

Homework 2 - Theory Part

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1 Question 1

These two rules are applied in the following sections:

$$\mathbb{E}[A] = \mathbb{E}[A] + \mathbb{E}[B]$$

$$\mathbb{E}[(A + B)^2] = \mathbb{E}[A^2 + B^2 + 2AB] = \mathbb{E}[A^2] + \mathbb{E}[B^2] + 2\mathbb{E}[AB]$$

We can define the expected prediction error on (x', y') as a following term:

$$x' = \mathbb{E}_{\text{train}, y'} \left[(y' - h_D(x'))^2 \right]$$

$$\begin{aligned} \mathbb{E}_{\text{train}, y'} \left[(y' - h_D(x'))^2 \right] &= \mathbb{E}_{\text{train}, y'} \left[(f(x') + \epsilon - h_D(x'))^2 \right] \\ &= \mathbb{E}_{\text{train}, y'} \left[((f(x') - h_D(x')) + \epsilon)^2 \right] \\ &= \mathbb{E} \left[(f(x') - h_D(x'))^2 \right] + \mathbb{E}[\epsilon^2] + 2\mathbb{E}[(f(x') - h_D(x'))] \mathbb{E}[\epsilon] \\ &= \mathbb{E} \left[(f(x') - h_D(x'))^2 \right] + \sigma_\epsilon^2 \end{aligned}$$

Note that $\mathbb{E}[\epsilon] = 0$

We can now derive the first term from above result:

$$\begin{aligned} \mathbb{E} \left[(f(x') - h_D(x'))^2 \right] &= \mathbb{E} \left[(f(x') - h_D(x'))^2 \right] \\ &= \mathbb{E} \left[((f(x') - \mathbb{E}[h_D(x')]) + (\mathbb{E}[h_D(x')] - h_D(x')))^2 \right] \\ &= \mathbb{E} \left[(f(x') - \mathbb{E}[h_D(x')])^2 \right] + 2\mathbb{E}[(f(x') - \mathbb{E}[h_D(x')]) (\mathbb{E}[h_D(x')] - h_D(x'))] \\ &\quad + \mathbb{E}[(\mathbb{E}[h_D(x')] - h_D(x'))^2] \end{aligned}$$

We have the following facts:

$$\mathbb{E} \left[(f(x') - \mathbb{E}[h_D(x')])^2 \right] = \text{bias}^2$$

$$\mathbb{E} [(\mathbb{E} [h_D (x')] - h_D (x'))^2] = \textit{variance}$$

Note: the bias term is independent of the expectation operator, so by continuing on above expression, we have:

$$= \textit{bias}^2 + 2 \textit{bias} \mathbb{E} [(\mathbb{E} [h_D (x')] - h_D (x'))] + \textit{variance}$$

Since $\mathbb{E} [(\mathbb{E} [h_D (x')] - h_D (x'))] = 0$:

$$\mathbb{E} [(f(x') - h_D (x'))^2] = \sigma_\epsilon^2 + \textit{bias}^2 + \textit{variance}$$

2 Question 2

2.1 a

Yes

$$\phi(x) = \begin{cases} x^2 & \text{if } 2k \leq x < 2k+1 \\ -x^2 & \text{if } 2k+1 \leq x < 2k+2 \end{cases}$$

All Xs will have positive values and all Os will have negative values, so they are linearly separable.

2.2 b

Yes

$$\phi(x) = x_1 x_2$$

All yellow points will have positive values and all blue points will have negative values, so they are linearly separable; however, some blue(yellow) points in first(second) region may overlap with another points in third(fourth) region. For example, (2,2) which is a yellow point in the first region, will overlap with (-2,-2) in the third region, since $2 \times 2 = (-2) \times (-2) = 4$

2.3 c

Yes, we can define the radius of a circle by r , so one way to make the dataset linearly separable is presented in the following:

$$r^2 = x_1^2 + x_2^2$$

$$\phi(x) = \begin{cases} (x_1, x_2, x_1^2 + x_2^2) & \text{if } 2k \leq x < 2k+1 \\ (x_1, x_2, -(x_1^2 + x_2^2)) & \text{if } 2k+1 \leq x < 2k+2 \end{cases}$$

The kernel of the above feature map is:

$$K(x, x') = \phi(x)^T \phi(x') = \begin{cases} (x_1 x'_1, x_2 x'_2, (x_1^2 + x_2^2)((x'_1)^2 + (x'_2)^2)) & \text{if } 2k \leq x < 2k+1 \\ (x_1 x'_1, x_2 x'_2, -(x_1^2 + x_2^2)((x'_1)^2 + (x'_2)^2)) & \text{if } 2k+1 \leq x < 2k+2 \end{cases}$$

