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Fitting regression models to interval-censored observations of illness-death models

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Abstract

The irreversible illness-death model allows subjects to move from an initial state ("health state") to a terminal state ("death state") either directly or through an intermediate state ("disease state"). Disease onset times may not be known exactly, for example if the disease status of a patient can only be assessed at regular visits. In this situation the disease onset times are usually interval-censored. This article presents the **SmoothHazard** package for R. It implements algorithms for simultaneously fitting regression models to the three transition intensities of an illness-death model where the times to the intermediate state may be interval-censored data. The three baseline hazard functions are either parametrized according to Weibull distributions or approximated by M-splines. For a given set of covariates, the intensities models can be combined into predictions of cumulative event probabilities and life expectancies.

Keywords: illness-death model, interval-censored data, left-truncated data, survival model, proportional regression models, Smooth Transition intensities, Weibull.

1. Introduction

The irreversible illness-death model is a special multi-state model which has many applications for example in medical research. The model allows subjects to make transitions from an initial state (health) to a terminal state (death) either directly or via an intermediate state (disease), see Figure 1.

- 1 | library(prodlim)
- plotIllnessDeathModel(stateLabels=c("0: Healthy","1: Diseased","2: Dead"),arrowLabelSymbol="alpha")

If the exact transition times are observed, standard procedures like those implemented in the **mstate** package can be used to estimate regression models for the three transitions (de Wreede

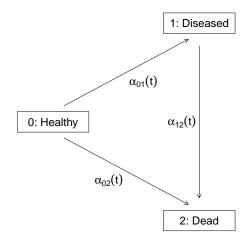


Figure 1: The irreversible illness-death model

et al. 2011). In particular, the regression coefficients can be estimated using Cox partial likelihood without the need to specify the baseline intensities. However, this possibility is lost when the transition times from the initial state to the transient state are interval censored. For example, it may not be possible to determine the exact onset time of dementia for a subject diagnosed at time R. Instead it is only known that the subject was last seen dementia-free at time L. Thus, the onset time is interval censored between L and R. Furthermore, for a subject who died without being diagnosed as demented before, it may not be possible to determine if the subject developed dementia between the last time he was seen and the time of death. The algorithms of the **SmoothHazard** package implement methods for estimating regression models under this type of censoring if the transition times into the absorbing state (e.g. death of the subject) are either known exactly or right censored (Joly et al. 2002). The msm package (Jackson 2011) allows to fit more general multi-state models to panel data (where states of each subjects are only known at a finite series of times). We focuse on a particular multi-state model, the illness-death model, where only one state is known at a finite series of times leading to data which are only interval censored. Even if the msm could be used, the direct expression of the likelihood can be derived making possible to estimate more flexible transition intensities with less assumptions.

Implemented are a parametric and a semi-parametric estimation approach. For the parametric approach, the Weibull distribution is used for the baseline transition intensities and the parameters are estimated by maximising the likelihood. For the semi-parametric approach, M-splines are used to approximate the baseline transition intensities and the parameters are estimated maximising a penalized likelihood. The methods allow delayed entry of the subjects, i.e. that the event times are left truncated.

Section 2 presents the model and the likelihood. Section 3 presents the estimation methods. Section 4 provides some examples illustrating **SmoothHazard** functions.

2. Data, model and questions

In order to illustrate the functionality of the package we provide a random subset containing

data from 1000 subjects that were enrolled in the Paquid study (Letenneur *et al.* 1999), a large cohort study on mental and physical aging.

```
library(SmoothHazard)
data(Paq1000)
```

The population consists of subjects aged 65 years and older living in Southwestern France. The event of interest is dementia and death without dementia is a competing risk. Furthermore, the time to dementia onset is interval censored.

