

# **An Automatic Finite-Sample Robustness Metric: Can Dropping a Little Data Make a Big Difference?**

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# Dropping data: Motivation

More data & cheaper computation  $\Rightarrow$

Statistical analyses are playing larger roles in decision making.

Decisions are important: We want **trustworthy** conclusions.

Data / models not always perfect: We want **robust** conclusions.

Would you be concerned if you could **reverse your conclusion** by removing a **small proportion** (say, 0.1%) of your data?

**Running example:** Angelucci et al. [2015], a randomized controlled trial study of the efficacy of microcredit based on 16,560 data points.

We can reverse the studies qualitative conclusions by removing 15 observations ( $< 0.1\%$  of the data).

**How do we find sets of influential points?** Difficult in general!

We provide a **automatic approximation** with finite-sample guarantees.

Studying the approximation reveals the causes of non-robustness.

# Dropping data: Mexico Microcredit

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Original result	-4.55 (5.88)

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## **The culprit is signal to noise ratio.**

By the end of the talk, we will see that the sensitivity is due to

- High variability of the outcome (household profit) relative to
- A small signal driving the conclusion (statistical significance)



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Would you be concerned if you could **reverse your conclusion** by removing a **small proportion** (say, 0.1%) of your data?

Not always! But sometimes, surely yes.

Thinking without random noise can be helpful.

Suppose you have a farm, and want to know whether your average yield is greater than 170 bushels per acre. At harvest, you measure 200 bushels per acre.

- Scenario one: If your yield is greater than 170 bushels per acre, you make a profit.
  - Don't care about sensitivity to small subsets
- Scenario two: You want to recommend your farming methods to a friend across the valley.
  - Might care about sensitivity to small subsets

For example, often in economics:

- Small fractions of data are missing not-at-random,
- Policy population is different from analyzed population,
- We report a convenient summary (e.g. mean) of a complex effect,
- Models are stylized proxies of reality.

# **Question 1:**

## **How do we find influential datapoints?**

# Which estimators do we study?

**Z-estimators.** Suppose we have  $N$  data points  $\vec{d} = d_1, \dots, d_N$ . Then:

$$\hat{\theta} := \vec{\theta} \text{ such that } \sum_{n=1}^N G(\vec{\theta}, d_n) = 0_P.$$

**Examples:** MLE, OLS, VB, &c (all minimizers of smooth empirical loss).

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**Function of interest.** Qualitative decision based on  $\phi(\hat{\theta}) \in \mathbb{R}$ . E.g.:

- A particular component:  $\phi(\theta) = \theta_d$
- The end of a confidence interval:  $\phi(\theta) = \theta_d + \frac{1.96}{\sqrt{N}} \hat{\sigma}(\hat{\theta})$

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Fix a proportion  $0 < \alpha \ll 1$  of points to drop and find a set  $\mathcal{S} \subset \{1, \dots, N\}$  with  $|\mathcal{S}| \leq \lfloor \alpha N \rfloor$  that extremizes  $\phi(\hat{\theta})$  when dropped.

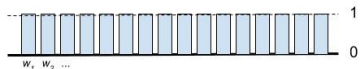
- **Problem:** There are many sets with  $|\mathcal{S}| \leq \lfloor \alpha N \rfloor$ .
  - E.g., in Angelucci et al. [2015],  $\binom{16,560}{15} \approx 1.5 \cdot 10^{51}$
- **Problem:** Evaluating  $\phi(\hat{\theta}(\vec{d}_{-\mathcal{S}}))$  requires an estimation problem.
  - E.g., in Angelucci et al. [2015] computing the OLS estimator.
  - Other examples are even harder (VB, machine learning)

**An approximation is needed!**

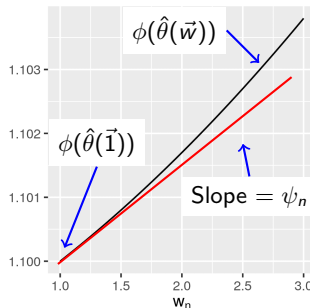
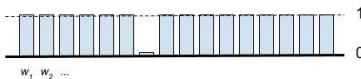
# Which estimators do we study?

$$\hat{\theta} := \vec{\theta} \text{ such that } \sum_{n=1}^N G(\vec{\theta}, d_n) = 0_P.$$

Original weights:  $\vec{1} = (1, \dots, 1)$



Leave points out by setting their elements of  $\vec{w}$  to zero.



