

# Closed Forms for Summations

## Lecture 19

# Two categories (maybe 3) of Summations

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- Indefinite summation:
  - $\sum_{1 \leq i \leq n} f(i)$ ;  $f$  not dependent on  $n$   
 $f$  dependent on  $n$
  - finite difference calculus has a long history: initial work done by Newton, Euler, Bernoulli, Boole.

Definite summation (particular solutions): Zeilberger, Gosper, Ramanujan, et al

- The Book  **$A=B$**  by Petkovsek, Wilf, Zeilberger)
- Online at <http://www.cis.upenn.edu/~wilf/AeqB.html>

# Indefinite summation parallels to integration

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- integration of polynomials
  - integration of rational functions
  - difference operator  $\Delta$  parallels the derivative
  - $\Sigma$  and  $s$  are similar
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- But not similar enough for some purposes!

## Some simple examples (Macsyma, in this case)

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$$\sum_{i=1}^n i = \frac{n(n+1)}{2}$$

$$\sum_{i=1}^n \frac{i}{2^i} = -\frac{n}{2^n} - \frac{2}{2^n} + 2$$

# A more elaborate example

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$$\sum_{n=0}^n \frac{n^4 4^n}{\binom{2n}{n}} = \frac{2(n+1)(63n^4 + 112n^3 + 18n^2 - 22n + 3)4^n}{693\binom{2n}{n}} - \frac{2}{231}$$

# Start simply

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- if we need  $g(n) = \sum_{i=a}^n f(i)$  we approach by finding the *indefinite summation*

$$h(x) = \sum_{i=0}^{x-1} f(i)$$

Then we can find the *definite summation* from  $a$  to  $n$ :

$$g(n) = h(n+1) - h(a).$$

Sidestepping any issues of singularities.

Note that this means  $\text{sum from } a \text{ to } b + \text{sum from } b+1 \text{ to } c = \text{sum from } a \text{ to } c$ , even if  $a < b < c$  is false..

$\Delta h(x)$  is defined by  $h(x+1) - h(x)$ , is  $f(x)$

## Also

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- $\Delta^{-1} f(x) = h(x)$ , and as a reminder, note that
$$h(x) = \sum_{i=0}^{x-1} f(i)$$
- Note parallel: we can obtain an expression for the summation by anti-differencing; compare to integration by anti-differentiation.

# Simple Properties of $\Delta$

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- Unique up to addition of functions whose first difference is zero
  - Constants, since  $h(x) := C$  means  $h(x+1) - h(x) = 0$
  - functions with period 1, e.g.  $h(x) := \sin(\pi x)$



It is also convenient to define shift operator,  $E$

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- $E f(x) := f(x+1)$
- hence
  - $\Delta f(x) = Ef(x) - f(x)$

$$\Delta(f \circ g) = E g \circ \Delta f + f \Delta g$$


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Proof that  $\Delta(f \circ g) = E g \circ \Delta f + f \Delta g$

Expand the right side,

$$g(x+1) * (f(x+1) - f(x)) + f(x) * (g(x+1) - g(x))$$

.. Multiply out..

$$g(x+1) * f(x+1) - \underline{g(x+1) * f(x)} + \underline{f(x) * g(x+1)} - f(x) * g(x)$$

.. The underlined terms cancel, leaving

$$f(x+1) * g(x+1) - f(x) * g(x),$$

Which is  $\Delta (f(x) \circ g(x))$ .

QED

$$\Delta(1/g) = \Delta g / (g \text{ E } g)$$

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Proof that  $\Delta(1/g) = \Delta g / (g \text{ E } g)$

Expand the right side,

$1/g(x+1) - 1/g(x)$ , combine over common denominator:

$$(g(x+1) - g(x)) / (g(x) * g(x+1))$$

Which corresponds to

$$\Delta g / (g \text{ E } g)$$

QED

# Summary of properties of $\Delta$

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$$\Delta k f(x) = k \Delta f(x) \quad k \in F$$

$$\Delta(g(x) + f(x)) = \Delta g(x) + \Delta f(x)$$

$$\Delta(f(x) \cdot g(x)) = E g(x) \cdot \Delta f(x) + f(x) \cdot \Delta g(x)$$

$$\Delta \left( \frac{1}{g(x)} \right) = - \frac{\Delta g(x)}{g(x) E g(x)}$$

$$\Delta \left( \frac{f(x)}{g(x)} \right) = - \frac{f(x) \Delta g(x) + g(x) \Delta f(x)}{g(x) E g(x)}$$

