

## SVR

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## SVM Categorization

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## SVM

### ❖ SVM

- ▶ SVC (Support Vector Classification)
- ▶ SVR (Support Vector Regression)

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## Support Vector Regression (SVR)

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## Contents

- ❖ Linear Support Vector Regression
- ❖ Nonlinear Support Vector Regression
- ❖ Conclusion

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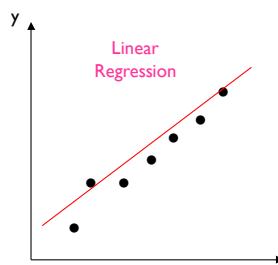
## Regression

- ❖ Given training data:

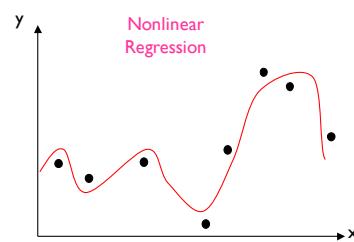
$$\{ (x_1, y_1), \dots, (x_n, y_n) \}, \quad x_i \in \mathbb{R}^d, y_i \in \mathbb{R}$$

- ❖ Find function:

$$f : \mathbb{R}^d \rightarrow \mathbb{R}$$



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## Regression

- ❖ “*best function*” or “*best approximation*”:

the expected error on *unseen data*  $(x_{n+1}, y_{n+1}), \dots, (x_{n+k}, y_{n+k})$  is minimal.

- ❖ As *unseen data are not available*

► The goal is to minimize *Residual Sum of Squared (RSS)*

$$RSS = \sum_{i=1}^n (y_i^{\text{expected}} - y_i)^2 = \sum_{i=1}^n (f(x_i) - y_i)^2$$

► The goal is to minimize *Root Mean Squared Error (RMS)*

$$RMS = \sqrt{\frac{1}{n} \sum_{i=1}^n (y_i^{\text{expected}} - y_i)^2} = \sqrt{\frac{1}{n} \sum_{i=1}^n (f(x_i) - y_i)^2}$$

- ❖ Existing techniques to solve the classification task:

- Classical (Linear) Regression
- NN

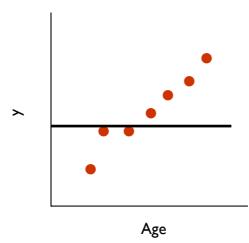
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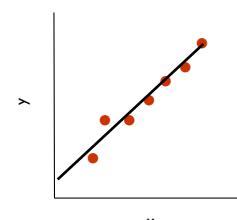
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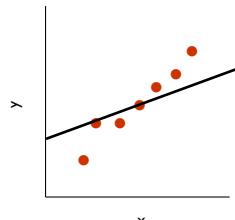
## Linear SVR



“Lazy case”  
(underfitting)



“Suspiciously smart case”  
(overfitting)



“Compromise case”, SVR  
(good generalizability)

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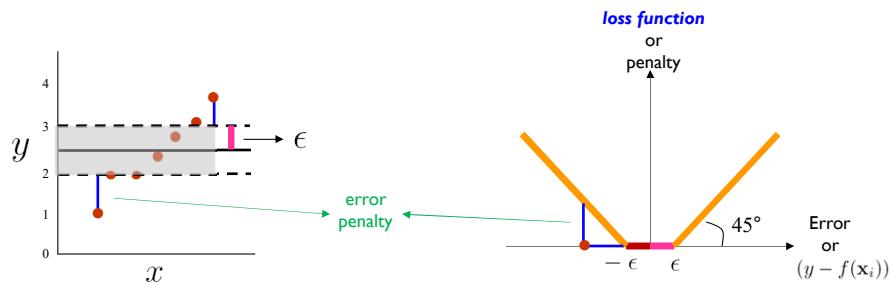
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## Linear SVR

The  $\epsilon$ -insensitive loss function



$$y = w_1 x + b$$

$$w_1 = 0$$

$$b = 2.5$$

$$|y_i - f(\mathbf{x}_i)|_\epsilon \equiv \max\{0, |y_i - f(\mathbf{x}_i)| - \epsilon\}$$

