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PAPER Calculation of Tearing Mode Stability in a Magnetically Diverted Tokamak Plasma

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1 Two-Filament Model of a Magnetically Diverted Plasma

1.1 Introduction

The aim of this section is to construct a very simple model of a magnetically diverted tokamak plasma.

1.2 Equilibrium Magnetic Field

Suppose that two current filaments run parallel to the z -axis [1]. Let the first filament carry the current I_p , and pierce the x - y plane at $x = y = 0$. Let the second filament carry the current I_c , and pierce the x - y plane at $x = 0, y = -a$. Here, a is the effective minor radius of the plasma. The first filament represents the “toroidal” (i.e., z -directed) plasma current, whereas the second represents the current flowing in the magnetic divertor coil. Suppose that there is a uniform externally generated “toroidal” (i.e., z -directed) magnetic field of strength B_0 . Let the system be periodic in the z direction with period $2\pi R_0$, where R_0 is the simulated major radius of the plasma. It is helpful to define the simulated toroidal angle, $\phi = z/R_0$.

The equilibrium magnetic field can be written in the divergence-free form

$$\mathbf{B} = \nabla\phi \times \nabla\psi_p + B_0 R_0 \nabla\phi, \quad (1)$$

where

$$\psi_p(x, y) = \frac{\mu_0 I_0 R_0}{4\pi} \ln(x^2 + y^2) + \frac{\mu_0 I_1 R_0}{4\pi} \ln[x^2 + (y + a)^2] \quad (2)$$

is the “poloidal” magnetic flux (divided by 2π) generated by the two current filaments.

1.3 Flux Coordinates

It is convenient to re-express the magnetic field as

$$\mathbf{B} = \nabla(\phi - q\theta) \times \nabla\psi_p, \quad (3)$$

where θ is a poloidal (i.e., in the x - y plane) angle, and $q = q(\psi_p)$ is the safety-factor [2]. Equations (1) and (3) can be reconciled provided

$$\nabla\psi_p \times \nabla\theta \cdot \nabla\phi = \frac{B_0}{R_0 q}. \quad (4)$$

Note, from Eq. (3), that $\mathbf{B} \cdot \nabla\psi_p = 0$, which implies that ψ_p is a magnetic flux-surface label. Furthermore, $\mathbf{B} \cdot \nabla(\phi - q\theta) = 0$, which implies that magnetic field-lines within a given flux-surface appear as straight lines, with gradient $d\phi/d\theta = q$, when plotted in the θ - ϕ plane. In fact, ψ_p, θ, ϕ are known as *flux-coordinates*, and θ is termed a “straight” poloidal angle [2].

1.4 Non-Diverted Edge Safety-Factor

In the absence of the divertor current, the plasma would have a circular cross-section of minor radius a , and an edge safety-factor of

$$q_* = \frac{2\pi B_0 a^2}{\mu_0 I_p R_0}. \quad (5)$$

1.5 Normalization Scheme

Let $x = aX$, $y = aY$, $\nabla = a^{-1}\hat{\nabla}$, and $\psi_p = \mu_0 I_p R_0 \psi / (2\pi)$. It follows that

$$\hat{\nabla}\psi \times \hat{\nabla}\theta \cdot \hat{\nabla}\phi = \frac{a}{R_0} \frac{q_*}{q}, \quad (6)$$

$$\psi = \frac{1}{2} \ln(X^2 + Y^2) + \frac{\beta}{2} \ln[X^2 + (Y+1)^2], \quad (7)$$

$$\psi_X = \frac{X}{X^2 + Y^2} + \frac{\beta X}{X^2 + (Y+1)^2}, \quad (8)$$

$$\psi_Y = \frac{Y}{X^2 + Y^2} + \frac{\beta(Y+1)}{X^2 + (Y+1)^2}, \quad (9)$$

where $\beta = I_c/I_p$. Here, $\psi_X \equiv \partial\psi/\partial X$, et cetera.

1.6 Magnetic X-point

The magnetic X-point forms at the point in the X - Y plane at which $\psi_X = \psi_Y = 0$. As is easily demonstrated, the coordinates of this point are (X_c, Y_c) , where $X_c = 0$ and $Y_c = -1/(1+\beta)$. The magnetic separatrix corresponds to the curve $\psi(X, Y) = \psi_c$, where

$$\psi_c \equiv \psi(X_c, Y_c) = \ln \left[\frac{\beta^\beta}{(1+\beta)^{1+\beta}} \right]. \quad (10)$$

It is helpful to define the normalized poloidal flux $\Psi = \psi_c/\psi$.

