# Package 'SOMbrero'

July 23, 2013

2 initGrid

initGrid	Create an empty Self-Organizing Map structure	

# Description

Create an empty Self-Organizing Map structure which is a list of 2-dimensional points.

# Usage

```
initGrid(dimension=c(5,5), topo=c("square"), dist.type=c("letremy", "maximum",
"euclidean", "manhattan", "canberra", "binary", "minkowski"))
## S3 method for class 'myGrid'
print(x, ...)
## S3 method for class 'myGrid'
summary(object, ...)
```

## **Arguments**

dimension	Vector of two integer points corresponding to the x dimension and the y dimension. Default values are: $(5, 5)$ .
topo	The topology to be used to build the grid. Default value is square.
dist.type	The distance type to be used. Default value is maximum.
x, object	an object of class myGrid
	not used

# Value

 $\verb|initGrid| function returns an object of class \verb|myGrid|, including the following components:$ 

coord	A two columns matrix which provides the coordinates of the points of the Self-Organizing Map structure,
topo	Same value as the arguments given to initGrid function,
dim	Same values as the arguments given to initGrid function.
dist.type	Same value as the arguments given to initGrid function.

## Author(s)

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```

# See Also

See plot.myGrid for plotting a myGrid class object in a graphical window.

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## **Examples**

```
# creating a default grid
# default parameters are: 5x5 dimension, squared topology
# and letremy distance type
initGrid()
# creating a 5x7 squared grid
initGrid(dimension=c(5, 7), topo="square", dist.type="maximum")
```

initSOM

Initialize parameters for the SOM algorithm

## Description

The initSOM function returns a paramSOM class object which contains the parameters needed to run the SOM algorithm.

## Usage

```
initSOM(dimension=c(5,5), topo=c("square"),
                    dist.type=c("letremy", "maximum", "euclidean", "manhattan",
                     "canberra", "binary", "minkowski"),
                    type=c("numeric", "relational", "korresp"),
                    mode=c("online"),
                    maxit=500, nb.save=0, verbose=FALSE, proto0=NULL,
                    init.proto=c("random", "obs"),
                    scaling=switch(type,
                                    "numeric"="unitvar",
                                    "relational"="none",
                                    "korresp"="chi2"),
                    radius.type=c("letremy"))
## S3 method for class 'paramSOM'
print(x, ...)
## S3 method for class 'paramSOM'
summary(object, ...)
```

# **Arguments**

dimension	Vector of two integer points corresponding to the x dimension and the y dimension of the $myGrid$ class object. Default values are: $(5,5)$ .
topo	The topology to be used to build the grid of the myGrid class object. Default value is square.
dist.type	The neighborhood relationship on the grid. Default value is "letremy" which is the original implementation from Patrick Letremy. The other possible values are the values passed to method in the function dist.
type	The SOM algorithm type. Possible values are: numeric (default value), korresp and relational.

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mode	The SOM algorithm mode. Default value is online.
maxit	The maximum number of iterations to be done during the SOM algorithm process. Default value is $500$ .
nb.save	The number of intermediate back-ups to be done during the algorithm process. Default value is $0.$
verbose	The boolean value which control the printing during the SOM algorithm process. Default value is ${\tt FALSE}.$
proto0	The initial prototypes. Default value is NULL.
init.proto	The method to be used to initialize the prototypes, either randomization or an observation sample. This argument is only considered when $proto0=NULL$ . Default value is random.
scaling	The type of data pre-processing. For numeric SOM, possibilities are unitvar (which is the default value for a numeric SOM), none (which is the only value allowed for a relational SOM), center and chi2 (which is only available for a korresp SOM and is also its default value).
radius.type	The neighbourhood type. Default value is "letremy", which corresponds to the original implementation from Patrick Letremy.
x, object	an object of class paramSOM.
	not used

## Value

The initSOM function returns an object of class paramSOM which is a list of the parameters passed to the initSOM function, plus the default parameters for whose which were not set by the user.

