# Variational Methods for Latent Variable Problems (part 2)

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Massachusetts Institute of Technology

#### **Outline**

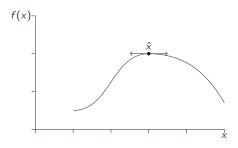
#### Outline for today:

- What counts as variational inference?
- Kullback-Leibler (KL) divergence and "standard" variational inference
- The classical EM algorithm as a special case of variational inference
- Variational inference as a generalization of the EM algorithm
- Some examples of VI in practice

Lots of very different procedures go by the name "variational inference." I propose an (idosyncratic) enompassing definition based on the use cases and the name:

#### Variational inference is inference using optimization.

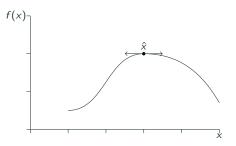
Think "calculus of variations:" an optimum  $\hat{x} = \operatorname*{argmax}_{\theta} f(x)$  is characterized by  $df/dx|_{\hat{x}} = 0$ , i.e. where small variations in  $\hat{x}$  result in no changes to the value of  $f(\hat{x})$ .



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Exercise: By this definition, which of these are VI?

- The maximum likelihood estimator (MLE).
- The Laplace approximation to a Bayesian posterior.
- Markov chain Monte Carlo (MCMC).

A more common definition of VI is the following.

Suppose we have a random variable  $\xi$  and a distribution  $\mathfrak{p}(\xi)$  that we want to know.

Let y denote data and  $\theta$  a parameter. Examples:

- The variable is  $\theta$ , and we wish to know the posterior  $\mathfrak{p}(\theta|y)$  (Bayes)
- The variable is y, and we wish to know  $\mathfrak{p}(y)$  (MLE)
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Let Q be some class of distributions which may or may not contain  $\mathfrak{p}(\xi)$ .

Variational inference finds the distribution in  $\mathcal Q$  closest to  $\mathfrak p$  according to some measure of "divergence" between distributions:

$$\mathfrak{q}^* = \operatorname*{argmin}_{\mathfrak{q} \in \mathcal{Q}} D(\mathfrak{q}, \mathfrak{p}).$$

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The most common choice of "divergence" is the **Kullback-Leibler** (KL) divergence, though other choices are possible (e.g. Li and Turner [2016], Liu and Wang [2016], Ambrogioni et al. [2018]).

#### KL divergence

The KL divergence is defined as:

$$\mathrm{KL}\left(\mathfrak{q}||\mathfrak{p}\right) := \underset{\mathfrak{q}(\xi)}{\mathbb{E}}\left[\log\mathfrak{q}(\xi)\right] - \underset{\mathfrak{q}(\xi)}{\mathbb{E}}\left[\log\mathfrak{p}(\xi)\right]$$

Some key attributes of KL divergence:

- $\mathrm{KL}\left(\mathfrak{q}||\mathfrak{p}\right) \geq 0$
- $\mathrm{KL}\left(\mathfrak{q}||\mathfrak{p}\right)=0\Rightarrow\mathfrak{p}=\mathfrak{q}$
- $\mathrm{KL}\left(\mathfrak{q}||\mathfrak{p}\right) \neq \mathrm{KL}\left(\mathfrak{p}||\mathfrak{q}\right)$
- $\bullet \ \mathrm{KL}\left(\mathfrak{q}||\mathfrak{p}\right)$  is a "strict" measure of closeness [Gibbs and Su, 2002]

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**Phony answer:** The KL divergence has an information theoretic interpretation [Kullback and Leibler, 1951].

Real answer: Mathematical convenience (normalizing constants pop out).

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**Example: The MLE minimizes KL divergence.** Suppose that  $x_n \stackrel{iid}{\sim} \mathfrak{p}(\cdot)$ , and  $\mathfrak{q}(\cdot|\theta) \in \mathcal{Q}$  is a (possibly misspecified) parameteric family of data distributions. Then

$$\begin{split} \underset{\theta}{\operatorname{argmin}} \operatorname{KL}\left(\mathfrak{p}||\mathfrak{q}\right) &= \underset{\theta}{\operatorname{argmin}} \ \left(-\underset{\mathfrak{p}(x_1)}{\mathbb{E}} \left[\log \mathfrak{q}(x_1|\theta)\right] + \underset{\mathfrak{p}(x_1)}{\mathbb{E}} \left[\log \mathfrak{p}(x_1)\right]\right) \\ &= \underset{\theta}{\operatorname{argmax}} \ \underset{\mathfrak{p}(x_1)}{\mathbb{E}} \left[\log \mathfrak{q}(x_1|\theta)\right] \approx \underset{\theta}{\operatorname{argmax}} \ \frac{1}{N} \sum_{n=1}^{N} \log \mathfrak{q}(x_n|\theta) = \hat{\theta} \ (\text{the MLE}). \end{split}$$

