What's New in Version 1.20

- 1. Added 'Foreground texture'-setting to the BR-manager & 'Background texture'-setting to the background-rendering components, to get the image output as render texture.
- 2. Added Opaqueness-setting to the background-rendering components, to set image transparency.
- 3. Updated blob detector (BlobDetectionDemo-scene) to be more consistent across frames.
- 4. Fixed image mover and joint overlayer in BackgroundRemovalDemo5-scene.
- 5. Fixed 'Keep last pose' behavior in AvatarController-component.
- 6. (1.20.1) Fixed issue switching to DirectML body-tracking processing mode for non-Nvidia GPUs (thanks to Kasey Cole).
- 7. (1.20.1) Added sorting of sensors' list by serial number, to avoid device number inconsistencies (thanks to Jonah Wintrich).

What's New in Version 1.19.x

- 1. Added two new face demo scenes hat overlay & show face image.
- 2. Updated BackgroundRemovalDemo2-scene with a new 'Apply sensor pose'-option.
- 3. Updated body-spin filter, to be configurable if the user faces forward, backward or changes direction.
- 4. Added IsInitFailed()-method to KM, to provide information if the sensor initialization has failed.
- 5. Fixed avatar-floating issue in AvatarController, when the user enters the scene in non-stand-up pose.
- 6. Fixed AvatarController repositioning issue for some models, when 'Apply muscle limits' is utilized.
- 7. Fixed and improved the feet detection in AvatarController, when 'Grounded feet' is utilized.
- 8. Fixed the reset of sensor pose in K4A-sensor interface, to avoid the extra camera tilt.
- 9. (1.19.1) Added support for Orbbec's Femto Bolt and Femto Mega cameras.
- 10. (1.19.2) Updated AvatarController to better handle muscle limits and offset nodes.
- 11. (1.19.2) Added 'Keep last pose'-setting to AvatarController, to keep the avatar pose after the user gets lost.

- 1. Added 'Start depth sensors'-option to KM, to allow scene startup without turning on the depth sensors (thanks to Marco Ciccotelli).
- 2. Added 3d-movie demo-scene (thanks to Hannes Rose).
- 3. Added display of user-body image on screen for different sensors.
- 4. Fixed background-image components, when sensors get stopped (thanks to Edgaras Art).
- 5. Fixed sharp avatar rotations in AvatarController-component (thanks to Moritz Skowronski).
- 6. Fixed sending Kinect data to multiple clients over the network (thanks to Guo Wei Leong).
- 7. Fixed merging of user-bodies in case of multiple cameras (thanks to Levent Alpsal).
- 8. Fixed wrong knee rotation, when 'Ignore Z-coordinates' is turned on (thanks to flymanbox).
- 9. Fixed estimations of shoulder and elbow orientations in some special cases.

- **10.** Fixed mesh bounding box in SceneMeshRendererGpu & UserMeshRendererGpu-components (thanks to Benjamin King).
- 11. (1.18.1) Multiple updates and fixes in Kinect-related components, required by customers.
- 12. (1.18.1) Upgraded the project to Unity 2021.3.0f1 LTS.
- 13. (1.18.2) Updated net-client and net-server components to be more resilient to unstable networks.
- 14. (1.18.2) Fixed sensor pose estimation and the update of current frames in Azure Kinect interface.

What's New in Version 1.17.x

- 1. Added 'Joint position smoothing' & 'Joint velocity smoothing'-settings to KM, to provide smoothing of joint positions and joint velocity calculations (thanks to matmat_35 & Edgaras Artemciukas).
- 2. Added support of IL2CPP scripting backend to the Azure Kinect sensor interface (thanks to Jelvand).
- 3. Fixed the functionality of 'Show Allowed Users Only'-setting of KM (thanks to dbb0000).
- 4. Fixed the offset node to apply rotation in AvatarController (thanks to Martin Cvengros).
- 5. Fixed the ColorImageJointOverlayer-component to work with ForegroundRenderer in BackgroundRemovalDemo5-scene (thanks to Mateusz Pomaski).
- 6. (1.17.1) Added support to Azure Kinect Body Tracking SDK v1.1.1.
- 7. (1.17.1) Added sample to display blurred color-camera background (thanks to Edgaras Artemciukas).
- 8. (1.17.1) Added sample to play multiple sequential recordings (thanks to Lasse Munk).
- 9. (1.17.2) Fixed the K4A-plugin, to utilize Azure Kinect BT SDK v1.1.1
- 10. (1.17.2) Added 'Save recording'-option to the device streaming modes, to save the live sensor data to recording-file (thanks to Mikhail Slobiskiy).
- 11. (1.17.3) Fixed the K4A-plugin, to utilize Azure Kinect BT SDK v1.1.2
- 12. (1.17.3) Fixed sensor-relative-position issue, when user bodies get merged across multiple sensors (thanks to 남대현).

