

# Locally Equivalent Weights for Bayesian MrP

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# What are we weighting for?<sup>1</sup>

$$\text{Target average response} = \frac{1}{N_T} \sum_{j=1}^{N_T} y_j \approx \frac{1}{N_S} \sum_{i=1}^{N_S} w_i y_i = \text{Weighted survey average response}$$

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$$\frac{1}{N_T} \sum_{j=1}^{N_T} \mathbf{x}_j = \frac{1}{N_S} \sum_{i=1}^{N_S} w_i \mathbf{x}_i$$

Such weights satisfy “covariate balance” for  $\mathbf{x}$ .

You can check covariate balance for any calibration weighting estimator, and any function  $f(\mathbf{x})$ .

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You can check covariate balance for any calibration weighting estimator, and any function  $f(\mathbf{x})$ .

Even more, covariate balance is the criterion for a popular class of calibration weight estimators:

## Raking calibration weights

“Raking” selects weights that

- Are as “close as possible” to some reference weights
- Under the constraint that they balance some selected regressors.

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## Balance checks as sensitivity analysis

One reason to balance  $f(\mathbf{x})$  is because we think  $\mathbb{E}[y|\mathbf{x}]$  might plausibly vary  $\propto f(\mathbf{x})$ , and want to check whether our estimator can capture this variability.

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### Balance-informed sensitivity check (BISC) (informal)

Pick a small  $\delta > 0$  and an  $f(\cdot)$ . Define a *new response variable*  $\tilde{y}$  such that

$$\mathbb{E}[\tilde{y}|\mathbf{x}] = \mathbb{E}[y|\mathbf{x}] + \delta f(\mathbf{x}).$$

We know the change this is supposed to induce in the target population.

Covariate balance checks whether our estimators produce the same change.

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We know the expected change this perturbation produces in the target distribution:

$$\mathbb{E}[\mu(\tilde{y}) - \mu(y)|\mathbf{x}] = \frac{1}{N_T} \sum_{j=1}^{N_T} (\mathbb{E}[\tilde{y}|\mathbf{x}_j] - \mathbb{E}[y|\mathbf{x}_j]) = \delta \frac{1}{N_T} \sum_{j=1}^{N_T} f(\mathbf{x}_j)$$

Then, check whether your estimator  $\hat{\mu}(\cdot)$  produces the same change for observed  $\tilde{y}, y$ :

$$\underbrace{\hat{\mu}(\tilde{y}) - \hat{\mu}(y)}_{\substack{\text{Replace weighted averages} \\ \text{with changes in an estimator}}} \stackrel{\text{check}}{\approx} \delta \frac{1}{N_T} \sum_{j=1}^{N_T} f(\mathbf{x}_j).$$

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When  $\hat{\mu}(\cdot) = \hat{\mu}_{\text{CW}}(\cdot)$ , BISC recovers the standard covariate balance check.

We will use  $\hat{\mu}(\cdot) = \hat{\mu}_{\text{MRP}}(\cdot)$ .



Suppose I have  $\tilde{y}$  such that  $\mathbb{E} [\tilde{y}|\mathbf{x}] = \mathbb{E} [y|\mathbf{x}] + \delta f(\mathbf{x})$ .

Now I need to evaluate  $\hat{\mu}_{\text{MrP}}(\tilde{y}) - \hat{\mu}_{\text{MrP}}(y)$ .

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**Problem:**  $\hat{\mu}_{\text{MrP}}(\cdot)$  is computed with MCMC.

- Each MCMC run typically takes hours, and
- Output is noisy, and  $\hat{\mu}_{\text{MrP}}(\tilde{y}) - \hat{\mu}_{\text{MrP}}(y)$  may be small.

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## MrP Local Equivalent Weights (MrPlew)

Form the first-order Taylor series approximation

$$\hat{\mu}_{\text{MrP}}(\tilde{y}) - \hat{\mu}_{\text{MrP}}(y) \approx \sum_{i=1}^{N_S} w_i^{\text{MrP}} (\tilde{y}_i - y_i) \quad \text{where} \quad w_i^{\text{MrP}} := \frac{d}{dy_i} \hat{\mu}_{\text{MrP}}(y).$$

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**Computation:** The weights are given by weighted averages of posterior covariances<sup>2</sup>.

