# Technical University Munich Informatics



### Introduction to Deep Learning (IN 2346)

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## **Exercise 2: Math Background (Solution)**

### 1 Linear algebra

- a)  $A \in \mathbb{R}^{M \times N}, B \in \mathbb{R}^{M \times M}, C \in \mathbb{R}^{1 \times N}, D \in \mathbb{R}^{1 \times 1}$ .
- b)  $f(\mathbf{x}) = \sum_{i=1}^{N} \sum_{j=1}^{N} x_i x_j M_{ij} = \sum_{i=1}^{N} x_i \sum_{j=1}^{N} x_j M_{ij} = \sum_{i=1}^{N} x_i (\mathbf{M} \cdot \mathbf{x})_i = \mathbf{x}^{\top} \mathbf{M} \mathbf{x}.$
- c) Proof: Consider  $\|\boldsymbol{u} \boldsymbol{v}\|^2$ , we have:

$$\|\boldsymbol{u} - \boldsymbol{v}\|^2 = \langle \boldsymbol{u} - \boldsymbol{v}, \boldsymbol{u} - \boldsymbol{v} \rangle$$

$$= \langle \boldsymbol{u}, \boldsymbol{u} \rangle - \langle \boldsymbol{u}, \boldsymbol{v} \rangle - \langle \boldsymbol{v}, \boldsymbol{u} \rangle + \langle \boldsymbol{v}, \boldsymbol{v} \rangle$$

$$= \|\boldsymbol{u}\|^2 - 2\langle \boldsymbol{u}, \boldsymbol{v} \rangle + \|\boldsymbol{v}\|^2$$

$$= 0$$

Hence, u = v.

\* ||x|| refers to the L2-norm  $||x||_2$ , unless stated otherwise.

### 2 Linear Least Square

a) By definition of the gradient, we need to determine  $\nabla_{\boldsymbol{x}} f(\boldsymbol{x}) = \begin{pmatrix} \frac{\partial f(x)}{\partial x_1} \\ \frac{\partial f(x)}{\partial x_2} \\ \vdots \\ \frac{\partial f(x)}{\partial x_n} \end{pmatrix}$ . For  $1 \leq k \leq n$ , we have

$$\frac{\partial f(\boldsymbol{x})}{\partial x_k} = \frac{\partial}{\partial x_k} \left( \sum_{i=1}^n b_i x_i \right) = \sum_{i=1}^n \frac{\partial}{\partial x_k} \left( b_i x_i \right) = \sum_{i=1}^n \delta_{ik} b_i = b_k.$$

The Kronecker delta is defined as follows:  $\delta_{ij} = \begin{cases} 0 & \text{if } i \neq j, \\ 1 & \text{if } i = j. \end{cases}$ 

Hence, we obtain 
$$\nabla_{\boldsymbol{x}} f(\boldsymbol{x}) = \begin{pmatrix} \frac{\partial f(\boldsymbol{x})}{\partial x_1} \\ \frac{\partial f(\boldsymbol{x})}{\partial x_2} \\ \vdots \\ \frac{\partial f(\boldsymbol{x})}{\partial x_n} \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} = \boldsymbol{b}.$$

b) To determine the gradient of the function  $f(x) = x^{\top} A x$ , where A is a symmetric matrix in  $\mathbb{S}_n$ , we can use the definition of the gradient:

$$\nabla_{\boldsymbol{x}} f(\boldsymbol{x}) = \left[ \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right]$$

We start by computing the partial derivative of f with respect to  $x_i$ .

$$\frac{\partial f}{\partial x_i} = \frac{\partial}{\partial x_i} (\boldsymbol{x}^\top \cdot (\boldsymbol{A}\boldsymbol{x})) = \frac{\partial \boldsymbol{x}^\top}{\partial x_i} \cdot (\boldsymbol{A}\boldsymbol{x}) + \boldsymbol{x}^\top \cdot \frac{\partial (\boldsymbol{A}\boldsymbol{x})}{\partial x_i} = \boldsymbol{e_i}^\top \cdot (\boldsymbol{A}\boldsymbol{x}) + \boldsymbol{x}^\top \cdot \boldsymbol{A}\boldsymbol{e_i}$$
$$= \sum_{i} A_{ij} x_j + \sum_{i} A_{ij} x_j = 2 \sum_{i} A_{ij} x_j = 2(\boldsymbol{A}\boldsymbol{x})_i$$

where  $e_i$  is the standard basis vector in the *i*'th direction (1 at the *i*'th, and all other entries are 0's).

