# Using car Functions in Other Functions

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July 29, 2013

#### Abstract

The car package (Fox and Weisberg, 2011) provides many functions that are applied to a fitted regression model, perform additional calculations on the model or possibly compute a different model, and then return values and graphs. In some cases, users may wish to write functions that call functions in car for a particular purpose. Because of the scoping rules used in R, several functions in car that work when called from the command prompt may fail when called inside another function. We discuss how users can modify their programs to avoid this problem.

### 1 deltaMethod

The car package includes many functions that require an object created by a modeling function like lm, glm or nls as input. For a simple example, the function deltaMethod uses the delta method (Fox and Weisberg, 2011, Sec. 4.4.6) to estimate the value and standard error of a nonlinear combination of parameter estimates. For example

Here deltaMethod returns the standard error of the estimate of  $\beta_1/(\beta_2+2)$ , where  $\beta_j$  is the parameter corresponding to the regressor  $t_j$ . The code

also works as expected. The func argument uses gsub to get the right row labels.

Consider the function:

```
f1 <- function(mod) {
  ans <- NULL
  for (x in 1:4) {</pre>
```

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Error in eval(expr, envir, enclos) : object 'x' not found

Worse yet, if x is defined in the same environment as m1, this function gives the wrong answer:

```
x <- 10
f1(m1)
Estimate SE
t1/(t1+1) 0.4539 0.03881
t1/(t1+2) 0.4539 0.03881
t1/(t1+3) 0.4539 0.03881
t1/(t1+4) 0.4539 0.03881
```

The core of the problem is the way that R does scoping. The regression object  $\mathtt{m1}$  was created in the global environment, whereas the argument  $\mathtt{z}$  in the  $\mathtt{f1}$  function is created in the local environment of the function. The call to  $\mathtt{deltaMethod}$  is evaluated in the global environment where  $\mathtt{m1}$  is defined, leading to the error message if  $\mathtt{z}$  does not exist in the global environment, and to wrong answers if it does exist.

For deltaMethod, there is an additional argument constants that can be used to fix the problem:

```
f2 <- function(mod) {</pre>
  ans <- NULL
  for (x in 1:4) {
     ans \leftarrow rbind(ans, deltaMethod(mod, "t1/(t2 + x)",
         func = gsub("x", x, "t1/(t1+x)"), constants=list(x=x)))
  ans
  }
 f2(m1)
          Estimate
                        SE
t1/(t1+1)
             1.8000 0.1893
t1/(t1+2)
             1.3538 0.1333
t1/(t1+3)
            1.0849 0.1026
t1/(t1+4)
            0.9051 0.0832
```

The constants argument is a named list of quantities defined in the local function that are needed in the evaluation of deltaMethod.

### 2 ncvTest

The function ncvTest (Fox and Weisberg, 2011, Sec. 6.5.2) computes tests for non-constant variance in linear models as a function of the mean, the default, or any other linear function of regressors, even for regressors not part of the mean function. For example,

fits prestige as a linear function of education, and tests for nonconstant variance as a function of income, another regressor in the data set Prestige. Embedding this in a function fails:

```
f3 <- function(meanmod, dta, varmod) {
   m3 <- lm(meanmod, dta)
   ncvTest(m3, varmod)
   }
f3(prestige ~ education, Prestige, ~ income)
Error in is.data.frame(data) : object 'dta' not found</pre>
```

In this case the model m3 is defined in the environment of the function, and the argument dta is defined in the global environment, and is therefore invisible when ncvTest is called. A solution is to copy dta to the global environment.

```
f4 <- function(meanmod, dta, varmod) {
   assign(".dta", dta, envir=.GlobalEnv)
   m1 <- lm(meanmod, .dta)
   ans <- ncvTest(m1, varmod)
   remove(".dta", envir=.GlobalEnv)
   ans
   }
f4(prestige ~ education, Prestige, ~income)
Non-constant Variance Score Test
Variance formula: ~ income
Chisquare = 1.521   Df = 1   p = 0.2175</pre>
```

The assign function copies the dta argument to the global environment where ncvTest will be evaluated, and the remove function removes it before exiting the function. This is an inherently problematic strategy, because an object assigned in the global environment will replace an existing object of the same name. Consequently we renamed the dta argument .dta, with an initial period, but this is not a guarantee that there was no preexisting object with this name.

