

An Automatic Finite-Sample Robustness Metric: Can Dropping a Little Data Make a Big Difference?



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Job talk 2021

Dropping data: Motivation

You're a data analyst, and you've

- Gathered some exchangeable data,
- Cleaned up / removed outliers,
- Checked for correct specification, and
- Drawn a conclusion from your statistical analysis
(e.g., based the sign / significance of some estimated parameter).

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Well done!

Would you be concerned if you could **reverse your conclusion** by removing a **small proportion** (say, 0.1%) of your data?

Dropping data: Mexico Microcredit

Consider β , a randomized controlled trial study of the efficacy of microcredit in Mexico based on 16,560 data points.

The variable “Beta” estimates the effect of microcredit in US dollars.

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Question: Is the reported interval $-4.55 \pm (5.88)$ a reasonable description of the uncertainty in the estimated efficacy of microcredit?

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...but sometimes, surely yes.

For example, often in economics:

- Small fractions of data are missing not-at-random,
- Policy population is different from analyzed population,
- We report a convenient summary (e.g. mean) of a complex effect,
- Models are stylized proxies of reality.

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Question 1: How do we find influential datapoints?

The number of subsets $\binom{N}{\lfloor \alpha N \rfloor}$ can be very large even when α is very small.

In the MX microcredit study, $\binom{16560}{15} \approx 1.4 \cdot 10^{51}$ sets to check for $\alpha = 0.0009$.

We provide a fast, automatic approximation based on the **influence function**.

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Question 2: What makes an estimator non-robust?

Non-robustness to removal of $\lfloor \alpha N \rfloor$ points is:

- Not (necessarily) caused by misspecification.
- Not (necessarily) caused by outliers.
- Not captured by standard errors.
- Not mitigated by large N .
- Primarily determined by the **signal to noise** ratio
... in a sense which we will define.

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- We provide deterministic error bounds for small α .
- We show the accuracy in simple experiments.
- We show the accuracy in a number of real-world experiments.

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Conclusion: Related work and future directions

Question 1:

How do we find influential datapoints?

Which estimators do we study?

We study “Z-estimators,” i.e., roots of estimating equations.

Suppose we have N data points d_1, \dots, d_N . Then:

$$\hat{\theta} := \vec{\theta} \text{ such that } \sum_{n=1}^N G(\vec{\theta}, d_n) = 0_P.$$

Examples: all minimizers of empirical loss (OLS, MLE, VB), and more.

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$$\phi(\vec{\theta}) = \vec{\theta}_p$$

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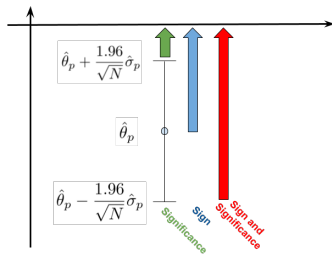
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Can we reverse our conclusion by dropping $\lfloor \alpha N \rfloor$ datapoints? \Leftrightarrow

Is there a \vec{w} , with $\lfloor \alpha N \rfloor$ zeros, such that $\phi(\hat{\theta}(\vec{w})) - \phi(\hat{\theta}) \geq \Delta$?

Hard! Evaluating $\hat{\theta}(\vec{w})$ is costly and lots of \vec{w} have $\lfloor \alpha N \rfloor$ zeros.

Taylor series approximation.

Is there a \vec{w} , with $\lfloor \alpha N \rfloor$ zeros, such that $\phi(\hat{\theta}(\vec{w})) - \phi(\hat{\theta}) \geq \Delta$?

To simplify the search over \vec{w} , we form the Taylor series approximation:

$$\phi(\hat{\theta}(\vec{w})) - \phi(\hat{\theta}) \approx \phi^{\text{lin}}(\vec{w}) - \phi(\hat{\theta}) := - \sum_{n: \vec{w}_n=0} \psi_n, \text{ where } \psi_n := \left. \frac{\partial \phi(\hat{\theta}(\vec{w}))}{\partial \vec{w}_n} \right|_{\vec{1}}.$$

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The values ψ_n are the “**empirical influence function.**” (?)

The ψ_n can be **easily and automatically** computed from $\hat{\theta}$.

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Easy! The most influential points for $\phi^{\text{lin}}(\vec{w})$ have the most negative ψ_n .

