

## 1 Inserting the Kinect camera into Husky

Short description on how to modify the Gazebo files to put Sick Laser range finder or alternatively the Kinect camera. it is sufficient to modify the husky-fabrickhalle.launch file to change the robot configuration. The **urdf** and **gazebo** files in the husky kinetic devel should remain the same.

## 2 Ekf

Questions and doubts for the Robot Localization package:

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