

Interaction between Automation and Human Capital: Labor Share and Inequality

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<https://rfan1994.github.io/files/Growth.pdf>

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October 18, 2022

Abstract

This paper studies how human capital responds to technological revolution since human capital is essential for understanding how labor share, wage premium, and inequality change in the era of automation. I develop a theoretical model by introducing heterogeneous workers (skilled and unskilled) and endogenous human capital to a task model framework. I calibrate the model to fit the data between 1980 and 2005 and discuss the policy implications. First, I find that human capital and automation are racing against each other. Human capital accumulation decreases the automation level and increases the labor share by 0.33%. Second, uneven responses of skilled and unskilled workers amplify inequality, explaining 77% of the wage premium increase. Industry and occupation-level data confirm the empirical implications of the model. Automation has a positive effect on overall skill levels and training investment. The responses of human capital to automation of skilled and unskilled workers are significantly different.

Keywords: Growth, Technology, Automation, Inequality

JEL Classification: J24, J31, O11, O14

*I thank Bulent Guler, Todd Walker, Rupal Kamdar and Laura Liu for their thorough guidance with this project. For their suggestions and support I thank Eric Sims, Yongseok Shin, Jing Cynthia Wu and Choongryul Yang. All errors are my own.

1 Introduction

Automation and artificial intelligence (AI) are important to explain the simultaneous decrease in the labor share and increase in the college premium since 1980 (e.g., Acemoglu and Autor, 2011; Autor and Salomons, 2018; Acemoglu and Restrepo, 2020; Aghion et al., 2021). Automation allows the machine to replace unskilled workers (high school graduates), reducing the labor share. However, it complements skilled workers (college graduates), increasing the college premium.

Human capital accumulation is a key way that workers could respond to automation that has not been discussed much in the literature. There are two ways that workers can adapt their human capital. Workers could respond to automation by increasing the supply of skilled workers (extensive margin). The share of employment with a Bachelor's degree and higher has increased from 26.98% to 43.74% from 1992 to 2021.¹ Additionally, workers can increase their skill levels through on-the-job training (intensive margin). The ratio between training (e.g., GED, ESL, work-related courses) and working hours has increased from 0.244% to 1.049% for high school graduates and from 0.758% to 1.212% for college graduates from 1995 to 2005.² Acquisition of new skills allows unskilled workers to relocate to less automated sectors and allows skilled workers to better take advantage of technology.

Important questions are how the human capital of each skill group responds to automation and to what extent the response of human capital changes the effect of automation on the labor market (labor share and wage premium) and welfare inequality. Sachs and Kotlikoff (2012) provide an earlier related study, which shows that young, low-skill workers respond to automation by decreasing investment in education as the wage depreciation limits their ability to save. Prettnner and Strulik (2020) show that automation increases the share of skilled workers because workers are motivated by higher wage premiums. In contrast to the existing studies on automation and human capital, I focus on on-the-job training. Athreya and Eberly (2015) document the stagnated college attainment accompanied by a substantial increase in the college premium. Not everyone is able or willing to attend college due to credit constraints or uncertainty, but most people spend a lot of time acquiring human capital throughout their life.

To study the interaction between automation and human capital and their macroeconomic implications, I adopt the task model framework of Acemoglu and Restrepo (2018). Tasks are defined as units of work activity that produce output; they can be produced by machine (only if automated) or labor. I extend the model by introducing heterogeneous workers, endogenous human capital, and directed

¹Data source: FRED (Federal Reserve Economic Data)

²Data source: ATES (Adult Training and Education Survey)

research and development (R&D) sector. Workers are different in their skill levels (skilled and unskilled); skilled workers have a comparative advantage over newer tasks and are more able to adjust their human capital. I endogenize human capital following Grossman et al. (2021). Human capital is accumulated by learning at the opportunity cost of wage income but increases the productivity of workers. Research and development (R&D) is directed and endogenous; skilled workers can become scientists and work in automation (automate old tasks favoring machine) or innovation (innovate new tasks favoring labor) sectors.

I start by studying the short-run effects of automation and human capital in a static model. Automation directly displaces unskilled workers (displacement effect) and indirectly affects skilled workers since unskilled workers relocate after being displaced (relocation effect). Higher automation increases the wage premium since it pushes unskilled workers to tasks that they have disadvantages compared with skilled workers. Higher human capital increases the effective labor supply, decreases automation incentives, and increases labor share. The human capital gap between skilled and unskilled workers increases the wage premium.

The short-run effects are only part of the story. I then embed this framework in a dynamic environment where I allow physical and human capital accumulation and endogenous R&D. The research is directed, and the R&D sector decides at which rate to automate existing or innovate new tasks based on the profit and cost of each patent type. The increase of automation is endogenous, resulting from technological revolution – a reduction in automation cost. After a reduction in automation cost, more scientists work in the automation sector and automation rate increases. Automation level increases and leads to higher innovation and human capital investments. A higher automation level complements the innovation sector since it drives up the capital price, pushes down the wage level, and increases the innovation patent profit. Innovation rate then increases and complements human capital investment since it increases future wage growth and incentivizes human capital investment. Higher human capital growth complements innovation and substitutes automation, which decreases the long-run automation level and increases the long-run labor share.

I highlight the uneven impacts of automation on skilled and unskilled workers and the distinctive responses of skilled and unskilled workers to automation. First, skilled workers benefit more from the productivity effect (improvement of allocation and higher innovation rate) of the technological revolution, while unskilled workers are affected more by the displacement effect. As a result, skilled workers are more incentivized than unskilled workers to invest in their human capital to maximize the benefit of automation. Unskilled workers save more through physical capital and less through human capital to insure against the wage drop caused by automation. Second, skilled and unskilled workers accumulate their human capital

in different ways. Skilled workers acquire skills through learning-or-doing, making it easier to adjust their human capital in response to the technology change. On the other hand, unskilled workers accumulate human capital passively through learning-by-doing, adapting to the technology change more slowly.

Before calibrating the model and implementing counterfactual policy experiments, I solve the social planner's problem. There are two externalities in the decentralized economy. First, skilled workers overinvest in their human capital. Skilled workers don't internalize their negative externalities in the R&D sector. High productivity in the production sector increases the opportunity cost of research and development. Second, too many tasks are automated. When developing innovation patents, the R&D sector does not internalize the positive externalities they generate on existing tasks. Keeping that in mind, an automation tax and a training tax on skilled workers seem to be appropriate for redistributive fiscal policy.

I calibrate the model to match key macroeconomic variables from 1980 (pre technological revolution) to 2005 (post technological revolution). The technological revolution is modeled as a reduction in automation cost to target the change in labor share. Human capital accumulation increases the labor share by about 0.33% (0.82% from skilled labor share and -0.48% from unskilled labor share). The direct effect of automation contributes only 23.4% of the wage premium increase, while the enlarged human capital gap causes 76.6% of the increase. I simulate the transition numerically and implement counterfactual policy experiments with an automation tax or a training tax on skilled workers. The automation level increases immediately after the reduction in automation cost as the automation rate increases. The value of innovation patents increases as the automation level increases, and innovation starts to catch up with automation. Endogenous human capital decreases the labor share in the short-run and slows innovation since workers spend more time on training and supply less labor. Once the workers accumulate enough human capital, the innovation rate increases and the economy converges to a lower automation level and a higher labor share than the scenario with fixed human capital. An automation tax decreases automation, increases labor share, and decreases wage inequality. A training tax increases automation and decreases labor share but is more efficient in reducing the wage and welfare inequality. A training tax also increases the technology growth rate and accelerates the transition by lowering the opportunity cost of research.

My research delivers four key results. First, a reduction in automation costs increases productivity. It improves production factor allocation and increases the innovation rate. The innovation sector develops more new tasks because of productivity gain. Second, human capital investment complements innovation but substitutes automation. Human capital investment increases effective labor sup-

ply and slows capital deepening. It decreases the overall automation level and increases labor share. With a high enough human capital growth rate, the human capital supply is abundant; the economy will never converge to a balanced growth path (BGP) where all the tasks are automated. Third, endogenous human capital amplifies the effect of the technological revolution. The direct effect of automation can explain only 23.4% of the wage premium change; the rest of the change is contributed by the enlarged human capital gap. Skilled workers benefit more from automation and are more incentivized than unskilled workers to invest in their human capital; they also have a higher ability to adjust their human capital accumulation. As a result, the human capital gap between skilled and unskilled workers increases, leading to a higher wage premium. When the human capital is endogenous, the labor share drops more in the short run; and it takes longer for the innovation rate to catch up since workers spend extra time on training to adapt to the new technology environment and supply less labor. Fourth, an automation tax decreases automation and increases labor share. A training tax on skilled workers is more efficient in reducing inequality and accelerating the recovery.

Last but not least, I confirm the empirical implications of the model using both industry and occupation level data. Using EU KLEMS (EU level analysis of capital, labor, energy, materials and service inputs) data, I find a positive response of education level to the development of automation, but with a four-year lag. Occupational level evidence is provided using O*NET (Occupational Information Network) and ATES (Adult Training and Education Survey). Skill levels grow faster in the occupations more exposed to automation, contributed mainly by the skilled workers. Skill level growth or training time is decreasing in the occupational automation exposure level but increasing in the workers' education level. Skilled and unskilled workers respond differently to automation; higher exposure to automation increases the human capital investment of skilled workers more than that of unskilled workers.

This paper makes four contributions to the literature. First, this paper is closely related to the study of the effects of automation on labor share, employment, wage, and inequality. Acemoglu and Autor (2011) and Acemoglu and Restrepo (2018) develop theoretical frameworks to explore the displacement effect of automation. Many empirical studies support the theoretical predictions and show that automation is important in explaining the ongoing change in the US labor market. Automation decreases the labor share (Autor and Salomons, 2018; Dinlersoz et al., 2018) and aggregate employment at the employment zone level (Aghioen et al., 2021). In terms of inequality, automation can explain between 50% and 70% of changes in the US wage structure (Acemoglu and Restrepo, 2020) and increases welfare inequality through the return to wealth (Moll et al., 2021). I contribute to this literature by distinguishing the direct and indirect effects of

automation through displacement and human capital response channels.

Second, my research contributes to the literature on endogenous growth³ and technology adoption. This literature goes back to Romer (1990) and has developed into an integrated framework for understanding endogenous growth from macro and microeconomic perspectives (Acemoglu, 2009; Aghion and Howitt, 2008). The setups of the research and development sector in my model are mostly similar to Acemoglu et al. (2013). In their model, unskilled workers are used in production, while skilled workers perform R&D functions and operations. In contrast to the canonical growth model, the R&D in my paper is directed; resources can be assigned to automation or innovation. Theory and data suggest that new technologies are complementary with skilled labor (Violante, 2008; Sanders and Ter Weel). I suggest that human capital is an important source of skill bias. Benhabib et al. (2017) argue that the innovation incentives and the growth rate depends on the adoption environment (Hall and Khan, 2003; Atkeson and Kehoe, 2007; and Acemoglu et al., 2013). In this paper, I study how the adoption environment affects the intensity and direction of research, determining the automation level and the growth rate.

Third, this paper contributes to the literature on human capital accumulation. I explore the heterogeneous human capital investment for different skill groups facing automation. The accumulation of human capital takes two forms. First, knowledge is passed across generations through education, and the initial skill type of the workers is determined by their choice of schooling investment (Schultz, 2003; Bohacek and Kapicka, 2008). Second, human capital can be accumulated after school. Experience can be accumulated by working through learning-by-doing (Imai et al., 2004; Thompson, 2010; Burdett et al., 2011). Skills can also be acquired by training at the opportunity cost of wage income through learning-or-doing (Frazis, 2007). This paper focuses mainly on after-school human capital acquisition following Stantcheva (2015). In my model, agents optimally choose the working and training time, and human capital evolves depending on the amount of training. I highlight the heterogeneous learning abilities of different types of workers.

Last, my paper explores the interaction between human capital and technology but distinguishes automation (substitutes labor) and innovation (complements labor) as two types of technological change. Technology and human capital can be twin engines of growth but can also be opponents racing against each other. The dynamics between innovation and human capital are complementary. Skills are required to implement and invent new technology (Lloyd-Ellis and Roberts,

³Aghion et al. (2014) discuss the setups and applications of Schumpeterian growth theory. Innovations replace older technologies, resulting in endogenous growth; individuals can choose to allocate the labor supply between production and research.

2002); new technology is more productive and will be adopted only when used with a high fraction of skilled workers (Beaudry et al., 2006); the endogenous growth would happen only if both innovation and human capital grow at the same time (Stokey, 2014; Stokey, 2020). However, the dynamics between automation and human capital are competitive. Since workers and R&D sectors are making decisions separately, growth can be described as a strategic game between workers and entrepreneurs on decisions of human capital and R&D investment (Redding, 1996).

In the rest of this paper, I start by setting up the model and solving static equilibrium in section 2. Then I bring the static framework under a dynamic environment in section 3. I solve the social planner’s problem in section 4 to explore the appropriate taxes. Then I calibrate the model, solve the transition and implement counterfactual experiments in section 5. Section 6 provides empirical evidence for the key implications of the model. Section 7 concludes.

2 Model with Automation

I develop a growth model with endogenous innovation, automation and human capital. I adopt the task model framework developed by Acemoglu and Restrepo (2018). However, I focus on the directed research and development and endogenous human capital investment. Human capital growth is endogenized following Grossman et al. (2021), but with more generalized accumulation functions.

2.1 Environment

Figure 1 presents the structure of the model. The formal model of the economy has three sectors: household, production, and the research and development (R&D) sector. There are two types of households: unskilled and skilled. Households consume, save and invest in human capital. Final good producers produce consumption goods by aggregating tasks produced by task producers. Tasks are defined as units of work activity that produce output. To produce tasks, task producers purchase patent intermediates (innovation or automation) from the R&D sector and combine them with production factors (capital, low-skill or high-skill labor). Unskilled workers can only work in the production sector, supplying low-skill labor. Skilled workers can work both in the production and the R&D sector, supplying high-skill labor or working as scientists to develop innovation or automation patents.

The economy is populated by two types of representative households: skilled households and unskilled households. They have the same preference and discount rate, but supply different types of labor and have different learning abilities. The



Figure 1: Model Structure

households make two decisions simultaneously. First, they make consumption-saving decisions to maximize lifetime utility. Second, they allocate their time between working and training to optimize their lifetime wage income. Unskilled households supply low-skill labor, and skilled household supply high-skill labor or work as scientists. Physical and human capital are two alternative ways for households to save for the future. If the return to physical capital (interest rate) is higher, households will prefer to save through physical capital; if the return to human capital (wage growth rate) is higher, they will favor human capital investment.

There are task and final good producers in the production sector, and all the producers are perfectly competitive. To produce tasks, task producers purchase patent intermediates from the R&D sector and combine them with production factors. If the task has been automated, the producers of this task will purchase automation patent intermediates and choose between labor (low and high-skill) and machines to minimize the production cost. If the task hasn't been automated, the producers of this task will purchase innovation patent intermediates and can only choose between low and high-skill labor to produce the intermediate goods. The final good producers purchase the tasks from the task producers at competitive prices and aggregate them into the consumption goods.

The skilled workers can work as scientists in the R&D sector to develop new patents. There are two types of patents: innovation patents bring new tasks to the economy, which increases labor productivity and can only be produced by labor;

automaton patents allow the firm to use machine instead of labor to produce the task. After developing the patent, the scientists hold the patent right and sell the task-specific patent intermediates to task producers at the price ψ . The growth of the economy is endogenous and Schumpeterian. The old tasks are destroyed when new ones are introduced, keeping the task measure constant.⁴

Household

The economy is populated by two types of representative households: skilled households with measure ϵ_H and unskilled households with measure ϵ_L . They share the same constant relative risk aversion (CRRA) preference $\frac{C^{1-\theta}}{1-\theta}$, with θ being the intertemporal elasticity of substitution, and discount rate ρ . However, they supply different types of labor and have different learning abilities. Households maximize their lifetime utility by making consumption-saving and working-learning decisions.

Unskilled households can only work in the production sector and supply low-skill labor. Each period, they receive return to capital K_L at rate r , wage income W_L , and transfers from the government T_L . Given the current technological environment, they allocate their time l_L to working and $1 - l_L$ to training. The total low-skill labor supply is $\epsilon_L l_L$. By allocating time to learning, they can increase the future wage by increasing their human capital, but at the opportunity cost of wage income. The accumulation of human capital is increasing in the time spent on training. Unskilled households maximize their lifetime utility:

$$\rho V_L(K_L, h_L) = \max_{C_L, L_L, 1-l_L} \frac{C_L^{1-\theta}}{1-\theta} + V_{LK}(K_L, h_L) \dot{K}_L + V_{Lh}(K_L, h_L) \dot{h}_L,$$

subject to the laws of motion of physical and human capital:

$$\begin{aligned} \dot{K}_L &= rK_L + \frac{W_L L_L}{\epsilon_L} - \tau_{hL} W_L (1 - l_L) + T_L - C_L, \\ \dot{h}_L &= \frac{(1 - l_L)^{\alpha_L}}{\mu_{hL}}, \\ L_L &= \epsilon_L l_L. \end{aligned}$$

Skilled households also receive the return to capital K_H at rate r , and transfers from the government T_H . They are different from unskilled workers in that they can work in the production sector by supplying high-skill labor L_H or the R&D sector by supplying research labor for automation (ϵ_I) and innovation (ϵ_N). When they work in the production sector, they receive the wage income W_H . When

⁴The task productivity is increasing in the task index. If the variety growth is not excluded, the growth rate will increase over time and converge to infinity.

they work in the research sector, they hold the patent they develop and receive the patent profits Π by selling patent intermediates to task producers. Skilled households maximize their lifetime utility:

$$\rho V_H(K_H, h_H) = \max_{C_H, L_H, 1-l_H} \frac{C_H^{1-\theta}}{1-\theta} + V_{HK}(K_H, h_H)\dot{K}_H + V_{Hh}(K_H, h_H)\dot{h}_H,$$

subject to the law of motion of physical and human capital:

$$\begin{aligned}\dot{K}_H &= r_t K_H + \frac{W_H L_H + \Pi}{\epsilon_H} - \tau_{hH} W_H (1 - l_H) + T_H - C_H, \\ \dot{h}_H &= \frac{(1 - l_H)^{\alpha_H}}{\mu_{hH}}, \\ L_H &= \epsilon_H l_H - \epsilon_N - \epsilon_I.\end{aligned}$$

The government collects taxes on training at rates τ_{hL} and τ_{hH} for unskilled and skilled workers. Training tax is linear in the opportunity cost of training $W_L(1-l_L)$ and $W_H(1-l_H)$.

