# Package 'supraHex'

February 25, 2014

Type Package

Title A supra-hexagonal map for analysing tabular omics data
Version 1.1.10
Date 2014-2-25
Author Hai Fang and Julian Gough
Maintainer Hai Fang <hfang@cs.bris.ac.uk></hfang@cs.bris.ac.uk>
<b>Depends</b> R (>= $3.0.2$ )
Imports hexbin, grid, MASS, lattice
Description A supra-hexagonal map is a giant hexagon on a 2-dimensional grid seamlessly consisting of smaller hexagons. It is supposed to train, analyse and visualise a high-dimensional omics input data. The supraHex is able to carry out gene clustering/meta-clustering and sample correlation, plus intuitive visualisations to facilitate exploratory analysis. More importantly, it allows for overlaying additional data onto the trained map to explore relations between input and additional data. So with supraHex, it is also possible to carry out multi-layer omics data comparisons. Uniquely to this package, users can ultrafastly understand any tabular omics data, both scientifically and artistically, especially in a sample-specific fashion but with out loss of information on large genes (see http://www.ncbi.nlm.nih.gov/pubmed/24309102).
URL http://supfam.org/supraHex
Collate sPipeline.r sHexGrid.r sTopology.r sInitial.r sTrainology.r sTrainSeq.r sTrainBatch.r sBMH.r sNeighDirect.r sNeighAny.r sHexDist.r sDistance.r sDmat.r sDmatMinima.r sDmatCluster.r sCompReorder.r sWriteData.r sMapOverlay.r visHexPattern.r visHexGrid.r visHexMapping.r visHexComp.r visColormap.r visColorbar.r visVp.r visHexMulComp.r visCompReorder.r visDmatCluster.r visKernels.r visColoralpha.r
License GPL-2
biocViews Bioinformatics, Clustering, Visualization, GeneExpression
R topics documented:
Fang

2 Fang

Index		45
	Xiang	44
	visVp	43
		42
	visHexPattern	40
	1	38
	r	37
		36
	visHexComp	35
		33
		32
	visColormap	31
	<u>.</u>	30
	visColoralpha	29
	•	28
		26
		24
	P83	22
	1	21
	· ·	18
	sNeighDirect	17
	sNeighAny	16
	sMapOverlay	15
		14
		12
	sDmatMinima	10 11
	sDmatCluster	9
	sDmat	8
	sDistance	7
	sCompReorder	5
		_

Fang

Human embryo gene expression dataset from Fang et al. (2010)

### Description

Human embryo dataset contains gene expression levels (5441 genes and 18 embryo samples) from Fang et al. (2010).

### Usage

data(Fang)

### Value

- Fang: a gene expression matrix of 5441 genes x 18 samples, involving six successive stages, each with three replicates.
- Fang. sampleinfo: a matrix containing the information of the 18 samples for the expression matrix *Fang*. The three columns correspond to the sample information: "Name", "Stage" and "Replicate".

Golub 3

• Fang. geneinfo: a matrix containing the information of the 5441 genes for the expression matrix *Fang*. The three columns correspond to the gene information: "AffyID", "EntrezGene" and "Symbol".

#### References

Fang et al. (2010). Transcriptome analysis of early organogenesis in human embryos. *Developmental Cell*, 19(1):174-84.

Golub

Leukemia gene expression dataset from Golub et al. (1999)

### **Description**

Leukemia dataset (learning set) contains gene expression levels (3051 genes and 38 patient samples) from Golub et al. (1999). This dataset has been pre-processed: capping into floor of 100 and ceiling of 16000; filtering by exclusion of genes with max/min <= 5 or max - min <= 500, where max and min refer respectively to the maximum and minimum intensities for a particular gene across mRNA samples; 2-base logarithmic transformation.

#### Usage

data(Golub)

#### Value

• Golub: a gene expression matrix of 3051 genes x 38 samples. These samples include 11 acute myeloid leukemia (AML) and 27 acute lymphoblastic leukemia (ALL) which can be further subtyped into 19 B-cell ALL and 8 T-cell ALL.

#### References

Golub et al. (1999). Molecular classification of cancer: class discovery and class prediction by gene expression monitoring, *Science*, Vol. 286:531-537. http://www-genome.wi.mit.edu/MPR/

sBMH

Function to identify the best-matching hexagons/rectangles for the input data

### **Description**

sBMH is supposed to identify the best-matching hexagons/rectangles (BMH) for the input data.

### Usage

```
sBMH(sMap, data, which_bmh = c("best", "worst", "all"))
```

4 sBMH

#### **Arguments**

sMap an object of class "sMap" or a codebook matrix

data a data frame or matrix of input data

which\_bmh which BMH is requested. It can be a vector consisting of any integer values from

[1, nHex]. Alternatively, it can also be one of "best", "worst" and "all" choices. Here, "best" is equivalent to 1, "worst" for nHex, and "all" for seq(1, nHex)

#### Value

a list with following components:

- bmh: the requested BMH matrix of dlen x length(which\_bmh), where dlen is the total number of rows of the input data
- qerr: the corresponding matrix of quantization errors (i.e., the distance between the input data and their BMH), with the same dimensions as "bmh" above
- mge: the mean quantization error for the "best" BMH
- call: the call that produced this result

### Note

"which\_bmh" upon request can be a vector consisting of any integer values from [1, nHex]

#### See Also

```
sPipeline
```

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10, mean=0, sd=1), nrow=100, ncol=10)</pre>
# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid
sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")</pre>
# 3) initialise the codebook matrix using "uniform" method
sI <- sInitial(data=data, sTopol=sTopol, init="uniform")</pre>
# 4) define trainology at "rough" stage
sT_rough <- sTrainology(sMap=sI, data=data, stage="rough")</pre>
# 5) training at "rough" stage
sM_rough <- sTrainBatch(sMap=sI, data=data, sTrain=sT_rough)</pre>
# 6) define trainology at "finetune" stage
sT_finetune <- sTrainology(sMap=sI, data=data, stage="finetune")</pre>
# 7) training at "finetune" stage
sM_finetune <- sTrainBatch(sMap=sM_rough, data=data, sTrain=sT_rough)</pre>
# 8) find the best-matching hexagons/rectangles for the input data
response <- sBMH(sMap=sM_finetune, data=data, which_bmh="best")</pre>
```

sCompReorder5

|--|

### Description

sCompReorder is supposed to reorder component planes for the input map/data. It returns an object of class "sReorder". It is realized by using a new map grid (with sheet shape consisting of a rectangular lattice) to train component plane vectors (either column-wise vectors of codebook/data matrix or the covariance matrix thereof). As a result, similar component planes are placed closer to each other. It is highly recommend to use trained map (i.e. codebook matrix) as input if data matrix is hugely big to save computational costs.

### Usage

```
sCompReorder(sMap, xdim = NULL, ydim = NULL,
 amplifier = NULL,
 metric = c("none", "pearson", "spearman", "kendall", "euclidean", "manhattan", "cos", "mi"),
 init = c("linear", "uniform", "sample"),
 algorithm = c("sequential", "batch"),
 alphaType = c("invert", "linear", "power"),
 neighKernel = c("gaussian", "bubble", "cutgaussian", "ep", "gamma"))
```

#### **Arguments**

sMap	an object of class "sMap" or input data frame/matrix
xdim	an integer specifying x-dimension of the grid
ydim	an integer specifying y-dimension of the grid
amplifier	an integer specifying the amplifier (3 by default) of the number of component planes. The product of the component number and the amplifier constitutes the number of rectangles in the sheet grid
metric	distance metric used to difine the similarity between component planes. It can be "none", which means directly using column-wise vectors of codebook/data matrix. Otherwise, first calculate the covariance matrix from the codebook/data matrix. The distance metric used for calculating the covariance matrix between component planes can be: "pearson" for pearson correlation, "spearman" for spearman rank correlation, "kendall" for kendall tau rank correlation, "euclidean" for euclidean distance, "manhattan" for cityblock distance, "cos" for cosine similarity, "mi" for mutual information. See sDistance for details
init	an initialisation method. It can be one of "uniform", "sample" and "linear" initialisation methods
algorithm	the training algorithm. Currently, only "sequential" algorithm has been implemented
alphaType	the alpha type. It can be one of "invert", "linear" and "power" alpha types
neighKernel	the training neighbor kernel. It can be one of "gaussian", "bubble", "cutgaussian", "ep" and "gamma" kernels

6 sCompReorder

#### Value

an object of class "sReorder", a list with following components:

- nHex: the total number of rectanges in the grid
- xdim: x-dimension of the grid
- ydim: y-dimension of the grid
- uOrder: the unique order/placement for each component plane that is reordered to the "sheet"-shape grid with rectangular lattice
- coord: a matrix of nHex x 2, with each row corresponding to the coordinates of each "uOrder" rectangle in the 2D map grid
- call: the call that produced this result

#### Note

To ensure the unique placement, each component plane mapped to the "sheet"-shape grid with rectangular lattice is determinied iteratively in an order from the best matched to the next compromised one. If multiple components are hit in the same rectangular lattice, the worse one is always sacrificed by moving to the next best one till all components are placed somewhere exclusively on their own.

#### See Also

sTopology, sPipeline, sBMH, sDistance, visCompReorder

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10, mean=0, sd=1), nrow=100, ncol=10)</pre>
colnames(data) <- paste(rep(S,10), seq(1:10), sep="")</pre>
# 2) get trained using by default setup
sMap <- sPipeline(data=data)</pre>
# 3) reorder component planes in different ways
# 3a) directly using column-wise vectors of codebook matrix
sReorder <- sCompReorder(sMap=sMap, amplifier=2, metric="none")</pre>
# 3b) according to covariance matrix of pearson correlation of codebook matrix
sReorder <- sCompReorder(sMap=sMap, amplifier=2, metric="pearson")</pre>
# 3c) directly using column-wise vectors of input matrix
sReorder <- sCompReorder(sMap=data, amplifier=2, metric="none")</pre>
# 3d) according to covariance matrix of pearson correlation of input matrix
sReorder <- sCompReorder(sMap=data, amplifier=2, metric="pearson")</pre>
# 4) visualise multiple component planes reorded within a sheet-shape rectangle grid
visCompReorder(sMap=sMap, sReorder=sReorder, margin=rep(0.1,4), height=7,
title.rotate=0, title.xy=c(0.45, 1), colormap="gbr", ncolors=10, zlim=c(-1,1),
border.color="transparent")
```

sDistance 7

sDistance

Function to compute the pairwise distance for a given data matrix

#### **Description**

sDistance is supposed to compute and return the distance matrix between the rows of a data matrix using a specified distance metric

