Supplementary Analyses: External Source Attribution and Adaptation while Viewing the Hand

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Overview

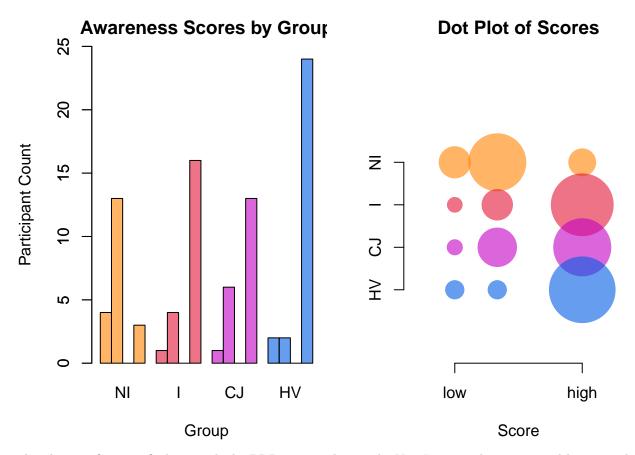
This document discusses analyses conducted to support and justify the main tests conducted for the study. These tests are not included in the Results and Discussion sections of the manuscript.

Awareness Scores

Show scores for all groups

At the end of the experiment, participants had to answer a series of questions to assess their awareness of the perturbation they experienced (adapted from Benson et al., 2011; Modchalingam et al., 2019). Each response was given a score and follow-up questions were dependent on the participant's responses to the previous question. Scores were added at the end to come up with an Awareness Score for the participant (where, 0 means low awareness and 3 means high awareness). Below are two plots showing the data on awareness scores by group. The barplot shows the number of participants that scored either 0, 1, 2, or 3 on the Awareness Questionnaire, for each of the four groups. The dot plot generated beside it, gives a visual of the number of participants scoring either high or low on the questionnaire, separated according to group.

plotAwareness()



The plots confirm our findings with the PDP-type analysis. The Non-Instructed group scored lower on the questionnaire compared to the other groups, suggesting unawareness of the nature of the perturbation.

Pearson correlation test between implicit reach aftereffects and passive localization

Here, we tested whether the shifts in passive localization are correlated with the angular reach deviations of the hand in *No Cursor - Without Strategy* trials. We performed a Pearson product-moment correlation test, which included all participants regardless of group.

getRAEPropCorrelation()

```
##
## Pearson's product-moment correlation
##
## data: dat$reachdeviation and dat$prop_recal
## t = -3.4856, df = 88, p-value = 0.000768
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.5180279 -0.1521885
## sample estimates:
## cor
## -0.3483022
```

We found a negative relationship (r = -0.35) between afferent-based changes in localization and reach aftereffects when excluding a strategy (p < 0.001, r-squared = 0.12). This relationship suggests that proprioceptive recalibration could be contributing to the reach aftereffects we have observed.

We performed the same test for updates in predicted sensory consequences and reach aftereffects.

getRAEPredCorrelation()

```
##
## Pearson's product-moment correlation
##
## data: dat$reachdeviation and dat$pred_update
## t = -2.9334, df = 88, p-value = 0.004274
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.47611605 -0.09737975
## sample estimates:
## cor
## -0.2984521
```

We found a negative realtionship (r = -0.30) between efferent-based changes in localization and reach after-effects when excluding a strategy (p < 0.01, r-squared = 0.09). This relationship suggests that updates in predictions are also contributing to reach aftereffects.

Performing these two correlations bring about two possible criticisms: 1) Significant relationships found from both correlation tests could be spurious, since data from all individuals across all groups were pooled together. 2) The multiple regression done in the main text will be valid if changes in proprioception are independent from updates in predictions.

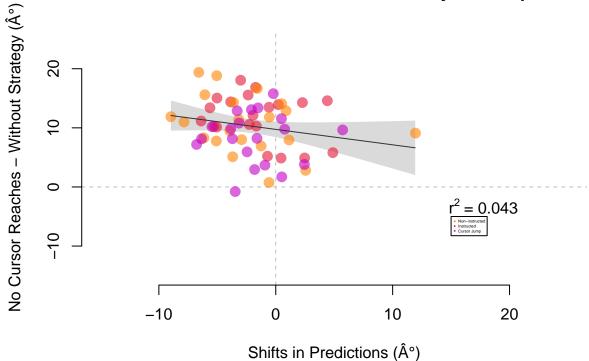
Justification for pooling data across participants from all groups

