Package 'move'

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	Bart Kranstauber <bart.kranstauber@uni-konstanz.de>, Kam- ı Safi <ksafi@orn.mpg.de>, Marco Smolla <msmolla@orn.mpg.de></msmolla@orn.mpg.de></ksafi@orn.mpg.de></bart.kranstauber@uni-konstanz.de>
Maintai	ner Marco Smolla <msmolla@orn.mpg.de></msmolla@orn.mpg.de>
ba	ion move is a package that contains functions to access movement data stored in move- nk.org as well as tools to visualize and statistically analyse animal movement data. Move ad- esses movement ecological questions.
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Description

move is a package that contains functions to access movement data stored at www.movebank.org as well as tools to visualize and statistically analyse animal movement data. Move addresses movement ecological questions.

Details

The package implements classes for movement data and supports

- Creation of Move objects (see Move-class) representing animals and their track
- Calculation of utilization densities using the dynamic Brownian bridge Movement Model
- Plotting tracks, utilization densities and contours
- · Access to raster, n.col, projection and coordinates
- Different CRS projection methods such as longlat or aeqd

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I. Creating Move objects

Move objects can be created from files with the function:

4 as.data.frame

move To create a Move object

II. Calculation of the utilization density

With the function below the dynamic Brownian Bridge Movement Model calculates the utilization density from a Move object:

brownian.bridge.dyn To calculate the utilization density

III. Accessing values

coordinates Track-coordinates of the Move Object

as.data.frame A data.frame with the important data of the Move Object

n.locs The number of locations

time.lag The time lags between the locations projection The projection method of the track/raster

IV. Plotting data

The track or the utilization density can be plotted with the following functions:

plot plots the utilization density with fixed width and height ratio (see DBBMM-class)

or the track (see Move-class)

image plots the utilization density fitted to the window contour adds the contours of utilization densities to a plot

Author(s)

Bart Kranstauber, Marco Smolla, Kamran Safi

Maintainer: Bart Kranstauber kranstauber@orn.mpg.de, Marco Smolla mmolla@orn.mpg.de

References

CRAN: http://move.r-forge.r-project.org/

as.data.frame Return a Data Frame

Description

Function to create a data.frame with the spatial data frame information from a Move object.

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Usage

```
## S4 method for signature 'Move'
as.data.frame(x,...)
```

Arguments

an object of the Move-class

additional arguments to be passed to or from methods

Details

as.data.frame extracts the sdf argument from a Move object (see Move-class)

Author(s)

Marco Smolla

Examples

```
## create a move object
data <- move(system.file("extdata","leroy.csv",package="move"),proj=CRS("+proj=longlat"))</pre>
## returns a data.frame with all information stored in the spatial data frame of the move object
df <- as.data.frame(data)</pre>
```

brownian.bridge.dyn Creates a DBBMM object

Description

The brownian.bridge.dyn function uses a Move object (see Move-class) to calculate the utilization density (UD) of the given track. It uses the dynamic Brownian Bridge Movement Model (dBBMM) to do so. The dBBMM has the advantage over the other Brownian Bridge Movement Model that changes in behaviour are accounted for. It does so by using the behavioral change point analysis in a sliding window. For details see Kranstauber et al. (2012).

Usage

```
brownian.bridge.dyn(object, raster, dimSize, location.error,
               margin=11, time.step=NULL, window.size=31, ext, ...)
```

Arguments

dimSize

object	a Move-class object, which can be created with the function move
raster	can be a RasterLayer object or numeric. If it is a RasterObject and dimSize is not set, brownian.bridge.dyn starts to calculate the UD. If raster is numeric,
	it describes the cell.size of the raster. Default is 1

can be numeric. If there is no input for raster, dimSize describes the number of

cells of the largest x or y dimenstion. Default is 10

location.error required numeric value. Describes the error of the location (sender/receiver)

system in map units.

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margin The margin used for the behavioral change point analysis.

time.step The size of the time steps taken for the calculation of the utilization density in

minutes, if left null 15 steps are taken in the shortest time interval.

window.size The size of the moving window along the track. Larger windows provide more

stable/accurate estimates of the brownian motion variance but are less well able

to capture more frequent changes in behaviour.

ext numeric value >0; extension factor. Decribes the amount of extension of the

bounding box of the animal track. It can be one (same extension into all four directions), two (first x, then y directional extension) or four numbers (xmin, xmax, ymin, ymax extension). Default is .25 (extends the bounding box by

25%)

... for additional arguments

Details

There are four ways to launch the brownian.bridge.dyn function which are as follows:

1. Serve a raster

A RasterLayer object is set for the raster argument which is then used to calculate the UD.