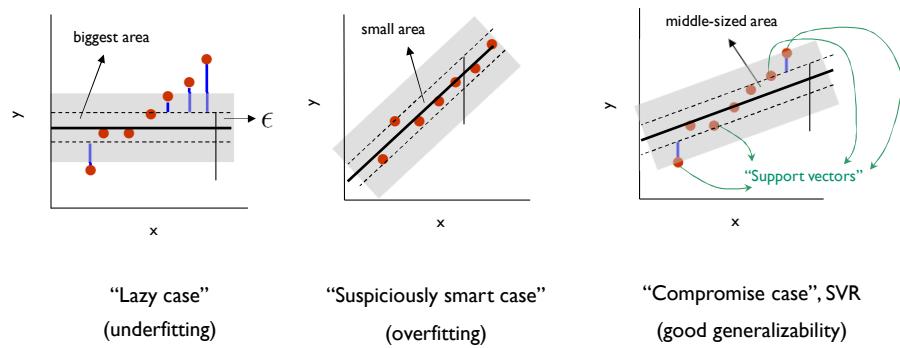
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## Linear SVR



“Lazy case”  
(underfitting)

“Suspiciously smart case”  
(overfitting)

“Compromise case”, SVR  
(good generalizability)

❖ The thinner the “tube”, the more complex the model

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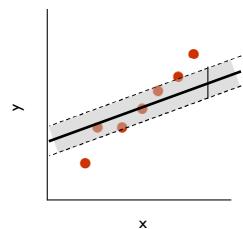
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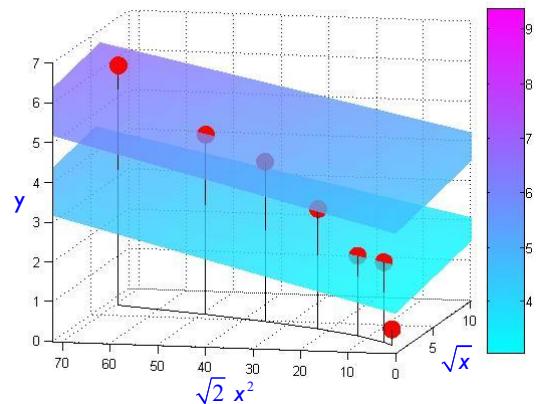
## Non-linear SVR

- ❖ Map the data into a *higher-dimensional space*:

$$x \rightarrow \Phi(x) = (\sqrt{x}, \sqrt{2}x^2)$$



$$y = w_1 x + b$$



$$y = w_1 \sqrt{x} + w_2 \sqrt{2}x^2 + b$$

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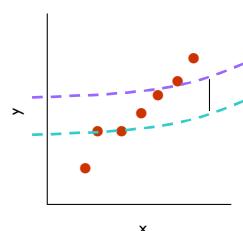
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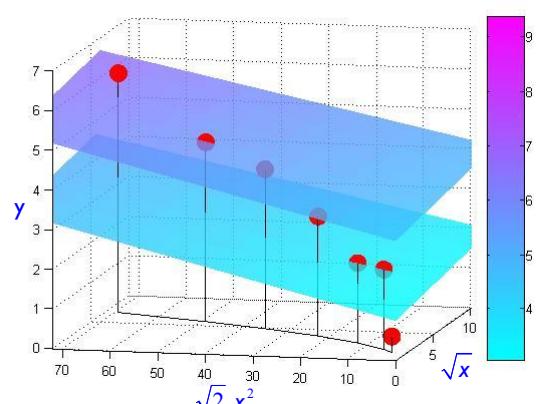
## Non-linear SVR

- ❖ Map the data into a *higher-dimensional space*:

$$x \rightarrow \Phi(x) = (\sqrt{x}, \sqrt{2}x^2)$$



$$y = \mathbf{w}'\Phi(x) + b$$



$$y = w_1 \sqrt{x} + w_2 \sqrt{2}x^2 + b$$

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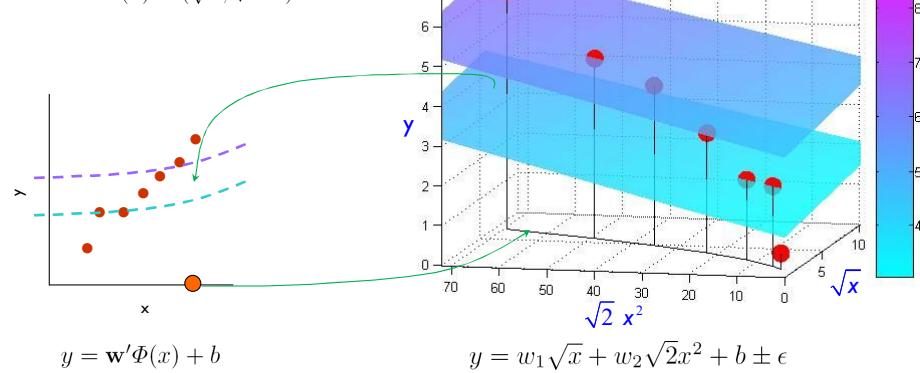
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## Non-linear SVR