1)

First, we looked into the possibility of a spurious correlation existing within our dataset. Essentially, we are looking for the existence of a group effect. One way of looking into group effects is to see how the relationships of predictions and proprioception with aftereffects change with the removal of the Hand View group (Note that we only remove the Hand View group because it was the group observed to be different from the others in measures of aftereffects and predicted sensory consequences). First, we investigate the relationship of predictions and aftereffects, without the Hand View group.

plotNoHVPredGroupCorrelations()

Reach Aftereffects and Predicted Sensory Consequences



```
##
## Call:
## lm(formula = reachdev ~ pred_update)
## Residuals:
##
       Min
                 1Q
                      Median
                                   3Q
                                           Max
                      0.1273
## -11.4243 -3.1410
                               3.5942
                                        7.9257
##
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
## (Intercept)
                9.7403
                           0.6557 14.854
                                            <2e-16 ***
                           0.1606 -1.625
                                             0.109
## pred_update -0.2611
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 4.515 on 59 degrees of freedom
## Multiple R-squared: 0.04286,
                                   Adjusted R-squared:
## F-statistic: 2.642 on 1 and 59 DF, p-value: 0.1094
```

```
##
## Pearson's product-moment correlation
##
## data: dat$reachdeviation and dat$pred_update
```

getNoHVRAEPredCorrelation()

We found that the correlation between predictions and aftereffects, after removing the Hand View group, was not significant (p > 0.10, r = -0.21, r-squared = 0.04). This suggests that the observed effect from previous analyses could be mainly driven by the Hand View group.

Next, we repeat the analyses for proprioceptive recalibration and aftereffects.

plotNoHVPropGroupCorrelations()


```
##
  lm(formula = reachdev ~ prop_recal)
##
##
  Residuals:
##
        Min
                        Median
                                      3Q
                   1Q
                                               Max
   -10.4506
                        0.6379
##
             -2.7755
                                  2.8786
                                            8.7508
##
## Coefficients:
```

```
## Estimate Std. Error t value Pr(>|t|)
## (Intercept) 8.9373 0.8070 11.075 4.88e-16 ***
## prop_recal -0.2536 0.1116 -2.273 0.0267 *
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 4.426 on 59 degrees of freedom
## Multiple R-squared: 0.08052, Adjusted R-squared: 0.06494
## F-statistic: 5.167 on 1 and 59 DF, p-value: 0.02668
```

getNoHVRAEPropCorrelation()

```
##
## Pearson's product-moment correlation
##
## data: dat$reachdeviation and dat$prop_recal
## t = -2.2731, df = 59, p-value = 0.02668
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.49986880 -0.03440588
## sample estimates:
## cor
## -0.283768
```

We found that the correlation between proprioceptive changes and aftereffects, after removing the Hand View group, was significant (p < 0.05, r = -0.28, r-squared = 0.08).

2)

We also looked into the relationships of both predictions and proprioception with reach aftereffects, for each individual group. First, I show results for correlation tests between proprioception and aftereffects for each group. I also plot these relationships to visualize the data better.

getPGPropCorr()

```
## Hand View group - Propriocetive Recalibration and Reach Aftereffects:
##
##
  Pearson's product-moment correlation
##
## data: dat$reachdeviation and dat$prop_recal
## t = -2.9848, df = 27, p-value = 0.005963
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.7311328 -0.1609830
## sample estimates:
##
          cor
## -0.4981002
##
## Cursor Jump group - Propriocetive Recalibration and Reach Aftereffects:
##
##
   Pearson's product-moment correlation
##
```

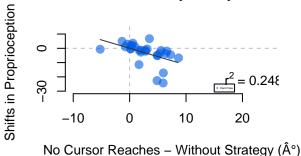
```
## data: dat$reachdeviation and dat$prop_recal
## t = -1.5424, df = 18, p-value = 0.1404
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.6811933 0.1188212
## sample estimates:
          cor
## -0.3416646
##
## Instructed group - Propriocetive Recalibration and Reach Aftereffects:
  Pearson's product-moment correlation
##
##
## data: dat$reachdeviation and dat$prop_recal
## t = -1.3092, df = 19, p-value = 0.2061
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.6398851 0.1644497
## sample estimates:
##
         cor
## -0.2876581
##
## Non Instructed group - Propriocetive Recalibration and Reach Aftereffects:
##
## Pearson's product-moment correlation
## data: dat$reachdeviation and dat$prop_recal
## t = -0.73844, df = 18, p-value = 0.4698
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.5706910 0.2933019
## sample estimates:
##
         cor
## -0.171475
```