In this subset 186 subjects are diagnosed as demented and 724 died from whom 597 without being diagnosed as demented before. Because of interval censoring more than 186 should have been demented, more than 127 should have been dead with dementia and less than 597 should have been dead without dementia (see Figure 2). There are two covariates in this subset: gender (578 women and 422 men) and primary school diploma (762 with diploma and 238 without diploma). Age is chosen as the basic time scale and subjects are non demented at entry into study. Consequently, we need to deal with left-truncated event times.

```
_{1} head(Paq1000)
```

	${\tt dementia}$	${\tt death}$	t0	1	r	t	certif	gender
1	1	1	72.3333	82.34014	84.73303	87.93155	0	0
2	0	1	77.9167	78.93240	78.93240	79.60048	0	1
3	0	1	79.9167	79.91670	79.91670	80.92423	0	0
4	0	1	74.6667	78.64750	78.64750	82.93501	1	1
5	0	1	76.6667	76.66670	76.66670	79.16636	0	1
6	0	0	66.2500	71.38070	71.38070	84.16975	1	0

Each row in the data corresponds to one subject. The variables dementia and death are the status variables (1 if an event occurred, 0 otherwise) for dementia and death, respectively. The variable t0 contains ages of subjects at entry into study. The variables 1 and r contain the left and right endpoints of the censoring intervals. For demented subjects, r is the age at the diagnostic visit and 1 is the age at the previous one. For non demented subjects, 1 and r are the age at the latest visit without dementia (1=r). The variable t is the age at death or at latest news. certif and gender are binary covariates.

The function idm computes estimates for the three transition intensities $\alpha_{01}(.)$, $\alpha_{02}(.)$, $\alpha_{12}(.)$ which are age-specific incidence rate of dementia, age-specific mortality rate of dementia-free subjects and age-specific mortality rate of demented sujects, respectively. Proportional transition intensities regression models allow for covariates on each transition:

$$\alpha_{hl}(t|Z_{hli}) = \alpha_{0,hl}(t) \exp\{\beta_{hl}^T Z_{hli}\}; \quad hl \in \{01, 02, 12\}$$

where $\alpha_{0,hl}$ are baseline transition intensities, Z_{hli} are covariates vectors for subject i and β_{hl} are vectors of regression parameters.

Covariates are specified independently for the regression models of the three transition intensities by the right hand side of the respective formula formula01, formula02 and formula12. Set the formula (~1 for no covariates.

Interval censoring and left truncation must be specified at the left side of the formula arguments using the Hist function. For left-truncated data, the entry argument of Hist must

4 Illness-Death Model for Interval-Censored Data: The **SmoothHazard** Package for R

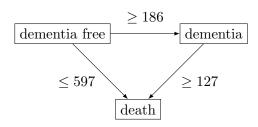


Figure 2: The exact number of transitions in the illness-death model with interval-censored time to disease is unknown.

contain the vector of delayed entry times. For interval-censored data, the time argument of Hist must contain a list of the left and right endpoints of the intervals.

A call of the idm function looks as follows:

```
fit <- idm(formula01=Hist(time=list(l,r),event=dementia,entry=t0)~certif,
formula02=Hist(time=t,event=death,entry=t0)~certif+gender,
formula12=~1,
data=Paq1000)
```

where the data argument contains the data frame in which to interpret the variables of formula01, formula02 and formula12.

Note that the left side of formula12 does not need to be filled because all the data informations are already contained in formula01 and formula02. In fact, the formula12 argument is required only if we want the covariates impacting transition 12 different from those impacting transition 02.

Questions? TODO

3. Fitting the illness-death model based on interval-censored data

The idm function computes estimates for the three transition intensities:

$$\alpha_{hl}(t|Z_{hli}) = \alpha_{0,hl}(t) \exp\{\beta_{hl}^T Z_{hli}\}; \qquad hl \in \{01, 02, 12\}$$
 (1)

In the situation where time to disease and time to death are not interval censored the regression coefficients can be estimated by the partial likelihood method (Cox 1975) without the need to specify or estimate the baseline hazard functions $\alpha_{0,hl}(t)$. For interval-censored transition times to state 1 the situation is more complex. It turns out that we have to estimate all parameters simultaneously and that we need a model for the baseline transition intensity functions. This can be seen by inspecting the likelihood function.

