

Package ‘ReacTran’

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Title Reactive transport modelling in 1D, 2D and 3D

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Depends R (>= 2.01), rootSolve, deSolve, shape

Description Routines for developing models that describe reaction and advective-diffusive transport in one, two or three dimensions. Includes transport routines in porous media, in estuaries, and in bodies with variable shape.

License GPL

LazyData yes

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Description

The R-package ReacTran contains routines that enable the development of reactive transport models in aquatic systems (rivers, lakes), porous media (floc aggregates, sediments,...) and even idealized organisms (spherical cells, cylindrical worms,...). The geometry of the model domain is either one-dimensional, two-dimensional or three-dimensional.

It contains:

- Functions to setup a finite-difference grid (1D or 2D)
- Functions to attach parameters and properties to this grid (1D or 2D)
- Functions to calculate the advective-diffusive transport term over the grid (1D, 2D, 3D)
- Utility functions

Details

Package:	ReacTran
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Date:	2009-05-31
License:	GNU Public License 2 or above

Author(s)

Karline Soetaert (Maintainer)

Filip Meysman

Examples

```
## Not run:
## show examples (see respective help pages for details)
example(tran.1D)
example(tran.2D)
example(tran.3D)
example(tran.volume.1D)

## open the directory with documents
browseURL(paste(system.file(package="ReacTran"), "/doc", sep=""))

## End(Not run)
```

Description

Weighing coefficients used in the finite difference scheme for advection calculated according to Fiadeiro and Veronis (1977).

This particular AFDW (advective finite difference weights) scheme switches from backward differencing (in advection dominated conditions; large Peclet numbers) to central differencing (under diffusion dominated conditions; small Peclet numbers).

This way it forms a compromise between stability, accuracy and reduced numerical dispersion.

Usage

```
fiadeiro(v, D, dx.aux=NULL, grid=list(dx.aux=dx.aux))
```

Arguments

<code>v</code>	advective velocity; either one value or a vector of length $N+1$, with N the number of grid cells $[L/T]$.
<code>D</code>	diffusion coefficient; either one value or a vector of length $N+1$ $[L^2/T]$.
<code>dx.aux</code>	auxiliary vector containing the distances between the locations where the concentration is defined (i.e. the grid cell centers and the two outer interfaces); either one value or a vector of length $N+1$.
<code>grid</code>	discretization grid as calculated by <code>setup.grid.1D</code> .

Details

The Fiadeiro and Veronis (1977) scheme adapts the differencing method to the situation at hand (checks for advection or diffusion dominance).

Finite difference schemes are based on following rationale:

- When using forward differences (AFDW = 0), the scheme is first order accurate, creates a low level of (artificial) numerical dispersion, but is highly unstable (state variables may become negative).
- When using backward differences (AFDW = 1), the scheme is first order accurate, is universally stable (state variables always remain positive), but the scheme creates high levels of numerical dispersion.
- When using central differences (AFDW = 0.5), the scheme is second order accurate, is not universally stable, and has a moderate level of numerical dispersion, but state variables may become negative.

Because of the instability issue, forward schemes should be avoided. Because of the higher accuracy, the central scheme is preferred over the backward scheme.

The central scheme is stable when sufficient physical dispersion is present, it may become unstable when advection is the only transport process.

The Fiadeiro and Veronis (1977) scheme takes this into account: it uses central differencing when possible (when physical dispersion is high enough), and switches to backward differencing when needed (when advection dominates). The switching is determined by the Peclet number

$$Pe = \text{abs}(v) * dx.aux / D.$$

- the higher the diffusion D ($Pe > 1$), the closer the AFDW coefficients are to 0.5 (central differencing)
- the higher the advection v ($Pe < 1$), the closer the AFDW coefficients are to 1 (backward differencing)

Value

the Advective Finite Difference Weighing (AFDW) coefficients as used in the transport routines `tran.1D` and `tran.volume.1D`; either one value or a vector of length $N+1$

Note

- If the state variables (concentrations) decline in the direction of the 1D axis, then the central difference scheme will be stable. If this is known a priori, then central differencing is preferred over the fiadeiro scheme.
- Each scheme will always create some numerical diffusion. This principally depends on the resolution of the grid (i.e. larger `dx.aux` values create higher numerical diffusion). In order to reduce numerical dispersion, one should increase the grid resolution (i.e. decrease `dx.aux`).

Author(s)

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References

- Fiadeiro ME and Veronis G (1977) Weighted-mean schemes for finite-difference approximation to advection-diffusion equation. *Tellus* 29, 512-522.
- Boudreau (1997) Diagenetic models and their implementation. Chapter 8: Numerical Methods. Springer.

Examples

```
#####
# Model formulation (set of differential equations)
#####

# This is a test model to evaluate the different finite difference schemes
# and evaluate their effect on numerical diffusion. The model describes the
# decay of organic carbon (OC) as it settles through the ocean water column.

model <- function (time, OC, pars, AFDW=1)
{
  dOC <- tran.1D(OC, flux.up=F_OC, D=D.eddy, v=v.sink, AFDW=AFDW, dx=dx) $dC - k*OC
  return(list(dOC))
}

#####
# Parameter set
#####

L <- 1000          # water depth model domain [m]
x.att <- 200       # attenuation depth of the sinking velocity [m]
v.sink.0 <- 10     # sinking velocity at the surface [m d-1]
D.eddy <- 10       # eddy diffusion coefficient [m2 d-1]
```

```

F_OC <- 10          # particle flux [mol m-2 d-1]
k <- 0.1            # decay coefficient [d-1]

#=====
# Model solution for a coarse grid (10 grid cells)
#=====

# Setting up the grid
N <- 10              # number of grid layers
dx <- L/N            # thickness of boxes [m]
dx.aux <- rep(dx, (N+1)) # auxilliary grid vector
x.int <- seq(from=0, to=L, by=dx) # water depth at box interfaces [m]
x.mid <- seq(from=dx/2, to=L, by=dx) # water depth at box centres [m]

# Exponentially declining sink velocity
v.sink <- v.sink.0*exp(-x.int/x.att) # sink velocity [m d-1]
Pe <- v.sink*dx/D.eddy                # Peclet number

# Calculate the weighing coefficients
AFDW <- fiadeiro(v=v.sink, D=D.eddy, dx.aux=dx.aux)

par(mfrow=c(2,1), cex.main=1.2, cex.lab=1.2)

# Plot the Peclet number over the grid

matplot(Pe, x.int, log="x", pch=19, ylim=c(L, 0), xlim=c(0.1, 1000),
  xlab="", ylab="depth [m]", main=expression("Peclet number"), axes=FALSE)
abline(h = 0)
axis(pos=NA, side=2)
axis(pos=0, side=3)

# Plot the AFDW coefficients over the grid

matplot(AFDW, x.int, pch=19, ylim=c(L, 0), xlim=c(0.5, 1),
  xlab="", ylab="depth [m]", main=expression("AFDW coefficient"), axes=FALSE)
abline(h = 0)
axis(pos=NA, side=2)
axis(pos=0, side=3)

# Three steady-state solutions for a coarse grid based on:
# (1) backward differences (BD)
# (2) central differences (CD)
# (3) Fiadeiro & Veronis scheme (FV)

BD <- steady.band(y=runif(N), func=model, AFDW=1.0, nspec=1)$y
CD <- steady.band(y=runif(N), func=model, AFDW=0.5, nspec=1)$y
FV <- steady.band(y=runif(N), func=model, AFDW=AFDW, nspec=1)$y
CONC <- cbind(BD, CD, FV)

par(mfrow=c(1,2))

# Plotting output
matplot(CONC, x.mid, pch=16, type="b", ylim=c(L, 0),
  xlab="", ylab="depth [m]", main=expression("conc (Low resolution grid)"),
  axes=FALSE)
abline(h = 0)
axis(pos=0, side=2)

```

```

axis(pos=0, side=3)
legend("bottomright",
legend=c("backward diff", "centred diff", "Fiadeiro&Veronis")
,col=c(1:3),lty=c(1:3),pch=c(16,16,16))

#=====
# Model solution for a fine grid (1000 grid cells)
#=====

# Setting up the grid
N <- 1000                                # number of grid layers
dx <- L/N                                # thickness of boxes[m]
dx.aux <- rep(dx, (N+1))                  # auxilliary grid vector
x.int <- seq(from=0,to=L,by=dx)           # water depth at box interfaces [m]
x.mid <- seq(from=dx/2,to=L,by=dx)        # water depth at box centres [m]

# Exponentially declining sink velocity
v.sink <- v.sink.0*exp(-x.int/x.att)      # sink velocity [m d-1]
Pe <- v.sink*dx/D.eddy                    # Peclet number

# Calculate the weighing coefficients
AFDW <- fiadeiro(v=v.sink,D=D.eddy,dx.aux=dx.aux)

# Three steady-state solutions for a coarse grid based on:
# (1) backward differences (BD)
# (2) centered differences (CD)
# (3) Fiadeiro & Veronis scheme (FV)

BD <- steady.band(y=runif(N), func=model, AFDW=1.0, nspec=1)$y
CD <- steady.band(y=runif(N), func=model, AFDW=0.5, nspec=1)$y
FV <- steady.band(y=runif(N), func=model, AFDW=AFDW, nspec=1)$y
HR_CONC <- cbind(BD,CD,FV)

# Plotting output
matplot(HR_CONC,x.mid,pch=16,type="b",ylim=c(L,0),
xlab="",ylab="depth [m]",main=expression("conc (High resolution grid)"),
axes=FALSE)
abline(h = 0)
axis(pos=0, side=2)
axis(pos=0, side=3)
legend("bottomright",
legend=c("backward diff", "centred diff", "Fiadeiro&Veronis")
,col=c(1:3),lty=c(1:3),pch=c(16,16,16))

# Results and conclusions:
# - For the fine grid, all three solutions are identical
# - For the coarse grid, the BD and FV solutions show numerical dispersion
#   while the CD is stable and provides more accurate results

```

Description

- g.sphere the surface and volume of a sphere

- `g.spheroid` the surface and volume of a spheroid
- `g.cylinder` the surface and volume of a cylinder; note that the surface are calculation ignores the top and bottom.