#### Usage

```
sDistance(data,
  metric = c("pearson", "spearman", "kendall", "euclidean", "manhattan", "cos", "mi"))
```

#### **Arguments**

data a data frame or matrix of input data

metric distance metric used to distance metric. See 'Note' below for options available

#### Value

• dist: a symmetric distance matrix of nRow x nRow, where nRow is the number of rows of input data matrix

#### Note

The distance metrics are supported:

- "pearson": Pearson correlation. Note that two curves that have identical shape, but different magnitude will still have a correlation of 1
- "spearman": Spearman rank correlation. As a nonparametric version of the pearson correlation, it calculates the correlation between the ranks of the data values in the two vectors (more robust against outliers)
- "kendall": Kendall tau rank correlation. Compared to spearman rank correlation, it goes a step further by using only the relative ordering to calculate the correlation. For all pairs of data points  $(x_i,y_i)$  and  $(x_j,y_j)$ , it calls a pair of points either as concordant (Nc in total) if  $(x_i-x_j)*(y_i-y_j)>0$ , or as discordant (Nd in total) if  $(x_i-x_j)*(y_i-y_j)<0$ . Finally, it calculates gamma coefficient (Nc-Nd)/(Nc+Nd) as a measure of association which is highly resistant to tied data
- "euclidean": Euclidean distance. Unlike the correlation-based distance measures, it takes the magnitude into account (input data should be suitably normalized
- "manhattan": Cityblock distance. The distance between two vectors is the sum of absolute value of their differences along any coordinate dimension
- "cos": Cosine similarity. As an uncentered version of pearson correlation, it is a measure of similarity between two vectors of an inner product space, i.e., measuring the cosine of the angle between them (using a dot product and magnitude)
- "mi": Mutual information (MI). MI provides a general measure of dependencies between variables, in particular, positive, negative and nonlinear correlations. The caclulation of MI is implemented via applying adaptive partitioning method for deriving equal-probability bins (i.e., each bin contains approximately the same number of data points). The number of bins is

8 sDmat

heuristically determined (the lower bound): 1 + log2(n), where n is the length of the vector. Because MI increases with entropy, we normalize it to allow comparison of different pairwise clone similarities: 2 \* MI/[H(x) + H(y)], where H(x) and H(y) stand for the entropy for the vector x and y, respectively

#### See Also

```
sDmatCluster
```

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10, mean=0, sd=1), nrow=100, ncol=10)</pre>
# 2) calculate distance matrix using different metric
sMap <- sPipeline(data=data)</pre>
# 2a) using "pearson" metric
dist <- sDistance(data=data, metric="pearson")</pre>
# 2b) using "cos" metric
# dist <- sDistance(data=data, metric="cos")</pre>
# 2c) using "spearman" metric
# dist <- sDistance(data=data, metric="spearman")</pre>
# 2d) using "kendall" metric
# dist <- sDistance(data=data, metric="kendall")</pre>
# 2e) using "euclidean" metric
# dist <- sDistance(data=data, metric="euclidean")</pre>
# 2f) using "manhattan" metric
# dist <- sDistance(data=data, metric="manhattan")</pre>
# 2g) using "mi" metric
# dist <- sDistance(data=data, metric="mi")</pre>
```

sDmat

Function to calculate distance matrix in high-dimensional input space but according to neighborhood relationships in 2D output space

#### **Description**

sDmat is supposed to calculate distance (measured in high-dimensional input space) to neighbors (defined by based on 2D output space) for each of hexagons/rectangles

### Usage

```
sDmat(sMap, which_neigh = 1,
  distMeasure = c("median", "mean", "min", "max"))
```

### **Arguments**

sMap an object of class "sMap"

which\_neigh which neighbors in 2D output space are used for the calculation. By default, it

sets to "1" for direct neighbors, and "2" for neighbors within neighbors no more

than 2, and so on

distance measure used to calculate distances in high-dimensional input space

sDmatCluster 9

#### Value

• dMat: a vector with the length of nHex. It stores the distance a hexaon/rectangle is away from its output-space-defined neighbors in high-dimensional input space

#### Note

"which\_neigh" is defined in output 2D space, but "distMeasure" is defined in high-dimensional input space

#### See Also

```
sNeighAny
```

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)

# 2) get trained using by default setup
sMap <- sPipeline(data=data)

# 3) calculate "median" distances in INPUT space to different neighbors in 2D OUTPUT space
# 3a) using direct neighbors in 2D OUTPUT space
dMat <- sDmat(sMap=sMap, which_neigh=1, distMeasure="median")
# 3b) using no more than 2-topological neighbors in 2D OUTPUT space
# dMat <- sDmat(sMap=sMap, which_neigh=2, distMeasure="median")</pre>
```

sDmatCluster

Function to partition a grid map into clusters

#### **Description**

sDmatCluster is supposed to obtain clusters from a grid map. It returns an object of class "sBase".

### Usage

```
sDmatCluster(sMap, which_neigh = 1,
  distMeasure = c("median", "mean", "min", "max"),
  clusterLinkage = c("average", "complete", "single", "bmh"))
```

### **Arguments**

sMap an object of class "sMap"

which\_neigh which neighbors in 2D output space are used for the calculation. By default, it

sets to "1" for direct neighbors, and "2" for neighbors within neighbors no more

than 2, and so on

distMeasure distance measure used to calculate distances in high-dimensional input space. It

can be one of "median", "mean", "min" and "max" measures

clusterLinkage cluster linkage used to derive clusters. It can be "bmh", which accumulates a

cluster just based on best-matching hexagons/rectanges but can not ensure each cluster is continuous. Instead, each cluster is continuous when using region-growing algorithm with one of "average", "complete" and "single" linkages

10 sDmatMinima

#### Value

an object of class "sBase", a list with following components:

• seeds: the vector to store cluster seeds, i.e., a list of local minima (in 2D output space) of distance matrix (in input space). They are represented by the indexes of hexagons/rectangles

- bases: the vector with the length of nHex to store the cluster memberships/bases, where nHex is the total number of hexagons/rectanges in the grid
- call: the call that produced this result

#### Note

The first item in the return "seeds" is the first cluster, whose memberships are those in the return "bases" that equals 1. The same relationship is held for the second item, and so on

#### See Also

```
sPipeline, sDmatMinima, sBMH, sNeighDirect, sDistance, visDmatCluster
```

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)

# 2) get trained using by default setup
sMap <- sPipeline(data=data)

# 3) partition the grid map into clusters based on different criteria
# 3a) based on "bmh" criterion
# sBase <- sDmatCluster(sMap=sMap, which_neigh=1, distMeasure="median", clusterLinkage="bmh")
# 3b) using region-growing algorithm with linkage "average"
sBase <- sDmatCluster(sMap=sMap, which_neigh=1, distMeasure="median", clusterLinkage="average")
# 4) visualise clusters/bases partitioned from the sMap
visDmatCluster(sMap,sBase)</pre>
```

sDmatMinima

Function to identify local minima (in 2D output space) of distance matrix (in high-dimensional input space)

### Description

sDmatMinima is supposed to identify local minima of distance matrix (resulting from sDmat). The criterion of being local minima is that the distance associated with a hexagon/rectangle is always smaller than its direct neighbors (i.e., 1-neighborhood)

### Usage

```
sDmatMinima(sMap, which_neigh = 1,
  distMeasure = c("median", "mean", "min", "max"))
```

sHexDist 11

### Arguments

sMap an object of class "sMap"

which\_neigh which neighbors in 2D output space are used for the calculation. By default, it

sets to "1" for direct neighbors, and "2" for neighbors within neighbors no more

than 2, and so on

distMeasure distance measure used to calculate distances in high-dimensional input space. It

can be one of "median", "mean", "min" and "max" measures

#### Value

• minima: a vector to store a list of local minima (represented by the indexes of hexogans/rectangles

#### Note

Do not get confused by "which\_neigh" and the criteria of being local minima. Both of them deal with 2D output space. However, "which\_neigh" is used to assist in the calculation of distance matrix (so can be 1-neighborhood or more); instead, the criterion of being local minima is only 1-neighborhood in the strictest sense

#### See Also

```
sDmat, sNeighAny
```

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)
# 2) get trained using by default setup
sMap <- sPipeline(data=data)</pre>
```

# 3) identify local minima of distance matrix based on "median" distances and direct neighbors minima <- sDmatMinima(sMap=sMap, which\_neigh=1, distMeasure="median")

sHexDist Function to calculate distances between hexagons/rectangles in a 2D grid

#### **Description**

sHexDist is supposed to calculate euclidian distances between each pair of hexagons/rectangles in a 2D grid of input "sTopol" or "sMap" object. It returns a symmetric matrix containing pairwise distances.

#### Usage

```
sHexDist(sObj)
```

### **Arguments**

```
s0bj an object of class "sTopol" or "sInit" or "sMap"
```

12 sHexGrid

#### Value

• dist: a symmetric matrix of nHex x nHex, containing pairwise distances, where nHex is the total number of hexagons/rectanges in the grid

#### Note

The return matrix has rows/columns ordered in the same order as the "coord" matrix of the input object does.