Thus, the gradient of f is:

$$\frac{\partial f(\boldsymbol{x})}{\partial \boldsymbol{x}} = [2(\boldsymbol{A}\boldsymbol{x})_1, 2(\boldsymbol{A}\boldsymbol{x})_2, \dots, 2(\boldsymbol{A}\boldsymbol{x})_n] = 2\boldsymbol{A}\boldsymbol{x}$$

Therefore, the gradient of the quadratic function  $f(x) = x^{\top} A x$  is  $\frac{\partial f}{\partial x} = 2Ax$ .

c) Let us first rewrite the expression:

$$f(x) = \|Ax - b\|_2^2$$
  
 $= (Ax - b)^{\top} (Ax - b)$   
 $= ((Ax)^{\top} - b^{\top}) (Ax - b)$   
 $= (x^{\top}A^{\top} - b^{\top}) (Ax - b)$   
 $= x^{\top}A^{\top}Ax - x^{\top}A^{\top}b - b^{\top}Ax + b^{\top}b$   
 $= x^{\top}A^{\top}Ax - 2x^{\top}A^{\top}b + b^{\top}b.$ 

Note that  $\boldsymbol{x}^{\top} \boldsymbol{A}^{\top} \boldsymbol{b} = \boldsymbol{b}^{\top} \boldsymbol{A} \boldsymbol{x}$ , because both result with a scalar. Since if  $s \in \mathbb{R} \to s^{\top} = s \to \boldsymbol{x}^{\top} \boldsymbol{A}^{\top} \boldsymbol{b} = (\boldsymbol{x}^{\top} \boldsymbol{A}^{\top} \boldsymbol{b})^{\top} = \boldsymbol{b}^{\top} \boldsymbol{A} \boldsymbol{x}$ .

Thus, by using part a)  $\rightarrow \frac{\partial \boldsymbol{b}^{\top} \boldsymbol{x}}{\partial \boldsymbol{x}} = \boldsymbol{b}$  and b)  $\rightarrow \frac{\partial \boldsymbol{x}^{\top} \boldsymbol{A} \boldsymbol{x}}{\partial \boldsymbol{x}} = 2\boldsymbol{A} \boldsymbol{x}$ , we obtain:

$$\nabla_{\boldsymbol{x}} f(\boldsymbol{x}) = \nabla_{\boldsymbol{x}} (\boldsymbol{x}^{\top} \boldsymbol{A}^{\top} \boldsymbol{A} \boldsymbol{x} - 2 \boldsymbol{x}^{\top} \boldsymbol{A}^{\top} \boldsymbol{b} + \boldsymbol{b}^{\top} \boldsymbol{b}) = \nabla_{\boldsymbol{x}} \boldsymbol{x}^{\top} \boldsymbol{A}^{\top} \boldsymbol{A} \boldsymbol{x} - \nabla_{\boldsymbol{x}} 2 \boldsymbol{x}^{\top} \boldsymbol{A}^{\top} \boldsymbol{b} + 0$$
$$= 2 \boldsymbol{A}^{\top} \boldsymbol{A} \boldsymbol{x} - 2 \boldsymbol{A}^{\top} \boldsymbol{b} = 2 \boldsymbol{A}^{\top} (\boldsymbol{A} \boldsymbol{x} - \boldsymbol{b})$$

### 3 Calculus - derivatives

a) The derivatives are:

• 
$$f_1'(x) = \left[ (x^3 + x + 1)^2 \right]' = 2(x^3 + x + 1)(x^3 + x + 1)' = 2(x^3 + x + 1)(3x^2 + 1)$$
  