1.7 Construction of Flux Coordinate System

Equation (6) yields

$$\frac{d\theta}{dL} = \frac{q_*}{q |\hat{\nabla}\psi|}. \quad (11)$$

where $\hat{\nabla} = a\nabla$, and dL is an element of normalized length around a magnetic flux-surface. It follows that

$$q(\psi) = \frac{q_*}{2\pi} \oint \frac{dL}{|\hat{\nabla}\psi|}, \quad (12)$$

where \oint implies a complete circuit in θ at constant ψ . It is easily demonstrated that, on such a circuit,

$$\frac{dX}{dL} = -\frac{\psi_Y}{\sqrt{\psi_X^2 + \psi_Y^2}}, \quad (13)$$

$$\frac{dY}{dL} = \frac{\psi_X}{\sqrt{\psi_X^2 + \psi_Y^2}}, \quad (14)$$

$$\frac{d\phi}{dL} = \frac{q_*}{\sqrt{\psi_X^2 + \psi_Y^2}}, \quad (15)$$

$$\frac{d\omega}{dL} = \frac{X\psi_X + Y\psi_Y}{(X^2 + Y^2)\sqrt{\psi_X^2 + \psi_Y^2}}, \quad (16)$$

where

$$\omega = \tan^{-1} \left(\frac{Y}{X} \right) \quad (17)$$

is a geometric poloidal angle. Here, ϕ is calculated on the assumption that we are following a magnetic field-line within the flux-surface (i.e., $d\phi/d\theta = q$). We need to integrate Eqs. (13)–(16) from $\omega = 0$ to $\omega = 2\pi$, subject to the initial condition $\phi(\omega = 0) = 0$, and then set $q(\psi) = \phi(\omega = 2\pi)/(2\pi)$. We can then compute θ using

$$\frac{d\theta}{dL} = \frac{1}{q\sqrt{\psi_X^2 + \psi_Y^2}}. \quad (18)$$

1.8 Results

Let $q_* = 12$ and $\beta = 0.2$. Figure 1 shows the magnetic flux-surfaces $\Psi = 0.9$, $\Psi = 1.0$, and $\Psi = 1.1$, plotted in the X - Y plane. Flux-surfaces characterized by $\Psi < 1$ do not enclose the divertor current filament, whereas those characterized by $\Psi > 1$ do enclose the filament. The magnetic separatrix, $\Psi = 1$, separates flux-surfaces that do and do not enclose the divertor current filament, and crosses itself at the magnetic X-point.

Figure 2 shows the safety-factor profile $q(\Psi)$. It is clear that the safety-factor generally increases with increasing Ψ . However, $q \rightarrow \infty$ as $\Psi \rightarrow 1$. In other words, the safety-factor tends to infinity as the magnetic separatrix is approached. It is apparent from the bottom panel that q approaches infinity logarithmically as $\Psi \rightarrow 1$ (because the plot of q versus $\log_{10}(|\Psi - 1|)$ asymptotes to a straight line as $|\Psi - 1| \rightarrow 0$). In other words, close to the separatrix we can write

$$q(\Psi) \simeq -\alpha_- \log(1 - \Psi) \quad (19)$$

for $\Psi < 1$, and

$$q(\Psi) \simeq -\alpha_+ \log(\Psi - 1) \quad (20)$$

for $\Psi > 1$. Moreover, it is clear from the figure that $\alpha_+ > \alpha_-$.

Figures 3 and 4 show the flux coordinate system inside and outside the magnetic separatrix, respectively. It can be seen that, as the magnetic separatrix is crossed, all the contours of θ converge onto the X-point, and then diverge away from it. This singular behavior occurs because the Jacobian of the coordinate system, $\mathcal{J} \equiv (\hat{\nabla}\psi \times \hat{\nabla}\theta \cdot \hat{\nabla}\phi)^{-1} = (R_0/a)(q/q_*)$, is infinite at the X-point.