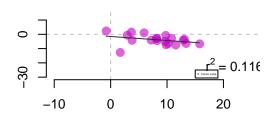
plotPGPropCorr()

```
##
## Call:
## lm(formula = prop_recal ~ reachdev)
## Residuals:
##
       Min
                 1Q
                      Median
                                   3Q
                                           Max
## -17.3669 -0.1675
                      1.8698
                               3.3186 10.8137
##
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.03101
                          1.61941 0.019 0.98486
## reachdev
              -1.16763
                          0.39119 -2.985 0.00596 **
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 6.455 on 27 degrees of freedom
## Multiple R-squared: 0.2481, Adjusted R-squared: 0.2203
```

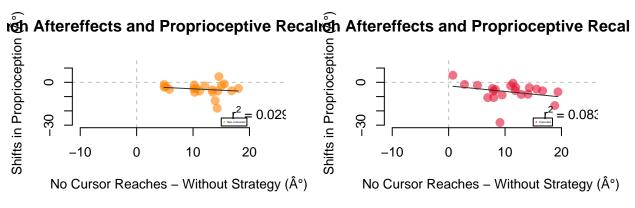
```
## F-statistic: 8.909 on 1 and 27 DF, p-value: 0.005963
##
## Call:
## lm(formula = prop_recal ~ reachdev)
## Residuals:
       Min
                 1Q Median
                                  3Q
## -10.7058 -1.2632 0.1503 1.7710
                                       4.2216
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
## (Intercept) -1.5133
                        1.6985 -0.891
                                            0.385
             -0.2815
                          0.1825 -1.542
## reachdev
                                            0.140
## Residual standard error: 3.44 on 18 degrees of freedom
## Multiple R-squared: 0.1167, Adjusted R-squared: 0.06766
## F-statistic: 2.379 on 1 and 18 DF, p-value: 0.1404
##
## Call:
## lm(formula = prop_recal ~ reachdev)
## Residuals:
##
       Min
                 1Q Median
                                  3Q
                                          Max
## -12.7639 -1.2245 0.1907 2.1117
                                       9.4246
##
## Coefficients:
             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -2.6318
                       3.2291 -0.815
                                          0.426
                          0.2610 -0.738
## reachdev
             -0.1927
                                            0.470
## Residual standard error: 4.551 on 18 degrees of freedom
## Multiple R-squared: 0.0294, Adjusted R-squared: -0.02452
## F-statistic: 0.5453 on 1 and 18 DF, p-value: 0.4698
```


Shifts in Proprioception

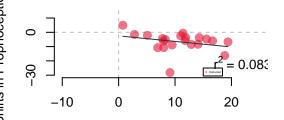




No Cursor Reaches – Without Strategy (°)



##



No Cursor Reaches – Without Strategy (°)

```
## Call:
## lm(formula = prop_recal ~ reachdev)
##
## Residuals:
                                     3Q
##
        Min
                  1Q
                        Median
                                             Max
                                          7.7182
   -22.1515 -0.9868
                        1.3045
##
                                 3.4939
##
##
  Coefficients:
##
               Estimate Std. Error t value Pr(>|t|)
##
                -2.4760
                             3.4737
                                     -0.713
                                               0.485
  (Intercept)
                -0.3894
                                    -1.309
## reachdev
                             0.2975
                                               0.206
##
## Residual standard error: 6.471 on 19 degrees of freedom
## Multiple R-squared: 0.08275,
                                     Adjusted R-squared:
## F-statistic: 1.714 on 1 and 19 DF, p-value: 0.2061
```

We see that only the Hand View group exhibits a significant relationship between proprioception and aftereffects (p < 0.01, r = -0.50, r-squared = 0.25), while other groups did not exhibit such a relationship (Cursor Jump: p > 0.10, r = -0.34, r-squared = 0.12; Instructed: p > 0.10, r = -0.29, r-squared = 0.03; Non-Instructed: p > 0.10, r = -0.17, r-squared = 0.08).

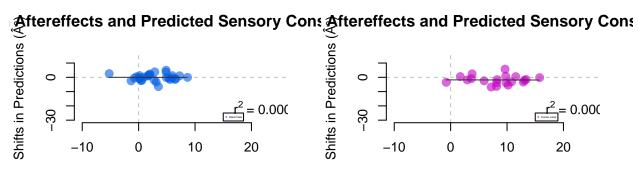
We then repeat the same analyses for predictions and aftereffects.