3 Question 3

3.1 a

$$\begin{aligned}\frac{df(x)}{dx} &= \frac{d(\log(x^4)\sin(x^3))}{dx} \\ &= \frac{d(\log(x^4))}{dx}\sin(x^3) + \frac{d(\sin(x^3))}{dx}\log(x^4) \\ &= \frac{4\sin(x^3)}{x} + 3x^2\cos(x^3)\log(x^4)\end{aligned}$$

3.2 b

$$\begin{aligned}\frac{d\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right)}{dx} &= -\frac{1}{2\sigma^2}2(x-\mu) = \frac{-(x-\mu)}{\sigma^2} \\ \frac{df(x)}{dx} &= \exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right) \frac{d\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right)}{dx} \\ &= \frac{-(x-\mu)}{\sigma^2} \exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right)\end{aligned}$$

3.3 c

i) Dimensions

The dimension of $\frac{\partial f_1}{\partial x}$ is 1×2 .

The dimension of $\frac{\partial f_2}{\partial x}$ is $1 \times n$.

The dimension of $\frac{\partial f_3}{\partial x}$ is $n^2 \times n$.

ii) Jacobians

The jacobian of f_1 :

$$\begin{aligned}\frac{\partial f_1}{\partial x} &= \left[\frac{\partial(\sin(x_1)\cos(x_2))}{\partial x_1} \quad \frac{\partial(\sin(x_1)\cos(x_2))}{\partial x_2} \right] \\ \frac{\partial f_1}{\partial x} &= \left[\cos(x_1)\cos(x_2) \quad -\sin(x_1)\sin(x_2) \right]\end{aligned}$$

The jacobian of f_2 :

$$f_2(x, y) = x^\top y = x_1y_1 + \cdots + x_ny_n$$

$$\frac{\partial f_1}{\partial x} = y^\top$$

The jacobian of f_3 :

$$x^\top x = \begin{bmatrix} x_1^2 & x_1 x_2 & \cdots & x_1 x_n \\ x_2 x_1 & x_2^2 & \cdots & x_2 x_n \\ \vdots & \vdots & \ddots & \vdots \\ x_n x_1 & x_n x_2 & \cdots & x_n^2 \end{bmatrix}$$

The derivative of the above matrix will be in the higher order.

The derivative of $x^\top x$ with respect to x_1 :

$$x^\top x = \begin{bmatrix} 2x_1 & x_2 & \cdots & x_n \\ x_1 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ x_1 & 0 & \cdots & 0 \end{bmatrix}$$

The derivative of $x^\top x$ with respect to x_2 :

$$x^\top x = \begin{bmatrix} 0 & x_1 & \cdots & 0 \\ x_1 & 2x_2 & \cdots & x_n \\ \vdots & \vdots & \ddots & \vdots \\ 0 & x_n & \cdots & 0 \end{bmatrix}$$

$$\vdots$$

And the derivative of $x^\top x$ with respect to x_n :

$$x^\top x = \begin{bmatrix} 0 & 0 & \cdots & x_1 \\ 0 & 0 & \cdots & x_2 \\ \vdots & \vdots & \ddots & \vdots \\ x_1 & x_2 & \cdots & 2x_n \end{bmatrix}$$

3.4 d

i)

The dimension of $\frac{df}{dz}$ is 1×1 , and it is: $-\frac{1}{2} \exp\left(-\frac{1}{2}z\right)$

The dimension of $\frac{dz}{dy}$ is $1 \times D$, and it is: $y^\top \left(S^{-1} + (S^{-1})^\top\right)$

The dimension of $\frac{dy}{dx}$ is $D \times D$, and it is a identity matrix.

In the chain rule, multiply all derivatives to get the final derivative.

ii)

The dimension of $\frac{df}{dx}$ is $1 \times D$:

$$f(x) = \text{tr}\left(xx^\top + \sigma I\right) = x_1^2 + \cdots + x_n^2 + n\sigma^2$$

So:

$$\frac{df}{dx} = 2x^\top$$

iii)

The dimension of $\frac{df}{dz}$ is $M \times M$

$$\frac{df}{dz} = \begin{bmatrix} 1 - \tanh^2(z_1) & 0 & \cdots & 0 \\ 0 & 1 - \tanh^2(z_2) & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 - \tanh^2(z_M) \end{bmatrix}$$

Or:

$$\frac{df}{dz} = \begin{bmatrix} \frac{1}{\cosh^2 z_1} & 0 & \cdots & 0 \\ 0 & \frac{1}{\cosh^2 z_2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \frac{1}{\cosh^2 z_M} \end{bmatrix}$$

The dimension of $\frac{dz}{dx}$ is $M \times N$

$$\frac{dz}{dx} = A$$

The final derivative is the product of each component.