- ❖ Map the data into a *higher-dimensional space*:

$$x \rightarrow \Phi(x) = (\sqrt{x}, \sqrt{2}x^2)$$



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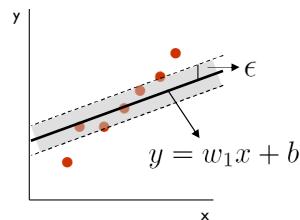
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## Linear SVR: derivation

- ❖ Given training data  $\{x_i, y_i\}_{i=1}^n$

- ❖ Find:  $w_1, b$   
such that  $y = w_1x + b$  optimally describes the data:



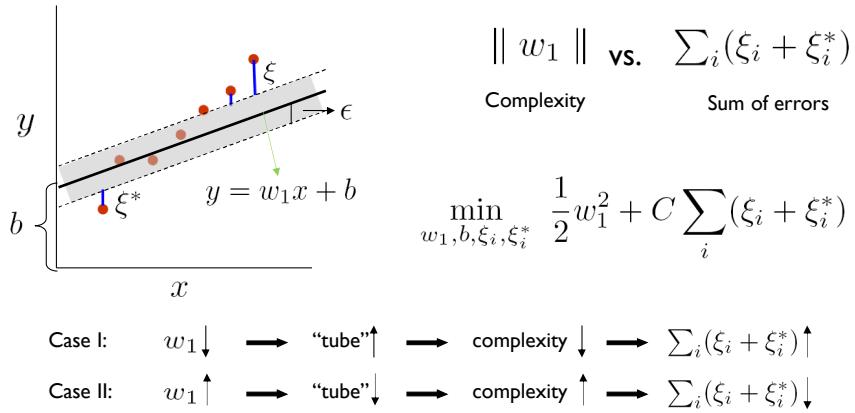
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## Linear SVR: derivation



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## Linear SVR: derivation

$$\min_{w_1, b, \xi_i, \xi_i^*} \frac{1}{2} w_1^2 + C \sum_i (\xi_i + \xi_i^*)$$



- Case I:  $w_1 \downarrow \rightarrow$  "tube"  $\uparrow \rightarrow$  complexity  $\downarrow \rightarrow \sum_i (\xi_i + \xi_i^*) \uparrow$   
Case II:  $w_1 \uparrow \rightarrow$  "tube"  $\downarrow \rightarrow$  complexity  $\uparrow \rightarrow \sum_i (\xi_i + \xi_i^*) \downarrow$

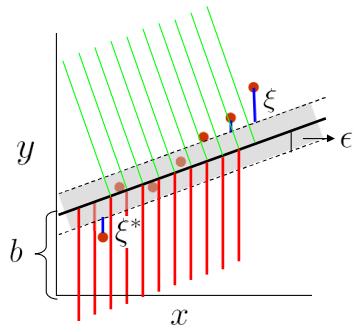
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## Linear SVR: derivation



$$\begin{aligned} & \min_{w_1, b, \xi_i, \xi_i^*} \frac{1}{2} w_1^2 + C \sum_i (\xi_i + \xi_i^*) \\ \text{s.t.:} \quad & y_i - [(w_1 x_{i1}) + b] \leq \epsilon + \xi_i \quad \text{\textbackslash\textbackslash\textbackslash} \\ & [(w_1 x_{i1}) + b] - y_i \leq \epsilon + \xi_i^* \quad \text{\textbar\textbar\textbar} \\ & \xi_i, \xi_i^* \geq 0 \quad i = 1, 2, \dots, n \end{aligned}$$

$$y = w_1 x + b$$

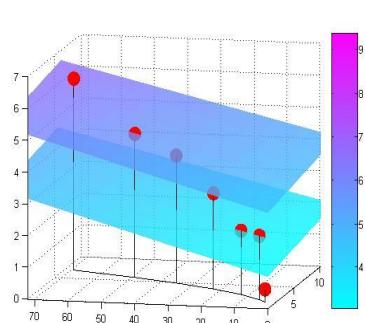
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## Non-linear SVR: derivation