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```

#### References

```
Letremy, P. (2005) Programmes bases sur l'algorithme de Kohonen et dedies a l'analyse des donnees. SAS/IML programs for 'korresp'. http://samos.univ-parisl.fr/Programmes-bases-sur-l-algorithme
```

# See Also

See initGrid for creating a SOM prior structure (grid).

```
# create a default 'paramSOM' class object
default.paramSOM <- initSOM()
summary(default.paramSOM)</pre>
```

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lesmis

Dataset "Les Miserables"

# Description

This dataset contains the coappearance network (igraph object) of characters in the novel Les Miserables (written by the French writter Victor Hugo).

# Usage

```
data(lesmis)
```

## **Format**

lesmis is an igraph object. Its vertices are the characters of the novel and an edge indicates that the two characters appear together in the same chapter of the novel, at least once. dissim.lesmis is a dissimilarity matrix computed with the function shortest.paths and containing the length of the shortest paths between pairs of nodes.

## **Details**

Les Miserables is a French historical novel, written by Victor Hugo and published in 1862. The co-appearance network has been extracted by D.E. Knuth (1993).

## Source

```
http://people.sc.fsu.edu/~jburkardt/datasets/sgb/jean.dat
```

## References

```
Hugo, H. (1862) Les Miserables.
```

Knuth, D.E. (1993) *The Stanford GraphBase: A Platform for Combinatorial Computing*. Reading (MA): Addison-Wesley.

```
data(lesmis)
## Not run: plot(lesmis,vertex.size=0)
```

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plot.myGrid

Draw a myGrid class object

## **Description**

Draw a grid corresponding to a myGrid class object in a graphical window.

# Usage

```
## S3 method for class 'myGrid'
plot(x, neuron.col="white", ...)
```

# Arguments

x The myGrid class object to be drawn.

neuron.col Color(s) used to depict the neurons. Default value is white. If the argument is

composed of one single color, neurons will all be filled with the same color. If the argument is composed of many colors, the number of colors must match the

total number of neurons.

... Further arguments to the plot function.

#### **Details**

Color filling process uses the coordinates of the object x, having class myGrid and included in x\$coord.

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```

# See Also

initGrid to define a myGrid class object.

```
# creating grid
a.grid <- initGrid(dimension=c(5,5), topo="square", dist.type="maximum")
# plotting grid
# without any color specification
plot(a.grid)
# generating colors from rainbow() function
my.colors <- rainbow(5*5)
plot(a.grid, neuron.col=my.colors)</pre>
```

plot.somRes 7

plot.somRes

Draw a somRes class object

# **Description**

Produce graphics to help interpreting a somRes object.

## Usage

```
## S3 method for class 'somRes'
plot(x, what=c("obs", "prototypes", "energy", "add"),
                        type=switch(what,
                                     "obs"="hitmap",
                                     "prototypes"="color",
                                     "add"="pie",
                                     "energy"=NULL),
                        variable = if (what=="add") NULL else
                          if (type=="boxplot") 1:min(5,ncol(x$data)) else 1,
                        my.palette=NULL,
                        is.scaled = if (x$parameters$type=="numeric") TRUE else
                          FALSE,
                        proportional=TRUE, print.title=FALSE, s.radius=1,
                        pie.graph=FALSE, pie.variable=NULL,
                        the.titles=if (what!="energy")
                          switch (type,
                                           "graph"=
                                             1:prod(x$parameters$the.grid$dim),
                                           paste("Cluster",
                                                 1:prod(x$parameters$
                                                          the.grid$dim))),
                        view = if (x$parameters$type=="korresp") "r" else NULL,
                         ...)
```

# Arguments

x	A somRes class object.
what	What you want to plot. Either the observations (obs, default case), the evolution of energy (energy), the prototypes (prototypes) or an additional variable (add).
type	Further argument indicating which type of chart you want to have. Choices depend on the value of what (what="energy" has no type argument). Default values are "hitmap" for obs, "color" for prototypes and "pie" for add. See section "Details" below for further details.
variable	Either the variable to be used for what="add" or the index of the variable of the data set to consider. For type="boxplot", the default value is the sequence from 1 to the minimum between 5 and the number of columns of the

