

Exercises: Swarm Intelligence

1. (PSO) [2 points] Suppose you want to use a PSO system to maximize the function

$$f(x) = \sum_{i=1}^2 (-x(i)) \sin(\sqrt{(|x(i)|)}),$$

where $-500 \leq x(i) \leq 500$. A graph of this function is shown in the slides of the lecture (the function's global maximum is at $f(x) = 837.9658$ for $x(i) = -420.9687, i = 1, 2$). Consider an illustrative example of a PSO system for composed of three particles. The space of solutions is a two dimensional real valued space: $-500 \leq x(i) \leq 500$. Consider the update rule for each particle i :

$$v_i = \omega v_i + \alpha_1 r_1 (x_i^* - x_i) + \alpha_2 r_2 (x^* - x_i),$$

where x_i^* denotes the personal best and x^* the social (global) best. To facilitate calculation, for this exercise we will ignore the fact that r_1 and r_2 are random numbers and fix them to 0.5 and $\alpha_1 = \alpha_2 = 1$. Suppose the current state of the swarm is as follows.

- Position of particles: $x_1 = (-400, -400); x_2 = (-410, -410); x_3 = (-415, -415);$
- Individual best positions: $x_1^* = x_1; x_2^* = x_2; x_3^* = x_3;$
- Social best position: $x^* = x_3;$
- Velocities: $v_1 = v_2 = v_3 = (-50, -50)$

- (a) Compute the fitness of each particle.
- (b) What would be the next position and fitness of each particle after one iteration of th PSO algorithm, when using $\omega = 2, \omega = 0.5,$ and $\omega = 0.1$? (Incase a component of a new position falls outside the range $-500 \leq x(i) \leq 500$, it is mapped to its closest value in the range. For instance, if the computation of new position gives (550, 500), it is set to (500, 500).)
- (c) Explain what is the effect of the parameter ω .
- (d) Give an advantage and a disadvantage of a high value of ω .

```
import numpy as np
import math

def fitness(x):
    return sum([(-x[i])*math.sin(math.sqrt(abs(x[i]))) for i in range(2)])

def newVal(old_v, omega, alpha1, alpha2, r1, r2, old_x, local_best, global_best):
    return omega*old_v + alpha1*r1*(local_best - old_x) + alpha2*r2*(global_best - old_x)

omega_list = [2, 0.5, 0.1]
r1, r2 = 0.5, 0.5
alpha1, alpha2 = 1, 1
x1, x2, x3 = np.array([-400, -400]), np.array([-410, -410]), np.array([-415, -415])
x_list = [x1, x2, x3]
v1, v2, v3 = np.array([-50, -50]), np.array([-50, -50]), np.array([-50, -50])
v_list = [v1, v2, v3]

print("a)")
for x in x_list:
    print("The fitness function of x=" + str(x) + " is " + str(fitness(x)) + ".")

print("b)")
for omega in omega_list:
    for j in range(3):
        new_v = newVal(v_list[j], omega, alpha1, alpha2, r1, r2, x_list[j], x_list[j], x_list[2])
        x = x_list[j] + new_v
        if(x[0] < -500):
            x[0] = -500
        if(x[0] > 500):
            x[0] = 500
        if(x[1] < -500):
            x[1] = -500
        if(x[1] > 500):
            x[1] = 500
        print("The new value for x" + str(j+1) + "=" + str(x_list[j]) + " when using omega=" + str(omega) + " is " + str(x))

a)
The fitness function of x=[-400 -400] is 730.3562005821021.
The fitness function of x=[-410 -410] is 807.9150929576671.
The fitness function of x=[-415 -415] is 829.0117583869608.
b)
The new value for x1=[-400 -400] when using omega=2 is [-500. -500.] with fitness -361.1783170627835.
The new value for x2=[-410 -410] when using omega=2 is [-500. -500.] with fitness -361.1783170627835.
The new value for x3=[-415 -415] when using omega=2 is [-500. -500.] with fitness -361.1783170627835.
The new value for x1=[-400 -400] when using omega=0.5 is [-432.5 -432.5] with fitness 804.4822309250023.
The new value for x2=[-410 -410] when using omega=0.5 is [-437.5 -437.5] with fitness 769.4947716725984.
The new value for x3=[-415 -415] when using omega=0.5 is [-440. -440.] with fitness 747.5297044219257.
The new value for x1=[-400 -400] when using omega=0.1 is [-412.5 -412.5] with fitness 819.9905472762648.
```