4 Question 4

4.1 a

$$\begin{aligned} R(f) &= \mathbb{E}_{(x,y) \sim \mathcal{P}}[\ell(f(x), y)] \\ &= \mathbb{E}_{(x,y) \sim \mathcal{P}}[\mathbb{1}_{f(x) \neq y}] \\ &= P_{(x,y) \sim \mathcal{P}}(f(x) \neq y) \end{aligned}$$

4.2 b

$$\begin{aligned} P(g(x) \neq Y \mid X = x) &= 1 - P(Y = g(x) \mid X = x) \\ &= 1 - [P(Y = 0, g(x) = 0 \mid X = x) + P(Y = 1, g(x) = 1 \mid X = x)] \\ &= 1 - [\mathbb{E}[\mathbb{1}_{Y=1} \mathbb{1}_{g(x)=1} \mid X = x] + \mathbb{E}[\mathbb{1}_{Y=0} \mathbb{1}_{g(x)=0} \mid X = x]] \\ &= 1 - [\mathbb{1}_{g(x)=1} \mathbb{E}[\mathbb{1}_{Y=1} \mid X = x] + \mathbb{1}_{Y=0} \mathbb{E}[\mathbb{1}_{g(x)=0} \mid X = x]] \\ &= 1 - [\mathbb{1}_{g(x)=1} P(Y = 1 \mid X = x) + \mathbb{1}_{g(x)=0} P(Y = 0 \mid X = x)] \\ &= 1 - [\mathbb{1}_{g(x)=1} \eta(x) + \mathbb{1}_{g(x)=0} (1 - \eta(x))] \end{aligned}$$

4.3 c

$$\begin{aligned} P(g(x) \neq Y \mid X = x) - P(f^*(x) \neq Y \mid X = x) &= 1 - [\mathbb{1}_{g(x)=1} \eta(x) + \mathbb{1}_{g(x)=0} (1 - \eta(x))] \\ &\quad - [1 - [\mathbb{1}_{f^*(x)=1} \eta(x) + \mathbb{1}_{f^*(x)=0} (1 - \eta(x))]] \\ &= - [\mathbb{1}_{g(x)=1} \eta(x) + \mathbb{1}_{g(x)=0} (1 - \eta(x))] \\ &\quad + [\mathbb{1}_{f^*(x)=1} \eta(x) + \mathbb{1}_{f^*(x)=0} (1 - \eta(x))] \\ &= \eta(x) [\mathbb{1}_{f^*(x)=1} - \mathbb{1}_{g(x)=1}] + (1 - \eta(x)) [\mathbb{1}_{f^*(x)=0} - \mathbb{1}_{g(x)=0}] \\ &= \eta(x) [\mathbb{1}_{f^*(x)=1} - \mathbb{1}_{g(x)=1}] + (1 - \eta(x)) [\mathbb{1}_{g(x)=1} - \mathbb{1}_{f^*(x)=1}] \\ &= 2\eta(x) \mathbb{1}_{f^*(x)=1} - 2\eta(x) \mathbb{1}_{g(x)=1} + \mathbb{1}_{g(x)=1} - \mathbb{1}_{f^*(x)=1} \\ &= (2\eta(x) - 1) (\mathbb{1}_{\{f^*(x)=1\}} - \mathbb{1}_{\{g(x)=1\}}) \end{aligned}$$

4.4 d

From previous section we have:

$$P(g(x) \neq Y \mid X = x) - P(f^*(x) \neq Y \mid X = x) = (2\eta(x) - 1) (\mathbb{1}_{\{f^*(x)=1\}} - \mathbb{1}_{\{g(x)=1\}})$$

So $(2\eta(x) - 1) (\mathbb{1}_{\{f^*(x)=1\}} - \mathbb{1}_{\{g(x)=1\}}) \geq 0$ is equivalent to $P(g(x) \neq Y \mid X = x) \geq P(f^*(x) \neq Y \mid X = x)$,
wh

We also know:

$$f^*(x) = \begin{cases} 1, & \text{if } \eta(x) \geq 1/2 \\ 0, & \text{otherwise} \end{cases}$$

So:

1) If $\eta(x) \geq 1/2$ then, $(2\eta(x) - 1) \geq 0$ and $\left(\mathbb{1}_{\{f^*(x)=1\}} - \mathbb{1}_{\{g(x)=1\}}\right) \geq 0$ (since $f^*(x) = 1$), therefore the final value is non-negative.

2) If $\eta(x) \leq 1/2$ then, $(2\eta(x) - 1) \leq 0$ and $\left(\mathbb{1}_{\{f^*(x)=1\}} - \mathbb{1}_{\{g(x)=1\}}\right) \leq 0$ (since $f^*(x) = 0$), therefore the final value is non-negative.

