

Determinants

Lecture 11

Computing Determinants comes up frequently

Numerous calculations can be phrased as matrix determinant calculations

Eigenvalues

Resultants

Solution of linear systems

This doesn't mean you *SHOULD* compute these by determinants necessarily...

Sparse Matrices

A **numerical** matrix of size $n \times m$ is sparse if it has $k \ll mn$ non-zero terms.

A **symbolic** matrix could either be numerically sparse or could have many terms where each term is a sparse polynomial.

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$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ a_{3,1} & a_{3,2} & a_{3,3} & a_{3,4} \end{pmatrix}$$

How large is a sparse NxN determinant?

$N!$ terms. Each term is size N .

For example, the generic 3×3 matrix has

$$\text{determinant } a_{1,1}a_{2,2}a_{3,3} - a_{1,2}a_{2,1}a_{3,3} - \\ a_{1,1}a_{2,3}a_{3,2} + a_{1,3}a_{2,1}a_{3,2} + a_{1,2}a_{2,3}a_{3,1} - a_{1,3}a_{2,2}a_{3,1}.$$

with, as expected, six terms

How large is a sparse NxN determinant?

and since we are using a computer to generate this, we can show you the 24 terms of the 4x4 determinant:

$$\begin{aligned} & a_{1,1}a_{2,2}a_{3,3}a_{4,4} - a_{1,2}a_{2,1}a_{3,3}a_{4,4} - a_{1,1}a_{2,3}a_{3,2}a_{4,4} + a_{1,3}a_{2,1}a_{3,2}a_{4,4} + a_{1,2}a_{2,3}a_{3,1}a_{4,4} - \\ & a_{1,3}a_{2,2}a_{3,1}a_{4,4} - a_{1,1}a_{2,2}a_{3,4}a_{4,3} + a_{1,2}a_{2,1}a_{3,4}a_{4,3} + a_{1,1}a_{2,4}a_{3,2}a_{4,3} - a_{1,4}a_{2,1}a_{3,2}a_{4,3} - \\ & a_{1,2}a_{2,4}a_{3,1}a_{4,3} + a_{1,4}a_{2,2}a_{3,1}a_{4,3} + a_{1,1}a_{2,3}a_{3,4}a_{4,2} - a_{1,3}a_{2,1}a_{3,4}a_{4,2} - \\ & a_{1,1}a_{2,4}a_{3,3}a_{4,2} + a_{1,4}a_{2,1}a_{3,3}a_{4,2} + a_{1,3}a_{2,4}a_{3,1}a_{4,2} - a_{1,4}a_{2,3}a_{3,1}a_{4,2} - \\ & a_{1,2}a_{2,3}a_{3,4}a_{4,1} + a_{1,3}a_{2,2}a_{3,4}a_{4,1} + a_{1,2}a_{2,4}a_{3,3}a_{4,1} - a_{1,4}a_{2,2}a_{3,3}a_{4,1} - \\ & a_{1,3}a_{2,4}a_{3,2}a_{4,1} + a_{1,4}a_{2,3}a_{3,2}a_{4,1} \end{aligned}$$

typeset kind of peculiarly, but not too bad.

This is actually a sum over all permutations of the indices X a coefficient which is the "sign" of the permutation

As happens with many facts about determinants, you should be able to prove that this determinant has $N!$ terms a few different ways. Here's another...

How large is a sparse NxN determinant?

Here are the 24 terms of the 4x4 determinant expanded in minors around the first row:

$$\begin{aligned} & a_{1,1}(a_{2,2}(a_{3,3}a_{4,4}-a_{3,4}a_{4,3})-a_{2,3}(a_{3,2}a_{4,4}-a_{3,4}a_{4,2})+a_{2,4}(a_{3,2}a_{4,3}-a_{3,3}a_{4,2}))-a_{1,2} \\ & (a_{2,1}(a_{3,3}a_{4,4}-a_{3,4}a_{4,3})-a_{2,3}(a_{3,1}a_{4,4}-a_{3,4}a_{4,1})+a_{2,4}(a_{3,1}a_{4,3}-a_{3,3}a_{4,1}))+a_{1,3}(a_{2,1} \\ & (a_{3,2}a_{4,4}-a_{3,4}a_{4,2})-a_{2,2}(a_{3,1}a_{4,4}-a_{3,4}a_{4,1})+a_{2,4}(a_{3,1}a_{4,2}-a_{3,2}a_{4,1}))-a_{1,4}(a_{2,1}(a_{3,2}a_{4,3}-a_{3,3}a_{4,2})- \\ & a_{2,2}(a_{3,1}a_{4,3}-a_{3,3}a_{4,1})+a_{2,3}(a_{3,1}a_{4,2}-a_{3,2}a_{4,1})) \end{aligned}$$

Which also gives us another proof there are $N!$ terms.