The new value for x2=[-410 -410] when using omega=0.1 is [-417.5 -417.5] with fitness 834.9351365389027.
The new value for x3=[-415 -415] when using omega=0.1 is [-420. -420.] with fitness 837.7290352197082.

c)
omega (ω) is the inertia parameter. It keeps the particle moving in the same direction and velocity. If the parameter omega > 1 then the particles might move too far in their own direction ignoring the swarm. If omega < 1 then they might move too slow and even stop.
d)
A disadvantage of a high value of omega was given in c), the particle could not take the swarm into account enough and keep on going on its course even if it's wrong. The advantage would be that if it's on the right course it will converge quickly.

2. (PSO) [2 points] Consider a particle “swarm” consisting of a single member. How would it perform in a trivial task such as the minimization of $f(x) = x^2$ when $\omega < 1$, assuming the particle starts with the velocity pointing away from the optimum (e.g. in a state with velocity $v = 10$; position $x = 20$)?

```
omega_list = [0.9, 0.6, 0.2, 0.001]

for omega in omega_list:
    v = 10
    x = 20
    print("First 10 value for omega=" + str(omega))
    for i in range(20):
        new_v = omega*v + alpha1*r1*(x - x) + alpha2*r2*(x - x)
        x = x + new_v
        fitness = x**2
        v = new_v
        print(fitness)

## Both local and global x are the only possible option which is x, so the two portions to the right are 0 whcih

First 10 value for omega=0.9
841.0
1376.41
1970.4721
2596.004401
3232.59336481
3865.1474454961
4482.74156885184
5077.695594969991
5644.840863705693
6180.937788203611
6684.214628186725
7154.003366598868
7590.453292935939
7994.306676669882
8366.723966555199
8709.148415517047
9023.20201891541
9310.606257433425
9573.122428421822
9812.50739093235
First 10 value for omega=0.6
676.0
876.1600000000001
1008.6976000000001
1092.6991360000004
1144.7124889600002
1176.5009760256003
1195.7830393692163
1207.4275069729179
1214.4412701902504
1218.65927787649
1221.1935924003365
1222.7154446830014
1223.6290109372085
1224.177314448192
1224.5063555078273
1224.703801366705
1224.822276522346
1224.8933643662442
1224.9360180627677
1224.9616106371482
First 10 value for omega=0.2
484.0
501.75999999999993
505.35039999999987
506.0700159999998
506.21400063999977
506.2428000255998
506.2485600010238
506.2497120000408
506.2499424000015
506.2499884799999
506.2499976959998
506.2499995391998
506.2499999078398
506.24999998156784
506.24999999631353
```

The particle swarm would converge further and further from the point we are looking for, maximizing it instead of minimizing. The smaller the omega, the slower the maximization.

3. (PSO) [2 points] Implement the PSO algorithm for clustering described in “Van der Merwe, D. W., and Andries Petrus Engelbrecht. "Data clustering using particle swarm optimization." Evolutionary Computation, 2003. CEC’03. The 2003 Congress on. Vol. 1. IEEE, 2003.” (see also swarm intelligence slides). Implement the k-means clustering.

Apply and compare the performance of the two algorithms in terms of quantization error on Artificial dataset 1 and on the Iris dataset (the latter available at UCI ML repository, see <https://archive.ics.uci.edu/ml/datasets/iris>). In both algorithms, use the true number of clusters as value of the parameter for setting the number of clusters.