The law of motion for human capital is a generalized form of Grossman et al. (2021). μ_{hL} and μ_{hH} capture the inverse of training efficiency, and α_L and α_H represent the training style. The training efficiency is decreasing in μ_{hj} , $j \in \{L, H\}$, and the human capital growth converges to 0 when μ_{hj} converges to infinity. When $\alpha_j \rightarrow 0$, human capital is accumulated through learning-by-doing, and the human capital growth rate is constant, no matter how much time the workers spend on training. When $\alpha_j \rightarrow 1$, human capital is accumulated through learning-or-doing, and the human capital accumulation rate is linear in the time spent on training⁵. Here I assume that $0 \leq \alpha_L < \alpha_H \leq 1$, skilled workers can adjust their human capital accumulation more easily through on-the-job training than unskilled workers, and unskilled workers mainly accumulate their human capital passively through working experience.

Production Sector

The final good sector is perfectly competitive and produces the consumption good Y by combining a unit measure of tasks $i \in [N-1, N]$, with an elasticity of substitution $\sigma \in (0, \infty)$. The output of each task i is $y(i)$. The creation of new tasks will destroy the oldest tasks, so the total measure of tasks in this economy remains constant at 1. The production function of final good sector takes the form:

$$Y = \tilde{A} \left(\int_{N-1}^N y(i)^{\frac{\sigma-1}{\sigma}} di \right)^{\frac{\sigma}{\sigma-1}}.$$

⁵Grossman et al. (2021) is a special case: $\mu = 1$ and $\alpha = 1$

The competitive final good producers purchase task i from the task producer at price $p(i)$, and solve the following problem:

$$\max Y - \int_{N-1}^N p(i)y(i)di.$$

The task sector is also competitive; task producers purchase task-specific intermediates $q(i)$ at price ψ from patent holders, which embodies the technology. Then they combine the task-specific intermediates with production factors (capital or labor). Suppose the automation patent has not been developed for the task. In that case, the task producers can only purchase the innovation patent intermediates. They can only use labor (high-skill $h(i)$ or low-skill $l(i)$) to produce the intermediate goods $y(i)$. If the task has been automated, the task producer can choose between automation and innovation patents and combine capital $k(i)$ with automation patent or labor (high-skill $h(i)$ or low-skill $l(i)$) with innovation patent. The production function of task producers is Cobb-Douglas:

$$y(i) = \begin{cases} q(i)^\eta \left(k(i) + \gamma_L(i, h_L)l(i) + \gamma_H(i, h_H)h(i) \right)^{1-\eta}, & i \text{ is automated} \\ q(i)^\eta \left(\gamma_L(i, h_L)l(i) + \gamma_H(i, h_H)h(i) \right)^{1-\eta}, & i \text{ is not automated} \end{cases}.$$

When the intermediate goods $y(i)$ are produced with machine, the productivity is normalized to 1. The productivity of the skilled worker $\gamma_H(i, h_H)$ and the unskilled worker $\gamma_L(i, h_L)$ are increasing in the task index i and the worker's human capital level h_H and h_L . The task producers solve the following problem:

$$\max p(i)y(i) - Rk(i) - W_Ll(i) - W_Hh(i) - \psi q(i).$$

Research Sector

Some skilled workers work as scientists in the R&D sector to develop new automation or innovation patents. An innovation patent introduces a new task to the economy and increases the productivity of labor, automation patent allows the firm to produce an existing task using machines and improves the production factor allocation. After developing new patents, scientists sell task-specific intermediates to task producers at the price ψ until the patent is outdated and destroyed. When a patent is destroyed, the patent holder is forced to exit the market and gets compensated by the new entry.⁶ The values of automation and innovation patents are defined as the sum of discounted profit by selling patent

⁶I borrow this structure of intellectual property rights from Acemoglu and Restrepo(2018) to exclude the creative destruction. They show that the structure with creative destruction has similar implications but introduces additional instability to the model.

intermediates, denoted by P_N and P_I , respectively. The amount of automation and innovation patents introduced to the economy (κ_I and κ_N) are functions of scientists hired in each sector (ϵ_I and ϵ_N). Assume that the production functions of the R&D sector take the form:

$$\kappa_I(\epsilon_I) = \frac{\epsilon_I^\lambda}{\mu_I}, \quad (1)$$

$$\kappa_N(\epsilon_N) = \frac{\epsilon_N^\lambda}{\mu_N}, \quad 0 < \lambda \leq 1. \quad (2)$$

The amount of new patents developed is increasing in the scientists working in the sector, with decreasing marginal productivity. Bloom et al. (2020) find empirical evidence showing that research effort is rising while research productivity is declining. λ captures the decreasing marginal productivity. μ_I and μ_N capture the inverse of research efficiency. The research is more costly with higher μ_I and μ_N .

2.2 Static Model Equilibrium

In this subsection, I start with a static version of the model to characterize the short-run effects of automation and human capital on allocation, factor prices and labor share. In section 3, I bring the static framework to a dynamic environment, to understand the interaction between the change of technology and human capital in the long-run.

By solving the final good producers' problem, I can derive the demand function for task i as a function of the task price $p(i)$, the demand for task i is decreasing in the task price $p(i)$:

$$y(i) = \tilde{A}^{\sigma-1} Y p(i)^{-\sigma}. \quad (3)$$

Proof. See Appendix A.

The task producers sell the tasks to final good producers. The task sector is perfectly competitive, so the price of the task $p(i)$ equals the cost of production. The effective cost depends on the ratio between the factor price and the factor productivity of the task. When the task has been automated, the task producers choose between capital and labor to minimize the production cost; when the task is new and has not been automated, the task producers can only select between

high-skill and low-skill labor. Thus, the price $p(i)$ of task i can be written as:

$$p(i) = \begin{cases} \Psi \min\{R^{1-\eta}, \left(\frac{W_L}{\gamma_L(i, h_L)}\right)^{1-\eta}, \left(\frac{W_H}{\gamma_L(i, h_H)}\right)^{1-\eta}\} & , \text{ if automated} \\ \Psi \min\left\{\left(\frac{W_L}{\gamma_L(i, h_L)}\right)^{1-\eta}, \left(\frac{W_H}{\gamma_L(i, h_H)}\right)^{1-\eta}\right\} & , \text{ if new,} \end{cases}$$

$$\text{where } \Psi = \left(\frac{\psi}{\eta}\right)^\eta \left(\frac{1}{1-\eta}\right)^{1-\eta}.$$

Proof. See Appendix A.

By plugging the price $p(i)$ into the demand function (Equation 3) derived from the final good sector above, the output of each task can be solved as:

$$p(i)y(i) = \begin{cases} Y\left(\frac{R}{A}\right)^{1-\hat{\sigma}} & , \text{ using capital} \\ Y\left(\frac{W_L}{A\gamma_L(i, h_L)}\right)^{1-\hat{\sigma}} & , \text{ using low-skill labor} \\ Y\left(\frac{W_H}{A\gamma_H(i, h_H)}\right)^{1-\hat{\sigma}} & , \text{ using high-skill labor,} \end{cases}$$

$$\text{where } \hat{\sigma} = 1 - (1 - \eta)(1 - \sigma) \text{ and } A = \left(\frac{\tilde{A}}{\Psi}\right)^{\frac{\sigma-1}{\hat{\sigma}-1}} = \left(\frac{\tilde{A}}{\Psi}\right)^{\frac{1}{1-\eta}}.$$

Proof. See Appendix A.

Assumption 1. (Elasticity of Substitution)

Assume that $\hat{\sigma} > 1$.

When $\hat{\sigma} > 1$, the tasks are substitutes. The output of the task is increasing in the task productivity and decreasing in the factor price. The demands for factors are decreasing in the factor prices. More workers are hired when their task productivity is higher.

Assumption 2. (Task Productivity)

Assume that skilled workers have a comparative advantage in high index tasks over machine and unskilled workers; all workers have an absolute advantage over machine. The task productivity is increasing in the index i and human capital h_H and h_L . The productivity of machine is constant over all tasks and is normalized to 1.

$$\begin{aligned} \gamma_K &= 1 \\ \gamma_H(i, h_H) &= e^{B(i)} e^{bh_H} \\ \gamma_L(i, h_L) &= e^{B(N-1)+B_L(i-(N-1))} e^{bh_L} \end{aligned}$$

The innovation patent is complementary to skilled workers and directly increases their productivity at the rate B . The innovation also has a spillover effect on unskilled workers and increases their productivity.⁷ The productivity of skilled and unskilled workers is always the same for the most outdated task ($N - 1$), but skilled workers have a comparative advantage over unskilled workers in new tasks ($B - B_L$). The newer the tasks, the more comparative advantage the skilled workers have. Task productivity is also increasing in the human capital level. Human capital is general and increases workers' productivity for all tasks.

Proposition 1. (Allocation)

The research sector always automates from the lowest index tasks. There exists automation level I , such that all the tasks between $N - 1$ and I are produced by machine, and all the tasks between I and N are produced by labor. Given automation level I , there exists a cutoff point S , such that all the tasks between I and S are produced by low-skill labor, and all the tasks between S and N are produced by high-skill labor.

The task producers have incentives to adopt the newest automation patent when the following condition is satisfied:

$$R < \frac{W_L}{\gamma_L(I, h_L)}$$

The task producers have incentives to adopt the newest innovation patent when the following condition is satisfied:

$$R > \frac{W_H}{\gamma_H(N, h_H)}$$

The allocation S must satisfy the no arbitrage condition:

$$\frac{W_H}{\gamma_H(S, h_L)} = \frac{W_L}{\gamma_L(S, h_L)}$$

Proof. See Appendix B.

Figure 2 presents the task allocation. Workers have a comparative advantage over machine on newer tasks. The R&D sector always automates the oldest tasks that have not been automated because the automation patent can generate more profit in the more outdated tasks. The R&D sector has incentives to develop the automation patent only if the firm is willing to purchase the automation patent

⁷To assure the existence of a balanced growth path. Without the spillover effect, the wage premium W_H/W_L converges to infinity in the long run.

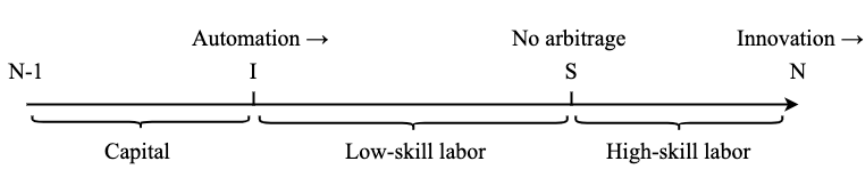


Figure 2: Task Allocation

once the patent is developed; so all the automated tasks are produced using machine. For the tasks that have not been automated, skilled workers have more advantage in the high index tasks, so skilled workers take the newest tasks, and the unskilled workers take the less updated tasks.

Proposition 2. (Equilibrium in Static Model)

After solving the firm's optimization problem and applying market clearing condition, the aggregate production function can be written as a constant elasticity of substitution (CES) production function, where the productivity of each production factor is determined endogenously by allocation:

$$Y = \frac{A}{1-\eta} \left((\Gamma_K K)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} + (\Gamma_L L_L)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} + (\Gamma_H L_H)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} \right)^{\frac{\hat{\sigma}}{\hat{\sigma}-1}}. \quad (4)$$

The equilibrium price and factor share can be solved as in a standard CES production function:

$$\begin{aligned} R &= A\Gamma_K \left(\frac{(1-\eta)Y}{A\Gamma_K K} \right)^{\frac{1}{\hat{\sigma}}}, & s_K &= \frac{RK}{Y}, \\ W_H &= A\Gamma_H \left(\frac{(1-\eta)Y}{A\Gamma_H L_H} \right)^{\frac{1}{\hat{\sigma}}}, & s_H &= \frac{W_H L_H}{Y}, \\ W_L &= A\Gamma_L \left(\frac{(1-\eta)Y}{A\Gamma_L L_L} \right)^{\frac{1}{\hat{\sigma}}}, & s_L &= \frac{W_L L_L}{Y}, \\ \omega &= \frac{W_H}{W_L} = \left(\frac{\Gamma_H}{\Gamma_L} \right)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} \left(\frac{L_L}{L_H} \right)^{\frac{1}{\hat{\sigma}}}, \end{aligned}$$

where Γ_K , Γ_L , and Γ_H represent the productivity of capital, low-skill and high-skill

labor and are determined endogenously by allocation:

$$\Gamma_K(\tilde{I}) = \tilde{I}^{\frac{1}{\hat{\sigma}-1}}, \quad (5)$$

$$\begin{aligned} \Gamma_H(N, \tilde{I}, \tilde{S}, h_H) &= \gamma_H(N, h_H) \left(\frac{1 - e^{-B(1-\tilde{S})(\hat{\sigma}-1)}}{B(\hat{\sigma}-1)} \right)^{\frac{1}{\hat{\sigma}-1}} \\ &= \underbrace{\gamma_H(N, h_H)}_{\text{Tech frontier}} \underbrace{\tilde{\Gamma}_H(\tilde{S})}_{\text{Allocation}}, \end{aligned} \quad (6)$$

$$\begin{aligned} \Gamma_L(N, \tilde{I}, \tilde{S}, h_L) &= \gamma_L(N, h_L) \left(\frac{e^{-B_L(1-\tilde{S})(\hat{\sigma}-1)} - e^{-B_L(1-\tilde{I})(\hat{\sigma}-1)}}{B_L(\hat{\sigma}-1)} \right)^{\frac{1}{\hat{\sigma}-1}} \\ &= \frac{\gamma_H(N, h_H)}{\gamma_{HL}} \tilde{\Gamma}_L(\tilde{I}, \tilde{S}). \end{aligned} \quad (7)$$

$\tilde{I} = I - (N - 1)$ represents the automation level, and $\tilde{S} = S - (N - 1)$ represents the labor allocation. $\gamma_{HL} = e^{(B-B_L)+bh_{HL}}$ represents the absolute advantage of skilled labor over unskilled labor on the frontier task N , $h_{HL} = h_H - h_L$ represents the human capital gap between skilled and unskilled workers.

Figure 3 presents the change in task allocation after an increase in automation level. As shown in Equation (5), capital productivity Γ_K is a function of automation. When more tasks are automated, task producers use the machine to replace labor, Γ_K increases, but Γ_L and Γ_H decrease. An increase in automation level increases the demand for capital but reduces the demand for both types of labor. As a result, the capital share increases, and the labor share decreases. Innovation does the opposite; it introduces new labor tasks, destroys old machine tasks, and increases labor productivity.

As shown in Equation (6) and (7), labor productivity Γ_H and Γ_L depend on the allocation and human capital level. Human capital accumulation increases Γ_L and Γ_H , which raises the wage level and labor share. Γ_H and Γ_L can be decomposed into two parts. The first part, $\gamma_H(N, h_H)$ or $\gamma_L(N, h_L)$, represents the technology frontier, the highest task productivity of each skill group. The second part, $\tilde{\Gamma}_H$ or $\tilde{\Gamma}_L$, captures the allocation. i.e., the measure of tasks produced by each type of worker. The ratio between Γ_H and Γ_L is increasing in the comparative advantage of skilled workers $B - B_L$ and the human capital gap h_{HL} . More tasks are produced by skilled workers when skilled workers have a higher comparative advantage and a larger human capital gap than unskilled workers. The skill wage premium increases when more tasks are assigned to skilled workers.

Proposition 3. (Comparative Statistics)

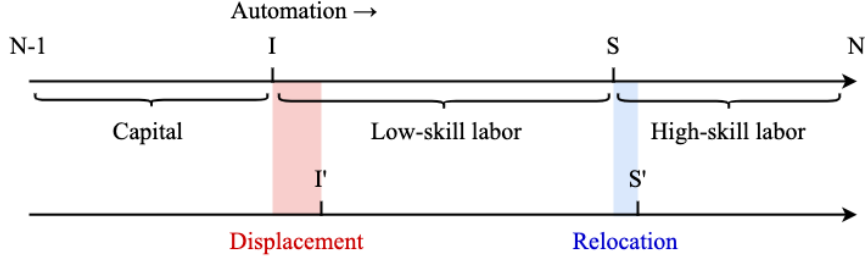


Figure 3: Change in Task Allocation

The change in labor share is given by the following equation:

$$\begin{aligned}
 d \ln(s_L + s_H) = & \frac{\hat{\sigma} - 1}{\hat{\sigma}} \frac{s_K}{1 - \eta} \underbrace{\left(\frac{s_L}{s_L + s_H} \frac{d \ln \tilde{\Gamma}_L}{d \tilde{I}} - \frac{d \ln H}{d \tilde{I}} \right) d \tilde{I}}_{\text{Automation}} \\
 & - \frac{\hat{\sigma} - 1}{\hat{\sigma}} \frac{s_K}{1 - \eta} \underbrace{(d \ln K - B d N - b d h - d \ln L)}_{\text{Capital deepening}},
 \end{aligned} \tag{8}$$

where the average change of human capital and labor supply is defined as:

$$\begin{aligned}
 d \ln h &= \frac{s_H}{s_H + s_L} d \ln h_H + \frac{s_L}{s_H + s_L} d \ln h_L, \\
 d \ln L &= \frac{s_H}{s_H + s_L} d \ln L_L + \frac{s_L}{s_H + s_L} d \ln L_L.
 \end{aligned}$$

The change of allocation \tilde{S} and wage can be written as:

$$\underbrace{d \tilde{S}}_{\text{Allocation}} = \frac{1}{\epsilon(\tilde{S})} \left(\underbrace{\frac{1}{\hat{\sigma}} (d \ln L_L - d \ln L_H - b d h_{HL})}_{\text{Labor supply}} - \underbrace{\frac{\hat{\sigma} - 1}{\hat{\sigma}} \frac{d \ln \tilde{\Gamma}_L}{d \tilde{I}} d \tilde{I}}_{\text{Automaton}} \right), \tag{9}$$

$$d \ln W_L = \underbrace{d \ln Y}_{\text{Productivity}} + \underbrace{\frac{\hat{\sigma} - 1}{\hat{\sigma}} \frac{d \ln \tilde{\Gamma}_L}{d \tilde{I}} d \tilde{I}}_{\text{Displacement}} + \underbrace{\frac{\hat{\sigma} - 1}{\hat{\sigma}} \frac{d \ln \tilde{\Gamma}_L}{d \tilde{S}} d \tilde{S}}_{\text{Relocate}}, \tag{10}$$

$$d \ln W_H = \underbrace{d \ln Y}_{\text{Productivity}} + \underbrace{\frac{\hat{\sigma} - 1}{\hat{\sigma}} \frac{d \ln \tilde{\Gamma}_H}{d \tilde{S}} d \tilde{S}}_{\text{Relocate}}, \tag{11}$$

$$d \ln \omega = (B - B_L) d \tilde{S} + b d h_{HL}, \tag{12}$$

where $\epsilon(\tilde{S})$ is the inverse of allocation elasticity taking the form:

$$\epsilon(\tilde{S}) = \underbrace{\frac{\hat{\sigma} - 1}{\hat{\sigma}} \left(\frac{d \ln \tilde{\Gamma}_L}{d \tilde{S}} - \frac{d \ln \tilde{\Gamma}_H}{d \tilde{S}} \right)}_{\text{Wage elasticity}} + \underbrace{(B - B_L)}_{\text{Comparative advantage}}. \quad (13)$$

As shown in Equation (9), right after an increase in automation, the wage of unskilled workers decreases through the displacement effect shown in Equation (10). At the original cutoff point S , the unit cost of using unskilled workers is lower than using skilled workers. The unskilled workers then relocate and take on some tasks that used to be performed by skilled workers until the no arbitrage condition is satisfied again. The shift of allocation S depends on the allocation elasticity derived in Equation (13). The labor allocation change is decreasing in the wage elasticity and comparative advantage of skilled workers. When the wage is elastic to the allocation, the no arbitrage condition can be satisfied with a small allocation change. With a high comparative advantage of skilled workers, the allocation is sticky since it's difficult to use unskilled workers to substitute the skilled workers.