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	data set. In all other cases, default value is 1. See somRes.plotting for further details.
my.palette	A vector of colors. If omitted, predefined palettes are used, depending on the plot case. This argument is used for the following combinations: all "color" types and "prototypes"/"poly.dist".
is.scaled	A boolean indicating whether values should be scaled prior to plotting or not. Default value is TRUE when type="numeric" and FALSE in the other cases.
proportional	Boolean used when what="add" and type="pie". It indicates if the pies should be proportional to the number of observations in the class. Default value is TRUE.
print.title	Boolean used to indicate whether each neuron should have a title or not. Default value is FALSE. It is feasible on the following cases: all "color" types, all "lines" types, all "barplot" types, all "radar" types, all "boxplot" types, all "names" types, "add"/"pie", "prototypes"/"umatrix", "prototypes"/"poly.dist" and "add"/"words".
s.radius	The size of the pies to be plotted (maximum size when $proportional=TRUE$ ). The default value is 0 . 9.
pie.graph	Boolean used when what="add" and type="graph". It indicates if the vertices should be pies or not.
pie.variable	The variable needed to plot the pies when what="add", type="graph" and argument pie.graph is set to TRUE.
the.titles	The titles to be printed for each neuron.
view	Used only when the algorithm's type is "korresp". It indicates whether rows ("r") or columns ("c") must be drawn.
•••	Further arguments to be passed to the underlined plot function (which can be plot, barplot, pie depending on type; see somRes.plotting for further details).

# **Details**

See somRes.plotting for further details.

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# See Also

trainSOM to run the SOM algorithm, that returns a somRes class object.

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predict.somRes

Predict the classification of a new observation

## **Description**

Predict the neuron where a new observation is classified

# Usage

```
## S3 method for class 'somRes'
predict(object, x.new, ...)
```

## **Arguments**

object a somRes object x.new the new observation

... not used

## **Details**

The length of the new observation must match the number of colums of the data set given to the SOM algorithm (see trainSOM).

#### Value

predict.somRes returns the number of the neuron to which the new observation is assigned (i.e., neuron with the closest prototype).

When the algorithm's type is "korresp", x.new must be the original contingency table passed to the algorithm.

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```

#### See Also

trainSOM

```
set.seed(2343)
my.som <- trainSOM(x.data=iris[-100,1:4], dimension=c(5,5))
predict(my.som, iris[100,1:4])</pre>
```

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```
presidentielles2002
```

2002 French presidential election data set

# **Description**

This data set provides the number of votes at the first round of the 2002 French presidential election for each of the 16 candidates for 106 administrative districts called "Departements".

## Usage

```
data(presidentielles2002)
```

#### **Format**

presidentielles2002 is a data frame of 106 rows (the French administrative districts called "Departements") and 16 columns (the candidates).

#### Source

The data are provided by the French minister "Ministere de l'Interieur". The original data can be downloaded at http://www.interieur.gouv.fr/Elections/Les-resultats/Presidentielles (2002 elections and "Resultats par departements")

## References

The 2002 French presidential election consisted of two rounds. The second round attracted a greater than usual amount of international attention because of far-right candidate Le Pen's unexpected victory over Socialist candidate Lionel Jospin. The event is known because, on the one hand, the number of candidates was unusually high (16) and, on the other hand, because the polls had failed to predict that Jean-Marie would be on the second round.

Further comments at http://en.wikipedia.org/wiki/French\_presidential\_election, \_2002 or at http://fr.wikipedia.org/wiki/%C3%89lection\_pr%C3%A9sidentielle\_fran%C3%A7aise\_de\_2002 (in French).

```
data(presidentielles2002)
apply(presidentielles2002,2,sum)
```

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protoDist

Compute distances between prototypes

## **Description**

Compute distances, either between all prototypes (mode="complete") or only between prototypes' neighbours (mode="neighbors").

# Usage

```
## S3 method for class 'somRes'
protoDist(object, mode=c("complete", "neighbors"), ...)
```

# **Arguments**

object a somRes object.

mode Specifies which distances should be computed.

... Not used.

#### **Details**

When mode="complete", distances between all prototypes are computed. When mode="neighbors", distances are computed only between the prototypes and their neighbors.

#### Value

When mode="complete", the function returns a square matrix which dimensions are equal to the product of the grid dimensions.

When mode="neighbors", the function returns a list which length is equal to the product of the grid dimensions; the length of each item is equal to the number of neighbors.

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```

#### See Also

trainSOM