•  $f_2'(x) = \left[ \frac{e^{2x} - 1}{e^{2x} + 1} \right]' = \frac{(e^{2x} - 1)'(e^{2x} + 1) - (e^{2x} - 1)(e^{2x} + 1)'}{(e^{2x} + 1)^2} = \frac{2e^{2x}(e^{2x} + 1) - (e^{2x} - 1)2e^{2x}}{(e^{2x} + 1)^2} = \frac{4e^{2x}}{(e^{2x} + 1)^2}$   
•  $f_3'(x) = \left[ (1 - x)\log(1 - x) \right]'$   
 $= \log(1 - x) \cdot (1 - x)' + (1 - x) \cdot \log'(1 - x)$   
 $= -\log(1 - x) + (1 - x) \cdot \frac{\partial \log(y)}{y} \cdot \frac{y}{x} = -\log(1 - x) + (1 - x) \cdot \frac{1}{1 - x} \cdot (1 - x)'$   
 $= -\log(1 - x) - 1$ 

b) The gradients are:

• 
$$\nabla f_4 = \frac{\partial}{\partial x} \left( \frac{1}{2} \| \boldsymbol{x} \|_2^2 \right) = \frac{\partial}{\partial x} \left( \frac{1}{2} \boldsymbol{x}^\top \boldsymbol{x} \right) = \frac{\partial}{\partial x} \left( \frac{1}{2} \boldsymbol{x}^\top I \boldsymbol{x} \right) = \frac{1}{2} \cdot 2Ix = \mathbf{x}$$
  
•  $\nabla f_5 = \frac{\partial}{\partial x} \left( \frac{1}{2} \| \boldsymbol{x} \|_2 \right) = \frac{\partial}{\partial x} \left( \frac{1}{2} \sqrt{\boldsymbol{x}^\top \boldsymbol{x}} \right) = \frac{1}{2} \cdot \frac{1}{2} (\boldsymbol{x}^\top \boldsymbol{x})^{-\frac{1}{2}} \cdot \frac{\partial (\boldsymbol{x}^\top \boldsymbol{x})}{x} = \frac{1}{2} \cdot \frac{1}{2} (\boldsymbol{x}^\top \boldsymbol{x})^{-\frac{1}{2}} \cdot 2I\boldsymbol{x} = \frac{1}{2} \frac{\boldsymbol{x}}{\|\boldsymbol{x}\|_2}$ 

c) The Jacobians are:

• 
$$J_{f_6} = \begin{bmatrix} \frac{\partial f_1}{\partial r} & \frac{\partial f_1}{\partial \varphi} \\ \frac{\partial f_2}{\partial r} & \frac{\partial f_2}{\partial \varphi} \end{bmatrix} = \begin{bmatrix} \cos(\varphi) & -r\sin(\varphi) \\ \sin(\varphi) & r\cos(\varphi) \end{bmatrix}$$
$$\begin{bmatrix} \frac{\partial f_1}{\partial t} \end{bmatrix} \begin{bmatrix} -r\sin t \end{bmatrix}$$

• 
$$J_{f_7} = \begin{bmatrix} \frac{\partial f_1}{\partial t} \\ \frac{\partial f_2}{\partial t} \end{bmatrix} = \begin{bmatrix} -r\sin t \\ r\cos t \end{bmatrix}$$

d) The divergences are:

• 
$$\operatorname{div} f_8 = \frac{\partial (-y)}{\partial x} + \frac{\partial x}{\partial y} = 0$$

• 
$$\operatorname{div} f_9 = \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} = 2$$