2. Set the cell size

To set the cell size set a numeric value for the raster argument but skip the dimSize. The numeric raster argument is used as the cell sizes of the raster. A RasterLayer object is created and returned to the same function.

3. Set the number of cells (col/row)

To set the number of cells along the largest dimension a numeric dimSize argument is set instead of the raster argument. A RasterLayer object is created and returned to the same function.

4. Using default raster

When there are no values set, the default raster value is used to calculate and create a RasterLayer object, which is returned to the same function. Note: depending on the size of the area of interest, the default cell size value can result in a large number of cells which may take a very long time to calculate!

The function prints an estimate of the size of the computational task ahead. This can give an indication of how long the computation is going to take. It should scale roughtly linearly with the duration of the computations. In our experience \$1*10^9\$ takes about a minute with a normal laptop.

Note

Note that the first few and last few segments of the trajectory are omitted in the calculation of the UD since a lower number of estimates for the Brownian motion variance are obtained for those segments.

Author(s)

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References

Kranstauber, B., Kays, R., LaPoint, S. D., Wikelski, M. and Safi, K. (2012), A dynamic Brownian bridge movement model to estimate utilization distributions for heterogeneous animal movement. Journal of Animal Ecology. doi: 10.1111/j.1365-2656.2012.01955.x

Examples

```
## create a move object
data <- move(system.file("extdata","leroy.csv",package="move"),proj=CRS("+proj=longlat"))
## change projection method to aequd and center the coordinate system to the track
data2 <- spTransform(data, CRSobj="+proj=aeqd", center=TRUE)
## create a DBBMM object
#dbbmm <- brownian.bridge.dyn(object=data2, location.error=23.5, dimSize=45, ext=.3, time.step=600)</pre>
```

burstTrack

Bursting a track

Description

Bursting a track by specified variable

Usage

```
## S4 method for signature 'Move,numeric'
burstTrack(object, by, breaks=5, sizeFUN="relTime")
```

Arguments

object a Move object

by column indicator like data\$behavior that is used to burst the track

breaks defines the number of steps by which the relative values, e.g. relative time, is

divided. Default value is 5.

sizeFUN specify a function to calculate the sizes of the centroids like function(11) lapply(lapply(l1, le

DOES NOT WORK AT THE MOMENT! Default is relative time of the burst

segemnt compared to the whole track

Details

The burstTrack function bursts (divides) a track in segments that are specified by the by attribute. If a colum with behavioral classfication is annotated to the coordinates of the Move object, the track can be bursted by that column. For every segment an indicator (a circle) is set in the middle of the segment. The size of this indicator depends on the sizeFUN and is by default defined by the relative time compared to the whole duration.

Note

sizeFUN does not work at the moment

8 contour

Author(s)

Marco Smolla

Examples

```
##here we need a annotated csv file
```

contour

Contour plot

Description

Contour plot of a RasterLayer from a DBBMM object.

Usage

```
## S4 method for signature '.UD' contour(x, ...)
```

Arguments

x an object of the DBBMM-class

... additional arguments like levels and nlevels, see details

Details

The contour function creates a shape of the area in which there is a 90% probability that the animal will be located. One or several probabilities can be set with levels. Choose values between 0 and 1. At least one level must be added, there is no default value set. You can also use nlevel to set a number of fixed distance levels.

To change parameters of the contour or line plotting use the usual parameters of the plot function.

Author(s)

Marco Smolla

```
## Not run:
## Create a DBBMM object to use this function
## See the examples of the brownian.bridge.dyn function
## Here we just load a previous session, where we already created a DBBMM object
load(system.file("extdata", "leroy.RData", package="move"), .GlobalEnv)

## to add a 50% and 90% contour to a plot from DBBMM object dbbmm
plot(dbbmm)
contour(dbbmm, levels=c(.5,.9), add=TRUE, plot=TRUE)

##to store the contours as a SpatialLinesDataFrame use
cnt <- contour(dbbmm, levels=c(.4,.9))

##print the contour on a google map +add the track</pre>
```

coordinates 9

```
require("RgoogleMaps")
cnt <- contour(x=dbbmm, y=data, levels=c(.4,.9), google=TRUE)
cnt <- contour(x=dbbmm, y=data, levels=c(.4,.9), google=TRUE, track=TRUE)
## End(Not run)</pre>
```

coordinates

Extract the track coordinates from a Move object

Description

The coordinates method extracts the coordinates of the track within a Move object.

