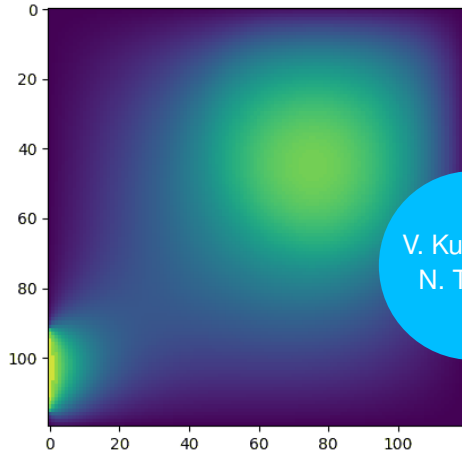




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## **Project 2: Time dependent heat equation with a source**

Scientific Computing

# Introduction

We solve the **time dependent heat equation**

$$\begin{cases} \partial_t u - \Delta u = f, & \text{in } (0, 1)^2, \\ u = g, & \text{on } \partial(0, 1)^2. \end{cases}$$

with a source  $f$  and boundary condition  $g$ .



# Discretization

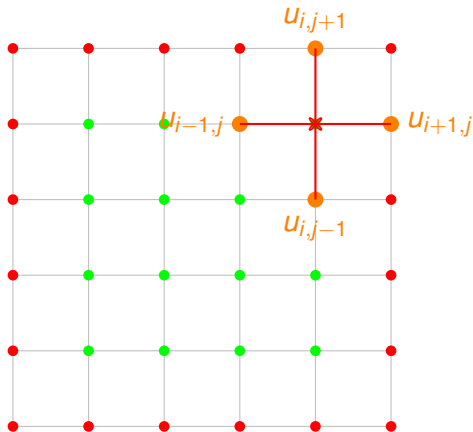
We use finite differences for the Laplacian

$$(\Delta u)(x) \approx (u(x_1 - \delta x, x_2) + u(x_1 + \delta x, x_2) + \\ u(x_1, x_2 - \delta x) + u(x_1, x_2 + \delta x) - 4u(x_1, x_2)) / \delta x^2$$

and the time derivative

$$\frac{u(x, t + \delta t) - u(x, t)}{\delta t} - (\Delta u)(x, t + \delta t) \approx f(x, t + \delta t) \\ \Longleftrightarrow u(x, t + \delta t) - \delta t (\Delta u)(x, t + \delta t) \approx \delta t f(x, t + \delta t) + u(x, t)$$





Let  $u_{ij}^{(\ell)} = u(x_{ij}, t_\ell)$ ,  $0 \leq i, j < N$ . Then

$$u_{ij}^{(\ell+1)} - \frac{\delta t}{\delta x^2} (Lu)_{ij}^{(\ell+1)} = \delta t f_{ij}^{(\ell+1)} + u_{ij}^{(\ell)}$$

where

$$(Lu)_{ij} = u_{i-1,j} + u_{i+1,j} + u_{i,j-1} + u_{i,j+1} - 4u_{ij}$$

and  $u_{ij}^{(\ell)} = g_{ij}^{(\ell)}$  in boundary points.



# Implementation details

```
def sparse_laplacian(self) -> csr_matrix:
    def in_bounds(i, j):
        return (0 <= i < self.N) and (0 <= j < self.N)

    L = lil_matrix((self.N**2, self.N**2))
    boundary_points = defaultdict(list)
    directions = [(-1, 0), (1, 0), (0, -1), (0, 1)]
    for i in range(self.N):
        for j in range(self.N):
            L[self.n(i, j), self.n(i, j)] = -4
            for dx, dy in directions:
                i_, j_ = i + dx, j + dy
                if in_bounds(i_, j_):
                    L[self.n(i, j), self.n(i_, j_)] = 1
            else:
                boundary_points[self.n(i, j)].append(((i+1)*self.dx, (j+1)*self.dx))
    self.boundary_points = boundary_points
    return (1/self.dx)**2 * csr_matrix(L)
```



# CG Method

```
def unpreconditioned_solve(self, b: np.ndarray, initial_guess: np.ndarray):  
    x = initial_guess  
    r = p = b - self.A@x  
    alpha = np.dot(r, r)  
  
    for _ in range(self.max_iterations):  
        v = self.A@p  
        _lambda = alpha / np.dot(v, p)  
        x = x + _lambda * p  
        r = r - _lambda * v  
        alpha_new = np.dot(r, r)  
        p = r + (alpha_new / alpha) * p  
        alpha = alpha_new  
  
        if alpha < self.tol**2:  
            return x  
  
    return None
```