#### See Also

```
sTopology, sInitial
```

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)

# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid
sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")

# 3) initialise the codebook matrix using "uniform" method
sI <- sInitial(data=data, sTopol=sTopol, init="uniform")

# 4) calculate distances between hexagons/rectangles in a 2D grid based on different objects
# 4a) based on an object of class "sTopol"
dist <- sHexDist(sObj=sTopol)
# 4b) based on an object of class "sMap"
dist <- sHexDist(sObj=sI)</pre>
```

sHexGrid

Function to define a supra-hexagonal grid

#### **Description**

sHexGrid is supposed to define a supra-hexagonal map grid. A supra-hexagon is a giant hexagon, which seamlessly consists of smaller hexagons. Due to the symmetric nature, it can be uniquely determined by specifying the radius away from the grid centroid. This function takes input the grid radius (or the number of hexagons in the grid, but will be adjusted to meet the definition of supra-hexagon), and returns a list (see 'Value' below) containing: the grid radius, the total number of hexagons in the grid, the 2D coordinates of the grid centroid, the step for each hexogan away from the grid centroid, and the 2D coordinates of all hexagons in the grid.

#### Usage

```
sHexGrid(r = NULL, nHex = NULL)
```

### Arguments

r an integer specifying the radius in a supra-hexagonal grid nHex the number of input hexagons in the grid

sHexGrid 13

#### Value

a list with following components:

- r: the grid radius
- nHex: the total number of hexagons in the grid. It may differ from the input value; actually it is always no less than the input one to ensure a supra-hexagonal grid exactly formed
- centroid: the 2D coordinates of the grid centroid
- stepCentroid: a vector with the length of nHex. It stores how many steps a hexagon is awawy from the grid centroid ('1' for the centroid itself). Starting with the centroid, it orders outward. Also, for those hexagons of the same step, it orders from the rightmost in an anti-clock wise
- coord: a matrix of nHex x 2 with each row specifying the 2D coordinates of a hexagon in the grid. The order of rows is the same as 'centroid' above
- call: the call that produced this result

#### Note

The relationships among return values:

- nHex = 1 + 6 \* r \* (r 1)/2
- centroid = coord[1, ]
- stepCentroid[1] = 1
- stepCentroid[2:nHex] = unlist(sapply(2:r,function(x)(c((1+6\*x\*(x-1)/2-6\*(x-1)+1):(1+6\*x\*(x-1)/2))>=1)\*x))

#### See Also

```
sTopology
```

```
# The supra-hexagonal grid is exactly determined by specifying the radius.
res <- sHexGrid(r=2)

# The grid is determined according to the number of input hexagons (after being adjusted).
# The return res$nHex is always no less than the input one.
# It ensures a supra-hexagonal grid is exactly formed.
res <- sHexGrid(nHex=12)

# Ignore input nHex if r is also given
res <- sHexGrid(r=3, nHex=100)

# By default, r=3 if no parameters are specified
res <- sHexGrid()</pre>
```

14 sInitial

sInitial

Function to initialise a sInit object given a topology and input data

#### **Description**

sInitial is supposed to initialise an object of class "sInit" given a topology and input data. As a matter of fact, it initialises the codebook matrix (in input high-dimensional space). The return object inherits the topology information (i.e., a "sTopol" object from sTopology), along with initialised codebook matrix and method used.

### Usage

```
sInitial(data, sTopol,
  init = c("linear", "uniform", "sample"))
```

#### **Arguments**

data a data frame or matrix of input data

sTopol an object of class "sTopol" (see sTopology)

init an initialisation method. It can be one of "uniform", "sample" and "linear" ini-

tialisation methods

#### Value

an object of class "sInit", a list with following components:

- nHex: the total number of hexagons/rectanges in the grid
- xdim: x-dimension of the grid
- ydim: y-dimension of the grid
- lattice: the grid lattice
- shape: the grid shape
- coord: a matrix of nHex x 2, with each row corresponding to the coordinates of a hexagon/rectangle in the 2D map grid
- · init: an initialisation method
- codebook: a codebook matrix of nHex x ncol(data), with each row corresponding to a prototype vector in input high-dimensional space
- call: the call that produced this result

### Note

The initialisation methods include:

- "uniform": the codebook matrix is uniformly initialised via randomly taking any values within the interval [min, max] of each column of input data
- "sample": the codebook matrix is initialised via randomly sampling/selecting input data
- "linear": the codebook matrix is linearly initialised along the first two greatest eigenvectors of input data

sMapOverlay 15

#### See Also

```
sTopology
```

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)

# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")

# 3) initialise the codebook matrix using different mehtods
# 3a) using "uniform" method
sI_uniform <- sInitial(data=data, sTopol=sTopol, init="uniform")
# 3b) using "sample" method
# sI_sample <- sInitial(data=data, sTopol=sTopol, init="sample")
# 3c) using "linear" method
# sI_linear <- sInitial(data=data, sTopol=sTopol, init="linear")</pre>
```

sMapOverlay

Function to overlay additional data onto the trained map for viewing the distribution of that additional data

#### **Description**

sMapOverlay is supposed to overlay additional data onto the trained map for viewing the distribution of that additional data. It returns an object of class "sMap". It is realised by first estimating the hit histogram weighted by the neighborhood kernel, and then calculating the distribution of the additional data over the map (similarly weighted by the neighborhood kernel). The final overlaid distribution of additional data is normalised by the hit histogram.

#### Usage

```
sMapOverlay(sMap, data, additional)
```

#### **Arguments**

sMap an object of class "sMap"

data a data frame or matrix of input data

additional a numeric vector or numeric matrix used to overlay onto the trained map. It

must have the length (if being vector) or row number (if matrix) being equal to

the number of rows in input data

#### Value

an object of class "sMap", a list with following components:

- nHex: the total number of hexagons/rectanges in the grid
- xdim: x-dimension of the grid
- ydim: y-dimension of the grid

16 sNeighAny

- lattice: the grid lattice
- · shape: the grid shape
- coord: a matrix of nHex x 2, with rows corresponding to the coordinates of all hexagons/rectangles in the 2D map grid
- init: an initialisation method
- neighKernel: the training neighborhood kernel
- codebook: a codebook matrix of nHex x ncol(additional), with rows corresponding to overlaid vectors
- hits: a vector of nHex, each element meaning that a hexagon/rectangle contains the number of input data vectors being hit wherein
- mge: the mean quantization error for the "best" BMH
- call: the call that produced this result

#### Note

Weighting by neighbor kernel is to avoid rigid overlaying by only focusing on the best-matching map nodes as there may exist several closest best-matching nodes for an input data vector.

#### See Also

```
sPipeline, sBMH, sHexDist, visHexMulComp
```

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)
colnames(data) <- paste(rep(S,10), seq(1:10), sep="")
# 2) get trained using by default setup
sMap <- sPipeline(data=data)
# 3) overlay additional data onto the trained map
# here using the first two columns of the input "data" as "additional"
# codebook in "sOverlay" is the same as the first two columns of codebook in "sMap"
sOverlay <- sMapOverlay(sMap=sMap, data=data, additional=data[,1:2])
# 4) viewing the distribution of that additional data
visHexMulComp(sOverlay)</pre>
```

sNeighAny

Function to calculate any neighbors for each hexagon/rectangle in a grid

#### **Description**

sNeighAny is supposed to calculate any neighbors for each hexagon/rectangle in a regular 2D grid. It returns a matrix with rows for the self, and columns for its any neighbors.

### Usage

```
sNeighAny(sObj)
```

sNeighDirect 17

#### **Arguments**

s0bj an object of class "sTopol" or "sInit" or "sMap"

#### Value

• aNeigh: a matrix of nHex x nHex, containing distance info in terms of any neighbors, where nHex is the total number of hexagons/rectanges in the grid

#### Note

The return matrix has rows for the self, and columns for its neighbors. The non-zeros mean the distance away from its neighbors, and the zeros for the self-self. It has rows/columns ordered in the same order as the "coord" matrix of the input object does.

#### See Also

sNeighDirect

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)

# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid
sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")

# 3) initialise the codebook matrix using "uniform" method
sI <- sInitial(data=data, sTopol=sTopol, init="uniform")

# 4) calculate any neighbors based on different objects
# 4a) based on an object of class "sTopol"
aNeigh <- sNeighAny(sObj=sTopol)
# 4b) based on an object of class "sMap"
# aNeigh <- sNeighAny(sObj=sI)</pre>
```

sNeighDirect

Function to calculate direct neighbors for each hexagon/rectangle in a grid

### **Description**

sNeighDirect is supposed to calculate direct neighbors for each hexagon/rectangle in a regular 2D grid. It returns a matrix with rows for the self, and columns for its direct neighbors.

### Usage

```
sNeighDirect(sObj)
```

### **Arguments**

```
s0bj an object of class "sTopol" or "sInit" or "sMap"
```

sPipeline

#### Value

• dNeigh: a matrix of nHex x nHex, containing presence/absence info in terms of direct neighbors, where nHex is the total number of hexagons/rectanges in the grid

#### Note

The return matrix has rows for the self, and columns for its direct neighbors. The "1" means the presence of direct neighbors, "0" for the absence. It has rows/columns ordered in the same order as the "coord" matrix of the input object does.