Usage

```
g.sphere(x)
```

```
g.spheroid(x, b=1)
```

```
g.cylinder(x, L=1)
```

Arguments

x	the radius
b	the ratio of long/short radius of the spheroid; if $b < 1$: the spheroid is oblate.
L	the length of the cylinder

Value

A list containing:

surf	the surface area
vol	the volume

Author(s)

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Examples

```
mf <- par(mfrow=c(3,2))
x <- seq(from=0,to=1,length=10)
plot(x, g.sphere(x)$surf,main="sphere surface")
plot(x, g.sphere(x)$vol,main="sphere volume")
plot(x, g.spheroid(x,b=0.5)$surf,main="spheroid surface")
plot(x, g.spheroid(x,b=0.5)$vol,main="spheroid volume")
plot(x, g.cylinder(x,L=1)$surf,main="cylinder surface")
plot(x, g.cylinder(x,L=1)$vol,main="cylinder volume")
par("mfrow"=mf)
```

p.exp

Common dependencies of one-dimensional properties with distance, to be used with setup.prop.1D

Description

Functions that define an y-property as a function of the one-dimensional x-coordinate. These routines can be used to specify properties and parameters as a function of distance, e.g. depth in the water column or the sediment.

They make a transition from an upper (or upstream) zone, with value `y.0` to a lower zone with a value `y.inf`.

Particularly useful in combination with [setup.prop.1D](#)

- `p.exp`: exponentially decreasing transition

$$y = y_{inf} + (y_0 - y_{inf}) \exp(-\max(0, x - x_0)/x_a)$$

- `p.lin`: linearly decreasing transition

$$y = y_0; y = y_0 - (y_0 - y_{inf}) * (x - x_L)/x_{att}; y = y_{inf}$$

for $0 \leq x \leq x_L$, $x_L \leq x \leq x_L + x_{att}$ and $(x \geq x_L + x_{att})$ respectively.

- `p.sig`: sigmoidal decreasing transition

$$y = y_{inf} + (y_0 - y_{inf}) \frac{\exp(-(x - (x_L + 0.5x_{att}))/0.25x_{att}))}{(1 + \exp(-(x - (x_L + 0.5 * x_{att}))/0.25x_{att}))}$$

Usage

```
p.exp(x, y.0=1, y.inf=0.5, x.L=0, x.att=1)
```

```
p.lin(x, y.0=1, y.inf=0.5, x.L=0, x.att=1)
```

```
p.sig(x, y.0=1, y.inf=0.5, x.L=0, x.att=1)
```

Arguments

<code>x</code>	the x-values for which the property has to be calculated.
<code>y.0</code>	the y-value at the origin
<code>y.inf</code>	the y-value at infinity
<code>x.L</code>	the x-coordinate where the transition zone starts; for $x \leq x.L$, the value will be equal to <code>y.0</code> . For $x \gg x.L + x.att$ the value will tend to <code>y.inf</code>
<code>x.att</code>	attenuation coefficient in exponential decrease, or the size of the transition zone in the linear and sigmoid decrease

Details

For `p.lin`, the width of the transition zone equals `x.att` and the depth where the transition zone starts is `x.L`.

For `p.sig`, the transition is smooth, but most pronounced in the transition zone.

For `p.exp`, there is no clearly demarcated transition zone; there is an abrupt change at `x.L` after which the property exponentially changes from `y.0` towards `y.L` with attenuation coefficient `x.att`; the larger `x.att` the less steep the change.

Value

the property value, estimated for each x-value.

Author(s)

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Examples

```
x<- seq(0,5,len=100)
plot(x, p.exp(x,x.L=2),xlab="x.coordinate", ylab="y value",ylim=c(0,1))
lines(x, p.lin(x,x.L=2),col="blue")
lines(x, p.sig(x,x.L=2),col="red")
```

```
setup.compaction.1D
```

Calculates the advective velocities of the pore water and the solid phase in a water saturated sediment assuming steady state compaction

Description

This function calculates the advective velocities of the pore water and the solid phase in a sediment based on the assumption of steady state compaction.

The velocities of the pore water (*u*) and the solid phase (*v*) are calculated in the middle (*mid*) of the grid cells and the interfaces (*int*).

One needs to specify the porosity at the interface (*por.0*), the porosity at infinite depth (*por.inf*), the porosity profile (*por.grid*) encoded as a 1D grid property (see [setup.prop.1D](#), as well as the advective velocity of the solid phase at one particular depth (either at the sediment water interface (*v.0*) or at infinite depth (*v.inf*)).

Usage

```
setup.compaction.1D(v.0 = NULL, v.inf = NULL, por.0, por.inf,
  por.grid)
```

Arguments

<i>v.0</i>	advective velocity of the solid phase at the sediment-water interface (also referred to as the sedimentation velocity); if <i>NULL</i> then <i>v.inf</i> must not be <i>NULL</i> [L/T]
<i>v.inf</i>	advective velocity of the solid phase at infinite depth (also referred to as the burial velocity); if <i>NULL</i> then <i>v.0</i> must not be <i>NULL</i> [L/T]
<i>por.0</i>	porosity at the sediment-water interface
<i>por.inf</i>	porosity at infinite depth
<i>por.grid</i>	porosity profile specified as a 1D grid property (see setup.prop.1D for details on the structure of this list)

Value

A list containing:

- u list with pore water advective velocities at the middle of the grid cells (*mid*) and at the grid cell interfaces (*int*).
- v list with solid phase advective velocities at the middle of the grid cells (*mid*) and at the grid cell interfaces (*int*).

Author(s)

Filip Meysman <f.meysman@nioo.knaw.nl>, Karline Soetaert <k.soetaert@nioo.knaw.nl>

References

Meysman, F. J. R., Boudreau, B. P., Middelburg, J. J. (2005) Modeling Reactive Transport in Sediments Subject to Bioturbation and Compaction. *Geochimica Et Cosmochimica Acta* 69, 3601-3617

Examples

```
# setup of the 1D grid

L <-10
grid <- setup.grid.1D(x.up=0,L=L,N=20)

# attaching an exponential porosity profile to the 1D grid
# this uses the "p.exp" profile function

por.grid <- setup.prop.1D(func=p.exp,grid=grid,y.0=0.9,y.inf=0.5,x.att=3)

# calculate the advective velocities

dummy <- setup.compaction.1D(v.0=1, por.0=0.9, por.inf=0.5, por.grid=por.grid)
u.grid <-dummy$u
v.grid <-dummy$v

# plotting the results

par(mfrow=c(2,1),cex.main=1.2,cex.lab=1.2)

matplot(por.grid$int,grid$x.int,pch=19,ylim=c(L,0), xlim=c(0,1),
xlab="",ylab="depth [cm]",main=expression("porosity"),axes=FALSE)
abline(h = 0)
axis(pos=0, side=2)
axis(pos=0, side=3)

matplot(u.grid$int,grid$x.int,type="l",lwd=2,col="blue",ylim=c(L,0),
xlim=c(0,max(u.grid$int,v.grid$int)),
xlab="",ylab="depth [cm]",main=expression("advective velocity [cm yr-1]"),
axes=FALSE)
abline(h = 0)
axis(pos=0, side=2)
axis(pos=0, side=3)
lines(v.grid$int,grid$x.int,lwd="2",col="red")
legend(x="bottomright", legend=c("pore water","solid phase"),
col=c("blue","red"),lwd=c(2,2))
```

 setup.grid.1D

 Creates a one-dimensional finite difference grid

Description

Subdivides the one-dimensional model domain into one or more zones that are each sub-divided into grid cells. The resulting grid structure can be used in the other `ReacTran` functions.

The grid structure is characterized by the position of the middle of the grid cells (`x.mid`) and the position of the interfaces between grid cells (`x.int`).

Distances are calculated between the interfaces (`dx`), i.e. the thickness of the grid cells. An auxiliary set of distances (`dx.aux`) is calculated between the points where the concentrations are specified (at the center of each grid cell and the two external interfaces).

A more complex grid consisting of multiple zones can be constructed when specifying the end-points of each zone (`x.down`), the interval length (`L`), and the number of layers in each zone (`N`) as vectors. In each zone, one can control the grid resolution near the upstream and downstream boundary. The grid resolution at the upstream interface changes according to the power law relation $dx[i+1] = \min(max.dx.1, p.dx.1 * dx[i])$, where `p.dx.1` determines the rate of increase and `max.dx.1` puts an upper limit on the grid cell size.

A similar formula controls the resolution at the downstream interface. This allows refinement of the grid near the interfaces.

Usage

```
setup.grid.1D(x.up=0, x.down=NULL, L=NULL, N=NULL, dx.1=NULL,
  p.dx.1=rep(1,length(L)), max.dx.1=L, dx.N=NULL,
  p.dx.N=rep(1,length(L)), max.dx.N=L)

## S3 method for class 'grid.1D':
plot(x, ...)
```

Arguments

<code>x.up</code>	position of the upstream interface; one value
<code>x.down</code>	position of the endpoint of each zone; one value when the model domain covers only one zone (<code>x.down</code> = position of downstream interface), or a vector of length <code>M</code> when the model domain is divided into <code>M</code> zones (<code>x.down[M]</code> = position of downstream interface)
<code>L</code>	thickness of zones; one value (model domain = one zone) or a vector of length <code>M</code> (model domain = <code>M</code> zones)
<code>N</code>	number of grid cells within a zone; one value or a vector of length <code>M</code>
<code>dx.1</code>	size of the first grid cell in a zone; one value or a vector of length <code>M</code>
<code>p.dx.1</code>	power factor controlling the increase in grid cell size near the upstream boundary; one value or a vector of length <code>M</code> . The default value is 1 (constant grid cell size)

<code>max.dx.1</code>	maximum grid cell size in the upstream half of the zone; one value or a vector of length M
<code>dx.N</code>	size of the last grid cell in a zone; one value or a vector of length M
<code>p.dx.N</code>	power factor controlling the increase in grid cell size near the downstream boundary; one value or a vector of length M. The default value is 1 (constant grid cell size)
<code>max.dx.N</code>	maximum grid cell size in the downstream half of the zone; one value or a vector of length M
<code>x</code>	the object of class <code>grid.1D</code> that needs plotting
<code>...</code>	additional arguments passed to the function plot

Value

a list of type `grid.1D` containing:

<code>N</code>	the total number of grid cells
<code>x.up</code>	position of the upstream interface; one value
<code>x.down</code>	position of the downstream interface; one value
<code>x.mid</code>	position of the middle of the grid cells; vector of length N
<code>x.int</code>	position of the interfaces of the grid cells; vector of length N+1
<code>dx</code>	distance between adjacent cell interfaces (thickness of grid cells); vector of length N
<code>dx.aux</code>	auxiliary vector containing the distance between adjacent cell centers; at the upper and lower boundary calculated as $(x[1] - x.up)$ and $(x.down - x[N])$ respectively; vector of length N+1

Author(s)

