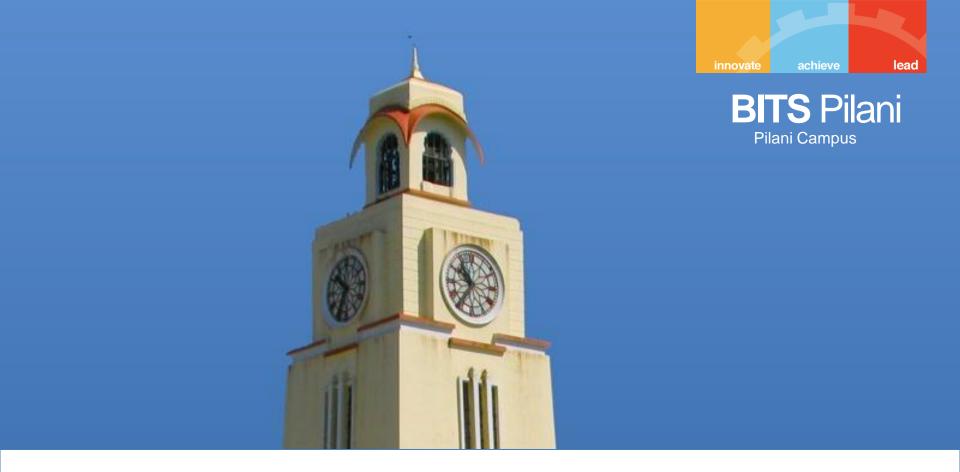




Data Structures & Algorithms
Design- SS ZG519
Lecture - 16

Dr. Padma Murali



Shortest Paths

innovate achieve lead

Shortest Paths

- Dijkstra's algorithm
- Floyd Warshall's algorithm

- How can we find the shortest route between two points on a map?
- Model the problem as a graph problem:
 - Road map is a weighted graph:

```
vertices = cities
edges = road segments between cities
edge weights = road distances
```

Goal: find a shortest path between two vertices (cities)

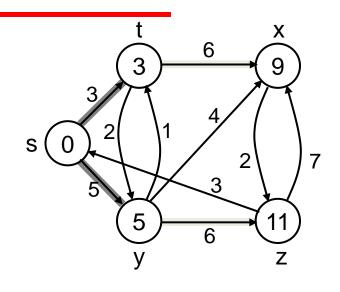
•Input:

Directed graph G = (V, E)

Weight function w : $E \rightarrow R$

•Weight of path $p = \langle v_0, v_1, \dots, v_k \rangle$

$$w(p) = \sum_{i=1}^{k} w(v_{i-1}, v_i)$$



•Shortest-path weight from u to v:

$$\delta(u, v) = \min \begin{cases} w(p) : u \xrightarrow{p} v & \text{if there exists a path from } u \text{ to } v \end{cases}$$

otherwise

•Shortest path u to v is any path p such that $w(p) = \delta(u, v)$

Variants of Shortest Paths

Single-source shortest path

G = (V, E) ⇒ find a shortest path from a given source vertex s to each vertex v ∈ V

Single-destination shortest path

- Find a shortest path to a given destination vertex t from each vertex
- Reverse the direction of each edge ⇒ single-source

Single-pair shortest path

- Find a shortest path from u to v for given vertices u and v
- Solve the single-source problem

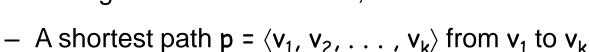
All-pairs shortest-paths

Find a shortest path from u to v for every pair of vertices u and v

Optimal Substructure of Shortest Paths

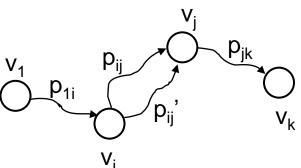
Given:

- A weighted, directed graph G = (V, E)
- A weight function w: $E \rightarrow \mathbb{R}$,



- A subpath of p: $p_{i,j} = \langle v_i, v_{i+1}, \dots, v_j \rangle$, with $1 \le i \le j \le k$