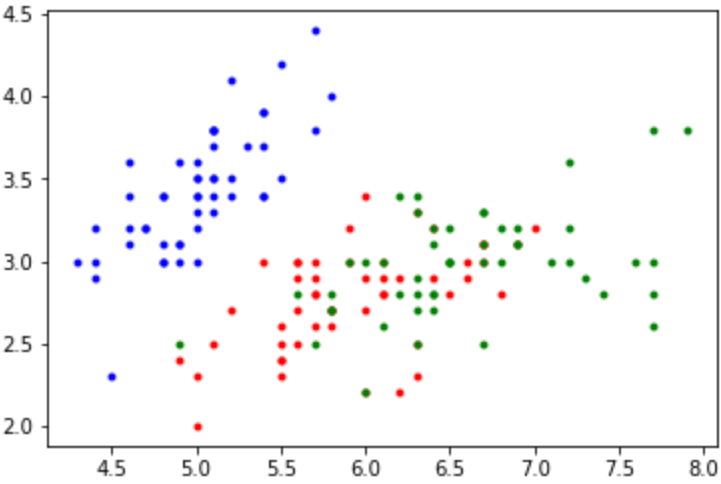
```
import numpy as np
import math
import matplotlib.pyplot as plt
from scipy.spatial import distance_matrix
from sklearn.datasets import load_iris
```

▼ Load or generate dataset

```
datasetName = 'iris' # you can select 'gen' or 'iris'
if datasetName == 'gen': #'gen' stands for the generated (Artificial)
    num_data = 400
    lb = -1
    ub = 1
    data = np.random.rand(num_data , 2)*(ub-lb) + lb
    label = np.zeros((num_data))
    for i in range(num_data):
        if data[i,0] >= 0.7 or (data[i,0]<= 0.3 and data[i,1] >= -0.2 - data[i,0]):
            label[i] = 1
        else:
            label[i] = 0
    plt.plot(data[label==0,0],data[label==0,1],'.b')
    plt.plot(data[label==1,0],data[label==1,1],'.r')

else:
    data = load_iris()
    label = data['target']
    data = data['data']
    plt.plot(data[label==0,0],data[label==0,1],'.b')
    plt.plot(data[label==1,0],data[label==1,1],'.r')
    plt.plot(data[label==2,0],data[label==2,1],'.g')
    num_data = 150
    n_cluster = len(set(label))
    lb = np.tile(np.min(data,axis=0) , n_cluster)
    ub = np.tile(np.max(data,axis=0) , n_cluster)

n_cluster = len(set(label))
dim_data = np.size(data, axis = 1)
```



▼ Initializing parameters

```
t_max = 100
Pmax = 50
dim = dim_data * n_cluster
w = 0.4
c1 = 1
c2 = 1
```

```
def getFitness(x):
    x = x.reshape((n_cluster , dim_data))
    D = distance_matrix(x, data)
    idx = np.argmin(D , axis = 0)
    D = np.min(D , axis = 0)
    J = 0
    for i in range(n_cluster):
        J = J + np.sum(D[idx == i])

    J = J / n_cluster
    return J
```

▼ Initializing population

```
X = np.random.rand(Pmax , dim) * (ub - lb) + lb
V = np.random.randn(Pmax , dim)
P = np.array(X)

Fit_X = np.ones(Pmax) * np.infty
Fit_P = np.ones_like(Fit_X) * np.infty

X_best = np.zeros_like(X[0])
Fit_best = np.infty
```

