A User's Guide to the POT Package (Version 1.1)

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1 Introduction

1.1 Why the POT package?

The

1.6 Legalese

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z 0, Coles et al. (1999) Fse the Fniform distribFtion on [0]

3.2 Threshold Selection

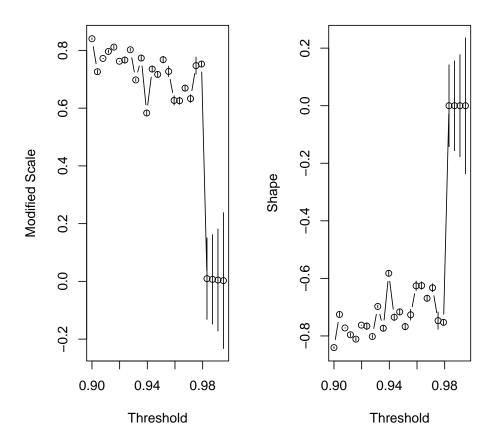


Figure 1: The threshold selection using the tcplot function

Mean Residual Life Plot

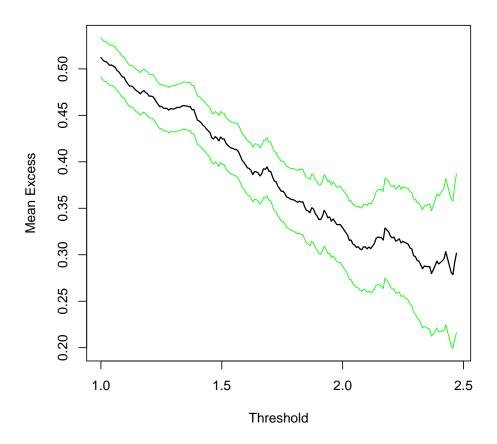


Figure 2: The threshold selection using the mrlplot function

The quantity $E[X-\mu_1/X>\mu_1]$ is linear in μ_1 . Or, $E[X-\mu_1/X>\mu_1]$ is simply the mean of excesses above the threshold μ_1

3.2.3 L-Moments plot: Imomplot

L-moments are summary statistics for probability distributions and data samples. They are analogous to ordinary moments – they provide measures of location, dispersion, skewness, kurtosis, and other aspects of the shape of probability distributions or data samples – but are computed from linear combinations of the ordered data values (hence the prefix L).

For the GPD, the following relation holds:

$$3^4 = 3 \frac{1+5}{5+}$$

L-Moments Plot

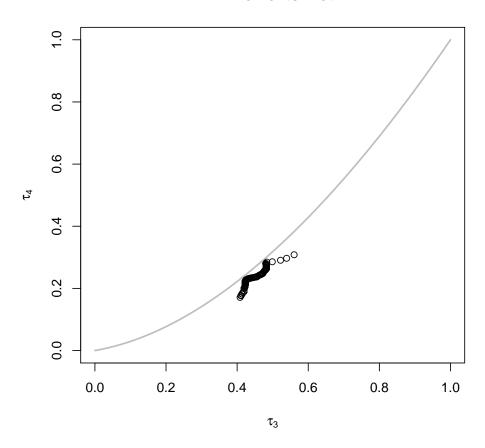


Figure 3: fig: The threshold selection using the Imomplot function

Dispersion Index Plot

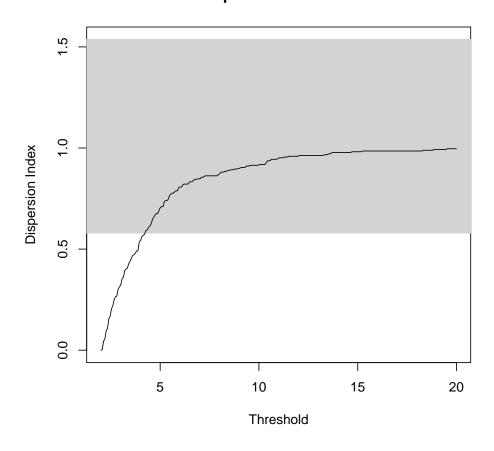


Figure 4: The threshold selection using the diplot function

3.3 Fitting the GPD

3.3.1 The univariate case

The main function to fit the GPD is called **fitgpd**. This is a generic function which can fit the GPD

Standard Error Type: observed

Standard Errors scale 0.2257

Asymptotic Variance Covariance scale scale 0.05094

Optimization Information Convergence: successful Function Evaluations: 6 Gradient Evaluations: 1