Then: p_{ij} is a shortest path from v_i to v_j



$s \rightarrow a$: only one path

$$\delta(s, a) = w(s, a) = 3$$

 $s \rightarrow b$: only one path

$$\delta(s, b) = w(s, a) + w(a, b) = -1$$

 $s \rightarrow c$: infinitely many paths

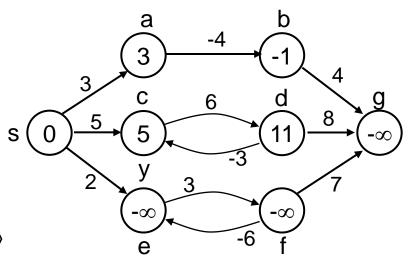
$$\langle s, c \rangle$$
, $\langle s, c, d, c \rangle$, $\langle s, c, d, c, d, c \rangle$

cycle has positive weight (6 - 3 = 3)

 $\langle s, c \rangle$ is shortest path with weight $\delta(s, c) = w(s, c) = 5$

What if we have negative-

weight edges?

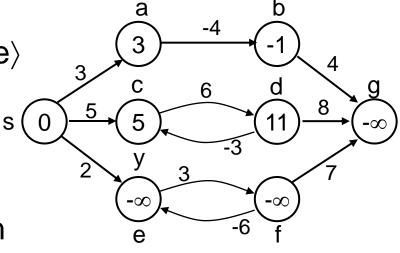


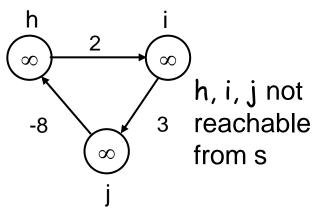
$s \rightarrow e$: infinitely many paths:

- $-\langle s, e \rangle, \langle s, e, f, e \rangle, \langle s, e, f, e, f, e \rangle$
- cycle (e, f, e) has negative weight:

$$3 + (-6) = -3$$

- can find paths from s to e with arbitrarily large negative weights
- $-\delta(s, e) = -\infty \Rightarrow$ no shortest path exists between s and e
- Similarly: $\delta(s, f) = -\infty$, $\delta(s, g) = -\infty$

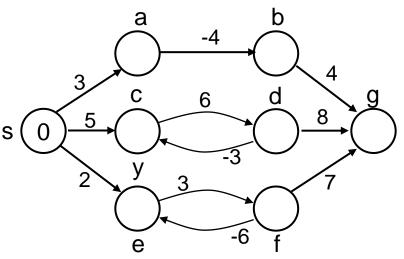




$$\delta(s, h) = \delta(s, i) = \delta(s, j) = \infty$$

Negative-Weight Edges

- Negative-weight edges may form negative-weight cycles
- If such cycles are reachable from the source: δ(s, v) is not properly defined
 - Keep going around the cycle, and get $w(s, v) = -\infty$ for all v on the cycle



Cycles



Can shortest paths contain cycles?

Negative-weight cycles No!

Positive-weight cycles: No!

By removing the cycle we can get a shorter path

Zero-weight cycles

- No reason to use them
- Can remove them to obtain a path with similar weight

We will assume that when we are finding shortest paths, the paths will have no cycles

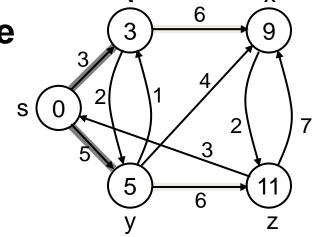
Shortest-Path Representation

For each vertex $v \in V$:

 $d[v] = \delta(s, v)$: a **shortest-path estimate**

- Initially, d[v]=∞
- Reduces as algorithms progress

 $\pi[v] = \mathbf{predecessor}$ of v on a shortest path from s



- If no predecessor, $\pi[v] = NIL$
- $-\pi$ induces a tree—shortest-path tree

Shortest paths & shortest path trees are not unique

Initialization

Alg.: INITIALIZE-SINGLE-SOURCE(V, s)

- 1. for each $v \in V$
- 2. do d[v] $\leftarrow \infty$
- 3. $\pi[v] \leftarrow NIL$
- 4. $d[s] \leftarrow 0$