▼ Main loop

```
plot_best = []
for T in range(t_max):

    # Get fitness of each individual
    for i in range(Pmax):
        Fit_X[i] = getFitness(X[i])

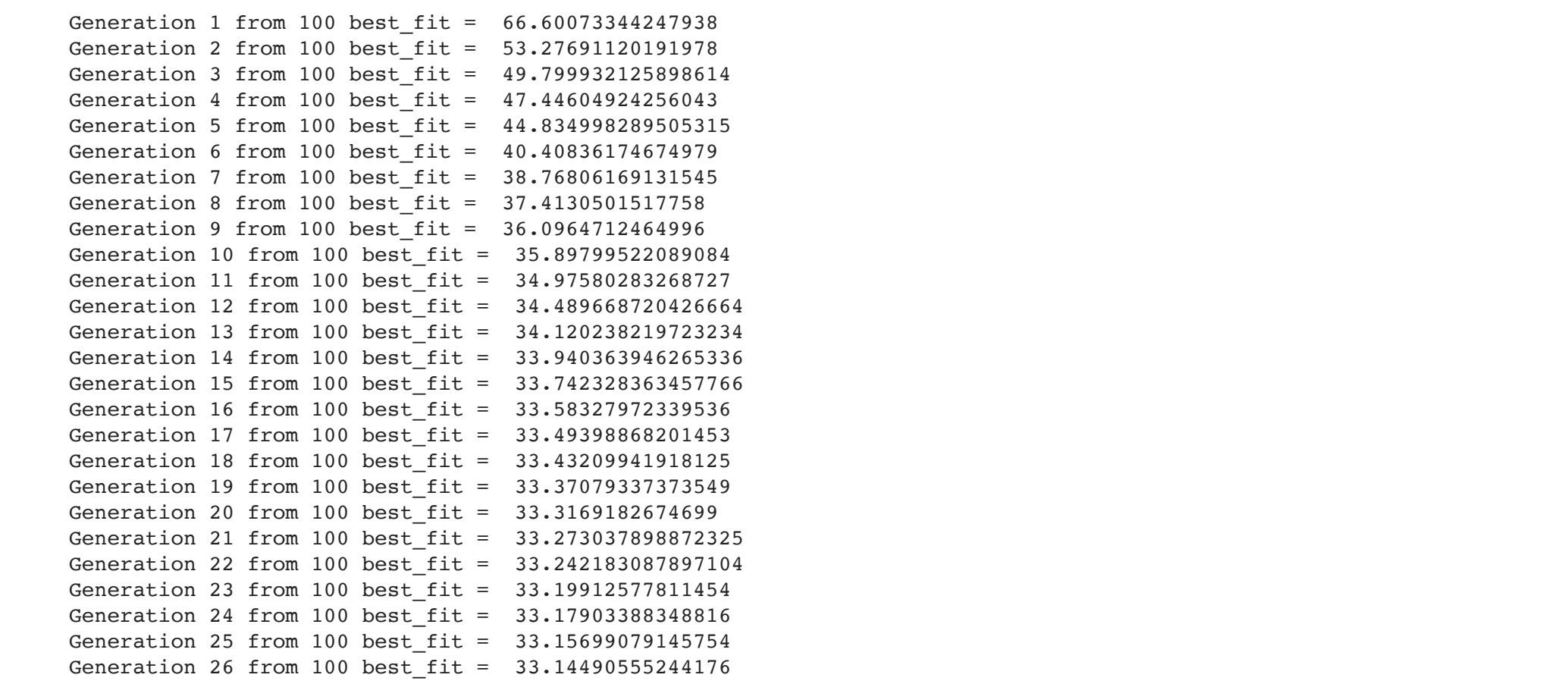
    # Update Personal bests
    P[Fit_X < Fit_P ,] = np.array(X[Fit_X < Fit_P ,])
    Fit_P[Fit_X < Fit_P] = np.array(Fit_X[Fit_X < Fit_P])

    # Update Global best
    if Fit_X.min() < Fit_best :
        X_best = X[np.argmin(Fit_X)]
        Fit_best = Fit_X.min()

    # Calculate velocity
    for i in range(Pmax):
        for d in range(dim):
            V[i,d] = w * V[i,d] + c1 * np.random.rand()*(P[i,d] - X[i,d]) + c2 * np.random.rand() * (X_best[d] - X[i,d])

    # Update population
    X = X + V

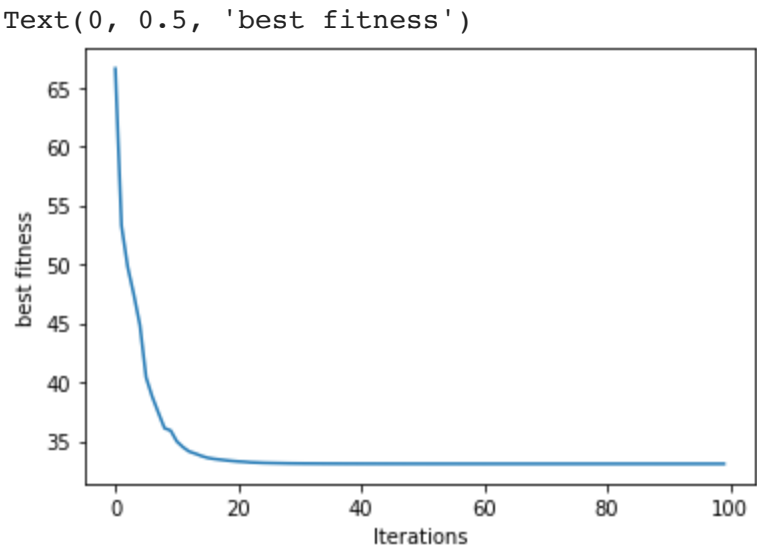
    print('Generation',str(T+1),'from',str(t_max), 'best_fit = ',str(Fit_best))
    plot_best.append(Fit_best)
```



