

PMR2352

19 de outubro de 2011

1 Ex 1

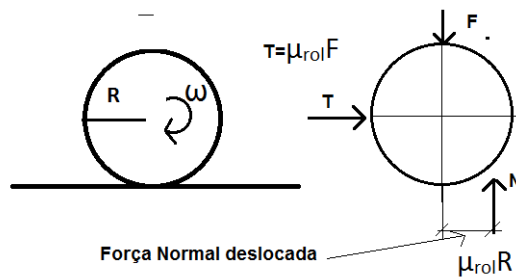


Figura 1: DCL

Exemplo

$$\mu_r R * \frac{\dot{x}}{|\dot{x}|}^1$$

TMB

$$m\ddot{x} = T - kx$$

$TMA)_{CENTRO}$

$$\frac{mR^2}{2}\ddot{\theta} = -T * R - \mu_r R \frac{\dot{x}}{|\dot{x}|} (mg)^2$$

$$\theta R = x$$

¹ajuste de sinal

²Normal

$$\dot{\theta}R = \dot{x}$$

$$\ddot{\theta}R = \ddot{x}$$

$$m\ddot{x} = T - kx$$

$$\frac{m}{2}\ddot{x} = -T - \mu_{rol}\frac{\dot{x}}{|\dot{x}|}mg$$

$$\frac{3m}{2}\ddot{x} = -kx - \mu_{rol}\frac{\dot{x}}{|\dot{x}|}mg$$

$$\frac{3m}{2}\ddot{x} + kx + \mu_{rol}\frac{\dot{x}}{|\dot{x}|}mg = 0$$

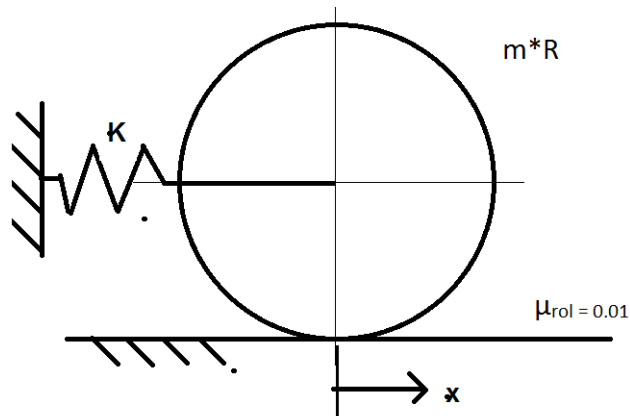


Figura 2: Exemplo

$$m_{eq}\ddot{x} + c_{eq}\dot{x} + k_{eq}x = 0$$

Para $\dot{x} > 0$

$$\frac{3m}{2}\ddot{x} + kx + \mu_{rol}mg = 0$$

Para $\dot{x} < 0$

$$\frac{3m}{2}\ddot{x} + kx - \mu_{rol}mg = 0$$

• $\dot{x}(0) = 0$

Para $t > 0$, para $t < T$

$$(2a + b)\ddot{x} + 2gx = 0(t)$$

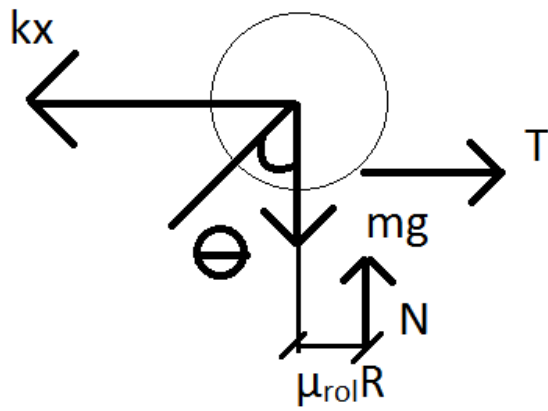


Figura 3: DCL exemplo

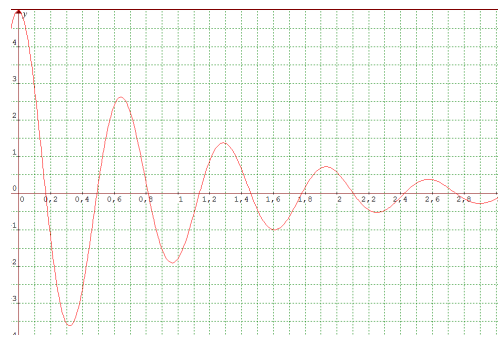


Figura 4: 2 ex1

2 Ex 2

$$2(\rho Aa)\ddot{x} + \rho Ab(\ddot{x} + \dot{v}(t)) = -2x\rho gA$$

$$(2a + b)\ddot{x} + 2gx = -b\dot{v}(t)$$

$$m_{eq}\ddot{x} + k_{eq}x = \psi(t)$$

$$\omega = \sqrt{\frac{2g}{2a + b}}$$

Para $0 < t < T$

$$(2a + b)\ddot{x} + 2gx = b\frac{V_0}{T}$$

Condições iniciais:

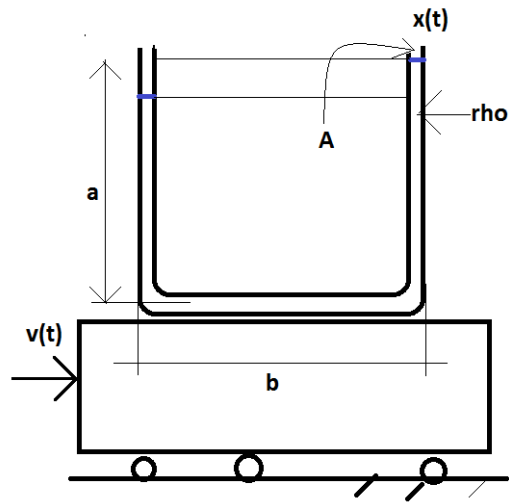


Figura 5: 1 Ex 2

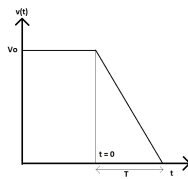


Figura 6: 2 Ex 2

- $x(0)=0$
- $\dot{x}(0) = 0$

Para $t < 0$, para $t > T$

$$(2a + b)\ddot{x} + 2gx = 0(t)$$

$$x(t) = \frac{1}{m\omega} \int_0^t F(\tau) \sin(\omega(t - \tau)) d\tau$$

$$x_h(t) = A \sin(\omega t) + B \cos(\omega t)$$

$$x_p(t) = \frac{bV_0}{2gT}$$

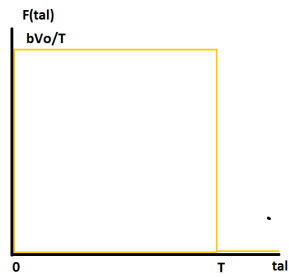


Figura 7: F de τ

$$x(t) = A \sin(\omega t) + B \cos(\omega t) + \frac{bV_0}{2gT}$$

$$\dot{x}(t) = A\omega \cos(\omega t) - B \sin(\omega t)$$

Condições Iniciais:

$$x(0) = 0 = B + \frac{bV_0}{2gT}$$

$$\dot{x}(0) = 0 = A\omega$$

Portanto

$$B = -\frac{bV_0}{2gT}$$

$$A = 0$$

$$x(t) = \frac{bV_0}{2gT}(1 - \cos(\omega t))$$

$$\dot{x}(t) = \frac{bV_0}{2gT}\omega \sin(\omega t)$$

Para $t=T$:

$$x(T) = \frac{bV_0}{2gT}(1 - \cos(\omega T))$$

$$\dot{x}(T) = \frac{bV_0}{2gT}\omega \sin(\omega T)$$

Para $t > T$

$$(2a + b)\ddot{x} + 2gx = 0$$

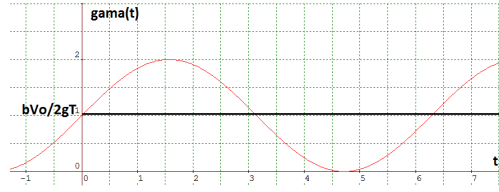


Figura 8: Para $0 < t < T; \omega t = 2\pi$

$$A' \sin(\omega t) + B' \cos(\omega t)$$

$$A' \omega \cos(\omega t) - B' \omega \sin(\omega t)$$

CI do trecho:

$$x(T) = \frac{bV_0}{2gT}(1 - \cos(\omega T)) = A' \sin(\omega T) + B' \cos(\omega T)$$

$$\dot{x}(T) = \frac{bV_0}{2gT}(\omega \sin(\omega T)) = A' \omega \cos(\omega T) - B' \omega \sin(\omega T)$$