# 4 Sigmoid derivative

a) 
$$\frac{d}{dx}\sigma(x) = \frac{d}{dx}\frac{1}{1+e^{-x}} = \frac{d}{dx}(1+e^{-x})^{-\frac{1}{2}} = \frac{-(1+e^{-x})^{-2}(-e^{-x})}{(1+e^{-x})^2} = \frac{e^{-x}}{(1+e^{-x})^2}$$

b) 
$$\frac{e^{-x}}{(1+e^{-x})^2}$$

$$= \frac{e^{-x}+1-1}{(1+e^{-x})^2}$$

$$= \frac{1+e^x}{(1+e^x)^2} - \frac{1}{(1+e^{-x})^2}$$

$$= \frac{1}{1+e^{-x}} - \frac{1}{(1+e^{-x})^2}$$

$$= \frac{1}{1+e^{-x}} \left(1 - \frac{1}{1+e^{-x}}\right)$$

### 5 Softmax derivative

#### 5.1 1st approach - two cases

When deriving  $\sigma(z)$  with respect to z, there are  $n \times n$  partial derivates but we notice that they reduce to only two distinct kinds:

- $\hat{y}_i = \sigma(z)_i$  w.r.t  $z_i$ . For example, deriving  $\frac{e^{z_1}}{\sum_{k=1}^n e^{z_k}}$  w.r.t  $z_1$ .  $(z_1$  appears both in the nominator and in the denominator)
- $\hat{y}_i = \sigma(z)_i$  w.r.t  $z_j, i \neq j$ . For example, deriving  $\frac{e^{z_1}}{\sum_{k=1}^n e^{z_k}}$  w.r.t  $z_2$  ( $z_2$  appears only in the denominator).

We first derive the first kind:

$$\begin{split} \frac{\partial \hat{y}_1}{\partial z_1} &= \partial \left( \frac{e^{z_1}}{\sum_{k=1}^n e^{z_k}} \right) / \partial z_1 = \frac{e^{z_1} \cdot \sum_{k=1}^n e^{z_k} - e^{z_1} \cdot e^{z_1}}{\left( \sum_{k=1}^n e^{z_k} \right) \left( \sum_{k=1}^n e^{z_k} \right)} = \frac{e^{z_1} \left( \sum_{k=1}^n e^{z_k} - e^{z_1} \right)}{\left( \sum_{k=1}^n e^{z_k} \right) \left( \sum_{k=1}^n e^{z_k} \right)} = \\ &= \frac{e^{z_1}}{\left( \sum_{k=1}^n e^{z_k} \right)} \cdot \frac{\sum_{k=1}^n e^{z_k} - e^{z_1}}{\left( \sum_{k=1}^n e^{z_k} \right)} = \hat{y}_1 \cdot \left( 1 - \frac{e^{z_1}}{\sum_{k=1}^n e^{z_k}} \right) = \hat{y}_1 \cdot \left( 1 - \hat{y}_1 \right). \end{split}$$

In the last and second to last equality, we used a trick, or the observation, that we can express these terms in means of  $\hat{y}$ . In a similar fashion, we derive the second kind:

$$\frac{\partial \hat{y}_1}{\partial z_2} = \partial \left( \frac{e^{z_1}}{\sum_{k=1}^n e^{z_k}} \right) / \partial z_2 = \underbrace{\frac{0 \cdot \sum_{k=1}^n e^{z_k} - e^{z_2} \cdot e^{z_1}}{\left(\sum_{k=1}^n e^{z_k}\right) \left(\sum_{k=1}^n e^{z_k}\right)}}_{(\sum_{k=1}^n e^{z_k})} = -\frac{e^{z_2}}{\left(\sum_{k=1}^n e^{z_k}\right)} \cdot \frac{e^{z_1}}{\left(\sum_{k=1}^n e^{z_k}\right)} = -\hat{y}_1 \hat{y}_2.$$

In conclusion, the partial derivatives of the softmax layer  $\hat{y} = \sigma(z)$  with respect to its input z are given by:

$$\frac{\partial \hat{y}_i}{\partial z_j} = \begin{cases} \hat{y}_i \cdot (1 - \hat{y}_i) & i = j \\ -\hat{y}_i \hat{y}_j & i \neq j \end{cases}$$

### 5.2 2nd approach - solve all in one!

A nice trick to solve both cases in one. First, we derive:

$$\frac{\partial \log(s_i)}{\partial z_j} = \frac{1}{s_i} \frac{\partial s_i}{\partial z_j}$$