Equation (8) shows how the labor share responds to the change in automation and human capital. An increase in automation decreases the labor share since it replaces unskilled workers directly. Human capital accumulation increases the labor share by increasing the effective labor supply.

The responses of wage levels are calculated in Equation (10) and (11). Since automation improves the allocation, it increases the wage for all the workers through the productivity effect. However, it decreases the wage of unskilled workers directly through the displacement effect and the wage of skilled workers through relocation effect.

After an increase in automation, the wage premium, as shown in Equation (12), always increases. Automation pushes unskilled workers to tasks where they have a disadvantage compared to skilled workers. The change in wage premium is increasing in the comparative advantage and decreasing in the wage elasticity. When the comparative advantage is higher, the unskilled workers absorb more impact from automation since relocation is difficult. Unskilled workers have to accept a much lower wage to compete with skilled workers because their productivity is much lower at those tasks. When the wage elasticity is higher, the unskilled workers can pass more effects of automation to skilled workers since they can benefit more from the relocation.

Automation and human capital are two opposing forces which together determine the labor share. An increase in automation decreases the labor share, while an increase in human capital does the opposite. Although unskilled workers can relocate after an increase in automation, an increase in automation always increases the wage premium. The wage premium rises more when the comparative advantage of skilled workers is high and the wage is inelastic to the allocation. The total

change of the wage premium after an increase in automation also depends on the human capital responses. If the human capital gap is enlarged after an increase in automation, the effect of automation on inequality will be amplified. In the next section, I move this static setting into a dynamic environment to understand the full effect of automation.

3 Dynamics and Balanced Growth Path

In this section, I extend the static framework above into a dynamic environment. First, capital accumulation is endogenous. Capital accumulation responds to the change in technology and human capital growth. Second, human capital growth is endogenous, depending on the time spent on training. Third, the R&D is endogenous and directed. The automation level and technology growth rate result from R&D investment.

3.1 Balanced Growth Path

Household

Given the interest rate $r(t)$, wage $W_H(h_H, t)$ and $W_L(h_L, t)$, technology growth rate $g_N(t)$ and $g_I(t)$, and human capital growth rate $g_{hH}(t)$ and $g_{hL}(t)$, households maximize their lifetime utility. By solving the households' problem, I can solve the intertemporal Euler equation, which characterizes the consumption-saving decision:

$$\frac{\dot{C}_H}{C_H} = \frac{\dot{C}_L}{C_L} = \frac{r - \rho}{\theta}.$$

The intratemporal Euler equation characterizes the optimal training decision for unskilled and skilled workers $j \in \{L, H\}$:

$$\underbrace{\frac{\delta \log W_j(h_j) l_j}{\delta h_j} \frac{\delta \dot{h}_j}{\delta(1-l_j)}}_{\text{Direct wage gain}} + \underbrace{\frac{\delta \log W_j(h_j)}{\delta h_j} \dot{h}_j + \frac{\delta \log W_j(h_j)}{\delta t}}_{\text{Return to human capital}} = r(1 + \tau_{hj}).$$

Physical and human capital are two ways for workers to save for the future. The training incentive is decreasing in interest rate r since a high interest rate increases the opportunity cost of training. The training incentive is increasing in return to human capital. Higher wage growth makes the household more willing to put effort into training.

By plugging in the production function, the marginal return rate of training is constant b , since the human capital is general and the growth rate of wage is linear in the human capital increase:

$$\frac{d \log W_H(h_H, t)}{dh_H} = \frac{d \log W_L(h_L, t)}{dh_L} = b.$$

Equations (14) and (15) characterize the wage growth rates of skilled and unskilled workers. They depend mainly on technology and human capital growth rate. The growth rate of physical capital and labor supply also has an impact on the wage growth rate:

$$\frac{dW_H(h_H, t)}{dt} = g_{WN} + g_{WI} + \frac{s_L}{s_H + s_L} g_{WS}, \quad (14)$$

$$\frac{dW_L(h_L, t)}{dt} = g_{WN} + g_{WI} - \frac{s_H}{s_H + s_L} g_{WS}. \quad (15)$$

I decompose the wage growth into three components. g_{WN} and g_{WI} are common effects of innovation and automation on wage growth for both skilled and unskilled workers. The difference between the skilled and unskilled workers' wage growth is contributed mainly by the shift of allocation g_{WS} :

$$g_{WN} = \underbrace{Bg_N}_{\text{Productivity}} + \underbrace{a(\tilde{I})(g_K - g_L - Bg_N - bg_h)}_{\text{Capital deepening}}, \quad (16)$$

$$g_{WI} = \underbrace{a(\tilde{I}) \frac{d \ln H}{d \tilde{I}} (g_I - g_N)}_{\text{Productivity}} + \underbrace{\frac{s_L}{s_H + s_L} (1 - a(\tilde{I})) \frac{d \ln \tilde{\Gamma}_L}{d \tilde{I}} (g_I - g_N)}_{\text{Displacement}}, \quad (17)$$

$$g_{WS} = \frac{B - B_L}{\epsilon(\tilde{S})} \underbrace{\left(\frac{1}{\hat{\sigma}} (g_{LL} - g_{LH} + b(g_{hL} - g_{hH})) \right)}_{\text{Labor supply}} - \underbrace{\frac{\hat{\sigma} - 1}{\hat{\sigma}} \frac{d \ln \tilde{\Gamma}_L}{d \tilde{I}} (g_I - g_N)}_{\text{Relocation}}, \quad (18)$$

where $a(\tilde{I})$ is defined as the importance of capital:

$$a(\tilde{I}) = \frac{1}{\hat{\sigma}} \frac{s_K}{1 - \eta},$$

g_{LH} and g_{LL} are growth rate of labor supply, and g_K is growth rate of capital supply:

$$g_h = \frac{s_H}{s_H + s_L} g_{hH} + \frac{s_L}{s_H + s_L} g_{hL},$$

$$g_L = \frac{s_H}{s_H + s_L} g_{LH} + \frac{s_L}{s_H + s_L} g_{LL}.$$

g_{WN} (Equation 16) is composed of two standard growth components: increase of technology frontier and capital accumulation. An increase in innovation always increases the wage for all the workers since it pushes the technology frontier and increases their productivity. g_{WI} (Equation 17) is the common effect of automation on all the skill groups. Automation improves allocation and increases productivity but decreases wage growth through the displacement effect. g_{WS} (Equation 18) captures the uneven wage growth as a result of the change in allocation. Automation decreases unskilled workers' wages more than skilled workers. The human capital investment of different skill groups is complementary. Skilled workers have more incentive to invest in human capital if unskilled workers increase their time spent on training and vice versa.

R&D Sector

After developing new tasks, the R&D sector produces task-specific intermediates and sells them to task producers. The production function of task producers is assumed to be Cobb-Douglas, the patent profit is a constant share η of the output:

$$\begin{aligned} \text{Automation: } \pi_I(t) &= \eta y(i) = \eta \left(\frac{R(t)}{A} \right)^{1-\hat{\sigma}} Y(t), \\ \text{Innovation: } \pi_N(i, t) &= \eta y(i) = \begin{cases} \eta \left(\frac{W_H(t)}{A \gamma_H(i, h_H(t))} \right)^{1-\hat{\sigma}} Y(t), & i > S(t) \\ \eta \left(\frac{W_L(t)}{A \gamma_L(i, h_L(t))} \right)^{1-\hat{\sigma}} Y(t), & i \leq S(t). \end{cases} \end{aligned}$$

Similar to the task output, the patent profit is decreasing in the factor price but increasing in the task productivity. The increase in automation increases capital demand and decreases labor demand. With a higher capital price and lower wage level, the automation patent value rises, and the innovation patent value falls. The development of innovation patents does the opposite.

When $\hat{\sigma} > 1$, accumulating human capital increases task productivity more than the wage level, increasing the output and patent profit. Higher innovation patent value increases the incentive of the R&D sector to innovate new tasks. The human capital and innovation R&D investment are complementary.

The patent value can be derived as the net gain of the new patent. When new task producers enter the market, they need to compensate the incumbent firms, who are forced to exit the market. Government imposes taxes on patent profit, τ_I for automation patents, and τ_N for innovation patents. The value of automation patent P_I and innovation patent P_N are derived in the following equations:

$$\begin{aligned} P_N(t) &= (1 - \tau_N) V_N(N(t), t) - (1 - \tau_I) V_I(t), \\ P_I(t) &= (1 - \tau_I) V_I(t) - (1 - \tau_N) V_N(I(t), t). \end{aligned}$$

The value of innovation patent P_N (automation patent P_I) is the total future profit generated by the innovation patent of task $N(t)$ (the automation patent of task $I(t)$), subtracted by the compensation paid to the incumbent automation patent holder of task $N(t) - 1$ (innovation patent holder of task $I(t)$). $V_I(t)$ and $V_N(i, t)$ are the discounted value of future profit by holding an automation patent and an innovation patent for task i at time t if the tasks are never destroyed:

$$V_N(i, t) = \int_t^\infty e^{-\int_t^\tau r(s)ds} \pi_N(i, \tau) d\tau,$$

$$V_I(t) = \int_t^\infty e^{-\int_t^\tau r(s)ds} \pi_I(\tau) d\tau.$$

Automated tasks are always produced by capital, and unskilled workers always produce the most outdated innovation task. The profitability of automation patents stays constant since the task productivity of machine is constant and normalized to 1. The profitability of innovation patents is decreasing over time because the comparative productivity of the task is decreasing as it's further to the technology frontier. It's straightforward to solve the expected profit of automation patent V_I and the most outdated innovation patent $V_N(I(t), t)$ using the following equations:

$$V_I(t) = \eta \int_t^\infty e^{-\int_t^\tau r(s)ds} \left(\frac{R}{A}\right)^{1-\hat{\sigma}} Y(\tau) d\tau,$$

$$V_N(I(t), t) = \eta \int_t^\infty e^{-\int_t^\tau r(s)ds} \left(\frac{W_L(\tau)}{A\gamma(I(t), h_L(\tau))}\right)^{1-\hat{\sigma}} Y(\tau) d\tau$$

$$= \eta e^{(\hat{\sigma}-1)B_L \tilde{I}(t)} \int_t^\infty e^{-\int_t^\tau (r(s) + (\hat{\sigma}-1)B_L g_N(s))ds} \left(\frac{W_L(\tau)}{A\gamma(N(\tau), h_L(\tau))}\right)^{1-\hat{\sigma}} Y(\tau) d\tau.$$

The newest tasks introduced by innovation patent $V_N(N(t), t)$ are produced firstly by skilled workers, then by unskilled workers when it becomes more outdated. To solve the value of the newest innovation patent, I define the value of the newest patent $N(t)$ at time t be $V_{NH}(t)$ if skilled workers produce the task and $V_{NL}(t)$ if unskilled workers produce it. The values of $V_{NH}(t)$ and $V_{NL}(t)$ are derived as:

$$V_{NH}(t) = \eta \int_t^\infty e^{-\int_t^\tau r(s)ds} \left(\frac{W_H(\tau)}{A\gamma(N(t), h_H(\tau))}\right)^{1-\hat{\sigma}} Y(\tau) d\tau$$

$$= \eta \int_t^\infty e^{-\int_t^\tau (r(s) + (\hat{\sigma}-1)B g_N(s))ds} \left(\frac{W_H(\tau)}{A\gamma(N(\tau), h_H(\tau))}\right)^{1-\hat{\sigma}} Y(\tau) d\tau,$$

$$V_{NL}(t) = \eta \int_t^\infty e^{-\int_t^\tau r(s)ds} \left(\frac{W_L(\tau)}{A\gamma(N(t), h_L(\tau))}\right)^{1-\hat{\sigma}} Y(\tau) d\tau$$

$$= \eta \int_t^\infty e^{-\int_t^\tau (r(s) + (\hat{\sigma}-1)B_L g_N(s))ds} \left(\frac{W_L(\tau)}{A\gamma(N(\tau), h_L(\tau))}\right)^{1-\hat{\sigma}} Y(\tau) d\tau.$$

I define $\tilde{\tau}(t)$ as the stopping time when the task $N(t)$ is switched from skilled workers to unskilled worker, i.e., $S(\tilde{\tau}(t)) = N(t)$. The expected profit of innovation patent can be solved explicitly:

$$V_N(N(t), t) = V_{NH}(t) - e^{-\int_t^{\tilde{\tau}(t)} (r(s) + (\hat{\sigma} - 1)B_{gN})ds} V_{NH}(\tilde{\tau}(t)) \\ + e^{-\int_t^{\tilde{\tau}(t)} (r(s) + (\hat{\sigma} - 1)B_{LgN})ds} V_{NL}(\tilde{\tau}(t)).$$

The no arbitrage condition needs to be satisfied between the production and R&D sectors. The wage payment of working in the production sector must equal the payoff of working as a scientist. The number of scientists working in automation and innovation sector must satisfy:

$$\frac{\lambda \epsilon_I(t)^{\lambda-1}}{\mu_I} P_I(t) = \frac{\lambda \epsilon_N(t)^{\lambda-1}}{\mu_N} P_N(t) = W_H(t). \quad (19)$$

Market Clearing and Consistency

The human capital and technology growth rates chosen by the households and R&D sector need to be consistent with the given aggregate growth rate:

$$g_{hH} = \frac{(1 - l_H)^{\alpha_H}}{\mu_{hH}}, \quad g_{hL} = \frac{(1 - l_L)^{\alpha_L}}{\mu_{hL}}, \quad g_N = \frac{\epsilon_N^\lambda}{\mu_N}, \quad g_I = \frac{\epsilon_I^\lambda}{\mu_I}.$$

The capital and labor markets need to be clear. The total capital demand must equal the capital supplied by skilled and unskilled workers. The low-skill labor demand needs to equal the total working time of unskilled workers. The skilled workers divide their working time into high-skill labor supply and research labor in automation and innovation sector. The market clearing conditions are listed in the following equations:

$$\int_{N-1}^N k(i)di = K = \epsilon_H K_H + \epsilon_L K_L, \\ \int_{N-1}^N l(i)di = L_L = \epsilon_L l_L, \\ \int_{N-1}^N h(i)di = L_H = \epsilon_H l_H - \epsilon_N - \epsilon_I.$$

Balanced Growth Path

After solving the dynamic problem of the households and R&D sector, I can characterize the Balanced Growth Path (BGP). Define normalized variables x as the

original variables X normalized by economic growth $e^{-\int_0^t g(\tau) d\tau}$ or technology frontier $\gamma_H(N, h_H)$. The economy's growth rate is defined as the total growth of technology and human capital $g = Bg_N + bg_{hH}$. A balanced growth path (BGP) is defined as a transition path on which the automation level and the labor allocation $\{\tilde{I}, \tilde{S}\}$, the factor shares $\{s_K, s_L, s_H\}$, the rental rate of capital $\{r\}$, the labor supply $\{L_H, L_L\}$ and the growth rates $\{g_N, g_I, g_{hH}, g_{hL}\}$ are constant over time. The normalized factor productivity $\{\tilde{\Gamma}_H, \tilde{\Gamma}_L, \gamma_{HL}\}$, capital, output and consumption $\{k, y, c_H, c_L\}$, labor wages $\{\omega_H, \omega_L\}$, expected patent profit $\{v_N, v_I, v_{NH}, v_{NL}\}$ and patent value $\{p_N, p_I\}$ are also constant on BGP.

The Euler equation with normalized variables can be written as:

$$\frac{\dot{c}_H}{c_H} = \frac{\dot{c}_L}{c_L} = \frac{r - \rho}{\theta} - g = 0.$$

On the balanced growth path, the normalized consumption is constant, so the long run interest rate needs to satisfy:

$$r = \rho + \theta g = \rho + \theta(Bg_N + bg_{hH}). \quad (20)$$

With constant growth rate, interest rate and wages, the value of automation and innovation patents are constant and can be written as:

$$p_N = (1 - \tau_N)v_N(N) - (1 - \tau_I)v_I, \quad (21)$$

$$p_I = (1 - \tau_I)v_I - (1 - \tau_N)v_N(I), \quad (22)$$

where $\tilde{t} - t = \frac{1 - \tilde{S}}{g_N}$, and $v_N(N)$, $v_N(I)$ and v_I can be solved explicitly:

$$v_N(N) = v_{NH} + e^{-(r-g+(\hat{\sigma}-1)B_L g_N)(\tilde{t}-t)} v_{NL} - e^{-(r-g+(\hat{\sigma}-1)B g_N)(\tilde{t}-t)} v_{NH}, \quad (23)$$

$$v_N(I) = e^{-(\hat{\sigma}-1)B_L(1-\tilde{I})} v_{NL}, \quad (24)$$

$$v_I = \eta \frac{1}{r-g} \left(\frac{R}{A}\right)^{1-\hat{\sigma}} y. \quad (25)$$

v_{NH} and v_{NL} are also constant on the BGP, and can be written as:

$$v_{NH} = \eta \frac{1}{r-g+(\hat{\sigma}-1)B g_N} \left(\frac{\omega_H}{A}\right)^{1-\hat{\sigma}} y, \quad (26)$$

$$v_{NL} = \eta \frac{1}{r-g+(\hat{\sigma}-1)B_L g_N} \left(\frac{\gamma_{HL}\omega_L}{A}\right)^{1-\hat{\sigma}} y. \quad (27)$$

The value of patents depends mainly on the automation level. Suppose the long-run interest rate is not too low. In that case, I can see from Equation (25), (26),

and (27) that an increase in automation decreases the wage level, decreases the patent value of automation, and increases the patent value of innovation.⁸ Also, with a higher automation level, as shown by equation (24), unskilled workers are performing the tasks they have more comparative advantages over the machine, lowering further the value of the automation patent. Higher technology growth rate g_N has an ambiguous effect on the patent value. It decreases the profit of automation patents by driving up the long-run interest rate (Equation 20). At the same time, it decreases the profit of innovation patents by accelerating its depreciation. A higher human capital growth rate always decreases the profit of automation patents by increasing the interest rate.