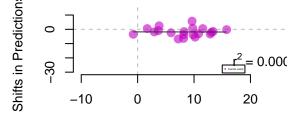
getPGPredCorr()

```
## Hand View group - Predictions and Reach Aftereffects:
##
  Pearson's product-moment correlation
##
## data: dat$reachdeviation and dat$pred_update
## t = -0.017867, df = 27, p-value = 0.9859
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.3694785 0.3635253
## sample estimates:
            cor
## -0.003438478
##
## Cursor Jump group - Predictions and Reach Aftereffects:
## Pearson's product-moment correlation
##
## data: dat$reachdeviation and dat$pred_update
## t = -0.036227, df = 18, p-value = 0.9715
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.4493613 0.4356283
## sample estimates:
## -0.008538431
## Instructed group - Predictions and Reach Aftereffects:
##
## Pearson's product-moment correlation
## data: dat$reachdeviation and dat$pred update
## t = -1.383, df = 19, p-value = 0.1827
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.6493428 0.1486644
## sample estimates:
##
         cor
## -0.3024313
## Non Instructed group - Predictions and Reach Aftereffects:
## Pearson's product-moment correlation
##
## data: dat$reachdeviation and dat$pred_update
## t = -1.3424, df = 18, p-value = 0.1961
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.6565472 0.1625469
## sample estimates:
##
          cor
## -0.3016734
```

plotPGPredCorr()

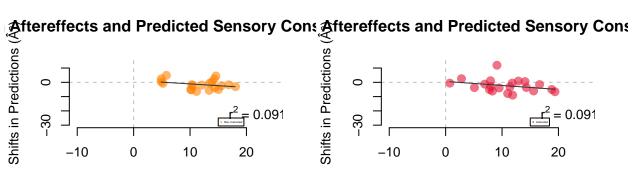
```
##
## Call:
## lm(formula = pred_update ~ reachdev)
##
## Residuals:
##
      Min
               1Q Median
                               3Q
                                      Max
## -6.4532 -1.3914 -0.1751 1.1821 4.9556
##
## Coefficients:
##
               Estimate Std. Error t value Pr(>|t|)
## (Intercept) -0.008827
                          0.598486 -0.015 0.988
## reachdev -0.002583
                        0.144571 -0.018
                                              0.986
##
## Residual standard error: 2.386 on 27 degrees of freedom
## Multiple R-squared: 1.182e-05, Adjusted R-squared: -0.03702
## F-statistic: 0.0003192 on 1 and 27 DF, p-value: 0.9859
##
## Call:
## lm(formula = pred_update ~ reachdev)
## Residuals:
               1Q Median
                               3Q
      Min
                                      Max
## -4.9437 -1.7332 -0.1119 1.8320 7.5661
##
## Coefficients:
               Estimate Std. Error t value Pr(>|t|)
## (Intercept) -1.786965
                        1.513885 -1.180
                                              0.253
              -0.005893
                          0.162676 -0.036
## reachdev
##
## Residual standard error: 3.066 on 18 degrees of freedom
## Multiple R-squared: 7.29e-05, Adjusted R-squared: -0.05548
## F-statistic: 0.001312 on 1 and 18 DF, p-value: 0.9715
##
## Call:
## lm(formula = pred_update ~ reachdev)
##
## Residuals:
   Min
             1Q Median
                           3Q
                                 Max
## -4.990 -1.916 -0.110 1.621 6.657
##
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
##
                           2.2770
                                  0.598
## (Intercept)
               1.3618
                                             0.557
## reachdev
               -0.2471
                           0.1840 -1.342
                                             0.196
## Residual standard error: 3.209 on 18 degrees of freedom
## Multiple R-squared: 0.09101, Adjusted R-squared: 0.04051
## F-statistic: 1.802 on 1 and 18 DF, p-value: 0.1961
```

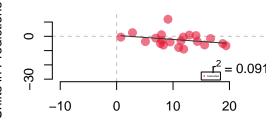




No Cursor Reaches – Without Strategy (°)

No Cursor Reaches – Without Strategy (°)





No Cursor Reaches – Without Strategy (°)

