+55 31 9 96434978 Belo Horizonte, Brazil **○** prezeck@gmail.com

## Paulo Rezeck

## Software Engineer / Ph.D. Student

**Portfolio:** rezeck.github.io scholar.google.com.br/rezeck linkedin.com/in/rezeck

## **EDUCATION**

DOCTOR OF PHILOSOPHY (PHD) IN COMPUTER SCIENCE  $06/2019 - 10/2022^*$ Universidade Federal de Minas Gerais (UFMG) Brazil 🔤 08/2016 - 02/2019MASTER OF SCIENCE (MSC) IN COMPUTER SCIENCE Universidade Federal de Minas Gerais (UFMG) Brazil 📀 BACHELOR OF SCIENCE (BSC) IN COMPUTER SCIENCE 08/2010 - 07/2016Universidade Federal de Minas Gerais (UFMG) Brazil 🔤 INTERNSHIP IN COMPUTER SCIENCE 02/2014 - 09/2015Eberhard Karls University of Tübingen Germany == PROFESSIONAL & ACADEMIC EXPERIENCE

TECH LEADER / DIGITAL INSPECTION OF INDUSTRIAL PAINTING ACTIVITIES USING COMPUTER VISION

08/2020 - 07/2022

Brazil 🔤

Petrobras / Universidade Federal de Minas Gerais (UFMG)

**Description:** Recognition of human actions for industrial painting activity using deep learning approaches.

- Technical leader of graduate students and design of microservice architecture using containerization (Docker);
- Experience with **neural networks** (CNN/GCN) and **algorithm optimization** (C++/Python/Ceres/Eigen/CUDA);

ROBOTICS ENGINEER / ARTIFICIAL INTELLIGENCE ROBOTIC RACING

02/2019 - 04/2020

**XQuad Team** 

Brazil 💽 / USA 📕

**Description:** Worked with a team specialized in UAV to create an AI for racing drones that can beat a human pilot. Awarded 7th/424 place at the Artificial Intelligence Robotic Racing (AIRR) competition.

- Experience in Linux embedded system and algorithm optimization (C++/Ceres/Eigen/CUDA/CMake);
- Experience with visual odometry (ORBSLAM2/ROVIO/VINS) and object detection algorithms (YOLO/OpenCV);

STUDENT RESEARCHER / ADVANCED TELEOPERATION OF EXCAVATORS IN THE MINING INDUSTRY

10/2017 - 08/2020

Vale Institute of Technology (ITV) / Universidade Federal de Minas Gerais (UFMG)

Brazil 🔯

**Description:** Develop a framework for excavator teleoperation using haptic technologies and visual immersion.

- Robotic manipulator haptic control (C++/ROS/MOVEit);
- Development of a master/slave systems for teleoperation (Unity/WebRTC/ROS);

STUDENT RESEARCHER/ COOPERATIVE MAGNETIC-MAPPING USING SMALL UAVS

09/2015 - 08/2017

Vale Institute of Technology (ITV) / Universidade Federal de Minas Gerais (UFMG)

Brazil 📀

**Description:** Control of multiple drones creating a magnetic mapping for planning the ore deposits exploration.

- Built visual interface for real-time control of drones (Python/JavaScript/QT);
- Developed applications for custom data acquisition and signal processing (Android Studio/Java/C++);

## Languages & Other Professional Qualifications

Programming Languages Python, C, C++, Java, MATLAB, ROS, OpenCV, Unity, Docker, Git, Linux. Experience with

& Framewoks good programming practices, clean code, debugging, and testing;

**Teaching Assistant** Mobile Robotics (2018) & Introduction to Artificial Intelligence (2021) both at UFMG.

**Scientific Production** 8 journals, 12 conferences, 4 workshop/abstracts.

**Languages** Portuguese (native), English (proficient), German (limited working proficiency).

Full CV available at rezeck.github.io.