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Examples

```
# one zone, constant resolution
(GR <- setup.grid.1D(x.up=0, L=10, N=10))
(GR <- setup.grid.1D(x.up=0, L=10, dx.1=1))
(GR <- setup.grid.1D(x.up=0, L=10, dx.N=1))
plot(GR)

# one zone, constant resolution, origin not zero
(GR<-setup.grid.1D(x.up=5, x.down=10, N=10))
plot(GR)

# one zone, variable resolution
(GR <- setup.grid.1D(x.up=0, L=10, dx.1=1, p.dx.1=1.2))
(GR <- setup.grid.1D(x.up=0, L=10, dx.N=1, p.dx.N=1.2))
plot(GR)

# one zone, variable resolution, imposed number of layers
(GR <- setup.grid.1D(x.up=0, L=10, N=6, dx.1=1, p.dx.1=1.2))
(GR <- setup.grid.1D(x.up=0, L=10, N=6, dx.N=1, p.dx.N=1.2))
plot(GR)
```

```
# one zone, higher resolution near upstream and downstream interfaces
(GR<-setup.grid.1D(x.up=0,x.down=10,
dx.1=0.1,p.dx.1=1.2,dx.N=0.1,p.dx.N=1.2))
plot(GR)

# one zone, higher resolution near upstream and downstream interfaces
# imposed number of layers
(GR<-setup.grid.1D(x.up=0,x.down=10, N=20,
dx.1=0.1,p.dx.1=1.2,dx.N=0.1,p.dx.N=1.2))
plot(GR)

# two zones, higher resolution near the upstream
# and downstream interface
(GR<-setup.grid.1D(x.up=0,L=c(5,5),dx.1=c(0.2,0.2),p.dx.1=c(1.1,1.1),
dx.N=c(0.2,0.2),p.dx.N=c(1.1,1.1)))
plot(GR)

# two zones, higher resolution near the upstream
# and downstream interface
# the number of grid cells in each zone is imposed via N
(GR <- setup.grid.1D(x.up=0,L=c(5,5),N=c(20,10),dx.1=c(0.2,0.2),
p.dx.1=c(1.1,1.1),dx.N=c(0.2,0.2),p.dx.N=c(1.1,1.1)))
plot(GR)
```

setup.grid.2D	<i>Creates a finite difference grid over a two-dimensional rectangular domain</i>
---------------	---

Description

Creates a finite difference grid over a rectangular two-dimensional model domain starting from two separate one-dimensional grids (as created by [setup.grid.1D](#)). The x-direction is taken as vertical, the y-direction as horizontal.

Usage

```
setup.grid.2D(x.grid=NULL, y.grid=NULL)
```

Arguments

x.grid	list containing the one-dimensional grid in the vertical direction - see setup.grid.1D for the structure of the list
y.grid	list containing the one-dimensional grid in the horizontal direction - see setup.grid.1D for the structure of the list

Value

a list of type `grid.2D` containing:

x.up	vertical position of the horizontal upstream interface (i.e. the upper boundary); one value
x.down	vertical position of the horizontal downstream interface (i.e. the lower boundary); one value

<code>x.mid</code>	vertical position of the middle of the grid cells; vector of length <code>x.N</code>
<code>x.int</code>	vertical position of the horizontal interfaces of the grid cells; vector of length <code>x.N+1</code>
<code>dx</code>	distance between adjacent cell interfaces (thickness of grid cells); vector of length <code>x.N</code>
<code>dx.aux</code>	auxiliary vector containing the distance between adjacent cell centers; at the upstream and downstream boundary calculated as $(x[1] - x.up)$ and $(x.down - x[x.N])$ respectively; vector of length <code>x.N+1</code>
<code>x.N</code>	total number of grid cells in the vertical direction; one value
<code>y.left</code>	horizontal position of the vertical upstream interface (i.e. the left boundary); one value
<code>y.right</code>	horizontal position of the vertical downstream interface (i.e. the right boundary); one value
<code>y.mid</code>	horizontal position of the middle of the grid cells; vector of length <code>y.N</code>
<code>y.int</code>	horizontal position of the vertical interfaces of the grid cells; vector of length <code>y.N+1</code>
<code>dy</code>	distance between adjacent cell interfaces (thickness of grid cells); vector of length <code>y.N</code>
<code>dy.aux</code>	auxiliary vector containing the distance between adjacent cell centers; at the upstream and downstream boundary calculated as $(y[1] - y.up)$ and $(y.down - y[y.N])$ respectively; vector of length <code>y.N+1</code>
<code>y.N</code>	total number of grid cells in the horizontal direction; one value

Author(s)

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Examples

```
# test of the setup.grid.2D functionality
x.grid <- setup.grid.1D(x.up=0, L=10, N=5)
y.grid <- setup.grid.1D(x.up=0, L=20, N=10)
(grid2D <- setup.grid.2D(x.grid, y.grid))
```

setup.prop.1D

Attaches a property to a one-dimensional grid

Description

This routine calculates the value of a given property at the middle of the grid cells (`mid`) and at the interfaces of the grid cells (`int`).

Two possibilities are available: either specifying a mathematical function (`func`) that describes the spatial dependency of the property, or obtaining the property from interpolation of a data series (via the input of the data matrix `xy`).

For example, in a sediment model, `setup.prop.1D` can be used to specify the porosity, the mixing intensity or some other parameter over the one-dimensional grid. Similarly, in a vertical water column model, `setup.prop.1D` can be used to specify the sinking velocity of particles or other model parameters change with water depth.

Usage

```

setup.prop.1D(func=NULL, value=NULL, xy=NULL,
              interpolate="spline", grid, ...)

## S3 method for class 'prop.1D':
plot(x, grid, xyswap = FALSE, ...)

```

Arguments

<code>func</code>	function that describes the spatial dependency. For example, one can use the functions provided in p.exp
<code>value</code>	constant value given to the property (no spatial dependency)
<code>xy</code>	a two-column data matrix where the first column (<code>x</code>) provides the position, and the second column (<code>y</code>) provides the values that need interpolation over the grid
<code>interpolate</code>	specifies how the interpolation should be done, one of "spline" or "linear"; only used when <code>xy</code> is present
<code>grid</code>	list specifying the 1D grid characteristics, see setup.grid.1D for details on the structure of this list
<code>x</code>	the object of class <code>prop.1D</code> that needs plotting
<code>xyswap</code>	if TRUE, then x- and y-values are swapped and the y-axis is oriented from top to bottom. Useful for drawing vertical depth profiles
<code>...</code>	additional arguments that are passed on to <code>func</code> or to the method

Details

There are two options to carry out the data interpolation:

- "spline" gives a smooth profile, but sometimes generates strange profiles - always check the result!
- "linear" gives a segmented profile

Value

A list of type `prop.1D` containing:

<code>mid</code>	property value in the middle of the grid cells; vector of length N (where N is the number of grid cells)
<code>int</code>	property value at the interface of the grid cells; vector of length N+1

Author(s)

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Examples

```

# Construction of the 1D grid
grid <- setup.grid.1D(x.up=0, L=10, N=10)

```

```
# Porosity profile via function specification

P.prof <- setup.prop.1D(func=p.exp,grid=grid,y.0=0.9,
y.inf=0.5,x.att=3)

# Porosity profile via data series interpolation

P.data <- matrix(ncol=2,data=c(0,3,6,10,0.9,0.65,0.55,0.5))
P.spline <- setup.prop.1D(xy=P.data,grid=grid)
P.linear <- setup.prop.1D(xy=P.data,grid=grid,interpolate="linear")

# Plot different profiles

plot(P.prof,grid,type="l",
      main="setup.prop, function evaluation")
points(P.data,cex=1.5,pch=16)
lines(grid$x.int,P.spline$int,lty="dashed")
lines(grid$x.int,P.linear$int,lty="dotdash")
```

setup.prop.2D

Attaches a property to a two-dimensional grid

Description

Calculates the value of a given property at the middle of grid cells (`mid`) and at the interfaces of the grid cells (`int`).

Two possibilities are available: either specifying a mathematical function (`func`) that describes the spatial dependency of the property, or assuming a constant value (`value`). To allow for anisotropy, the spatial dependency can be different in the x and y direction.

For example, in a sediment model, the routine can be used to specify the porosity, the mixing intensity or other parameters over the grid of the rectangular sediment domain.

Usage

```
setup.prop.2D(func = NULL, y.func = func, value = NULL, y.value = value, grid,...)

## S3 method for class 'prop.2D':
contour(x, grid, xyswap = FALSE, filled = FALSE, ...)
```

Arguments

<code>func</code>	function that describes the spatial dependency in the x-direction
<code>y.func</code>	function that describes the spatial dependency in the y-direction. By default the same as in the x-direction.
<code>value</code>	constant value given to the property in the x-direction
<code>y.value</code>	constant value given to the property in the y-direction. By default the same as in the x-direction.
<code>grid</code>	list specifying the 2D grid characteristics, see setup.grid.2D for details on the structure of this list
<code>x</code>	the object of class <code>prop.1D</code> that needs plotting

<code>filled</code>	if <code>TRUE</code> , uses <code>filled.contour</code> , else <code>contour</code>
<code>xyswap</code>	if <code>TRUE</code> , then <code>x</code> - and <code>y</code> -values are swapped and the <code>y</code> -axis is oriented from top to bottom. Useful for drawing vertical depth profiles
<code>...</code>	additional arguments that are passed on to <code>func</code> or to the method

Details

- The `x`-axis is taken in the vertical pointing downwards (`N` grid cells).
- The `y`-axis is taken in the horizontal pointing to the right (`M` grid cells).
- When the property is isotropic, the `x.mid` and `y.mid` values are identical. This is for example the case for the porosity.
- When the property is anisotropic, the `x.mid` and `y.mid` values can differ. This can be for example the case for the velocity, where in general, the value will differ between the `x` and `y` direction.

Value

A list of type `prop.2D` containing:

<code>x.mid</code>	property value in the <code>x</code> -direction defined at the middle of the grid cells; <code>NxM</code> matrix
<code>y.mid</code>	property value in the <code>y</code> -direction at the middle of the grid cells; <code>NxM</code> matrix
<code>x.int</code>	property value in the <code>x</code> -direction defined at the (horizontal) <code>x</code> -interfaces of the grid cells; <code>(N+1)xM</code> matrix
<code>y.int</code>	property value in the <code>y</code> -direction at the (vertical) <code>y</code> -interfaces of the grid cells; <code>Nx(M+1)</code> matrix

Author(s)

Filip Meysman <f.meysman@nioo.knaw.nl>, Karline Soetaert <k.soetaert@nioo.knaw.nl>

Examples

```
# Inverse quadratic function
inv.quad <- function(x,y,a=NULL,b=NULL)
return(1/((x-a)^2+(y-b)^2))

# Construction of the 2D grid
x.grid <- setup.grid.1D(x.up=0,L=10,N=10)
y.grid <- setup.grid.1D(x.up=0,L=10,N=10)
grid2D <- setup.grid.2D(x.grid,y.grid)

# Attaching the inverse quadratic function to the 2D grid
(twoD<-setup.prop.2D(func=inv.quad,grid=grid2D,a=5,b=5))
contour(log(twoD$x.int))
```

tran.1D

*General one-dimensional advective-diffusive transport***Description**

Estimates the transport term (i.e. the rate of change of a concentration due to diffusion and advection) in a one-dimensional model of a liquid (volume fraction constant and equal to one) or in a porous medium (volume fraction variable and lower than one).