Generation 27 from 100 best_fit = 33.13493575284692
Generation 28 from 100 best_fit = 33.125055333183155
Generation 29 from 100 best_fit = 33.11492095786735
Generation 30 from 100 best_fit = 33.10883002125492
Generation 31 from 100 best_fit = 33.10360141656511
Generation 32 from 100 best_fit = 33.10041077629246
Generation 33 from 100 best_fit = 33.09720917489895
Generation 34 from 100 best_fit = 33.09453084129018
Generation 35 from 100 best_fit = 33.09166700676863
Generation 36 from 100 best_fit = 33.08968468147017
Generation 37 from 100 best_fit = 33.08812453780922
Generation 38 from 100 best_fit = 33.08630259084432
Generation 39 from 100 best_fit = 33.08497314461755
Generation 40 from 100 best_fit = 33.08419413512454
Generation 41 from 100 best_fit = 33.08313910292089
Generation 42 from 100 best_fit = 33.08246691093388
Generation 43 from 100 best_fit = 33.08162332545695
Generation 44 from 100 best_fit = 33.08081749428024
Generation 45 from 100 best_fit = 33.08020581221439
Generation 46 from 100 best_fit = 33.07954652907066
Generation 47 from 100 best_fit = 33.07906555494047
Generation 48 from 100 best_fit = 33.078554515870174
Generation 49 from 100 best_fit = 33.07815819013169
Generation 50 from 100 best_fit = 33.077637078796755
Generation 51 from 100 best_fit = 33.077352380577324
Generation 52 from 100 best_fit = 33.077105468464644
Generation 53 from 100 best_fit = 33.076853652310966
Generation 54 from 100 best_fit = 33.076493647331304
Generation 55 from 100 best_fit = 33.07623243021249
Generation 56 from 100 best_fit = 33.07603424367988
Generation 57 from 100 best_fit = 33.07580676536372
Generation 58 from 100 best_fit = 33.07564900130257
Generation 59 from 100 best_fit = 33.07552328856124

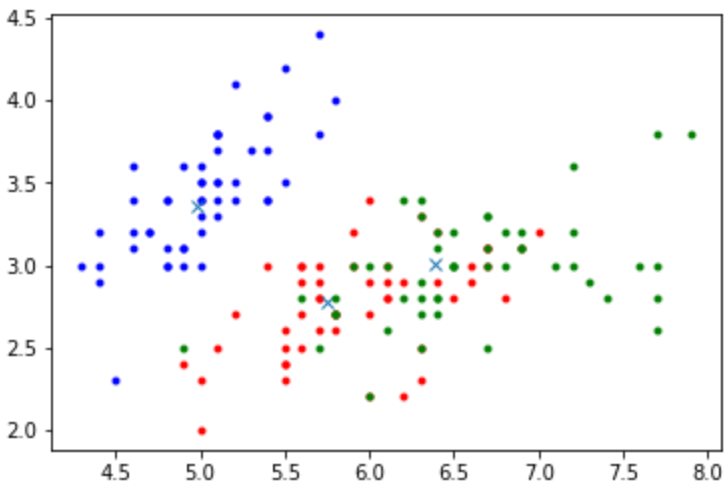
Plot the process

```
plt.plot(plot_best)
plt.xlabel('Iterations')
plt.ylabel('best fitness')
```



```
plt.plot(data[label==0,0],data[label==0,1],'.b')
plt.plot(data[label==1,0],data[label==1,1],'.r')
center = X_best.reshape((n_cluster , dim_data))
plt.plot(center[:,0] , center[:,1],'x')

if datasetName == 'iris':
    plt.plot(data[label==2,0],data[label==2,1],'.g')
```



