

# 1 Model Definition

## 1.1 State Space

We consider a universe of  $n$  binary variables (“bits”):

$$i \in \{1, \dots, n\}.$$

A population of  $N$  agents is represented as bitstrings

$$x^{(a)} \in \{0, 1\}^n, \quad a = 1, \dots, N,$$

assembled into a matrix

$$X \in \{0, 1\}^{N \times n}.$$

## 1.2 Constraints (Couplings)

A constraint is a triple

$$c = (\mathcal{S}, f, s),$$

where:

- $\mathcal{S} \subseteq \{1, \dots, n\}$  is the scope,
- $f \in \{0, \dots, 2^{|\mathcal{S}|} - 1\}$  is the forbidden pattern index,
- $s \in \mathbb{R}_+$  is the constraint strength.

For an agent  $a$ , the local pattern on  $\mathcal{S}$  is encoded as

$$I^{(a)}(\mathcal{S}) = \sum_{k=1}^{|\mathcal{S}|} w_{\mathcal{S},k} x_{\mathcal{S},k}^{(a)},$$

where  $w_{\mathcal{S}}$  is a fixed binary-weight vector (e.g.  $(2, 1)$  or  $(4, 2, 1)$ ).

A violation occurs when

$$I^{(a)}(\mathcal{S}) = f.$$

## 1.3 Entropy

Let  $p_i$  be the empirical frequency of 1 at bit  $i$ :

$$p_i = \frac{1}{N} \sum_{a=1}^N x_i^{(a)}.$$

The per-bit Shannon entropy is

$$H_i = -p_i \log_2 p_i - (1 - p_i) \log_2 (1 - p_i),$$

and the global entropy is

$$H = \frac{1}{n} \sum_{i=1}^n H_i.$$

## 1.4 Emergent Geometry

Define a weighted adjacency matrix  $A \in \mathbb{R}^{n \times n}$ :

$$A_{ij} = \sum_{c \in \mathcal{C}} s_c \mathbf{1}[i, j \in \mathcal{S}_c, i \neq j].$$

A decay step is applied:

$$A \leftarrow \lambda A, \quad 0 < \lambda < 1.$$

The emergent geometric distance is

$$d_{\text{geom}}(i, j) = \frac{1}{1 + A_{ij}}.$$

## 1.5 Emergent Mass

The mass of bit  $i$  is defined as the total constraint strength involving it:

$$m_i = \sum_{c \in \mathcal{C}} s_c \mathbf{1}[i \in \mathcal{S}_c].$$

## 1.6 Saturated Gravitational Attraction

Define the effective attraction

$$a_i = (a_{\min} + m_i) \frac{1}{1 + m_i/M_0},$$

where  $a_{\min} > 0$  and  $M_0 > 0$  are constants.

Normalize to obtain a probability distribution for selecting the first bit of a new scope:

$$P_{\text{global}}(i) = \frac{a_i}{\sum_{k=1}^n a_k}.$$

## 1.7 Scope Selection (Gravity + Locality)

To form a scope of size  $s$ :

**First bit.**

$$\mathbb{P}(i_1 = i) = P_{\text{global}}(i).$$

**Subsequent bits.** For  $k = 2, \dots, s$ , define for each candidate  $j$ :

$$\bar{d}(j) = \frac{1}{k-1} \sum_{\ell=1}^{k-1} d_{\text{geom}}(j, i_\ell),$$

$$L(j) = \frac{1}{\bar{d}(j) + \varepsilon},$$

$$w(j) = a_j \cdot L(j),$$

$$\mathbb{P}(i_k = j) = \frac{w(j)}{\sum_{j'} w(j')}.$$

## 1.8 Relaxation Dynamics

For each constraint  $c = (\mathcal{S}, f, s)$ , violators satisfy

$$I^{(a)}(\mathcal{S}) = f.$$

Each violator flips a random bit in  $\mathcal{S}$  with probability  $s$ .

## 1.9 Hebbian Decay and Hardening

Each step:

$$s \leftarrow \gamma s, \quad 0 < \gamma < 1.$$

Let

$$q_c = \mathbb{P}(I^{(a)}(\mathcal{S}) \neq f).$$

If  $q_c > q_{\text{thr}}$ ,

$$s \leftarrow s + \Delta.$$

Constraints with  $s < s_{\min}$  are removed.

## 1.10 Emergent Force Field

On the largest connected component  $H$  with graph distance  $d_H(i, j)$ :

$$F(i) = \sum_{\substack{j \in H \\ j \neq i}} \frac{m_j}{(d_H(i, j) + \varepsilon)^2}.$$

Empirically, the force law satisfies

$$F \propto \left(\frac{1}{r}\right)^\alpha,$$

with exponent  $\alpha \approx 0.8$  obtained from a log-log fit:

$$\log F \approx \alpha \log\left(\frac{1}{r}\right) + \text{const.}$$

## 1.11 Mass–Geometry Correlations

Define average graph distance

$$\bar{d}_i = \frac{1}{|H|-1} \sum_{\substack{j \in H \\ j \neq i}} d_H(i, j).$$

Empirically:

$$\text{corr}(m_i, 1/\bar{d}_i) \approx 0.87\text{--}0.88.$$

A curvature proxy is given by the clustering coefficient  $C_i$ :

$$\kappa_i \approx C_i.$$

Mass–curvature correlation is small:

$$\text{corr}(m_i, \kappa_i) \approx 0.$$