For subject i, let us denote the conditional event-free survival function by

$$S(t|Z_{01i}, Z_{02i}) = e^{-A_{01}(t|Z_{01i}) - A_{02}(t|Z_{02i})}$$

where $A_{hl}(.|Z_{hli})$ are the conditional cumulative intensity functions:

$$A_{hl}(t|Z_{hli}) = \int_0^t \alpha_{hl}(u|Z_{hli})du$$

.

We set $\delta_{1i} = 1$ ($\delta_{1i} = 0$) if subject i has (has not) been observed diseased, and $\delta_{2i} = 1$ ($\delta_{2i} = 0$) if subject i is (is not) dead.

If $\delta_{2i} = 0$, T_i is time to death; if $\delta_{2i} = 0$, death event is right-censored at T_i . We denote by L_i and R_i the interval censoring times. If subject i has been observed diseased at time R_i and has last been seen non diseased at time L_i ($L_i < R_i$), time to disease is interval-censored between L_i and R_i . The likelihood contribution for subject i is:

$$\mathcal{L}_{i} = \frac{1}{S(T_{0i}|Z_{01i}, Z_{02i})} \int_{L_{i}}^{R_{i}} S(u|Z_{01i}, Z_{02i}) \alpha_{01}(u|Z_{01i}) \frac{e^{-A_{12}(T_{i}|Z_{12i})}}{e^{-A_{12}(u|Z_{12i})}} \left(\alpha_{12}(T_{i}|Z_{12i})\right)^{\delta_{2i}} du \quad (2)$$

If subject i has never been seen diseased, time to disease is right-censored and the interval censoring times are set to the right censoring time ($L_i = R_i$). The likelihood contribution for subject i is:

$$\mathcal{L}_{i} = \frac{1}{S(T_{0i}|Z_{01i}, Z_{02i})} \left(S(T_{i}|Z_{01i}, Z_{02i}) \left(\alpha_{02}(T_{i}|Z_{02i}) \right)^{\delta_{2i}} + \int_{L_{i}}^{T_{i}} S(u|Z_{01i}, Z_{02i}) \alpha_{01}(u|Z_{01i}) \frac{e^{-A_{12}(T_{i}|Z_{12i})}}{e^{-A_{12}(u|Z_{12i})}} \left(\alpha_{12}(T_{i}|Z_{12i}) \right)^{\delta_{2i}} du \right) \quad (3)$$

If time to disease and time to death are both right-censored at the same time, we have $L_i = R_i = T_i$ and the integral value in (3) is zero.

3.1. The Weibull parametrization

The default estimation method in function idm computes the maximum likelihood estimate for the three transition intensities using a Weibull parametrization for the baseline transition intensities:

$$\alpha_{0,hl}(t) = a_{hl} b_{hl}^{a_{hl}} t^{a_{hl}-1}; \quad hl \in \{01, 02, 12\}.$$

where a_{hl} and b_{hl} are shape and scale parameters.

```
fit.weib <- idm(formula02=Hist(time=t,event=death,entry=t0)~certif+gender,
formula01=Hist(time=list(l,r),event=dementia,entry=t0)~certif+gender,
data=Paq1000,intensities="Weib")
print(fit.weib)
```

Call:

```
idm(formula01 = Hist(time = list(1, r), event = dementia, entry = t0) ~
  certif + gender, formula02 = Hist(time = t, event = death,
  entry = t0) ~ certif + gender, data = Paq1000, intensities = "Weib")
```

Illness-death model: Results of Weibull regression for the intensity functions.

