```
Inputs: k = 10, t_{max} = T and f(\mathbf{x}); set w = 0.05, c_1 = 0.05, c_2 = 0.05, c_3 = 0.05
0.05, c_4 = 0.20 and initialize parameters \mathbf{x_i}, \mathbf{v_i}
Outputs: Global best value
 t = 0,
 while t < t_{max}
   t \leftarrow t + 1
   Function evaluation step:
    Calculate the function f(\mathbf{x}) for \mathbf{x}_i
   Velocity update step:
    Randomly choose values for r_1, r_2, r_3, r_4 in the range '0' and '1'.
    Then update the velocity of each particle as in Eq (7).
   Position update step:
    Add updated velocity to existing position.
    Check constraint on the particles \mathbf{x}^T P_1 \mathbf{x} \leq 1.
    for m = 1 to k
     if \mathbf{x}_m^T P_1 \mathbf{x}_m > 1 then
       \mathbf{x}_m = \mathbf{x}_{mprev}
      end if
    end for
 end while
```