The automation level is constant on the BGP, and needs to converge to the level where the innovation and automation grow at the same rate:

$$g_N = g_I. \quad (28)$$

By plugging in the R&D sector production function (Equation 1 and 2) and no arbitrage condition between production and research sector (Equation 19 and 28), the value of automation and innovation patent needs to satisfy:

$$\frac{p_N}{p_I} = \left(\frac{\mu_N}{\mu_I} \right)^{\frac{1}{\lambda}}. \quad (29)$$

Proposition 4. (Human Capital Growth and Automation Level)

The automation level on the BGP is decreasing in the human capital growth rate. There exists a human capital growth rate g_{hH}^ , such that the economy will never be fully automated if the human capital growth rate $g_{hH} > g_{hH}^*$.*

Proof. See Appendix B.

Human capital complements innovation patents but substitutes automation patents. A higher human capital growth rate slows the capital deepening and drives up the long-run capital rental rate (Equation 20). With a higher interest rate, the automaton level is lowered to satisfy the equilibrium condition (Equation 29).

In the long run, $g_N = g_I$, the allocation between working and training for unskilled and skilled workers $j \in \{L, H\}$ needs to satisfy:

$$\frac{b}{\mu_{hj}}(1 - (1 - \alpha_j)l_j)(1 - l_j)^{\alpha_j - 1} + Bg_N = r(1 + \tau_{hj})$$

The time spent on training is decreasing in the interest rate and increasing in the technology growth rate. The interaction between human capital and technology

⁸See Acemoglu and Restrepo (2018) for more details.

rate is shown in equation (Equation 30) by plugging in the long-run interest rate (Equation 20):

$$(1 - \theta) \frac{b}{\mu_{hj}} (1 - l_j)^{\alpha_j} + \alpha \frac{b}{\mu_{hj}} l_j (1 - l_j)^{\alpha_j - 1} = \rho + (\theta - 1) B g_N. \quad (30)$$

Proposition 5. (Human Capital and Technology Growth Rate)

In the long run, if the intertemporal elasticity of substitution $\theta > 1$, the human capital and technology growth are substitutes; if $\theta < 1$, the human capital and technology growth are complements.

Proof. See Appendix B.

When the intertemporal elasticity of substitution θ is greater than 1, the capital stock response to the technology change is small. The long-run interest rate increases more than the economic growth rate, and the return to physical capital dominates the return to human capital. As a result, workers prefer saving through physical capital to human capital, working more and training less. On the contrary, when θ is smaller than 1, the benefit of human capital dominates, and the workers spend more time on training.

The human capital growth needs to converge to the same growth rate:

$$g_{hH} = g_{hL}. \quad (31)$$

Assumption 3. (Cost of Training)

In order to have balanced growth path exist, assume that the cost of training for skilled workers is increasing in the human capital gap between skilled and unskilled workers:

$$\frac{\mu_{hH}}{\mu_{hL}} = e^{\lambda_h(h_{HL} - h_{HL}^*)}. \quad (32)$$

This assumption is necessary to guarantee the existence of a balanced growth path. Without the assumption, equation (31) and (32) can't be satisfied simultaneously. To maintain a higher human capital gap, skilled workers face a higher cost of training. College costs have increased by 169% since 1980, while the college premium has increased only by 14%.⁹

3.2 Long-Run Comparative Statics

In this subsection, I discuss the long-run implications of technological revolution, modeled as a permanent decline in μ_I . The technological revolution increases the R&D sector efficiency; the automation tasks are now easier to develop. In this subsection, I focus on the case where human capital and technology growth are complementary, i.e., $\theta < 1$.

⁹Source: CNBC

Proposition 6. (Long-run Comparative Statics)

- *A reduction in automation cost increases the automation level \tilde{I} .*
- *A reduction in automation cost increases the technology growth rate g_N and human capital growth rate g_{hL} and g_{hH} . Human capital accumulation slows down the capital deepening and pushes back the automation level.*
- *A reduction in automation cost increases the human capital gap $h_H L$ and amplifies wage inequality. The change in human capital gap depends on the human capital accumulation parameters α_H and α_L and the elasticity of human capital investment cost to human capital gap λ_h :*

$$dh_{HL} = \frac{1}{\lambda_h} \frac{(\alpha_H - \alpha_L)l_L}{(1 - l_L)\alpha_H + l_L\alpha_L} d \log g_h$$

Proof. See Appendix B.

A reduction in automation cost immediately increases the automation level. Since automation patents are now easier to develop, the measure of automated tasks increases. A higher automation level improves the allocation and increases productivity. The value of innovation patents increases as the automation level increases. The innovation rate thus increases. A higher innovation rate increases future wage growth and incentivizes more human capital investment. Higher human capital growth complements innovation but substitutes automation. Human capital accumulation increases the effective labor supply and slows capital deepening, favoring innovation and decreasing the long-run automation level.

Although both skill groups respond to the technological revolution, their responses are uneven. Both skilled and unskilled workers benefit from the technological revolution's productivity effect, but unskilled workers are affected more by the displacement effect. As a result, human capital investment incentives are higher for skilled workers than unskilled workers. Also, skilled workers have a higher ability to adjust their human capital investment. Skilled workers invest more in human capital than unskilled workers until the human capital gap converges to a higher level.

To summarize the main result of this section, a reduction in automation cost increases the automation level and complements the innovation sector. Human capital accumulation complements innovation but substitutes automation. It lowers the automation level and increases the labor share. The increase in the human capital gap amplifies the effect of technological change on wage inequality.

4 Social Planner's Problem

In the next section, I solve the transition path computationally and implement counterfactual experiments. Before that, I first solve the social planner's problem (SPP) in this section to discuss the inefficiency of the decentralized economy (CE). The social planner's problem is subject to the same aggregate production function and laws of motion as in the decentralized economy. However, the social planner maximizes the total social welfare by allocating the final good between consumption and saving, allocating time between working and training, and allocating skilled workers between the production and R&D sectors.

4.1 Solution of SPP

The social planner maximizes social welfare by solving the following maximization problem:

$$\begin{aligned} & \rho V_{SPP}(K, N, I, h_H, h_L) \\ &= \max_{C_H, C_L, L_H, L_L, \epsilon_N, \epsilon_I} \{ \epsilon_H u(C_H) + \epsilon_L u(C_L) + V_K \dot{K} + V_N \dot{N} + V_I \dot{I} + V_{h_H} \dot{h}_H + V_{h_L} \dot{h}_L \}, \end{aligned}$$

subject to the resource constraint and laws of motion:

$$\begin{aligned} \dot{K} &= Y - \delta K - \epsilon_H C_H - \epsilon_L C_L, \\ \dot{N} &= \frac{1}{\mu_N} \epsilon_N^\lambda, \\ \dot{I} &= \frac{1}{\mu_I} \epsilon_I^\lambda, \\ \dot{h}_H &= \frac{1}{\mu_{h_H}} \left(1 - \frac{L_H + \epsilon_N + \epsilon_I}{\epsilon_H} \right)^{\alpha_H}, \\ \dot{h}_L &= \frac{1}{\mu_{h_L}} \left(1 - \frac{L_L}{\epsilon_L} \right)^{\alpha_L}, \\ Y &= \frac{A}{1 - \eta} \left((\Gamma_K K)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} + (\Gamma_L L_L)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} + (\Gamma_H L_H)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} \right)^{\frac{\hat{\sigma}}{\hat{\sigma}-1}}. \end{aligned}$$

Similar to the decentralized economy, the consumption-saving decision can be characterized by the intertemporal Euler equations:

$$\frac{\dot{C}_H}{C_H} = \frac{\dot{C}_L}{C_L} = \frac{Y_K - \delta - \rho}{\theta}.$$

The total return to human capital investment equals the net return to physical capital. The total return to human capital includes the direct return to human

capital and the growth of labor return. Thus, the human capital investment can be characterized by the intratemporal Euler equations:

$$\begin{aligned}
-\frac{\delta \dot{h}_H}{\delta L_H} \frac{Y_{h_H}}{Y_{L_H}} + \frac{\dot{Y}_{L_H}}{Y_{L_H}} &= \frac{L_H}{\epsilon_H} \frac{b \delta \dot{h}_H}{\delta(1-l_H)} + \frac{\dot{Y}_{L_H}}{Y_{L_H}} = Y_K - \delta, \\
-\frac{\delta \dot{h}_L}{\delta L_L} \frac{Y_{h_L}}{Y_{L_L}} + \frac{\dot{Y}_{L_L}}{Y_{L_L}} &= \underbrace{\frac{L_L}{\epsilon_L} \frac{b \delta \dot{h}_L}{\delta(1-l_L)}}_{\text{Human capital return}} + \underbrace{\frac{\dot{Y}_{L_L}}{Y_{L_L}}}_{\text{Growth}} = \underbrace{Y_K - \delta}_{\text{Physical capital return}}.
\end{aligned}$$

Optimal investments in the R&D sector need to satisfy the no arbitrage condition, i.e., the long-run productivity gain of R&D investment equals the return to high-skill labor in the production sector:

$$\frac{\frac{\delta \dot{I}}{\delta \epsilon_I} Y_I}{Y_K - \delta - \frac{\dot{Y}_{L_H}}{Y_{L_H}}} = \frac{\frac{\delta \dot{N}}{\delta \epsilon_N} Y_N}{Y_K - \delta - \frac{\dot{Y}_{L_H}}{Y_{L_H}}} = Y_{L_H}.$$

4.2 Externality

To compare the balanced growth paths of SPP and CE, I use the prices in CE to substitute the derivatives in SPP.

$$\begin{aligned}
Y_K &= \frac{R}{1-\eta}, \quad Y_{L_H} = \frac{W_H}{1-\eta}, \quad Y_{L_L} = \frac{W_L}{1-\eta}, \\
\frac{Y_N}{Y} &= \frac{s_L}{1-\eta} (B - B_L) + \frac{1}{\hat{\sigma}-1} \left(\frac{\omega_H}{A} \right)^{1-\hat{\sigma}} - \frac{1}{\hat{\sigma}-1} \left(\frac{R}{A} \right)^{1-\hat{\sigma}}, \\
\frac{Y_I}{Y} &= \frac{1}{\hat{\sigma}-1} \left(\frac{R}{A} \right)^{1-\hat{\sigma}} - \frac{1}{\hat{\sigma}-1} e^{B_L(1-\tilde{l})(1-\hat{\sigma})} \left(\frac{\omega_L h_{HL}}{A} \right)^{1-\hat{\sigma}}, \\
\frac{\dot{Y}_{L_H}}{Y_{L_H}} &= g_{WH} = g_{WN} + g_{WI} + \frac{s_L}{s_H + s_L} g_{WS} + b g_{hH}, \\
\frac{\dot{Y}_{L_L}}{Y_{L_L}} &= g_{WL} = g_{WN} + g_{WI} - \frac{s_H}{s_H + s_L} g_{WS} + b g_{hL}.
\end{aligned}$$

The return to capital (Y_K) and labor (Y_{L_H} and Y_{L_L}) in SPP is higher than that in CE since only a fraction η of the output in CE is paid to the patent holder. The total returns to automation (Y_N) and innovation (Y_I) in SPP are productivity gains by introducing additional automation and innovation patents to the economy. They are higher than the patent value in CE since patent holders in CE only get a fraction η of the return to the new patents. The wage growth rate in SPP is consistent with CE.

Euler equation	SPP	$\frac{\dot{C}_H}{C_H} = \frac{\dot{C}_L}{C_L} = \frac{\frac{R}{1-\eta} - \delta - \rho}{\theta}$
	CE	$\frac{\dot{C}_H}{C_H} = \frac{\dot{C}_L}{C_L} = \frac{r - \rho}{\theta}$
Innovation rate	SPP	$\frac{\lambda \epsilon_N^{\lambda-1}}{\mu_N} \frac{(1-\eta) P_N^{SPP}}{Y} = \frac{W_H}{Y}$
	CE	$\frac{\lambda \epsilon_N^{\lambda-1}}{\mu_N} \frac{P_N}{Y} = \frac{W_H}{Y}$
Automation rate	SPP	$\frac{\lambda \epsilon_I^{\lambda-1}}{\mu_I} \frac{(1-\eta) P_I^{SPP}}{Y} = \frac{W_H}{Y}$
	CE	$\frac{\lambda \epsilon_I^{\lambda-1}}{\mu_I} \frac{P_I}{Y} = \frac{W_H}{Y}$
Innovation patent	SPP	$\frac{P_N^{SPP}}{Y} = \frac{\frac{Y_N}{Y}}{\frac{R}{1-\eta} - \delta - g_{WH}}$
	CE	$\frac{P_N}{Y} = (1 - \tau_N) \frac{V_N(N)}{Y} - (1 - \tau_I) \frac{V_I}{Y}$
Automation patent	SPP	$\frac{P_I^{SPP}}{Y} = \frac{\frac{Y_I}{Y}}{\frac{R}{1-\eta} - \delta - g_{WH}}$
	CE	$\frac{P_I}{Y} = (1 - \tau_I) \frac{V_I}{Y} - (1 - \tau_N) \frac{V_N(I)}{Y}$
Skilled training	SPP	$\frac{L_H}{\epsilon_H} \frac{b \delta \dot{h}_H}{\delta(1-l_H)} + g_{WH} = \frac{R}{1-\eta} - \delta$
	CE	$l_H \frac{b \delta \dot{h}_H}{\delta(1-l_H)} + g_{WH} = r(1 + \tau_{hH})$
Unskilled training	SPP	$l_L \frac{b \delta \dot{h}_L}{\delta(1-l_L)} + g_{WL} = \frac{R}{1-\eta} - \delta$
	CE	$l_L \frac{b \delta \dot{h}_L}{\delta(1-l_L)} + g_{WL} = r(1 + \tau_{hL})$

Table 1: Comparison Between SPP and CE

Table 1 compares the equations characterizing the BGP of SPP and CE. First, the production externality of production and R&D sectors is common in endogenous growth literature. The production sector does not internalize the patent profit, and the R&D sector does not internalize the productivity gain of the production sector. The socially-planned economy always invests more capital and grows faster than the decentralized economy. I will focus on the second and third externalities in the following discussions.

Second, the skilled workers overinvest in human capital. When workers invest in human capital, they increase their productivity in the production sector. Comparing the skilled workers' human capital policy function of SPP and CE, I can find that skilled workers fail to internalize their negative effect on the R&D sector. Higher labor productivity increases the opportunity cost of research and development; fewer scientists work in the R&D sector. The number of scientists hired in the research sector is decreasing in the wage premium.

Third, the R&D sector automates too many tasks. The innovation patent value of SPP is higher than that of CE. When an innovation task is developed, the patent holder only benefits from the productivity gain of the single task. However, the new task complements other tasks and increases the return to all the production

factor providers and patent holders. At the same time, the new task pushes the technology frontier and increases the productivity of all the unskilled workers.

Based on the social planner’s problem, I will focus on an automation tax and a training tax on skilled workers in the counterfactual experiments of section 5. An automation tax decreases the value of automation patents and lowers the automation level; a training tax on skilled workers favors unskilled workers and reduces the human capital accumulation of skilled workers.

5 Calibration and Transition Path

I calibrate the model to match the moments in 1980 and 2005, and simulate the transition in between. Then I discuss the policy implications by conducting a variety of counterfactual experiments.

5.1 Calibration

I use the data from 1980 and 2005 to calibrate the model parameters and the size of the automation cost reduction z . Acemoglu and Autor (2011) document that the structural change in the labor market started in 1982. We can observe a decline in labor share accompanied by an increasing college wage premium. Thus, I consider 1980 as the starting point of the technological revolution. I cut the data at 2005 to exclude the effect of the Great Recession. Restrepo (2015) demonstrates an interaction between the Great Recession and the labor market structural change. All the parameters are assumed to be the same in 1980 and 2005 except for the automation cost. After the technology shock, the cost of automation decreases to $z\mu_I$; the economy gradually converges to a new balanced growth path.

Parameter	Description	Value	Reference
θ	Intertemporal elasticity of substitution	0.9	Beaudry and Van Wincoop (1996)
σ	Factor elasticity of substitution	2	
δ	Depreciation rate	0.1	BEA Depreciation Estimates
B_L	Comparative advantage of unskilled workers	1	
b	Return to human capital	1	
ϵ_H	high-skill workers share	0.3	FRED
ϵ_L	Low skill workers share	0.7	FRED
λ	R&D production function	0.5	Prettner and Strulik (2020)

Table 2: External Calibration

The parameters in Table 2 are calibrated externally. Intertemporal elasticity of substitution takes the value of 0.9.¹⁰ Factor elasticity of substitution is set to

¹⁰Beaudry and Van Wincoop (1996) provide evidence that IES is significantly different from zero and close to one.

be 2. I set the rate of depreciation of traditional capital to $\delta = 0.1$ based on the depreciation rates suggested by the Bureau of Economic Analysis. The comparative advantage of unskilled workers and return to human capital are normalized to 1. ϵ_H and ϵ_L are set to match the share of workers with a college degree or higher and workers with a high school diploma or lower.¹¹ λ in the R&D sector production function follows the calibration from Prettnner and Strulik (2020).

Parameter	Description	Value	Targeted moment	Value
ρ	Discount rate	0.0121	Long run interest rate	4.0%
η	Patent share	0.1125	RD and GDP ratio	2.8%
A	Capital productivity	0.1190	Short run interest rate	4.0%
B_H	Skill comparative advantage	2.2651	Wage premium (1980)	1.4
μ_N	Cost of innovation	2.3619	RD growth rate	2.8%
μ_I	Cost of automation	9.0135	Labor share (1980)	0.625
μ_h	Cost of h_L accumulation	193.5608	Human capital growth rate	0.3%
α_H	h_H accumulation function	0.9026	Change of training time (H)	0.141
α_L	h_L accumulation function	0.2797	Change of training time (L)	0.160
λ	RD Decreasing return	0.7675	Wage premium (2005)	1.6
z	Technological revolution	0.7853	Labor share (2005)	0.605

Table 3: Internal Calibration

Notes: Data are from FRED and ATES. All the macroeconomic moments are from FRED. The changes in training time are computed using ATES. The details on how I choose the moments are presented in Appendix C.