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- 5 **Optional:** Compute $\hat{\theta}(\vec{w}^*)$, and verify that $\Delta \leq \phi(\hat{\theta}(\vec{w}^*)) - \phi(\hat{\theta})$.

Computing the influence function.

How to compute $\psi_n := \left. \frac{\partial \phi(\hat{\theta}(\vec{w}))}{\partial \vec{w}_n} \right|_{\vec{1}}$? Recall $\sum_{n=1}^N \vec{w}_n G(\hat{\theta}(\vec{w}), d_n) = 0_P$.

Step zero: Implement software to compute $G(\theta, d_n)$ and $\phi(\theta)$. Find $\hat{\theta}$.

Step one: By the chain rule, $\psi_n = \left. \frac{\partial \phi(\hat{\theta}(\vec{w}))}{\partial \vec{w}_n} \right|_{\vec{1}} = \left. \frac{\partial \phi(\theta)}{\partial \theta^T} \right|_{\hat{\theta}} \left. \frac{\partial \hat{\theta}(\vec{w})}{\partial \vec{w}_n} \right|_{\vec{1}}$.

Step two: By the implicit function theorem:

$$\left. \frac{\partial \hat{\theta}(\vec{w})}{\partial \vec{w}_n} \right|_{\vec{1}} = \left(\sum_{n=1}^N \left. \frac{\partial}{\partial \theta^T} G(\vec{\theta}, d_n) \right|_{\hat{\theta}} \right)^{-1} G(\hat{\theta}, d_n).$$

Step three: Use *automatic differentiation* on $G(\theta, d_n)$ and $\phi(\theta)$ from step zero to compute $\left. \frac{\partial \phi(\theta)}{\partial \theta^T} \right|_{\hat{\theta}}$ and $\left. \frac{\partial}{\partial \theta^T} G(\vec{\theta}, d_n) \right|_{\hat{\theta}}$. Put the pieces together.

-
- The user does step zero. The rest is automatic.
 - The primary computational expense is the Hessian inverse.

Question 2:

What makes an estimator non-robust?

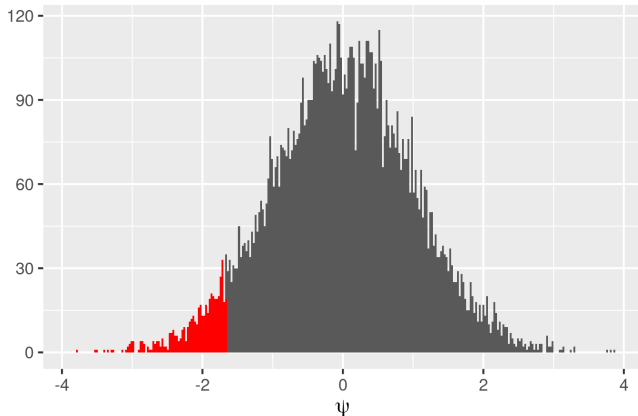
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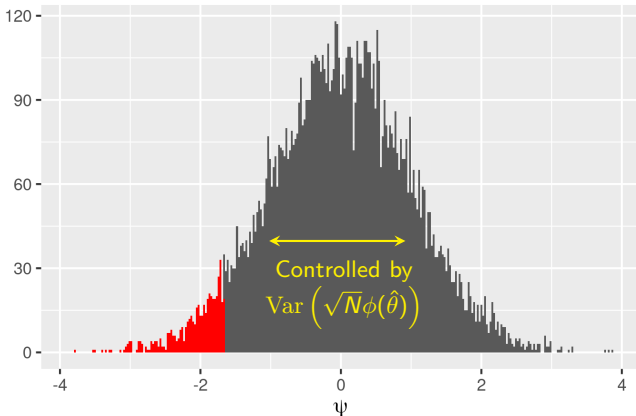
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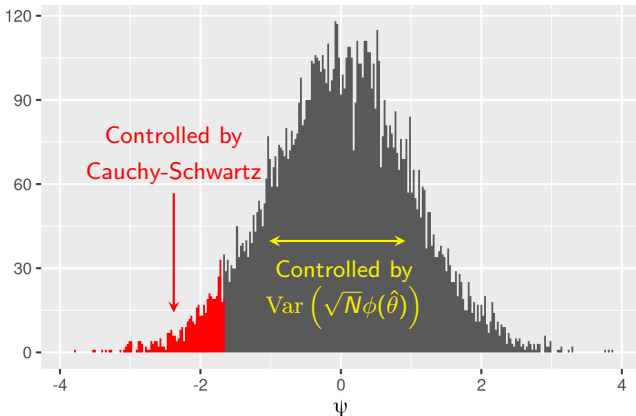
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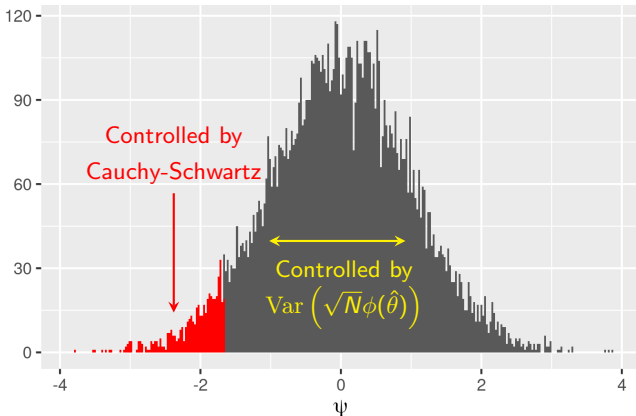
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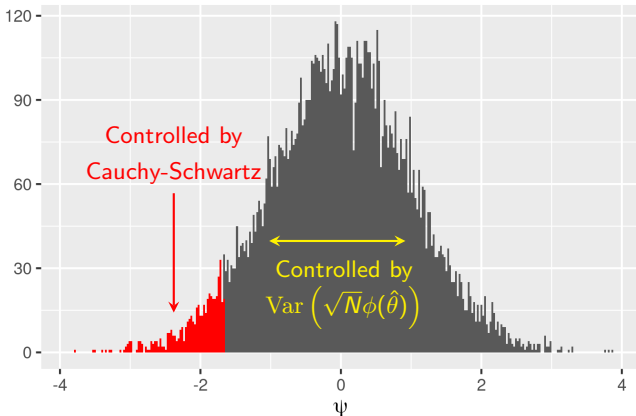