The interfaces between grid cells can have a variable cross-sectional area, for example when modelling spherical or cylindrical geometries (see example).

Usage

```
tran.1D(C, C.up = C[1], C.down = C[length(C)],
        flux.up = NULL, flux.down = NULL, a.bl.up = NULL, C.bl.up = NULL,
        a.bl.down = NULL, C.bl.down = NULL,
        D = 0, v = 0, AFDW = 1, VF = 1, A = 1, dx,
        full.check = FALSE, full.output = FALSE)
```

Arguments

C	concentration, expressed per unit of phase volume, defined at the centre of each grid cell. A vector of length N [M/L3]
C.up	concentration at upstream boundary. One value [M/L3]
C.down	concentration at downstream boundary. One value [M/L3]
flux.up	flux across the upstream boundary, positive = INTO model domain. One value [M/L2/T]
flux.down	flux across the downstream boundary, positive = OUT of model domain. One value, expressed per unit of total surface [M/L2/T]
a.bl.up	convective transfer coefficient across the upstream boundary layer. Flux = a.bl.up*(C.bl.up-C0). One value [L/T]
C.bl.up	concentration at the upstream boundary layer. One value [M/L3]
a.bl.down	convective transfer coefficient across the downstream boundary layer (L). Flux = a.bl.down*(CL-C.bl.down). One value [L/T]
C.bl.down	concentration at the downstream boundary layer. One value [M/L3]
D	diffusion coefficient, defined on grid cell interfaces. One value, a vector of length N+1 [L2/T], or a 1D property list; the list contains at least the element int (see setup.prop.1D) [L2/T]
v	advective velocity in the x-axis direction, defined on the grid cell interfaces. Can be positive (downstream flow) or negative (upstream flow). One value, a vector of length N+1 [L/T], or a 1D property list; the list contains at least the element int (see setup.prop.1D) [L/T]
AFDW	weight used in the finite difference scheme for advection, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. One value, a vector of length N+1, or a 1D property list; the list contains at least the element int (see setup.prop.1D) [-]

VF	Volume fraction defined at the grid cell interfaces. One value, a vector of length $N+1$, or a 1D property list; the list contains at least the elements <code>int</code> and <code>mid</code> (see setup.prop.1D) [-].
A	Interface area defined at the grid cell interfaces. One value, a vector of length $N+1$, or a 1D grid property list; the list contains at least the elements <code>int</code> and <code>mid</code> (see setup.prop.1D) [L2].
dx	distance between adjacent cell interfaces (thickness of grid cells). One value, a vector of length N , or a 1D grid list containing at least the elements <code>dx</code> and <code>dx.aux</code> (see setup.grid.1D) [L].
full.check	logical flag enabling a full check of the consistency of the arguments (default = FALSE; TRUE slows down execution by 50 percent).
full.output	logical flag enabling a full return of the output (default = FALSE; TRUE slows down execution by 20 percent).

Details

The **boundary conditions** are either

- (1) zero-gradient.
- (2) fixed concentration.
- (3) convective boundary layer.
- (4) fixed flux.

The above order also shows the priority. The default condition is the zero gradient. The fixed concentration condition overrules the zero gradient. The convective boundary layer condition overrules the fixed concentration and zero gradient. The fixed flux overrules all other specifications.

Transport properties:

The *diffusion coefficient* (D), the *advective velocity* (v), the *volume fraction* (VF), the *interface surface* (A), and the *advective finite difference weight* (AFDW) can be either be specified as one value, a vector or a 1D property list as generated by [setup.prop.1D](#).

When a vector, this vector must be of length $N+1$, defined at all grid cell interfaces, including upper and lower boundary.

The **finite difference grid** (`dx`) is specified either as one value, a vector or a 1D grid list, as generated by [setup.grid.1D](#).

Value

dC	the rate of change of the concentration C due to transport, defined in the centre of each grid cell. The rate of change is expressed per unit of phase volume [M/L ³ /T].
C.up	concentration at the upstream interface. One value [M/L ³]. only when (<code>full.output</code> = TRUE)
C.down	concentration at the downstream interface. One value [M/L ³]. only when (<code>full.output</code> = TRUE)
adv.flux	advective flux across at the interface of each grid cell. A vector of length $N+1$ [M/L ² /T]. only when (<code>full.output</code> = TRUE)
dif.flux	diffusive flux across at the interface of each grid cell. A vector of length $N+1$ [M/L ² /T]. only when (<code>full.output</code> = TRUE)

flux	total flux across at the interface of each grid cell. A vector of length N+1 [M/L ² /T]. only when (full.output = TRUE)
flux.up	flux across the upstream boundary, positive = INTO model domain. One value [M/L ² /T].
flux.down	flux across the downstream boundary, positive = OUT of model domain. One value [M/L ² /T].

Note

The advective-diffusion equation is not checked for mass conservation. Sometimes, this is not an issue, for instance when v represents a sinking velocity of particles or a swimming velocity of organisms. In others cases however, mass conservation needs to be accounted for. To ensure mass conservation, the advective velocity must obey certain continuity constraints: in essence the product of the volume fraction (VF), interface surface area (A) and advective velocity (v) should be constant. In sediments, one can use `setup.compaction.1D` to ensure that the advective velocities for the pore water and solid phase meet these constraints.

In terms of the units of concentrations and fluxes we follow the convention in the geosciences. The concentration C , $C.up$, $C.down$ as well as the rate of change of the concentration dC are always expressed per unit of phase volume (i.e. per unit volume of solid or liquid). Total concentrations (e.g. per unit volume of bulk sediment) are obtained by multiplication with the appropriate volume fraction. In contrast, fluxes are always expressed per unit of total interface area (so here the volume fraction is accounted for).

Author(s)

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References

Soetaert and Herman (2009). A practical guide to ecological modelling - using R as a simulation platform. Springer

Examples

```
#####
##### EXAMPLE 1: O2 and OC consumption in sediments #####
#####

# this example uses only the volume fractions
# in the reactive transport term

#####
# Model formulation #
#####

# Monod consumption of oxygen (O2)

O2.model <- function (t=0,O2,pars=NULL) {
  tran <- tran.1D(C=O2,C.up=C.ow.O2,D=D.grid,v=v.grid,
    VF=por.grid,dx=grid)$dC
  reac <- - R.O2*(O2/(Ks+O2))
  return(list(dCd_t = tran+reac))
}
```

```

# First order consumption of organic carbon (OC)

OC.model <- function (t=0,OC,pars=NULL) {
  tran <- tran.1D(C=OC,flux.up=F.OC,D=Db.grid,v=v.grid,
    VF=svf.grid,dx=grid)$dC
  reac <- - k*OC
  return(list(dCdt = tran + reac))
}

#####
# Parameter definition #
#####

# Parameter values

F.OC    <- 25    # input flux organic carbon [micromol cm-2 yr-1]
C.ow.O2 <- 0.25  # concentration O2 in overlying water [micromol cm-3]
por      <- 0.8   # porosity
D        <- 400   # diffusion coefficient O2 [cm2 yr-1]
Db       <- 10    # mixing coefficient sediment [cm2 yr-1]
v        <- 1     # advective velocity [cm yr-1]
k        <- 1     # decay constant organic carbon [yr-1]
R.O2     <- 10    # O2 consumption rate [micromol cm-3 yr-1]
Ks       <- 0.005 # O2 consumption saturation constant

# Grid definition

L <- 10    # depth of sediment domain [cm]
N <- 100   # number of grid layers
grid <- setup.grid.1D(x.up=0,L=L,N=N)

# Volume fractions

por.grid <- setup.prop.1D(value=por,grid=grid)
svf.grid <- setup.prop.1D(value=(1-por),grid=grid)
D.grid <- setup.prop.1D(value=D,grid=grid)
Db.grid <- setup.prop.1D(value=Db,grid=grid)
v.grid <- setup.prop.1D(value=v,grid=grid)

#####
# Model solution      #
#####

# Initial conditions + simulation O2

O2 <- rep(0,length.out=N)
O2 <- steady.band(y=O2, func=O2.model, nspec=1)$y

# Initial conditions + simulation OC

OC <- rep(0,length.out=N)
OC <- steady.band(y=OC, func=OC.model, nspec=1)$y

# Plotting output

par(mfrow=c(1,2))

```

```

matplot(O2,grid$x.mid,pch=16,type="b",ylim=c(L,0),
xlim=c(min(0,min(O2)),max(O2)),
xlab="",ylab="depth [cm]",main=expression("O2 concentration"),
axes=FALSE)
abline(h = 0)
axis(pos=0, side=2)
axis(pos=0, side=3)

matplot(OC,grid$x.mid,pch=16,type="b",ylim=c(L,0),
xlim=c(min(0,min(OC)),max(OC)),
xlab="",ylab="depth [cm]",main=expression("OC concentration"),
axes=FALSE)
abline(h = 0)
axis(pos=0, side=2)
axis(pos=0, side=3)

#####
##### EXAMPLE 2: O2 in a cylindrical and spherical organism #####
#####

# This example uses only the surface areas
# in the reactive transport term

#=====#
# Model formulation #
#=====#

# the numerical model - rate of change=transport-consumption
Cylinder.Model <- function(time,O2,pars)
  return (list(tran.1D(C=O2,C.down=BW,D=Da,A=A.cyl,dx=dx)$dC-Q))

Sphere.Model <- function(time,O2,pars)
  return (list(tran.1D(C=O2,C.down=BW,D=Da,A=A.sphere,dx=dx)$dC-Q))

#=====#
# Parameter definition #
#=====#

# parameter values

BW <- 2 # mmol/m3, oxygen conc in surrounding water
Da <- 0.5 # cm2/d effective diffusion coeff in organism
R <- 0.0025 # cm radius of organism
Q <- 250000 # nM/cm3/d oxygen consumption rate/ volume / day
L <- 0.05 # cm length of organism (if a cylinder)

# the numerical model

N <- 40 # layers in the body
dx <- R/N # thickness of each layer
x.mid <- seq(dx/2,by=dx,length.out=N) # distance of center to mid-layer
x.int <- seq(0,by=dx,length.out=N+1) # distance to layer interface

# Cylindrical surfaces
A.cyl <- 2*pi*x.int*L # surface at mid-layer depth

# Spherical surfaces