They can be easily computed with standard software<sup>3</sup> **without re-running MCMC**.

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<sup>2</sup>G., Broderick, and Jordan 2018.

<sup>3</sup>We use `brms` (Bürkner 2017).

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**Use in BISC:** For a wide set of judiciously chosen  $f(\cdot)$ , check

$$\delta \sum_{i=1}^{N_S} w_i^{\text{MrP}} f(\mathbf{x}_i) \stackrel{\text{check}}{\approx} \delta \frac{1}{N_T} \sum_{j=1}^{N_T} f(\mathbf{x}_j).$$

- We have defined BISC in terms of  $\tilde{y}$  such that  $\mathbb{E} [\tilde{y}|\mathbf{x}] = \mathbb{E} [y|\mathbf{x}] + \delta f(\mathbf{x})$
- We have approximated  $\hat{\mu}_{\text{MrP}}(\tilde{y}) - \hat{\mu}_{\text{MrP}}(y)$  for  $\tilde{y} \approx y$

How to get such a  $\tilde{y}$ ? **Recall  $y$  is binary!** Two approaches:

**Option 1:** Force  $\tilde{y}$  to be binary.

1. Make some guess  $\hat{m}(\mathbf{x}) \approx \mathbb{E} [y|\mathbf{x}]$ 
  - E.g. Posterior mean, or
  - Shrunk posterior mean, or
  - Some values that gives the same posterior
2. Take  $u_n \stackrel{iid}{\sim} \text{Unif}(0, 1)$
3. Assume  $y_n = \mathbb{I}(u_n \leq \hat{m}(\mathbf{x}_n))$
4. Draw  $u_n | y_n$
5. Set  $\tilde{y}_n = \mathbb{I}(u_n \leq \hat{m}(\mathbf{x}_n) + \delta \mathbf{x}_n)$

**Option 2:** Allow  $\tilde{y}$  to take generic values.

1. Set  $\tilde{y}_n = y_n + \delta f(\mathbf{x}_n)$ .

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  - Realistic
  - Have to pick  $\hat{m}(\mathbf{x})$
  - $\tilde{Y} - Y_S$  not infinitesimally small
  - **Sanity check for theory**

**Option 2:** Allow  $\tilde{y}$  to take generic values.

1. Set  $\tilde{y}_n = y_n + \delta f(\mathbf{x}_n)$ .
  - Not realistic
  - No additional assumptions
  - $\tilde{Y} - Y_S$  may be infinitesimally small
  - **Use for theory**

## BISC Theorem: (sketch)

Take  $\tilde{y}_n = y_n + \delta f(\mathbf{x}_n)$ .

We state conditions for Bayesian hierarchical logistic regression under which

$$\left| \hat{\mu}_{\text{MrP}}(Y_S) - \hat{\mu}_{\text{MrP}}(Y_S) - \delta \sum_{i=1}^{N_S} w_i^{\text{MrP}} f(\mathbf{x}_i) \right| = \text{Small?}$$

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<sup>2</sup>Donsker with uniformly bounded  $\mathbb{E} [\mathbf{x} f(\mathbf{x})]$ .

<sup>3</sup>G. and Broderick 2024; Kasprzak, G., and Broderick 2025.



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For a very broad class<sup>2</sup> of  $\mathcal{F}$ .

**Uniformity justifies searching for “imabanced”  $f$ .**

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## Uniformity justifies searching for “imabanced” $f$ .

The uniformity result builds on our earlier work on uniform and finite-sample error bounds for Bernstein–von Mises theorem–like results<sup>3</sup>.

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<sup>3</sup>G. and Broderick 2024; Kasprzak, G., and Broderick 2025.

# Real Data: Marital Name Change Survey

Analysis of changing names after marriage<sup>4</sup>.

- **Target population:** ACS survey of US population 2017–2022<sup>5</sup>
- **Survey population:** Marital Name Change Survey (from Twitter)<sup>6</sup>
- **Respose:** Did the female partner keep their name after marriage?
- For regressors, use bins of age, education, state, and decade married.