#### See Also

sHexDist

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)

# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid
sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")

# 3) initialise the codebook matrix using "uniform" method
sI <- sInitial(data=data, sTopol=sTopol, init="uniform")

# 4) calculate direct neighbors based on different objects
# 4a) based on an object of class "sTopol"
dNeigh <- sNeighDirect(sObj=sTopol)
# 4b) based on an object of class "sMap"
# dNeigh <- sNeighDirect(sObj=sI)</pre>
```

sPipeline

Function to setup the pipeline for completing ab initio training given the input data

### Description

sPipeline is supposed to finish ab inito training for the input data. It returns an object of class "sMap".

#### Usage

```
sPipeline(data = NULL, xdim = NULL, ydim = NULL,
   nHex = NULL, lattice = c("hexa", "rect"),
   shape = c("suprahex", "sheet"),
   init = c("linear", "uniform", "sample"),
   algorithm = c("batch", "sequential"),
   alphaType = c("invert", "linear", "power"),
   neighKernel = c("gaussian", "bubble", "cutgaussian", "ep", "gamma"),
   finetuneSustain = F, verbose = T)
```

sPipeline 19

### **Arguments**

data	a data frame or matrix of input data	
xdim	an integer specifying x-dimension of the grid	
ydim	an integer specifying y-dimension of the grid	
nHex	the number of hexagons/rectangles in the grid	
lattice	the grid lattice, either "hexa" for a hexagon or "rect" for a rectangle	
shape	the grid shape, either "suprahex" for a supra-hexagonal grid or "sheet" for a hexagonal/rectangle sheet	
init	an initialisation method. It can be one of "uniform", "sample" and "linear" initialisation methods	
algorithm	the training algorithm. It can be one of "sequential" and "batch" algorithm	
alphaType	the alpha type. It can be one of "invert", "linear" and "power" alpha types	
neighKernel	the training neighborhood kernel. It can be one of "gaussian", "bubble", "cut-gaussian", "ep" and "gamma" kernels	
finetuneSustain		
	logical to indicate whether sustain the "finetune" training. If true, it will repeat the "finetune" stage until the mean quantization error does get worse. By default, it sets to true	
verbose	logical to indicate whether the messages will be displayed in the screen. By default, it sets to false for no display	

### Value

an object of class "sMap", a list with following components:

- nHex: the total number of hexagons/rectanges in the grid
- xdim: x-dimension of the grid
- ydim: y-dimension of the grid
- lattice: the grid lattice
- shape: the grid shape
- coord: a matrix of nHex x 2, with rows corresponding to the coordinates of all hexagons/rectangles in the 2D map grid
- init: an initialisation method
- neighKernel: the training neighborhood kernel
- codebook: a codebook matrix of nHex x ncol(data), with rows corresponding to prototype vectors in input high-dimensional space
- hits: a vector of nHex, each element meaning that a hexagon/rectangle contains the number of input data vectors being hit wherein
- mqe: the mean quantization error for the "best" BMH
- call: the call that produced this result

20 sPipeline

#### Note

The pipeline sequentially consists of:

• i) sTopology used to define the topology of a grid (with "suprahex" shape by default ) according to the input data;

- ii) sInitial used to initialise the codebook matrix given the pre-defined topology and the input data (by default using "uniform" initialisation method);
- iii) sTrainology and sTrainSeq used to get the grid map trained at both "rough" and "fine-tune" stages. If instructed, sustain the "finetune" training until the mean quantization error does get worse;
- iv) sBMH used to identify the best-matching hexagons/rectangles (BMH) for the input data, and these response data are appended to the resulting object of "sMap" class.

#### Author(s)

Hai Fang <hfang@cs.bris.ac.uk>

#### References

Hai Fang and Julian Gough. (2014) supraHex: an R/Bioconductor package for tabular omics data analysis using a supra-hexagonal map. *Biochemical and Biophysical Research Communications*, 443(1), 285-289. DOI: http://dx.doi.org/10.1016/j.bbrc.2013.11.103, PMID: http://www.ncbi.nlm.nih.gov/pubmed/?term=24309102

#### See Also

sTopology, sInitial, sTrainology, sTrainSeq, sTrainBatch, sBMH, visHexMulComp

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10, mean=0, sd=1), nrow=100, ncol=10)</pre>
colnames(data) <- paste(rep(S,10), seq(1:10), sep="")</pre>
# 2) get trained using by default setup but with different neighborhood kernels
# 2a) with "gaussian" kernel
sMap <- sPipeline(data=data, neighKernel="gaussian")</pre>
# 2b) with "bubble" kernel
# sMap <- sPipeline(data=data, neighKernel="bubble")</pre>
# 2c) with "cutgaussian" kernel
# sMap <- sPipeline(data=data, neighKernel="cutgaussian")</pre>
# 2d) with "ep" kernel
# sMap <- sPipeline(data=data, neighKernel="ep")</pre>
# 2e) with "gamma" kernel
# sMap <- sPipeline(data=data, neighKernel="gamma")</pre>
# 3) visualise multiple component planes of a supra-hexagonal grid
visHexMulComp(sMap, colormap="jet", ncolors=20, zlim=c(-1,1), gp=grid::gpar(cex=0.8))
```

sTopology 21

sTopology	Function to define the topology of a map grid	

#### **Description**

sTopology is supposed to define the topology of a 2D map grid. The topological shape can be either a supra-hexagonal grid or a hexagonal/rectangle sheet. It returns an object of "sTopol" class, containing: the total number of hexagons/rectangles in the grid, the grid xy-dimensions, the grid lattice, the grid shape, and the 2D coordinates of all hexagons/rectangles in the grid. The 2D coordinates can be directly used to measure distances between any pair of lattice hexagons/rectangles.

#### Usage

```
sTopology(data = NULL, xdim = NULL, ydim = NULL,
    nHex = NULL, lattice = c("hexa", "rect"),
    shape = c("suprahex", "sheet"))
```

### **Arguments**

data	a data frame or matrix of input data
xdim	an integer specifying x-dimension of the grid
ydim	an integer specifying y-dimension of the grid
nHex	the number of hexagons/rectangles in the grid
lattice	the grid lattice, either "hexa" for a hexagon or "rect" for a rectangle
shape	the grid shape, either "suprahex" for a supra-hexagonal grid or "sheet" for a hexagonal/rectangle sheet

### Value

an object of class "sTopol", a list with following components:

- nHex: the total number of hexagons/rectanges in the grid. It is not always the same as the input nHex (if any); see "Note" below for the explaination
- xdim: x-dimension of the grid
- ydim: y-dimension of the grid
- lattice: the grid lattice
- shape: the grid shape
- coord: a matrix of nHex x 2, with each row corresponding to the coordinates of a hexagon/rectangle in the 2D map grid
- call: the call that produced this result

#### Note

The output of nHex depends on the input arguments and grid shape:

- How the input parameters are used to determine nHex is taken priority in the following order: "xdim & ydim" > "nHex" > "data"
- If both of xdim and ydim are given, nHex = xdim \* ydim for the "sheet" shape, r = (min(xdim, ydim) + 1)/2 for the "suprahex" shape

22 sTrainBatch

• If only data is input, nHex = 5 \* sqrt(dlen), where dlen is the number of rows of the input data

- With nHex in hand, it depends on the grid shape:
  - For "sheet" shape, xy-dimensions of sheet grid is determined according to the square root
    of the two biggest eigenvalues of the input data
  - For "suprahex" shape, see sHexGrid for calculating the grid radius r. The xdim (and ydim) is related to r via xdim = 2 \* r 1

#### See Also

```
sHexGrid, visHexMapping
```

### **Examples**

```
# For "suprahex" shape
sTopol <- sTopology(xdim=3, ydim=3, lattice="hexa", shape="suprahex")</pre>
# Error: "The suprahex shape grid only allows for hexagonal lattice"
# sTopol <- sTopology(xdim=3, ydim=3, lattice="rect", shape="suprahex")</pre>
# For "sheet" shape with hexagonal lattice
sTopol <- sTopology(xdim=3, ydim=3, lattice="hexa", shape="sheet")</pre>
# For "sheet" shape with rectangle lattice
sTopol <- sTopology(xdim=3, ydim=3, lattice="rect", shape="sheet")</pre>
# By default, nHex=19 (i.e., r=3; xdim=ydim=5) for "suprahex" shape
sTopol <- sTopology(shape="suprahex")</pre>
# By default, xdim=ydim=5 (i.e., nHex=25) for "sheet" shape
sTopol <- sTopology(shape="sheet")</pre>
# Determine the topolopy of a supra-hexagonal grid based on input data
# 1) generate an iid normal random matrix of 100x10
data <- matrix(rnorm(100*10, mean=0, sd=1), nrow=100, ncol=10)</pre>
# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid
sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")</pre>
# visualise a supre-hexagonal grid
visHexMapping(sTopol,mappingType="indexes")
```

sTrainBatch

Function to implement training via batch algorithm

#### **Description**

sTrainBatch is supposed to perform batch training algorithm. It requires three inputs: a "sMap" or "sInit" object, input data, and a "sTrain" object specifying training environment. The training is implemented iteratively, but instead of choosing a single input vector, the whole input matrix is used. In each training cycle, the whole input matrix first land in the map through identifying the corresponding winner hexagon/rectangle (BMH), and then the codebook matrix is updated via updating formula (see "Note" below for details). It returns an object of class "sMap".

sTrainBatch 23

#### Usage

sTrainBatch(sMap, data, sTrain)

#### **Arguments**

sMap an object of class "sMap" or "sInit"
data a data frame or matrix of input data
sTrain an object of class "sTrain"

#### Value

an object of class "sMap", a list with following components:

- nHex: the total number of hexagons/rectanges in the grid
- xdim: x-dimension of the grid
- ydim: y-dimension of the grid
- lattice: the grid lattice
- shape: the grid shape
- coord: a matrix of nHex x 2, with each row corresponding to the coordinates of a hexagon/rectangle in the 2D map grid
- init: an initialisation method
- neighKernel: the training neighborhood kernel
- codebook: a codebook matrix of nHex x ncol(data), with each row corresponding to a prototype vector in input high-dimensional space
- call: the call that produced this result

### Note

Updating formula is: 
$$m_i(t+1) = \frac{\sum_{j=1}^{dlen} h_{wi}(t)x_j}{\sum_{j=1}^{dlen} h_{wi}(t)}$$
, where