The remaining parameters in Table 3 are calibrated using the Simulated Method of Moments (SMM), which aims at finding a value θ^* maximizing the likelihood function. $\hat{m}_S(\theta)$ is the moment simulated by the model given θ as the parameter of the model; \hat{m}_M is the moment observed in the data.

$$L(\theta) = -(\hat{m}_S(\theta) - \hat{m}_M)^T(\hat{m}_S(\theta) - \hat{m}_M)$$

The share of profit paid to the patent holder η is set to match the R&D investment and GDP ratio. The return to capital is, on average, 4% in the data, which pins down the capital productivity A . The comparative advantage of skilled workers B_H is calibrated to match the skill premium in 1980. The cost of innovation μ_N is set to match the long-run growth rate. The labor share is decreasing in the automation level, and the cost of automation determines the automation level. Thus, the cost of automation μ_I is set to match the labor share in 1980. Human capital investment cost μ_h is closely related to the human capital growth rate. The parameters in the human capital accumulation function α_H and α_L are picked to match the training time change for college and high school graduates. The size of technology shock z is closely related to the change in labor share; after a reduction in automation cost, more tasks are automated, and labor share decreases. The details on how I choose the moments are presented in Appendix C.

¹¹Data source: FRED

Moment	1980	2005	
		Fixed human capital	Endogenous human capital
Automation level	0.6818	0.7796	0.7623
Labor share	0.6174	0.5906	0.5939
Skilled labor share	0.2814	0.2758	0.2840
Unskilled labor share	0.3360	0.3148	0.3099
Wage premium	1.4012	1.4454	1.5897
Technology growth rate	4.2036%	5.5177%	5.2122%
Human capital growth rate	0.2612%	0.2612%	0.2743%
Welfare inequality	1.0087	1.0902	1.1859

Table 4: Calibration Result

Notes: The first column presents the key moments before the technological revolution. The second and third columns present the key moments after the technological revolution with fixed or endogenous human capital.

The calibration result is presented in Table 4. A reduction in automation costs increases automation, lowers labor share, and raises wage inequality. R&D investment is directed more to automation since the automation department is more efficient. As more tasks are automated, labor share decreases, and wage inequality increases. However, the higher automation level increases the allocation efficiency, which increases the profit of innovation patents and the innovation rate. A 20% reduction of the automation cost increases the technology growth rate by about 1%.

I compare the two scenarios with and without human capital. A higher innovation rate increases wage growth and complements human capital investment. Workers accumulate human capital at a higher rate, increasing the effective labor supply, pushing back automation, and increasing the labor share. Human capital accumulation increases the labor share by about 0.33% (0.82% from skilled labor share and -0.48% from unskilled labor share). Skilled and unskilled workers respond differently to the reduction in automation costs, which increases the human capital gap. Only 23.4% of the wage premium increase is contributed directly by automation, and the increase in the human capital gap causes 76.6% of the increase.

The technology growth rate is lower in the scenario with endogenous human capital due to the higher opportunity cost of research. The skilled workers are more productive in the production sector, and fewer skilled workers become scientists and work in the R&D sector.

5.2 Transition Path

The transition path between two balanced growth path before and after political or technological shock is consist of state variables capital stock $\{k(t)\}$, automation level $\{\tilde{I}(t)\}$, absolute advantage $\{\gamma_{HL}(t)\}$; growth rates of the economy

$\{g_N(t), g_I(t), g_{hH}(t), g_{hL}(t)\}$; price functions $\{r(t), \omega_H(t), \omega_L(t)\}$; policy functions $\{f_{Hk}(t), f_{Lk}(t), f_{Hc}(t), f_{Lc}(t)\}$ and $\{f_{Hl}(t), f_{Ll}(t)\}$ for households; $\{f_K(t), f_H(t), f_L(t)\}$ for firms; $\{f_{\epsilon_N}(t), f_{\epsilon_I}(t)\}$ for R&D sector, and allocation $\{\tilde{S}(t)\}$, such that:

1. Given the state variables, growth rates and price functions, household policy functions $\{f_{Hk}(t), f_{Lk}(t), f_{Hc}(t), f_{Lc}(t)\}$ and $\{f_{Hl}(t), f_{Ll}(t)\}$ solve household's problem
2. Given the state variables, growth rates and price functions, firm policy functions $\{f_K(t), f_{LH}(t), f_{LL}(t)\}$ solve firm's problem
3. Given the state variables, growth rates and price functions, R&D sector policy functions $\{f_{\epsilon_N}(t), f_{\epsilon_I}(t)\}$ solve R&D sector's problem
4. Consistency and market clearing conditions are satisfied.

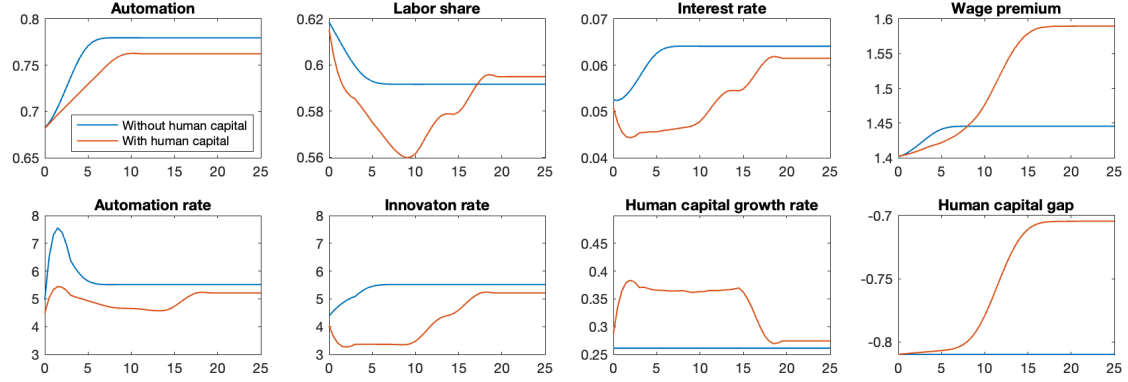


Figure 4: Transition Path

Notes: The figure shows the simulation of the transition path after a reduction in automation cost with the calibrated model. Red lines show the transition with fixed human capital investment; blue lines show the transition with endogenous human capital investment. The detailed algorithm is provided in Appendix D. Oscillations are caused by computational errors.

Figure 4 plots the simulation result of the transition path with the calibrated model. The detailed algorithm is provided in Appendix D. The simulation with fixed human capital investment (scenario 1) is plotted with blue lines, and the simulation with endogenous human capital (scenario 2) is plotted with red lines. A reduction in automation cost immediately increases the automation rate. However, the technological change increases capital demand but decreases the demand for skilled and unskilled workers. As a result, the capital rental rate increases, and wages decrease. These price changes increase the innovation patent value and decrease the automation patent value. The innovation rate starts to rise, and

automation slows down; both rates converge to a higher level than the initial rates.

In scenario 2 with endogenous human capital, the labor share initially drops more than in scenario 1 with fixed human capital investment due to higher human capital investment and lower labor supply. It takes more time for the innovation rate to catch up in scenario 2 with endogenous human capital since workers spend more time on training and supply less labor right after the technological revolution. Once the workers accumulate enough human capital, the innovation rate starts to catch up, and the labor share increases and reaches a level higher than in scenario 1. Skilled workers accumulate their human capital faster than unskilled workers, the human capital gap keeps increasing, and the wage premium grows faster than in scenario 1.

Endogenous human capital decreases the long-run automation level and increases the long-run labor share. However, it amplifies the effects of the technological revolution on the labor market outcomes. The labor share drops more in the short-run, and the wage premium increases more in both the short- and long-run.

5.3 Policy Implications

In section 4, I solve the social planner's problem and discuss the externalities of the decentralized economy. In the decentralized economy, the R&D sector automates too many tasks, and skilled workers invest too much in human capital. Two taxes are appropriate to correct the externalities and increase the overall social welfare: an automation tax (τ_I) and a training tax on skilled workers (τ_{hH}). An automation tax decreases the value of automation patents and lowers the automation level; a training tax on skilled workers favors unskilled workers and decreases the human capital accumulation of skilled workers.

I address the quantitative implications with the calibrated model and consider a redistributive policy. I consider the case in which all the workers receive equal transfers, which are financed by either an automation tax or a training tax on skilled workers in a revenue-neutral way. Results are shown in Figure 5. Blue and red lines plot the predicted economic aggregates for the new balanced growth path with different tax rates of an automation tax and a training tax on skilled workers.

In the long run, an automation tax decreases the automation level and increases the labor share; fewer tasks are automated due to a lower profit of automation patents. Lower automation level decreases the wage and welfare inequality. On the other hand, a training tax increases the automation level and decreases the labor share. It favors automation and suppresses human capital investment. However, the human capital growth rate is higher than the *laissez-faire* rate. When the tax reduces the human capital investment, it decreases the opportunity cost of R&D

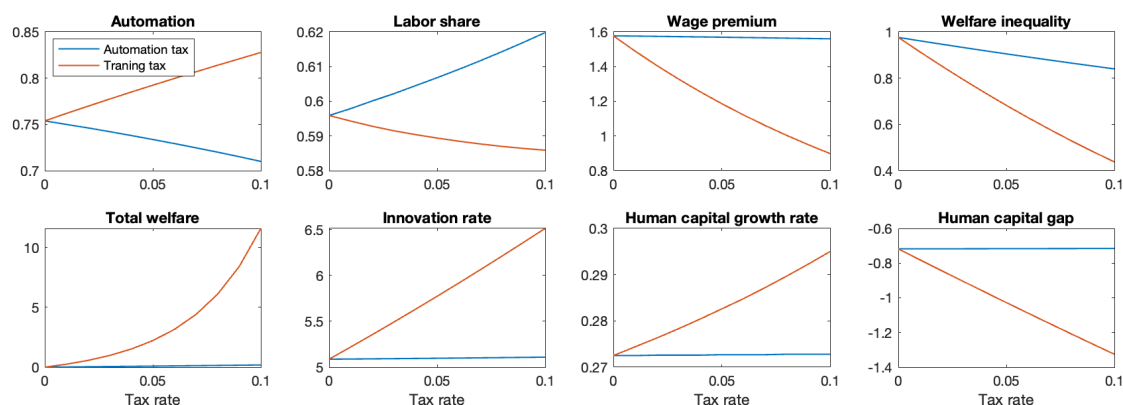


Figure 5: Tax Analysis

Notes: Equal transfers to all the workers are financed by alternative tax rates of an automation tax (blue lines) or a training tax on skilled workers (red lines). The figure shows the predicted economic aggregates for the new balanced growth path (after the technological revolution) with the calibrated model. The x-axis is the alternative tax rate.

and increases the technology growth rate. Higher technology growth rate increases the wage growth and encourages more human capital investment. A training tax reduces the wage premium and welfare inequality more efficiently than an automation tax. A small tax on training significantly decreases the human capital gap and favors unskilled workers.

In the long run, consistent with the result of the social planner's problem in section 4, both automation tax and training tax on skilled workers improve the economy's efficiency and boost long-run growth. The automation tax corrects the positive externality of innovation on aggregate productivity. The training tax on skilled workers corrects the negative externality of training in the R&D sector. However, the long-run implication does not tell the whole story; I next plot the transition path while imposing taxes.

Figure 6 plots the transition path with a 1% automation tax (blue lines) or a 0.7% training tax (red lines) on skilled workers, which renders the same fiscal revenue as the automation tax. The automation tax does not change much the transition dynamics. It uniformly decreases the automation level and increases the labor share. On the other hand, the training tax significantly reshapes the transition path. Skilled workers invest less in training and supply more high-skill labor at the early stage of the technological revolution, the innovation rate catches up with the automation rate earlier, and the labor share recovers faster after the technological revolution.

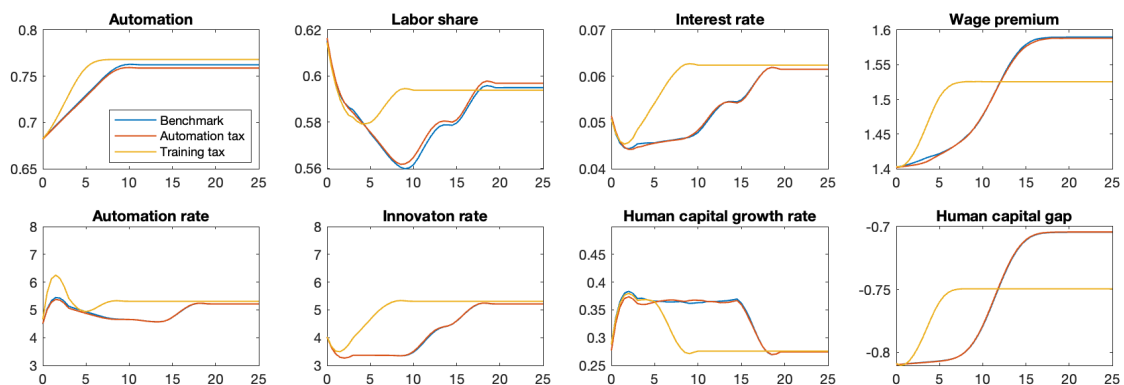


Figure 6: Adjustment Dynamics (automation or training tax)

Notes: Blue lines show the simulation of the transition path after a reduction of automation cost, red lines show the transition with a 1% automation tax, and yellow lines show the transition with a 0.7% training tax on skilled workers. Oscillations are caused by computational errors.

6 Empirical Implications

I study the implications of my model in the context of exposure to automation affecting skill levels and training time. I start by documenting recent changes in skill levels and human capital investment. Then I estimate the effect of automation on the human capital response at the industry and occupation levels. Finally, I finalize explore the heterogeneous responses of college graduates or higher (skilled workers) and high school graduates or lower (unskilled workers) to the technology change.

At the industry level, I use the EU KLEMS (EU level analysis of capital, labor, energy, materials and service inputs) and use Total Factor Productivity (TFP) growth as an approximation of the automation process following Autor and Salomons (2018). After a reduction of automation costs, both automation and innovation rates increase, leading to an increase in TFP. I use labor composition (share of college graduates) in the EU KLEMS to approximate human capital.

At the occupation level, I use the automation occupational exposure constructed by Webb (2019), which measures how likely the workers in each occupation can be replaced by machine. I use the measure of skill level and importance in O*NET (Occupational Information Network) to approximate the human capital stock. I use the training time in ATES (Adult Training and Education Survey) to measure the investment in human capital.

6.1 Changes in Skill Level and Human Capital Investment

I document recent trends in skill levels and human capital investment. At the industry level, I focus on the change of labor composition (share of college graduates or higher); at the occupation level, I focus on the skill level change and the time spent on training.

To explore the human capital change at the industry level, I use the EU KLEMS September 2017 release, an industry-level panel dataset covering all individual EU-28 countries and the United States from 1995 to 2015. The data set contains statistical data on the economic growth (value added, compensation to capital and labor, etc.) and labor market composition (compensation and employment share for high/medium/low educated workers), and analytical data on the growth factors (TFP, capital services, hours worked, labor composition, etc.).

Industry	100×Annualized log change			
	1995	2000	2005	2010
Accommodation and food service activities	-4.621	5.880	3.514	6.990
Agriculture, forestry and fishing	7.564	8.061	5.722	2.950
Arts, entertainment and recreation	5.433	4.225	3.221	2.307
Construction	2.375	2.481	2.821	3.721
Education	0.836	0.263	1.071	1.127
Electricity, gas, steam and air conditioning supply	-0.389	1.290	3.568	3.925
Financial and insurance activities	2.248	1.412	1.669	3.753
Health and social work	2.564	0.822	1.937	2.432
Information and communication	3.194	1.934	3.660	2.844
Mining and quarrying	6.689	3.550	4.495	6.311
Other service activities	3.793	4.261	3.511	3.300
Professional, scientific, technical, administrative and support service activities	1.491	1.358	1.335	2.495
Public administration and defense, compulsory social security	2.186	2.553	2.808	2.806
Real estate activities	3.613	2.000	3.091	2.656
Total manufacturing	3.884	2.619	4.248	3.707
Transportation and storage	2.991	2.305	6.175	4.027
Water supply, sewerage, waste management and remediation activities	3.532	2.446	1.437	4.999
Wholesale and retail trade repair of motor vehicles and motorcycles	3.984	2.603	2.770	4.607
Total	2.854	2.781	3.172	3.609

Table 5: Trends in Skilled Worker Share by Industry

Notes: Data are from the EU KLEMS (EU level analysis of capital, labor, energy, materials and service inputs). I calculate the average change of skilled worker shares for the following periods: 1995-1999, 2000-2004, 2005-2009, and 2010-2014.

Table 5 summarizes the change in the share of skilled workers (college graduates or higher) by industry. Between 1995 and 2015, the aggregate share of skilled workers increased. There are significant variations between industries; industries using more unskilled workers like agriculture and manufacturing experienced more labor composition change, while industries using more skilled workers like edu-

cation and health experienced less. First, workers respond to the technological change by investing more in human capital. Second, as shown in Restrepo (2015), automation replaces unskilled workers, and unskilled workers relocate to industries that are less exposed to automation. In subsection 6.2, I estimate the effect of automation on labor composition while controlling for the relocation effect.

To explore the skill change at the occupation level, I use the O*NET (Occupational Information Network) data. I merge all the history releases of O*NET and construct panel data. For each occupation, O*NET measures the importance and level of different skills and updates the data almost twice a year. The first official O*NET data set was released in 2003, and a major change was made in 2010. In other releases, only a subset of occupations was updated. There are two groups of skills: basic skills, including content and process; cross-functional skills, including complex problem solving, resource management, social, systems and technical. Each subgroup includes several detailed skill types, which describe the specifically developed capacities needed for the occupation.