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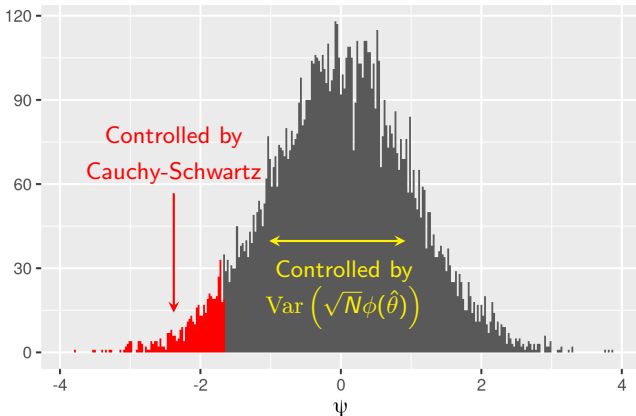


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- The “shape” $\hat{\Gamma}_\alpha \leq \sqrt{\alpha(1-\alpha)}$ and converges to a nonzero constant

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Recall that standard errors reject when $\frac{\Delta}{\hat{\sigma}_\phi} \leq \frac{1.96}{\sqrt{N}}$.

Corollary: Leave- $\lfloor \alpha N \rfloor$ -out is different from standard errors.

Leave- α -out robustness does not vanish as $N \rightarrow \infty$.

Leave- α -out is different from standard errors.

Insignificance is always non-robust.

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- Robustness to removing a $\lfloor \alpha N \rfloor$ datapoints is principally determined by the signal to noise ratio, does not disappear asymptotically, and is distinct from (and typically larger than) standard errors.
- Robustness to removing a $\lfloor \alpha N \rfloor$ datapoints is easy to check! We can quickly and automatically find an approximate influential set which is accurate for small α .

Links and references

Tamara Broderick, Ryan Giordano, Rachael Meager (alphabetical authors)
“An Automatic Finite-Sample Robustness Metric: Can Dropping a Little Data Change Conclusions?”

<https://arxiv.org/abs/2011.14999>

See the paper for applications to:

- Hierarchical meta-analysis of microcredit (?)
- Cash transfers randomized controlled trial (?)
- Oregon Medicaid experiment (?)
- Expository simulations

zaminfluence: R package with leave- α -out robustness for OLS and IV estimators

<https://github.com/rgiordan/zaminfluence>

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