Usage

```
## S4 method for signature 'Move'
coordinates(obj,...)
```

Arguments

obj A valid Move object

... Additional arguments, see Details

Details

obj The move object includes a special data frame with the track coordinates and a time stamp. They are returned as a matrix.

Author(s)

Marco Smolla

```
## create a move object
data <- move(system.file("extdata","leroy.csv",package="move"), proj=CRS("+proj=longlat"))
## extract the coordinates
coords <- coordinates(data)</pre>
```

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DBBMM-class

The DBBMM class

Description

The DBBMM object is created within the brownian.bridge.dyn function from a Move object. It includes beneath others a raster object and probabilities.

Slots

```
DBMvar Object of class "dBMvarianceTmp": includes the window.size, margin, means, in.windows,
     break.list, and points of interest
crs part of the Raster-class
ext the extension factor set by the user
data part of the Raster-class
extent part of the Raster-class
file part of the Raster-class
history part of the Raster-class
layernames part of the Raster-class
legend part of the Raster-class
method stores the method that was used to calculate the utilization distribution (UD), e.g. dynamic
     Brwonian Bridge
ncols part of the Raster-class
nrows part of the Raster-class
rotated part of the Raster-class
rotation part of the Raster-class
title part of the Raster-class
z part of the Raster-class
```

Methods

```
contour signature(object = "DBBMM"): adds a contour line to a plot
image signature(object = "DBBMM"): plots the raster from a DBBMM object with fixed cell
    size ratio

plot signature(object = "DBBMM"): plots the raster from a DBBMM object with resize insenstive proportions

proj4string signature(object = "DBBMM"): extracts the projection method of the raster stored
    within the DBBMM object

raster signature(object = "DBBMM"): extracts the raster from the DBBMM object

outerProbability signature(object = "DBBMM"): calculates the animal occurence probabilities at the border of the raster
```

Author(s)

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DBBMMStack-class

The DBBMMStack class

Description

The DBBMMStack object is created within the brownian.bridge.dyn function from a Move object. It includes beneath others a raster object and probabilities.

Slots

```
crs part of the Raster-class
ext the extension factor set by the user
extent part of the Raster-class
filename part of the Raster-class
layers part of the Raster-class
layernames part of the Raster-class
method the method that was used to calculate the utilization distribution, e.g. dynamic Brwonian Bridge
ncols part of the Raster-class
nrows part of the Raster-class
rotated part of the Raster-class
rotation part of the Raster-class
title part of the Raster-class
title part of the Raster-class
```

Methods

Author(s)

12 emd

 emd

Earth Movers Distance between DBBMM objects

Description

Calculates the Earth Movers Distance between two rasters stored in DBBMM objects

Usage

```
## S4 method for signature 'RasterLayer,RasterLayer,numeric,logical,logical'
emd(x, y, threshold, integer, greatcircle)
  ## S4 method for signature 'DBBMM,DBBMM,numeric,logical,logical'
emd(x, y, threshold, integer, greatcircle)
```

Arguments

```
x a DBBMM object
y a DBBMM object
threshold ...
integer ...
greatcircle ...
```

Details

•••

Note

•••

Author(s)

Marco Smolla

```
## Not run:
    load(system.file("extdata", "leroy.RData", package="move"), .GlobalEnv)
## End(Not run)
```

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getMovebankAnimals	Animals, tags and IDs in a Movebank stu	ıdv
gethovebankAntinats	minuis, iugs and ibs in a movedant sin	iu y

Description

Returns the animals, their tags and IDs from a Movebank study

Usage

```
getMovebankAnimals(study, login)
```

Arguments

study	a character string (study name)	or the numeric stud	ly ID as it is stored on Move-

bank

login an object of the MovebankLogin-class, if empty you'll be asked to enter your

username or password

Details

The function returns a data.frame that incldues the animalID, animalName, id, sensor_type_id and tag_id from the requested study.