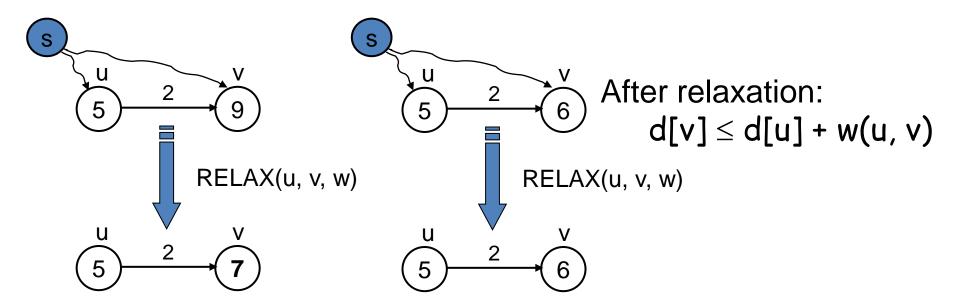
All the shortest-paths algorithms start with INITIALIZE-SINGLE-SOURCE

Relaxation



 Relaxing an edge (u, v) = testing whether we can improve the shortest path to v found so far by going through u

```
If d[v] > d[u] + w(u, v)
we can improve the shortest path to v
\Rightarrow update d[v] and \pi[v]
```



RELAX(u, v, w)

```
    if d[v] > d[u] + w(u, v)
    then d[v] ← d[u] + w(u, v)
    π[v] ← u
```

- All the single-source shortest-paths algorithms
 - start by calling INIT-SINGLE-SOURCE
 - then relax edges
- The algorithms differ in the order and how many times they relax each edge



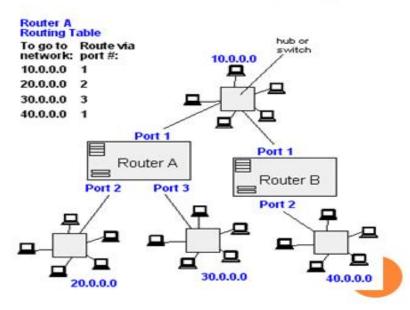
APPLICATIONS OF DIJKSTRA'S ALGORITHM

- Traffic Information Systems are most prominent use
- Mapping (Map Quest, Google Maps)
- Routing Systems



From Computer Desktop Encyclopedia

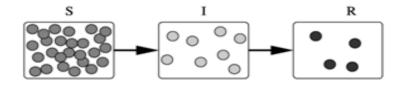
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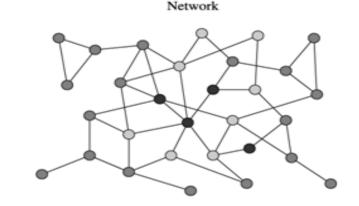




APPLICATIONS OF DIJKSTRA'S ALGORITHM

- o epidemiology
- Prof. Lauren Meyers (Biology Dept.) uses networks to model the spread of infectious diseases and design prevention and response strategies.
- Vertices represent individuals, and edges their possible contacts.
 It is useful to calculate how a particular individual is connected to others.
- Knowing the shortest path lengths to other individuals can be a relevant indicator of the potential of a particular individual to infect others.





* Single-Source shortest-paths problem A for a given vertex called the source in a weighted connected graph, find shortest paths to all its other vertices. & This algorithm is applicable to graphs with nonnegative weights only.

Algorithms Design Nov 1st

* Dijketra's algorithm finds shortest palts to a graph's vertices in order of their distance from a guien source. & First, it finds the shortest path from the source to a vertex nearest to it, then to a second nearest, and so on.



& In general, before its it iteration, the algorithm has identified the shortest paths to i-1 other vertices nearest to the source. & Example of a greedy algorithm.

Shortest Path Algorithm

Dijketra's algorithm for getting a

Shortest fath from a westex to

Shortest fath from a westex to

every other westex in a connected

weighted graph.

step! Let u, be the wester with and are which we are going to start and are going to start and are going to find the shortest fath to a going to find the shortest parign u, a every other every other every other every other permanent label o. Assign every other permanent label o. Assign every werter a temporary label . writex has been

Step 2 ventil every vertex has been assigned a permanent label, do the (i) Take the wester ui which has most recently got a permanent lakel -> eay "d". " label is d". For each wertex is which is adjacent to Ui and has not received a permanent label if d+meight(ui,v) < x(v) -> the temporary label of v.

Algorithms Design Nov 1st

change the temporary label of vo to d + weight (vi, v). Otherwise label of v is unchanged.