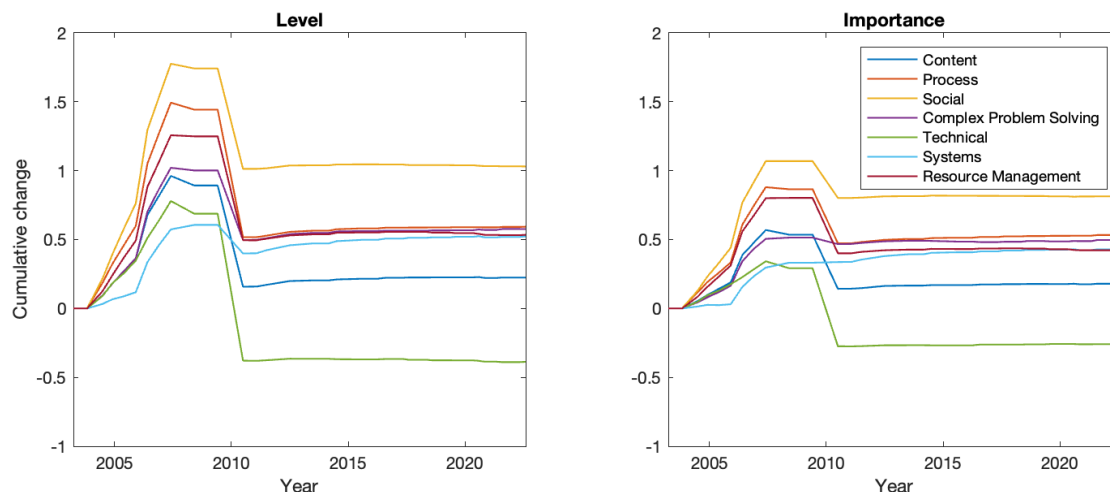


Figure 7: Trends in Skill Level and Importance

Notes: Data are from the O*NET (Occupational Information Network). I calculate the average skill level or importance for the seven skill groups. The x-axis is the release date of the data; the y-axis is the change in skill level or importance compared with the first release.

Figure 7 summarizes the changes in importance and level for each skill group. Between 2000 and 2020, the trends in level and importance are very similar. The main change happened between 2002 and 2010, and only minor changes were made after the major update in 2010. The level and importance of social skills have grown significantly faster than other skills, while only technical skills are lower and less important than before.

To see if automation exposure affects the human capital accumulation as pre-

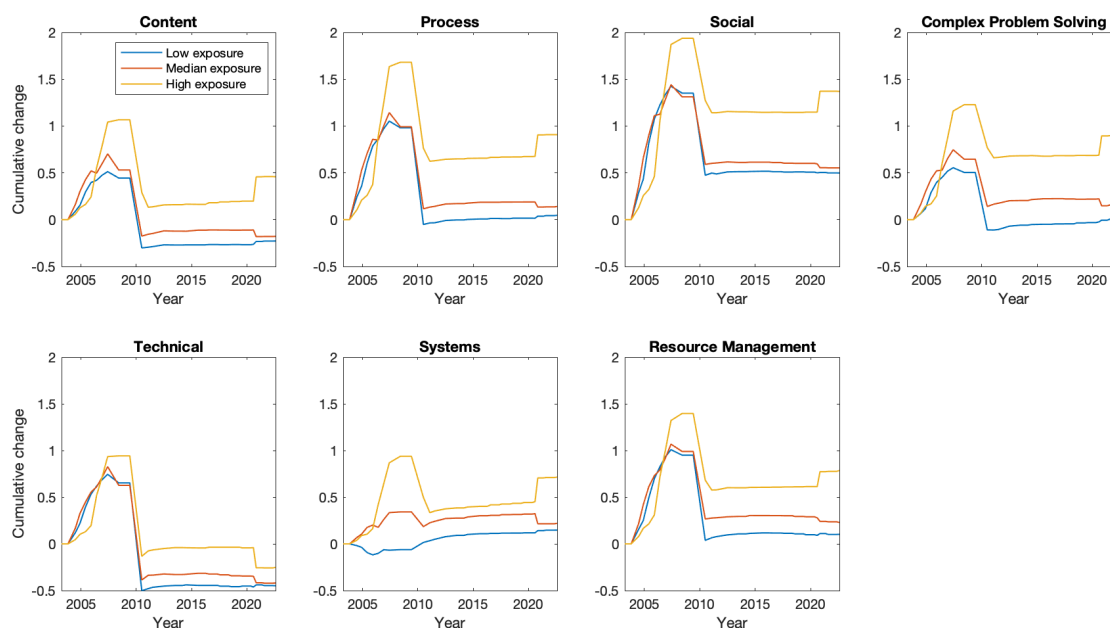


Figure 8: Trends in Skill Level Facing Different Automation Exposure

Notes: Data are from the O*NET (Occupational Information Network). I partition the occupations into groups with low (under the 33rd percentiles), medium (between the 33rd and 66th percentiles) and high (above the 66th percentiles) automation exposures. Then I calculate the average skill level or importance for the seven skill groups. The x-axis is the release date of the data; the y-axis is the change in skill level compared with the first release.

dicted in the model, I partition the occupations into groups with low (under the 33rd percentiles), medium (between the 33rd and 66th percentiles) and high (above 66th percentiles) automation exposures. To do so, I use the automation occupational exposure measure constructed by Webb (2019). He uses the overlap between the text of job task descriptions (O*NET) and the text of patents (Google Patents Public Data) to measure the exposure of tasks to automation. The measure ranges from 0% to 100%, indicating how likely the labor is to be displaced in each occupation. Figure 8 summarizes the change in level for each skill group by automation exposure. The skill levels of all the skill groups increase significantly more when the occupation is more exposed to automation, especially process, social and complex problem solving skills.

Another important empirical implication of my model is the heterogeneous responses of different skill groups. The education level is measured by the share of skilled workers working in the occupation. O*NET provides detailed information on workers' education levels for each occupation. I construct the ratio of workers with a college degree or higher as the empirical analog of the share of skilled workers. I partition the occupations into groups with low (under the 33rd percentiles),

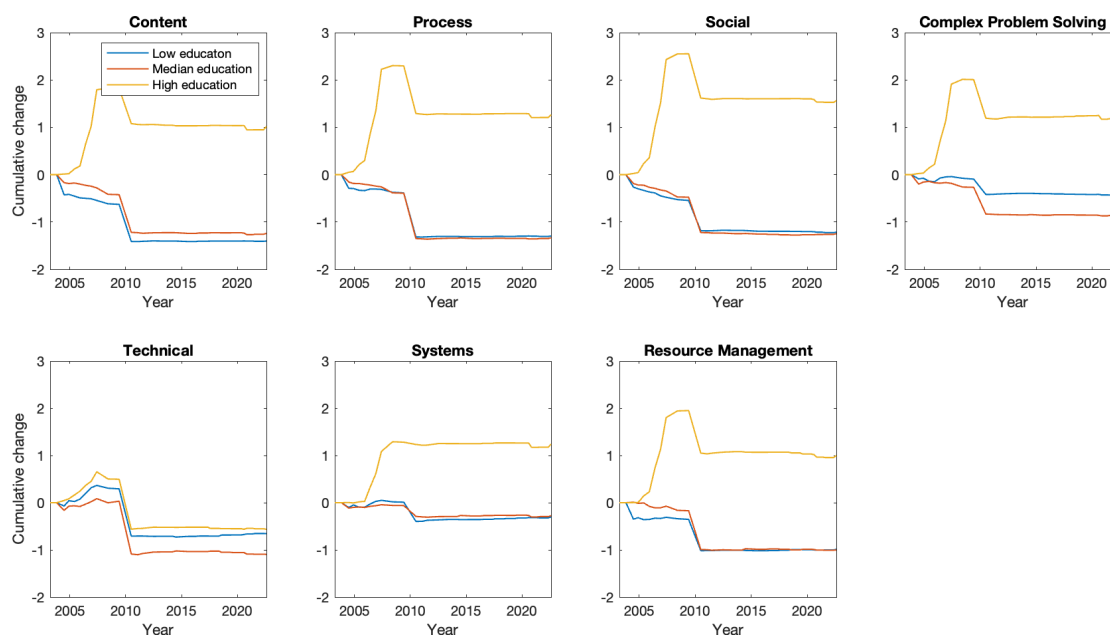


Figure 9: Trends in Skill Level with Different Education level

Notes: Data are from the O*NET (Occupational Information Network). I partition the occupations into groups with low (under the 33rd percentiles), medium (between the 33rd and 66th percentiles) and high (above the 66th percentiles) education. Then I calculate the average skill level or importance for the seven skill groups. The x-axis is the release date of the data; the y-axis is the change in skill level compared with the first release.

medium (between the 33rd and 66th percentiles) and high (above 66th percentiles) education levels. Figure 9 summarizes the change in level for each skill group with different education levels. The skill levels of the occupation grow significantly faster as more skilled workers work in this occupation, except for technical skills.

A direct measure of human capital investment can be constructed using ATES (Adult Training and Education Survey). The ATES collects data about adults ages 16 to 65 who are not enrolled in high school. I use the hours per week in ESL (English as a Second Language) and ABE (Adult Basic Education)/GED (General Equivalency Diploma) classes multiplied by the number of weeks spent to construct the total hours spent on nondegree credentials. ATES also asks about the total hours spent on work experience programs. Other relevant data ATES provides are hours per week worked for pay, worker's occupation (20 aggregate groups) if employed, sex, age and ethnicity.

Figure 10 plots the average training-working time ratio and the ratio of workers participating in any type of training for each occupation. Both ratios are decreasing in automation exposure. Workers exposed more to automation invest less in their human capital. First, unskilled workers exposed to automation face a higher risk of being replaced by the machine and not eligible for work-related courses.

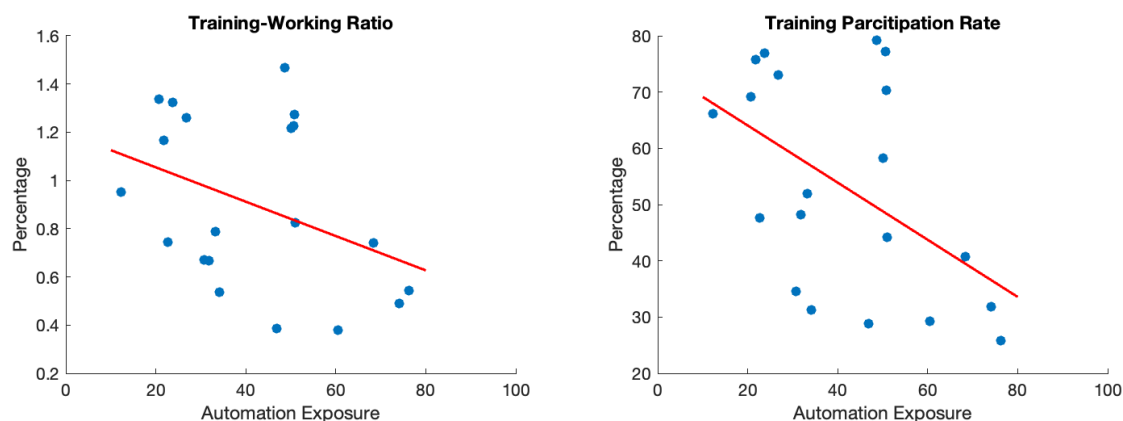


Figure 10: Training Facing Different Automation Exposure

Notes: Data are from the ATES (Adult Training and Education Survey). I calculate the average training-working time ratio and the ratio of workers participating in any type of training for each occupation. The x-axis is the automation occupational exposure constructed by Webb (2019).

Second, displaced workers relocate to new occupations that are less exposed to automation and are more likely to participate in workplace training.

In this subsection, I have documented that the labor composition, skill level change, and training investment respond differently based on automation exposure. It seems contradictory that occupations with higher automation exposure experience higher skill growth rates, but workers spend less time on training when their occupation is more exposed to automation. First, when an occupation is exposed to automation, unskilled workers are more likely to be displaced, while skilled workers are more likely to work at this occupation to complement the new technology. The labor composition change increases the average skill level in this occupation. Second, the growth in skill level is mainly attributed to skilled workers. Skilled workers can acquire skills to adapt to the new technology environment more quickly than unskilled workers. Indeed, the skill growth rate is higher for occupations with a higher ratio of skilled workers. I will explore the heterogeneous responses in more detail in the following subsection. Third, skills can be acquired outside formal workplace training.

6.2 Effects of Automation on Human Capital Investment

Based on the model, after a reduction of automation cost, both automation and innovation rates increase. In the long run, workers respond to the change in technology by investing more in their human capital. As a result, we should observe an overall increase in human capital or an improvement in labor composition (higher ratio of skilled workers). To test the correlation between automation and human

capital growth, I use EU KLEMS data and estimate the equation:

$$\begin{aligned} \Delta \ln Y_{ic,t-1} = & \beta_0 + \beta_1 \Delta \ln TFP_{i,c \neq c(i),t-k} + \beta_2 \Delta \ln TFP_{i,c \neq c(i),t-k-1} + \beta_3 \Delta \ln Y_{ic,t-2} \\ & + \Delta L_{ic,t-1} + \alpha_c + \gamma_t + \epsilon_{ict}. \end{aligned} \quad (33)$$

I regress the outcome variable $\Delta \ln Y_{ic,t-1}$ on the TFP growth rate $\Delta \ln TFP_{i,c \neq c(i),t-k}$ with time lag $k \in \{1, 2, 3, 4, 5\}$ while controlling the lagged values of both TFP growth $\Delta \ln TFP_{i,c \neq c(i),t-k-1}$ and of outcome variable growth $\Delta \ln Y_{ic,t-2}$. To interpret β_1 as the effect of automation on human capital, not a result of relocation, I control for the change of employment $\Delta L_{ic,t-1}$. I also control for the fixed effect of country α_c and year γ_t . To overcome the endogeneity between TFP and labor composition, I follow Autor and Salomons (2018). I construct industry-level TFP growth for each industry-country pair as the leave-out mean of industry-level TFP growth in all other countries, then rescaled it to have a unit standard deviation. The coefficient β_1 measures the impact of TFP growth on outcome variables with different lags.

To measure human capital growth, I use two related variables: the change in the share of skilled workers (college graduates) and the growth rate attributed to labor composition change. The estimation result is reported in Table 6 and 7. The coefficient β_1 is not significant except when $k = 4$. The TFP growth does not immediately impact the labor composition but has a positive effect with a four-year lag. A one standard deviation positive TFP shock increases the share of skilled workers by 0.55% and increases the growth rate attributed to labor composition change by 0.28% after four years.

To estimate the effect of automation on labor composition more structurally, I adopt simple local projection models in Autor and Salomons (2018). They document well in their paper the impact of automation on employment, hours worked, wage bills, and labor share. I adopt their estimation method while the outcome of interest is the labor composition and the growth rate attributed to labor composition change. I estimate the equation:

$$\begin{aligned} \ln Y_{ic,t+K} - \ln Y_{ic,t-1} = & \beta_0 + \beta_1 \Delta \ln TFP_{i,c \neq c(i),t-1} + \sum_{k=0}^K \beta_2^k \Delta \ln TFP_{i,c \neq c(i),k} \\ & + \beta_3 \Delta \ln TFP_{i,c \neq c(i),t-2} + \beta_4 \Delta \ln Y_{ic,t-2} + \alpha_c + \gamma_t + \epsilon_{ict}, \end{aligned} \quad (34)$$

where $\ln Y_{ic,t+K} - \ln Y_{ic,t-1}$ represents the log change in share of high educated labor in industry i and country c , from year $t - 1$ to year $t + K$. The impulse variable is the log change in other-country-industry TFP between years $t - 2$ and $t - 1$, $\Delta \ln TFP_{i,c \neq c(i),t-1}$. I estimate the effects while controlling for lagged values of both TFP growth $\Delta \ln TFP_{i,c \neq c(i),t-2}$ and of outcome variable growth $\Delta \ln Y_{ic,t-2}$,

VARIABLES	(1)	(2)	(3)	(4)	(5)	(6)
	100×Annualized log change in share of skilled workers					
TFP Growth	-0.219 (0.311)					
TFP Growth (lag 1)		0.339 (0.252)				
TFP Growth (lag 2)			0.310 (0.251)			
TFP Growth (lag 3)				-0.253 (0.257)		
TFP Growth (lag 4)					0.550** (0.271)	
TFP Growth (lag 5)						-0.412 (0.282)
Constant	4.305 (2.770)	4.655** (1.971)	5.924*** (1.963)	7.012*** (1.987)	7.012*** (2.033)	9.188*** (2.090)
Observations	2,301	2,657	2,325	1,993	1,661	1,330
R-squared	0.120	0.123	0.135	0.151	0.178	0.223

Table 6: TFP Effect on High Educated Labor Share

Notes: Data are from EU KLEMS. The table presents estimates of the incidence of TFP growth on labor composition change. Coefficients are for observed TFP shocks in $t = \{0, -1, -2, -3, -4, -5\}$, rescaled to have a unit standard deviation. Robust standard errors are in parenthesis. ***, **, * denotes statistical significance at 1, 5 and 10 percent levels.

and subsequent TFP innovations occurring between $t = 0$ and $t = K$. I also control the fixed effect of country α_c and year γ_t .

The estimation result is plotted in Figure 11. Coefficients plotted in the figure are the response of outcomes to the TFP shock in $t = 0$. The trend is consistent with the result above. The TFP shock does not affect the labor composition immediately but has a long-run effect on human capital growth. The effect of TFP on human capital gradually increases over time and peaks five years after the technological change.

A similar pattern can be found using occupational data. When an occupation is more exposed to automation, we should observe a higher growth in skill level. To test the correlation between automation and skill level growth, I use O*NET data and estimate the equation:

$$y_{ijt} = \beta_0 + \beta'_1 T_t + \beta'_2 T_t \times AOE_i + \alpha_0 B_t + \alpha'_j T_t \times D_j + \gamma_j D_j + \epsilon_{ijt}, \quad (35)$$

where y_{ijt} is the level of skill j for occupation i at time t . T_t is a vector of time dummy variables created for each release date t . AOE_i is the automation occupational exposure for occupation i , ranging between 0% and 100%. $T_t \times AOE_i$ is the interaction between time dummy variables and automation. B_t is a dummy variable controlling for the update in June 2010, $B_t = 1$ if the data is released after June 2010. D_j is a dummy variable created for each skill j . The automation

VARIABLES	(1)	(2)	(3)	(4)	(5)	(6)
	Labor composition growth					
TFP Growth	-0.0787 (0.0739)					
TFP Growth (lag 1)		0.0997 (0.0806)				
TFP Growth (lag 2)			0.171** (0.0864)			
TFP Growth (lag 3)				0.107 (0.0941)		
TFP Growth (lag 4)					0.281** (0.109)	
TFP Growth (lag 5)						0.0879 (0.121)
Constant	-0.817 (0.726)	-0.924 (0.752)	-1.093 (0.800)	-1.301 (0.850)	-1.389 (0.933)	-1.610 (0.997)
Observations	2,597	2,300	2,003	1,706	1,409	1,113
R-squared	0.193	0.189	0.195	0.218	0.221	0.280

Table 7: TFP Effect on Labor Composition Growth

Notes: Data are from the EU KLEMS. The table presents estimates of the incidence of TFP growth on growth rate attributed to labor composition change. Coefficients are for observed TFP shocks in $t = \{0, -1, -2, -3, -4, -5\}$, rescaled to have a unit standard deviation. Robust standard errors are in parenthesis. ***, **, * denotes statistical significance at 1, 5 and 10 percent levels.