Note

See the 'browesMovebank' vignette (move website download section) for more information about security and how to use Movebank from within R.

Author(s)

Marco Smolla

getMovebankData	Download data from Movebank

Description

getMovebankData downloads the location and timestemp columns of an animal of study stored in Movebank and creates a Move object

Usage

```
getMovebankData(study, animalName, login, moveObject = TRUE, ...)
```

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Arguments

study character, full name of the study, as stored on Movebank animalName chracter, name of the individual as stored on Movebank

login a MovebankLogin, if empty you'll be asked to enter your username or password logical, if FALSE a data.frame with coordinates and timestamps is returned.

Default is TRUE

... passing on additional arguments

Details

With the getMovebankData function you can access the location and timestamp data of a particular animal within a certain study. By default moveObject is TRUE. Thus the function returns a Move object if an animalName is given. If there is no animalName, the whole study is downloaded and stored as a MoveStack object. Remember that you need an account at Movebank.org, see movebankLogin.

Note

See the 'browesMovebank' vignette (move website download section) for more information about security and how to use Movebank from within R.

Author(s)

Marco Smolla

getMovebankID	Study ID
50 CHO V COUTINED	Simayin

Description

Returns the study ID of a certain study stored on Movebank

Usage

```
getMovebankID(x,login)
```

Arguments

x character, full name of the study, as stored on Movebank

login an object of the MovebankLogin-class, if empty you'll be asked to enter your

username or password

Details

The getMovebankID function returns the ID of a study as it is stored on Movebank.org.

Note

See the 'browesMovebank' vignette (move website download section) for more information about security and how to use Movebank from within R.

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Author(s)

Marco Smolla

getMovebankSensors

Information about Movebank sensors

Description

getMovebankSensors returns information about sensors in a study.

Usage

getMovebankSensors(study, login)

Arguments

study a character string (study name) or the numeric study ID as it is stored on Move-

bank, if missing the function returns a data.frame with information about all

sensor types in Movebank

login an object of the MovebankLogin-class, if empty you'll be asked to enter your

username or password

Details

The function returns either information about all sensor types that are available on Movebank or the sensor IDs corresponding to to the animal IDs in a specific study.

Note

See the 'browesMovebank' vignette (move website download section) for more information about security and how to use Movebank from within R.

Author(s)

Marco Smolla

getMovebankSensorsAttributes

Available sensor attributes

Description

This function returns all attributes of the sensors of the requested study.

Usage

```
getMovebankSensorsAttributes(study, login)
```

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Arguments

study a character string (study name) or the numeric study ID as it is stored on Move-

bank

login an object of the MovebankLogin-class, if empty you'll be asked to enter your

username or password

Details

Returns the attributes of the sensors of a study, i.e. which sensor has which id and which data stored (e.g. GPS sensors store longitute and latitude locations, and timestamps and have 673 as their ID on Movebank).

Note

See the 'browesMovebank' vignette (move website download section) for more information about security and how to use Movebank from within R.

Author(s)

Marco Smolla

getMovebankStudies All studies on Movebank

Description

Returns all studies available on Movebank

Usage

getMovebankStudies(login)

Arguments

login an object of the MovebankLogin-class, if empty you'll be asked to enter your

username or password

Details

Returns all studies available on Movebank.

Note

See the 'browesMovebank' vignette (move website download section) for more information about security and how to use Movebank from within R.

Author(s)

getMovebankStudy 17

Description

This function returns information about the requested study like the authors of that study, licence type, citation and more.

Usage

```
getMovebankStudy(study, login)
```

Arguments

study a character string (study name) or the numeric study ID as it is stored on Move-

bank

login an object of the MovebankLogin-class, if empty you'll be asked to enter your

username or password

Note

See the 'browesMovebank' vignette (move website download section) for more information about security and how to use Movebank from within R.

Author(s)

Marco Smolla

leroy	GPS track data from a fisher	

Description

This file includes spatial data from a fisher (*Martes pennanti*). It can be used to test the different functions from the move package.

