Locally Equivalent Weights for Bayesian MrP

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- 1. Assume your initial model was accurate
- 2. Select some perturbation your model should be able to capture
- 3. Use local sensitivity to detect whether the change is what you expect
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Checks of this form can recover generalized versions of many standard diagnostics for linear models.

Regression bias:

$$\begin{aligned} y &= \theta^\mathsf{T} \mathbf{x} + \varepsilon \\ \tilde{y} &= (\theta + \delta)^\mathsf{T} \mathbf{x} + \varepsilon \\ \hat{\theta}(y) &= \hat{\theta}(\tilde{y}) + \delta \end{aligned}$$

Regression residual exogeneity:

$$\tilde{y} = y + \varepsilon z$$
$$\hat{\theta}(y) = \hat{\theta}(\tilde{y})$$

Regression fisher information:

 $\mathcal{I}:=$ Fisher information

 $\Sigma :=$ Score covariance

$$\mathcal{I}^{-1} = \Sigma$$

General models "bias check"

$$\begin{aligned} y &= f(\mathbf{x}, \varepsilon, \theta) \\ \tilde{y} &= f(\mathbf{x}, \varepsilon, \theta + \delta) \\ \hat{\theta}(y) &\stackrel{\text{check}}{=} \hat{\theta}(\tilde{y}) + \delta \end{aligned}$$

General models "exogeneity check":

$$y \sim \mathcal{P}(y|\mathbf{x})$$
 and $\mathcal{P}(\mathbf{x}) = w$
$$\tilde{w} = w + \delta$$

$$\hat{\theta}(\tilde{w}) \stackrel{\text{check}}{=} \hat{\theta}(w)$$

General models "information check":

 $y \sim \mathcal{P}(y|\theta)$

 $\tilde{y} \sim$ Importance sample using \tilde{w} where

$$\tilde{w} = \frac{\mathcal{P}(y|\hat{\theta} + \delta)}{\mathcal{P}(y|\hat{\theta})}$$

$$\hat{\theta}(\tilde{w}) \stackrel{\text{check}}{=} \hat{\theta}(1) + \delta$$

Student contributions and ongoing work:

- · Vladimir Palmin is working on extending MrPlew to lme4
- Sequoia Andrade is working on generalizing to other local sensitivity checks
- · Lucas Schwengber is working on novel flow-based techniques for local sensitivity
- (Currently recruiting!) Doubly–robust Bayesian Hierarchical MrP



Vladimir Palmin



Seguoia Andrade



Lucas Schwengber

Preprint and R package (hopefully) coming soon!

References i