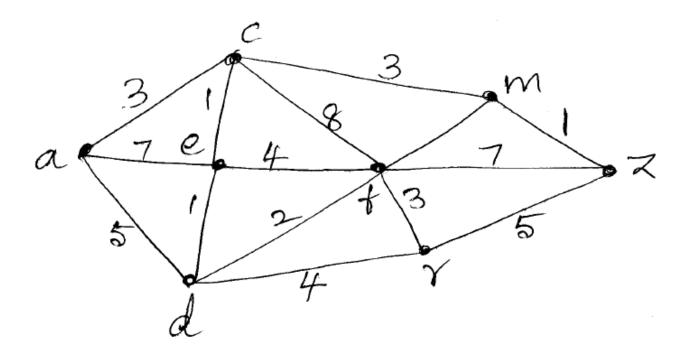
(ii) Take a vertex v which has a temporary label, smallest among all temporary labels in the graph.

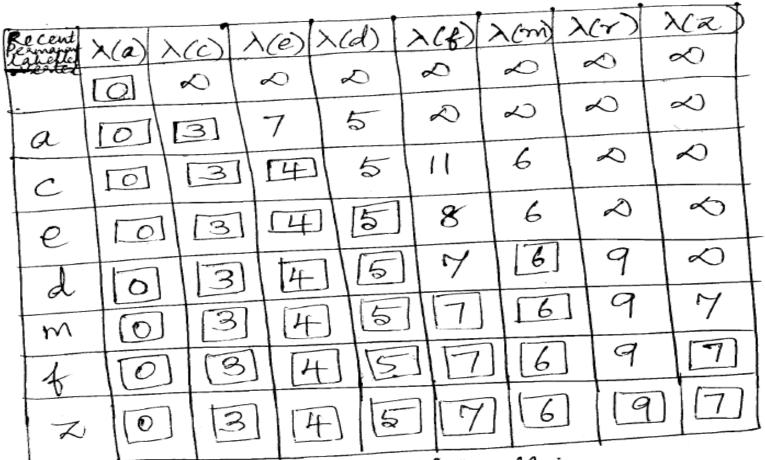
Set u; +1 = v and make its' label permanent. If there is a tie for smallest temporary level choose any of them for permanent label.

Step 3 Algorithm ends only if all vertices have got a permanent lakel.



Find shortest paths and their lengths from vertex a to every other vertex

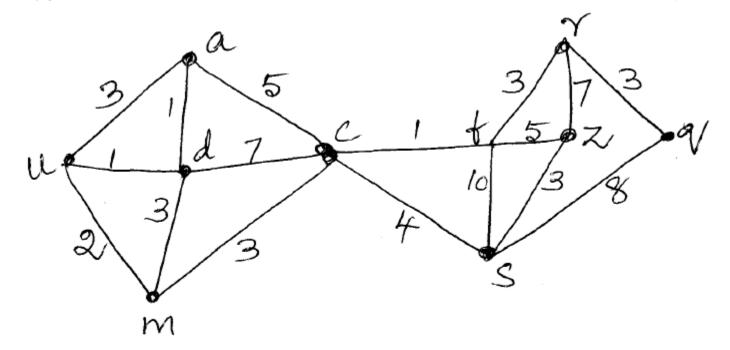


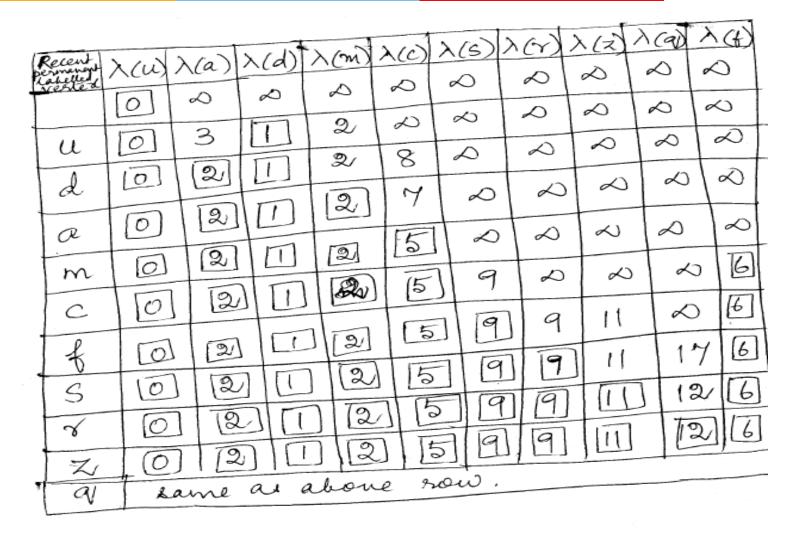


) -> denotes permanent labelling.