No Cursor Reaches – Without Strategy (°)

```
##
## Call:
##
  lm(formula = pred_update ~ reachdev)
##
## Residuals:
                                 30
##
       Min
                10
                   Median
                                        Max
   -6.2501 -2.3003 -0.5786
                            2.4896 13.8935
##
##
##
  Coefficients:
##
               Estimate Std. Error t value Pr(>|t|)
##
                 0.6212
                             2.3755
                                      0.262
                                                0.797
  (Intercept)
## reachdev
                -0.2813
                             0.2034
                                     -1.383
                                                0.183
##
## Residual standard error: 4.425 on 19 degrees of freedom
## Multiple R-squared: 0.09146,
                                     Adjusted R-squared:
## F-statistic: 1.913 on 1 and 19 DF, p-value: 0.1827
```

We see that none of the groups exhibited a significant relationship between predictions and aftereffects (Hand View: p > 0.10, r = -0.003, r-squared = 0.00001; Cursor Jump: p > 0.10, r = -0.009, r-squared = 0.00007; Instructed: p > 0.10, r = -0.30, r-squared = 0.09; Non-Instructed: p > 0.10, r = -0.30, r-squared = 0.09).

Taken together, these results show that the significant relationship we found, specifically for updates in predictions seem to be spurious. That is, there seems to be a group effect. According to Makin & Orban de Xivry (2019), if a relationship is spurious, then one would need to take into account group differences when pooling data across participants together.

3)

To account for group differences, we conducted a mean correction procedure. We took the mean prediction and proprioception values for each group, then subtracted the mean from each individual score within that group. Afterwards, we conducted the multiple regression again on this mean corrected dataset.

getMeanCorrectedGLM()

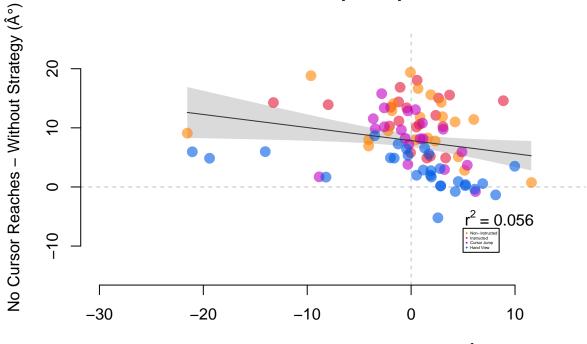
```
##
## Call:
  glm(formula = RAE ~ pas_loc + pred_update, data = data)
##
## Deviance Residuals:
##
       Min
                         Median
                                       3Q
                   1Q
                                                 Max
##
  -11.1828
              -3.8277
                        -0.3714
                                   4.2415
                                            11.9536
##
## Coefficients:
##
               Estimate Std. Error t value Pr(>|t|)
                 7.8396
                            0.5458
                                    14.362
## (Intercept)
                                           < 2e-16 ***
                -0.3049
                                    -3.007
## pas loc
                            0.1014
                                            0.00345 **
                                    -2.317
                                            0.02286 *
## pred_update
                -0.4197
                            0.1811
##
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
##
  (Dispersion parameter for gaussian family taken to be 26.81468)
##
##
       Null deviance: 2622.9
                              on 89
                                     degrees of freedom
## Residual deviance: 2332.9
                              on 87
                                     degrees of freedom
## AIC: 556.36
##
## Number of Fisher Scoring iterations: 2
```

However, we found that both predictors (predictions: p < 0.05; proprioception: p < 0.01) were still significant after doing such a correction.

As a side note, we can also consider proprioception and predictions separately. First, we replot the relationship of proprioceptive recalibration with aftereffects after the correction, then test for a correlation.

plotMeanCorrectedPropCorrelations()

Reach Aftereffects and Proprioceptive Recalibration



Shifts in Corrected Passive Localization (°)

```
##
## Call:
## lm(formula = reachdev ~ prop_recal)
##
## Residuals:
##
       Min
                 1Q
                      Median
                                   3Q
## -12.4900 -4.1665 -0.3211
                               4.2778 11.5323
##
## Coefficients:
##
              Estimate Std. Error t value Pr(>|t|)
## (Intercept) 7.83956
                          0.55922 14.019
                                            <2e-16 ***
                          0.09704 -2.278
                                            0.0251 *
## prop_recal -0.22109
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 5.305 on 88 degrees of freedom
## Multiple R-squared: 0.0557, Adjusted R-squared: 0.04497
## F-statistic: 5.191 on 1 and 88 DF, p-value: 0.02513
```