```

```

A.sphere <- 4*pi*x.int^2 # surface of sphere, at each mid-layer

#####
# Model solution      #
#####

# the analytical solution of cylindrical and spherical model
cylinder <- function(Da,Q,BW,R,r) BW+Q/(4*Da)*(r^2-R^2)
sphere   <- function(Da,Q,BW,R,r) BW+Q/(6*Da)*(r^2-R^2)

# solve the model numerically for a cylinder
O2.cyl <- steady.1D (runif(N),
func=Cylinder.Model,nspec=1,atol=1e-10)$y

# solve the model numerically for a sphere
O2.sphere <- steady.1D (runif(N),
func=Sphere.Model,nspec=1,atol=1e-10)$y

#####
# Plotting output    #
#####

par(mfrow=c(1,1))

plot(x.mid,O2.cyl,xlab="distance from centre, cm",ylab="mmol/m3",
main="tran.1D",sub="diffusion-reaction in a cylinder and sphere")
lines(x.mid, cylinder(Da,Q,BW,R,x.mid))

points(x.mid, O2.sphere, pch=18,col="red" )
lines(x.mid, sphere(Da,Q,BW,R,x.mid),col="red")

legend ("topleft",lty=c(1,NA),pch=c(NA,1),
       c("analytical solution","numerical approximation"))
legend ("bottomright",pch=c(1,18),lty=1,col=c("black","red"),
       c("cylinder","sphere"))

#####
##### EXAMPLE 3: O2 consumption in a spherical aggregate #####
#####

# this example uses both the surface areas and the volume fractions
# in the reactive transport term

#####
# Model formulation #
#####

Aggregate.Model <- function(time,O2,pars) {

  tran <- tran.1D(C=O2, C.down=C.ow.O2,
    D=D.grid, A=A.grid,
    VF=por.grid, dx=grid )$dC

  reac <- - R.O2*(O2/(Ks+O2))*(O2>0)
  return(list(dCdt = tran+reac))

}

```

```

#####
# Parameter definition #
#####

# Parameters

C.ow.O2 <- 0.25      # concentration O2 water [micromol cm-3]
por      <- 0.8       # porosity
D        <- 400       # diffusion coefficient O2 [cm2 yr-1]
v        <- 0         # advective velocity [cm yr-1]
R.O2     <- 1000000    # O2 consumption rate [micromol cm-3 yr-1]
Ks       <- 0.005     # O2 saturation constant [micromol cm-3]

# Grid definition
R <- 0.025           # radius of the aggregate [cm]
N <- 100             # number of grid layers
grid <- setup.grid.1D(x.up=0,L=R,N=N)

# Volume fractions

por.grid <- setup.prop.1D(value=por,grid=grid)
D.grid <- setup.prop.1D(value=D,grid=grid)

# Surfaces

A.mid <- 4*pi*grid$x.mid^2 # surface of sphere
A.int <- 4*pi*grid$x.int^2 # surface of sphere
A.grid=list(int=A.int,mid=A.mid)

#####
# Model solution      #
#####

# Numerical solution: steady state

O2.agg <- steady.1D (runif(N),
func=Aggregate.Model,nspec=1,atol=1e-10)$y

#####
# Plotting output      #
#####

par(mfrow=c(1,1))

plot(grid$x.mid,O2.agg,xlab="distance from centre, cm",
ylab="mmol/m3",
main="Diffusion-reaction of O2 in a spherical aggregate")
legend ("bottomright",pch=c(1,18),lty=1,col=c("black"),
c("O2 concentration"))

```


Description

Estimates the transport term (i.e. the rate of change of a concentration due to diffusion and advection) in a two-dimensional model domain.

Usage

```
tran.2D ( C, C.x.up=C[1,], C.x.down=C[nrow(C),],
  C.y.up=C[,1], C.y.down=C[,ncol(C)],
  flux.x.up=NULL, flux.x.down=NULL, flux.y.up=NULL, flux.y.down=NULL,
  a.bl.x.up=NULL, C.bl.x.up=NULL, a.bl.x.down=NULL, C.bl.x.down=NULL,
  a.bl.y.up=NULL, C.bl.y.up=NULL, a.bl.y.down=NULL, C.bl.y.down=NULL,
  D.grid=NULL, D.x=NULL, D.y=D.x,
  v.grid=NULL, v.x=0, v.y=0,
  AFDW.grid=NULL, AFDW.x=1, AFDW.y=AFDW.x,
  VF.grid=NULL, VF.x=1, VF.y=VF.x,
  A.grid=NULL, A.x=1, A.y=1,
  grid=NULL, dx=NULL, dy=NULL,
  full.check = FALSE, full.output = FALSE)
```

Arguments

C	concentration, expressed per unit volume, defined at the centre of each grid cell; Nx*Ny matrix [M/L3].
C.x.up	concentration at upstream boundary in x-direction; vector of length Ny [M/L3].
C.x.down	concentration at downstream boundary in x-direction; vector of length Ny [M/L3].
C.y.up	concentration at upstream boundary in y-direction; vector of length Nx [M/L3].
C.y.down	concentration at downstream boundary in y-direction; vector of length Nx [M/L3].
flux.x.up	flux across the upstream boundary in x-direction, positive = INTO model domain; vector of length Ny [M/L2/T].
flux.x.down	flux across the downstream boundary in x-direction, positive = OUT of model domain; vector of length Ny [M/L2/T].
flux.y.up	flux across the upstream boundary in y-direction, positive = INTO model domain; vector of length Nx [M/L2/T].
flux.y.down	flux across the downstream boundary in y-direction, positive = OUT of model domain; vector of length Nx [M/L2/T].
a.bl.x.up	transfer coefficient across the upstream boundary layer. in x-direction $Flux = a.bl.x.up * (C.bl.x.up - C[1,])$. One value [L/T].
C.bl.x.up	concentration at the upstream boundary layer in x-direction; vector of length Ny [M/L3].
a.bl.x.down	transfer coefficient across the downstream boundary layer in x-direction; $Flux = a.bl.x.down * (C.bl.x.down - C.bl.x.down)$. One value [L/T].
C.bl.x.down	concentration at the downstream boundary layer in x-direction ; vector of length Ny [M/L3].
a.bl.y.up	transfer coefficient across the upstream boundary layer. in y-direction $Flux = a.bl.y.up * (C.bl.y.up - C[,1])$. One value [L/T].
C.bl.y.up	concentration at the upstream boundary layer in y-direction; vector of length Nx [M/L3].

<code>a.bl.y.down</code>	transfer coefficient across the downstream boundary layer in y-direction; $\text{Flux} = a.bl.y.down * (C.bl.y.down - C.bl.y.down)$. One value [L/T].
<code>C.bl.y.down</code>	concentration at the downstream boundary layer in y-direction ; vector of length N_x [M/L ³].
<code>D.grid</code>	diffusion coefficient defined on all grid cell interfaces. A <code>prop.2D</code> list created by <code>setup.prop.2D</code> [L ² /T].
<code>D.x</code>	diffusion coefficient in x-direction, defined on grid cell interfaces. One value, a vector of length (N_x+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $(N_x+1) * N_y$ matrix [L ² /T].
<code>D.y</code>	diffusion coefficient in y-direction, defined on grid cell interfaces. One value, a vector of length (N_y+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x * (N_y+1)$ matrix [L ² /T].
<code>v.grid</code>	advective velocity defined on all grid cell interfaces. Can be positive (downstream flow) or negative (upstream flow). A <code>prop.2D</code> list created by <code>setup.prop.2D</code> [L/T].
<code>v.x</code>	advective velocity in the x-direction, defined on grid cell interfaces. Can be positive (downstream flow) or negative (upstream flow). One value, a vector of length (N_x+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $(N_x+1) * N_y$ matrix [L/T].
<code>v.y</code>	advective velocity in the y-direction, defined on grid cell interfaces. Can be positive (downstream flow) or negative (upstream flow). One value, a vector of length (N_y+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x * (N_y+1)$ matrix [L/T].
<code>AFDW.grid</code>	weight used in the finite difference scheme for advection in the x-direction, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. A <code>prop.2D</code> list created by <code>setup.prop.2D</code> [-].
<code>AFDW.x</code>	weight used in the finite difference scheme for advection in the x-direction, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. One value, a vector of length (N_x+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $(N_x+1) * N_y$ matrix [-].
<code>AFDW.y</code>	weight used in the finite difference scheme for advection in the y-direction, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. One value, a vector of length (N_y+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x * (N_y+1)$ matrix [-].
<code>VF.grid</code>	Volume fraction. A <code>prop.2D</code> list created by <code>setup.prop.2D</code> [-].
<code>VF.x</code>	Volume fraction at the grid cell interfaces in the x-direction. One value, a vector of length (N_x+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $(N_x+1) * N_y$ matrix [-].
<code>VF.y</code>	Volume fraction at the grid cell interfaces in the y-direction. One value, a vector of length (N_y+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x * (N_y+1)$ matrix [-].
<code>A.grid</code>	Interface area. A <code>prop.2D</code> list created by <code>setup.prop.2D</code> [L ²].
<code>A.x</code>	Interface area defined at the grid cell interfaces in the x-direction. One value, a vector of length (N_x+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $(N_x+1) * N_y$ matrix [L ²].
<code>A.y</code>	Interface area defined at the grid cell interfaces in the y-direction. One value, a vector of length (N_y+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x * (N_y+1)$ matrix [L ²].

<code>dx</code>	distance between adjacent cell interfaces in the x-direction (thickness of grid cells). One value or vector of length N_x [L].
<code>dy</code>	distance between adjacent cell interfaces in the y-direction (thickness of grid cells). One value or vector of length N_y [L].
<code>grid</code>	discretization grid, a list containing at least elements <code>dx</code> , <code>dx.aux</code> , <code>dy</code> , <code>dy.aux</code> (see setup.grid.2D) [L].
<code>full.check</code>	logical flag enabling a full check of the consistency of the arguments (default = FALSE; TRUE slows down execution by 50 percent).
<code>full.output</code>	logical flag enabling a full return of the output (default = FALSE; TRUE slows down execution by 20 percent).

Details

The **boundary conditions** are either

- (1) zero-gradient
- (2) fixed concentration
- (3) convective boundary layer
- (4) fixed flux

This is also the order of priority. The zero gradient is the default, the fixed flux overrules all other.