The last row of the lattle denotes the shortest paths to all other vertices from vertex a.

Example: 2 Find the shortest path from u to every other wertex.





Dijkstra's Algorithm

Single-source shortest path problem:

No negative-weight edges: w(u, v) > 0 ∀ (u, v) ∈ E

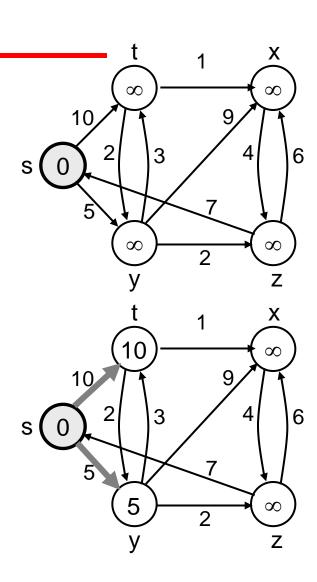
Maintains two sets of vertices:

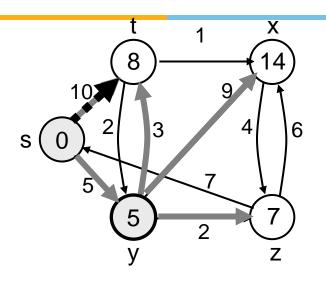
- S = vertices whose final shortest-path weights have already been determined
- Q = vertices in V S: min-priority queue
 - Keys in Q are estimates of shortest-path weights (d[v])

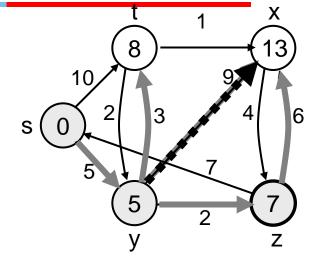
Repeatedly select a vertex $u \in V - S$, with the minimum shortest-path estimate d[v]

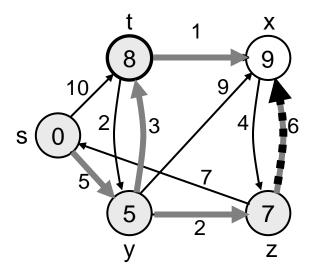
Dijkstra (G, w, s)

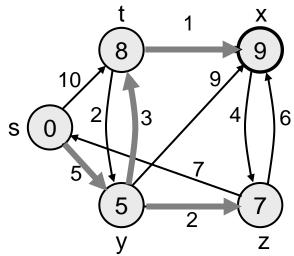
- 1. INITIALIZE-SINGLE-SOURCE(V, s)
- 2. S ← Ø
- 3. $Q \leftarrow V[G]$
- 4. while $Q \neq \emptyset$
- 5. **do** $u \leftarrow EXTRACT-MIN(Q)$
- 6. $S \leftarrow S \cup \{u\}$
- 7. **for** each vertex $v \in Adj[u]$
- 8. **do** RELAX(u, v, w)







