

$\text{dist}(p_1, p_4) = r_1 \rightarrow D_1: O, p_1, p_4: S$   
 $\text{dist}(p_1, p_2) = r_2 \rightarrow D_2: O, p_1, p_2: S$   
 $\text{dist}(p_2, p_3) = r_2 \rightarrow D_3: O, p_1, p_3: S$   
 $\text{dist}(p_3, p_4) = r_1 \rightarrow D_4: O, p_3, p_4: S$   
 $\text{angle}(p_1, p_4) = \delta_1$

$\text{fix}(p_4) = p: \text{dist}(O, p_4) \& \text{angle}(p_4)$   
 $\text{fix}(p_3) = p$   
 $\text{fix}(p_3, p_4)$

