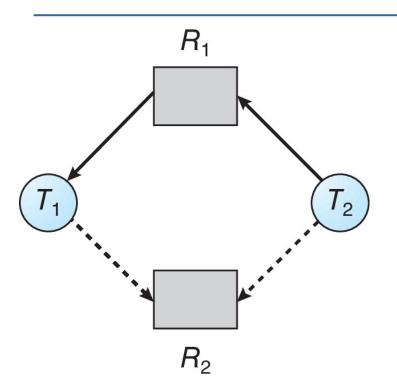
Suppose that process P_i requests a resource R_i.

The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph.

If a cycle is found, then the allocation will put the system in an unsafe state. In that case, thread T_i will have to wait for its requests to be satisfied.



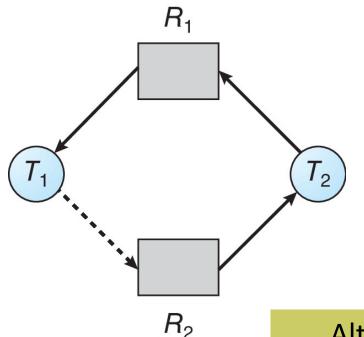
Example of Using the Algorithm



Suppose that T2 requests R2.

Can the request be granted?

Example of Using the Algorithm (Cont.)



Suppose that T_2 requests R_2 .

Can the request be granted?

Although R₂ is currently free, we cannot allocate it to T2, since this action will create a cycle in the graph.

A cycle, indicates that the system is in an unsafe state. If T_1 requests R_2 , and T_2 requests R_1 , then a deadlock will occur.

Deadlock Overview

https://www.youtube.com/watch?v=MYgmmJJfdBg



Banker's Algorithm

- Multiple instances of resources
- Each process must a priori claim maximum use
- When a process requests a resource it may have to wait
- When a process gets all its resources it must return them in a finite amount of time.



Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

• **Available**: Vector of length *m*.

If available [j] = k, there are k instances of resource type R_j available

Max: n x m matrix.

If Max[i,j] = k, then process P_i may request at most k instances of resource type R_i



Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

Allocation: n x m matrix.

If Allocation[i,j] = k then P_i is currently allocated k instances of R_i

Need: n x m matrix.

If Need[i,j] = k, then P_i may need k more instances of R_j to complete its task

$$Need[i,j] = Max[i,j] - Allocation[i,j]$$



Safety Algorithm

1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

```
Work = Available

Finish[i] = false for i = 0, 1, ..., n-1
```

- **2.** Find an *i* such that both:
 - (a) Finish[i] = false
 - (b) $Need_i \leq Work$

If no such i exists, go to step 4

- Work = Work + Allocation;
 Finish[i] = true
 go to step 2
- **4.** If *Finish*[*i*] == true for all *i*, then the system is in a safe state



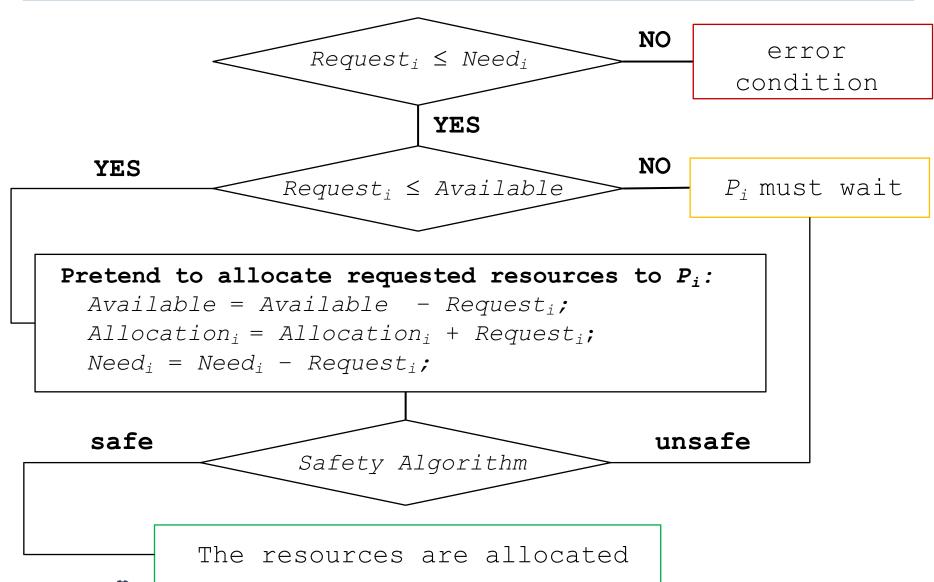
Resource-Request Algorithm for Process P_i

- Algorithm determines whether requests can be safely granted.
- Request_i = request vector for process P_i
- If $Request_i[j] = k$ then process P_i wants k instances of resource type R_j





Resource-Request Algorithm for Process P_i



Resource-Request Algorithm for Process P_i (cont.)