These location data were collected via a 105g GPS tracking collar (manufactured by E-obs gmbh) and programmed to record the animal's location every 15 minutes, continuously. The collar was deployed from 10 February 2009 through 04 March 2009 on an adult, resident, male fisher, in New York, USA. Scott LaPoint tracked this fisher for part of his dissertation research hoping to better understand how fishers were moving throughout this developed landscape.

Author(s)

Marco Smolla

References

For more information, contact Scott LaPoint <sdlapoint@gmail.com>

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Examples

```
## create a Move object from the data set
data <- move(system.file("extdata","leroy.csv",package="move"),proj=CRS("+proj=longlat"))</pre>
```

lines

Plotting a track as lines

Description

Function for plotting a recorded track from a Move object as lines

Usage

```
## S4 method for signature 'Move'
lines(x,add=FALSE,...)
```

Arguments

x Move object

add if TRUE the lines are added to a plot

... arguments to be passed on, e.g. col for color, or add to add the lines to a plot.

Author(s)

Marco Smolla

Examples

```
load(system.file("extdata", "leroy.RData", package="move"), .GlobalEnv)
#plot the track of a single individual, with additional parameters
lines(data, col="#428536", lwd=2)
```

move

Create a Move object

Description

The move method creates a Move object from a Movebank file. Additionally the projection method must be set with the 'proj' argument.

An alternative to this method is to import one's own data, and specify the location and timestamp columns.

Usage

```
## S4 method for signature 'character, ANY, ANY, ANY, ANY, ANY'
move(x, proj)
## S4 method for signature 'numeric, numeric, POSIXct, data.frame, CRS, character'
move(x, y, time, data, proj, animal, species="sp", study="std",...)
```

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Arguments

X	Full path to the file location, OR column indicator for non-Movebank data for the x coordinates; e.g. data\$x
у	column indicator for non-Movebank data for the y coordinates
time	column indicator for non-Movebank data for the time stamps, with POSIXct conversion, i.e. as.POSIXct(data\$timestamp, format="%Y-%m-%d %H:%M:%S", tz="UTC")
data	full parh of the location of the non-Movebank file
proj	projection method for non-Movebank data; requires a valid CRS (see CRS-class) object, like CRS("+proj=longlat +ellps=WGS84")
animal	animal ID or name, either single character or a vector with length of the number of coordinates
species	name of the species
study	name of the study
	Additional arguments

Details

There are two ways to import data to make a Move object. Either the path to a file downloaded from www.Movebank.org is set for the x argument, or the file is first imported with the base read.csv function and then the columns with the x and y coordinates, and the timestamp, as well as the whole data.frame of the imported data are given to the move function.

Note

The imported data set is checked whether it is in a Movebank format. If this is not the case, you have to use the alternative import for non-Movebank data.

Because the SpatialPointsDataFrame function that creates the spatial data frame (sdf) of the Move object can not process NA location values, all rows with NA locations are omitted. A list of the omitted timestamps is stored in the timesMissedFixes argument of the Move object.

If the data include double timestamps check your data for valitdity. You may want to consider a function to delete double timetamps, like:

```
data <- data[which(!duplicated(data$timestamp)), ]</pre>
```

Author(s)

Marco Smolla

```
## create a move object from a Movebank csv file
data <- move(system.file("extdata","leroy.csv",package="move"),proj=CRS("+proj=longlat"))

## create a move object from non-Movebank data
file <- read.table(system.file("extdata","leroy.csv",package="move"), header=TRUE, sep=",", dec=".")
data <- move(x=file$location.long, y=file$location.lat, time=as.POSIXct(file$timestamp, format="%Y-%m-%d %left")</pre>
```

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Move-class

The Move class

Description

The Move object is created with the move function. It is the required object class for the brownian.bridge.dyn function which calculates the utilization density.

Slots

```
animal Object of class "character": animal ID or name;
species Object of class "character": species name;
dateCreation Object of class "numeric": time stamp when the file was downloaded;
study Object of class "character": name of the study;
citation Object of class "character": how to cite the study;
license Object of class "character": the license under which the data were publicated;
timesMissedFixes Object of class "POSIXct": stores the timestamps of lines of the data set that
    were removed because they included NA locations
bbox belongs to the SpatialPointsDataFrame
coords coordinates of the track, belongs to the SpatialPointsDataFrame
coords.nrs belongs to the SpatialPointsDataFrame
data additional data of that object that is stored in the SpatialPointsDataFrame
proj4string projection of the coordinates
timestamps timestamps according to the coordinates
```