- t denotes the training time/step
- $x_i$  is an input vector j from the input data matrix (with dlen rows in total)
- i and w stand for the hexagon/rectangle i and the winner BMH w, respectively
- $m_i(t+1)$  is the prototype vector of the hexagon i at time t+1
- $h_{wi}(t)$  is the neighborhood kernel, a non-increasing function of i) the distance  $d_{wi}$  between the hexagon/rectangle i and the winner BMH w, and ii) the radius  $\delta_t$  at time t. There are five kernels available:
  - For "gaussian" kernel,  $h_{wi}(t) = e^{-d_{wi}^2/(2*\delta_t^2)}$
  - For "cutguassian" kernel,  $h_{wi}(t) = e^{-d_{wi}^2/(2*\delta_t^2)} * (d_{wi} \le \delta_t)$
  - For "bubble" kernel,  $h_{wi}(t) = (d_{wi} \leq \delta_t)$
  - For "ep" kernel,  $h_{wi}(t) = (1 d_{wi}^2/\delta_t^2) * (d_{wi} \le \delta_t)$
  - For "gamma" kernel,  $h_{wi}(t) = 1/\Gamma(d_{wi}^2/(4*\delta_t^2) + 2)$

#### See Also

sTrainology, visKernels

24 sTrainology

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10, mean=0, sd=1), nrow=100, ncol=10)

# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")

# 3) initialise the codebook matrix using "uniform" method sI <- sInitial(data=data, sTopol=sTopol, init="uniform")

# 4) define trainology at "rough" stage sT_rough <- sTrainology(sMap=sI, data=data, stage="rough")

# 5) training at "rough" stage sM_rough <- sTrainBatch(sMap=sI, data=data, sTrain=sT_rough)

# 6) define trainology at "finetune" stage sT_finetune <- sTrainology(sMap=sI, data=data, stage="finetune")

# 7) training at "finetune" stage sM_finetune <- sTrainBatch(sMap=sM_rough, data=data, sTrain=sT_rough)</pre>
```

sTrainology

Function to define trainology (training environment)

### Description

sTrainology is supposed to define the train-ology (i.e., the training environment/parameters). The trainology here refers to the training algorithm, the training stage, the stage-specific parameters (alpha type, initial alpha, initial radius, final radius and train length), and the training neighbor kernel used. It returns an object of class "sTrain".

#### Usage

```
sTrainology(sMap, data,
  algorithm = c("batch", "sequential"),
  stage = c("rough", "finetune", "complete"),
  alphaType = c("invert", "linear", "power"),
  neighKernel = c("gaussian", "bubble", "cutgaussian", "ep", "gamma"))
```

### Arguments

an object of class "sMap" or "sInit"

data
a data frame or matrix of input data
algorithm
the training algorithm. It can be one of "sequential" and "batch" algorithm
stage
the training stage. The training can be achieved using two stages (i.e., "rough" and "finetune") or one stage only (i.e., "complete")

alphaType
the alpha type. It can be one of "invert", "linear" and "power" alpha types
neighKernel
the training neighbor kernel. It can be one of "gaussian", "bubble", "cutgaussian", "ep" and "gamma" kernels

sTrainology 25

#### Value

an object of class "sTrain", a list with following components:

• algorithm: the training algorithm

• stage: the training stage

• alphaType: the alpha type

• alphaInitial: the initial alpha

• radiusInitial: the initial radius

• radiusFinal: the final radius

• neighKernel: the neighbor kernel

• call: the call that produced this result

#### Note

Training stage-specific parameters:

- "radiusInitial": it depends on the grid shape and training stage
  - For "sheet" shape: it equals max(1, ceiling(max(xdim, ydim)/8)) at "rough" or "complete" stage, and max(1, ceiling(max(xdim, ydim)/32)) at "finetune" stage
  - For "suprahex" shape: it equals max(1, ceiling(r/2)) at "rough" or "complete" stage, and max(1, ceiling(r/8)) at "finetune" stage
- "radiusFinal": it depends on the training stage
  - At "rough" stage, it equals radiusInitial/4
  - At "finetune" or "complete" stage, it equals 1
- "trainLength": how many times the whole input data are set for training. It depends on the training stage and training algorithm
  - At "rough" stage, it equals max(1, 10 \* trainDepth)
  - At "finetune" stage, it equals max(1, 40 \* trainDepth)
  - At "complete" stage, it equals max(1, 50 \* trainDepth)
  - When using "batch" algorithm and the trainLength equals 1 according to the above equation, the trainLength is forced to be 2 unless radiusInitial equals radiusFinal
  - Where trainDepth is the training depth, defined as nHex/dlen, i.e., how many hexagons/rectanges are used per the input data length (here dlen refers to the number of rows)

#### See Also

sInitial

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)
# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")
# 3) initialise the codebook matrix using "uniform" method
sI <- sInitial(data=data, sTopol=sTopol, init="uniform")</pre>
```

26 sTrainSeq

```
# 4) define trainology at different stages
# 4a) define trainology at "rough" stage
sT_rough <- sTrainology(sMap=sI, data=data, stage="rough")
# 4b) define trainology at "finetune" stage
sT_finetune <- sTrainology(sMap=sI, data=data, stage="finetune")
# 4c) define trainology using "complete" stage
sT_complete <- sTrainology(sMap=sI, data=data, stage="complete")</pre>
```

sTrainSeq

Function to implement training via sequential algorithm

### Description

sTrainSeq is supposed to perform sequential training algorithm. It requires three inputs: a "sMap" or "sInit" object, input data, and a "sTrain" object specifying training environment. The training is implemented iteratively, each training cycle consisting of: i) randomly choose one input vector; ii) determine the winner hexagon/rectangle (BMH) according to minimum distance of codebook matrix to the input vector; ii) update the codebook matrix of the BMH and its neighbors via updating formula (see "Note" below for details). It also returns an object of class "sMap".

#### Usage

```
sTrainSeq(sMap, data, sTrain)
```

#### **Arguments**

sMap an object of class "sMap" or "sInit"
data a data frame or matrix of input data
sTrain an object of class "sTrain"

#### Value

an object of class "sMap", a list with following components:

- nHex: the total number of hexagons/rectanges in the grid
- xdim: x-dimension of the grid
- ydim: y-dimension of the grid
- lattice: the grid lattice
- shape: the grid shape
- coord: a matrix of nHex x 2, with each row corresponding to the coordinates of a hexagon/rectangle in the 2D map grid
- init: an initialisation method
- neighKernel: the training neighborhood kernel
- codebook: a codebook matrix of nHex x ncol(data), with each row corresponding to a prototype vector in input high-dimensional space
- call: the call that produced this result

sTrainSeq 27

#### Note

Updating formula is:  $m_i(t+1) = m_i(t) + \alpha(t) * h_{wi}(t) * [x(t) - m_i(t)]$ , where

- t denotes the training time/step
- i and w stand for the hexagon/rectangle i and the winner BMH w, respectively
- x(t) is an input vector randomly choosen (from the input data) at time t
- $m_i(t)$  and  $m_i(t+1)$  are respectively the prototype vectors of the hexagon i at time t and t+1
- $\alpha(t)$  is the learning rate at time t. There are three types of learning rate functions:
  - For "linear" function,  $\alpha(t) = \alpha_0 * (1 t/T)$
  - For "power" function,  $\alpha(t) = \alpha_0 * (0.005/\alpha_0)^{t/T}$
  - For "invert" function,  $\alpha(t) = \alpha_0/(1+100*t/T)$
  - Where  $\alpha_0$  is the initial learing rate (typically,  $\alpha_0=0.5$  at "rough" stage,  $\alpha_0=0.05$  at "finetune" stage), T is the length of training time/step (often being set to input data length, i.e., the total number of rows)
- $h_{wi}(t)$  is the neighborhood kernel, a non-increasing function of i) the distance  $d_{wi}$  between the hexagon/rectangle i and the winner BMH w, and ii) the radius  $\delta_t$  at time t. There are five kernels available:
  - For "gaussian" kernel,  $h_{wi}(t) = e^{-d_{wi}^2/(2*\delta_t^2)}$
  - For "cutguassian" kernel,  $h_{wi}(t) = e^{-d_{wi}^2/(2*\delta_t^2)} * (d_{wi} \le \delta_t)$
  - For "bubble" kernel,  $h_{wi}(t) = (d_{wi} \le \delta_t)$
  - For "ep" kernel,  $h_{wi}(t) = (1 d_{wi}^2/\delta_t^2) * (d_{wi} \le \delta_t)$
  - For "gamma" kernel,  $h_{wi}(t) = 1/\Gamma(d_{wi}^2/(4*\delta_t^2) + 2)$

#### See Also

```
sTrainology, visKernels
```

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)

# 2) from this input matrix, determine nHex=5*sqrt(nrow(data))=50,
# but it returns nHex=61, via "sHexGrid(nHex=50)", to make sure a supra-hexagonal grid
sTopol <- sTopology(data=data, lattice="hexa", shape="suprahex")

# 3) initialise the codebook matrix using "uniform" method
sI <- sInitial(data=data, sTopol=sTopol, init="uniform")

# 4) define trainology at "rough" stage
sT_rough <- sTrainology(sMap=sI, data=data, algorithm="sequential", stage="rough")

# 5) training at "rough" stage
sM_rough <- sTrainSeq(sMap=sI, data=data, sTrain=sT_rough)

# 6) define trainology at "finetune" stage
sT_finetune <- sTrainology(sMap=sI, data=data, algorithm="sequential", stage="finetune")

# 7) training at "finetune" stage
sM_finetune <- sTrainSeq(sMap=sM_rough, data=data, sTrain=sT_rough)</pre>
```

28 sWriteData

sWriteData	Function to write out the best-matching hexagons and/or cluster bases in terms of data

### **Description**

sWriteData is supposed to write out the best-matching hexagons and/or cluster bases in terms of data.

### Usage