Survey observations:  $N_S = 4,364$

Target observations (rows):  $N_T = 4,085,282$

Uncorrected survey mean:  $\frac{1}{N_S} \sum_{i=1}^{N_S} y_i = 0.462$

Raking:  $\hat{\mu}_{CW} = 0.263$

MrP:  $\hat{\mu}_{MrP} = 0.288$  (Post. sd = 0.0169)

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<sup>4</sup>Based on Alexander (2019).

<sup>5</sup>Ruggles et al. 2024.

<sup>6</sup>Cohen 2019.

## Covariate balance for primary effects

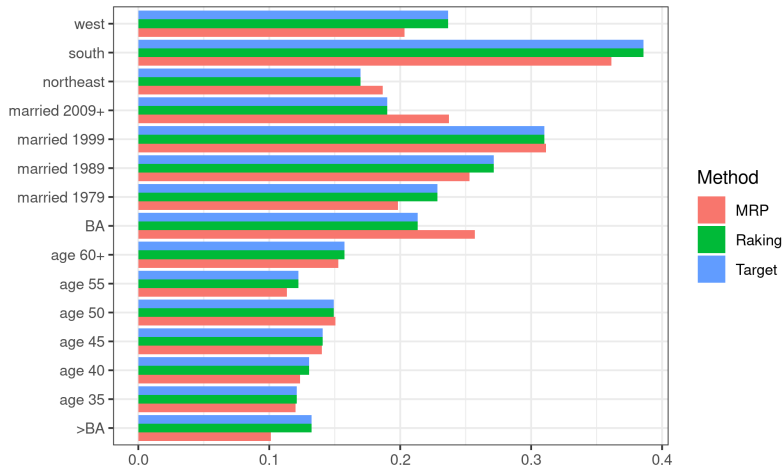


Figure 1: Imbalance plot for primary effects

## Covariate balance for interaction effects

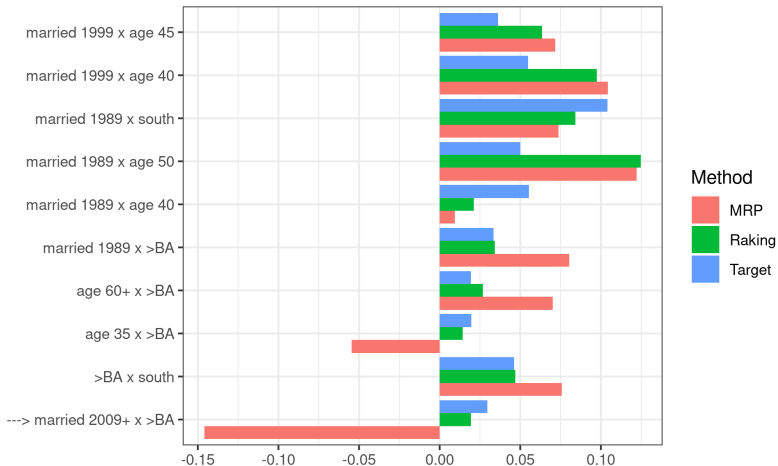
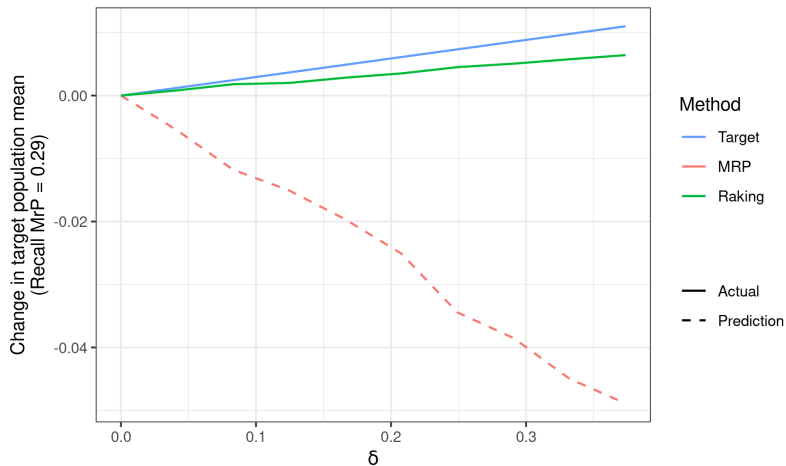


