

<b>Observations</b>	<b>ITTI</b>	<b>GBVS</b>	<b>PFT</b>	<b>PQFT</b>	<b>ENT-CON</b>	<b>ENT-KLD</b>
<b>go_alone</b>	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000
<b>head_toward</b>	0.00146	0.04781	0.01294	0.02982	0.01619	0.02730
<b>go_away</b>	0.04952	0.02009	-0.03281	0.01635	-0.01624	-0.00526
<b>overtake</b>	0.04721	0.04149	0.01184	0.03407	0.00109	0.05625
<b>slow_down</b>	0.00996	0.02267	0.01569	0.04101	0.01768	0.05115
<b>follow_car</b>	0.01574	0.04859	0.00204	0.02750	-0.00926	-0.01375
<b>Mean</b>	0.02065	0.03011	0.00162	0.02479	0.00158	0.01928
<b>Variance</b>	0.00041	0.00031	0.00027	0.00018	0.00015	0.00075