1.9 Significance of Flux Coordinates

To understand the significance of the flux coordinate system, suppose that the plasma is subject to a magnetic perturbation that varies with θ , ϕ and time, t , as $\exp[i(m\theta - n\phi) + \gamma t]$. Here, m and n are integers. In other words, the perturbation, which is, of course, single-valued in the angular coordinates θ and ϕ , possesses m periods in the poloidal angle and n periods in the toroidal angle. The scalar product of the curl of the linearized MHD Ohm's law yields

$$-\gamma b^{\psi_p} + i\gamma \frac{B_0}{R_0 q} (m - nq) \xi^{\psi_p} \simeq \frac{B_0}{R_0 q} i m \eta_{\parallel} j_{\phi}, \quad (21)$$

where subscripts and superscripts denote covariant and contravariant components in the ψ_p , θ , ϕ coordinate system. Here, \mathbf{b} is the perturbed magnetic field, $\boldsymbol{\xi}$ the plasma displacement, \mathbf{j} the perturbed current density, and η_{\parallel} the parallel plasma electrical resistivity.

The previous equation described how the inductive electric field generated by a time-varying magnetic field drives a current parallel to magnetic field-lines. On a general magnetic flux-surface, the first two terms on the left-hand side of the previous equation cancel one another out, and there is no driven current. In other words, the plasma displaces rather than allowing a parallel inductive current to flow. However, it is clear from the equation that there exist special magnetic flux-surfaces, termed *rational* flux-surfaces, at which the safety-factor takes the rational value $q = m/n$. On a rational flux-surface, the two terms on the left-hand side of the previous equation cannot cancel one another out, because the second term is zero. Hence, in general, a parallel inductive current flows on a rational flux-surface. The current is a shielding current that acts to suppress magnetic reconnection on the flux-surface, or, at least, to slow down reconnection such that it takes place on the comparatively long resistive timescale.

We can now appreciate that by employing a flux coordinate system we can distinguish rational magnetic flux-surfaces from irrational flux-surfaces. We can also calculate the angular variation of the particular magnetic perturbation that drives a shielding current at a particular rational surface. Note, finally, that it is clear from Figs. 2–4 that rational flux-surfaces exist both inside and outside the magnetic separatrix.

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Data availability

The digital data used in the figures in this paper can be obtained from the author upon reasonable request.

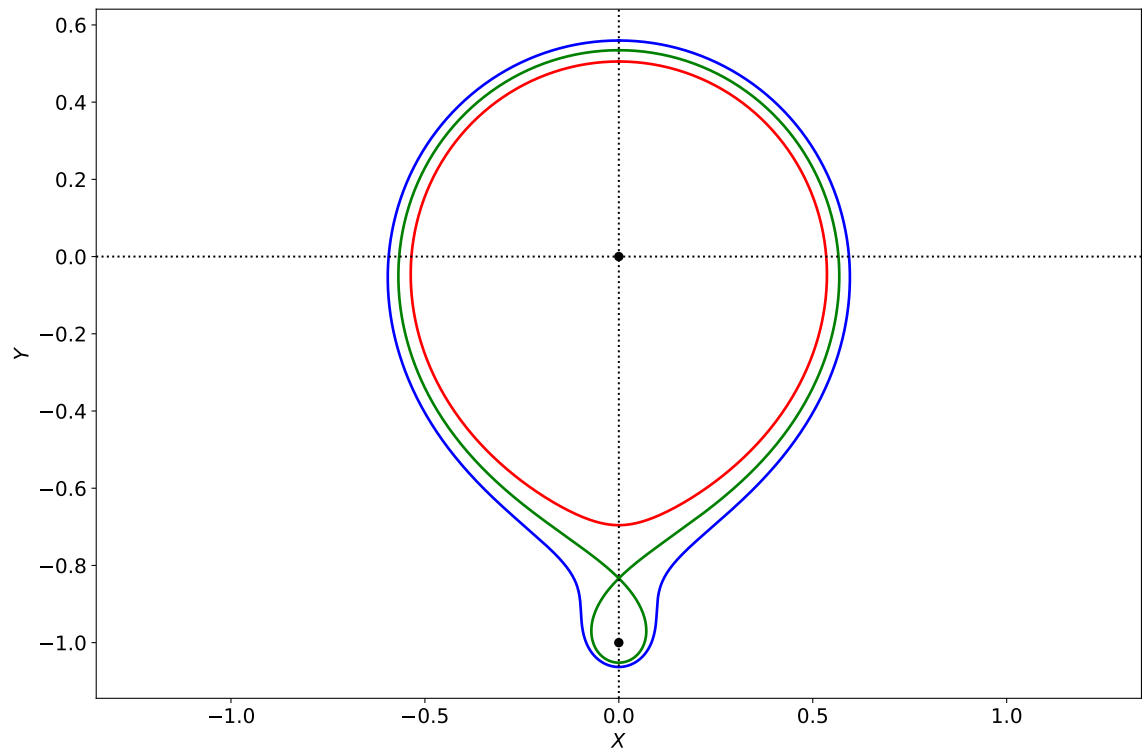


Figure 1. The magnetic flux-surfaces $\Psi = 0.9$ (red), $\Psi = 1.0$ (green), and $\Psi = 1.1$ (blue), plotted in the X - Y plane. The black dots shows the locations of the two current filaments. Here, $\beta = 0.2$.

