

SVR

1

SVM Categorization

2

SVM

❖ SVM

- ▶ SVC (Support Vector Classification)
- ▶ SVR (Support Vector Regression)

▶ 3

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

3

Support Vector Regression (SVR)

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

4

Contents

- ❖ Linear Support Vector Regression
- ❖ Nonlinear Support Vector Regression
- ❖ Conclusion

► 5

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

5

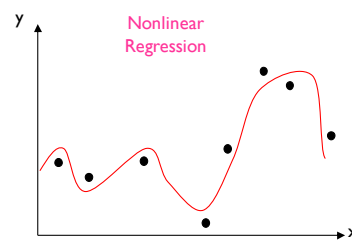
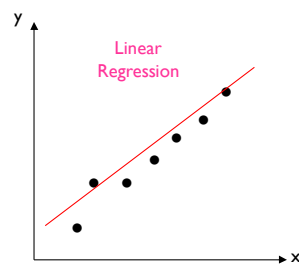
Regression

- ❖ Given training data:

$$\{ (x_1, y_1), \dots, (x_n, y_n) \}, \quad x_i \in \mathbb{R}^d, y_i \in \mathbb{R}$$

- ❖ Find function:

$$f : \mathbb{R}^d \rightarrow \mathbb{R}$$



► 6

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

6

Regression

❖ “best function” or “best approximation”:

the expected error on *unseen* data $(x_{n+1}, y_{n+1}), \dots, (x_{n+k}, y_{n+k})$ is minimal.

❖ As unseen data are not available

- ▶ The goal is to minimize *Residual Sum of Squared (RSS)*

$$RSS = \sum_{i=1}^n (y_i^{\text{expected}} - y_i)^2 = \sum_{i=1}^n (f(x_i) - y_i)^2$$

- ▶ The goal is to minimize *Root Mean Squared Error (RMS)*

$$RMS = \sqrt{\frac{1}{n} \sum_{i=1}^n (y_i^{\text{expected}} - y_i)^2} = \sqrt{\frac{1}{n} \sum_{i=1}^n (f(x_i) - y_i)^2}$$

❖ Existing techniques to solve the classification task:

- ▶ Classical (Linear) Regression
- ▶ NN

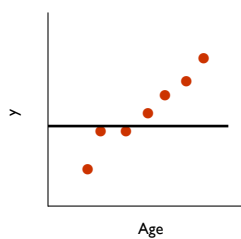
▶ 7

KHU, M.M.Pedram, pedram@khu.ac.ir

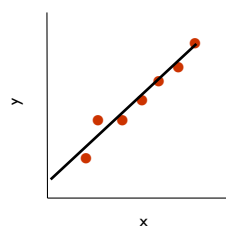
DM, Spring 2018

7

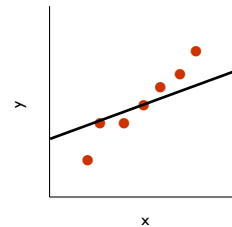
Linear SVR



“Lazy case”
(underfitting)



“Suspiciously smart case”
(overfitting)



“Compromise case”, SVR
(good generalizability)