Value

a list containing:

<code>dC</code>	the rate of change of the concentration C due to transport, defined in the centre of each grid cell, a $N_x \times N_y$ matrix. [M/L ³ /T].
<code>C.x.up</code>	concentration at the upstream interface in x-direction. A vector of length N_y [M/L ³]. Only when <code>full.output</code> = TRUE.
<code>C.x.down</code>	concentration at the downstream interface in x-direction. A vector of length N_y [M/L ³]. Only when <code>full.output</code> = TRUE.
<code>C.y.up</code>	concentration at the the upstream interface in y-direction. A vector of length N_x [M/L ³]. Only when <code>full.output</code> = TRUE.
<code>C.y.down</code>	concentration at the downstream interface in y-direction. A vector of length N_x [M/L ³]. Only when <code>full.output</code> = TRUE.
<code>x.flux</code>	flux across the interfaces in x-direction of the grid cells. A $(N_x+1) \times N_y$ matrix [M/L ² /T]. Only when <code>full.output</code> = TRUE.
<code>y.flux</code>	flux across the interfaces in y-direction of the grid cells. A $N_x \times (N_y+1)$ matrix [M/L ² /T]. Only when <code>full.output</code> = TRUE.
<code>flux.x.up</code>	flux across the upstream boundary in x-direction, positive = INTO model domain. A vector of length N_y [M/L ² /T].
<code>flux.x.down</code>	flux across the downstream boundary in x-direction, positive = OUT of model domain. A vector of length N_y [M/L ² /T].
<code>flux.y.up</code>	flux across the upstream boundary in y-direction, positive = INTO model domain. A vector of length N_x [M/L ² /T].
<code>flux.y.down</code>	flux across the downstream boundary in y-direction, positive = OUT of model domain. A vector of length N_x [M/L ² /T].

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References

Soetaert and Herman, a practical guide to ecological modelling - using R as a simulation platform, 2009. Springer

Examples

```
# Parameters
F      <- 100          # input flux [micromol cm-2 yr-1]
por    <- 0.8          # constant porosity
D      <- 400          # mixing coefficient [cm2 yr-1]
v      <- 1            # advective velocity [cm yr-1]

# Grid definition
x.N <- 4  # number of cells in x-direction
y.N <- 6  # number of cells in y-direction
x.L <- 8  # domain size x-direction [cm]
y.L <- 24 # domain size y-direction [cm]
dx  <- x.L/x.N      # cell size x-direction [cm]
dy  <- y.L/y.N      # cell size y-direction [cm]

# Intial conditions
C <- matrix(nrow=x.N, ncol=y.N, data=0, byrow=FALSE)

# Boundary conditions: fixed concentration
C.x.up <- rep(1, times=y.N)
C.x.down <- rep(0, times=y.N)
C.y.up <- rep(1, times=x.N)
C.y.down <- rep(0, times=x.N)

# Only diffusion
tran.2D(full.output=TRUE, C=C, D.x=D, D.y=D, v.x=0, v.y=0,
        VF.x=por, VF.y=por, dx=dx, dy=dy,
        C.x.up=C.x.up, C.x.down=C.x.down,
        C.y.up=C.y.up, C.y.down=C.y.down)

# Strong advection, backward (default), central and forward
#finite difference schemes
tran.2D(C=C, D.x=D, v.x=100*v, VF.x=por, dx=dx, dy=dy,
        C.x.up=C.x.up, C.x.down=C.x.down, C.y.up=C.y.up, C.y.down=C.y.down)

tran.2D(AFDW.x=0.5, C=C, D.x=D, v.x=100*v, VF.x=por, dx=dx, dy=dy,
        C.x.up=C.x.up, C.x.down=C.x.down, C.y.up=C.y.up, C.y.down=C.y.down)

tran.2D(AFDW.x=0, C=C, D.x=D, v.x=100*v, VF.x=por, dx=dx, dy=dy,
        C.x.up=C.x.up, C.x.down=C.x.down, C.y.up=C.y.up, C.y.down=C.y.down)

# Boundary conditions: fixed fluxes
flux.x.up <- rep(200, times=y.N)
flux.x.down <- rep(-200, times=y.N)
flux.y.up <- rep(200, times=x.N)
flux.y.down <- rep(-200, times=x.N)
```

```

tran.2D(C=C, D.x=D, v.x=0, VF.x=por, dx=dx, dy=dy,
       flux.x.up=flux.x.up, flux.x.down=flux.x.down,
       flux.y.up=flux.y.up, flux.y.down=flux.y.down)

# Boundary conditions: convective boundary layer on all sides

a.bl <- 800 # transfer coefficient
C.bl.x.up <- rep(1, times=(y.N)) # fixed conc at boundary layer
C.bl.y.up <- rep(1, times=(x.N)) # fixed conc at boundary layer
tran.2D(full.output=TRUE, C=C, D.x=D, v.x=0, VF.x=por,
       dx=dx, dy=dy, C.bl.x.up=C.bl.x.up, a.bl.x.up=a.bl, C.bl.x.down=C.bl.x.up,
       a.bl.x.down=a.bl, C.bl.y.up=C.bl.y.up, a.bl.y.up=a.bl,
       C.bl.y.down=C.bl.y.up, a.bl.y.down=a.bl)

# Runtime test with and without argument checking

n.iterate <-1000

test1 <- function()
{
  for (i in 1:n.iterate )
  ST<-tran.2D(full.check=TRUE,C=C,D.x=D,v.x=0,VF.x=por,
dx=dx,dy=dy,C.bl.x.up=C.bl.x.up,a.bl.x.up=a.bl,C.x.down=C.x.down)
}
system.time(test1())

test2 <- function()
{
  for (i in 1:n.iterate )
  ST<-tran.2D(full.output=TRUE,C=C,D.x=D,v.x=0,VF.x=por,
dx=dx,dy=dy,C.bl.x.up=C.bl.x.up,a.bl.x.up=a.bl,C.x.down=C.x.down)
}
system.time(test2())

test3 <- function()
{
  for (i in 1:n.iterate )
  ST<-tran.2D(full.output=TRUE,full.check=TRUE,C=C,D.x=D,v.x=0,
VF.x=por,dx=dx,dy=dy,C.bl.x.up=C.bl.x.up,a.bl.x.up=a.bl,C.x.down=C.x.down)
}
system.time(test3())

## =====
## A 2-D model with diffusion in x- and y direction and first-order
## consumption
## =====

N      <- 51      # number of grid cells
XX     <- 10      # total size
dy     <- dx <- XX/N # grid size
Dy     <- Dx <- 0.1 # diffusion coeff, X- and Y-direction
r      <- 0.005    # consumption rate
ini    <- 1        # initial value at x=0

N2     <- ceiling(N/2)
X      <- seq (dx,by=dx,len=(N2-1))
X      <- c(-rev(X),0,X)

```

```

# The model equations

Diff2D <- function (t,y,parms) {
  CONC <- matrix(nr=N,nc=N,y)
  dCONC <- tran.2D(CONC, D.x=Dx, D.y=Dy, dx=dx, dy=dy)$dC + r * CONC
  return (list(as.vector(dCONC)))
}

# initial condition: 0 everywhere, except in central point
y <- matrix(nr=N,nc=N,data=0)
y[N2,N2] <- ini # initial concentration in the central point...

# solve for 10 time units
times <- 0:10
out <- ode.2D (y=y, func=Diff2D, t=times, parms=NULL,
              dim = c(N,N), lrw = 160000)

pm <- par (mfrow=c(2,2))

# Compare solution with analytical solution...
for (i in seq(2,11,by=3))
{
  tt <- times[i]
  mat <- matrix(nr=N,nc=N,out[i,-1])
  plot(X,mat[N2,],type="l",main=paste("time=",times[i]),
       ylab="Conc",col="red")
  ana <- ini*dx^2/(4*pi*Dx*tt)*exp(r*tt-X^2/(4*Dx*tt))
  points(X,ana,pch="+")
}
legend ("bottom", col=c("red","black"), lty=c(1,NA), pch=c(NA,"+"),
       c("tran.2D","exact"))
par("mfrow"=pm )

```

tran.3D

General three-dimensional advective-diffusive transport

Description

Estimates the transport term (i.e. the rate of change of a concentration due to diffusion and advection) in a three-dimensional rectangular model domain.

Do not use with too many boxes!

Usage

```

tran.3D (C, C.x.up=C[,1,], C.x.down=C[dim(C)[1],,],
        C.y.up=C[,1,], C.y.down=C[,dim(C)[2],],
        C.z.up=C[,1,], C.z.down=C[,dim(C)[3],],
        flux.x.up=NULL, flux.x.down=NULL,
        flux.y.up=NULL, flux.y.down=NULL,
        flux.z.up=NULL, flux.z.down=NULL,
        a.bl.x.up=NULL, C.bl.x.up=NULL, a.bl.x.down=NULL, C.bl.x.down=NULL,

```

```

a.bl.y.up=NULL, C.bl.y.up=NULL, a.bl.y.down=NULL, C.bl.y.down=NULL,
a.bl.z.up=NULL, C.bl.z.up=NULL, a.bl.z.down=NULL, C.bl.z.down=NULL,
D.grid=NULL, D.x=NULL, D.y=D.x, D.z=D.x,
v.grid=NULL, v.x=0, v.y=0, v.z=0,
AFDW.grid=NULL, AFDW.x=1, AFDW.y=AFDW.x, AFDW.z=AFDW.x,
VF.grid=NULL, VF.x=1, VF.y=VF.x, VF.z=VF.x,
A.grid=NULL, A.x=1, A.y=1, A.z=1,
grid=NULL, dx=NULL, dy=NULL, dz=NULL,
full.check = FALSE, full.output = FALSE)

```

Arguments

C	concentration, expressed per unit volume, defined at the centre of each grid cell; Nx*Ny*Nz matrix [M/L3].
C.x.up	concentration at upstream boundary in x-direction; matrix of dimensions Ny*Nz [M/L3].
C.x.down	concentration at downstream boundary in x-direction; matrix of dimensions Ny*Nz [M/L3].
C.y.up	concentration at upstream boundary in y-direction; matrix of dimensions Nx*Nz [M/L3].
C.y.down	concentration at downstream boundary in y-direction; matrix of dimensions Nx*Nz [M/L3].
C.z.up	concentration at upstream boundary in z-direction; matrix of dimensions Nx*Ny [M/L3].
C.z.down	concentration at downstream boundary in z-direction; matrix of dimensions Nx*Ny [M/L3].
flux.x.up	flux across the upstream boundary in x-direction, positive = INTO model domain; matrix of dimensions Ny*Nz [M/L2/T].
flux.x.down	flux across the downstream boundary in x-direction, positive = OUT of model domain; matrix of dimensions Ny*Nz [M/L2/T].
flux.y.up	flux across the upstream boundary in y-direction, positive = INTO model domain; matrix of dimensions Nx*Nz [M/L2/T].
flux.y.down	flux across the downstream boundary in y-direction, positive = OUT of model domain; matrix of dimensions Nx*Nz [M/L2/T].
flux.z.up	flux across the upstream boundary in z-direction, positive = INTO model domain; matrix of dimensions Nx*Ny [M/L2/T].
flux.z.down	flux across the downstream boundary in z-direction, positive = OUT of model domain; matrix of dimensions Nx*Ny [M/L2/T].
a.bl.x.up	transfer coefficient across the upstream boundary layer. in x-direction $Flux=a.bl.x.up*(C.bl.x.up-C[1,,])$. One value [L/T].
C.bl.x.up	concentration at the upstream boundary layer in x-direction; matrix of dimensions Ny*Nz [M/L3].
a.bl.x.down	transfer coefficient across the downstream boundary layer in x-direction; $Flux=a.bl.x.down*(C.bl.x.down-C[1,,])$. One value [L/T].
C.bl.x.down	concentration at the downstream boundary layer in x-direction ; matrix of dimensions Ny*Nz [M/L3].
a.bl.y.up	transfer coefficient across the upstream boundary layer. in y-direction $Flux=a.bl.y.up*(C.bl.y.up-C[,1,])$. One value [L/T].