$$\begin{aligned} & \min_{w_1, b, \xi_i, \xi_i^*} \frac{w_1^2 + w_2^2}{2} + C \sum_i (\xi_i + \xi_i^*) \\ \text{s.t.:} \quad & y_i - (\mathbf{w}' \phi(x_{i1})) - b \leq \epsilon + \xi_i \\ & (\mathbf{w}' \phi(x_{i1})) + b - y_i \leq \epsilon + \xi_i^* \\ & \xi_i, \xi_i^* \geq 0 \quad i = 1, 2, \dots, n \end{aligned}$$

$$y = \mathbf{w}' \Phi(x) + b$$

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## Non-linear SVR: derivation

$$\begin{aligned} \min_{\mathbf{w}, b, \xi_i, \xi_i^*} \quad & \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i (\xi_i + \xi_i^*) \\ \text{s.t.:} \quad & \left. \begin{array}{l} y_i - (\mathbf{w}' \phi(\mathbf{x}_i)) - b \leq \epsilon + \xi_i \\ (\mathbf{w}' \phi(\mathbf{x}_i)) + b - y_i \leq \epsilon + \xi_i^* \\ \xi_i, \xi_i^* \geq 0 \quad i = 1, 2, \dots, n \end{array} \right\} \quad \text{These are } g_i(\mathbf{x}) \leq 0 \end{aligned}$$

$$L := \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i (\xi_i + \xi_i^*) - \sum_i (\eta_i \xi_i + \eta_i^* \xi_i^*) \\ - \sum_i \alpha_i (\epsilon + \xi_i - y_i + \mathbf{w}' \phi(\mathbf{x}_i) + b) - \sum_i \alpha_i^* (\epsilon + \xi_i^* + y_i - \mathbf{w}' \phi(\mathbf{x}_i) - b)$$

❖ Since all constraints are inequality constraints, Lagrangian multiplier should satisfy KKT condition, i.e.  $\alpha_i, \alpha_i^*, \xi_i, \xi_i^* \geq 0$

❖ Saddle point of  $L$  has to be found:

$$\begin{array}{ll} \min \text{ with respect to} & \mathbf{w}, b, \xi_i, \xi_i^* \\ \max \text{ with respect to} & \alpha_i, \alpha_i^*, \eta_i, \eta_i^* \end{array}$$

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## Non-linear SVR: derivation

$$L := \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i (\xi_i + \xi_i^*) - \sum_i (\eta_i \xi_i + \eta_i^* \xi_i^*) \\ - \sum_i \alpha_i (\epsilon + \xi_i - y_i + \mathbf{w}' \phi(\mathbf{x}_i) + b) - \sum_i \alpha_i^* (\epsilon + \xi_i^* + y_i - \mathbf{w}' \phi(\mathbf{x}_i) - b)$$

$$\begin{aligned} \frac{\partial L}{\partial \mathbf{w}} = \mathbf{w} - \sum_i (\alpha_i - \alpha_i^*) \phi(\mathbf{x}_i) = 0 \\ \dots \\ \text{regression hyperplane in } \phi \text{ space:} \\ f(\mathbf{x}) = \mathbf{w}' \phi(\mathbf{x}) + b \end{aligned}$$

→  $f(\mathbf{x}) = \sum_i (\alpha_i - \alpha_i^*) (\phi(\mathbf{x}_i)' \phi(\mathbf{x})) + b$   
 $f(\mathbf{x}) = \sum_i (\alpha_i - \alpha_i^*) k(\mathbf{x}_i, \mathbf{x}) + b$

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## Strengths and Weaknesses of SVR

### ❖ Strengths of SVR:

- ▶ No local minima
- ▶ It scales relatively well to high dimensional data
- ▶ Trade-off between complexity and error can be controlled explicitly via  $C$  and  $\epsilon$
- ▶ Overfitting is avoided (for any fixed  $C$  and  $\epsilon$ )
- ▶ Robustness of the results
- ▶ "Huber (1964) demonstrated that the best cost function over the worst model over any pdf of  $y$  given  $x$  is the linear cost function. Therefore, if the pdf  $p(y|x)$  is unknown the best cost function is the linear penalization over the errors" (Perez-Cruz et al., 2003)

### ❖ Weaknesses of SVR:

- ▶ What is the best trade-off parameter  $C$  and best  $\epsilon$ ?
- ▶ What is a good transformation of the original space