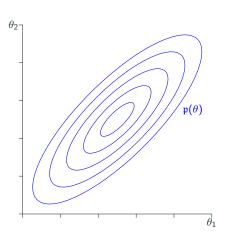
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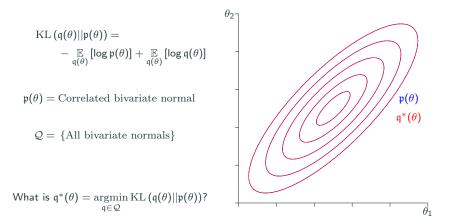
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 $\mathfrak{p}(\theta) = \text{Correlated bivariate normal}$ 

 $\mathcal{Q} = \, \{ \text{All bivariate normals} \}$ 

What is  $q^*(\theta) = \operatorname*{argmin}_{q \in \mathcal{Q}} \mathrm{KL}\left(q(\theta)||p(\theta)\right)$ ?





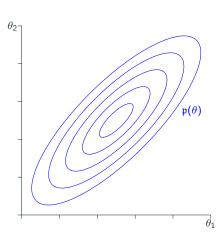
Sufficiently expressive families recover the target distribution.

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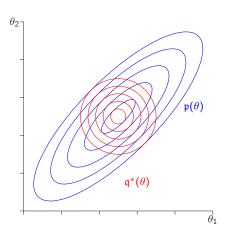


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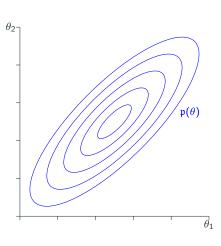
KL minimizers "fit inside" the second argument.

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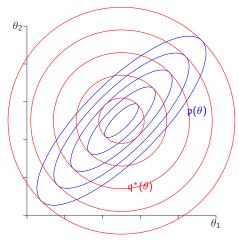


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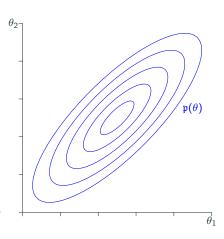
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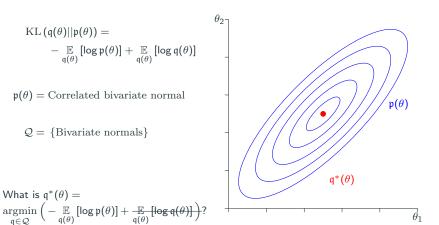
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 $\mathcal{Q} = \, \{ \text{Bivariate normals} \}$ 

What is 
$$q^*(\theta) = \underset{q \in \mathcal{Q}}{\operatorname{argmin}} \left( - \underset{q(\theta)}{\mathbb{E}} [\log \mathfrak{p}(\theta)] + \underset{q(\theta)}{\overline{\mathbb{E}}} [\log q(\theta)] \right)?$$





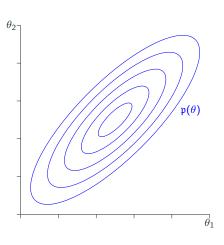
Without the entropy, the KL minimizer concentrates on the maximum of  $\log \mathfrak{p}(\theta)$ .

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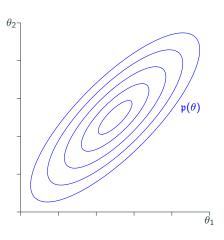
Without  $\log \mathfrak{p}(\theta)\text{, the KL minimizer is infinitely dispersed.}$ 

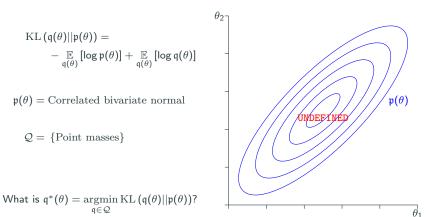
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$$\mathcal{Q} = \{ \text{Point masses} \}$$

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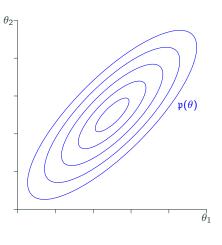
Without a common dominating measure, the KL divergence is undefined.