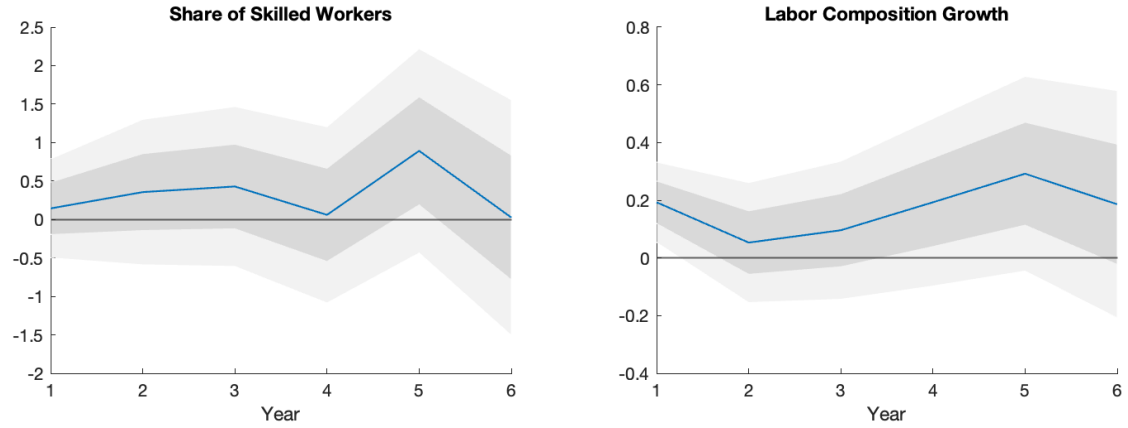


Figure 11: Local Projection Estimates of the Relationship Between TFP Growth and Human Capital

Notes: Data are from the EU KLEMS. The figure presents estimates of the incidence of TFP growth on labor composition or growth rate attributed to labor composition change. Coefficients are for responses of the outcome variables at $t = \{1, 2, 3, 4, 5, 6\}$ to observed TFP shocks in $t = 0$. TFP shocks are rescaled to have a unit standard deviation. Bands are 95% and 70% CI.

effect is estimated while controlling the fixed effect D_j and the common time trend $T_t \times D_j$ for each skill j .

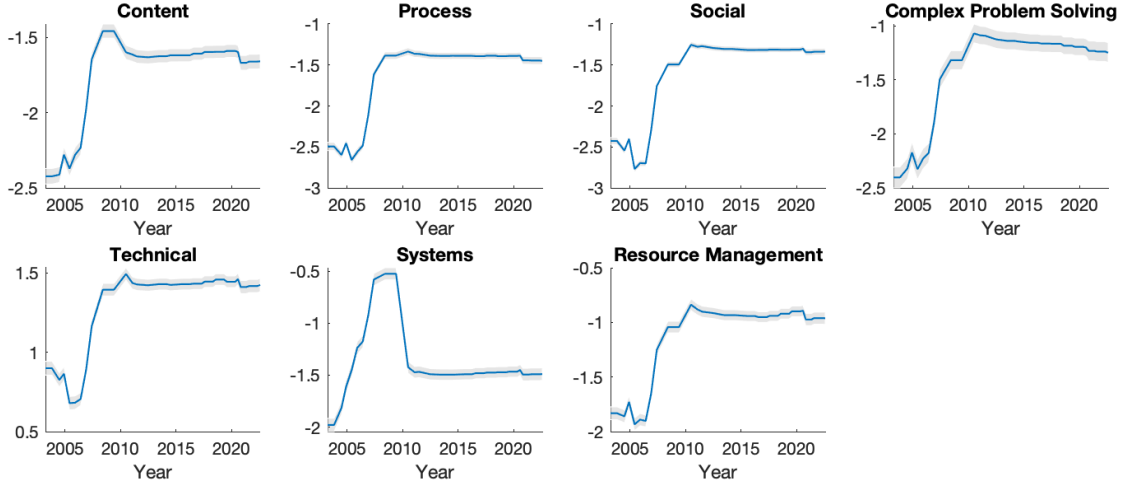


Figure 12: Responses of Skill Levels to Automation

Notes: Data are from the O*NET. The figure presents estimates of the effect of automation exposure on skill level. Coefficients are for skill level responses to automation exposure at each release date (β'_2). The automation effect is estimated while controlling the fixed effect and the common time trend for each skill. Bands are 95% CI.

β'_2 is interpreted as the effect of automation on skill level at each release date. The estimation result for β'_2 is reported in Figure 12. The effect of automation on skill level is increasing overtime for all skill groups except systems skills. This result is consistent with the estimation at industry level, workers respond to automation by increasing their skill levels.

6.3 Heterogeneous Responses

The key empirical implication of my model is that skilled and unskilled workers respond differently to automation. First, automation benefits skilled workers more than unskilled workers. Second, skilled workers have a better ability to learn. When an occupation is exposed to automation, skilled workers increase their skill level more than unskilled workers. Using O*NET data, I estimate the equation:

$$\begin{aligned}
 y_{ijt} = & \beta_0 + \beta'_1 T_t + \beta'_2 T_t \times AOE_i + \beta'_3 T_t \times EDUC_{it} + \beta'_4 T_t \times AOE_i \times EDUC_{it} \\
 & + \alpha_0 B_t + \alpha'_j T_t \times D_j + \gamma_j D_j + \epsilon_{ijt},
 \end{aligned} \tag{36}$$

where y_{ijt} is the level of skill j for occupation i at time t . T_t is a vector of time dummy variables created for each release date t . AOE_i is the automation occupational exposure for occupation i , ranging between 0% and 100%. $EDUC_i$ is the ratio of skilled workers (college graduates or higher) at occupation i , ranging between 0% and 100%. $T_t \times AOE_i$, $T_t \times EDUC_i$ and $T_t \times AOE_i \times EDUC_i$ are

the interaction between time dummy variables and automation or education. I use $T_t \times EDUC_{it}$ to control for the relocation effect. When unskilled workers get displaced due to automation, the average education level increases and positively affects the average occupational skill level. B_t is a dummy variable controlling for the update in June 2010, $B_t = 1$ if the data is released after June 2010. D_j is a dummy variable created for each skill j . The automation effect is estimated while controlling the fixed effect D_j and the common time trend $T_t \times D_j$ for each skill j .

β'_2 is interpreted as the effect of automation on skill level at each release date. The key coefficient of the regression is β'_4 , which captures the different human capital responses of skilled and unskilled workers facing automation. The estimation result for β'_2 (upper panel) and β'_4 (lower panel) are reported in Figure 13. Contrary to the estimation result in the last subsection, the effect of automation on skill level decreases over time after controlling for the education level of each occupation. Consistent with the predictions of my model, when the workers are more exposed to automation, they have less incentive to invest in their human capital due to the displacement effect. However, as documented in the precious subsection, the overall skill levels increase more as the occupation is more exposed to automation. The increase is contributed mainly by worker relocation and human capital investment of skilled workers. Automation displaces unskilled workers, increases the share of skilled workers at this occupation. Skilled workers acquire new skills adapting to automation and benefit more from technological change.

Estimation result of β'_4 shows that skilled and unskilled workers respond differently to exposure to automation. Skilled workers increase their human capital investment more than unskilled workers, especially social and systems skills. The difference between skilled and unskilled workers is increasing overtime, the human capital gap enlarges when workers are exposed to automation.

The result is consistent with the empirical result of Acemoglu et al. (2020). Robots adopters experience a decline in the share of production workers but increase the overall employment. They hire more skilled workers and equip them with new skills to take advantage of the technology. The difference between skilled and unskilled workers could be underestimated using the equation above because of the relocation. If the worker exposed to automation has low skill levels, he is at higher risk of being displaced, and his human capital accumulation slows down more due to joblessness.

A similar pattern can be found using the direct measure of human capital investment. I use ATES data and calculate the total training hours for each individual spent on ESL, ABE and work experience programs. I only keep employed individuals, so their exposure to automation can be measured based on their occupation. I estimate the equation:

$$y = \beta_0 + \beta_1 AOE + \beta_2 SKILL + \beta_3 AOE \times SKILL + T + \Gamma + \epsilon, \quad (37)$$

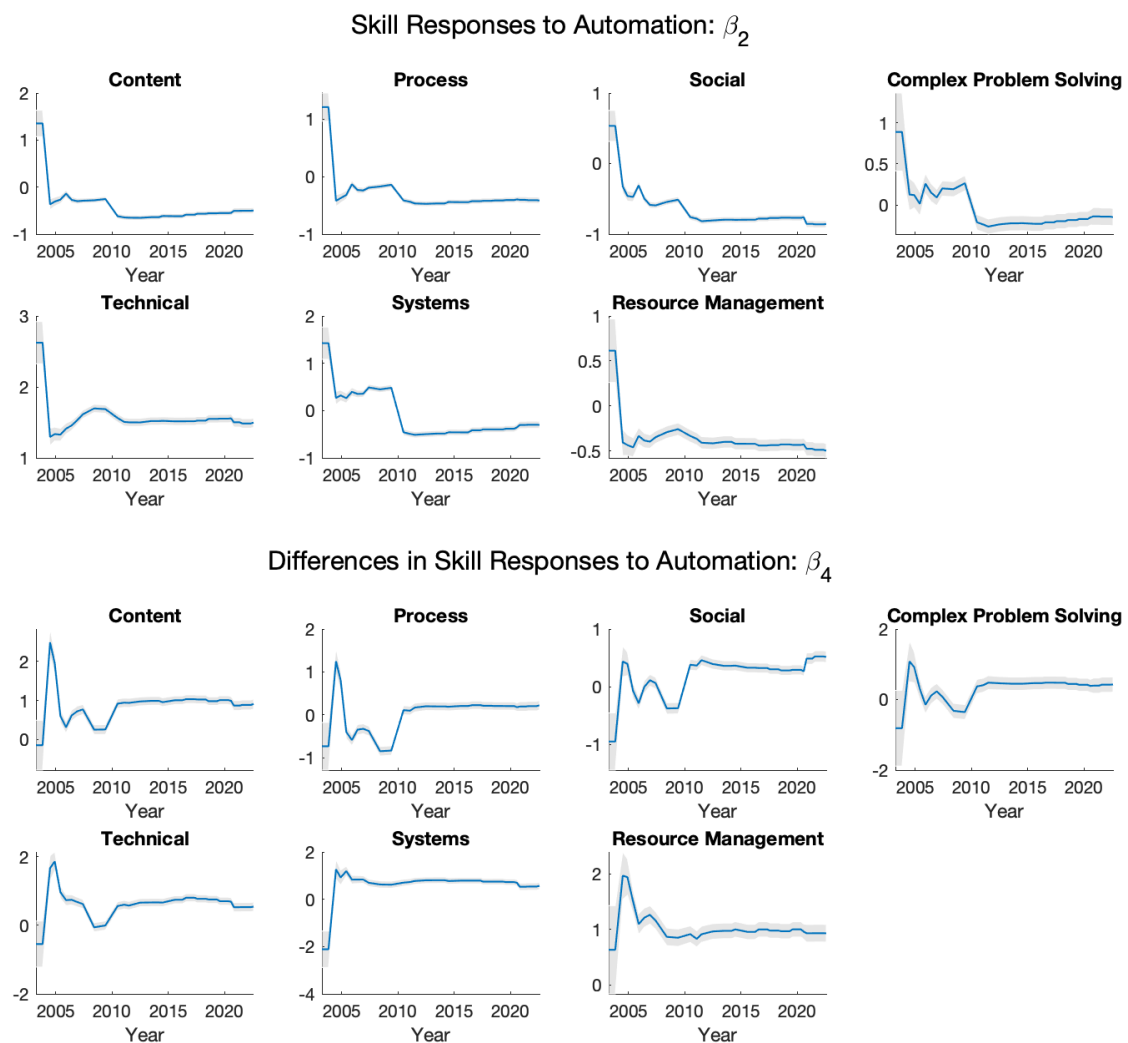


Figure 13: Heterogeneous Responses of Skill Levels to Automation

Notes: Data are from the O*NET. The figure presents estimates of the effect of automation exposure on skill level. Coefficients in the upper panel are for responses of the skill levels to automation exposure at each release date (β_2). Coefficients in the lower panel are for the difference between skilled and unskilled workers in skill level responses to automation exposure at each release date (β_4). The automation effect is estimated while controlling the relocation effect, and the fixed effect and common time trends for each skill. Bands are 95% CI.

where y represents the total training hours for each individual. AOE is the automation occupational exposure for the worker's occupation. $SKILL$ is the skill group of the worker (1 if with a college degree or higher and 0 otherwise). T is a vector of year dummy variables created for each survey year. Γ is the vector of control variables, including age, sex and ethnicity.

The key coefficient of the regression is β_3 , which captures the different train-

VARIABLES	(1)	(2)
	Training hours	
AOE \times SKILL	10.02*** (0.0752)	10.40*** (0.0753)
AOE	-4.852*** (0.0534)	-5.666*** (0.0540)
SKILL	1.260*** (0.0277)	1.250*** (0.0277)
Constant	23.91*** (0.0250)	27.48*** (0.0355)
Observations	202,747,797	202,747,797
R-squared	0.015	0.015
Time dummies	Yes	Yes
Control variable	No	Yes

Table 8: Effect of Automation on Training

Notes: Data are from the ATES (Adult Training and Education Survey). The table presents estimates of the incidence of automation and education on training hours (weighted least squares). *AOE* is the automation occupational exposure for the worker’s occupation. *SKILL* is the skill group of the worker (1 if with a college degree or higher and 0 otherwise). In the second column, I control for sex, age and ethnicity. Robust standard errors are in parenthesis. ***, **, * denotes statistical significance at 1, 5 and 10 percent levels.

ing investment of skilled and unskilled workers in response to automation. The estimation result is reported in Table 8. The result is consistent with the occupational skill level change above. Workers working in occupations more exposed to automation invest less in training, and skilled workers invest more in training than unskilled workers. With a 1 percent increase in automation level, skilled workers spend 0.1 hour more than unskilled workers.

The empirical findings are consistent with the theoretical implications of my model. Automation decreases human capital investment through the displacement effect, but increases human capital investment through the productivity effect. The responses of skilled and unskilled to automation are significantly different. Automation increases the overall skill level and human capital investment, and the increase is attributed mainly to skilled workers.

7 Conclusion

This paper discusses the adjustments of human capital to a reduction of automation cost. When a technological revolution lowers the cost of automation, it immediately increases automation, displaces workers and lowers the wage growth rate. A higher automation level improves the production factor allocation and increases innovation incentives in the R&D sector. The innovation rate catches up with the automation rate and encourages human capital investment. A higher human

capital growth rate increases the effective labor supply, complementing innovation and substituting automation. With endogenous human capital responses, the economy converges to a balanced growth path with a lower automation level and a higher labor share compared to the scenario with fixed human capital. However, skilled workers respond more than unskilled workers to the technological revolution. Skilled workers benefit more from the productivity effect, while unskilled workers are affected more by the displacement effect. Skilled workers also have more ability to adjust their human capital investment. The uneven responses amplify wage inequality.

Indeed, the data supports the implications of this mechanism. Occupations with higher automation exposure experience higher skill growth rate. This higher growth rate is attributed to worker relocation and human capital accumulation of skilled workers. High automation exposure decreases the human capital investment incentive of unskilled workers. Skilled workers adjust more than unskilled workers in the human capital facing automation exposure.

Theory and data suggest that the new technological changes are skill-biased and complement skilled workers (Violante, 2018). In my model, I assume constant elasticity of substitution between production factors, which may underestimate the uneven effect of automation on different skill groups. The allocation friction of unskilled workers could also contribute to inequality after an increase in automation level. Another extension of my model is to consider multi-dimensional skills; as shown in the empirical section, each skill group responds differently to the ongoing technological changes.

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Appendix A Firm Problem

Final Good Producer

The competitive final good producers solve the following problem:

$$\begin{aligned} \max \quad & Y - \int_{N-1}^N p(i)y(i)di, \\ & Y = \tilde{A} \left(\int_{N-1}^N y(i)^{\frac{\sigma-1}{\sigma}} di \right)^{\frac{\sigma}{\sigma-1}}. \end{aligned}$$

Take first order condition with respect to $y(i)$:

$$\tilde{A} \left(\int_{N-1}^N y(i)^{\frac{\sigma-1}{\sigma}} di \right)^{\frac{1}{\sigma-1}} y(i)^{-\frac{1}{\sigma}} - p(i) = 0.$$

Then the demand function of each task can be written as:

$$y(i) = \tilde{A}^{\sigma-1} Y p(i)^{-\sigma}.$$

Task Producer

The task producers who have adopted machine solves the following problem:

$$\begin{aligned} \max \quad & p(i)y(i) - Rk(i) - \psi q(i), \\ & y(i) = q(i)^\eta k(i)^{1-\eta}. \end{aligned}$$

Take first order condition with respect to $k(i)$ and $q(i)$:

$$\begin{aligned} q(i)\psi &= \eta p(i)y(i), \\ k(i)R &= (1-\eta)p(i)y(i). \end{aligned}$$

The unit cost of production can be written as:

$$\begin{aligned} y(i) &= \left(\frac{\eta p(i)y(i)}{\psi} \right)^\eta \left(\frac{(1-\eta)p(i)y(i)}{R} \right)^{1-\eta}, \\ p(i) &= \left(\frac{\psi}{\eta} \right)^\eta \left(\frac{R}{1-\eta} \right)^{1-\eta} \\ &= \Psi R^{1-\eta}, \quad \Psi = \left(\frac{\psi}{\eta} \right)^\eta \left(\frac{1}{1-\eta} \right)^{1-\eta}. \end{aligned}$$

Plug in the demand function solved from final good producer problem, the output of the task $p(i)y(i)$ can then be solved:

$$p(i)y(i) = \left(\frac{\tilde{A}}{\Psi} \right)^{\sigma-1} Y R^{(1-\eta)(1-\sigma)} = Y \left(\frac{R}{A} \right)^{1-\hat{\sigma}},$$

where $\hat{\sigma} = 1 - (1 - \eta)(1 - \sigma)$ and $A = \left(\frac{\tilde{A}}{\Psi}\right)^{\frac{\sigma-1}{\hat{\sigma}-1}} = \left(\frac{\tilde{A}}{\Psi}\right)^{\frac{1}{1-\eta}}$. The demand of capital for task i is:

$$k(i) = (1 - \eta)A^{\hat{\sigma}-1}YR^{-\hat{\sigma}}.$$

Similarly, the unit cost of task if the producers use unskilled or skilled workers can be solved as:

$$p(i) = \begin{cases} \Psi\left(\frac{W_L}{\gamma_L(i, h_L)}\right)^{1-\eta}, & \text{unskilled worker} \\ \Psi\left(\frac{W_H}{\gamma_H(i, h_H)}\right)^{1-\eta}, & \text{skilled worker.} \end{cases}$$

The output of the tasks $p(i)y(i)$ are:

$$p(i)y(i) = \begin{cases} Y\left(\frac{W_L}{A\gamma_L(i, h_L)}\right)^{1-\hat{\sigma}}, & \text{unskilled worker} \\ Y\left(\frac{W_H}{A\gamma_H(i, h_H)}\right)^{1-\hat{\sigma}}, & \text{skilled worker.} \end{cases}$$

And the demand of unskilled and skilled workers can be solved as:

$$l(i) = (1 - \eta)A^{\hat{\sigma}-1}\frac{Y}{\gamma_L(i, h_L)}\left(\frac{W_L}{\gamma_L(i, h_L)}\right)^{-\hat{\sigma}},$$

$$h(i) = (1 - \eta)A^{\hat{\sigma}-1}\frac{Y}{\gamma_H(i, h_H)}\left(\frac{W_H}{\gamma_H(i, h_H)}\right)^{-\hat{\sigma}}.$$

Appendix B Proposition Proofs

Factor Allocation

The research sector always automates the least updated tasks since they are the tasks where machine have less disadvantage. The research sector will develop the patent only if the firm can make more profit by adopting machine and is willing to purchase the patent. As a result, for all the task that are automated ($N - 1 \leq i \leq I$), it must be true that:

$$R^{1-\eta} < \min\left\{\left(\frac{W_L}{\gamma_L(i, h_L)}\right)^{1-\eta}, \left(\frac{W_H}{\gamma_H(i, h_H)}\right)^{1-\eta}\right\},$$

and all the firms who have access to automation patent choose to produce the task using machine.