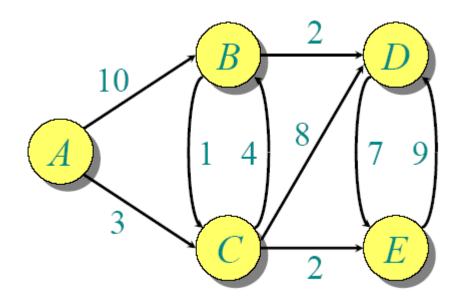


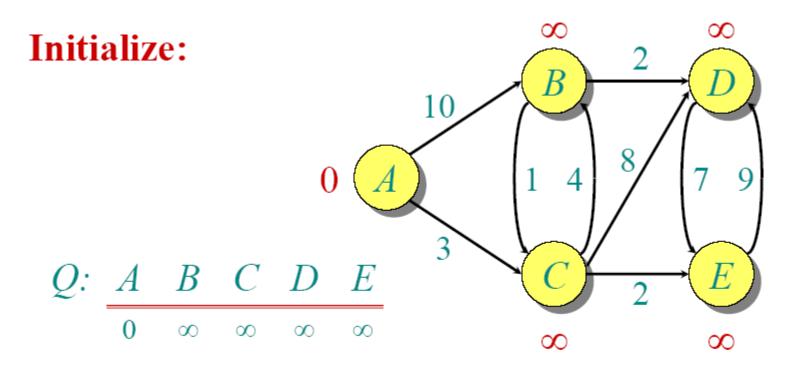


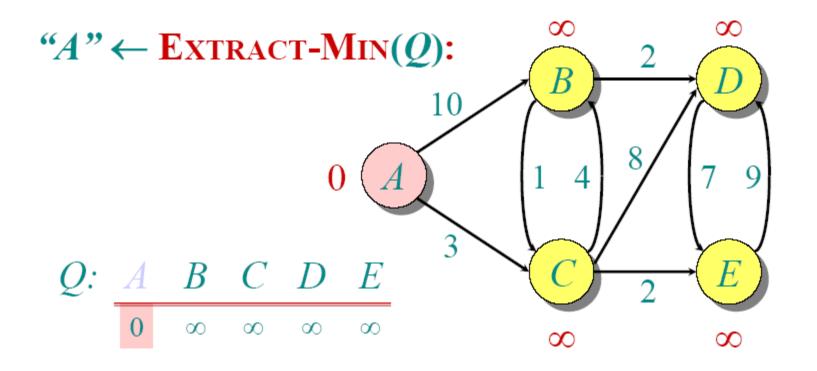
Dijkstra (G, w, s)

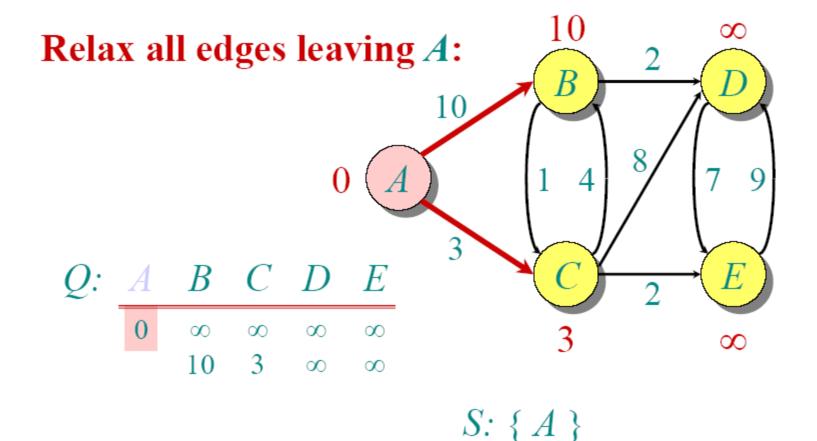


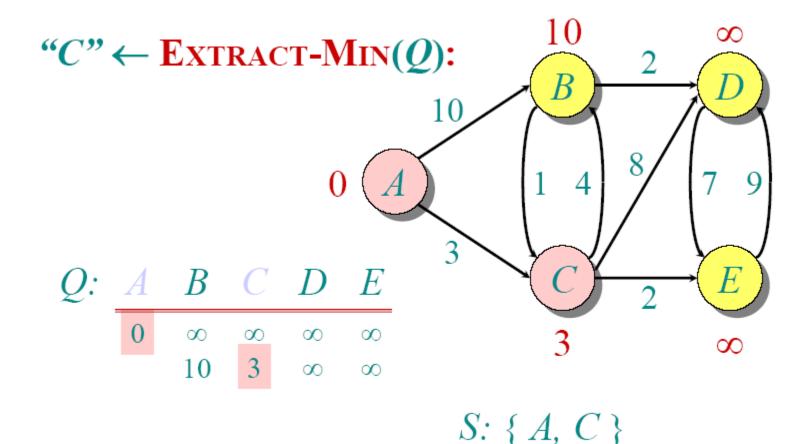
- 1. INITIALIZE-SINGLE-SOURCE(V, s) $\leftarrow \Theta(V)$
- 2. S ← Ø
- 3. $Q \leftarrow V[G] \leftarrow O(V)$ build min-heap
- 4. while $Q \neq \emptyset \leftarrow$ Executed O(V) times
- 5. **do** $u \leftarrow EXTRACT-MIN(Q) \leftarrow O(lgV)$
- 6. $S \leftarrow S \cup \{u\}$
- 7. **for** each vertex $v \in Adj[u]$
- 8. **do** RELAX(u, v, w) \leftarrow O(E) times; O(IgV) Running time: O(VIgV + EIgV) = O(EIgV)