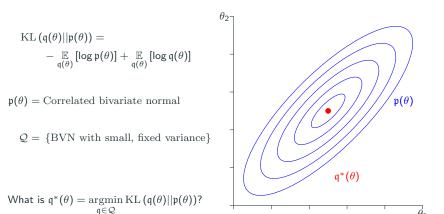
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 $\mathcal{Q} = \{ \text{BVN with small, fixed variance} \}$ 

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Sufficently concentrated distributions with constant entropy act like a point mass at the maximum of  $\log \mathfrak{p}(\theta)$ .

```
Observations: y = (y_1, ..., y_N)
Unknown latent variables: z = (z_1, ..., z_N)
```

Unknown global parameter:  $\theta \in \mathbb{R}^D$ . We want:  $\hat{\theta} = \underset{\theta}{\operatorname{argmax}} \log p(y|\theta)$ .

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The EM algorithm alternates between two steps. Starting at an iterate  $\hat{\theta}_{(i)}$ , repeat until convergence:

The E-step: Compute 
$$Q_{(i)}(\theta) := \underset{p(z|y,\hat{\theta}_{(i)})}{\mathbb{E}} [\log p(y|\theta,z) + \log p(z|\theta)]$$

The M-step: Compute the next iterate  $\hat{ heta}_{(i+1)} := \operatorname*{argmax}_{ heta} \mathcal{Q}_{(i)}( heta)$ 

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The EM algorithm works / is useful when:

- The joint log probability  $\log p(y|\theta,z) + \log p(z|\theta)$  is easy to write down
- The posterior  $p(z|y,\theta)$  is easy to compute
- The marginalizing integral  $p(y|\theta) = \int p(y|\theta,z)p(z|\theta)dz$  is hard

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Is the EM algorithm VI?

Can you spot the lie?

Let  $\mathcal{Q}_z$  denote a family of distributions on z, parameterized by a finite-dimensional parameter  $\eta$ , such that  $p(z|\theta,y) \in \mathcal{Q}_z$  for the observed y and all  $\theta$ .

**Exercise:** When does  $Q_z$  exist? (Indexed by a finite-dimensional parameter  $\eta$ .)

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Let 
$$q(z|\hat{\eta}(\theta)) := p(z|\theta, y)$$
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In an abuse of notation, write  $\eta \in \mathcal{Q}_z$  for  $\eta \in \{\eta : \mathfrak{q}(z|\eta) \in \mathcal{Q}_z\}$ .

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Then:

$$\begin{split} \log p(y|\theta) &= \log p(y|\theta) + \mathrm{KL}\left(\mathfrak{q}(z|\hat{\eta}(\theta))||p(z|\theta,y)\right) \\ &= \log p(y|\theta) + \operatorname*{argmax}_{\eta \in \mathcal{Q}_z} \left( -\mathrm{KL}\left(\mathfrak{q}(z|\eta)||p(z|\theta,y)\right) \right) \\ &= \operatorname*{argmax}_{\eta \in \mathcal{Q}_z} \left( \log p(y|\theta) - \mathrm{KL}\left(\mathfrak{q}(z|\eta)||p(z|\theta,y)\right) \right) \\ &= \operatorname*{argmax}_{\eta \in \mathcal{Q}_z} \left( \log p(y|\theta) + \underset{\mathfrak{q}(z|\eta)}{\mathbb{E}} \left[ \log p(z|\theta,y) - \log \mathfrak{q}(z|\eta) \right] \right) \\ &= \operatorname*{argmax}_{\eta \in \mathcal{Q}_z} \left( \underset{\mathfrak{q}(z|\eta)}{\mathbb{E}} \left[ \log p(y|\theta) \log p(z|\theta,y) - \log \mathfrak{q}(z|\eta) \right] \right) \\ &= \operatorname*{argmax}_{\eta \in \mathcal{Q}_z} \left( \underset{\mathfrak{q}(z|\eta)}{\mathbb{E}} \left[ \log p(y,z|\theta) \right] + \underset{\mathfrak{q}(z|\eta)}{\mathbb{E}} \left[ \log \mathfrak{q}(z|\eta) \right] \right) \end{split}$$