> fitgpd(x, thresh = 1, scale = 2, method = "mle")

Estimator: MLE
Deviance: 363.0409
AIC: 365.0409

Varying Threshold: FALSE

scal e1 shape1 scal e2 shape2 al pha 7. 299e-02 4. 474e-02 3. 098e-02 3. 381e-02 2. 001e-06

Asymptotic Variance Covariance

	scal e1	shape1	scal e2	shape2	al pha
scal e1	5.327e-03	-2. 155e-03	2.007e-06	-1.397e-06	2.200e-11
shape1	-2.155e-03	2.002e-03	-1.774e-07	3.600e-07	-7.491e-11
scal e2	2.007e-06	-1.774e-07	9.597e-04	-8.989e-04	1.712e-11
shape2	-1.397e-06	3.600e-07	-8.989e-04	1.143e-03	-1.930e-11
al pha	2.200e-11	-7. 491e-11	1.712e-11	-1.930e-11	4.003e-12

Optimization Information

Convergence: successful Function Evaluations: 99 Gradient Evaluations: 9

In the summary, we can see $\lim_{u \to u} \Pr[X_1 > u \mid X_2 > u] = 0.02$. ThiTf186.07670Td[(.)570Td[(.78(su)1(mmarTf2))]

Pickands' Dependence Function

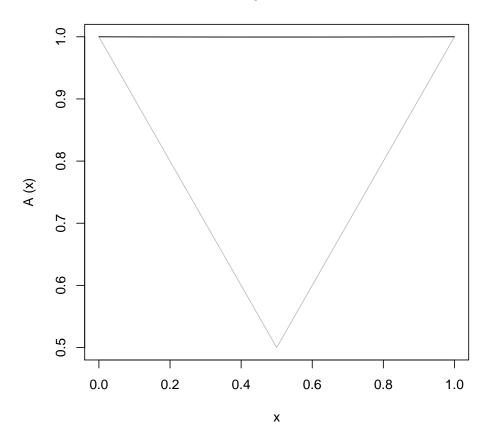


Figure 5: The Pickands' dep8nd8nce function

Optimization Information

Convergence: successful Function Evaluations: 53 Gradient Evaluations: 8

Note that as all bivariate ex(i)1(o)reme value dis1(o)ributions are asymptotically dep8nd8ns1(b)atis1(o)ic of Coles et al. (1999) is always equal to 1.

Another way to detect the s1(o)r8ngth of dep8nd8nce is to plot the Pickands' dep8nd8nce function – see Figure 5. This is simply done with the **pickdep** function.

> pi ckdep(MI og)

The horizontal line corresponds to indep8nd8nce while the other ones corresponds to p8rfect dep8nd8nce. Please note that by cons1(o)ruction, theixed and asymetrojc mixed mod8ls can not mod8l p8rfect dep8nd8nce variables.

3.3.3 Markov Chains for Exceedances

structure using a Markov Chains while the joint distribution is obviously a multivariate extreme value distribution. This idea was first introduces by Smith et al. (1997).

In the remainder of this section, we will only focus with first order Markov Chains. Thus, the likelihood for all exceedances is:

$$L(y_1,...,y_n; ,) = \frac{\prod_{i=2}^n f(y_{i-1},y_i; ,)}{\prod_{i=2}^{n-1} f(y_i;)}$$

```
> x <- rgpd(200, 1, 2, 0.25)
> mle <- fitgpd(x, 1, method = "mle")
> mom <- fitgpd(x, 1, method = "moments")
> pwmb <- fitgpd(x, 1, method = "pwmb")
> pwmu <- fitgpd(x, 1, method = "pwmu")
> gpd. fiscale(mle, conf = 0.9)
```

If there is some troubles try to put vert.lines = FALSE or change
 the range...
conf.inf conf.sup
1.374242 2.045960

If there is some troubles try to put vert.lines = FALSE or change
the range...
conf.inf conf.sup
0.2454545 0.5424242