For the tasks that are not automated, skilled workers always have advantage over more updated tasks. $\frac{W_H}{W_L}$ is increasing in S , when $S \rightarrow I$, $\frac{W_H}{W_L} \rightarrow 0$, when $S \rightarrow N$, $\frac{W_H}{W_L} \rightarrow \infty$. $\frac{\gamma_H(S, h_L)}{\gamma_L(S, h_L)}$ is increasing in S . There exists a unique cutoff point S such that:

$$\frac{W_H}{W_L} = \frac{\gamma_H(S, h_L)}{\gamma_L(S, h_L)},$$

Then, for other tasks that are not automated, we get:

$$\frac{W_H}{\gamma_H(i, h_L)} \frac{\gamma_L(i, h_L)}{W_L} = e^{(B-B_N)(S-i)} \frac{W_H}{\gamma_H(S, h_L)} \frac{\gamma_L(S, h_L)}{W_L} = e^{(B-B_N)(S-i)}.$$

If $i < S$, then $\frac{W_H}{\gamma_H(i, h_L)} \frac{\gamma_L(i, h_L)}{W_L} > 1$, the firm will choose to produce the task using unskilled workers. If $i > S$ then $\frac{W_H}{\gamma_H(i, h_L)} \frac{\gamma_L(i, h_L)}{W_L} < 1$, the firm will choose to produce the task using skilled workers.

Aggregate Production Function

At equilibrium, the market clearing condition needs to be satisfied:

$$\begin{aligned} K &= \int_{N-1}^I k(i) di = \int_{N-1}^I (1-\eta) A^{\hat{\sigma}-1} Y R^{-\hat{\sigma}} di, \\ L_L &= \int_I^S l_L(i) di = \int_{N-1}^I (1-\eta) A^{\hat{\sigma}-1} \frac{Y}{\gamma_L(i, h_L)} \left(\frac{W_L}{\gamma_L(i, h_L)} \right)^{-\hat{\sigma}} di, \\ L_H &= \int_S^N l_H(i) di = \int_{N-1}^I (1-\eta) A^{\hat{\sigma}-1} \frac{Y}{\gamma_H(i, h_H)} \left(\frac{W_H}{\gamma_H(i, h_H)} \right)^{-\hat{\sigma}} di. \end{aligned}$$

Then the factor prices could be solved using market clearing condition:

$$\begin{aligned} R &= A \Gamma_K \left(\frac{(1-\eta)Y}{A \Gamma_K K} \right)^{\frac{1}{\hat{\sigma}}}, \quad \Gamma_K = (I - N + 1)^{\frac{1}{\hat{\sigma}-1}}, \\ W_L &= A \Gamma_L \left(\frac{(1-\eta)Y}{A \Gamma_L L_L} \right)^{\frac{1}{\hat{\sigma}}}, \quad \Gamma_L = \left(\frac{\gamma_L(S, h_L)^{\hat{\sigma}-1} - \gamma_L(I, h_L)^{\hat{\sigma}-1}}{B_L(\hat{\sigma}-1)} \right)^{\frac{1}{\hat{\sigma}-1}}, \\ W_H &= A \Gamma_H \left(\frac{(1-\eta)Y}{A \Gamma_H L_H} \right)^{\frac{1}{\hat{\sigma}}}, \quad \Gamma_H = \left(\frac{\gamma_H(N, h_H)^{\hat{\sigma}-1} - \gamma_H(S, h_H)^{\hat{\sigma}-1}}{B(\hat{\sigma}-1)} \right)^{\frac{1}{\hat{\sigma}-1}}. \end{aligned}$$

Plug in the factor price and output for each task:

$$\begin{aligned}
Y &= \int_{N-1}^N p(i)y(i)di \\
&= \int_{N-1}^I Y\left(\frac{R}{A}\right)^{1-\hat{\sigma}} di + \int_I^S Y\left(\frac{W_L}{A\gamma_L(i, h_L)}\right)^{1-\hat{\sigma}} di + \int_S^N Y\left(\frac{W_H}{A\gamma_H(i, h_H)}\right)^{1-\hat{\sigma}} di, \\
\left(\frac{(1-\eta)Y}{A}\right)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} &= \int_{N-1}^I \frac{(\Gamma_K K)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}}}{\Gamma_K^{\hat{\sigma}-1}} di + \int_I^S \frac{(\Gamma_L L_L \gamma_L(i, h_L))^{\frac{\hat{\sigma}-1}{\hat{\sigma}}}}{\Gamma_L^{\hat{\sigma}-1}} di + \int_S^N \frac{(\Gamma_H L_H \gamma_H(i, h_H))^{\frac{\hat{\sigma}-1}{\hat{\sigma}}}}{\Gamma_H^{\hat{\sigma}-1}} di.
\end{aligned}$$

The final good could be written as

$$Y = \frac{A}{1-\eta} \left((\Gamma_K K)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} + (\Gamma_L L_L)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} + (\Gamma_H L_H)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}} \right)^{\frac{\hat{\sigma}}{\hat{\sigma}-1}}.$$

Human Capital Growth and Automation Level

The long run interest rate needs to satisfy:

$$r = \rho + \theta g = \rho + \theta(Bg_N + bg_{hH}).$$

Higher human capital growth rate increases the long run interest rate, which increases the innovation patent value and decreases the automation patent value. The automation level needs to decrease in order to have:

$$\frac{p_N}{p_I} = \left(\frac{\mu_N}{\mu_I}\right)^{\frac{1}{\lambda}}.$$

Human Capital and Technology Growth Rate

On the balanced growth path, the human capital investment needs to satisfy the following equation:

$$(1-\theta)\frac{b}{\mu_{hj}}(1-l_j)^{\alpha_j} + \alpha\frac{b}{\mu_{hj}}l_j(1-l_j)^{\alpha_j-1} = \rho + (\theta-1)Bg_N.$$

Define $f(l)$ as the left hand side of the equation, I can take derivative of $f(l)$ as:

$$f'(l) = \alpha_j \frac{b}{\mu_{hj}} (1-l_j)^{\alpha_j-1} (\theta + (1-\alpha_j) \frac{l_j}{1-l_j}) > 0.$$

If $\theta - 1 > 0$, the labor supply is increasing in g_N ; If $\theta - 1 < 0$, the labor supply is decreasing in g_N .

Long-run comparative statistics

On the balanced growth path, the value of patent needs to satisfy:

$$\frac{p_N}{p_I} = \left(\frac{\mu_N}{\mu_I}\right)^{\frac{1}{\lambda}}.$$

The left hand side is increasing in the automation level. Higher automation level decrease the demand for labor and decreases the wage level. Lower wage level increases the innovation patent value p_N and decreases the automation patent value p_I . The right hand side is decreasing in the cost of automation. When the automation cost decreases, the right hand side decreases, the automation level must increase.

The number of scientist working on the innovation sector must satisfy:

$$\frac{\lambda \epsilon_N(t)^{\lambda-1}}{\mu_N} p_N(t) = \omega_H(t).$$

Higher automation level increases p_N and increases the number of scientists working in the innovation sector. The innovation rate is higher.

On the balanced growth path, the human capital of skilled and unskilled workers need to grow at the same rate $g_{hH} = g_{hL} = g_h$. Using the policy function for human capital investment, I can get:

$$\alpha_H((\mu_{hH}g_{hH})^{-\frac{1}{\alpha_H}} - 1) = \alpha_L((\mu_{hL}g_{hL})^{-\frac{1}{\alpha_L}} - 1).$$

Then I can derive the ratio of human capital investment cost and human capital gap as:

$$\begin{aligned} \log\left(\frac{\mu_{hH}}{\mu_{hL}}\right) &= \left(\frac{\alpha_H}{\alpha_L} - 1\right) \log(\mu_{hL}g_h) - \alpha_H \log\left(\left(\frac{\alpha_H}{\alpha_L} - 1\right)(\mu_{hL}g_h)^{\frac{1}{\alpha_L}} + 1\right) - \log\left(\frac{\alpha_H}{\alpha_L}\right), \\ h_{HL} - h_{HL}^* &= -\frac{\alpha_H}{\lambda_h} \log\left(\frac{\alpha_L(\mu_{hL}g_h)^{-\frac{1}{\alpha_L}} + \alpha_H - \alpha_L}{\alpha_H(\mu_{hL}g_h)^{-\frac{1}{\alpha_H}}}\right). \end{aligned}$$

Take derivatives on g_h , I can get:

$$dh_{HL} = \frac{1}{\lambda_h} \frac{(\alpha_H - \alpha_L)l_L}{(1 - l_L)\alpha_H + l_L\alpha_L} d\log g_h.$$

Appendix C Calibration

To calibrate the parameters internally, I need to find the relevant moments. Discount rate ρ can be calibrated using the long-run interest rate and growth rate:

$$r = \rho + \theta g.$$

Patent share η is calibrated using the ratio of R&D investment and GDP:

$$\frac{W_H(\epsilon_N + \epsilon_I)}{Y} = \left(\frac{W_H}{Y}\right)^{\frac{\lambda}{\lambda-1}} \left(\left(\frac{1}{\lambda} \frac{\mu_N}{p_N}\right)^{\frac{1}{\lambda-1}} + \left(\frac{1}{\lambda} \frac{\mu_I}{p_I}\right)^{\frac{1}{\lambda-1}} \right) \propto \eta^{\frac{1}{1-\lambda}}.$$

Cost of innovation needs to set to match the innovation growth rate:

$$g_N = \left(\frac{1}{\mu_N}\right)^{\frac{1}{1-\lambda}} \left(\frac{\lambda P_N}{W_H}\right)^{\frac{\lambda}{1-\lambda}} \propto \left(\frac{1}{\mu_N}\right)^{\frac{1}{1-\lambda}}.$$

Capital productivity A and cost of automation are calibrated using short run interest rate and capital share:

$$R = AH \left(\frac{s_K}{1-\eta} \right)^{\frac{1}{1-\sigma}} \propto A,$$

$$\frac{P_I}{P_N} = \left(\frac{\mu_I}{\mu_N} \right)^{\frac{1}{\lambda}} \propto \mu_I^{\frac{1}{\lambda}}.$$

Skill comparative advantage B_H and training cost elasticity λ_h is calibrated using wage premium in 1980 and 2005:

$$\omega = \left(\frac{\Gamma_H}{\Gamma_L} \right)^{\frac{\hat{\sigma}-1}{\hat{\sigma}}},$$

$$d \ln \omega = (B - B_L) d\tilde{S} + b d h_{HL},$$

$$d h_{HL} = \frac{1}{\lambda_h} \frac{(1 - \frac{\alpha_L}{\alpha_H}) l_L}{1 - (1 - \frac{\alpha_L}{\alpha_H}) l_L} d \log(g_h) \propto \frac{1}{\lambda_h}.$$

Training law of motion α_H and α_L are calibrated using the change of training time:

$$d \log(1 - l_H) = \frac{1}{(1 - l_L) \alpha_H + l_L \alpha_L} d \log(g_h),$$

$$d \log(1 - l_L) = \frac{1}{\alpha_L} d \log(g_h).$$

Size of technology wave is calibrated to match the change of labor share:

$$\frac{P_I}{P_N} = \left(\frac{\mu_I}{\mu_N} \right)^{\frac{1}{\lambda}} \propto \mu_I^{\frac{1}{\lambda}}.$$

Appendix D Transition Path Algorithm

To solve the transition path numerically between two balanced growth path. I firstly solve the BGP before and after political or technological shock, and use them as the starting and end point.

- (1) Start with the initial guess of capital stock $\{k_0(t)\}$, labor supply $\{L_{H0}(t), L_{L0}(t)\}$, automation level $\{\tilde{I}_0(t)\}$, human capital gap $\{h_{HL0}(t)\}$ and growth rates $\{g_{N0}(t), g_{hH0}(t), g_{hL0}(t)\}$.
- (2) By solving firm's problem, I can get prices $\{r(t), \omega_H(t), \omega_L(t)\}$, capital and labor share $\{s_K(t), s_H(t), s_L(t)\}$:

$$\begin{aligned}
r &= A\Gamma_K \left(\frac{(1-\eta)y}{A\Gamma_K k} \right)^{\frac{1}{\sigma}} - \delta \\
\omega_H &= A\tilde{\Gamma}_H \left(\frac{(1-\eta)y}{A\tilde{\Gamma}_H L_H} \right)^{\frac{1}{\sigma}} \\
\omega_L &= A \frac{\tilde{\Gamma}_L}{\gamma_{HL}} \left(\frac{(1-\eta)y}{A \frac{\tilde{\Gamma}_L}{\gamma_{HL}} L_L} \right)^{\frac{1}{\sigma}} \\
s_K &= (1-\eta) \left(\frac{R}{A\Gamma_K} \right)^{1-\hat{\sigma}} \\
s_H &= (1-\eta) \left(\frac{\omega_H}{A\tilde{\Gamma}_H} \right)^{1-\hat{\sigma}} \\
s_L &= (1-\eta) \left(\frac{\omega_L}{A \frac{\tilde{\Gamma}_L}{\gamma_{HL}}} \right)^{1-\hat{\sigma}}
\end{aligned}$$

and task allocation $\{\tilde{S}(t)\}$:

$$\frac{\omega_H}{\gamma_H(h_L, S)} = \frac{\omega_L}{\gamma_L(h_L, S)}$$

- (3) Given factor prices $\{r(t), \omega_H(t), \omega_L(t)\}$ and growth rates $\{g_{N0}(t), g_{hH0}(t), g_{hL0}(t)\}$, I can solve consumption $\{c_H(t), c_L(t)\}$ and capital $\{k_H(t), k_L(t)\}$ by solving household's problem:

$$\begin{aligned}
g &= B_H g_{N0} + b g_{hH0} \\
\frac{\dot{c}_H}{c_H} &= \frac{\dot{c}_L}{c_L} = \frac{r - \rho}{\theta} - g \\
\dot{k}_H &= (r - g)k_H + \omega_H L_H + \pi - c_H \\
\dot{k}_L &= (r - g)k_L + \omega_L L_L - c_L
\end{aligned}$$

then solve the new capital stock $\{k_1(t)\}$:

$$\dot{k} = \dot{k}_H + \dot{k}_L$$

- (4) Given factor prices $\{r(t), \omega_H(t), \omega_L(t)\}$ and growth rates $\{g_{N0}(t), g_{hH0}(t), g_{hL0}(t)\}$, I can solve the patent value of R&D sector:

$$\begin{aligned}
p_N &= (1 - \tau_N)v_N(N) - (1 - \tau_I)v_I \\
p_I &= (1 - \tau_I)v_I - (1 - \tau_N)v_N(I)
\end{aligned}$$

Where V_{NH} , V_{NL} and V_I can be solved recursively given factor prices and growth rates.

- (5) Given factor prices $\{r(t), \omega_H(t), \omega_L(t)\}$, patent value $\{p_N(t), p_I(t)\}$ I can solve human capital investment $\{g_{hH}(t), g_{hL}(t)\}$ using HH's problem:

$$\begin{aligned}\frac{b}{\mu_{hH}} \alpha_H l_H (1 - l_H)^{\alpha_H - 1} + b g_{hH} + g_{WH} &= (1 + \tau_{hH}) r \\ \frac{b}{\mu_{hL}} \alpha_L l_L (1 - l_L)^{\alpha_L - 1} + b g_{hL} + g_{WL} &= (1 + \tau_{hL}) r\end{aligned}$$

and growth rates $\{g_{N1}(t), g_{I1}(t)\}$ and labor supply $\{L_{H1}(t), L_{L1}(t)\}$ using research sector's problem:

$$\begin{aligned}\frac{p_N}{\mu_N} &= \frac{\omega_H}{y} \\ \frac{p_I}{\mu_I} &= \frac{\omega_H}{y} \\ L_H &= \epsilon_H l_H - \mu_N g_N - \mu_I g_I \\ L_L &= \epsilon_L l_L\end{aligned}$$

- (6) Given growth rate $\{g_{N1}(t), g_{I1}(t), g_{hH1}(t), g_{hL1}(t)\}$, I can solve the new automation level $\{\tilde{I}_1(t)\}$ and human capital gap $\{h_{HL1}(t)\}$ using the law of motion:

$$\begin{aligned}\dot{\tilde{I}} &= g_I - g_N \\ \dot{h}_{HL} &= b(g_{hH} - g_{hL})\end{aligned}$$

- (7) Update capital stock $\{k_0(t)\}$, labor supply $\{L_{H0}(t), L_{L0}(t)\}$, automation level $\{\tilde{I}_0(t)\}$, human capital gap $\{h_{HL0}(t)\}$ and growth rates $\{g_{N0}(t), g_{hH0}(t), g_{hL0}(t)\}$, and go back to 2 until converges.