References

- [1] N. Pomphrey and A. Reiman, *Phys. Fluids B* **4**, 938 (1992).
- [2] A.H. Boozer, *Rev. Mod. Phys.* **76**, 1071 (2004).

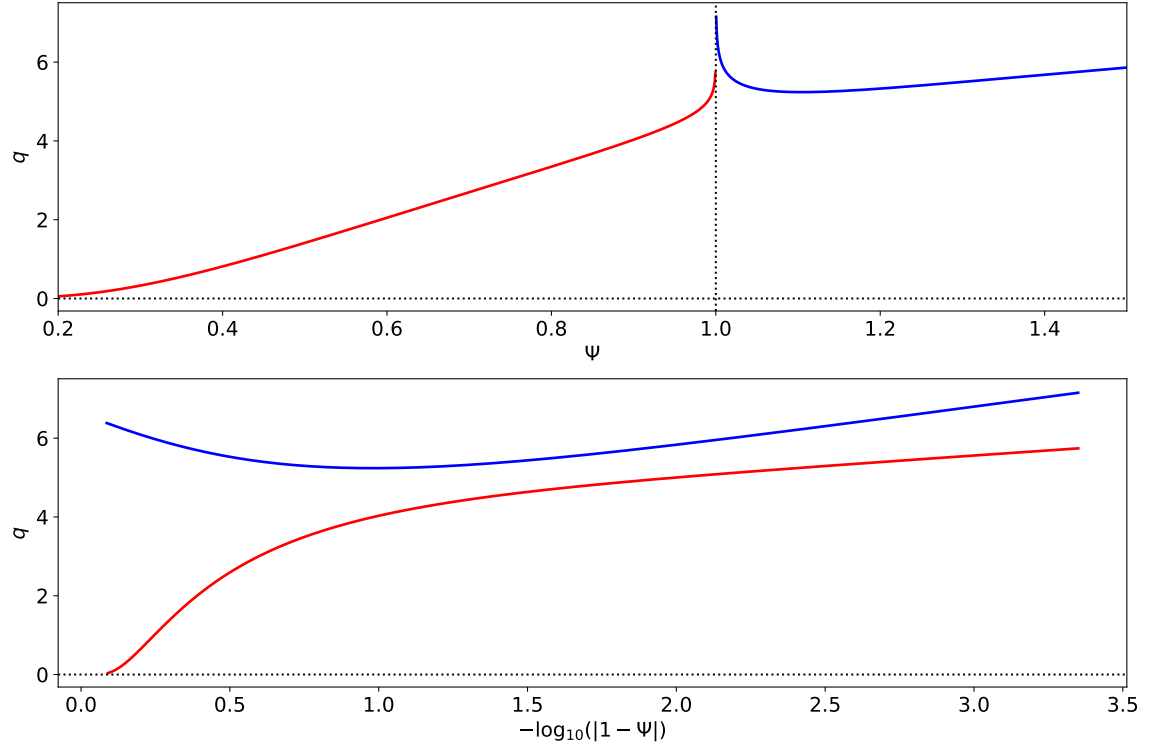


Figure 2. The safety-factor $q(\Psi)$ calculated for $q_* = 12$ and $\beta = 0.2$.