From the previous slide, the marginal MLE is given by

$$\begin{split} \hat{\theta} &:= \underset{\theta}{\operatorname{argmax}} \log p(y|\theta) \\ &= \underset{\eta \in \mathcal{Q}_z}{\operatorname{argmax}} \left( \log p(y|\theta) - \operatorname{KL} \left( \mathfrak{q}(z|\eta) || p(z|\theta, y) \right) \right) \\ &= \underset{\theta}{\operatorname{argmax}} \underset{\eta \in \mathcal{Q}_z}{\operatorname{argmax}} \left( \underset{\mathfrak{q}(z|\eta)}{\mathbb{E}} \left[ \log p(y, z|\theta) \right] + \underset{\mathfrak{q}(z|\eta)}{\mathbb{E}} \left[ \log \mathfrak{q}(z|\eta) \right] \right) \end{split}$$

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The EM algorithm revisited. Starting at an iterate  $\hat{\theta}_{(i)}$ :

#### The E-step:

- 1. For a fixed  $\hat{\theta}_{(i)}$ , optimize  $\bigstar$  for  $\eta$ . Since only the KL divergence depends on  $\eta$ , the optimum is  $\hat{\eta}(\hat{\theta}_{(i)})$ , and  $\mathfrak{q}(z|\hat{\eta}(\hat{\theta}_{(i)})) = p(z|\hat{\theta}_{(i)},y)$ .
- 2. Then use  $\hat{\eta}(\hat{\theta}_{(i)})$  to compute the expectation in  $\bigstar \bigstar$  as a function of  $\theta$ .

The M-step: Keeping  $\eta$  fixed at  $\hat{\eta}(\hat{\theta}_{(i)})$ ), optimize  $\bigstar \bigstar$  as a function of  $\theta$  to give  $\hat{\theta}_{i+1}$ . The entropy  $\underset{\mathfrak{q}(z|\eta)}{\mathbb{E}}[\log \mathfrak{q}(z|\eta)]$  does not depend on  $\theta$  and can be ignored.

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The EM algorithm revisited. Starting at an iterate  $\hat{\theta}_{(i)}$ :

#### The E-step:

- 1. For a fixed  $\hat{\theta}_{(i)}$ , optimize  $\bigstar$  for  $\eta$ . Since only the KL divergence depends on  $\eta$ , the optimum is  $\hat{\eta}(\hat{\theta}_{(i)})$ , and  $\mathfrak{q}(z|\hat{\eta}(\hat{\theta}_{(i)})) = p(z|\hat{\theta}_{(i)},y)$ .
- 2. Then use  $\hat{\eta}(\hat{\theta}_{(i)})$  to compute the expectation in  $\bigstar \bigstar$  as a function of  $\theta$ .

**The M-step:** Keeping  $\eta$  fixed at  $\hat{\eta}(\hat{\theta}_{(i)})$ ), optimize  $\bigstar \bigstar$  as a function of  $\theta$  to give  $\hat{\theta}_{i+1}$ . The entropy  $\underset{\mathfrak{q}(z|\eta)}{\mathbb{E}} [\log \mathfrak{q}(z|\eta)]$  does not depend on  $\theta$  and can be ignored.

⇒ The EM algorithm is coordinate ascent on the objective

$$f(\theta, \eta) = \log p(y|\theta) - \mathrm{KL} \left( \mathfrak{q}(z|\eta) || p(z|\theta, y) \right).$$

$$\hat{\theta}, \hat{\eta} := \underset{\theta, \eta \in \mathcal{Q}_z}{\operatorname{argmax}} \left( \log p(y|\theta) - \operatorname{KL} \left( \mathfrak{q}(z|\eta) || p(z|\theta, y) \right) \right).$$

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#### Corollaries:

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- If  $p(z|\theta,y)$  is intractable, we can now consider different approximating families which may not contain  $p(z|\theta,y)$ .

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**Exercise:** Recall that the Neyman-Scott paradox disappears when, instead of pairs, we have many observations, all from the same  $z_n$ . Can you use the VI perspective on the marginal EM algorithm to explain this phenomenon?