```
sWriteData(sMap, data, sBase = NULL, filename = NULL,
keep.data = F)
```

#### **Arguments**

sMap an object of class "sMap" or a codebook matrix

data a data frame or matrix of input data

sBase an object of class "sBase"

filename a character string naming a filename

keep.data logical to indicate whether or not to also write out the input data. By default, it

sets to false for not keeping it. It is highly expensive to keep the large data sets

#### Value

a data frame with following components:

- ID: ID for data. It inherits the rownames of data (if exists). Otherwise, it is sequential integer values starting with 1 and ending with dlen, the total number of rows of the input data
- Hexagon\_index: the index for best-matching hexagons
- Cluster\_base: optional, it is only appended when sBase is given. It stores the cluster memberships/bases
- data: optional, it is only appended when keep.data is true

#### Note

If "filename" is not NULL, a tab-delimited text file will be also written out. If "sBase" is not NULL and comes from the "sMap" partition, then cluster bases are also appended. if "keep.data" is true, the data will be part of output.

### See Also

sBMH

visColoralpha 29

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)

# 2) get trained using by default setup
sMap <- sPipeline(data=data)

# 3) write datas BMH hitting the trained map
output <- sWriteData(sMap=sMap, data=data, filename="sData_output.txt")

# 4) partition the grid map into cluster bases
sBase <- sDmatCluster(sMap=sMap, which_neigh=1,
distMeasure="median", clusterLinkage="average")

# 5) write datas BMH and cluster bases
output <- sWriteData(sMap=sMap, data=data, sBase=sBase, filename="sData_base_output.txt")</pre>
```

visColoralpha

Function to add transparent (alpha) into colors

#### **Description**

visColoralpha is supposed to add transparent (alpha) into colors.

### Usage

```
visColoralpha(col, alpha)
```

### **Arguments**

col input colors. It can be vector of R color specifications, such as a color name (as

listed by 'colors()), a hexadecimal string of the form "#rrggbb" or "#rrggbbaa"

alpha numeric vector of values in the range [0, 1] for alpha transparency channel (0

means transparent and 1 means opaque)

### Value

a vector of colors (after transparent being added)

### Note

none

#### See Also

```
visColormap
```

30 visColorbar

#### **Examples**

```
# 1) define "blue-white-red" colormap
palette.name <- visColormap(colormap="bwr")
# 2) use the return function "palette.name" to generate 10 colors spanning "bwr"
col <- palette.name(10)
# 3) add transparent (alpha=0.5)
cols <- visColoralpha(col, alpha=0.5)</pre>
```

visColorbar

Function to define a colorbar

#### **Description**

visColorbar is supposed to define a colorbar

#### Usage

```
visColorbar(colormap = c("bwr", "jet", "gbr", "wyr", "br", "yr", "rainbow", "wb"),
ncolors = 40, zlim = c(0, 1), gp = grid::gpar())
```

### **Arguments**

colormap

short name for the colormap. It can be one of "jet" (jet colormap), "bwr" (blue-white-red colormap), "gbr" (green-black-red colormap), "wyr" (white-yellow-red colormap), "br" (black-red colormap), "yr" (yellow-red colormap), "wb" (white-black colormap), and "rainbow" (rainbow colormap, that is, red-yellow-green-cyan-blue-magenta). Alternatively, any hyphen-separated HTML color names, e.g. "blue-black-yellow", "royalblue-white-sandybrown", "darkgreen-white-darkviolet". A list of standard color names can be found in http://html-color-codes.info/color-names

ncolors

the number of colors specified

zlim

the minimum and maximum z values for which colors should be plotted, defaulting to the range of the finite values of z. Each of the given colors will be used to color an equispaced interval of this range. The midpoints of the intervals cover the range, so that values just outside the range will be plotted

gp

an object of class gpar, typically the output from a call to the function gpar (i.e., a list of graphical parameter settings)

### Value

invisibly

#### Note

none

### See Also

visColormap, visHexMulComp, visCompReorder

visColormap 31

#### **Examples**

```
# draw "blue-white-red" colorbar
visColorbar(colormap="bwr")
```

visColormap

Function to define a colormap

### **Description**

visColormap is supposed to define a colormap. It returns a function, which will take an integer argument specifying how many colors interpolate the given colormap.

### Usage

```
visColormap(colormap = c("bwr", "jet", "gbr", "wyr", "br", "yr", "rainbow", "wb"))
```

#### **Arguments**

colormap

short name for the colormap

#### Value

• palette.name: a function that takes an integer argument for generating that number of colors interpolating the given sequence

#### Note

The input colormap includes:

- "jet": jet colormap
- "bwr": blue-white-red
- "gbr": green-black-red
- "wyr": white-yellow-red
- "br": black-red
- "yr": yellow-red
- "wb": white-black
- "rainbow": rainbow colormap, that is, red-yellow-green-cyan-blue-magenta
- Alternatively, any hyphen-separated HTML color names, e.g. "blue-black-yellow", "royalblue-white-sandybrown", "darkblue-lightblue-lightyellow-darkorange", "darkgreen-white-darkviolet", "darkgreen-lightgreen-lightpink-darkred". A list of standard color names can be found in http://html-color-codes.info/color-names

#### See Also

 ${\tt visHexComp}$ 

32 visCompReorder

#### **Examples**

```
# 1) define "blue-white-red" colormap
palette.name <- visColormap(colormap="bwr")
# 2) use the return function "palette.name" to generate 10 colors spanning "bwr"
palette.name(10)</pre>
```

visCompReorder

Function to visualise multiple component planes reorded within a sheet-shape rectangle grid

#### **Description**

visCompReorder is supposed to visualise multiple component planes reorded within a sheet-shape rectangle grid

### Usage

```
visCompReorder(sMap, sReorder, margin = rep(0.1, 4),
height = 7, title.rotate = 0, title.xy = c(0.45, 1),
colormap = c("bwr", "jet", "gbr", "wyr", "br", "yr", "rainbow", "wb"),
ncolors = 40, zlim = NULL,
border.color = "transparent", gp = grid::gpar())
```

### **Arguments**

sMap an object of class "sMap"

sReorder an object of class "sReorder"

margin margins as units of length 4 or 1

height a numeric value specifying the height of device

title.rotate the rotation of the title title.xy the coordinates of the title

colormap short name for the colormap. It can be one of "jet" (jet colormap), "bwr" (blue-

white-red colormap), "gbr" (green-black-red colormap), "wyr" (white-yellow-red colormap), "br" (black-red colormap), "yr" (yellow-red colormap), "wb" (white-black colormap), and "rainbow" (rainbow colormap, that is, red-yellow-green-cyan-blue-magenta). Alternatively, any hyphen-separated HTML color names, e.g. "blue-black-yellow", "royalblue-white-sandybrown", "darkgreen-white-darkviolet". A list of standard color names can be found in http://

html-color-codes.info/color-names

ncolors the number of colors specified

zlim the minimum and maximum z values for which colors should be plotted, de-

faulting to the range of the finite values of z. Each of the given colors will be used to color an equispaced interval of this range. The midpoints of the intervals

cover the range, so that values just outside the range will be plotted

border.color the border color for each hexagon

gp an object of class "gpar". It is the output from a call to the function "gpar" (i.e.,

a list of graphical parameter settings)

visDmatCluster 33

#### Value

invisible

#### Note

none

#### See Also

visVp, visHexComp, visColorbar, sCompReorder

### **Examples**

```
# 1) generate data with three different distributions, each with an iid normal random matrix of 1000 x 3
data <- cbind(matrix(rnorm(1000*3,mean=0,sd=1), nrow=1000, ncol=3),
matrix(rnorm(1000*3,mean=0.5,sd=1), nrow=1000, ncol=3),
matrix(rnorm(1000*3,mean=-0.5,sd=1), nrow=1000, ncol=3))
colnames(data) <- c("S1", "S1", "S2", "S2", "S2", "S3", "S3", "S3")

# 2) sMap resulted from using by default setup
sMap <- sPipeline(data=data)

# 3) reorder component planes
sReorder <- sCompReorder(sMap=sMap, amplifier=2, metric="none")

# 4) visualise multiple component planes reorded within a sheet-shape rectangle grid
visCompReorder(sMap=sMap, sReorder=sReorder, margin=rep(0.1,4), height=7,
title.rotate=0, title.xy=c(0.45, 1), colormap="gbr", ncolors=10, zlim=c(-1,1),
border.color="transparent")</pre>
```

visDmatCluster

Function to visualise clusters/bases partitioned from a suprahexagonal grid

### **Description**

visDmatCluster is supposed to visualise clusters/bases partitioned from a supra-hexagonal grid

### Usage

```
visDmatCluster(sMap, sBase, height = 7,
  margin = rep(0.1, 4), area.size = 1,
  gp = grid::gpar(cex = 0.8, font = 2, col.label = "black"),
  border.color = "transparent",
  colormap = c("rainbow", "jet", "bwr", "gbr", "wyr", "br", "yr", "wb"),
  clip = c("on", "inherit", "off"), newpage = T)
```