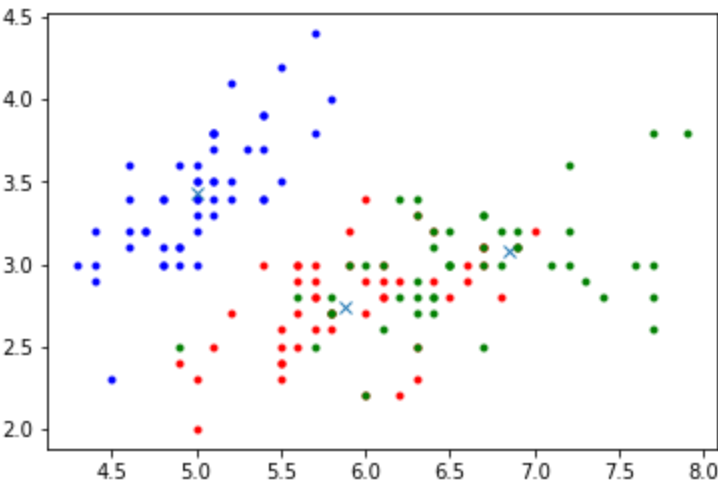
As clustering is a search problem, PSO can be used for searching through data to find centers. PSO finds a vector, while centers in our problem are 3 distinguished vectors. Thus, the paper suggests finding a vector with 6 dimensions and changing it to 3 vectors with 2 components. In this term, the fitness function tries to find the margin between data and centroids, so PSO tries to minimize this function.

Use obtained centers as initial centers for Kmeans

```
from sklearn.cluster import KMeans
kmeans = KMeans(n_clusters=n_cluster,n_init=1, init=center).fit(data)
new_centers = kmeans.cluster_centers_
```

```
plt.plot(data[label==0,0],data[label==0,1],'.b')
plt.plot(data[label==1,0],data[label==1,1],'.r')
plt.plot(new_centers[:,0] , new_centers[:,1], 'x')
```

```
if datasetName == 'iris':
    plt.plot(data[label==2,0],data[label==2,1],'.g')
```



```
getFitness(new_centers.reshape((-1)))
```

32.40828967795775

The paper suggests using found centroids by PSO in the previous step as initial points of Kmeans instead of random points. This trick leads to better fitness that can be seen.

4. (ACO) [2 points] Read the paper: Blum, Christian, and Marco Dorigo. "Search bias in ant colony optimization: On the role of competition-balanced systems." IEEE Transactions on Evolutionary Computation 9.2 (2005): 159-174. Figure 1 shows a (toy) problem instance for the 2-cardinality tree problem. The 2-cardinality tree problem amounts to finding a subtree T of a given undirected graph G with exactly 2 edges and the minimum possible weight.

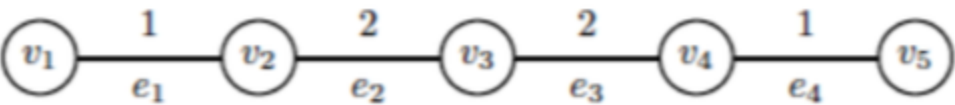


Figure 1: 2-cardinality problem instance

- (a) Is ACO for this problem a Competition-Balanced System (CBS)? Justify your answer. (A definition of CBS also given in the slides.)

The ACO for this problem is not a Competition-Balanced System because some solution components in this cardinality problem occur in a larger number of feasible solutions.

- (b) If a combination of an ACO algorithm and a problem instance is not a CBS, is the induced bias always harmful? Justify your answer.

The combination of an ACO algorithm and a problem instance is not a CBS does not always imply a harmful induced bias. Some combinations have biases which are desirable - ex: First Order Deceptive Systems.

5. (ACO) [2 point] The figure below shows an example of an instance of a source- destination problem from the ACO book by Dorigo and Stuetzle. The goal is to reach the destination node from the source one using a shortest path through the given graph. What results do you expect for an ant colony algorithm that does not use tabu lists (except for inhibition of immediate return to the previous node)?