Let  $\mathcal{Q}^{pm}_{\theta}$  denote a family of constant-entropy near-point mass distributions on  $\theta$ , located at some free parameter  $\vartheta$ . Assume a uniform prior on  $\theta$ .

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$$\begin{aligned} & \underset{\theta, \eta \in \mathcal{Q}_z}{\operatorname{argmax}} \left( \log p(y|\theta) - \operatorname{KL} \left( \mathfrak{q}(z|\eta) || p(z|\theta, y) \right) \right) \\ &= \underset{\theta \in \mathcal{Q}_\theta^{pm}, \eta \in \mathcal{Q}_z}{\operatorname{argmax}} \left( \underset{\mathfrak{q}(\theta|\vartheta)}{\mathbb{E}} \left[ \log p(y|\theta) \right] - \underset{\mathfrak{q}(\theta|\vartheta)}{\mathbb{E}} \left[ \log \mathfrak{q}(\theta|\vartheta) \right] - \operatorname{KL} \left( \mathfrak{q}(z|\eta) || p(z|\theta, y) \right) \right) \\ &= \underset{\theta \in \mathcal{Q}_\theta^{pm}, \eta \in \mathcal{Q}_z}{\operatorname{argmax}} \operatorname{KL} \left( \mathfrak{q}(\theta|\vartheta) \mathfrak{q}(z|\eta) || \log p(z, \theta|y) \right). \end{aligned}$$

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**Exercise:** Under what circumstances is  $p(\theta|y)$  is approximately a point mass?

Suppose we can't compute  $p(z|\theta,y)$  and / or we think that  $p(\theta|y)$  may not be well-approximated by a point mass.

Choose some tractable approximating family  $q(\theta, z|\gamma) \in \mathcal{Q}_{\theta z}$ . Then find

$$\hat{\gamma} := \operatorname*{argmin}_{\gamma \in \mathcal{Q}_{\theta z}} \mathrm{KL} \left( \mathfrak{q}(\theta, z | \gamma) || p(\theta, z | y) \right).$$

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#### Now we're doing "Variational Bayes" (VB).

The EM algorithm — and, indeed, the MLE — can be understood as Variational Bayes with a uniform prior and particular choices of approximating distributions.

Some common approximating families:

- Factorizing families, e.g.  $\mathfrak{q}(\theta,z|\gamma)=\mathfrak{q}(\theta|\gamma)\mathfrak{q}(z|\gamma)$ . These families model some components of the posterior as independent.
  - For historical reasons, this is known as a mean-field approximation.
- Factorizing families + an exponential family assumption.
- Normal approximations (possibly after an invertible unconstraining transformation):  $q(\theta, z|\gamma) = \mathcal{N}(\theta, z|\gamma)$ .
- Independent normal approximations. This is used by a lot of "black-box VI" methods [Ranganath et al., 2014, Kucukelbir et al., 2017].

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What do you need from an approximating family? Expressivity, plus:

$$\mathrm{KL}\left(\mathfrak{q}||\mathfrak{p}\right) := \underbrace{\mathbb{E}_{\mathfrak{q}(\xi|\eta)}[\log\mathfrak{q}(\xi|\eta)]}_{\mathrm{Tractable\ entropy}} \quad - \quad \underbrace{\mathbb{E}_{\mathfrak{q}(\xi|\eta)}[\log\mathfrak{p}(\xi)]}_{\mathrm{Tractable\ expectations}}$$

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- Factorizing families + an exponential family assumption.
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- Monte Carlo is often used for the expectations.
  - See, e.g., Ranganath et al. [2014].
- The entropy is harder. In general, there is a tradeoff between expressivity and tractable entropy.
  - "Normalizing flows" are an example of a highly expressive approximating family (neural nets!) designed to maintain a tractable entropy. [Rezende and Mohamed, 2015]

As an example application of VB, consider a logistic regression with random effects fit (generalized linear mixed model) to an internet advertising dataset from Criteo Labs with N=61895 datapoints [Giordano et al., 2018, Section 5.3].