### 3 Boot

The Boot function in car provides a convenience front-end for the function boot in the boot package (Canty and Ripley, 2013; Fox and Weisberg, 2012). With no arguments beyond the name of a regression object and the number of replications R, Boot creates the proper arguments for boot for case resampling bootstraps, and returns the coefficient vector for each sample:

```
m1 <- lm(time ~ t1 + t2, Transact)</pre>
b1 <- Boot(m1, R=999)
 summary(b1)
              R original bootBias bootSE bootMed
                   144.37
                            5.6255 188.348
                                             149.33
(Intercept) 999
t1
            999
                     5.46
                            0.0360
                                      0.687
                                               5.52
            999
                     2.03 -0.0073
                                               2.03
                                      0.151
```

The returned object b1 is of class "boot", as are objects created directly from the boot function, so helper functions in the boot package and in car can be used on these objects, e.g.,

The Boot function would have scoping problems even without the user embedding it in a function because the boot function called by Boot tries to evaluate the model defined in the global environment in a local environment. We solve this problem, and avoid assigning in a global environment and possibly overwriting an existing object, by defining a our own environment,

```
.carEnv <- new.env(parent=emptyenv())</pre>
```

and then evaluating the model in the environment .carEnv. This turns out to fail as well in certain circumstances. For example,

```
meanmod <- time ~ t1 + t2
m2 <- lm(meanmod, Transact)
Boot(m2, R=999)</pre>
```

Here meanmod is in the global environment and Boot is evaluating in the .carEnv environment. We solved this problem by making .carEnv globally available by using the code car:::.carEnv in place of .carEnv, as in the function Boot.default:

```
Boot.default <- function(object, f=coef, labels=names(coef(object)),</pre>
                      R=999, method=c("case", "residual")) {
  if(!(require(boot))) stop("The 'boot' package is missing")
  f0 <- f(object)</pre>
  if(length(labels) != length(f0)) labels <- paste("V", seq(length(f0)), sep="")
  method <- match.arg(method)</pre>
  if(method=="case") {
     boot.f <- function(data, indices, .fn) {</pre>
      assign(".boot.indices", indices, envir=car:::.carEnv)
      mod <- update(object, subset=get(".boot.indices", envir=car:::.carEnv))</pre>
      if(mod$gr$rank != object$gr$rank){
            out <- .fn(object)</pre>
            out <- rep(NA, length(out)) } else {out <- .fn(mod)}</pre>
     out
     }
    } else {
    boot.f <- function(data, indices, .fn) {</pre>
      first <- all(indices == seq(length(indices)))</pre>
      res <- if(first) object$residuals else
                   residuals(object, type="pearson")/sqrt(1 - hatvalues(object))
      res <- if(!first) (res - mean(res)) else res
      val <- fitted(object) + res[indices]</pre>
      if (!is.null(object$na.action)){
            pad <- object$na.action</pre>
            attr(pad, "class") <- "exclude"</pre>
            val <- naresid(pad, val)</pre>
      assign(".y.boot", val, envir=car:::.carEnv)
      mod <- update(object, get(".y.boot", envir=car:::.carEnv) ~ .)</pre>
      if(mod$qr$rank != object$qr$rank){
            out <- .fn(object)</pre>
            out <- rep(NA, length(out)) } else {out <- .fn(mod)}</pre>
      out
      7
  b <- boot(data.frame(update(object, model=TRUE)$model), boot.f, R, .fn=f)
  colnames(b$t) <- labels</pre>
  if(exists(".y.boot", envir=car:::.carEnv))
     remove(".y.boot", envir=car:::.carEnv)
```

```
if(exists(".boot.indices", envir=car:::.carEnv))
    remove(".boot.indices", envir=car:::.carEnv)
b
}
```

The was also fixed in bootCase.

## References

Angelo Canty and Brian Ripley. boot: Bootstrap R (S-Plus) functions. R package version 1.3-9, 2013.

- J. Fox and S. Weisberg. An R Companion to Applied Regression. Sage, Thousand Oaks CA, 2nd edition, 2011. URL http://z.umn.edu/carbook.
- J. Fox and S. Weisberg. Bootstrapping regression models in R. Technical report, 2012. URL http://socserv.mcmaster.ca/jfox/Books/Companion/appendix/Appendix-Bootstrapping.pdf.