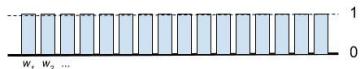
The slopes  $\psi_n := \left. \frac{\partial \phi(\hat{\theta}(\vec{w}))}{\partial w_n} \right|_{\vec{1}}$  are values of the **empirical influence function** [Hampel, 1986]. We call them “influence scores.”

Second-order derivatives control the error of the linear approximation.

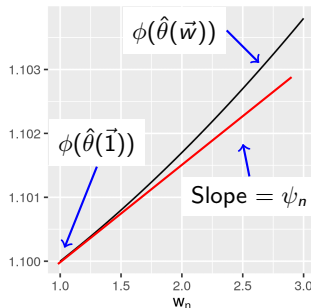
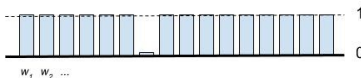
# Which estimators do we study?

$$\hat{\theta}(\vec{w}) := \vec{\theta} \text{ such that } \sum_{n=1}^N \vec{w}_n G(\vec{\theta}, d_n) = 0_P.$$

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# Taylor series approximation.

**Problem:** How large can you make  $\phi(\hat{\theta}(\vec{w}))$  leaving out no more than  $\lfloor \alpha N \rfloor$  points? **Combinatorially hard!**

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To simplify the search over  $\vec{w}$ , we form the Taylor series approximation:

$$\phi(\hat{\theta}(\vec{w})) \approx \phi^{\text{lin}}(\vec{w}) := \phi(\hat{\theta}(\vec{1})) + \sum_{n=1}^N \psi_n(\vec{w}_n - 1)$$

**Approximate solution:** How large can you make  $\phi^{\text{lin}}(\vec{w})$  leaving out no more than  $\lfloor \alpha N \rfloor$  points? **Easy!**

The most influential points for  $\phi^{\text{lin}}(\vec{w})$  have the most negative  $\psi_n$ .

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We provide **finite-sample theory** showing that

$$\left| \phi(\hat{\theta}(\vec{w})) - \phi^{\text{lin}}(\vec{w}) \right| = O \left( \left\| \frac{1}{N}(\vec{w} - \vec{1}) \right\|_2^2 \right) = O(\alpha) \text{ as } \alpha \rightarrow 0.$$

## How to compute the influence scores $\psi_n$ ?

By the chain rule,  $\psi_n = \left. \frac{\partial \phi(\hat{\theta}(\vec{w}))}{\partial \vec{w}_n} \right|_{\vec{1}} = \left. \frac{d\phi(\theta)}{d\theta^T} \right|_{\hat{\theta}} \left. \frac{\partial \hat{\theta}(\vec{w})}{\partial \vec{w}_n} \right|_{\vec{1}}.$

Recall that  $\hat{\theta}(\vec{w}) := \vec{\theta}$  such that  $\sum_{n=1}^N \vec{w}_n G(\vec{\theta}, d_n) = 0_P.$

The **implicit function theorem** expresses  $\left. \frac{\partial \hat{\theta}(\vec{w})}{\partial \vec{w}_n} \right|_{\vec{1}}$  as a linear system.

Computation of  $\psi_n$  is fully automatable from a software implementation of  $G(\cdot, \cdot)$  and  $\phi(\cdot)$  with **automatic differentiation** [Baydin et al., 2017].



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- 6 **Optional:** Compute  $\hat{\theta}(\vec{w}^*)$ , and verify that  $\phi(\hat{\theta}(\vec{w}^*)) - \phi(\hat{\theta}) \geq \Delta$ .

## **Question 2:**

**What makes an estimator non-robust?**



# Question 3:

## When is our approximation accurate?

## **Conclusion: Related work and future directions**

Tamara Broderick, Ryan Giordano, Rachael Meager (alphabetical authors)  
“An Automatic Finite-Sample Robustness Metric: Can Dropping a Little Data Change Conclusions?”

<https://arxiv.org/abs/2011.14999>

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- A. Baydin, B. Pearlmutter, A. Radul, and J. Siskind. Automatic differentiation in machine learning: A survey. *The Journal of Machine Learning Research*, 18(1):5595–5637, 2017.
- F. Hampel. *Robust statistics: The approach based on influence functions*, volume 196. Wiley-Interscience, 1986.