# Occasionally useful property

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- The chain rule

- $\Delta_1 f(g(x)) = \Delta_{g(x)} f(x)$

- where  $\Delta_h f(x) = f(x+h) - f(x)$

# Proof...

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- The chain rule

$$\bullet \quad \underset{1}{\Delta} f(g(x)) = \underset{\Delta g(x)}{\overset{g(x)}{\Delta}} f(x)$$

$f(g(x+1))-f(g(x))$  on left

$f(g(x)+\Delta g(x))-f(g(x))$  on right =

$f(g(x)+g(x+1)-g(x))-f(g(x))\dots$  QED

# The simplest non-trivial form to sum is a polynomial

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- $A(x) = \sum a_i x^i$
- The analogy to differential calculus is to integrate, term by term:
  - easy since  $Dx^n = nx^{n-1}$ .
- Differences of powers are not so concise:  
 $\Delta(x^n) = (x+1)^n - x^n = \sum (\text{binomial}(n,i) x^i, i=0..n-1) \dots$   
has  $n-1$  terms.

INSTEAD consider *factorial functions*, defined by

$$[x]_n = x(x-1)(x-2)\dots(x-n+1).$$

# What is the difference of a factorial function?

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- $\Delta [x]_n = n[x]_{n-1}$

- Proof:

$$\Delta [x]_n = E[x]_n - [x]_n .$$

$$E[x]_n = (x+1)x(x-1)(x-2)\dots (x-n+2)$$

$$[x]_n = x(x-1)(x-2)\dots (x-n+2)(x-n+1).$$

All the terms in red are the same, and one can factor them out. they are  $[x]_{n-1}$ . The remaining factor is simply  $(x+1)-(x-n+1) = n$ .

- The product is  $n[x]_{n-1}$  . QED



## To sum a polynomial of degree $d$ , convert it to factorial form:

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- one way is to set up a table by which we expand  $d$  factorial functions  $[x]_1 = x$ ,  $[x]_2 = x^2 - x$ , etc, solve for powers of  $x$ , e.g.  $x^2 = [x]_2 + [x]_1$ , and we can substitute into any polynomial, collect  $[]$  terms and provide the result.
- Another is to use Newton's *divided difference interpolation formula*, which as a special case gives:
- $f(x) = \sum ([x]_i / i! \Delta^i f(0))$  where we mean by  $\Delta f(0)$ , is  $\Delta f(x)$  where  $x=0$ . We define higher differences in the obvious way:  $(\Delta^2 f(0) = \Delta (\Delta f(0)) = \Delta (f(1) - f(0)) = \Delta (f(2) - f(1) - (f(1) - f(0))) = f(2) - 2f(1) + f(0))$ . ) This is almost always written in a table.

## Divided difference table for $f = 3x^3 - 2x + 1$

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$x$	$f(x)$	$\Delta f(x)$	$\Delta^2 f(x)$	$\Delta^3 f(x)$
0	1	1	18	18
1	2	19	36	
2	21	55		
3	76			

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$$\Delta^{-1} f = \sum ([x]_i / i! \Delta^i f(0)) = 1 * [x]_1 + 1/2 * [x]_2 + 18/3! * [x]_3 + 18/4! * [x]_4 .$$

Converting BACK to conventional polynomial form can be done by expanding  $[x]_i$  and combining terms

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Total is  $1 \cdot x$

$+1/2 \cdot x \cdot (x-1)$

$+18/3! \cdot x \cdot (x-1) \cdot (x-2)$

$+18/4! \cdot x \cdot (x-1) \cdot (x-2) \cdot (x-3) =$

$$\frac{3x^4}{4} - \frac{3x^3}{2} - \frac{x^2}{4} + 2x$$

# Sums of rational functions

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- Define factorial operators on functions...
- $[f(x)]_k = f(x) \cdot f(x-1) \cdot \dots \cdot f(x-k+1)$  for  $k > 0$
- extend the operator by noticing
- $[f(x)]_k = [f(x)]_r \cdot [f(x-r)]_{k-r}$
- Define  $[f(x)]_0$  to be 1 and use the previous line as an identity. Then for  $k=0$  we get
- $[f(x)]_{-r} = 1/[f(x+r)]_r$

# Differences of factorials

$$(11) \quad [f(x)]_{-\ell} = \frac{1}{[f(x+\ell)]_{\ell}}$$

We will call the value of  $k$  or  $\ell$  in equations 9 and 11, the factorial degree of function, because of its parallel to the "power" degree. We now proceed to examine the differences of factorials.

$$(12) \quad \Delta[f(x)]_k = [f(x)]_{k-1} \triangle_k f(x-k+1), \quad k > 0.$$

A special case of this is eq. 5 for factorial polynomials.

$$(13) \quad \Delta[f(x)]_{-\ell} = -[f(x)]_{-(\ell+1)} \triangle_{\ell} Ef(x)$$

$$= \frac{\triangle_{\ell} Ef(x)}{[f(x+\ell+1)]_{\ell+1}}$$

Notice that the factorial degree is decreased (resp. increased) by 1 on differencing factorials (resp. reciprocal factorials).