Looking around for on-line summaries of the many useful and elementary properties of the determinant, I found this:

<http://mathworld.wolfram.com/Determinant.html>

$N*N!$ vs $O(1)$.

The size of any numerical (floating point) determinant of any size is a constant (one fp number).

Are there intermediate positions and complexities? How best to compute symbolic determinants? Note that *SOME* symbolic determinants will be small (even zero!)

One of my favorite papers is

M. Gentleman and S. Johnson,
*Analysis of Algorithms, A Case Study: Determinants of
Matrices with Polynomial Entries*

ACM Transactions on Mathematical Software (TOMS)

Volume 2 , Issue 3 (September 1976)

[DOI] <http://doi.acm.org/10.1145/355694.355696>
gentleman.pdf

Two models

All elements distinct symbols (the model already discussed).

All elements are univariate polynomials dense to the same degree.

Two distinct algorithms: Gaussian elimination

The Gaussian elimination method, using exact division, is appropriate for computations over the integers; **If we ignore pivoting**, the algorithm consists of $n - 1$ steps, indexed by a variable k running from 1 to $n - 1$. The k^{th} step involves the computation of an $n - k + 1$ by $n - k + 1$ matrix, which we shall call $A^{(k+1)}$; the entries will be denoted $a_{ij}^{(k+1)}$ with $k + 1 \leq i, j \leq n$. The original matrix is identified with $A^{(1)}$.

For each k , the entry $a_{ij}^{(k+1)}$ is computed by the formula

$$a_{ij}^{(k+1)} = (a_{kk}^{(k)} a_{ij}^{(k)} - a_{ik}^{(k)} a_{kj}^{(k)}) / a_{k+1, k+1}^{(k)}$$

for $k + 1 \leq i, j \leq n$, where $A^{(0)}$ is taken to be 1. The division is always exact, so each $a_{ij}^{(k)}$ is a polynomial and $a_{nn}^{(n)}$ is the determinant of $A^{(n)}$

Cost of Gaussian elimination / I

An analysis of this algorithm shows that each $a^{(k)}$ is a determinant (minor) of some k -by- k submatrix of the original matrix. Since we assumed all entries in the original matrix to be of the same size, we may expect that all elements in $A^{(k)}$, for a given i , are the same size.

Cost of Gaussian elimination / II

To compute $a_{ij}^{(k)}$ takes two multiplications, a subtraction, and a division. In general, the cost of multiplying two polynomials will depend on their size; in our situation the size is assumed to depend only on the order of the minor making up the element. Thus we shall use numbers C_{rs} to compute the cost of our algorithm, C_{rs} is the cost of multiplying a minor of order r by a minor of order s . Notice that $C_{1,1}$ is the cost of multiplying two elements from the original matrix. We assume also that an exact division of A by B to yield C has the same cost as a multiplication of B by C , and we ignore the costs of addition and subtraction.

We can now write the cost for Gaussian elimination in terms of the C_{rs} . To compute $a_{ij}^{(k+1)}$ requires two multiplications of cost C_{kk} , a division of cost $C_{k-1,k+1}$, and a subtraction whose cost we do not count. There are, for a given k , $(n-k)^2$ elements $a_{ij}^{(k+1)}$; so the total cost for the Gaussian elimination is

$$G = \sum_{k=1}^{n-1} (n-k)^2 (2C_{kk} + C_{k-1,k+1}).$$

Cost of Gaussian elimination / II

Note that, when $C_{rs} = 1$ for all r and s , representing the familiar floating-point or fixed-length integer case, the cost becomes

$$G = 3 \sum_{k=1}^{n-1} (n-k)^2 = n^3 - \frac{3}{2}n^2 + \frac{1}{2}n.$$

Cost of Expansion by Minors

$$\begin{aligned} M &= \sum_{k=2}^n \binom{n}{k} k C_{k-1,1} = n \sum_{k=2}^n \frac{(n-1)!}{(k-1)!(n-k)!} C_{k-1,1} = n \sum_{k=2}^n \binom{n-1}{k-1} C_{k-1,1} \\ &= n \sum_{k=1}^{n-1} \binom{n-1}{k} C_{k1}. \end{aligned}$$

Once again, we examine the cost when each C_{rs} is 1; we have

$$M = n \sum_{k=1}^{n-1} \binom{n-1}{k} = n(2^{n-1} - 1).$$

this goes a long way toward explaining why numerical analysts don't do this.