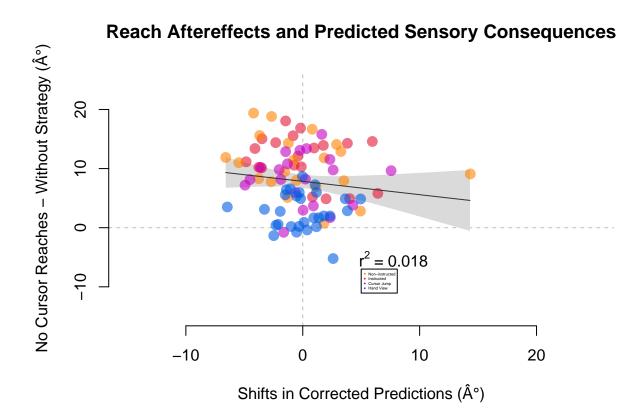
getMeanCorrectedRAEPropCorrelation()

```
##
## Pearson's product-moment correlation
##
## data: dat$RAE and dat$pas_loc
```

```
## t = -2.2783, df = 88, p-value = 0.02513
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.42245270 -0.03040403
## sample estimates:
## cor
## -0.2360091
```

We found that proprioception has a significant relationship with aftereffects (p=0.03, r = -0.24), but this is less in magnitude compared to the original data (r-squared went from 0.12 to 0.06). We repeated the same analyses for predictions.

plotMeanCorrectedPredCorrelations()



```
##
## Call:
## lm(formula = reachdev ~ pred)
##
## Residuals:
        Min
                  1Q
                       Median
                                     3Q
                                             Max
  -12.4734 -3.9394
                      -0.3644
                                         10.5983
##
                                 4.3454
##
## Coefficients:
               Estimate Std. Error t value Pr(>|t|)
                             0.5702 13.748
                                              <2e-16 ***
## (Intercept)
                 7.8396
```

```
## pred -0.2254  0.1768 -1.275  0.206
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 5.41 on 88 degrees of freedom
## Multiple R-squared: 0.01814, Adjusted R-squared: 0.006978
## F-statistic: 1.625 on 1 and 88 DF, p-value: 0.2057
```

getMeanCorrectedRAEPredCorrelation()

We found the predictions did not have a significant relationship with aftereffects (p=0.21, r = -0.13), and r-squared values were reduced from 0.09 to 0.02.

Next, we quantified the difference between this mean corrected model (mod2) from the original model (mod1). From the AIC values, we found that mod1 (AIC = 535.74) seems to be a better model than mod 2 (AIC = 556.36). To test this more formally, we conducted a Cox test. Note that an ANOVA would be inappropriate as these two models are non-nested. A Cox test would investigate whether the second model would add any explanatory value to the first model. Below is the definition from the R help file:

"If the first model contains the correct set of regressors, then a fit of the regressors from the second model to the fitted values from first model should have no further explanatory value. But if it has, it can be concluded that model 1 does not contain the correct set of regressors."

getOrigCorrRegComp()

```
## Cox test
##
## Model 1: RAE ~ pred_update + prop_recal
## Model 2: RAE ~ pas_loc + pred_update
## Estimate Std. Error z value Pr(>|z|)
## fitted(M1) ~ M2    7.4697    2.0824   3.5870   0.0003345 ***
## fitted(M2) ~ M1 -11.1376    1.1626 -9.5798 < 2.2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1</pre>
```

Given that mod1 should contain the group effects, we consider the second result (fitted(M2) \sim M1; p < .001), suggesting that mod 1 does add explanatory value to mod2. Note that the Cox test also does the comparison the other way. Nevertheless, these results show that there is indeed a group effect present (which was expected given the design of the experiment), and this is partially explaining the variance in the data. Despite accounting for groups, we found that both predictors were still significant when we conducted the multiple regression. This suggests that, although a group effect does exist, our conclusion that changes in proprioception and predictions could be contributing to reach aftereffects are justified.

Independence of changes in proprioception from prediction

Aside from how proprioceptive changes and updates in predictions are calculated. Here, we conduct formal tests to show the independence of the two.

