# An Automatic Finite-Sample Robustness Metric: Can Dropping a Little Data Make a Big Difference?

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### Dropping data: Motivation

More data & cheaper computation  $\Rightarrow$  Statistical analyses are playing larger roles in decision making.

Decisions are important: We want **trustworthy** conclusions. Data / models not always perfect: We want **robust** conclusions.

Would you be concerned if you could **reverse your conclusion** by removing a **small proportion** (say, 0.1%) of your data?

**Running example:** Angelucci et al. [2015], a randomized controlled trial study of the efficacy of microcredit based on 16,560 data points. We can reverse the studies qualitative conclusions by removing 15 observations (< 0.1% of the data).

How do we find sets of influential points? Difficult in general!

We provide a automatic approximation with finite-sample guarantees.

Studying the approximation reveals the causes of non-robustness.

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#### The culprit is signal to noise ratio.

By the end of the talk, we will see that the sensitivity is due to

- High variability of the outcome (hosehold profit) relative to
- A small signal driving the conclusion (statistical significance)

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Would you be concerned if you could **reverse your conclusion** by removing a **small proportion** (say, 0.1%) of your data? Not always! But sometimes, surely yes.

Thinking without random noise can be helpful.

Suppose you have a farm, and want to know whether your average yield is greater than 170 bushels per acre. At harvest, you measure 200 bushels per acre.

- Scenario one: If your yield is greater than 170 bushels per acre, you
  make a profit.
  - Don't care about sensitivity to small subsets
- Scenario two: You want to recommend your farming methods to a friend across the valley.
  - Might care about sensitivity to small subsets

#### For example, often in economics:

- Small fractions of data are missing not-at-random,
- Policy population is different from analyzed population,
- We report a convenient summary (e.g. mean) of a complex effect,
- Models are stylized proxies of reality.

#### Question 1:

How do we find influential datapoints?

# Which estimators do we study?

**Z-estimators.** Suppose we have N data points  $\vec{d} = d_1, \dots, d_N$ . Then:

$$\hat{\theta} := \vec{\theta} \text{ such that } \sum_{n=1}^{N} G(\vec{\theta}, d_n) = 0_P.$$

Examples: MLE, OLS, VB, &c (all minimizers of smooth empirical loss).

Function of interest. Qualitative decision based on  $\phi(\hat{\theta}) \in \mathbb{R}$ . E.g.:

- A particular component:  $\phi(\theta) = \theta_d$
- The end of a confidence interval:  $\phi(\theta) = \theta_d + \frac{1.96}{\sqrt{N}}\hat{\sigma}(\hat{\theta})$

Fix a proportion  $0 < \alpha \ll 1$  of points to drop and find a set  $\mathcal{S} \subset \{1, \dots N\}$  with  $|\mathcal{S}| \leq \lfloor \alpha N \rfloor$  that extremizes  $\phi(\hat{\theta})$  when dropped.

- **Problem:** There are many sets with  $|\mathcal{S}| \leq \lfloor \alpha N \rfloor$ . • E.g., in Angelucci et al. [2015],  $\binom{16,560}{15} \approx 1.5 \cdot 10^{51}$
- ullet Problem: Evaluating  $\phi(\hat{ heta}(ec{d}_{-\mathcal{S}}))$  requires an estimation problem.
  - E.g., in Angelucci et al. [2015] computing the OLS estimator.
  - Other examples are even harder (VB, machine learning)

#### An approximation is needed!

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### Which estimators do we study?

Suppose we have N data points  $d_1, \ldots, d_N$ . Then:

$$\hat{\theta}(\vec{w}) := \vec{\theta}$$
 such that  $\sum_{n=1}^{N} \vec{w}_n G(\vec{\theta}, d_n) = 0_P$ .

Leave points out by setting their elements of  $\vec{w}$  to zero.

Is there a  $\vec{w}$ , with  $\lfloor \alpha N \rfloor$  zeros, such that  $\phi(\hat{\theta}(\vec{w})) - \phi(\hat{\theta}) \geq \Delta$ ?