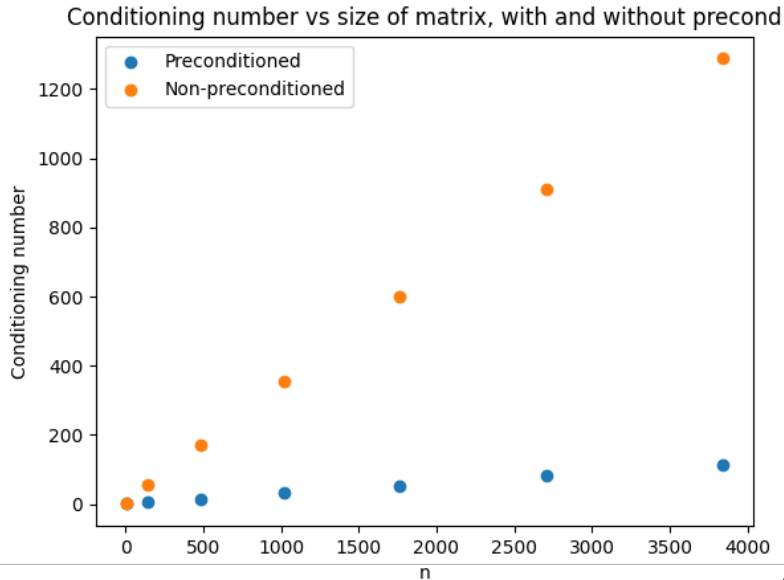
# Preconditioning

- $A$  is spd, we are doing CG  $\rightsquigarrow$  Incomplete Cholesky as preconditioner.
- We use IC(0)  $\rightsquigarrow$  Sparsity pattern is conserved.
- $A = L^T L \rightsquigarrow A \approx \tilde{L}^T \tilde{L}$
- Improvements: Smaller conditioning number  $\rightsquigarrow$  Fewer iterations needed
- Downsides: Solve two sparse triangular systems  $\rightsquigarrow$  More computing time per iteration

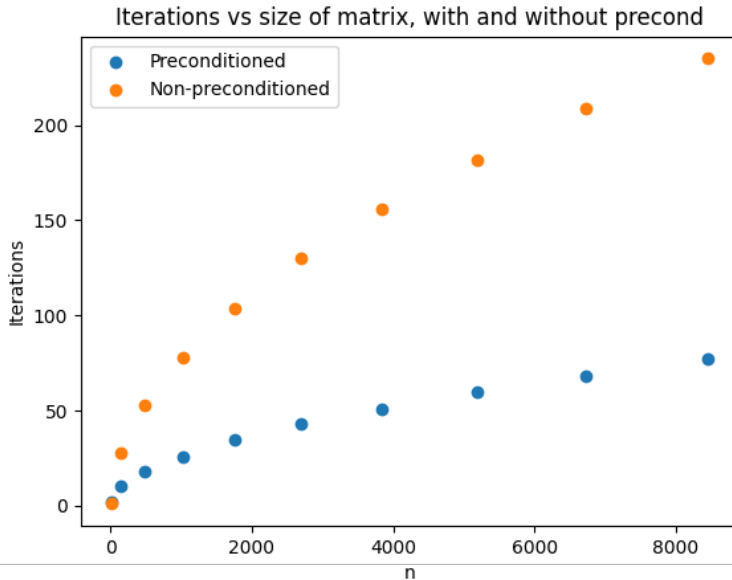




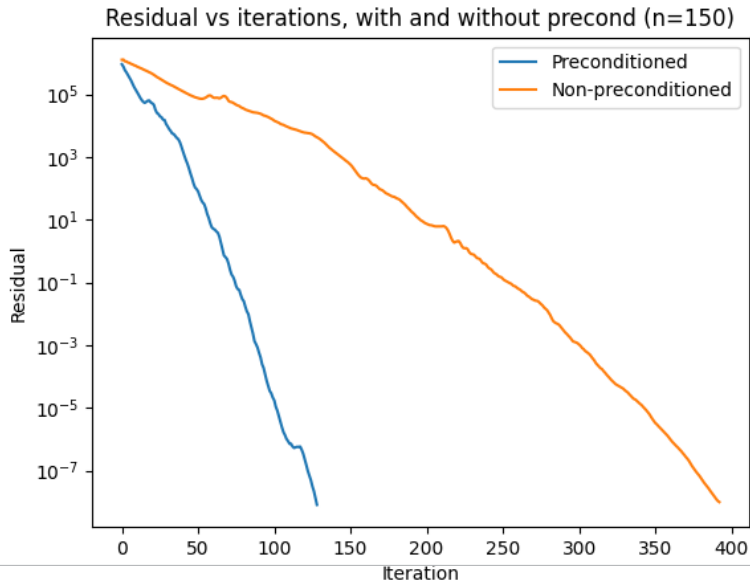
# Results (conditioning number)



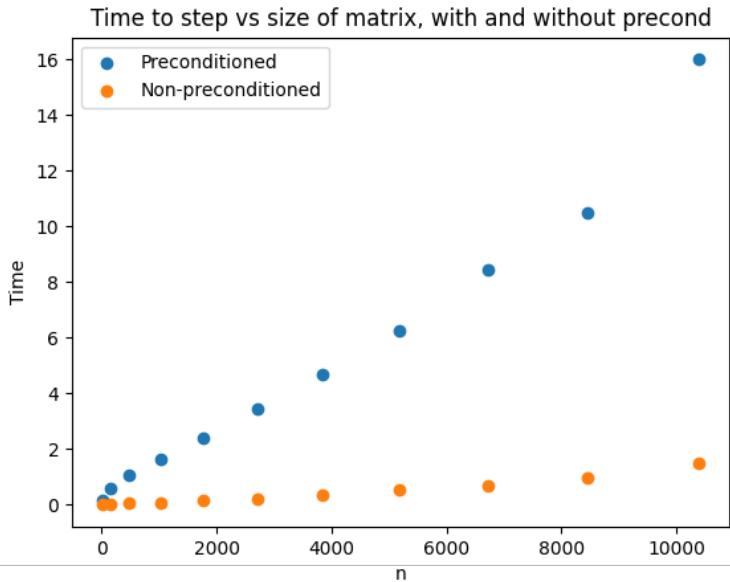
# Results (iterations)



# Results (residual)



# Results (time)



# References

- [1] [Dominik Götdeke](#).  
Scientific computing.  
Lecture Notes, June 2024.  
Version: 25th June 2024.

**ChatGPT** was used for implementation details regarding sparse matrices and visualizing our numerically computed solution.