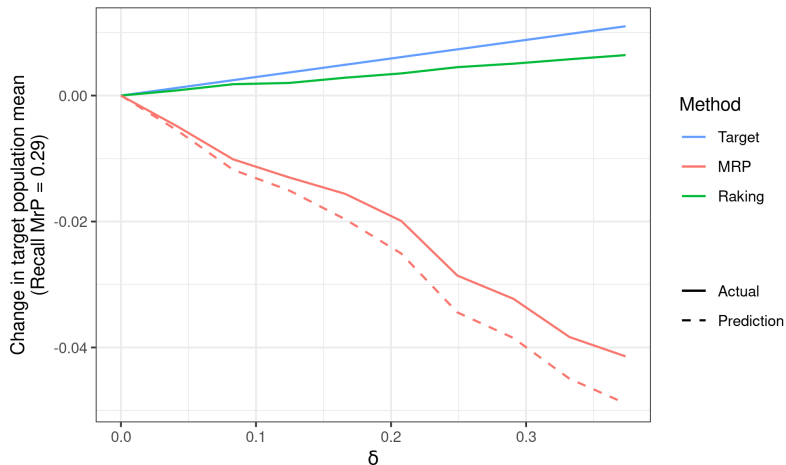
Figure 2: Imbalance plot for select interaction effects



**Figure 3:** Predictions for the name change dataset



## Predictions and actual MCMC results



**Figure 4:** Predictions and refit for the name change dataset

Running ten MCMC refits: 10 hours    Computing approximate weights: 16 seconds

Analysis of national support for gay marriage.<sup>7</sup>

- **Target population:** US Census Public Use Microdata Sample 2000
- **Survey population:** Combined national-level polls from 2004
- **Response:** “Do you favor allowing gay and lesbian couples to marry legally?”
- For regressors, use race, gender, age, education, state, region, and continuous statewide religion and political characteristics, including some analyst–selected interactions.

Survey observations:  $N_S = 6,341$

Target observations (rows):  $N_T = 9,694,541$

Uncorrected survey mean:  $\frac{1}{N_S} \sum_{i=1}^{N_S} y_i = 0.333$

Raking:  $\hat{\mu}_{\text{CW}} = 0.33$

MrP:  $\hat{\mu}_{\text{MrP}} = 0.337$  (Post. sd = 0.039)

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<sup>7</sup>Based on Kastellec, Lax, and Phillips (2010), see also Lax and Phillips (2009).