To simplify the search over  $\vec{w}$ , we form the Taylor series approximation:

$$\phi(\hat{\theta}(\vec{w})) - \phi(\hat{\theta}) \approx \phi^{\text{lin}}(\vec{w}) - \phi(\hat{\theta}) := -\sum_{n:\vec{w}_n = 0} \psi_n, \text{ where } \psi_n := \left. \frac{\partial \phi(\hat{\theta}(\vec{w}))}{\partial \vec{w}_n} \right|_{\vec{1}}.$$

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The values  $\psi_n$  are the "empirical influence function." [?] The  $\psi_n$  can be easily and automatically computed from  $\hat{\theta}$ . The approximation is typically accurate for small  $\alpha$ .

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**Easy!** The most influential points for  $\phi^{\text{lin}}(\vec{w})$  have the most negative  $\psi_n$ .

#### Procedure:

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- Report non-robustness if  $\Delta \leq \phi^{\text{lin}}(\vec{w}^*) \phi(\hat{\theta}) = -\sum_{n=1}^{\lfloor \alpha N \rfloor} \psi_{(n)}$ .

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- **5 Optional:** Compute  $\hat{\theta}(\vec{w}^*)$ , and verify that  $\Delta \leq \phi(\hat{\theta}(\vec{w}^*)) \phi(\hat{\theta})$ .

# Computing the influence function.

How to compute  $\psi_n := \frac{\partial \phi(\hat{\theta}(\vec{w}))}{\partial \vec{w}_n}\Big|_{\vec{1}}$ ? Recall  $\sum_{n=1}^N \vec{w}_n G(\hat{\theta}(\vec{w}), d_n) = 0_P$ .

**Step zero:** Implement software to compute  $G(\theta, d_n)$  and  $\phi(\theta)$ . Find  $\hat{\theta}$ .

**Step one:** By the chain rule,  $\psi_n = \frac{\partial \phi(\hat{\theta}(\vec{w}))}{\partial \vec{w}_n}\Big|_{\vec{1}} = \frac{\mathrm{d}\phi(\theta)}{\mathrm{d}\theta^T}\Big|_{\hat{\theta}} \frac{\partial \hat{\theta}(\vec{w})}{\partial \vec{w}_n}\Big|_{\vec{1}}.$ 

**Step two:** By the implicit function theorem:

$$\left. \frac{\partial \hat{\theta}(\vec{w})}{\partial \vec{w}_n} \right|_{\vec{1}} = \frac{1}{N} \left( \frac{1}{N} \sum_{n'=1}^{N} \frac{\partial}{\partial \theta^T} G(\vec{\theta}, d_{n'}) \right|_{\hat{\theta}} \right)^{-1} G(\hat{\theta}, d_n).$$

**Step three:** Use automatic differentiation on  $\phi(\theta)$  and  $G(\theta, d_n)$  from step zero to compute  $\frac{\partial \phi(\theta)}{\partial \theta^T}$  and  $\frac{\partial}{\partial \theta^T}G(\vec{\theta}, d_n)$ .

- The user does step zero. The rest is automatic.
- The primary computational expense is the Hessian inverse.
- Automatic differentiation is the chain rule applied to a program.
- Typically  $\psi_n = O(N^{-1})$ .

#### **Question 2:**

What makes an estimator non-robust?

**Question 3:** 

When is our approximation accurate?

Conclusion: Related work and future directions

#### Links and references

Tamara Broderick, Ryan Giordano, Rachael Meager (alphabetical authors) "An Automatic Finite-Sample Robustness Metric: Can Dropping a Little Data Change Conclusions?"

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M. Angelucci, D. Karlan, and J. Zinman. Microcredit impacts: Evidence from a randomized microcredit program placement experiment by Compartamos Banco. American Economic Journal: Applied Economics, 7(1):151–82, 2015.