

Configuration	
No. of Cameras in the ACS	2
No. of Joints in the ACS	1
Random transformations per test (n)	30
Number of tests	100
Input ($i = 1 \dots n$)	
Rotations of cameras ($\mathbf{R}_{AW}^i, \mathbf{R}_{BW}^i$)	$2 \times 30 \times 100$
Translations of cameras (T_{AW}^i, T_{BW}^i)	$2 \times 30 \times 100$
Zero Mean Gaussian noise:	
$0 \leq \sigma_{rot} \leq 2.4^\circ$ and $0 \leq \sigma_{trans} \leq 0.1meters$	
Output	
Mean error of joint pose estimation (see equation (??))	
STD error of joint pose estimation (see equation (??))	