We want to estimate:

 $\beta$ : Regression parameters (5-dimensional)

u: Random effects (5000-dimensional)

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We use the following VB approximation:

$$\begin{split} q\left(\beta_{k}\right) &= \mathcal{N}\left(\beta_{k}; \eta_{\beta_{k}}\right), \text{ for } k = 1, ..., K_{x} \\ q\left(u_{t}\right) &= \mathcal{N}\left(u_{t}; \eta_{u_{t}}\right), \text{ for } t = 1, ..., T \\ q\left(\tau\right) &= \operatorname{Gamma}\left(\tau; \eta_{\tau}\right) \\ q\left(\mu\right) &= \mathcal{N}\left(\mu; \eta_{\mu}\right) \\ q\left(\theta\right) &= q\left(\tau\right) q\left(\mu\right) \prod_{t=1}^{K_{x}} q\left(\beta_{k}\right) \prod_{t=1}^{T} q\left(u_{t}\right). \end{split}$$

We will compare the joint MAP ( $\approx$  MLE), MCMC, and the VB approximation.

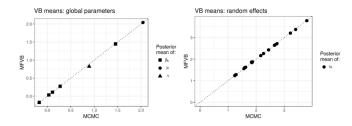


Figure 13: Comparison of MCMC and MFVB means

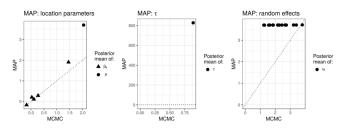
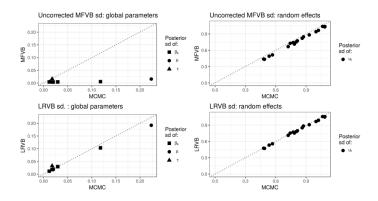


Figure 14: Comparison of MCMC and Laplace means



Note that standard mean-field VB under-estimates posterior covariances. We have a paper about alleviating this problem using "linear response." [Giordano et al., 2018]

The Hessian was singular at the MAP, so the Laplace approximation could not be computed.



VB is slower than the MAP, but much faster than MCMC.

Method	Seconds
MAP (optimum only)	12
VB (optimum only)	57
VB (including sensitivity for $\beta$ )	104
VB (including sensitivity for $\beta$ and $u$ )	553
MCMC (Stan)	21066

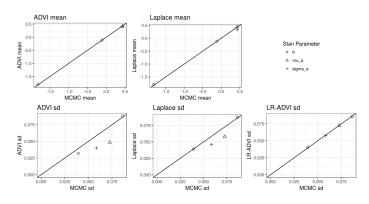


Figure 7: Election model

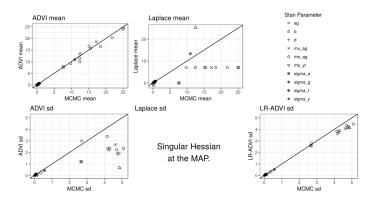


Figure 8: Sesame Street model

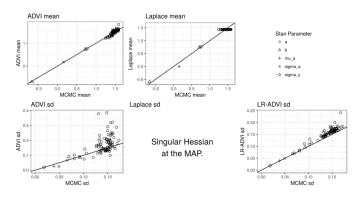


Figure 9: Radon model

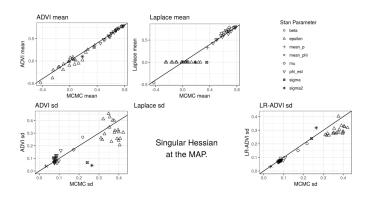


Figure 10: Ecology model

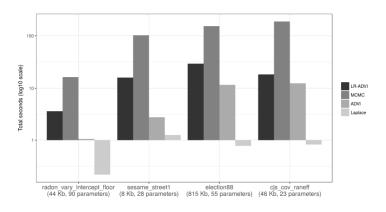


Figure 11: Comparision of timing in ADVI experiments

#### Conclusion

- Variational inference can be thought of as approximate marginalization using optimization.
- Not only is variational inference closely related to familiar existing frequentist methods (like the EM algorithm), it can help us understand those methods better.
- The key to a good variational approximation is tractable expectations, tractable entropy, and expressivity.
- It is important to be aware of variational inference's shortcomings (e.g., underestimation of variance in the mean field approximation).
- There are a zillion topics to work on in variational inference. A good place to start reading is Blei et al. [2017].

#### Thanks for having me!

#### **Conclusions**

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