

III: our method. (see section ??) F: using feature correspondences.

Algorithm	Relative Rotation (Degree)		
	Roll	Pitch	Yaw
III	17.7158	-11.3660	-80.1913
F	17.5459	-10.6024	-78.9854

Algorithm	Relative Translation (mm)		
	T_x	T_y	T_z
III	295.4183	-232.4576	34.5004
F	294.0235	-229.8369	28.9739