The regression parameters HR have the usual interpretation, as in a fully parametric Cox regression model (CELIA, PIERRE: is this correct? There are some confusing other parametrizations of the Weibull model, eg. the function 'psm' of harrel's R-package rms)

The three baseline transition intensity functions can be displayed as functions of time, functions of age in our illustrative example (Figure 3).

```
par(mgp=c(4,1,0),mar=c(5,5,5,5))
plot(fit.weib,conf.int=TRUE,lwd=3,citype="shadow",xlim=c(65,100), axis2.las=2,axis1.at=seq (65,100,5),xlab="Age (years)")
```

Maximization algorithm

The Weibull parameters a_{hl} and b_{hl} and the vectors of regression parameter $\hat{\beta}_{hl}$ are obtained simultaneously by maximizing the log-likelihood using a combination of a Marquardt's algorithm (Marquardt 1963) which is a robust Newton-like algorithm and a steepest descent algorithm. Using the Marquardt's algorithm, few iterations are needed if the initial value is judiciously chosen. The Marquardt's algorithm step involves a line search with a step reduction if the new point is not better. Using the steepest descent algorithm, the convergence

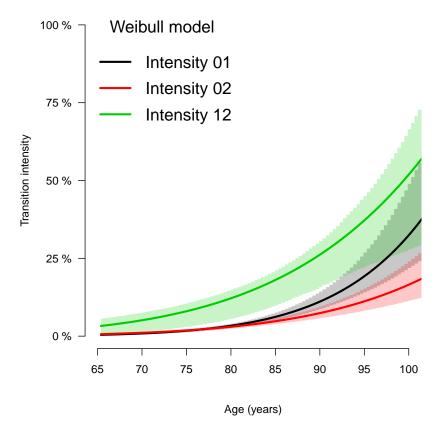


Figure 3: Estimated baseline intensities using Weibull regression for all transitions in the Paq1000 data.

is slower. The steepest descent step involves a full line search and is attempted only if the Marquardt's algorithm step has failed, due generally to a difficulty to inverse the Hessian matrix of the log-likelihood. We stop the iterations when the differences between two consecutive parameters values, log-likelihood values, and gradient values is small enough. The default convergence criteria are 10^{-5} , 10^{-5} and 10^{-3} and can be changed by means of the eps argument. The variances of parameter estimates are estimated using the inverse of the matrix of the second derivatives at convergence.

3.2. The penalized likelihood

The other estimation option in the function idm permits to relax the strict parametric assumptions of the Weibull regression models. With the option intensities="Splines", M-splines are used to approximate the three baseline transition intensities. Although this option implies a considerable amount of extra computations (see below), the call and the printed output are very similar to the Weibull model:

```
fit.splines <- idm(formula02=Hist(time=t,event=death,entry=t0)~certif+gender,
```

```
8
```

```
formula01=Hist(time=list(l,r),event=dementia,entry=t0)~certif+gender,
2
           data=Pag1000,intensities="Splines")
   print(fit.splines)
Call:
idm(formula01 = Hist(time = list(l, r), event = dementia, entry = t0) ~
    certif + gender, formula02 = Hist(time = t, event = death,
    entry = t0) ~ certif + gender, data = Paq1000, intensities = "Splines")
Illness-death model using a penalized likelihood approach with splines
approximation for the intensity functions.
number of subjects: 1000
number of events '0-->1': 186
number of events '0-->2' or '0-->1-->2': 724
number of subjects: 1000
number of covariates: 2 2 2
number of deleted observations due to missing:
Smoothing parameters:
      transition01 transition02 transition12
knots
                 7
                              7
kappa
                         500000
                                        20000
           1000000
             coef SE.coef
                              HR
                                           CI
                                                    Wald p.value
certif_01 -0.4981 0.2075 0.6077 [0.40;0.91] 5.7622609 0.016374
gender_01 -0.0558  0.1655  0.9458  [0.68;1.31]  0.1135984  0.736084
certif_02 0.1290 0.1283 1.1376 [0.88;1.46] 1.0101740 0.314861
gender_02 0.5043 0.1215 1.6558 [1.30;2.10] 17.2238696 < 0.0001
certif_12 -0.2037  0.2388  0.8157  [0.51;1.30]  0.7273826  0.393733
gender_12  0.6449  0.1934  1.9058  [1.30;2.78]  11.1222626  0.000853
                         Without cov With cov
Penalized log likelihood
                           -3073.099 -3046.848
Model converged.
number of iterations:
convergence criteria: parameters= 0.0000000076
                    : likelihood= 0.0000002
                    : second derivatives= 0.00000000005
```