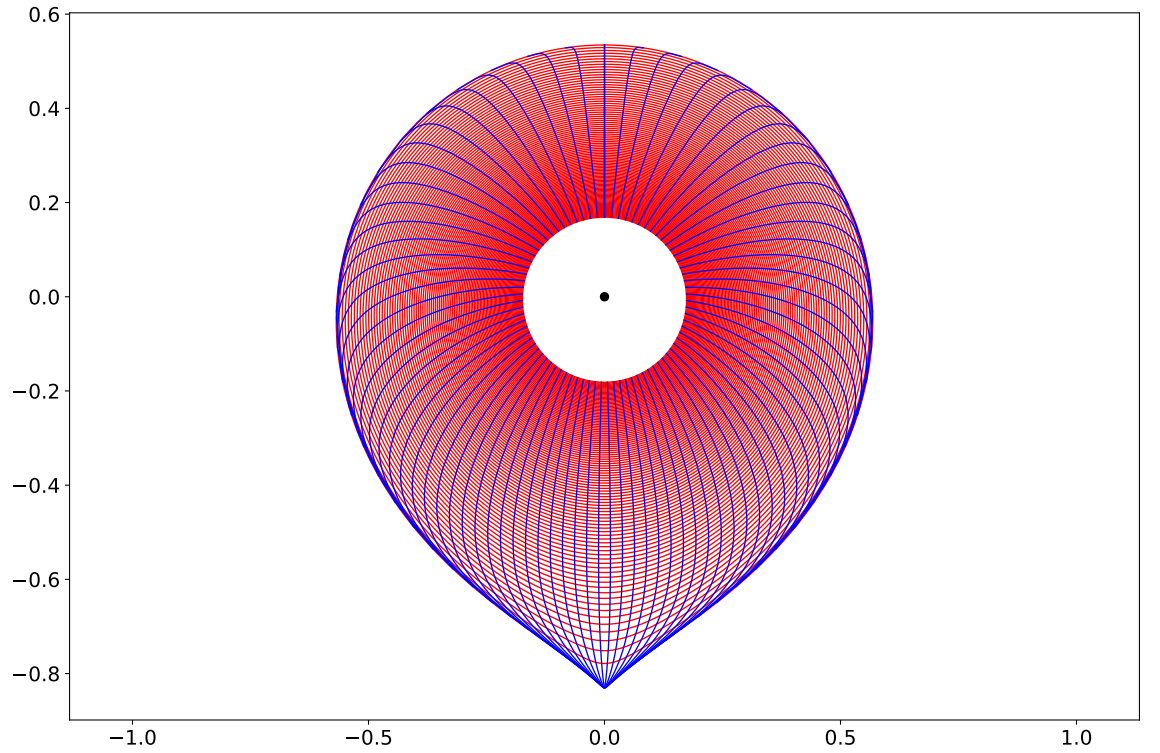


Figure 3. The flux coordinate system inside the magnetic separatrix calculated for $q_* = 12$ and $\beta = 0.2$. The red curves are surfaces of constant ψ , whereas the blue curves are surfaces of constant θ . The black dots shows the locations of the plasma current filaments.