34 visDmatCluster

#### **Arguments**

sMap an object of class "sMap" sBase an object of class "sBase"

height a numeric value specifying the height of device

margin margins as units of length 4 or 1

area.size an inteter or a vector specifying the area size of each hexagon

gp an object of class "gpar". It is the output from a call to the function "gpar" (i.e.,

a list of graphical parameter settings)

border.color the border color for each hexagon

colormap short name for the colormap. It can be one of "jet" (jet colormap), "bwr" (blue-

white-red colormap), "gbr" (green-black-red colormap), "wyr" (white-yellow-red colormap), "br" (black-red colormap), "yr" (yellow-red colormap), "wb" (white-black colormap), and "rainbow" (rainbow colormap, that is, red-yellow-green-cyan-blue-magenta). Alternatively, any hyphen-separated HTML color names, e.g. "blue-black-yellow", "royalblue-white-sandybrown", "darkgreen-white-darkviolet". A list of standard color names can be found in http://

html-color-codes.info/color-names

clip either "on" for clipping to the extent of this viewport, "inherit" for inheriting the

clipping region from the parent viewport, or "off" to turn clipping off altogether

newpage logical to indicate whether to open a new page. By default, it sets to true for

opening a new page

### Value

invisible

#### Note

none

### See Also

```
sDmatCluster, visColormap, visHexGrid
```

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10, mean=0, sd=1), nrow=100, ncol=10)
# 2) get trained using by default setup
sMap <- sPipeline(data=data)
# 3) partition the grid map into clusters using region-growing algorithm
sBase <- sDmatCluster(sMap=sMap, which_neigh=1,
distMeasure="median", clusterLinkage="average")
# 4) visualise clusters/bases partitioned from the sMap
visDmatCluster(sMap,sBase)</pre>
```

visHexComp 35

			_	
V٦	SH	ŀΡΥ	Cor	ทท

Function to visualise a component plane of a supra-hexagonal grid

#### **Description**

visHexComp is supposed to visualise a supra-hexagonal grid in the context of viewport

#### Usage

```
visHexComp(sMap, comp, margin = rep(0.6, 4),
    area.size = 1,
    colormap = c("bwr", "jet", "gbr", "wyr", "br", "yr", "rainbow", "wb"),
    ncolors = 40, zlim = c(0, 1),
    border.color = "transparent", newpage = T)
```

#### **Arguments**

sMap an object of class "sMap"

comp a component/column of codebook matrix from an object "sMap"

margin margins as units of length 4 or 1

area.size an inteter or a vector specifying the area size of each hexagon

colormap short name for the colormap. It can be one of "jet" (jet colormap), "bwr" (blue-

white-red colormap), "gbr" (green-black-red colormap), "wyr" (white-yellow-red colormap), "br" (black-red colormap), "yr" (yellow-red colormap), "wb" (white-black colormap), and "rainbow" (rainbow colormap, that is, red-yellow-green-cyan-blue-magenta). Alternatively, any hyphen-separated HTML color names, e.g. "blue-black-yellow", "royalblue-white-sandybrown", "darkgreen-white-darkviolet". A list of standard color names can be found in http://

html-color-codes.info/color-names

ncolors the number of colors specified

zlim the minimum and maximum z values for which colors should be plotted, de-

faulting to the range of the finite values of z. Each of the given colors will be used to color an equispaced interval of this range. The midpoints of the intervals

cover the range, so that values just outside the range will be plotted

border.color the border color for each hexagon

newpage a logical to indicate whether or not to open a new page

#### Value

invisible

#### Note

none

#### See Also

```
visColormap, visHexGrid
```

36 visHexGrid

#### **Examples**

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)
colnames(data) <- paste(rep(S,10), seq(1:10), sep="")
# 2) sMap resulted from using by default setup
sMap <- sPipeline(data=data)
# 3) visualise the first component plane with a supra-hexagonal grid
visHexComp(sMap, comp=sMap$codebook[,1], colormap="jet", ncolors=100, zlim=c(-1,1))</pre>
```

visHexGrid

Function to visualise a supra-hexagonal grid

### **Description**

visHexGrid is supposed to visualise a supra-hexagonal grid

### Usage

```
visHexGrid(hbin, area.size = 1, border.color = NULL,
  fill.color = NULL)
```

#### **Arguments**

hbin an object of class "hexbin"

area.size an inteter or a vector specifying the area size of each hexagon

border.color the border color for each hexagon fill.color the filled color for each hexagon

### Value

invisible

### Note

none

#### See Also

visHexComp

```
# 1) generate an iid normal random matrix of 100x10
data <- matrix( rnorm(100*10,mean=0,sd=1), nrow=100, ncol=10)
colnames(data) <- paste(rep(S,10), seq(1:10), sep="")
# 2) sMap resulted from using by default setup
sMap <- sPipeline(data=data)
# 3) create an object of "hexbin" class from sMap</pre>
```

visHexMapping 37

```
dat <- data.frame(sMap$coord)</pre>
xdim <- sMap$xdim</pre>
ydim <- sMap$ydim
hbin <- hexbin::hexbin(dat$x, dat$y, xbins=xdim-1, shape=sqrt(0.75)*ydim/xdim)
# 4) visualise hbin object
vp <- hexbin::hexViewport(hbin)</pre>
visHexGrid(hbin)
```

visHexMapping

Function to visualise various mapping items within a supra-hexagonal

grid

#### **Description**

visHexMapping is supposed to visualise various mapping items within a supra-hexagonal grid

### Usage

```
visHexMapping(s0bj,
 mappingType = c("indexes", "hits", "dist", "antidist", "bases", "customized"),
 labels = NULL, height = 7, margin = rep(0.1, 4),
 area.size = 1,
 gp = grid::gpar(cex = 0.7, font = 1, col.label = "black"),
 border.color = "black", fill.color = "transparent",
 clip = c("on", "inherit", "off"), newpage = T)
```

#### **Arguments**

s0bj an object of class "sMap" or "sInit" or "sTopol" the mapping type, can be "indexes", "hits", "dist", "antidist", "bases", and "cusmappingTypetomized" labels NULL or a vector with the length of nHex height a numeric value specifying the height of device margin margins as units of length 4 or 1 an inteter or a vector specifying the area size of each hexagon area.size an object of class "gpar". It is the output from a call to the function "gpar" (i.e., gp a list of graphical parameter settings) border.color the border color for each hexagon fill.color the filled color for each hexagon

clip either "on" for clipping to the extent of this viewport, "inherit" for inheriting the clipping region from the parent viewport, or "off" to turn clipping off altogether

newpage

logical to indicate whether to open a new page. By default, it sets to true for

opening a new page

### Value

invisible

38 visHexMulComp

#### Note

The mappingType includes:

- "indexes": the index of hexagons in a supra-hexagonal grid
- "hits": the number of input data vectors hitting the hexagons
- "dist": distance (in high-dimensional input space) to neighbors (defined in 2D output space)
- "antidist": the oppose version of "dist"
- "bases": clusters partitioned from the sMap
- "customized": displaying input "labels"

#### See Also

sDmat, sDmatCluster, visHexGrid

#### **Examples**

```
\# 1) generate data with three different distributions, each with an iid normal random matrix of 1000 x 3
data <- cbind(matrix(rnorm(1000*3,mean=0,sd=1), nrow=1000, ncol=3),</pre>
matrix(rnorm(1000*3,mean=0.5,sd=1), nrow=1000, ncol=3),
matrix(rnorm(1000*3,mean=-0.5,sd=1), nrow=1000, ncol=3))
colnames(data) <- c("S1", "S1", "S1", "S2", "S2", "S2", "S3", "S3", "S3")</pre>
# 2) sMap resulted from using by default setup
sMap <- sPipeline(data=data)</pre>
# 3) visualise supported mapping items within a supra-hexagonal grid
# 3a) for indexes of hexagons
\verb|visHexMapping(sMap,mappingType="indexes")| \\
# 3b) for the number of input data vectors hitting the hexagons
visHexMapping(sMap,mappingType="hits")
# 3c) for distance (in high-dimensional input space) to neighbors (defined in 2D output space)
visHexMapping(sMap,mappingType="dist")
# 3d) for anti-distance (in high-dimensional input space) to neighbors (defined in 2D output space)
visHexMapping(sMap,mappingType="antidist")
# 3e) for clusters/bases partitioned from the sMap
visHexMapping(sMap,mappingType="bases")
```

visHexMulComp

Function to visualise multiple component planes of a supra-hexagonal grid

#### **Description**

visHexMulComp is supposed to visualise multiple component planes of a supra-hexagonal grid

#### Usage

```
visHexMulComp(sMap, margin = rep(0.1, 4), height = 7,
  title.rotate = 0, title.xy = c(0.45, 1),
  colormap = c("bwr", "jet", "gbr", "wyr", "br", "yr", "rainbow", "wb"),
  ncolors = 40, zlim = NULL,
  border.color = "transparent", gp = grid::gpar())
```

visHexMulComp 39

#### **Arguments**

sMap an object of class "sMap"

margin margins as units of length 4 or 1

height a numeric value specifying the height of device

title.rotate the rotation of the title
title.xy the coordinates of the title

colormap short name for the colormap. It can be one of "jet" (jet colormap), "bwr" (blue-

white-red colormap), "gbr" (green-black-red colormap), "wyr" (white-yellow-red colormap), "br" (black-red colormap), "yr" (yellow-red colormap), "wb" (white-black colormap), and "rainbow" (rainbow colormap, that is, red-yellow-green-cyan-blue-magenta). Alternatively, any hyphen-separated HTML color names, e.g. "blue-black-yellow", "royalblue-white-sandybrown", "darkgreen-white-darkviolet". A list of standard color names can be found in http://

html-color-codes.info/color-names

ncolors the number of colors specified

zlim the minimum and maximum z values for which colors should be plotted, de-

faulting to the range of the finite values of z. Each of the given colors will be used to color an equispaced interval of this range. The midpoints of the intervals

cover the range, so that values just outside the range will be plotted

border.color the border color for each hexagon

gp an object of class gpar, typically the output from a call to the function gpar (i.e.,

a list of graphical parameter settings)

#### Value

invisible

#### Note

none

#### See Also

visVp, visHexComp, visColorbar

```
# 1) generate data with three different distributions, each with an iid normal random matrix of 1000 x 3
data <- cbind(matrix(rnorm(1000*3,mean=0,sd=1), nrow=1000, ncol=3),
matrix(rnorm(1000*3,mean=-0.5,sd=1), nrow=1000, ncol=3))
colnames(data) <- c("S1","S1","S2","S2","S2","S3","S3","S3")
# 2) sMap resulted from using by default setup
sMap <- sPipeline(data=data)
# 3) visualise multiple component planes of a supra-hexagonal grid
visHexMulComp(sMap, colormap="jet", ncolors=20, zlim=c(-1,1), gp=grid::gpar(cex=0.8))</pre>
```

40 visHexPattern

visHexPattern	Function to visualise codebook matrix or input patterns within a supra-hexagonal grid
	supra-nexagonai gria

#### **Description**

visHexPattern is supposed to codebook matrix or input patterns within a supra-hexagonal grid.

