Position	Name	Description
1	Frame number	Indicate at which frame the object is present
2	Identity number	Each pedestrian trajectory is identified by a unique ID (-1 for detec
3	Bounding box left	Coordinate of the top-left corner of the pedestrian bounding box
4	Bounding box top	Coordinate of the top-left corner of the pedestrian bounding box
5	Bounding box width	Width in pixels of the pedestrian bounding box
6	Bounding box height	Height in pixels of the pedestrian bounding box
7	Confidence score	Indicates how confident the detector is that this instance is a pede ground truth and results, it acts as a flag whether the entry is to be
8	x	3D x position of the pedestrian in real-world coordinates (-1 if not a
9	y	3D y position of the pedestrian in real-world coordinates (-1 if not a
10	z	3D z position of the pedestrian in real-world coordinates (-1 if not a