Methods

```
move signature(object = "Move"): creates a Move object
getMovebankData signature(object = "character"): creates a Move object by accessing Move-
bank
spTransform signature(object = "Move"): transforms coordinates to a different projection
    method
show signature(object = "Move"): prints a summary of all data stored in the Move object
as.data.frame signature(object = "Move"): extracts the spatial data frame
coordinates signature(object = "Move"): extracts the coordinates only from the Move object
proj4string signature(object = "Move"): extracts the projection method from the Move object
time.lag signature(object = "Move"): calculates time lags between coordinates
n.locs signature(object = "Move"): calculates number of locations
plot signature(object = "Move"): plots the track of the animal
```

Author(s)

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ogin into Movebank

Description

Creates an object that can be used with all Movebank browsing functions.

Usage

```
## S4 method for signature 'character, character'
movebankLogin(username, password)
```

Arguments

username Your Movebank username
password Your Movebank password

Details

Use this function to login to Movebank. After you logged in, you can use the Movebank browsing functions from the move package.

Note

If you do not have the RCurl package installed movebankLogin will store your username and password in the object you assign it to. Furthermore, if you have no RCurl a http connection is used to retrieve data from Movebank instead of the more secure https protocol.

Author(s)

Marco Smolla

```
## Not run:
##first create the login object
login <- movebankLogin{username="xxx", password="zzz"}
##and than use it with Movebank browsing functions
getMovebankStudies(login)
## End(Not run)</pre>
```

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MovebankLogin-class The MovebankLogin class

Description

The MovebankLogin object is needed for every Movebank browsing function. Alternatively, one can also chose to enter the username and password everytime one uses one of the browsing functions.

Slots

```
username username as characterpassword password as characterrcurl logical value, whether RCurl is installed or not
```

Methods

```
movebankLogin signature(object = "character"): creates a MovebankLogin object
```

Author(s)

Marco Smolla

moveStack

Creating a MoveStack

Description

Either stacks a list of Move objects or creates a MoveStack from a Movebank csv file

Usage

```
## S4 method for signature 'list'
moveStack(x)
  ## S4 method for signature 'character'
moveStack(x, proj)
```

Arguments

x a list of Move objects or the path to a csv file as character proj the projection of the coordinates

Details

This function stacks single Move objects to a MoveStack object, or creates a MoveStack from a Movebank file with several individuals.

Author(s)

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Examples

```
## Not run:
    we need more than one test file
## End(Not run)
```

MoveStack-class

The MoveStack class

Description

The MoveStack object is created within the brownian.bridge.dyn function from a Move object. It includes beneath others a raster object and probabilities.

Slots

citation Object of class "dBMvariance": includes the break.list and points of interest, ...;

bbox belongs to the SpatialPointsDataFrame

coords the extension factor set by the user

coords.nrs belongs to the SpatialPointsDataFrame

data additional data of that object that is stored in the SpatialPointsDataFrame

dateCreation date and timestamp when this object was created

idData additional data to all individuals

license the license terms of the used track material

proj4string projection of all coordinates

study name of the study

timestamps timestamps according to the coordinates

trackId a vector that indicates, which data, coordinates and timestamps belong to an individual

Methods

Methods defined with class "MoveStack" in the signature:

```
[ signature(x="MoveStack"): select subset ...
getMovebankData signature(object = "character"): creates a MoveStack object by accessing Movebank
```

Author(s)

24 outerProbability

n.locs

Extract the number of locations of a track from a Move object

Description

The n.locs method returns the number of locations of a track from a Move object.

Usage

```
## S4 method for signature 'Move'
n.locs(obj)
```

Arguments

obj

A Move object

Details

obj a Move object

Author(s)

Marco Smolla

outerProbability

Calculates the probabilities at the edges of a raster

Description

The outerProbability method calculates the summed probability of the cells at the border of a raster

Usage

```
## S4 method for signature 'RasterLayer'
outerProbability(raster,border)
```

Arguments

raster a RasterLayer object that has values for the raster cells

border numeric from 0 to 1; ratio of the number of columns at the border relative to the

whole raster from which the probabilities should be summed up

Author(s)

plot 25

Examples

```
load(system.file("extdata", "leroy.RData", package="move"), .GlobalEnv)

## calculate the probabilities of 20% of the raster at

## the border from the DBBMM object dbbmm
outerProbability(dbbmm, border=.2)

"[1] 0.001669491"
```

plot

Plotting a track or a raster

Description

Function for plotting a recorded track from a Move object or the probability values from a DBBMM object