```
set.seed(2343)
my.som <- trainSOM(x.data=iris[,1:4], dimension=c(5,5))
protoDist(my.som)</pre>
```

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quality

Compute SOM algorithm quality criteria

## **Description**

The quality function computes several quality criteria for the result of a SOM algorithm.

# Usage

## Arguments

```
sommap A somRes object (see trainSOM for details).

quality.type The quality type to compute. Two types are implemented: quantization and topographic. The output of the function is one those or both of them using the option "all". Default value is the latter.

... Not used.
```

#### Value

The quality function returns either a numeric value (if only one type is computed) or a list a numeric values (if all types are computed)

The quantization error calculates the mean distance between the sample vectors and their respective cluster prototypes. It is a decreasing function of the size of the map.

The topographic error is the simplest of the topology preservation measure: it calculates the ratio of sample vectors for which the second best matching unit is in the direct neighborhood of the best matching unit.

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```

## References

Polzlbauer, G. (2004) Survey and comparison of quality measures for self-organizing maps. In: *Proceedings of the Fifth Workshop on Data Analysis (WDA'04), Paralic, J., Polzlbauer, G., Rauber, A. (eds)* Sliezsky dom, Vysoke Tatry, Slovakia: Elfa Academic Press, 67–82.

#### See Also

```
trainSOM, plot.somRes
```

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## **Examples**

```
my.som <- trainSOM(x.data=iris[,1:4])
quality(my.som, quality.type="all")
quality(my.som, quality.type="topographic")</pre>
```

SOMbrero

Self Organizing Maps Bound to Realize Euclidean and Relational Outputs

# **Description**

This package implements the stochastic (also called on-line) Self-Organising Map (SOM) algorithm for numeric and relational data.

It is based on a grid (see initGrid) which is part of the parameters given to the algorithm (see initSOM and trainSOM). Many graphs can help you with the results (see plot.somRes).

#### **Details**

Package: SOMbrero Type: Package Version: 0.4

Date: 2013-07-22 License: GPL (>= 2)

URL: http://sombrero.r-forge.r-project.org/

The version of the SOM algorithm implemented in this package is the stochastic version.

Several variants able to handle non-vectorial data are also implemented in their stochastic versions: type="korresp" for contingency tables, as described in Cottrel et al., 1993.

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#### References

Kohonen T. (2001) Self-Organizing Maps. Berlin/Heidelberg: Springer-Verlag, 3rd edition.

Cottrell, M., Letremy, P., Roy, E. (1993) Analyzing a contingency table with Kohonen maps: a Factorial Correspondence Analysis. In: *Proceedings of IWANN'93*, *J. Cabestany, J. Mary, A. Prieto (Eds.)*, *Lecture Notes in Computer Science*, Springer-Verlag, 305–311.

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Letremy, P. (2005) Programmes bases sur l'algorithme de Kohonen et dedies a l'analyse des donnees. SAS/IML programs for 'korresp'. http://samos.univ-parisl.fr/Programmes-bases-sur-l-algorithme

Olteanu, M., Villa-Vialaneix, N., Cottrell, M. (2012) On-line relational SOM for dissimilarity data. In: Advances in Self-Organizing Maps (Proceedings of WSOM 2012, Santiago, Chili, 12-14 decembre 2012), Estevez P., Principe J., Zegers P., Barreto G. (eds.), 'Advances in Intelligent Systems and Computing' series, Berlin/Heidelberg: Springer Verlag, 198, 13–22.

#### See Also

initGrid, trainSOM and plot.somRes.

somRes.plotting

Plotting somRes results

# **Description**

Useful details on how to produce graphics to help interpreting a somRes object. Important: all these graphics are available when the algorithm's type is "numeric"; those which are available for a korresp SOM are marked by a \* and those which are available for a relational SOM are marked with a #.

## **Graphics on the observations:** what="obs"

The possible values for type are: "hitmap"(\*, #), "color", "lines", "barplot", "names"(\*, #), "boxplot" and "radar".

For the cases what="obs" and what="add", if a neuron is empty, nothing will be plotted at its location.

- "hitmap" (\*, #) plots proportional areas according to the number of observations per neuron. It is the default plot when what="obs".
- "color" can have two more arguments, var, the index of the variable to be considered (default, 1), and my.palette for the colors to be used. Neurons are filled using the given colors according to the average value level of the observations for the chosen variable.
- "lines" plots, for each neuron, the average value level of the observations, with lines. One point represents a variable. All variables of the dataset used to train the algorithm are plotted.
- "barplot" is similar to "lines" but using barplots. Then, a bar represents a variable.
- "radar" is similar to "lines" but using radars. Then, a slice represents a variable. If needed, a legend can be added; its location has to be passed by the key.loc argument (see stars).
- "names" (\*, #) prints on the grid the element names (i.e., the names of the rows) in the neuron to which it belongs.
- "boxplot" plots boxplots for several observations in every neuron. This case can handle 5 variables at most. The default behavior is to plot the boxplots forthe first 5 variables of the data set; if there is less than 5 variables in the data set, they will all be plotted.

When the algorithm's type is korresp or relational, only the types "hitmap" and "names" are available.

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# Graphic on the energy: what="energy" (\*, #)

This graphic is only available if some intermediate backups have been registered (i.e., x\$parameters\$nb.save>1). Graphic plots the evolution of the level of the energy according to the registered steps.

# Graphics on the prototypes: what="prototypes"