Again, the estimated baseline transition intensities can conveniently be visualized in a joint graph (Figure 4).

```
\begin{array}{ll} & par(mgp=c(4,1,0),mar=c(5,5,5,5)) \\ & plot(fit.splines,conf.int=TRUE,lwd=3,citype="shadow",xlim=c(65,100), axis2.las=2,axis1.at=seq(65,100,5),xlab="Age (years)") \\ \end{array}
```

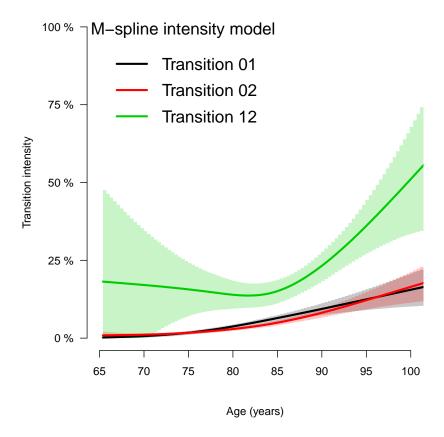


Figure 4: Estimated baseline intensities using M-splines for all transitions in the Paq1000 data.

3.3. Penalized likelihood and M-splines

To control the smoothness of the estimated intensity functions, we penalize the likelihood by a term which specificies the curvature of the intensity functions that is the square of the second derivates. The penalized log-likelihood (pl) is defined as:

$$pl = l - \kappa_{01} \int {\alpha''_{01}}^2 (u|Z_{01}) du - \kappa_{02} \int {\alpha''_{02}}^2 (u|Z_{02}) du - \kappa_{12} \int {\alpha''_{12}}^2 (u|Z_{12}) du$$
(4)

where l is the log-likelihood and κ_{01} , κ_{02} and κ_{12} are three positive smoothing parameters which control the trade-off between the data fit and the smoothness of the functions.

Maximization of (4) defines the maximum penalized likelihood estimators (MPLE) $\hat{\alpha}_{01}$, $\hat{\alpha}_{02}$ and $\hat{\alpha}_{12}$. The parameters being maximized are the regression coefficients and further parameters defined by a linear combination of M-splines (Ramsay 1988). The latter are described in the remaining of this section.

A spline of order k is a piecewise polynomial functions of degree k-1. The places where the polynomial pieces connect are the knots. We denote by $t^{01}=(t_1^{01},\ldots,t_{J_{01}}^{01})$ a sequence of

 J_{01} knots used to define the M-spline approximation of $\alpha_{0,01}$ and by $t^{02}=(t_1^{02},\ldots,t_{J_{02}}^{02})$ and $t^{12}=(t_1^{02},\ldots,t_{J_{12}}^{02})$ similar sequences for $\alpha_{0,02}$ and $\alpha_{0,12}$, respectively.

CELIA, PIERRE: please explain here that we define the estimate as a linear combination of several M-splines M_i , $i=1,\ldots,?$ and what you mean by free parameters...

For $hl \in \{01, 02, 12\}$:

$$\tilde{\alpha}_{0,hl}(x) = \sum_{i=1}^{n} a_i M_i(x)$$

where n is the number of free parameters.