Usage

```
## S4 method for signature 'Move,missing'
plot(x, google = FALSE, maptype = "terrain", ...)
## S4 method for signature 'MoveStack,missing'
plot(x, google = FALSE, maptype = "terrain", ...)
```

Arguments

X	Move or a DBBMM object
google	logical argument for a Move object. If TRUE, a map from googlemaps is downloaded and the track is plotted on top
maptype	defines the type of map to construct. There are several possible maptype values, including satellite, terrain, hybrid, and mobile.
	arguments to be passed to methods, such as graphical parameters, and the logical add argument (see par)

Details

If x is a Move object a track is plotted with points and lines. The track can be added to another plot with the add = TRUE.

If x is a DBBMM object its raster object is plotted with the corresponding cell values. Unlike the image function, the cell size ratio keeps the same when the plot window is resized.

The google argument works together with a Move object. If TRUE the GetMap function from the RgoogleMaps package generates a URL to download a map that fits with the track. After downloading the map, the track is plotted on top of the map.

Note

If you want to combine e.g. a track and a raster, or a track and a google map, make sure that both objects have the same projection method. Use proj4string to find it out and spTransform to change the projection method of a Move object.

26 plotBursts

Author(s)

Marco Smolla

Examples

```
load(system.file("extdata", "leroy.RData", package="move"), .GlobalEnv)

## plot a Move object
plot(data)

#to plot a google map with overlayed track
plot(data, google=TRUE)

## add a track from a Move object to a plot
lines(data, add=TRUE)

## plot the raster of a DBBMM object
plot(dbbmm)
```

plotBursts

Plotting the centroids of a track

Description

Plotting centroids ...

Usage

```
## S4 method for signature 'list'
plotBursts(object, add=TRUE, ...)
  ## S4 method for signature 'SpatialPointsDataFrame'
plotBursts(object, add, ...)
```

Arguments

object a SpatialPointsDataFrame or a list of these that include coordinates and color, and size of the centroid indicators

add logical, if FALSE a new plot is generated. Default value is TRUE

additional plot attributes

Details

The SpatialPointsDataFrame that should be used here is generated by burstTrack.

Note

••

Author(s)

points 27

Examples

```
## Not run:
we need an anotated file here
## End(Not run)
```

points

Plotting a track as points

Description

Function for plotting a recorded track from a Move object as points

Usage

```
## S4 method for signature 'Move'
points(x,add=FALSE,...)
```

Arguments

x Move or a DBBMM object

add if TRUE the points are added to a plot

... arguments to be passed on, e.g. col for color, or add to add the points to a plot.

Author(s)

Marco Smolla

raster

Extract raster from DBBMM

Description

raster plot of a RasterLayer from a DBBMM object.

Usage

```
## S4 method for signature 'DBBMM' raster(x)
```

Arguments

Х

a DBBMM object

Details

The raster function extraxcts the raster object from the DBBMM object.

28 raster2contour

Value

An object from class RasterLayer is returned.

Author(s)

Marco Smolla

raster2contour

Convert raster to contour lines

Description

The funciton converts a raster object to a SpatialLinesDataFrame.

Usage

```
## S4 method for signature 'RasterLayer'
raster2contour(x, ...)
```

Arguments

x a RasterLayer or a DBBMM object

... additional arguments that are passed on from other functions

Details

The raster2contour function creates a SpatialLinesDataFrame from a given raster or DBBMM object. This allows to reproject the contours to different projections.

Author(s)

Marco Smolla

```
load(system.file("extdata", "leroy.RData", package="move"), .GlobalEnv)
raster2contour(dbbmm)
```

searchMovebankStudies 29

```
searchMovebankStudies Search for a study
```

Description

Searches for a study within movebank

Usage

```
searchMovebankStudies(x, login, sensor = FALSE)
```

Arguments

x a character string to search within the Movebank study names

login an object of the MovebankLogin-class, if empty you'll be asked to enter your

username or password

sensor logical, if TRUE you can search for studies using a certain sensor type. Default

is FALSE (not implemented yet)

Details

The search function searches explicitly for the entered phrase. If you for example type 'Goose' it will not show you studies including 'goose'. So rather search for 'oose' to find both.