From above two conditions: $(2\eta(x) - 1) \left(\mathbb{1}_{\{f^*(x)=1\}} - \mathbb{1}_{\{g(x)=1\}}\right) \geq 0$

4.5 e

Since we don't know the true distribution of P , we can't construct the η , and $f^*(x)$ isn't realizable.

5 Question 5

5.1 a

$$risk = \sum_D (y - h(x))^2$$

5.2 b

$$\begin{aligned} \mathbb{E}_{D \sim p} [\text{error}_{LOO}] &= \mathbb{E}_{D \sim p} \left[\frac{1}{n} \sum_{i=1}^n \ell \left(h_{D \setminus i}(x_i), y_i \right) \right] \\ &= \frac{1}{n} \sum_{i=1}^n \mathbb{E}_{D \sim p} \left[\ell \left(h_{D \setminus i}(x_i), y_i \right) \right] \\ &= \frac{1}{n} \sum_{i=1}^n \mathbb{E}_{\substack{D' \sim p, \\ (x, y) \sim p}} [\ell(h_{D'}(x), y)] \\ &= \mathbb{E}_{\substack{D' \sim p, \\ (x, y) \sim p}} \left[(y - h_{D'}(x))^2 \right] \end{aligned}$$

With $n - 1$ data points, the LOO error is an unbiased estimator risk of h'_D , therefore, when n is large we have unbiased estimator of risk of h_D .

5.3 c

From Linear Regression:

$$\theta^* = (X^\top X)^{-1} X^\top y$$

The complexity of multiplying $d \times n$ matrix by $n \times d$ matrix is $O(dnd)$, so we have the following total complexity:

$$O(dnd + d^3 + ddn + dn) = O(d^3 + d^2n)$$

5.4 d

$$\text{error}_{LOO} = \frac{1}{n} \sum_{i=1}^n \left(y_i - \left[\left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{X}_{-i}^\top \mathbf{y}_{-i} \right]^\top x_i \right)^2$$

So the complexity of the above formula will be:

$$O(n(dnd + d^3 + ddn + dn)) = O(n(d^3 + d^2n)) = O(nd^3 + d^2n^2)$$

5.5 e

From section d we have:

$$\begin{aligned} \text{error}_{LOO} &= \frac{1}{n} \sum_{i=1}^n \left(y_i - \left[\left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{X}_{-i}^\top \mathbf{y}_{-i} \right]^\top x_i \right)^2 \\ &= \frac{1}{n} \sum_{i=1}^n \left(y_i - \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i \right)^2 \end{aligned}$$

From the question and the above formula, we should show that the following statement is true:

$$y_i - \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i = \frac{y_i - \mathbf{w}^{*\top} \mathbf{x}_i}{1 - \mathbf{x}_i^\top \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i}$$

So:

$$\begin{aligned} \left(y_i - \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i \right) \left(1 - \mathbf{x}_i^\top \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i \right) &= y_i - \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i \\ &\quad - y_i \mathbf{x}_i^\top \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i + \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i \mathbf{x}_i^\top \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i \end{aligned}$$

Note, we know that $(\mathbf{X}^\top \mathbf{X}) = \mathbf{X}_{-i}^\top \mathbf{X}_{-i} + \mathbf{x}_i \mathbf{x}_i^\top$, so the last term of the above equation will be:

$$\begin{aligned} \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i \mathbf{x}_i^\top \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i &= \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \left(\mathbf{X}^\top \mathbf{X} - \mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right) \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i \\ &= \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i - \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i \end{aligned}$$

We can now apply this expression, to continue the previous derivation:

Note, we also know that $\mathbf{X} = (y_i \mathbf{x}_i^\top + \mathbf{y}_{-i}^\top \mathbf{X}_{-i})$

$$\begin{aligned} &= y_i - \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i \\ &\quad - y_i \mathbf{x}_i^\top \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i + \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}_{-i}^\top \mathbf{X}_{-i} \right)^{-1} \mathbf{x}_i \mathbf{x}_i^\top \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i \\ &= y_i - y_i \mathbf{x}_i^\top \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i - \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i \\ &= y_i - \left(y_i \mathbf{x}_i^\top + \mathbf{y}_{-i}^\top \mathbf{X}_{-i} \right) \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i \\ &= y_i - \left(\mathbf{y}^\top \mathbf{X} \right) \left(\mathbf{X}^\top \mathbf{X} \right)^{-1} \mathbf{x}_i \\ &= y_i - \mathbf{w}^{*\top} \mathbf{x}_i \end{aligned}$$

The complexity of the above expression is $O(d^3 + d^2 n)$, which is efficient than the expression in section d.