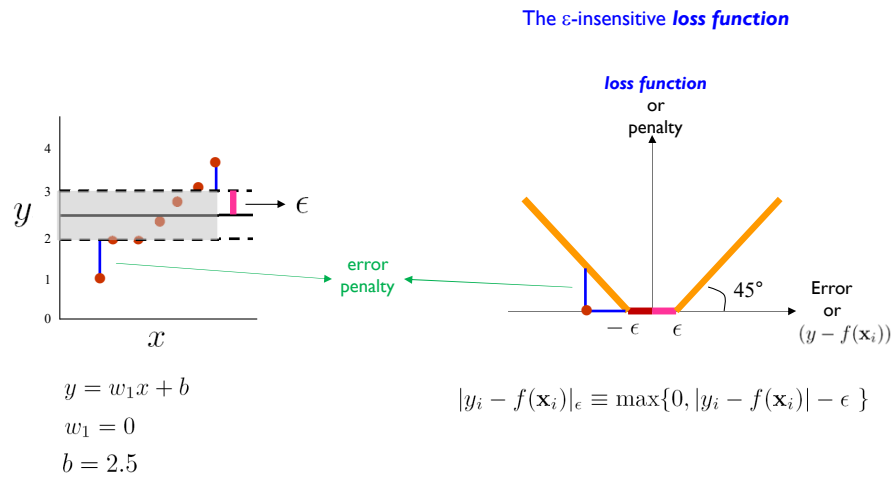
▶ 8

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

8

Linear SVR



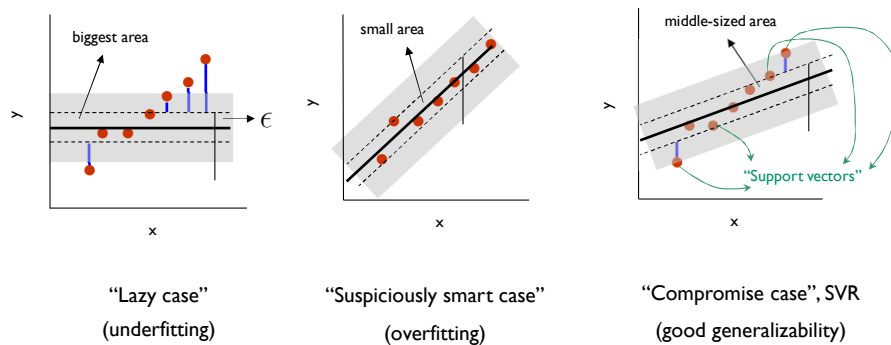
► 9

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

9

Linear SVR



❖ The thinner the “tube”, the more complex the model

► 10

KHU, M.M.Pedram, pedram@khu.ac.ir

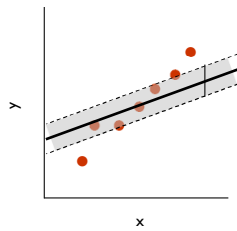
DM, Spring 2018

10

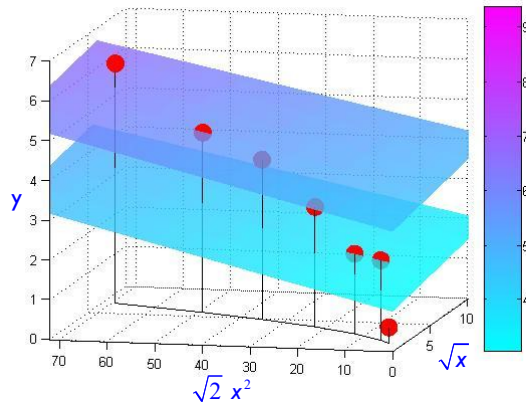
Non-linear SVR

❖ Map the data into a *higher-dimensional space*:

$$x \rightarrow \Phi(x) = (\sqrt{x}, \sqrt{2}x^2)$$



$$y = w_1 x + b$$



$$y = w_1 \sqrt{x} + w_2 \sqrt{2} x^2 + b$$

► 11

KHU, M.M.Pedram, pedram@khu.ac.ir

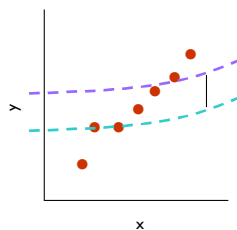
DM, Spring 2018

11

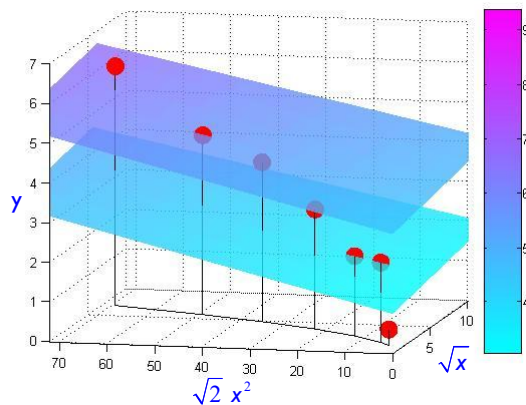
Non-linear SVR

❖ Map the data into a *higher-dimensional space*:

$$x \rightarrow \Phi(x) = (\sqrt{x}, \sqrt{2}x^2)$$



$$y = \mathbf{w}'\Phi(x) + b$$



$$y = w_1 \sqrt{x} + w_2 \sqrt{2} x^2 + b$$

► 12

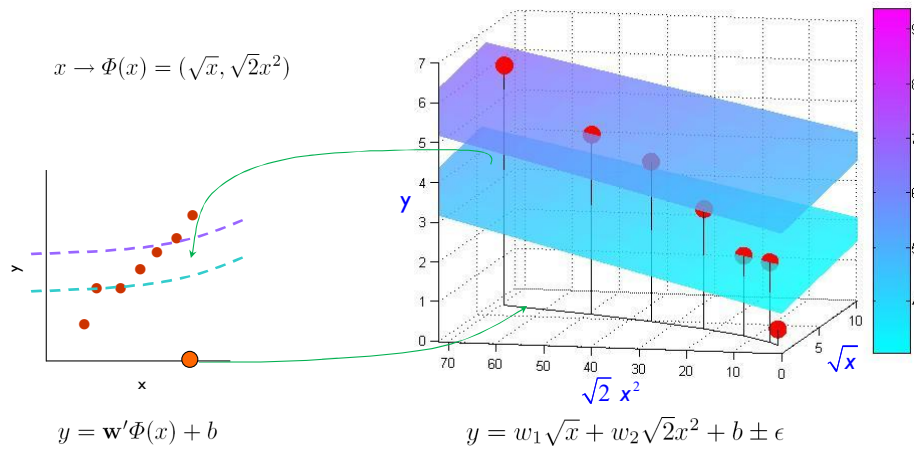
KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

