System	fri/desk	fr2/xyz	fr3/office	fr3/nst
DVO SlAM	0.021m	0.018m	0.035m	0.018m
RGB-D SLAM	0.02m	0.008m	0.032m	0.017m
MRSMap	0.043m	0.020m	0.042m	2.018m
Voxel Hashing	0.023m	0.022m	0.023m	0.087m
Kintinuous	0.037m	0.029m	0.030m	0.031m
Frame-to-model	0.022m	0.014m	0.025m	0.027m
Elastic Fusion	0.020m	0.011m	0.017m	0.016m
Bundle Fusion	0.016m	0.011m	0.022m	0.012m