<code>C.bl.y.up</code>	concentration at the upstream boundary layer in y-direction; matrix of dimensions $N_x \times N_z$ [M/L3].
<code>a.bl.y.down</code>	transfer coefficient across the downstream boundary layer in y-direction; $\text{Flux} = a.bl.y.down * (C.bl.y.down - C.bl.y.up)$. One value [L/T].
<code>C.bl.y.down</code>	concentration at the downstream boundary layer in y-direction ; matrix of dimensions $N_x \times N_z$ [M/L3].
<code>a.bl.z.up</code>	transfer coefficient across the upstream boundary layer. in y-direction $\text{Flux} = a.bl.y.up * (C.bl.z.up - C.bl.z.down)$. One value [L/T].
<code>C.bl.z.up</code>	concentration at the upstream boundary layer in z-direction; matrix of dimensions $N_x \times N_y$ [M/L3].
<code>a.bl.z.down</code>	transfer coefficient across the downstream boundary layer in z-direction; $\text{Flux} = a.bl.z.down * (C.bl.z.up - C.bl.z.down)$. One value [L/T].
<code>C.bl.z.down</code>	concentration at the downstream boundary layer in z-direction ; matrix of dimensions $N_x \times N_y$ [M/L3].
<code>D.grid</code>	diffusion coefficient defined on all grid cell interfaces. Should contain elements <code>x.int</code> , <code>y.int</code> , <code>z.int</code> , arrays with the values on the interfaces in x, y and z-direction, and with dimensions $(N_x+1) \times N_y \times N_z$, $N_x \times (N_y+1) \times N_z$ and $N_x \times N_y \times (N_z+1)$ respectively. [L2/T].
<code>D.x</code>	diffusion coefficient in x-direction, defined on grid cell interfaces. One value, a vector of length (N_x+1) , or a $(N_x+1) \times N_y \times N_z$ array [L2/T].
<code>D.y</code>	diffusion coefficient in y-direction, defined on grid cell interfaces. One value, a vector of length (N_y+1) , or a $N_x \times (N_y+1) \times N_z$ array [L2/T].
<code>D.z</code>	diffusion coefficient in z-direction, defined on grid cell interfaces. One value, a vector of length (N_z+1) , or a $N_x \times N_y \times (N_z+1)$ array [L2/T].
<code>v.grid</code>	advective velocity defined on all grid cell interfaces. Can be positive (downstream flow) or negative (upstream flow). Should contain elements <code>x.int</code> , <code>y.int</code> , <code>z.int</code> , arrays with the values on the interfaces in x, y and z-direction, and with dimensions $(N_x+1) \times N_y \times N_z$, $N_x \times (N_y+1) \times N_z$ and $N_x \times N_y \times (N_z+1)$ respectively. [L/T].
<code>v.x</code>	advective velocity in the x-direction, defined on grid cell interfaces. Can be positive (downstream flow) or negative (upstream flow). One value, a vector of length (N_x+1) , or a $(N_x+1) \times N_y \times N_z$ array [L/T].
<code>v.y</code>	advective velocity in the y-direction, defined on grid cell interfaces. Can be positive (downstream flow) or negative (upstream flow). One value, a vector of length (N_y+1) , or a $N_x \times (N_y+1) \times N_z$ array [L/T].
<code>v.z</code>	advective velocity in the z-direction, defined on grid cell interfaces. Can be positive (downstream flow) or negative (upstream flow). One value, a vector of length (N_z+1) , or a $N_x \times N_y \times (N_z+1)$ array [L/T].
<code>AFDW.grid</code>	weight used in the finite difference scheme for advection in the x-direction, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. Should contain elements <code>x.int</code> , <code>y.int</code> , <code>z.int</code> , arrays with the values on the interfaces in x, y and z-direction, and with dimensions $(N_x+1) \times N_y \times N_z$, $N_x \times (N_y+1) \times N_z$ and $N_x \times N_y \times (N_z+1)$ respectively. [-].
<code>AFDW.x</code>	weight used in the finite difference scheme for advection in the x-direction, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. One value, a vector of length (N_x+1) , a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $(N_x+1) \times N_y \times N_z$ array [-].

AFDW.y	weight used in the finite difference scheme for advection in the y-direction, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. One value, a vector of length (Ny+1), a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x \times (N_y+1) \times N_z$ array [-].
AFDW.z	weight used in the finite difference scheme for advection in the z-direction, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. One value, a vector of length (Nz+1), a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x \times N_y \times (N_z+1)$ array [-].
VF.grid	Volume fraction. A list. Should contain elements <code>x.int</code> , <code>y.int</code> , <code>z.int</code> , arrays with the values on the interfaces in x, y and z-direction, and with dimensions $(N_x+1) \times N_y \times n_z$, $N_x \times (N_y+1) \times N_z$ and $N_x \times N_y \times (N_z+1)$ respectively. [-].
VF.x	Volume fraction at the grid cell interfaces in the x-direction. One value, a vector of length (Nx+1), a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $(N_x+1) \times N_y \times N_z$ array [-].
VF.y	Volume fraction at the grid cell interfaces in the y-direction. One value, a vector of length (Ny+1), a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x \times (N_y+1) \times N_z$ array [-].
VF.z	Volume fraction at the grid cell interfaces in the z-direction. One value, a vector of length (Nz+1), a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x \times N_y \times (N_z+1)$ array [-].
A.grid	Interface area, a list. Should contain elements <code>x.int</code> , <code>y.int</code> , <code>z.int</code> , arrays with the values on the interfaces in x, y and z-direction, and with dimensions $(N_x+1) \times N_y \times n_z$, $N_x \times (N_y+1) \times N_z$ and $N_x \times N_y \times (N_z+1)$ respectively. [L2].
A.x	Interface area defined at the grid cell interfaces in the x-direction. One value, a vector of length (Nx+1), a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $(N_x+1) \times N_y \times N_z$ array [L2].
A.y	Interface area defined at the grid cell interfaces in the y-direction. One value, a vector of length (Ny+1), a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x \times (N_y+1) \times N_z$ array [L2].
A.z	Interface area defined at the grid cell interfaces in the z-direction. One value, a vector of length (Nz+1), a <code>prop.1D</code> list created by <code>setup.prop.1D</code> , or a $N_x \times N_y \times (N_z+1)$ array [L2].
dx	distance between adjacent cell interfaces in the x-direction (thickness of grid cells). One value or vector of length N_x [L].
dy	distance between adjacent cell interfaces in the y-direction (thickness of grid cells). One value or vector of length N_y [L].
dz	distance between adjacent cell interfaces in the z-direction (thickness of grid cells). One value or vector of length N_z [L].
grid	discretization grid, a list containing at least elements <code>dx</code> , <code>dx.aux</code> , <code>dy</code> , <code>dy.aux</code> , <code>dz</code> , <code>dz.aux</code> (see <code>setup.grid.2D</code>) [L].
full.check	logical flag enabling a full check of the consistency of the arguments (default = FALSE; TRUE slows down execution by 50 percent).
full.output	logical flag enabling a full return of the output (default = FALSE; TRUE slows down execution by 20 percent).

Details

Do not use this with too large grid.

The **boundary conditions** are either

- (1) zero-gradient
- (2) fixed concentration
- (3) convective boundary layer
- (4) fixed flux

This is also the order of priority. The zero gradient is the default, the fixed flux overrules all other.

Value

a list containing:

dC	the rate of change of the concentration C due to transport, defined in the centre of each grid cell, an array with dimension $N_x*N_y*N_z$ [M/L3/T].
C.x.up	concentration at the upstream interface in x-direction. A matrix of dimension N_y*N_z [M/L3]. Only when <code>full.output = TRUE</code> .
C.x.down	concentration at the downstream interface in x-direction. A matrix of dimension N_y*N_z [M/L3]. Only when <code>full.output = TRUE</code> .
C.y.up	concentration at the upstream interface in y-direction. A matrix of dimension N_x*N_z [M/L3]. Only when <code>full.output = TRUE</code> .
C.y.down	concentration at the downstream interface in y-direction. A matrix of dimension N_x*N_z [M/L3]. Only when <code>full.output = TRUE</code> .
C.z.up	concentration at the upstream interface in z-direction. A matrix of dimension N_x*N_y [M/L3]. Only when <code>full.output = TRUE</code> .
C.z.down	concentration at the downstream interface in z-direction. A matrix of dimension N_x*N_y [M/L3]. Only when <code>full.output = TRUE</code> .
x.flux	flux across the interfaces in x-direction of the grid cells. A $(N_x+1)*N_y*N_z$ array [M/L2/T]. Only when <code>full.output = TRUE</code> .
y.flux	flux across the interfaces in y-direction of the grid cells. A $N_x*(N_y+1)*N_z$ array [M/L2/T]. Only when <code>full.output = TRUE</code> .
z.flux	flux across the interfaces in z-direction of the grid cells. A $N_x*N_y*(N_z+1)$ array [M/L2/T]. Only when <code>full.output = TRUE</code> .
flux.x.up	flux across the upstream boundary in x-direction, positive = INTO model domain. A matrix of dimension N_y*N_z [M/L2/T].
flux.x.down	flux across the downstream boundary in x-direction, positive = OUT of model domain. A matrix of dimension N_y*N_z [M/L2/T].
flux.y.up	flux across the upstream boundary in y-direction, positive = INTO model domain. A matrix of dimension N_x*N_z [M/L2/T].
flux.y.down	flux across the downstream boundary in y-direction, positive = OUT of model domain. A matrix of dimension N_x*N_z [M/L2/T].
flux.z.up	flux across the upstream boundary in z-direction, positive = INTO model domain. A matrix of dimension N_x*N_y [M/L2/T].
flux.z.down	flux across the downstream boundary in z-direction, positive = OUT of model domain. A matrix of dimension N_x*N_y [M/L2/T].