- Added support for Azure Kinect Body Tracking SDK v1.1.0 (big thanks to 葛西浩!).
- 2. Added optional bone colliders to the AvatarController-component.
- 3. Updated BackgroundUserBodyImage- & BackgroundColorCamUserImage-components to support individual user indexes (thanks to Tepat Huleux).
- 4. Fixed SceneMeshDemo and BackgroundRemovalDemo2-scenes to limit the space in camera coordinates (thanks to Tomas Durkin).
- 5. Fixed the dst/cst transfer issue in case of KinectNetServer running with ARKit sensor interface.
- 6. (1.16.1) Added 'Body tracking model type'-setting to the Kinect4AzureInterface-component, to allow switching between the full or lite body tracking models.
- 7. (1.16.1) Added KinectStatusChecker-component (thanks to Jess Deacon), and JointAngleCalculator-sample (thanks to Frank Fedel).
- 8. (1.16.1) Fixed body-merge issue in case of multiple RealSense sensors (thanks to Jorge Pelaez).
- 9. (1.16.2) Added 'Fixed step indices'-user detecttion order (thanks to Jasper Cook).
- 10. (1.16.2) Improved SwipeUp-gesture detection (thanks to Andy Cockayne).

11. (1.16.2) Fixed calculation of color & depth overlay positions in case of multiple sensors (thanks to Casey Farina).

What's New in Version 1.15

- 1. Added experimental Apple iPhone Pro & iPad Pro ARKit sensor interface (available on request).
- 2. Updated RealSense sensor interface with Cubemos body tracking v3.0 (available on request).
- 3. Updated multiple scenes & components in the package, to cope with the mobile sensor requirements.
- 4. Updated FollowSensorTransform-component & UserSkeletonCollider-component, to allow matching of depth or color camera poses (big thanks to Max Ellinger).
- 5. Added DepthSpriteViewerMulticam-component, to apply sensor-specific body collisions (thanks to Kurt Lorey).

What's New in Version 1.14

- 1. Added 2nd pose-detection scene, to demonstrate moving pose detection (thanks to Hogan Brown).
- 2. Added experimental Cubemos body tracking SDK support to the RealSense sensor interface (as separate download).
- 3. Updated the multi-camera setup scene and user-body-merger script, to provide better calibration of multiple sensors, as well as better merging of user bodies in multi-camera setups (big thanks to wangpeng, Juha Kauppinen and Janne Sormunen).
- 4. Updated 2d depth collider demo, to allow rotation of the depth collider (thanks to Vince Wloch).
- 5. Updated blob detector demo, to allow resizing of the background image (thanks to Jay Daligdig).
- 6. Added 'Portrait mode'-setting to the BodySlicer-component, to allow estimation of the body sizes, when the sensor is turned sideways (thanks to Fabian Wiedenstridt).
- 7. Added color-camera aligned user-silhouette background component, to allow color camera overlay (thanks to Max Jourdain).

- 1. Added 3rd overlay demo scene, to utilize the HandOverlayer-component (thanks to Edgaras Art).
- 2. Added photo-booth overlay demo scene, to demonstrate how to manage multiple joint overlays in 2D mode, gesture detection and hand grip interaction, all in one scene.
- 3. Added color-camera IR frame transformation API, to be used when needed.
- 4. Updated the scene-mesh and user-mesh scenes, components and shaders, to support HDRP & URP.
- 5. Replaced UserBodyBlender with SceneBlendRenderer-component in the fitting room demo-scenes, to support HDRP & URP (thanks to Fernando Gonzalez).
- 6. Updated the BackgroundRemovalByDist-component to support different max left & right distances (thanks to Mark Dodson).
- 7. Updated the AvatarController-comp. to use unscaled time for smoothing (thanks to Ruben Gonzalez).
- 8. Fixed 'Point cloud player list'-issue when using multiple sensors (thanks to Ashlee Lim).

9. Fixed BackgroundRemovalByBodyBounds-component in camera ortho mode (thanks to sukim).

What's New in Version 1.12.x

- 1. Added two green-screen demo scenes and related components, to provide better background segmentation, with volumetric blending and lighting options (thanks to Clyde DeSouza).
- 2. Added 'Horizontal movement'-setting to the AvatarController-component, to allow in-place avatar movements (thanks to Lawrence Horwitz).
- 3. Added HmdHeadMover-component, to allow HMD-controlled avatar movement on VR platforms (thanks to Miguel Angel Cienfuegos Tellez).
- 4. Added optional frame synchronization between the master and subordinate K4A-devices.
- 5. Added 'Use synchronized samples'-option to the MultiCameraSetup-component, to allow camera pose estimation on synchronized frames (thanks to Jesse Kirberger).
- 6. Added MoveLeft & MoveRight gestures (thanks to Indra Adi D. C).
- 7. Updated most of the scene materials to support HDRP. Some custom shaders may still not work.
- 8. Updated SimpleHoloCamera-component to respect the camera pose (thanks to Ajay Kumar).
- 9. Fixed cursor position issue in the MouseControl-component (thanks to Fedor Savchenko).
- 10. Fixed canvas scaling issue in the InteractionManager-component (thanks to Raymond Tsang).
- 11. (1.12.1) Fixed the reported issues in v1.12 and improved the multi-camera setup.