*R. Moenck, Macsyma Users' Conf. 1977*

## What does this mean for summation ( $\Delta^{-1}$ )?

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- If we can get rational expressions so they look like the RHS of that equation, we can find their summation, namely  $[f(x)]_{-l}$

We need to use Shift Free Decomposition to go further.

Given a product of functions, we can decompose it into a product of factorial functions.

Let  $S = a \circ b \circ c$  where  $a, b, c$  are mutually relatively prime and  $Ea = b$ . Then shift  $S$ :

$$ES = (Ea) \circ (Eb) \circ (Ec) = b \circ Eb \circ Ec$$

$$\text{GCD}(S, ES) = b$$

So we can divide out  $b$  and  $a$  from  $S$  and express  $S = [b]_2 \circ c$ .



If we apply this observation repeatedly, we can get  $S$  to be shift free

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- $S = [s_1]_1 \text{ } \textcircled{+} \text{ } [s_2]_2 \text{ } \textcircled{+} \text{ } \dots \text{ } \textcircled{+} \text{ } [s_k]_k$  where the individual  $s_k$  are shift-free.
- Analogous to partial fraction decomposition in the differential calculus Hermite integration process, we can form a shift-free partial fraction for some rational function we wish to sum. That is,
- $A(x)/S(x) = \sum (A_i/[s_i]_i), i=1..k$
- and a "complete" decomposition
- $A(x)/S(x) = \sum \sum (A_{ij}/[s_i]_j), i=1..k, j=1..i$

**Shift-1 independence is not enough. We need to show  $S(x)$  is  $k$ -shift-free**

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- Compute resultant of  $S(x)$  and  $S(x+k)$  with respect to  $k$ . If there is an integer  $k > 1$  shift, then fill in the terms for numerator and denominator. e.g. if  $S = x^*(x+3)$ , change it to  $[x+3]_4$  and multiply numerator by  $(x+1)(x+2)$ .

# Summation by parts

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- Similar to Hermite integration using

$$\Delta^{-1}(u \nabla v) = u \nabla v - \Delta^{-1}(E v \nabla u)$$

can be used to reduce denominators of the form

$$[x_i]_j \text{ to } [x_i]_1$$

- EVENTUALLY... one gets a rational function plus an indefinite summation of terms with shift-free denominators of factorial degree 1.

# The transcendental part

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- Define  $\psi_m(x) = D^m(\log \Gamma(x+1))$ ,  $m > 0$  where  $n! = \Gamma(n+1)$  is the well-known gamma function

$$\Delta \psi_m(x) =$$

$$D^m(\Delta \log \Gamma(x+1)) =$$

$$D^m(\log(\Gamma(x+2)/\Gamma(x+1))) =$$

$$D^m \log(x+1) =$$

$$D^{m-1}(1/(x+1)) =$$

$$((-1)^{m-1} / (m-1)! (x+1)^{-m}.$$

# The sum of a negative power of $x+1$ finishes the task

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- $\Delta^{-1}(x+1)^{-m} = (-1)^{m-1}/(m-1)! \psi_m(x)$
- The  $\psi_m$  functions are known as polygamma functions and serve a role similar to logs in Hermite integration.
- Rational summation is pretty much solved, though people still look for fast ways of doing some of the steps (shift-free decomposition).

# This is not the end of the story: what about more elaborate summands?

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- Gosper's algorithm looks at  $\sum a_i = \Delta^{-1}a_i$  by seeking a "telescoping function"  $f(n)$ .
- Let  $a_n = \Delta g(n) = g(n+1)-g(n)$
- then suppose  $g(n)=f(n)*a_n$ .
- We have to solve the functional equation
- $C(n)=a_{n+1}/a_n = (f(n)+1)/f(n+1)$
- Only the ratio of 2 terms is used (easily computed).  
If  $C(n)$  is rational in  $n$ , then this is called hypergeometric summation.

# Restrictions/ Extensions

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- Note that the terms  $a_n$  can be far more general than rational; the requirement is on the RATIO:  $a_{n+1}/a_n$  is rational.
- Gosper's work is the basis for a decision procedure, widely used in computer algebra systems.
- Excellent reference:  $A=B$ , by Petkovsec, Wilf, Zeilberger