12

Non-linear SVR

- ❖ Map the data into a *higher-dimensional space*:



► 13

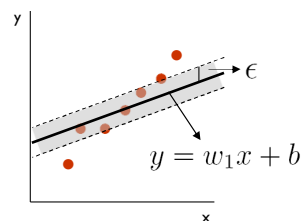
KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

13

Linear SVR: derivation

- ❖ Given training data $\{x_i, y_i\}_{i=1}^n$
- ❖ Find: w_1 , b
such that $y = w_1x + b$ optimally describes the data:



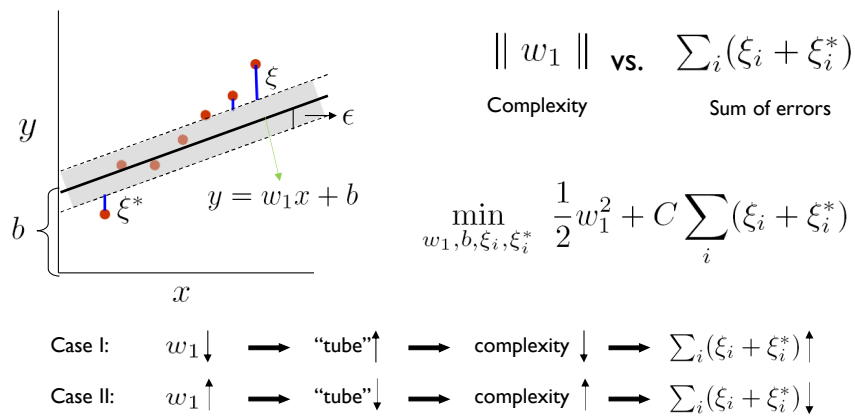
► 14

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

14

Linear SVR: derivation



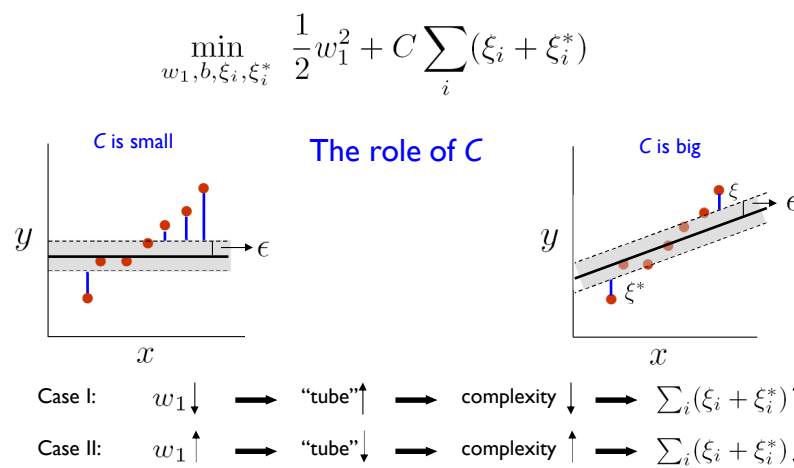
► 15

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

15

Linear SVR: derivation



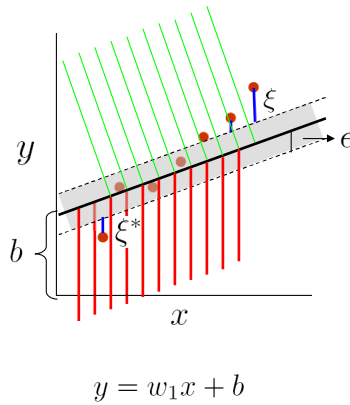
► 16

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

16

Linear SVR: derivation



$$\min_{w_1, b, \xi_i, \xi_i^*} \frac{1}{2} w_1^2 + C \sum_i (\xi_i + \xi_i^*)$$

s.t.:

$$y_i - [(w_1 x_{i1}) + b] \leq \epsilon + \xi_i \quad \text{green lines}$$

$$[(w_1 x_{i1}) + b] - y_i \leq \epsilon + \xi_i^* \quad \text{red lines}$$

$$\xi_i, \xi_i^* \geq 0 \quad i = 1, 2, \dots, n$$

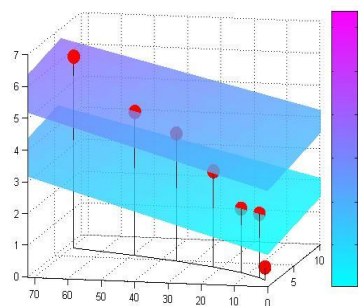
► 17

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

17

Non-linear SVR: derivation



$$y = \mathbf{w}'\Phi(x) + b$$

$$\min_{w_1, b, \xi_i, \xi_i^*} \frac{w_1^2 + w_2^2}{2} + C \sum_i (\xi_i + \xi_i^*)$$

s.t.:

$$y_i - (\mathbf{w}'\phi(x_{i1})) - b \leq \epsilon + \xi_i$$

$$(\mathbf{w}'\phi(x_{i1})) + b - y_i \leq \epsilon + \xi_i^*$$

$$\xi_i, \xi_i^* \geq 0 \quad i = 1, 2, \dots, n$$

► 18

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

18

Non-linear SVR: derivation

$$\min_{\mathbf{w}, b, \xi_i, \xi_i^*} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i (\xi_i + \xi_i^*)$$

$$\text{s.t.:} \quad \left. \begin{aligned} y_i - (\mathbf{w}'\phi(\mathbf{x}_i)) - b &\leq \epsilon + \xi_i \\ (\mathbf{w}'\phi(\mathbf{x}_i)) + b - y_i &\leq \epsilon + \xi_i^* \\ \xi_i, \xi_i^* &\geq 0 \quad i = 1, 2, \dots, n \end{aligned} \right\} \quad \text{These are } g_i(\mathbf{x}) \leq 0$$

$$L := \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i (\xi_i + \xi_i^*) - \sum_i (\eta_i \xi_i + \eta_i^* \xi_i^*) - \sum_i \alpha_i (\epsilon + \xi_i - y_i + \mathbf{w}'\phi(\mathbf{x}_i) + b) - \sum_i \alpha_i^* (\epsilon + \xi_i^* + y_i - \mathbf{w}'\phi(\mathbf{x}_i) - b)$$

❖ Since all constraints are inequality constraints, Lagrangian multiplier should satisfy KKT condition, i.e. $\alpha_i, \alpha_i^*, \xi_i, \xi_i^* \geq 0$

❖ Saddle point of L has to be found:

$$\begin{aligned} \text{min with respect to} \quad & \mathbf{w}, b, \xi_i, \xi_i^* \\ \text{max with respect to} \quad & \alpha_i, \alpha_i^*, \eta_i, \eta_i^* \end{aligned}$$

► 19

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

19

Non-linear SVR: derivation

$$L := \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i (\xi_i + \xi_i^*) - \sum_i (\eta_i \xi_i + \eta_i^* \xi_i^*) - \sum_i \alpha_i (\epsilon + \xi_i - y_i + \mathbf{w}'\phi(\mathbf{x}_i) + b) - \sum_i \alpha_i^* (\epsilon + \xi_i^* + y_i - \mathbf{w}'\phi(\mathbf{x}_i) - b)$$

$$\frac{\partial L}{\partial \mathbf{w}} = \mathbf{w} - \sum_i (\alpha_i - \alpha_i^*) \phi(\mathbf{x}_i) = 0$$

...

regression hyperplane in ϕ space:

$$f(\mathbf{x}) = \mathbf{w}'\phi(\mathbf{x}) + b$$

$$\begin{aligned} \rightarrow f(\mathbf{x}) &= \sum_i (\alpha_i - \alpha_i^*) (\phi(\mathbf{x}_i)' \phi(\mathbf{x})) + b \\ f(\mathbf{x}) &= \sum_i (\alpha_i - \alpha_i^*) k(\mathbf{x}_i, \mathbf{x}) + b \end{aligned}$$

► 20

KHU, M.M.Pedram, pedram@khu.ac.ir

DM, Spring 2018

20

Strengths and Weaknesses of SVR

❖ Strengths of SVR:

- ▶ No local minima
- ▶ It scales relatively well to high dimensional data
- ▶ Trade-off between complexity and error can be controlled explicitly via C and ϵ
- ▶ Overfitting is avoided (for any fixed C and ϵ)
- ▶ Robustness of the results
- ▶ "Huber (1964) demonstrated that the best cost function over the worst model over any pdf of y given x is the linear cost function. Therefore, if the pdf $p(y|x)$ is unknown the best cost function is the linear penalization over the errors" (Perez-Cruz et al., 2003)

❖ Weaknesses of SVR:

- ▶ What is the best trade-off parameter C and best ϵ ?
- ▶ What is a good transformation of the original space