What's New in Version 1.11

- 1. Added experimental InteractionManager & InteractionInputModule-components, to manage user hand interactions (grip and release).
- 2. Added experimental interaction demo scenes, to show how to utilize hand grips & releases for interaction with virtual objects and UI.
- 3. Added SetSensorMinMaxIrValues() to KM, to set the values used for IR-texture generation (thanks to Carl Emil Carlsen)
- 4. Added EnableSensorPoseData() to KM to enable/disable the pose stream (thanks to Ruben Gonzalez).
- 5. Updated FollowSensorTransform to match the depth sensor pose (thanks to Fedor Savchenko).
- 6. Fixed the issue with persistent data-path, when called out of the main thread by NetClientInterface (thanks to Robert LiKamWa).
- 7. Upgraded K4A plugin to Azure Kinect Sensor SDK v1.4.0 & Body Tracking SDK v1.0.1.

- 1. Added DepthIrFilterDemo-scene, to show how to get depth-filtered IR image (thanks to Krystian Babilinski).
- 2. Added the BodySlicer-component and HeightEstimatorDemo-scene (thanks to Fernando Gonzalez).
- 3. Added Holographic Viewer Demo-scene, to demonstrate simple holographic scene view.
- 4. Added 'Detect floor for pose estimation'-setting to the Kinect4AzureInterface-component.

- 5. Added FollowUserJointPose-component to allow first person experiences (thanks to 이상철).
- 6. Updated BackgroundRemovalManager to support multiple instances (thanks to Sangjin Lee).
- 7. Updated blob detector to respect different camera resolutions (thanks to Jay Daligdig).

What's New in Version 1.9.x

- 1. Added user body merger, to merge the sensor-detected users, when multiple sensors are connected and properly calibrated (big thanks to Cy-Fighter LLC http://cy-fighter.com).
- 2. Updated MultiCameraSetup-scene to provide manual adjustment of the camera poses, after the automatic pose estimation is complete.
- 3. Added depth-color and body-depth frame synchronization to the net-client sensor interface.
- 4. Added automatic net-server discovery option to the net-client sensor interface (LAN only).
- 5. Added KinectEventManager-component, to deliver frame events to the registered listeners.
- 6. Updated thread waiting times, to lower CPU utilizations (thanks to Sheng Jiang).
- 7. Moved background-removal-by-body-bounds filter to separate component.
- 8. (v1.9.1) Added 'Loop playback'-setting to the K4A-interface (thanks to Vincenzo Lancianese).
- 9. (v1.9.1) Updated to Azure Kinect Body Tracking SDK v1.0.0.
- 10. (v1.9.1) Many small fixes and updates in various scripts, components and scenes.
- 11. (v1.9.2) Added methods to KM, to start and stop the depth sensors (thanks to Tom Goethals).
- 12. (v1.9.2) Added 'Console log messages'-option to KinectManager (thanks to cecarlsen).
- 13. (v1.9.2) Updated MultiCameraSetup, to utilize multiple body joints and motion smoothing.
- 14. (v1.9.2) Added 'Point cloud player list'-setting to the sensor interfaces, to allow filtering of bodies by the point-cloud vertex shader (thanks to Vincenzo Lancianese).

What's New in Version 1.8

- 1. Updated to Azure Kinect Body Tracking SDK v0.9.5 with multiple instance support.
- 2. Added MultiCameraSetup-scene, to automatically detect the positions and rotations of the sensors in a multi-camera setup.
- 3. Added 'Use multi-cam config'-setting to KinectManager, to utilize the sensor configuration, as saved by the MultiCameraSetup-scene.
- 4. Implemented simple fusion of the body joints, when multiple calibrated cameras are used.
- 5. Added BackgroundRemovalDemo3-scene and BackgroundRemovalByBodyIndex-component, to filter users by the detected body indices.
- 6. Added compression and decompression of the raw data frames in net-server and net-client interface.
- 7. Updated the classic mesh renderer scripts, to build the mesh in a separate thread and to support color camera resolution (thanks to N. Naydenov & G. Martini).

