

Biologically Plausible Learning under Non-Stationary and Sparse Regimes

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Mega Pod: Vostok

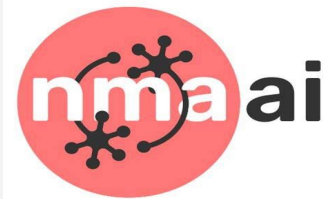
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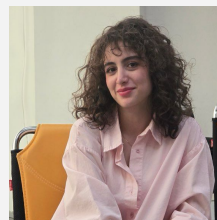
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Project dataset: Microlearning

Group Members:



Ramtin



Motahareh

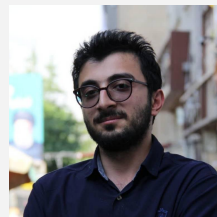


AmirMahdi



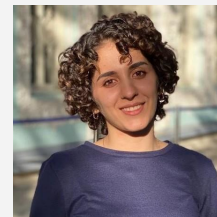
Rana

Reza

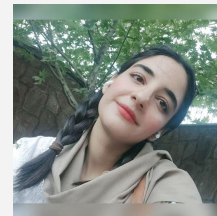


Maryam

Sasan



Fatemeh



Farnaz



Daniel

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Introduction to Microlearning:



Learning effectively in brain → Coordinate synaptic updates

Credit assignment problem → Synapses depend on each other

Backpropagation → Biologically implausible

Hebbian learning → Biologically plausible

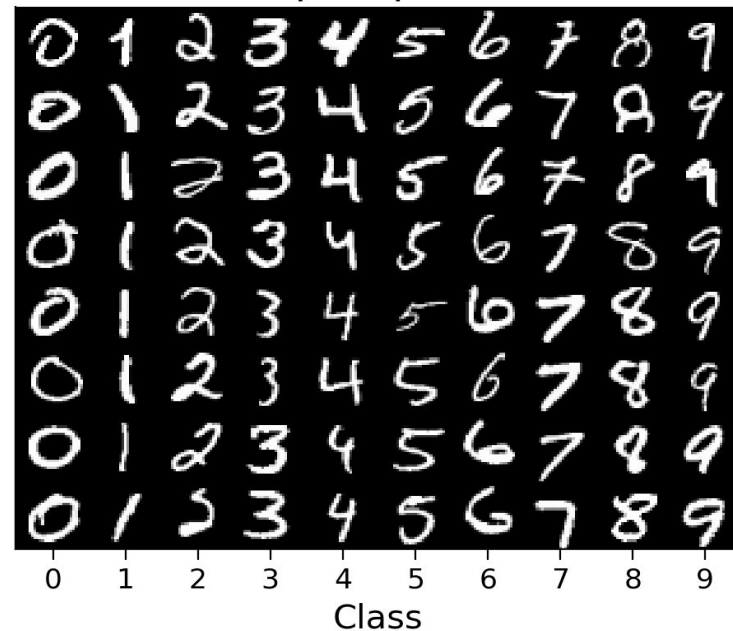
Dataset:

The MNIST Dataset

Handwritten Digit Images

10 classes

Examples per class



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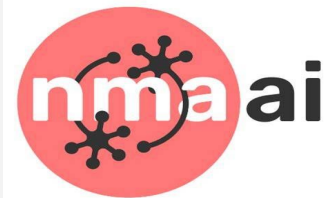
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Research Questions:



Q1. How do **biologically plausible local learning rules** (e.g., Hebbian, FA) perform in non-stationary settings **compared to BP**, considering performance degradation and forgetting as new tasks are introduced?

Q2. Can **combining Hebbian learning with sparse coding** lead to more interpretable or robust internal representations on MNIST, and how does the level of sparsity influence this?

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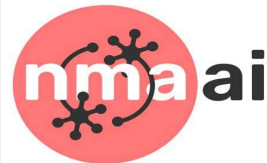
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Robustness comparison:

- Adding gaussian noise to image data
- Comparing accuracy



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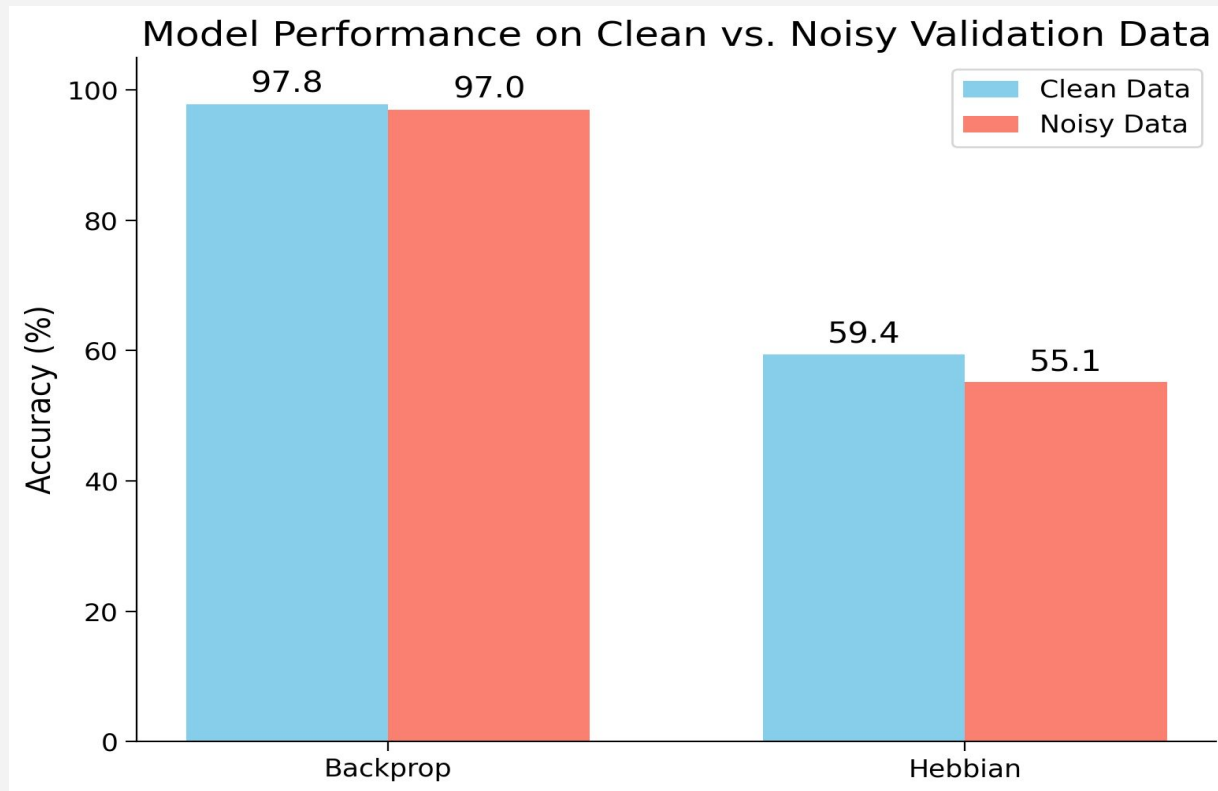
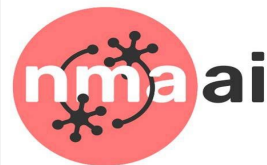
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Robustness:



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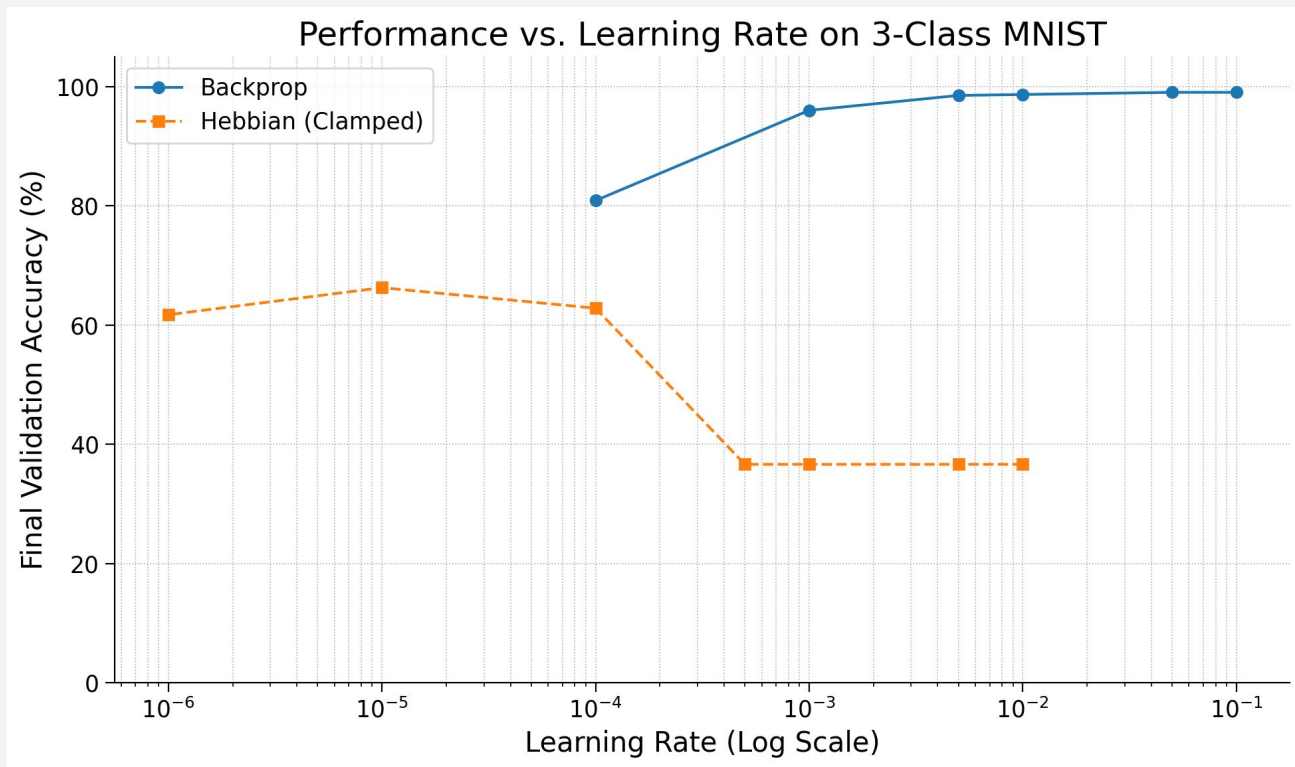
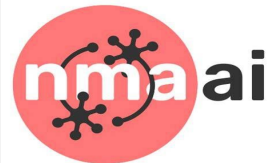
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Learning rate:



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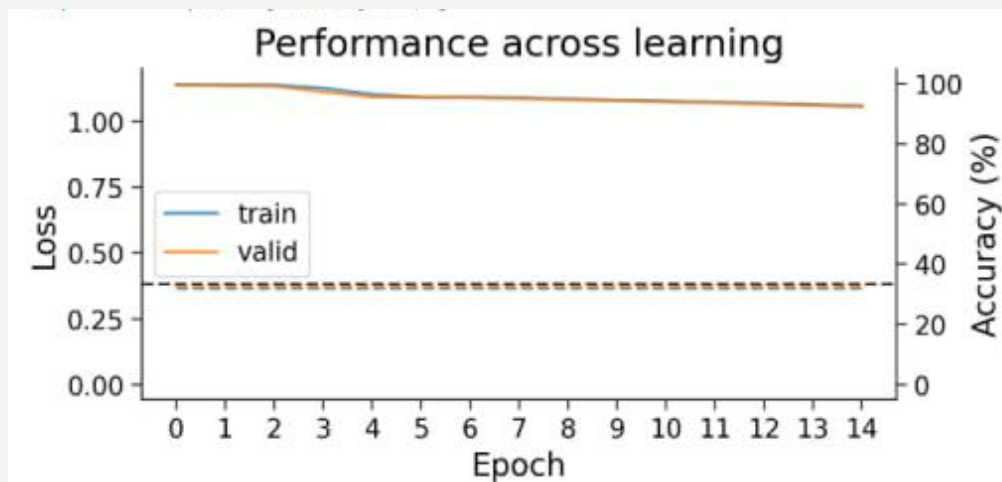
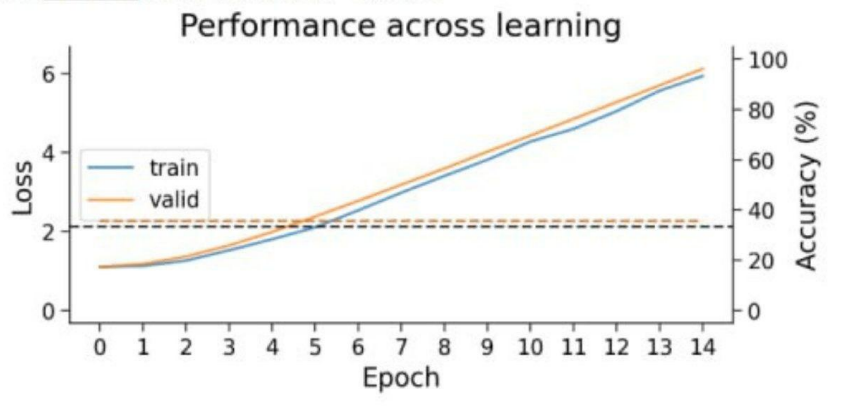
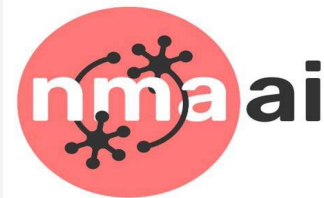
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Changing Number of Layers:



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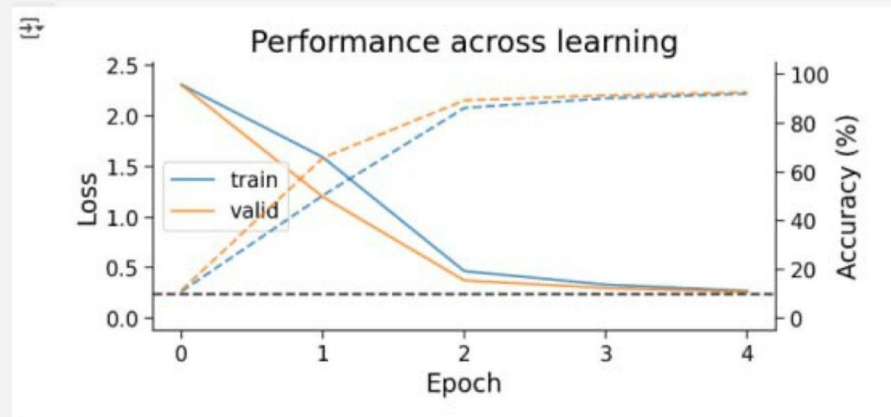
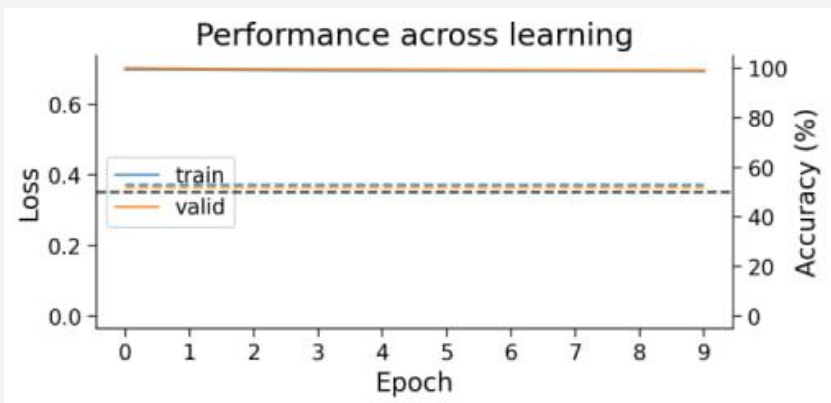
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Different Activation Functions:



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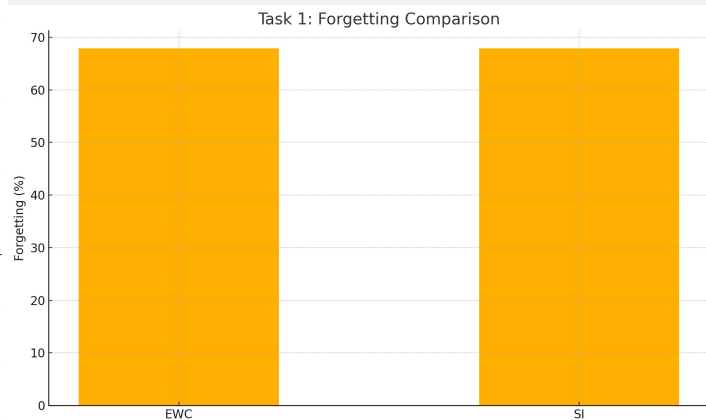
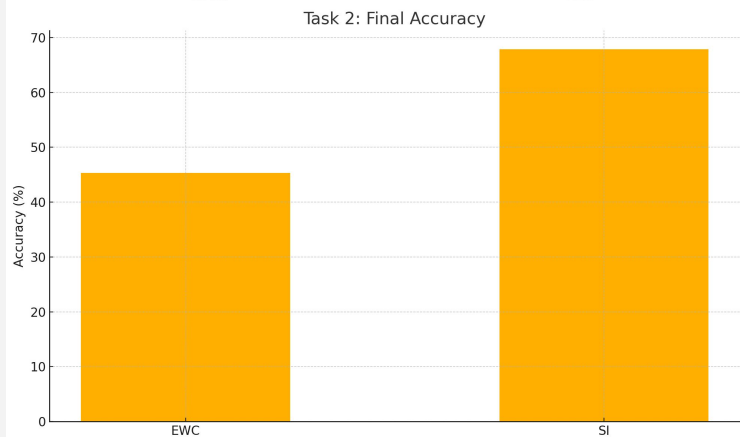
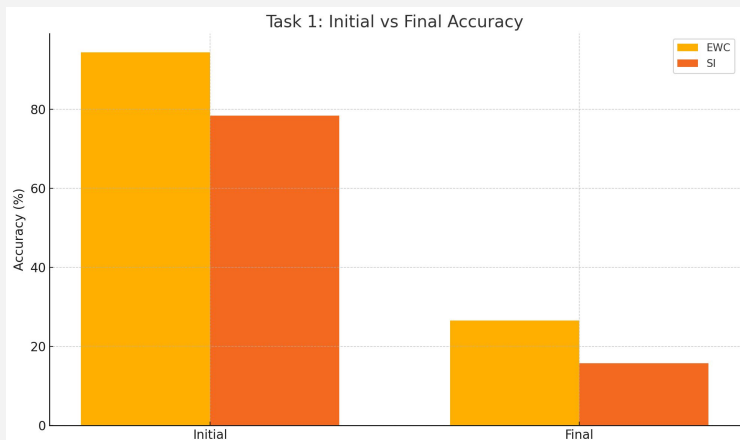
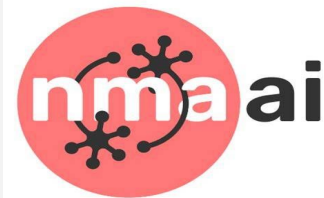
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Continual Learning:

Two class MNIST: Compare ewc vs. si



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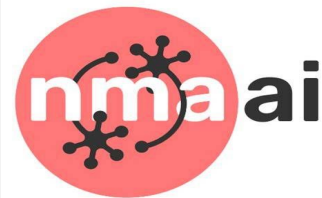
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Continual Learning:

Backward Transfer (BWT)



Method	Task 1 Initial (%)	Task 1 Final (%)	BWT (%)
EWC	94.42	26.52	-67.90
SI	78.41	15.79	-62.62

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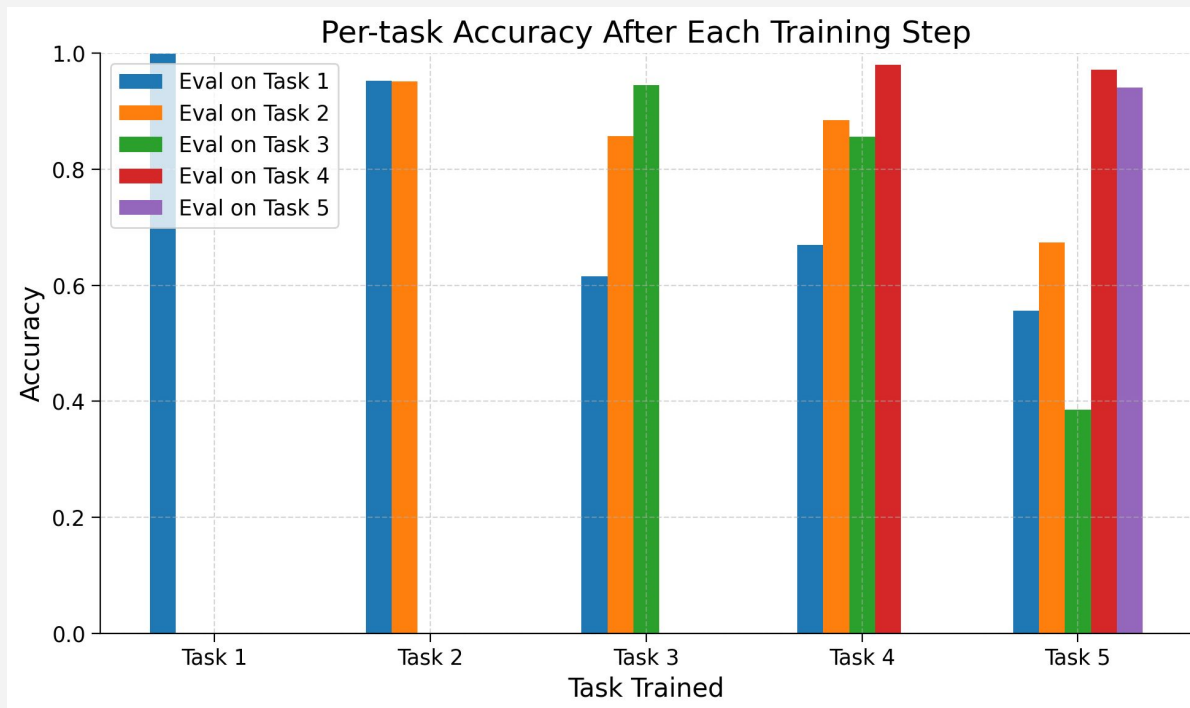
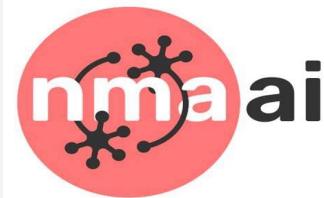
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Continual Learning:

EWC MLP



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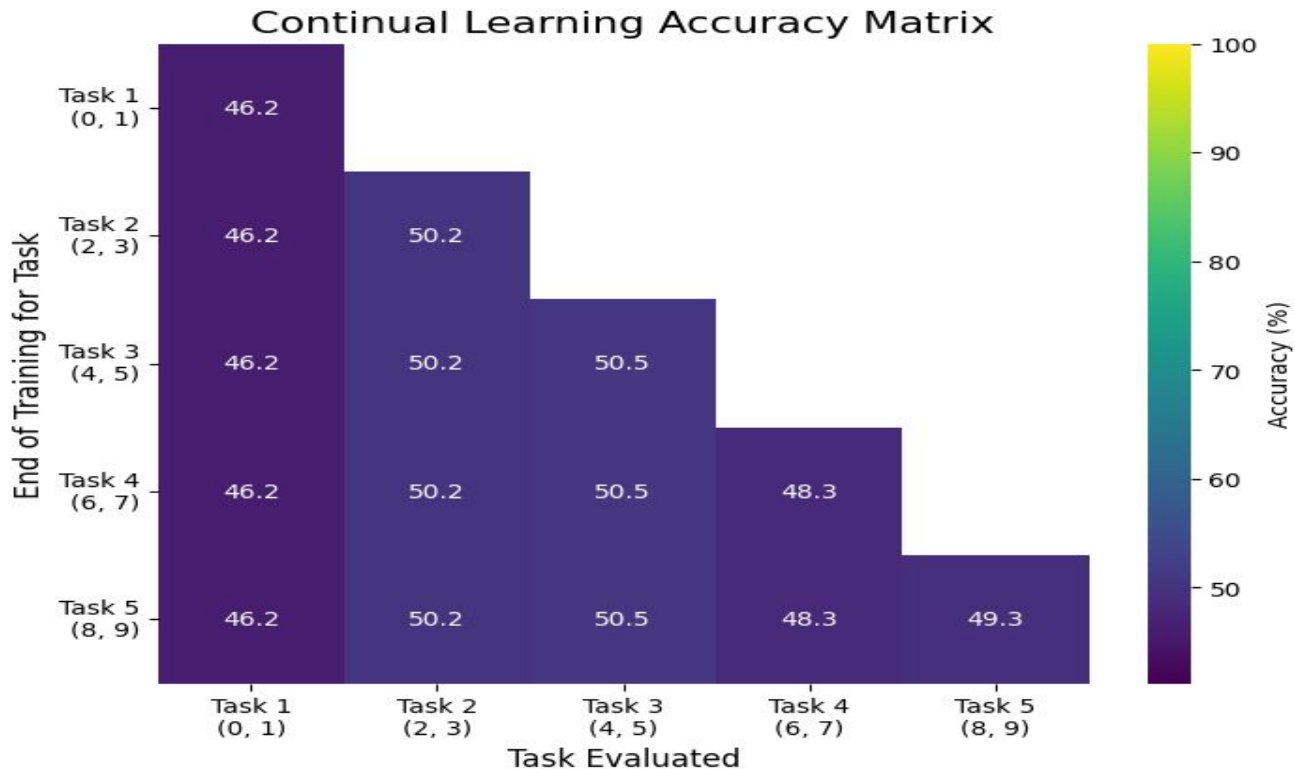
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Continual Learning:

Hebbian MLP



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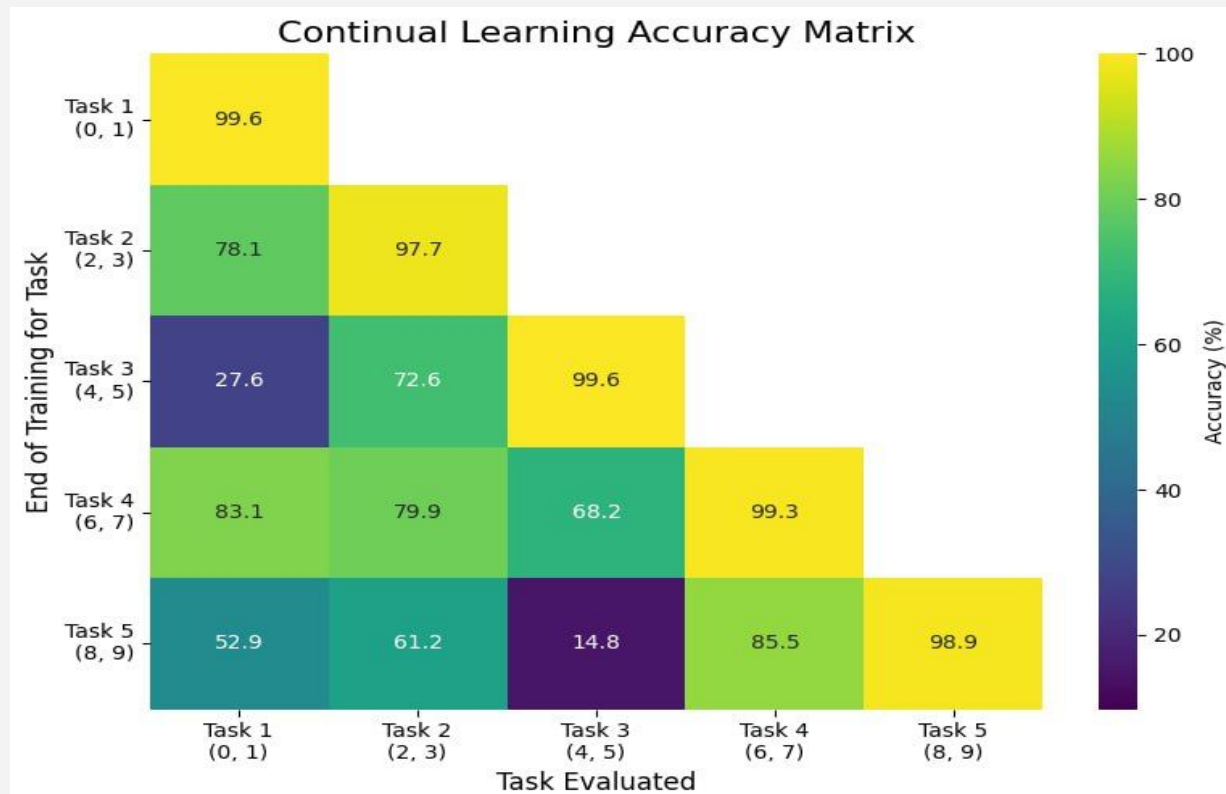
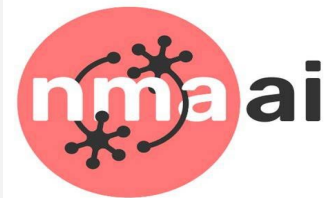
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Continual Learning:

Hybrid KAN



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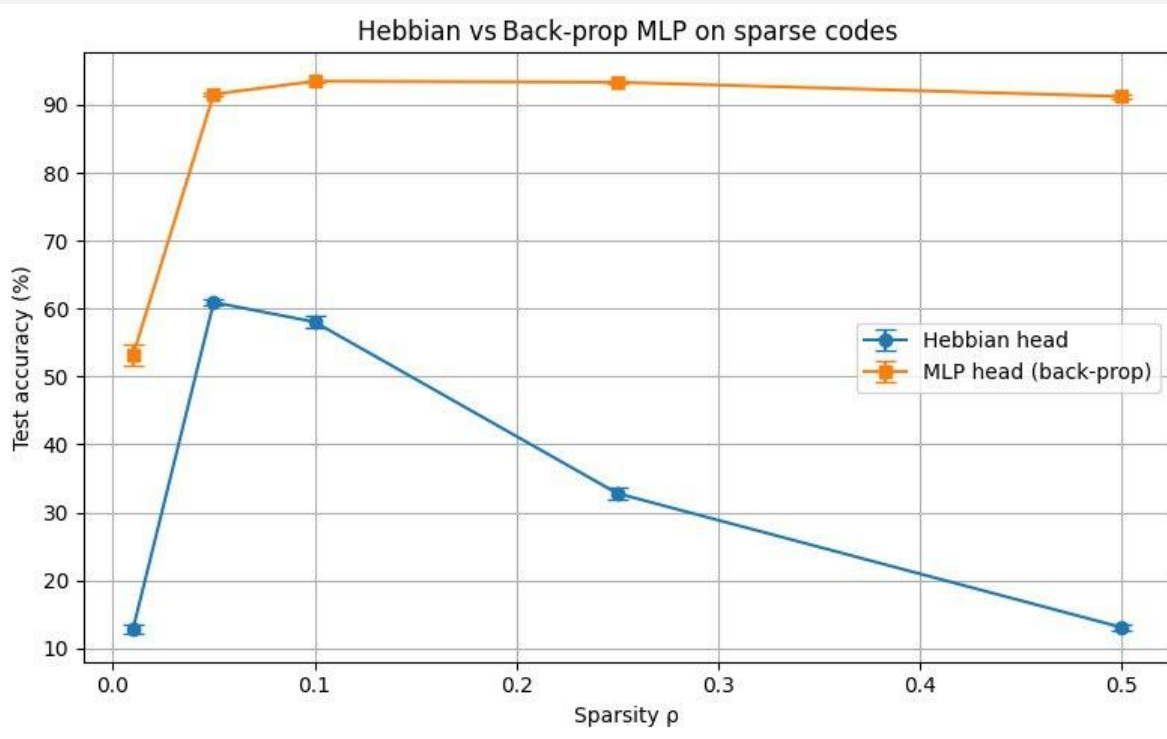
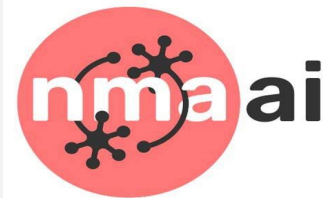
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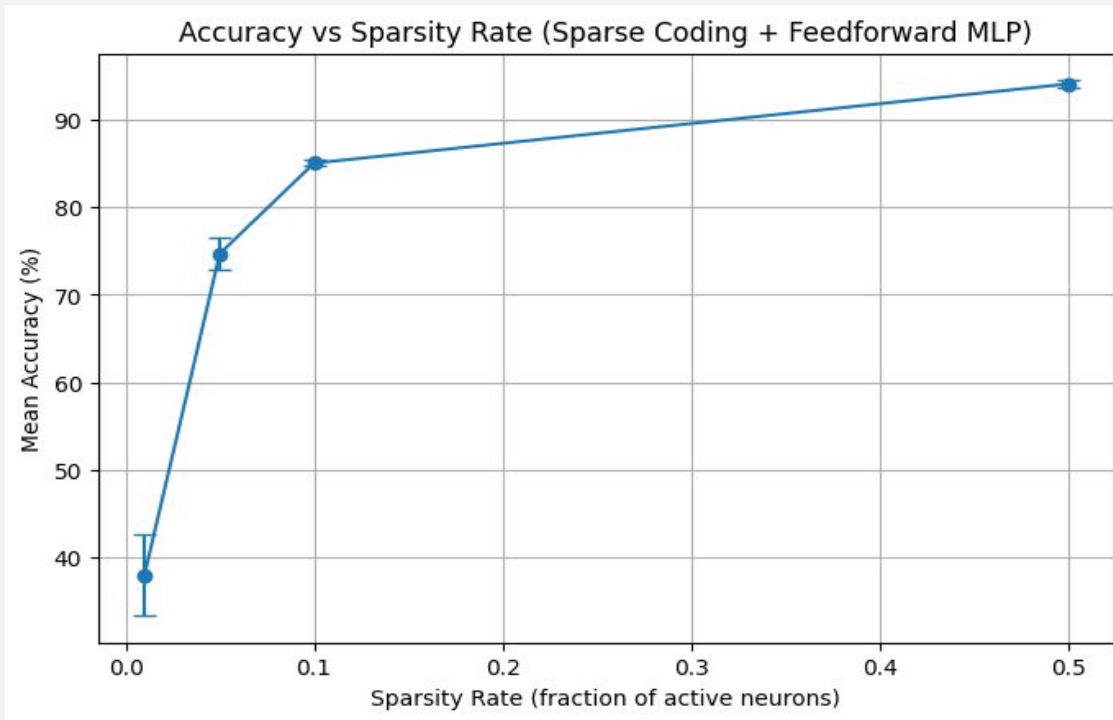
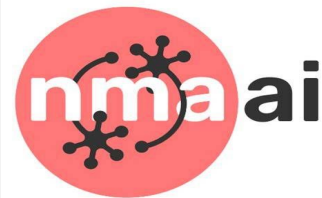
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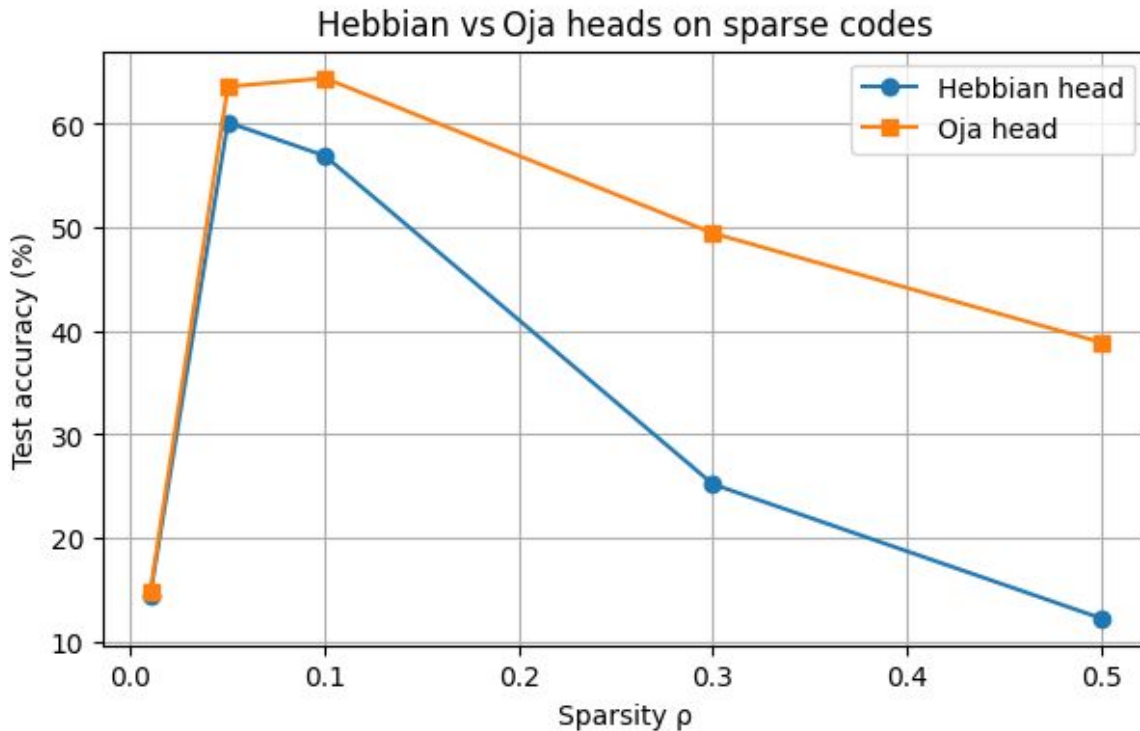
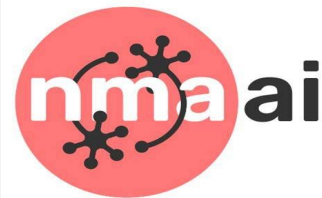
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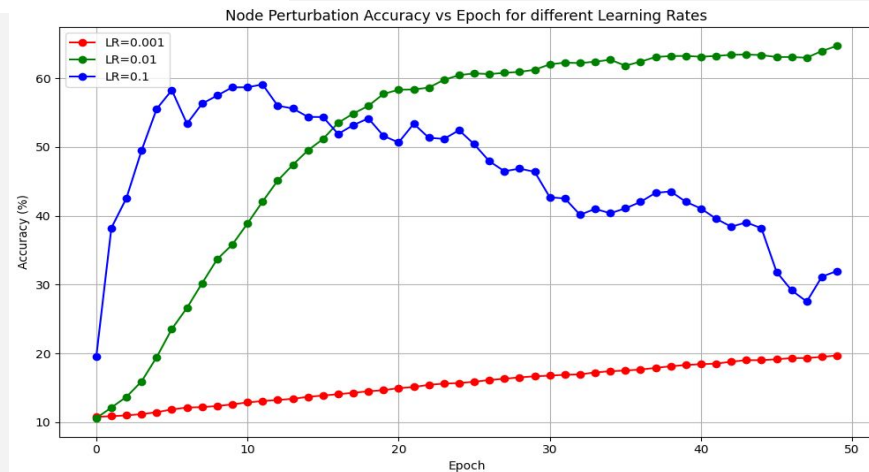
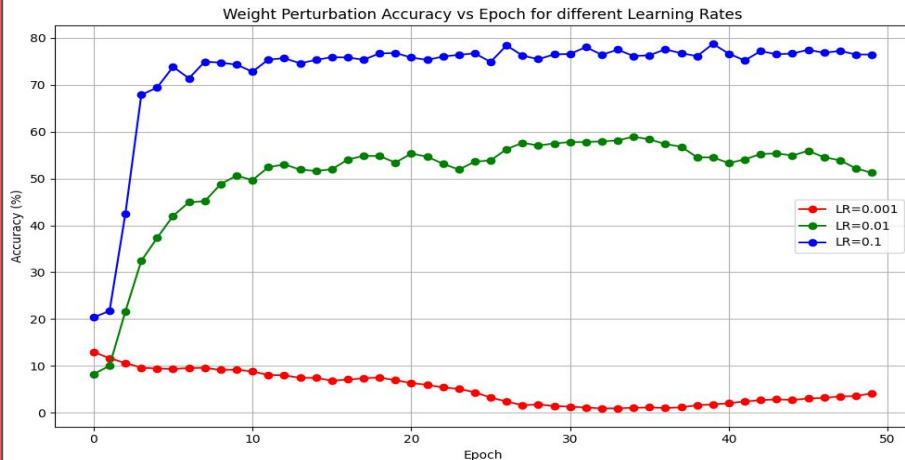
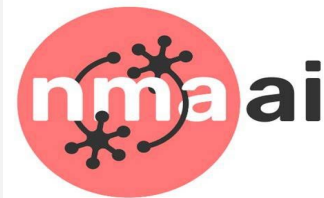
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Weight and Node Perturbation:



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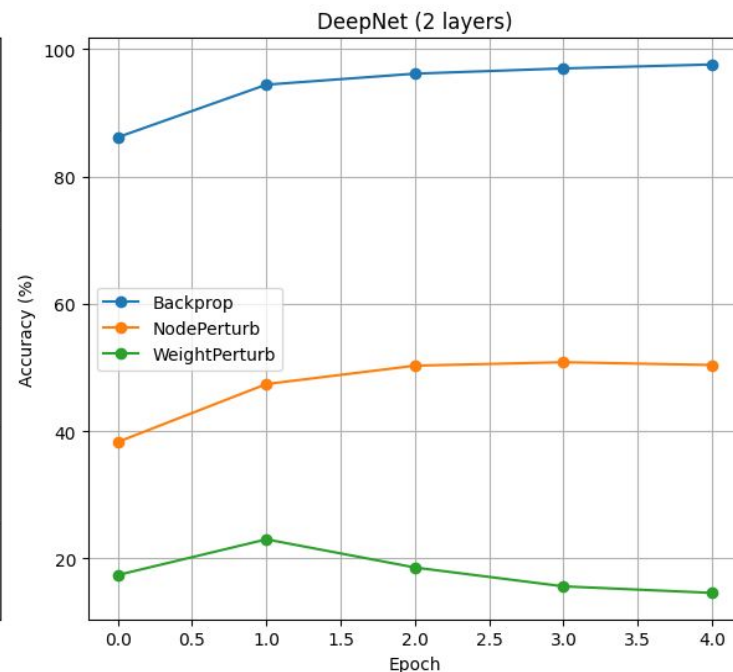
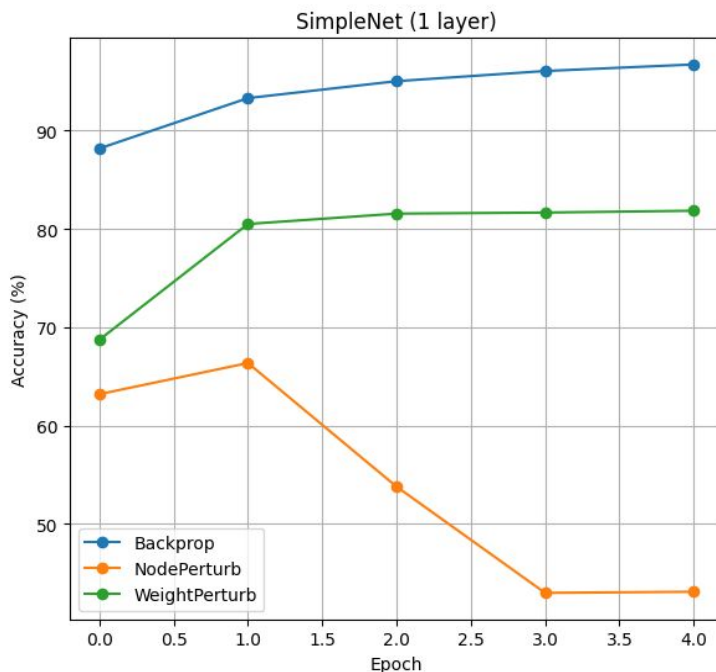
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Weight and Node Perturbation:



Comparison of Learning Methods with LR=0.1



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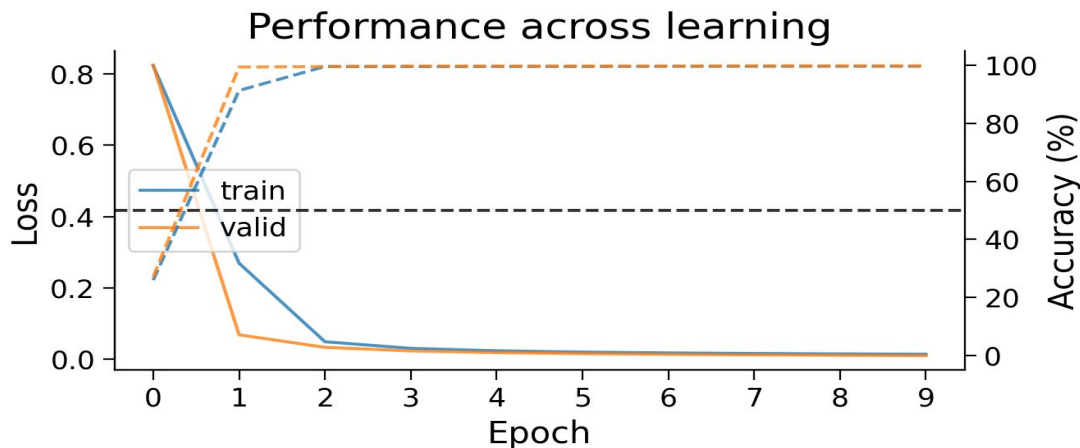
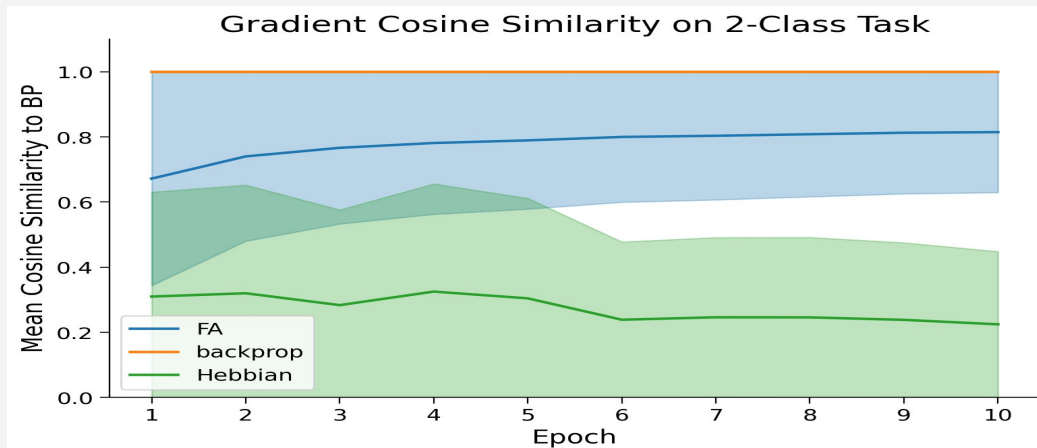
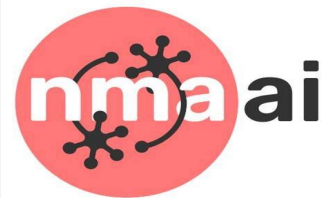
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Feedback Alignment:



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Conclusion and Discussion

- Backpropagation remains most accurate and robust, especially under noise and task switching.
- Hebbian learning and perturbation methods perform worse in raw accuracy, but show promise when combined with **sparse representations**.
- Biologically plausible methods are more sensitive to architecture choices (depth, activation) and hyperparameters.
- Our experiments highlight both the **limitations** and **untapped potential** of local learning rules in dynamic conditions.

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Future Work

- Hybrid Learning Architectures
- Sparse Coding & Interpretability
- Representation Analysis with RDMS
- Visualization of Learning Trajectories

THANK YOU!