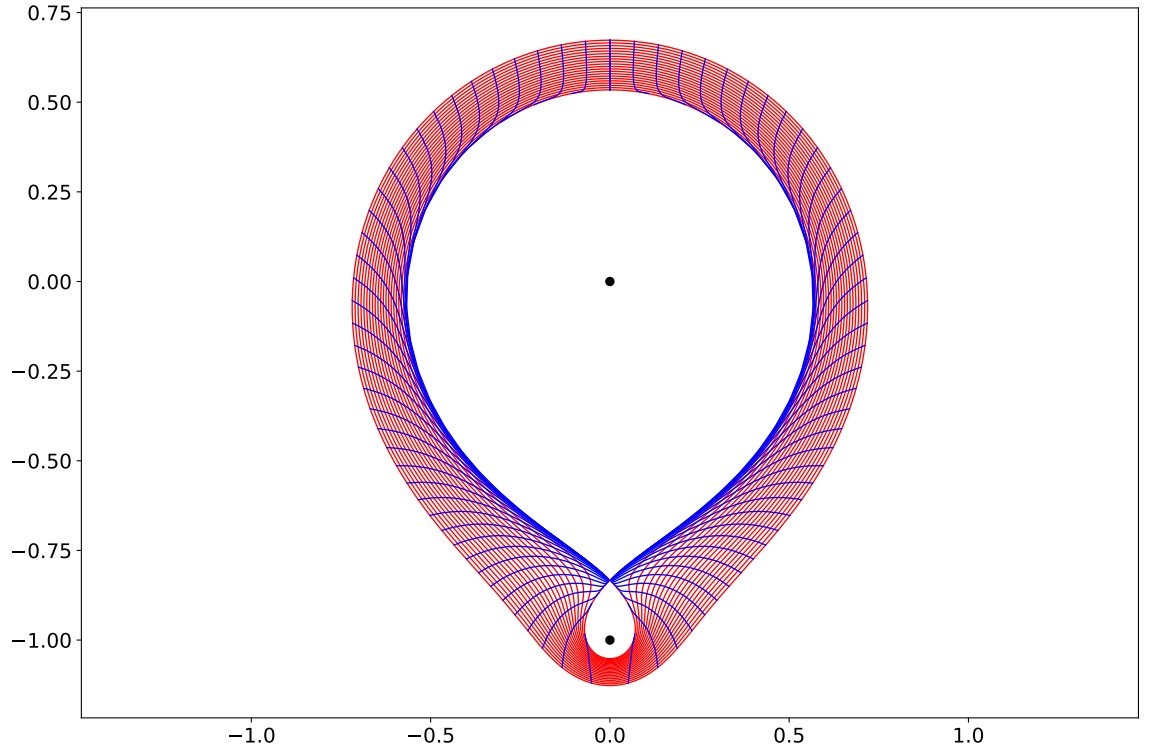


Figure 4. The flux coordinate system outside the magnetic separatrix calculated for $q_* = 12$ and $\beta = 0.2$. The red curves are surfaces of constant ψ , whereas the blue curves are surfaces of constant θ . The black dots show the locations of the two current filaments.

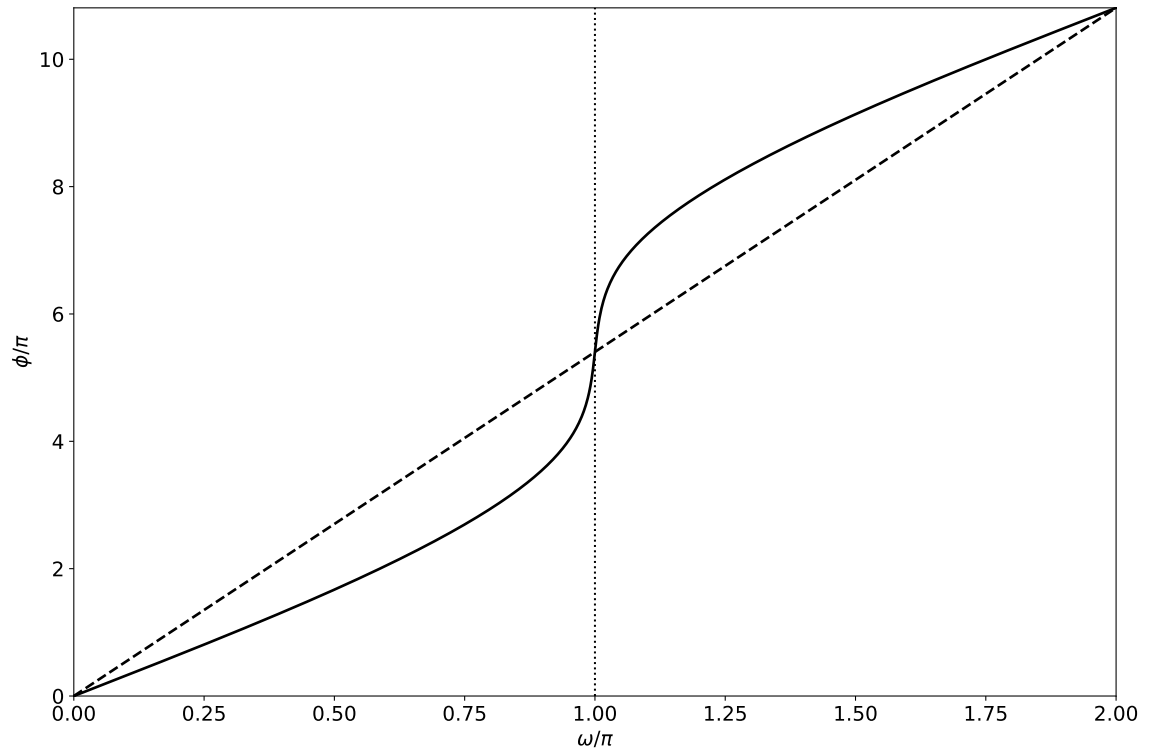


Figure 5. The variation of the toroidal angle, ϕ , with the geometric poloidal angle, ω , on a magnetic field-line lying within a magnetic flux-surface characterized by $\Psi = 0.999$, calculated with $q_* = 12$ and $\beta = 0.2$. The dashed line shows the mean gradient of the field-line.