```
The possible values for type are: "3d"(*), "lines"(*, #), "barplot"(*, #), "radar"(*, #), "color"(*), "smooth.dist" (*, #), "poly.dist"(*, #), "umatrix"(*, #), "mds"(*, #) and "grid.dist"(*, #).
```

- "lines" (\*, #) has the same behavior as the "lines" case described in the observations section, but according to the prototypes level;
- "barplot" (\*, #) has the same behavior as the "barplot" case described in the observations section, but according to the prototypes level;
- "radar" (\*, #) has the same behavior as the "radar" case described in the observations section, but according to the prototypes level;
- "color" (\*) has the same behavior as the "color" case described in the observations section, but according to the prototypes level;
- "3d" case is similar to the "color" case, but in 3 dimensions, with x and y the coordinates of the grid and z the value of the prototypes for the considered variable;
- "smooth.dist" (\*, #) depicts the average distance between a prototypes and its neighbors on a map where x and y are the coordinates of the prototypes on the grid;
- "poly.dist" (\*, #) also represents the distances between prototypes but with polygons plotted for each neuron. The closest from the border the polygon point is, the closest the pairs of prototypes are. The color used for filling the polygon shows the number of observations in each neuron. A white polygon means that there is no observation. With the default colors, a red polygon means a high number of observations;
- "umatrix" (\*, #) is another way of plotting distances between prototypes. The grid is plotted and filled with my.palette colors according to the mean distance between the current neuron and the neighboring neurons. With the default colors, red indicates proximity.
- "mds" (\*, #) plots the number of the neuron on a map according to a Multi Dimensional Scaling (MDS) projection on a two dimensional space.
- "grid.dist" (\*, #) plots on a 2 dimension map all distances. The number of points on this picture is equal to: number of neurons×(number of neurons-1)/2. On the x axis corresponds to the prototype distances whereas the y axis depicts the grid distances.

# Graphics on an additional variable: what="add" (#)

The case what="add" considers an additional variable, which has to be given to the argument variable. Its length must match the number of observations in the original data. Then the possible values for type are: "pie"(#), "color"(#), "lines"(#), "boxplot"(#), "barplot"(#), "radar"(#), "names"(#), "words"(#) and "graph"(#).

• "color" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be a numerical vector;

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• "lines" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be a numerical matrix or a data frame;

- "boxplot" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be either a numeric vector or a numeric matrix/data frame:
- "barplot" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be either a numeric vector or a numeric matrix/data frame;
- "radar" (#) has the same behavior as the "color" case described in the observations section. Then, the additional variable must be a numerical matrix or data frame;
- "pie" requires the argument variable to be a factor vector and plots one pie for each neuron according to this factor;
- "names" (#) has the same behavior as the "names" case described in the observations section. Then, the names to be printed are the elements of the variable given to the variable argument;
- "words" (#) needs the argument variable be a contingency table: names of the columns will be used as words and the values express the frequency of a given word in the observation. Then, for each neuron of the grid, the words will be printed with sizes proportional to their frequency in the neuron;
- Last option is "graph" (#). The argument variable must be an igraph object (see library(igraph). According to the existing edges in the graph and to the clustering obtained with the SOM algorithm, a clustered graph will be produced where a vertex between two vertices represents a neuron and the width of an edge is proportional to the number of edges in the given graph between the vertices affected to the corresponding neurons. The option can handle two more arguments: pie.graph and pie.variable. These are used to display the vertex as pie charts. For this case, pie.graph must be set to TRUE and a factor vector is supplied by pie.variable.

When the algorithm's type is korresp, no graphic is available for what="add".

All these graphics are available for a relational SOM.

## Further arguments via ...

Further arguments, their reference functions and the plot.somRes cases are summarized in the following list:

- plot is called by the cases:
  - what="energy"
  - type="lines"
  - what="prototypes"/type="mds"
- plot.myGrid is called by the cases:
  - what="obs"/type="hitmap"
  - type="color"
  - what="prototypes"/type="poly.dist"
  - what="prototypes"/type="umatrix"

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- plot.igraph is called by the case what="add"/type="graph"
- pie is called by the case what="add"/type="pie"
- barplot is called by the cases type="barplot"
- boxplot is called by the cases type="boxplot"
- stars is called by the cases type="radar"
- persp is called by the case what="prototypes"/type="3d"
- wordcloud is called by the cases:

```
- type="names"
- what="add"/type="words"
```

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```

# **Examples**

```
# run the SOM algorithm on the numerical data of 'iris' data set
iris.som <- trainSOM(x.data=iris[,1:4], nb.save=2)

# plots
# on energy
plot(iris.som, what="energy") # energy
# on prototypes
plot(iris.som, what="prototypes", type="3d", variable="Sepal.Length")
# on an additional variable: the flower species
plot(iris.som, what="add", type="pie", variable=iris$Species)</pre>
```

superClass

Create super-clusters from SOM clustering

## **Description**

Aggregate the resulting clustering of the SOM algorithm into super-clusters.

# Usage

```
## S3 method for class 'somRes'
superClass(sommap, method="ward", members=NULL, k=NULL,
h=NULL, ...)
## S3 method for class 'somSC'
print(x, ...)
## S3 method for class 'somSC'
summary(object, ...)
## S3 method for class 'somSC'
```

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# Arguments

sommap	A somRes object
method, memb	pers
	Arguments passed to the holust function.
k, h	Arguments passed to the cutree function (respectively, the number of superclusters or the height where to cut the dendrogram).
x, object	A somSC object
type	The type of plot to draw. Default value is "dendrogram", to plot the dendrogram of the clustering. Case "grid" plots the grid in color according to the super clustering. All other cases are those available in the function plot.somRes.
plot.var	A boolean indicating whether a graph showing the evolution of the explained variance should be plotted. This argument is only used when type="dendrogram", its default value is TRUE.
plot.legend	A boolean indicating whether a legend should be added to the plot. This argument is only used when type is either "grid" or "hitmap" or "mds". Its default value is FALSE.
add.type	A boolean, which default value is FALSE, indicating whether you are giving an additional variable to the argument variable or not. If you do, the function plot.somRes will be called with the argument what set to "add".
	Used for plot.somSC: further arguments passed either to the function plot (case type="dendro") or to plot.myGrid (case type="grid") or to plot.somRes (all other cases).

## **Details**

The superClass function can be used in 2 ways:

- to choose the number of super clusters via an helust object: then, both arguments k and h are not filled.
- to cut the clustering into super clusters: then, either argument k or argument h must be filled. See cutree for details on these arguments.

The squared distance between prototypes is passed to the algorithm.

The different super classes are identified in the following ways:

```
• either with different color, when type is set among: "grid" (*, #), "hitmap" (*, #), "lines" (*, #), "barplot" (*, #), "boxplot", "mds" (*, #), "dendro3d" (*, #), "graph" (*, #)
```

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```
• or with title, when type is set among: "color" (*), "poly.dist" (*, #), "pie" (#), "radar" (#)
```

In the list above, graphics available for a korresp SOM are marked with a \* whereas those available for a relational SOM are marked with a #.

