Actuation Model	Actuator Parameters
Target Joint Angles (PD)	proportional gains k_p, derivative gains k_d
Target Joint Velocities (Vel)	derivative gains k_d
Torques (Tor)	none
Muscle Activations (MTU)	optimal contractile element length, serial elastic element rest length, maximum isometric force, pennation, moment arm, maximum moment arm joint orientation, rest joint orientation.