- 1. If $Request_i \leq Need_i$ go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim.
- 2. If $Request_i \le Available$, go to step 3. Otherwise, P_i must wait, since resources are not available.
- 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request;;

Allocation; = Allocation; + Request;;

Need; = Need; - Request;;
```

- If safe \Rightarrow the resources are allocated to P_i
- If unsafe $\Rightarrow P_i$ must wait, and the old resource-allocation state is restored



Example of Banker's Algorithm

5 processes P₀ through P₄;

3 resource types:

A (10 instances), B (5instances), and C (7 instances)

• Snapshot at time T_0 :

	<u>Allocation</u>	<u> Max</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	753	3 3 2
P_1	200	3 2 2	
P_2	302	902	
P_3	211	222	
P_4	002	4 3 3	



Example (cont.)

The content of the matrix Need is defined to be Max – Allocation

	<u>Allocation</u>	<u>Max</u>	<u>Available</u>		<u>Need</u>
	ABC	ABC	ABC		ABC
P_0	010	753	3 3 2	P_0	743
P_1	200	3 2 2		P_1	122
P_2	302	902		P_2	600
P_3	211	222		P_3	011
P_4	002	433		P_4	431

Is system in a safe state?



Example: P_1 Request (1,0,2)

• Check that Request \leq Available (that is, $(1,0,2) \leq (3,3,2) \Rightarrow$ true)

	<u>Allocation</u>	<u>Max</u> <u>Avai</u>	<u>lable</u>	_	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	ABC	ABC A	ВС		A B C	ABC	ABC
P_0	010	753 3	3 2	P_0	010	743	230
P_1	200	322		P_1	302	020	
P_2	302	902		P_2	302	600	
P_3	211	222		P_3	211	011	
P_4	002	433		P_4	002	431	

Executing safety algorithm shows that sequence $\langle P_1, P_3, P_4, P_0, P_2 \rangle$ satisfies safety requirement.



Example: P₀ Request (0,2,0)

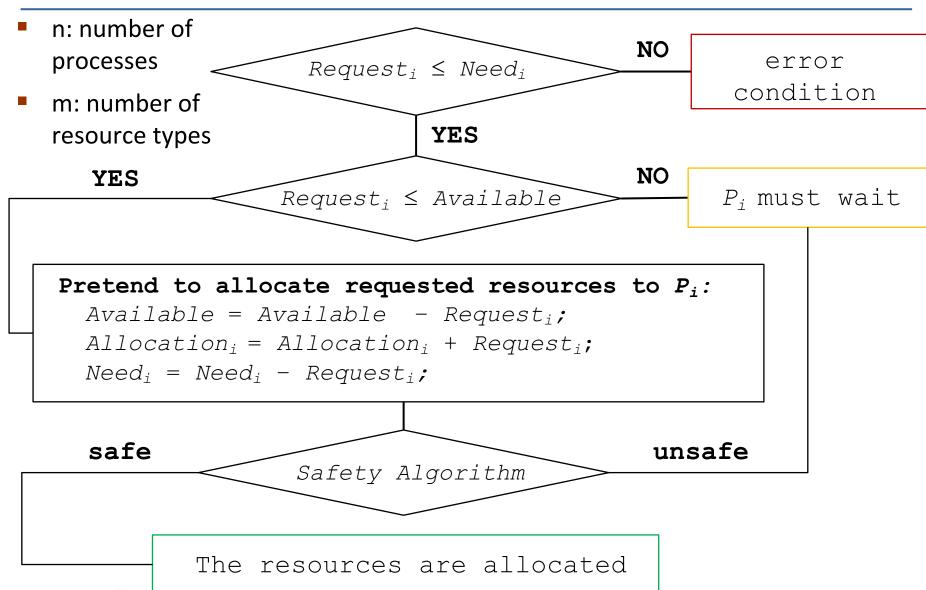
Current state (before P₀ request)

	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	743	230
P_1	302	020	
P_2	302	600	
P_3	211	011	
P_4	002	431	

Is the request granted?



Banker Algorithm Time Complexity



Safety Algorithm

```
BOOLEAN function SAFESTATE is -- Determines if current state is safe
{ NOCHANGE : boolean;
 WORK : array[1..m] of INTEGER = AVAILABLE;
 FINISH: array[1..n] of boolean = [false, ..,false];
  I : integer;
  repeat
   NOCHANGE = TRUE:
    for I = 1 to N do
                                        What is time complexity?
      if ((not FINISH[i]) and
         NEEDi <= WORK) then {
         WORK = WORK + ALLOCATION_i;
         FINISH[i] = true;
         NOCHANGE = false;
  until NOCHANGE;
  return (FINISH == (true, .., true));
```

https://cis.temple.edu/~ingargio/old/cis307f95/readings/deadlock.html

Amirkabir University of Technology (Tehran Polytechnic)

In Class Practice

تصویر زیر از سیستم را در نظر بگیرید (R=Resource ،P=Process)

Available						
RD RC RB RA						
7	9	5	8			

Maximum Demand						
RD	RC	RB	RA			
4	1	2	3	P0		
2	5	2	0	P1		
5	0	1	5	P2		
0	3	5	1	P3		
3	3	0	3	P4		

Current Allocation							
RD	RC	RB	RA				
1	1	0	1	P0			
1	2	1	0	P1			
3	0	0	4	P2			
0	1	2	1	P3			
0	3	0	1	P4			

به سوالات زیر با استفاده از الگوریتم بانکدار پاسخ دهید.

الف (۳ نمره): ماتریس needs را محاسبه کنید (نوشتن فرمول محاسبه این ماتریس و فرایند محاسبات شما الزامی است).

ب (۴ نمره): تعریف وضعیت safe در الگوریتم بانکدار چیست و ایا این سیستم در وضعیت safe است؟ اگر چنین است، ترتیبی امن (safe order) از اجرا پردازهها را بیان کنید. (نوشتن مراحل محسابات الزامی است)

پ (۳ نمره): ایا درخواست ۱ منبع از نوع RA توسط P0 میتواند طبق الگوریتم بانکدار به صورت امن (safely) برآورده شود؟ (نوشتن مراحل محسابات الزامی است)