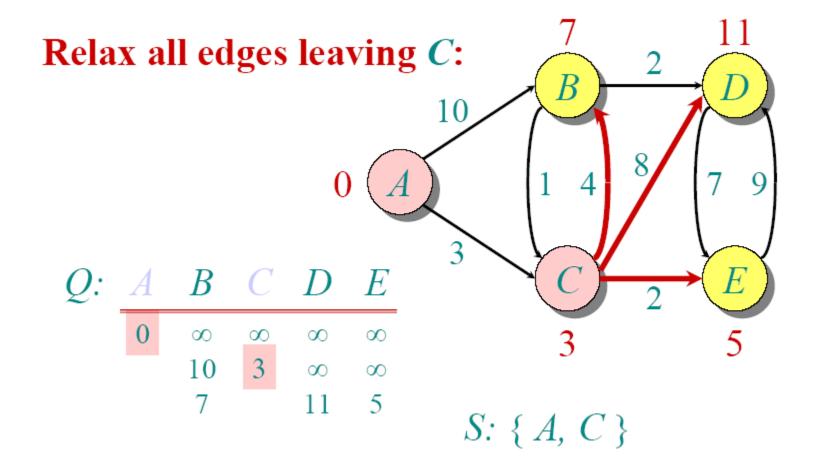


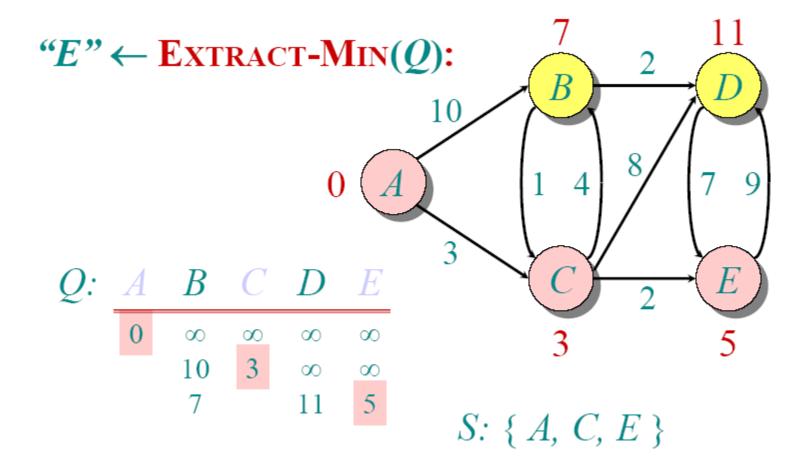


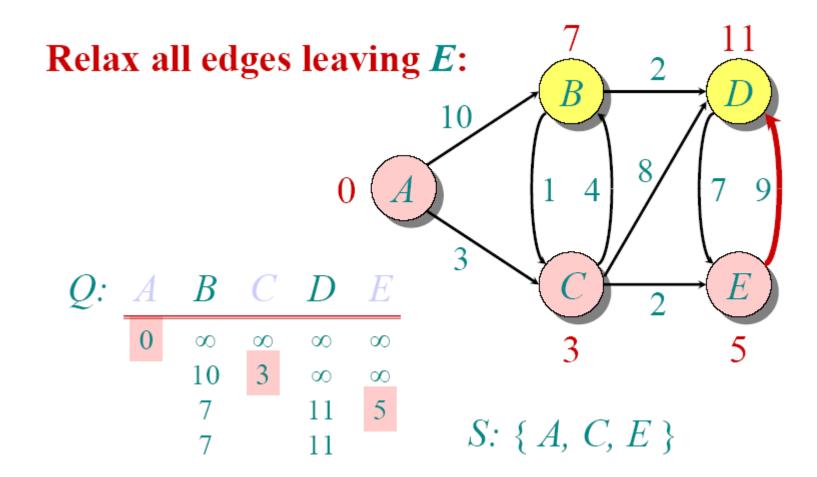