### Usage

```
visHexPattern(s0bj,
  plotType = c("lines", "bars", "radars"),
  pattern = NULL, height = 7, margin = rep(0.1, 4),
  colormap = c("customized", "bwr", "jet", "gbr", "wyr", "br", "yr", "rainbow", "wb"),
  customized.color = "red", zeropattern.color = "gray",
  legend.cex = 0.8, newpage = T)
```

#### **Arguments**

s0bj an object of class "sMap" or "sTopol" or "sInit"

plotType the plot type, can be "lines" for line/point graph, "bars" for bar graph, "radars"

for radar graph

pattern By default, it sets to "NULL" for the codebook matrix. It is intended for the

user-input patterns, i.e., a matrix with the dimension of nHex x nPattern, where nHex is the number of hexagons and nPattern is the number of elements for each

pattern

height a numeric value specifying the height of device

margin margins as units of length 4 or 1

colormap short name for the predifined colormap, and "customized" for custom input (see

the next 'customized.color'). The predifined colormap can be one of "jet" (jet colormap), "bwr" (blue-white-red colormap), "gbr" (green-black-red colormap), "wyr" (white-yellow-red colormap), "br" (black-red colormap), "yr" (yellow-red colormap), "wb" (white-black colormap), and "rainbow" (rainbow colormap, that is, red-yellow-green-cyan-blue-magenta). Alternatively, any hyphen-separated HTML color names, e.g. "blue-black-yellow", "royalblue-white-sandybrown", "darkgreen-white-darkviolet". A list of standard color names can be found in

http://html-color-codes.info/color-names

customized.color

the customized color for pattern visualisation

zeropattern.color

the color for zero horizental line

legend.cex a numerical value giving the amount by which legend text should be magnified

relative to the default (i.e., 1)

newpage logical to indicate whether to open a new page. By default, it sets to true for

opening a new page

#### Value

invisible

visHexPattern 41

#### Note

The "plotType" includes:

• "lines": line plot. If multple colors are given, the points are also plotted. When the pattern involves both positive and negative values, zero horizental line is also shown

- "bars": bar plot. When the pattern involves both positive and negative values, the zero horizental line is in the middle of the hexagon; otherwise at the top of the hexagon for all negative values, and at the bottom for all positive values
- "radars": radar plot. Each radar diagram represents one pattern, wherein each element value is proportional to the distance from the center. Note, it starts on the right and wind counterclockwise around the circle

#### See Also

sPipeline, visColormap

```
\# 1) generate data with three different distributions, each with an iid normal random matrix of 1000 x 3
data <- cbind(matrix(rnorm(1000*3,mean=0,sd=1), nrow=1000, ncol=3),</pre>
matrix(rnorm(1000*3, mean=0.5, sd=1), nrow=1000, ncol=3),
matrix(rnorm(1000*3, mean=-0.5, sd=1), nrow=1000, ncol=3))
colnames(data) <- c("S1", "S1", "S1", "S2", "S2", "S2", "S3", "S3", "S3")</pre>
# 2) sMap resulted from using by default setup
sMap <- sPipeline(data=data)</pre>
# 3) plot codebook patterns using different types
# 3a) line plot
visHexPattern(sMap, plotType="lines", customized.color="red", zeropattern.color="gray")
# visHexPattern(sMap, plotType="lines", customized.color=rep(c("red","green","blue"),each=3))
# 3b) bar plot
visHexPattern(sMap, plotType="bars")
# visHexPattern(sMap, plotType="bars", colormap="jet", legend.cex=0.8)
# visHexPattern(sMap, plotType="bars", customized.color=rep(c("red", "green", "blue"), each=3))
# 3c) radar plot
visHexPattern(sMap, plotType="radars")
# visHexPattern(sMap, plotType="radars", colormap="jet", legend.cex=0.8)
# visHexPattern(sMap, plotType="radars", customized.color=rep(c("red", "green", "blue"), each=3))
# 4) plot user-input patterns using different types
\# 4a) generate pattern data with two different groups "S" and "T"
nHex <- sMap$nHex
pattern <- cbind(matrix(runif(nHex*3,min=0,max=1), nrow=nHex, ncol=3),</pre>
matrix(runif(nHex*3,min=1,max=2), nrow=nHex, ncol=3))
colnames(pattern) <- c("S1", "S2", "S3", "T1", "T2", "T3")</pre>
# 4b) for line plot
visHexPattern(sMap, plotType="lines", pattern=pattern, customized.color="red", zeropattern.color="gray")
# visHexPattern(sMap, plotType="lines", pattern=pattern, customized.color=rep(c("red", "green"), each=3))
# 4c) for bar plot
visHexPattern(sMap, plotType="bars", pattern=pattern, customized.color=rep(c("red", "green"), each=3))
# 4d) for radar plot
visHexPattern(sMap, plotType="radars", pattern=pattern, customized.color=rep(c("red", "green"), each=3))
```

42 visKernels

visKernels

Function to visualize neighborhood kernels

### **Description**

visKernels is supposed to visualize a series of neighborhood kernels, each of which is a non-increasing functions of: i) the distance  $d_{wi}$  between the hexagon/rectangle i and the winner w, and ii) the radius  $\delta_t$  at time t.

### Usage

```
visKernels(newpage = T)
```

### **Arguments**

newpage

logical to indicate whether to open a new page. By default, it sets to true for opening a new page

#### Value

invisible

#### Note

There are five kernels that are currently supported:

- • For "gaussian" kernel,  $h_{wi}(t) = e^{-d_{wi}^2/(2*\delta_t^2)}$
- For "cutguassian" kernel,  $h_{wi}(t) = e^{-d_{wi}^2/(2*\delta_t^2)}*(d_{wi} \leq \delta_t)$
- For "bubble" kernel,  $h_{wi}(t) = (d_{wi} \le \delta_t)$
- For "ep" kernel,  $h_{wi}(t) = (1 d_{wi}^2/\delta_t^2) * (d_{wi} \le \delta_t)$
- • For "gamma" kernel,  $h_{wi}(t) = 1/\Gamma(d_{wi}^2/(4*\delta_t^2) + 2)$

These kernels above are displayed within a plot for each fixed radius. Three different radii (i.e., 1 and 2) are illustrated.

#### See Also

```
{\it sTrainSeq, sTrainBatch}
```

```
# visualise currently supported five kernels
visKernels()
```

visVp 43

visVp

Function to create viewports for multiple supra-hexagonal grids

### **Description**

visVp is supposed to create viewports, which describe rectangular regions on a graphics device and define a number of coordinate systems for each of supra-hexagonal grids.

### Usage

```
visVp(height = 7, xdim = 1, ydim = 1, colNum = 1,
rowNum = 1, gp = grid::gpar())
```

#### **Arguments**

height a numeric value specifying the height of device

xdim an integer specifying x-dimension of the grid

ydim an integer specifying y-dimension of the grid

colNum an integer specifying the number of columns

rowNum an integer specifying the number of rows

gp an object of class gpar, typically the output from a call to the function gpar (i.e.,

a list of graphical parameter settings)

#### Value

vpnames an R object of "viewport" class

### Note

none

### See Also

visHexMulComp, visCompReorder

```
# 1) create 5x5 viewports
vpnames <- visVp(colNum=5, rowNum=5)
# 2) look at names of these viewports
vpnames</pre>
```

44 Xiang

Xiang

Arabidopsis embryo gene expression dataset from Xiang et al. (2011)

### **Description**

Arabidopsis embryo dataset contains gene expression levels (3625 genes and 7 embryo samples) from Xiang et al. (2011). This dataset has been pre-processed: capping into floor of intensity 777.6; 2-base logarithmic transformation; row/gene centering; and keeping genes with at least 2-fold changes (in any stage) as compared to the average over embryo stages.

### Usage

data(Xiang)

### Value

• Xiang: a gene expression matrix of 3625 genes x 7 stage samples. These embryo stages are: zygote, quadrant, globular, heart, torpedo, bent, and mature.

### References

Xiang et al. (2011) Genome-wide analysis reveals gene expression and metabolic network dynamics during embryo development in Arabidopsis. *Plant Physiol*, 156(1):346-356.

## **Index**

```
*Topic datasets
    Fang, 2
    Golub, 3
    Xiang, 44
Fang, 2
Golub, 3
sBMH, 3, 6, 10, 16, 20, 28
sCompReorder, 5, 33
sDistance, 5, 6, 7, 10
sDmat, 8, 10, 11, 38
sDmatCluster, 8, 9, 34, 38
{\tt sDmatMinima}, {\it 10}, {\it 10}
sHexDist, 11, 16, 18
sHexGrid, 12, 22
sInitial, 12, 14, 20, 25
sMapOverlay, 15
sNeighAny, 9, 11, 16
sNeighDirect, 10, 17, 17
sPipeline, 4, 6, 10, 16, 18, 41
sTopology, 6, 12, 13, 15, 20, 21
sTrainBatch, 20, 22, 42
sTrainology, 20, 23, 24, 27
sTrainSeq, 20, 26, 42
sWriteData, 28
visColoralpha, 29
visColorbar, 30, 33, 39
visColormap, 29, 30, 31, 34, 35, 41
visCompReorder, 6, 30, 32, 43
visDmatCluster, 10, 33
visHexComp, 31, 33, 35, 36, 39
visHexGrid, 34, 35, 36, 38
visHexMapping, 22, 37
visHexMulComp, 16, 20, 30, 38, 43
visHexPattern, 40
visKernels, 23, 27, 42
visVp, 33, 39, 43
Xiang, 44
```