Non-negativity of $\tilde{\alpha}_{0,hl}$ is obtained by constraining the coefficients a_i to be positive. In practice, we estimate parameters θ_i such that $a_i = \theta_i^2$ maximize the penalized likelihood. Each M-spline has an order k. For simplicity we suppress in the notation that the M-splines are specific to the transition and also write $t = (t_1, \ldots, t_J)$ for a generic sequence of knots.

An M-spline of order k is computed using the following recursion: CELIA, PIERRE: I dont understand the notation M(x|1,t). For k=1,

$$M_j(x|1,t) = \begin{cases} \frac{1}{(t_{j+1}-t_j)} & \text{if } t_j \le x < t_{j+1} \\ 0 & \text{elsewhere} \end{cases}$$

For k > 1,

$$M_{j}(x|k,t) = \begin{cases} \frac{k[(x-t_{j})M_{j}(x|k-1,t) + (t_{j+k}-x)M_{j+1}(x|k-1,t)]}{(k-1)(t_{j+k}-t_{j})} & \text{if } t_{j} \leq x < t_{j+k} \\ 0 & \text{elsewhere} \end{cases}$$

CELIA, PIERRE: I dont understand the role of the knot sequence in the previous display. where $t = t_1, ..., t_{n+k}$ is a knot sequence.

CELIA, PIERRE: the following sentence is not clear (why are density properties appealing? maybe you can elaborate (or delete?) and move it to the introduction or discussion?

The M-spline family is particularly appealing to statisticians because each M_i has the properties of a probability density function over the interval $[t_i, t_{i+k}]$. One such property is $\int M_i(x)dx = 1$.

With each M-spline we associate an integrated spline or I-splines I_i , i = 1, ..., n. It is defined as $I_i(x|k,t) = \int_{t_k}^x M_i(u|k,t) du$. Given the coefficients a_i , we can approximate the cumulative baseline transition intensities \hat{A}_{hl} by a linear combination of I-splines:

$$\tilde{A}_{0,hl}(x) = \sum_{i=1}^{n} a_i I_i(x).$$

Because M-splines are non-negative, the positivity constraint on a_i ensures that $\tilde{A}_{0,hl}$ is monotone increasing. Each M_j is a piecewise polynomial of degree k-1 and each I_j is a piecewise polynomial of degree k. In the package we have implemented cubic M-splines, that is we set k=4.

Choice of the knots

The knots sequence has some properties to ensure continuity conditions. Among them, we have: $t_1 = \ldots = t_k$ and $t_{n+1} = \ldots = t_{n+k}$. The number of free parameters n corresponds to k+ the number of knots interior to $[t_k, t_{n+1}]$

In **SmoothHazard**, the knots are put equidistantly between them by default. The knots argument can be fulfilled to choose their location freely but in general the shape of a spline function is not very sensitive to knot placement. However, there must be several data points between each pair of different knots and there must be a knot before or at the first data point and after or at the last data point. Increasing the number of data points between a pair of knots leads to a better defined curve.

The number of knots can be specified in the n.knots argument. It must be understood as the number of different knots *i.e.* the number of knots from t_k to t_{n+1} . The default is 7 on the three transitions which leads to a number of free parameters on each transition n = 3 + 5 = 9. Increasing the number of knots in a region leads to a greater flexibility of the function in that region. The number of knots and their location can be chosen differently for each transition.

Choice of smoothing parameters

The default values for the smoothing parameters are suitable for the Paq1000 data set. However, these values can be expected to be very different depending on time scale and number of subjects. They can be changed into the kappa argument. An approximate cross-validation technique to determine the smoothing parameters is also available with the option CV=TRUE. In this case, the kappa argument contains the initial values for the smoothing parameters. We use an approximate leave-one-out score proposed by O'Sullivan (1988) for survival models and extended for multi-state models (Commenges et al. 2007) for which only one estimation of the model is required by tested values of the smoothing parameters.