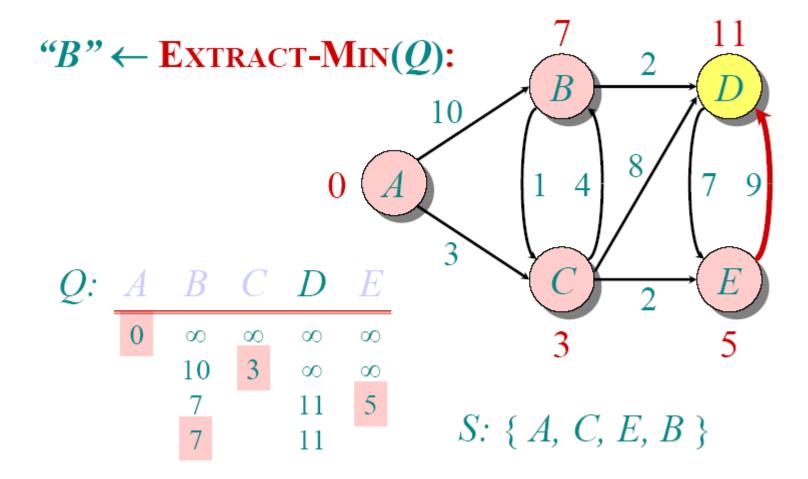


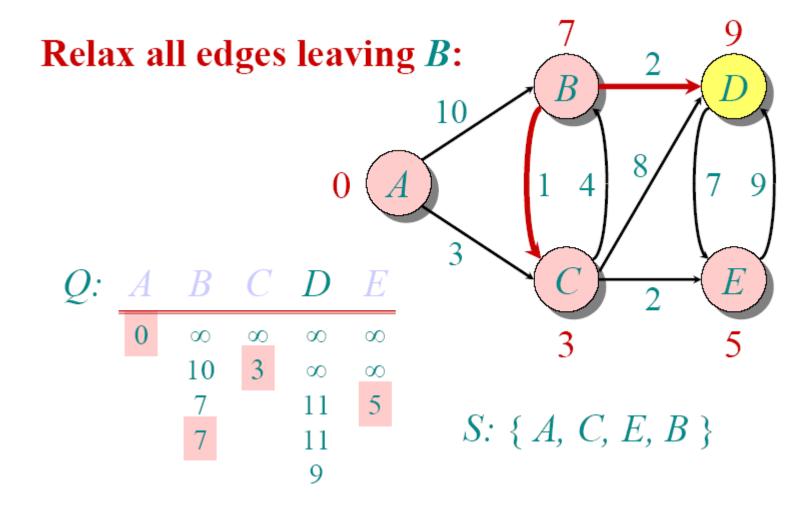


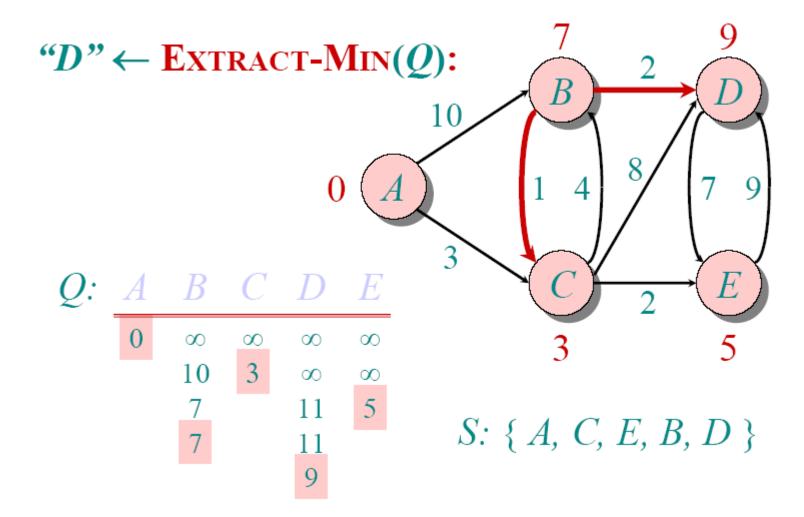












EXAMPLE