To show that changes in predictions and proprioception are independent predictors/contributors to reach aftereffects, proprioception should be able to predict the residuals of regressing aftereffects on predictions.

getPredResidByPropCorrelation()

```
##
## Pearson's product-moment correlation
##
## data: mod1_Res and prop
## t = -4.7727, df = 88, p-value = 7.18e-06
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.6038417 -0.2718971
## sample estimates:
## cor
## -0.4534553
```

We find a significant relationship between proprioception and residuals of regressing aftereffects on predictions (p < 0.001, r = -0.45). We can also see if the same is true for predictions and residuals of regressing aftereffects on proprioception.

getPropResidByPredCorrelation()

```
##
## Pearson's product-moment correlation
##
## data: mod1_Res and pred
## t = -4.3864, df = 88, p-value = 3.185e-05
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
## -0.5798053 -0.2372980
## sample estimates:
## cor
## -0.4235737
```

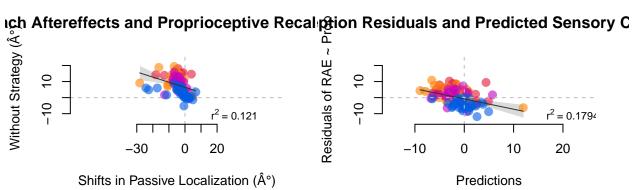
We find a significant relationship as well (p < 0.001, r = -0.42). Lastly, we can compare these two relationships with our original correlational plots.

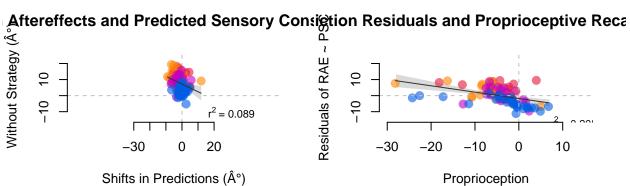
plotRelationships()

```
##
## Call:
## lm(formula = reachdev ~ prop_recal)
##
## Residuals:
## Min 1Q Median 3Q Max
## -11.8236 -4.0634 -0.2784 3.7385 10.8567
```

```
##
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
## (Intercept) 6.39900
                         0.67956 9.416 5.7e-15 ***
## prop_recal -0.31817
                         0.09128 -3.486 0.000768 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 5.118 on 88 degrees of freedom
## Multiple R-squared: 0.1213, Adjusted R-squared: 0.1113
## F-statistic: 12.15 on 1 and 88 DF, p-value: 0.000768
##
##
## Call:
## glm(formula = mod1_Res ~ pred)
##
## Deviance Residuals:
      \mathtt{Min}
           10
                    Median
## -9.3382 -3.4593 -0.6328 4.0243 13.1090
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
## (Intercept) -0.8363
                          0.5245 -1.594
               -0.6381
                          0.1455 -4.386 3.19e-05 ***
## pred
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## (Dispersion parameter for gaussian family taken to be 21.49113)
##
      Null deviance: 2304.7 on 89 degrees of freedom
## Residual deviance: 1891.2 on 88 degrees of freedom
## AIC: 535.47
## Number of Fisher Scoring iterations: 2
##
## Call:
## lm(formula = reachdev ~ pred_update)
## Residuals:
##
               1Q Median
      Min
                              3Q
                                     Max
## -11.191 -3.720 -0.292
                            4.271
##
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
## (Intercept) 7.2109
                          0.5896 12.231 < 2e-16 ***
## pred_update -0.4797
                          0.1635 -2.933 0.00427 **
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 5.211 on 88 degrees of freedom
## Multiple R-squared: 0.08907, Adjusted R-squared: 0.07872
## F-statistic: 8.605 on 1 and 88 DF, p-value: 0.004274
##
```

```
##
## Call:
   glm(formula = mod1_Res ~ prop)
##
##
##
  Deviance Residuals:
##
       Min
                 1Q
                      Median
                                    3Q
                                            Max
                     -0.3509
                                3.7624
                                        12.8586
##
   -9.6556
            -3.1015
##
##
   Coefficients:
##
               Estimate Std. Error t value Pr(>|t|)
##
   (Intercept) -1.78999
                            0.61669
                                     -2.903 0.00468 **
               -0.39535
                            0.08284
                                     -4.773 7.18e-06 ***
##
   prop
##
  Signif. codes:
                      '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
##
   (Dispersion parameter for gaussian family taken to be 21.56813)
##
##
       Null deviance: 2389.3
                                      degrees of freedom
                               on 89
## Residual deviance: 1898.0
                              on 88 degrees of freedom
   AIC: 535.8
##
## Number of Fisher Scoring iterations: 2
```





By considering the residuals, we are essentially controlling for one predictor. However, the existence of a significant relationship, between one predictor and the residuals of aftereffects with the other predictor, suggests that the two predictors are independent from each other.

