

III: our method. (see section ??) M: manual measurement

Algorithm	Relative Rotation (Degree)		
	Roll	Pitch	Yaw
III	1.3182	88.4530	0.7315
M	0 ± 5	90 ± 5	0 ± 5

Algorithm	Relative Translation (mm)		
	T_x	T_y	T_z
III	291.3321	-17.2837	-292.1382
M	290 ± 20	0 ± 20	280 ± 20