# Value

The superClass function returns an object of class somSC which is a list of the following elements:

cluster The super clustering of the prototypes (only if either k or h are given by user).

tree An hclust object.

som The somRes object given as argument (see trainSOM for details).

## Author(s)

```
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```

#### See Also

```
hclust, cutree, trainSOM, plot.somRes
```

# Examples

```
set.seed(11051729)
my.som <- trainSOM(x.data=iris[,1:4])
# choose the number of super-clusters
sc <- superClass(my.som)
plot(sc)
# cut the clustering
sc <- superClass(my.som, k=4)
summary(sc)
plot(sc)
plot(sc, type="hitmap", plot.legend=TRUE)</pre>
```

trainSOM

Run the SOM algorithm

# Description

The trainSOM function returns a somRes class object which contains the outputs of the algorithm.

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## Usage

```
trainSOM(x.data, ...)
## S3 method for class 'somRes'
print(x, ...)
## S3 method for class 'somRes'
summary(object, ...)
```

## **Arguments**

x.data a data frame or matrix containing the observations to be mapped on the grid by

SOM algorithm.

Further arguments to be passed to the function initSOM for specifying the parameters of the algorithm. The default values of the arguments maxit and dimension are calculated according to the SOM type if the user does not set them:

- maxit is equal to (number of rows+number of columns)\*5 if the SOM type is korresp; it is equal to number of rows\*5 in all other SOM types
- dimension: for a korresp SOM, is equal to maximum between 5 and the minimum of 10 and the ceiling value of the square root of (number of rows+number of columns); in all other SOM types, the square root only considers the number of rows.

x, object an object of class somRes

## **Details**

The version of the SOM algorithm implemented in this package is the stochastic version.

Several variants able to handle non-vectorial data are also implemented in their stochastic versions: type="korresp" for contingency tables, as described in Cottrel et al., 1993.

# Value

The trainSOM function returns an object of class somRes which contains the following components:

clustering the final classification of the data.

prototypes the final coordinates of the prototypes.

energy the final energy of the map.

backup a list containing some intermediate backups of the prototypes coordinates, clus-

tering, energy and the indexes of the recorded backups, if nb.save is set to a

value larger than 1.

data the original dataset used to train the algorithm.

parameters a list of the map's parameters, which is an object of class paramSOM as pro-

duced by the function initSOM.

The function summary.somRes also provides an ANOVA (ANalysis Of VAriance) of each input numeric variables in function of the map's clusters. This is helpful to see which variables participate to the clustering.

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## Note

Warning! Recording intermediate backups with the argument nb.save can strongly increase the computational time since calculating the entire clustering and the energy is time consumming. Use this option with care and only when it is strictly necessary.

#### Author(s)

```
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```

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Kohonen T. (2001) Self-Organizing Maps. Berlin/Heidelberg: Springer-Verlag, 3rd edition.

Cottrell, M., Letremy, P., Roy, E. (1993) Analyzing a contingency table with Kohonen maps: a Factorial Correspondence Analysis. In: *Proceedings of IWANN'93*, *J. Cabestany, J. Mary, A. Prieto (Eds.)*, *Lecture Notes in Computer Science*, Springer-Verlag, 305–311.

Olteanu, M., Villa-Vialaneix, N., Cottrell, M. (2012) On-line relational SOM for dissimilarity data. In: Advances in Self-Organizing Maps (Proceedings of WSOM 2012, Santiago, Chili, 12-14 decembre 2012), Estevez P., Principe J., Zegers P., Barreto G. (eds.), 'Advances in Intelligent Systems and Computing' series, Berlin/Heidelberg: Springer Verlag, 198, 13–22.

#### See Also

See plot.somRes to plot the outputs of the algorithm.

```
# Run trainSOM algorithm on the iris data with 500 iterations
iris.som <- trainSOM(x.data=iris[,1:4])
iris.som
summary(iris.som)</pre>
```