Note

See the 'browesMovebank' vignette (move website download section) for more information about security and how to use Movebank from within R.

Author(s)

Marco Smolla

show Show a Move object

Description

Displays a summary of a Move object.

Usage

```
## S4 method for signature 'Move'
show(object)
  ## S4 method for signature 'MoveStack'
show(object)
```

Arguments

object a Move or MoveStack object

30 split

Details

The show function displays a summary of a Move object. This includes:

- animal ID
- species name
- study name
- · number of track points
- · receiver type
- · projection method
- · date of file creation
- the first three lines of the spatial data frame
- · study citation
- · data license
- number of omitted locations due to NAs in the dataset

If the imported data are not from the Movebank database Animal, Species, nPoints, Receiver, and Study are not shown.

Author(s)

Marco Smolla

split

Splitting a MoveStack

Description

Splitting MoveStack in a list of Move objects

Usage

```
## S4 method for signature 'MoveStack,missing'
split(x, f, drop=FALSE, ...)
```

Arguments

Χ	MoveStack object
f	not needed
drop	not needed
	not needed

Details

A MoveStack is splitted into a list of Move objects by the trackIds of the given MoveStack. To stack this list again moveStack can be used.

Author(s)

spTransform 31

Examples

##we would need a moveStack object right here

spTransform Move object projection method	spTransform	Transform Move object projection method	
---	-------------	---	--

Description

The spTransform function transforms the coordinates stored in the Move object from the default longlat coordinates to the default aequd projection method or a different projection.

Usage

```
## S4 method for signature 'Move,character'
spTransform(x,CRSobj,center=FALSE)
    ## S4 method for signature 'Move,missing'
spTransform(x,center=FALSE,...)
```

Arguments

X	a Move or a MoveStack object
CRSobj	a CRS like character that describes the projection method to which the coordinates should be transformed, if missing "+proj=aequd" is used as default value
center	logical, if TRUE the center of the coordinate system is the center of the track; FALSE is default
	for additional arguments

Details

The spTransform function transforms the coordinates of a Move object by default from "+proj=longlat" to "+proj=aeqd". In this format the coordinates can be used by the brownian.bridge.dyn function.

If center is TRUE the center of the coordinate system is set to the center of the track.

Author(s)

Marco Smolla

```
## create a Move object
data <- move(system.file("extdata","leroy.csv",package="move"),proj=CRS("+proj=longlat"))
## transform the Move object by default into "+aeqd" projection method
## and center the coordinate system
data2 <- spTransform(data, center=TRUE)

## transform the Move object into another projection method, like mollweide
data3 <- spTransform(data, CRSobj="+proj=moll")

##check projection method</pre>
```

32 summary

```
proj4string(data)
"[1] +proj=longlat +ellps=WGS84"
proj4string(data2)
"[1] +proj=longlat +lon_0=-73.8871629 +lat_0=42.73884025 +ellps=WGS84"
proj4string(data3)
"[1] +proj=moll +ellps=WGS84"
```

subset-method

Returns a single object from a MoveStack

Description

Returning a single Move object

Usage

```
## S4 method for signature 'MoveStack,ANY,ANY' x[i]
```

Arguments

x MoveStack object

i numeric, number of position in the stack

Author(s)

Marco Smolla

summary

A summary of a DBBMM or Move object

Description

Summarizes the information of the raster from a DBBMM or the data from a Move object

Usage

```
## S4 method for signature 'DBBMM'
summary(object)
  ## S4 method for signature 'Move'
summary(object)
```

Arguments

object

a DBBMM or Move object

Details

Returns the projection, extent, and maximum and minimum values of the raster stored within the DBBMM object.

time.lag 33

Author(s)

Marco Smolla

time.lag

Calculates the time lags between the coordinates

Description

The time.lag function calculates the time lags between locations.

Usage

```
## S4 method for signature 'Move'
time.lag(x,...)
```

Arguments

x a Move object... further arguments

Details

Optionally the argument units can be passed on to ensure the time lag in a certain unit. For more information on the units argument see the help of difftime.

Value

The function returns numeric vector time lags.

Author(s)

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