- 1. Added KinectNetServer-component to share sensor streams over the network, and KinectNetServer-scene to act as network server for the connected sensor.
- 2. Added NetClientInterface-component to receive the sensor streams over the network, as well as NetClientDemo1-demo to show the network sensor functionality.
- 3. Added 'Finger orientations'-setting to AvatarController, to determine whether the model should reflect the user's finger orientations or not.
- 4. Added 'Mesh texture'-setting to SceneMeshRendererGpu & UserMeshRendererGpu components, to select between the color and infrared textures (thanks to Alan).
- 5. Added UserSkeletonCollider-component to UserMeshDemo-scene, to provide collisions with physical objects (thanks to Daniel Gontz).
- 6. Fixed "missing hands" issue, when the user is far from the sensor (thanks to Nayden).
- 7. Added caching of space tables, to improve the scene load time (thanks to Gianluca Martini).
- 8. (1.7.1) Updated KinectNetServer & NetClientInterface to exchange transformed depth & color frames.
- 9. (1.7.1) Fixed user-tracking bug in Kinect2Interface and AvatarMatcher-script (thanks to Hao Tseng).
- 10. (1.7.1) Added 'Users face backwards'-setting to Kinect2Interface (thanks to Leif Dehmelt).

What's New in Version 1.6

- 1. Added BackgroundRemovalDemo4 scene, to show how to display virtual environment within the user's silhouette.
- 2. Added BackgroundRemovalDemo5 scene, to demonstrate how to display the user's silhouette in a 3d scene, according to the user's distance to the sensor.
- 3. Upgraded K4A plugin to Azure Kinect Sensor SDK v1.3.0 & Body Tracking SDK v0.9.4. Updated sensor interfaces to support the new hand-related joints, as well as the joint tracking states.
- 4. Added 'Ignore inferred joints'-setting to the KinectManager-component, to determine whether to consider or ignore the inferred joints.
- 5. Updated SceneMeshDemo & UserMeshDemo-scenes to undistort the mesh and to apply scene lighting (big thanks to Alan & Gianluca Martini).

What's New in Version 1.5

- 1. Added BodyDataRecorderDemo scene, to show how to record and replay the user body data.
- 2. Added PlayerDetectorDemo scene, to demonstrate how to play a recording, when no user is present.
- 3. Updated SceneMeshDemo scene, to create and update the scene mesh on GPU instead of CPU.
- 4. Updated UserMeshDemo scene, to create and update the user mesh on GPU instead of CPU.
- 5. Fixed model's head rotation in the AvatarController-component (big thanks to N. Naydenov).

- 1. Added MoCap-Animator demo scene, to demonstrate motion capturing into Unity animation.
- 2. Added SceneMeshDemo scene, to show how to integrate part of the real environment into the scene.

- 3. Added UserMeshDemo scene, to show how to integrate the user into the scene.
- 4. Added 2nd background-removal demo scene, to demonstrate how to display part of the real environment on virtual background.
- 5. Updated K4A plugin to use Azure Kinect Body Tracking SDK 0.9.3.

What's New in Version 1.3

- 1. Added background-removal demo scene, to show how to display user bodies on virtual background.
- 2. Added pose detection demo scene, to demonstrate how to detect the user matching static pose.
- 3. Added infrared image texture as an option of getting IR frames and displaying them on screen (big thanks to Gianluca Martini).
- 4. Updated K4A plugin to use the Azure Kinect Body Tracking SDK 0.9.2.
- 5. Fixed K4A interface issue, when the device's sync mode is Master (big thanks to Andreas Pedroni).

What's New in Version 1.2

- 1. Added two fitting-room demo scenes, to demonstrate humanoid model overlays.
- 2. Added experimental RealSense body tracking. It's in preview state, far from perfect yet.
- 3. Added horizontal, vertical & forward offset settings to the JointOverlayer-component, to allow better adjustment of the overlaying object.
- 4. Added more visual effects to the point-cloud demo scene.
- 5. Updated K4A plugin to Azure Kinect Sensor SDK 1.2.
- 6. Fixed setting of K4A color and depth modes that require 15 fps.
- 7. Fixed play-recording in the Azure Kinect interface.

- 1. Replaced DepthEngine 1.0 with 2.0, to conform to Azure Kinect Sensor SDK 1.2.
- 2. Added two gesture demo scenes, to demonstrate discrete and continuous gesture tracking.
- 3. Added multi-scene demo, to show how to use the KinectManager in multi-scene projects.
- 4. Added 'Point cloud resolution'-setting to the sensor interface components, to allow depth-to-color and color-to-depth image conversions.
- 5. Added IMU rotation tracking and FollowSensorTransform-component, to allow sensor pose tracking.
- 6. Fixed AvatarController issue that caused the model to freeze, when the user ID changes.
- 7. Multiple updates, improvements and bug fixes, reported by the users.