Therefore:

$$\frac{\partial s_i}{\partial z_j} = s_i \cdot \frac{1}{s_i} \frac{\partial s_i}{\partial z_j} = s_i \cdot \frac{\partial \log(s_i)}{\partial z_j} = s_i \frac{\partial}{\partial z_j} \log(\frac{e^{z_i}}{\sum_{k=1}^C e^{z_k}}) = s_i \frac{\partial}{\partial z_j} [z_i - \log(\sum_{k=1}^C e^{z_k})]$$

$$= s_i (\delta_{ij} - \frac{1}{\sum_{k=1}^C e^{z_k}} e^{z_j}) = s_i (\delta_{ij} - s_j)$$

With

$$\begin{cases} \delta_{ij} = 1 & i = j \\ \delta_{ij} = 0 & i \neq j \end{cases}$$

### 6 Probability

a) We use the definition of the variance, namely

$$Var(X) = \mathbb{E}[X^2] - \mathbb{E}[X]^2 \tag{1}$$

and equivalently,

$$\mathbb{E}[X^2] = \text{Var}(X) + \mathbb{E}[X]^2. \tag{2}$$

Since  $X, Y \sim \mathcal{N}(0, \sigma^2)$ , we are given that  $\mathbb{E}[X] = \mathbb{E}[Y] = 0$ . With these observations, we obtain

$$\operatorname{Var}(XY) \stackrel{(1)}{=} \mathbb{E}[X^{2}Y^{2}] - \mathbb{E}[XY]^{2}$$

$$\stackrel{(*)}{=} \mathbb{E}[X^{2}]\mathbb{E}[Y^{2}] - \mathbb{E}[X]^{2}\mathbb{E}[Y]^{2}$$

$$\stackrel{(2)}{=} (\operatorname{Var}(X) + \mathbb{E}[X]^{2})(\operatorname{Var}(Y) + \mathbb{E}[Y]^{2}) - \mathbb{E}[X]^{2}\mathbb{E}[Y]^{2}$$

$$= \operatorname{Var}(X)\operatorname{Var}(Y) + \operatorname{Var}(X)\underbrace{\mathbb{E}[Y]^{2}}_{=0} + \operatorname{Var}(Y)\underbrace{\mathbb{E}[X]^{2}}_{=0}$$

$$= \operatorname{Var}(X)\operatorname{Var}(Y)$$

(\*)X,Y are independent.

b) We use the properties of the expectation and the variance of a random variable. For the mean of Z, we observe:

$$\begin{split} \mathbb{E}[Z] &= \mathbb{E}\left[\frac{X - \mu}{\sigma}\right] \\ &= \frac{1}{\sigma} \cdot \mathbb{E}[X - \mu] \\ &= \frac{1}{\sigma} \cdot (\mathbb{E}[X] - \mathbb{E}[\mu]) \\ &= \frac{1}{\sigma} \cdot (\mu - \mu) \\ &= 0 \end{split}$$

For the variance, remember that:

$$\begin{aligned} &\operatorname{Var}\left[\frac{X-\mu}{\sigma}\right] \\ &= \mathbb{E}\left[\left(\frac{X-\mu}{\sigma} - \mathbb{E}\left[\frac{X-\mu}{\sigma}\right]\right)^2\right] \\ &= \mathbb{E}\left[\left(\frac{X-\mu}{\sigma} - \frac{\mathbb{E}[X]-\mu}{\sigma}\right)^2\right] \\ &= \mathbb{E}\left[\left(\frac{X-\mathbb{E}[X]}{\sigma}\right)^2\right] \\ &= \frac{1}{\sigma^2}\mathbb{E}\left[(X-\mathbb{E}[X])^2\right] \\ &= \frac{1}{\sigma^2} \cdot \operatorname{Var}[X]. \end{aligned}$$

Therefore, we observe that:

$$Var[Z]$$

$$= Var \left[ \frac{X - \mu}{\sigma} \right]$$

$$= \frac{1}{\sigma^2} Var[X]$$

$$= \frac{1}{\sigma^2} \sigma^2$$

$$= 1.$$

In summary, we conclude that  $Z \sim \mathcal{N}(0, 1)$ .