Maximization algorithm

The vectors of spline coefficients for fixed κ_{01} , κ_{12} and κ_{02} and the vectors of regression parameters $\hat{\beta}_{01}$, $\hat{\beta}_{02}$, $\hat{\beta}_{12}$ are obtained simultaneously by maximizing the penalized log-likelihood using the same maximization algorithm as with the Weibull parametrization (see Section 3.1).

Increasing the number of knots does not deteriorate the MPLE: this is because the degree of smoothing in the penalized likelihood method is tuned by the smoothing parameters κ_{01} , κ_{12} and κ_{02} . On the other hand, once a sufficient number of knots is established, there is no advantage in adding more. Moreover, the more knots, the longer the running time. Some numerical problem can arise, particularly for a large number of knots. That is why the maximum number of knots is limited to 25. So it is recommended to start with a small number of knots (e.g. 5 or 7) and increase the number of knots until the graph of the transition intensities function remains unchanged (rarely more than 12 knots).

The choice of the smoothing parameters can be fastidious. The idm function can be run with the approximate cross-validation option. However, the running time is very long and an empirical technique can be preferred. It consists in repeating the idm running trying different smoothing parameters. After each estimation, the transition intensities can be plotted. This is done with the plot function. If the curves seem too smooth it may be useful to reduce the associated smoothing parameter. Similarly, if the curves are to wiggly, the associated smoothing parameter may be increased.

4. Predicting parameters of life

Most often in illness-death models, the functions of interest are the transition intensities. However, other functions/quantities which can be expressed in terms of the transition intensities (Touraine $et\ al.\ 2013$) and may provide additional information and have a more natural interpretation.

The function idm returns an "idmWeib" or "idmSplines" class object depending on the parametrization of the transition intensities (Weibull or splines). These objects can be used in argument of the predict.idmWeib and predict.idmSplines functions in order to obtain transition probabilities between ages 70 and 80 (and cumulative probabilities). For example, for a female subject who is healthy at age 70 and has primary school certificate:

```
$p00
[1] 0.8899268 0.8245325 0.8759390
$p01
[1] 0.03041876 0.02406653 0.05422249
$p11
[1] 0.2649379 0.2802728 0.7980570
$p12
[1] 0.7350621 0.2019430 0.7197272
[1] 0.06035533 0.07735229 0.12578106
$p02_1
[1] 0.01929910 0.00399737 0.02334086
$p02
[1] 0.07965443 0.09042787 0.13498797
$F01
[1] 0.04971786 0.03197171 0.07140308
$F0.
[1] 0.1100732 0.1240610 0.1754675
```

where TP\$p00, TP\$p01, TP\$p11, TP\$p02 are the transition probabilities; TP\$p02_1 and TP\$p02_0 are the probabilities of transition from state 0 to state 2 coming through state 1 or not; F01 is the probability for of becoming diseased between ages 70 and 80; F0. is the probability of exit from state 0 between ages 70 and 80.

If the predict function is used with an idmSplines object, the s input must be greater than the first knot and the t input must be lower than the last knot.

The "idmWeib" or "idmSplines" objects can also be used in argument of the lifexpect function to obtain life expectancies. For example, for a female subjects who has primary school certificate, the following code:

```
$life.in.0.expectancy
[1] 4.047053
```

\$life.expectancy.nondis
[1] 5.416446

\$life.expectancy.dis
[1] 4.057387

produces healthy life expectancy, life expectancy for a non diseased subject and life expectancy for a diseased subject. Again, if this function is used with an idmSplines object, the s input must be greater than the first knot. Moreover, life expectancies are calculated integrating up to infinity using an "idmWeib" object but up to the last knot using an "idmSplines" object. Consequently using an "idmSplines" object, it must be acceptable to assume that any subject should be in state 2 (dead) at the age corresponding to the last knot. Otherwise, the life expectancies would be underestimated.

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