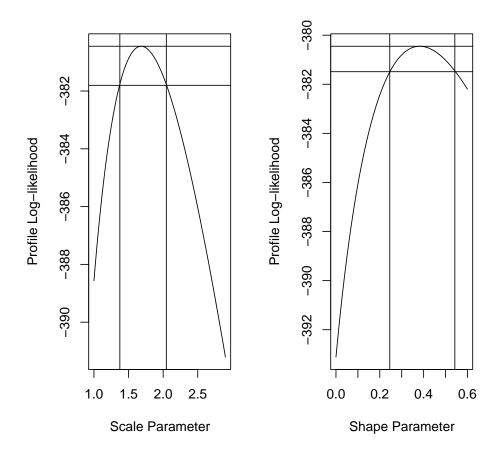


Figure 6: The profile log-likelihood confidence intervals

conf.inf conf.sup 7.420834 12.678397

thn...
conf.inf conf.sup

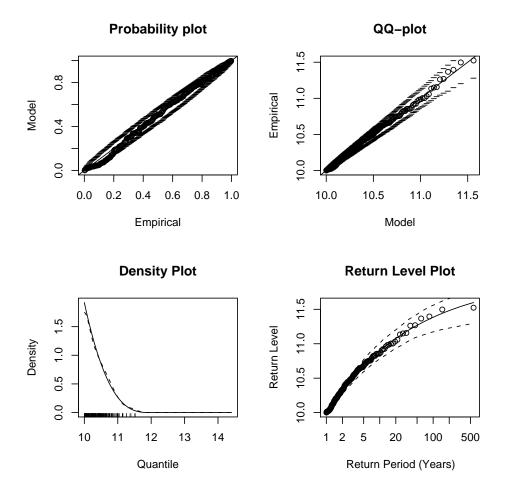


Figure 8: Graphical diagnostic for a fitted POT model (univariate case)

3.5 Model Checking

To check the fitted model, users must call function **plot** which has a method for the uvpot, bvpot and mcpot classes. For example, this is a generic function which calls functions: pp (probability/probability plot), qq (quantile/quantile plot), dens

r which = 4 for a return level plot;

Note that "which" can be a vector like c(1, 3) or 1: 3.

Thus, the following instruction gives the same graphic.

```
> plot(fitted, which = 1)
> pp(fitted)
```

If a return level plot is asked (4 which), a value for npy is needed. "npy" corresponds to the *mean number of events per year*. This is required o (i.e. 1) will be chosen.

3.6 Declustering Techniques

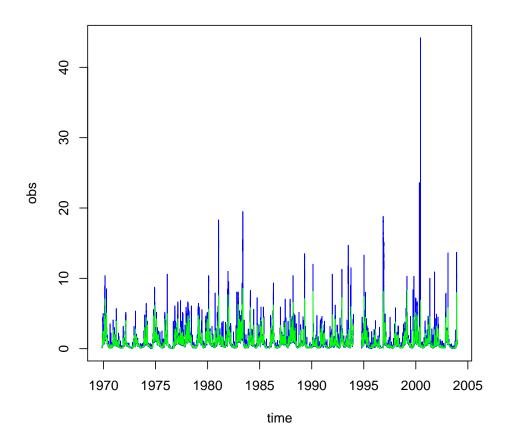


Figure 10: Instantaneous flood discharges and averaged dischaged over duration 3 days. Data ardieres

time Min. :1970 1st Qu.:1981 Median :1991 Mean :1989 3rd Qu.:1997 Max. :2004	obs Min. : 0.022 1st Qu.: 0.236 Median : 0.542 Mean : 1.024 3rd Qu.: 1.230 Max. : 44.200 NA's : 1.000		
	Mean Residual Life Plot		Dispersion Index Plot
Mean Excess 0 5 10 15 20	5 10 15 Threshold	Dispersion Index	0: 0: 0: 0 10 20 30 40 Threshold
Modified Scale -100 -60 -20 20		Shape	1 2 3 4 5

Figure 11: Threshold selection for river Ardières at Beaujeu.

10

Threshold

15

5

10

Threshold

15

5

The result of function **fitgpd** gives the name of the estimator, if a varying threshold was used, the threshold value, the number and the proportion of observations above the threshold, parameter estimates, standard error estimates and type, the asymptotic variance-covariance matrix and convergence diagnostic.

Figure 12 shows graphic diagnostics for the fitted model. It can be seen that the fitted model "mle" seems to be appropriate. Suppose we want to know the return level associated to the 100-year return period.

If there is some troubles try to put vert.lines = FALSE or change the range...

A Dependence Models for Bivariate Extreme Value Distributions

A.1 The Logisitic model

The logisitic model is defined by:

$$V(x,y) = x^{-1/} + y^{-1/}$$
, 0 <

A.5 The Mixed model

- Liang Peng and A.H. Welsh. Robust estimation of the generalized pareto distribution. *Extremes*, 4(1): 53–65, 2001.
- J. Pickands. Multivariate extreme value distributions. In *Proceedings 43rd Session International Statistical Institute*, 1981.