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References

Soetaert and Herman, a practical guide to ecological modelling - using R as a simulation platform, 2009. Springer

Examples

```
#####
# Diffusion in 3-D; imposed boundary conditions
#####
diffusion3D <- function(t,Y,par) {
  yy    <- array(dim=c(n,n,n),data=Y) # vector to 3-D array
  dY    <- -r*yy # consumption
  BND    <- matrix(nr=n,nc=n,1) # boundary concentration

  dY <- dY + tran.3D(C=yy,
    C.x.up=BND, C.y.up=BND, C.z.up=BND,
    C.x.down=BND,C.y.down=BND,C.z.down=BND,
    D.x=Dx, D.y=Dy, D.z=Dz,
    dx = dx, dy=dy, dz=dz,full.check=TRUE)$dC
  return(list(as.vector(dY)))
}

# parameters
dy    <- dx <- dz <-1 # grid size
Dy    <- Dx <- Dz <-1 # diffusion coeff, X- and Y-direction
r      <- 0.025 # consumption rate

n <- 10
y <- array(dim=c(n,n,n),data=10.)

print(system.time(
  ST3 <- steady.3D(y,func=diffusion3D,parms=NULL,pos=TRUE,dimens=c(n,n,n),
    lrw=2000000, verbose=TRUE)
))

y <- array(dim=c(n,n,n),data=ST3$y)
filled.contour(y[, , n/2],color.palette=terrain.colors)
```

tran.volume.1D

1-D volumetric advective-diffusive transport in an aquatic system

Description

Estimates the volumetric transport term (i.e. the rate of change of the concentration due to diffusion and advection) in a one-dimensional model of an aquatic system (river, estuary).

Volumetric transport implies the use of flows (mass per unit of time) rather than fluxes (mass per unit of area per unit of time) as is done in [tran.1D](#).

The `tran.volume.1D` routine is particularly suited for modelling channels (like rivers, estuaries) where the cross-sectional area changes, but where this area change needs not to be explicitly modelled as such.

Another difference with `tran.1D` is that the present routine also allows lateral water or lateral mass input (as from side rivers or diffusive lateral ground water inflow).

Usage

```
tran.volume.1D(C, C.up=C[1], C.down=C[length(C)],
  C.lat=C, F.up=NULL, F.down=NULL, F.lat=NULL,
  Disp,          flow = 0, flow.lat=NULL, AFDW = 1,
  V=NULL, full.check = FALSE, full.output = FALSE)
```

Arguments

<code>C</code>	tracer concentration, defined at the centre of the grid cells. A vector of length N [M/L ³].
<code>C.up</code>	tracer concentration at the upstream interface. One value [M/L ³].
<code>C.down</code>	tracer concentration at downstream interface. One value [M/L ³].
<code>C.lat</code>	tracer concentration in the lateral input, defined at grid cell centres. One value, a vector of length N , or a list as defined by setup.prop.1D [M/L ³]. The default is <code>C.lat = C</code> , (a zero-gradient condition). Setting <code>C.lat=0</code> , together with a positive <code>F.lat</code> will lead to dilution of the tracer concentration in the grid cells.
<code>F.up</code>	total tracer input at the upstream interface. One value [M/T].
<code>F.down</code>	total tracer input at downstream interface. One value [M/T].
<code>F.lat</code>	total lateral tracer input, defined at grid cell centres. One value, a vector of length N , or a 1D list property as defined by setup.prop.1D , [M/T].
<code>Disp</code>	BULK dispersion coefficient, defined on grid cell interfaces. One value, a vector of length $N+1$, or a 1D list property as defined by setup.prop.1D [L ³ /T].
<code>flow</code>	water flow rate, defined on grid cell interfaces. One value, a vector of length $N+1$, or a list as defined by setup.prop.1D [L ³ /T]. If <code>flow.lat</code> is not NULL the <code>flow</code> should be one value containing the flow rate at the upstream boundary. If <code>flow.lat</code> is not NULL then <code>flow</code> must be a vector or a list.
<code>flow.lat</code>	lateral water flow rate [L ³ /T] into each volume box, defined at grid cell centres. One value, a vector of length N , or a list as defined by setup.prop.1D . If <code>flow.lat</code> has a value, then <code>flow</code> should be the flow rate at the upstream interface (one value). For each grid cell, the <code>flow</code> at the downstream side of a grid cell is then estimated by water balance (adding <code>flow.lat</code> in the cell to flow rate at the upstream side of the grid cell). If <code>flow.lat</code> is NULL, then it is determined by water balance from <code>flow</code> .
<code>AFDW</code>	weight used in the finite difference scheme for advection, defined on grid cell interfaces; backward = 1, centred = 0.5, forward = 0; default is backward. One value, a vector of length $N+1$, or a list as defined by setup.prop.1D [-].
<code>V</code>	grid cell volume, defined at grid cell centres [L ³]. One value, a vector of length N , or a list as defined by setup.prop.1D .
<code>full.check</code>	logical flag enabling a full check of the consistency of the arguments (default = FALSE; TRUE slows down execution by 50 percent).
<code>full.output</code>	logical flag enabling a full return of the output (default = FALSE; TRUE slows down execution by 20 percent).

Details

The **boundary conditions** are of type

- 1. zero-gradient (default)
- 2. fixed concentration
- 3. fixed input

The *bulk dispersion coefficient* (`Disp`) and the *flow rate* (`flow`) can be either one value or a vector of length $N+1$, defined at all grid cell interfaces, including upstream and downstream boundary.

The spatial discretisation is given by the volume of each box (`V`), which can be one value or a vector of length $N+1$, defined at the centre of each grid cell.

The water flow is mass conservative. Over each volume box, the routine calculates internally the downstream outflow of water in terms of the upstream inflow and the lateral inflow.

Value

<code>dC</code>	the rate of change of the concentration <code>C</code> due to transport, defined in the centre of each grid cell [M/L ³ /T].
<code>F.up</code>	mass flow across the upstream boundary, positive = INTO model domain. One value [M/T].
<code>F.down</code>	mass flow across the downstream boundary, positive = OUT of model domain. One value [M/T].
<code>F.lat</code>	lateral mass input per volume box, positive = INTO model domain. A vector of length N [M/T].
<code>F</code>	mass flow across at the interface of each grid cell. A vector of length $N+1$ [M/T]. Only provided when (<code>full.output = TRUE</code>)
<code>flow.up</code>	water flow across the upstream boundary, positive = INTO model domain. One value [L ³ /T]. Only provided when (<code>full.output = TRUE</code>)
<code>flow.down</code>	water flow across the downstream boundary, positive = OUT of model domain. One value [L ³ /T]. Only provided when (<code>full.output = TRUE</code>)
<code>F.lat</code>	lateral water input on each volume box, positive = INTO model domain. A vector of length N [L ³ /T]. Only provided when (<code>full.output = TRUE</code>)
<code>F</code>	water flow across at the interface of each grid cell. A vector of length $N+1$ [M/T]. Only provided when (<code>full.output = TRUE</code>)

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References

Soetaert and Herman (2009) A practical guide to ecological modelling - using R as a simulation platform. Springer.

See Also

[tran.1D](#)

Examples

```
#####
#  EXAMPLE : organic carbon (OC) decay in a widening river      #
#####

# Two scenarios are simulated: the baseline includes only input
# of organic matter upstream. The second scenario simulates the
# input of an important side river half way the estuary.

#=====#
# Model formulation #
#=====#

river.model <- function (t=0,OC,pars=NULL)
{
  tran <- tran.volume.1D(C=OC,F.up=F.OC,F.lat=F.lat,Disp=Disp,
  flow=flow.up,flow.lat=flow.lat,V=Volume)$dC
  reac <- - k*OC
  return(list(dCdt = tran + reac))
}

#=====#
# Parameter definition #
#=====#

# Initialising morphology estuary:

nbox          <- 500      # number of grid cells
lengthEstuary <- 100000   # length of estuary [m]
BoxLength     <- lengthEstuary/nbox # [m]
Distance      <- seq(BoxLength/2, by=BoxLength, len=nbox) # [m]
Int.Distance   <- seq(0, by=BoxLength, len=(nbox+1)) # [m]

# Cross sectional area: sigmoid function of estuarine distance [m2]
CrossArea <- 4000 + 72000 * Distance^5 / (Distance^5+50000^5)

# Volume of boxes (m3)
Volume <- CrossArea*BoxLength

# Transport coefficients
Disp    <- 1000   # m3/s, bulk dispersion coefficient
flow.up <- 180    # m3/s, main river upstream inflow
flow.lat.0 <- 180 # m3/s, side river inflow

F.OC    <- 180      # input organic carbon [mol s-1]
F.lat.0 <- 180      # lateral input organic carbon [mol s-1]

k        <- 10/(365*24*3600) # decay constant organic carbon [s-1]

#=====#
# Model solution #
#=====#
#scenario 1: without lateral input
F.lat <- rep(0,length.out=nbox)
flow.lat <- rep(0,length.out=nbox)
```

```

Conc1 <- steady.band(runif(nbox),fun=river.model,nspec=1)$y
tran1 <- tran.volume.1D(C=Conc1,F.up=F.OC,F.lat=F.lat,Disp=Disp,
flow=flow.up,flow.lat=flow.lat,V=Volume,full.output=TRUE)

#scenario 1: with lateral input
F.lat <- F.lat.0*dnorm(x=Distance/lengthEstuary,
mean = Distance[nbox/2]/lengthEstuary, sd = 1/20, log = FALSE)/nbox
flow.lat <- flow.lat.0*dnorm(x=Distance/lengthEstuary,
mean = Distance[nbox/2]/lengthEstuary, sd = 1/20, log = FALSE)/nbox
Conc2 <- steady.band(runif(nbox),fun=river.model,nspec=1)$y
tran2 <- tran.volume.1D(C=Conc2,F.up=F.OC,F.lat=F.lat,Disp=Disp,
flow=flow.up,flow.lat=flow.lat,V=Volume,full.output=TRUE)

#=====#
# Plotting output      #
#=====#
par(mfrow=c(2,1))

matplot(Distance/1000,cbind(Conc1,Conc2),lwd=2,
main="Organic carbon decay in the estuary",xlab="distance [km]",
ylab="OC Concentration [mM]",
type="l")
legend ("topright",lty=1,col=c("black","red"),
c("baseline","with side river input"))

matplot(Int.Distance/1000,cbind(tran1$flow,tran2$flow),lwd=2,
main="Longitudinal change in the water flow rate",xlab="distance [km]",
ylab="Flow rate [m3 s-1]", ylim=c(0,400),
type="l")
legend ("bottomright",lty=1,col=c("black","red"),
c("baseline","with side river input"))

```

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