Next, recall how the VIF score between proprioception and prediction was low. However, the low VIF score from predictions and proprioceptive changes could be trivial, given that predicted sensory consequences are measured by subtracting Passive Localization scores from Active Localization (PSC = ACT - PAS). To investigate this further, we could simulate either ACT or PAS scores that will also have a low VIF score with the other variable, but will not correlate with the residuals of regressing aftereffects on the other variable.

First, we generated simulated PAS scores. To do this, we shuffled the PSC scores then subtracted them from ACT scores. Then we tested whether these simulated PAS scores will correlate with the residuals of regressing reach aftereffects with ACT scores.

getACTResidByFakePASCorrelation()

```
##
## Call:
##
  glm(formula = RAE ~ ACT)
##
## Deviance Residuals:
##
        Min
                   1Q
                         Median
                                        3Q
                                                 Max
##
  -10.7549
              -3.2870
                        -0.5072
                                   3.5372
                                             13.4746
##
## Coefficients:
##
               Estimate Std. Error t value Pr(>|t|)
  (Intercept) 5.08077
                           0.69193
                                     7.343 9.97e-11 ***
##
## ACT
               -0.47254
                           0.08327
                                    -5.675 1.75e-07 ***
##
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## (Dispersion parameter for gaussian family taken to be 21.82019)
##
##
       Null deviance: 2622.9
                             on 89
                                     degrees of freedom
## Residual deviance: 1920.2 on 88
                                     degrees of freedom
  AIC: 536.84
##
##
  Number of Fisher Scoring iterations: 2
##
##
##
   Pearson's product-moment correlation
##
## data: mod1 Res and PAS
## t = 0.20965, df = 88, p-value = 0.8344
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
##
   -0.1856063 0.2283780
## sample estimates:
##
         cor
## 0.0223436
##
##
     Variables
## 1
     fake_pas 1.094477
           PSQ 1.094477
```

We found that the simulated PAS scores do not significantly correlate (p = 0.81, r = -0.03) with the residuals of regressing aftereffects on ACT, even if ACT was a significant predictor of aftereffects (p < 0.001). The

VIF score between the simulated PAS scores and PSC was still low (vif = 1.11). We also repeated this analysis the other way around and generated simulated ACT scores instead.

getPASResidByFakeACTCorrelation()

```
##
## Call:
## glm(formula = RAE ~ PAS)
## Deviance Residuals:
                         Median
        Min
                   1Q
                                                Max
## -11.8236
              -4.0634
                        -0.2784
                                   3.7385
                                            10.8567
##
## Coefficients:
               Estimate Std. Error t value Pr(>|t|)
##
                           0.67956
                                     9.416 5.7e-15 ***
## (Intercept) 6.39900
                           0.09128 -3.486 0.000768 ***
## PAS
               -0.31817
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## (Dispersion parameter for gaussian family taken to be 26.19)
##
##
       Null deviance: 2622.9 on 89
                                     degrees of freedom
## Residual deviance: 2304.7 on 88 degrees of freedom
## AIC: 553.27
##
## Number of Fisher Scoring iterations: 2
##
##
##
   Pearson's product-moment correlation
##
## data: mod1_Res and ACT
## t = 0.64729, df = 88, p-value = 0.5191
## alternative hypothesis: true correlation is not equal to 0
## 95 percent confidence interval:
   -0.1402526 0.2720508
## sample estimates:
##
          cor
## 0.06883793
##
##
     Variables
                    VIF
## 1
     fake_act 1.100108
## 2
           PSQ 1.100108
```

We found that the simulated ACT scores do not significantly correlate (p = 0.92, r = 0.01) with the residuals of regressing aftereffects on PAS, even if PAS was a significant predictor of aftereffects (p < 0.001). The VIF score between the simulated ACT scores and PSC was still low (vif = 1.08).

Another simple check is to show that ACT and PAS VIF scores are high, as these are considered to be collinear. This is exactly what we found (vif = 3.37), as shown below.

getActPasCollinearity()

```
## Variables VIF
```

```
## 1 act_loc 3.369193
## 2 pas_loc 3.369193
```

Given the low VIF score we found for predictions and proprioception, but high VIF score for ACT and PAS, we are certain that the VIF score informs uf about the collinearity of these variables. However, it is trivial in its ability to show the independence of predictions from proprioception. Thus, the residual analyses on the previous section above is more informative in showing that these two predictors are independently contributing to reach aftereffects.