## Covariate balance for primary effects

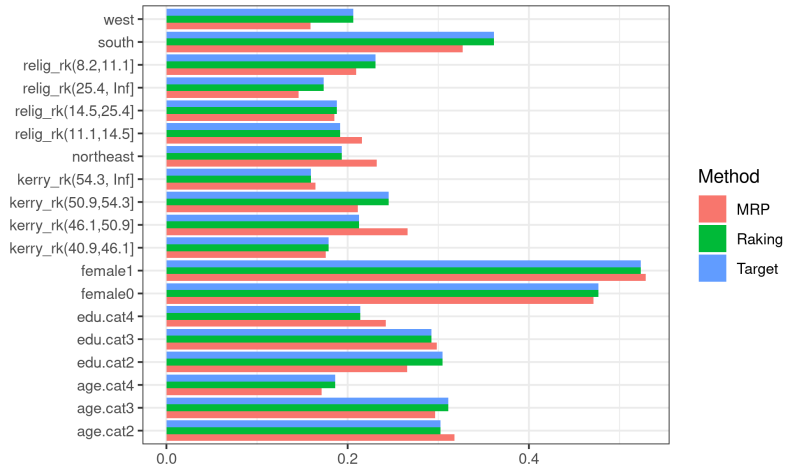


Figure 5: Imbalance plot for primary effects

## Covariate balance for interaction effects

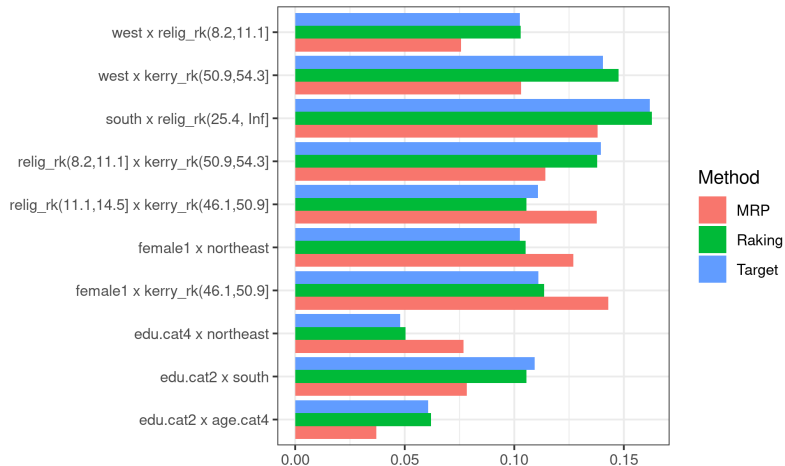
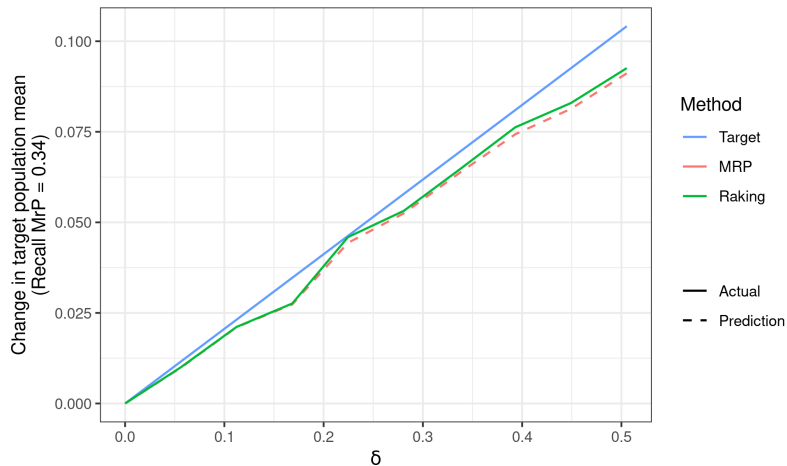
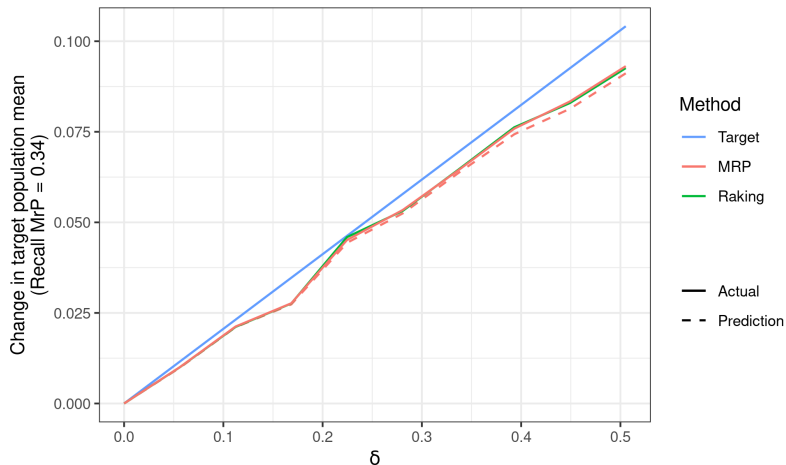


Figure 6: Imbalance plot for select interaction effects



**Figure 7:** Predictions for the gay marriage dataset

## Predictions and actual MCMC results



**Figure 8:** Predictions and refit for the gay marriage dataset

Running ten MCMC refits: 11 hours    Computing approximate weights: 23 seconds

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