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# SCIENTIFIC MACHINE LEARNING AND TENSORFLOW TUTORIAL

Introduction and TensorFlow basics

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Numerical PDEs: Analysis, Algorithms, and Data Challenges

**ICERM** 

**Brown University** 



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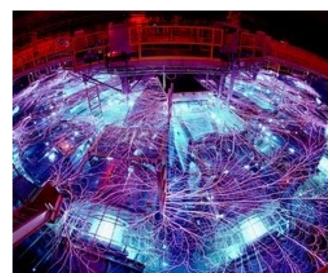
#### THE GOAL OF SCIENTIFIC MACHINE LEARNING









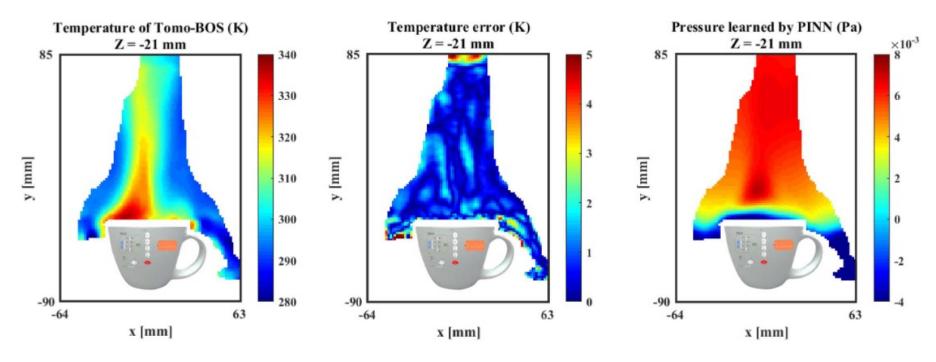


- Given experimental/high fidelity simulation data from a system,
- Find a mathematical model that describes the system
- Experiments/simulations generate noisy, biased, sparse data





#### PDE Inverse problems

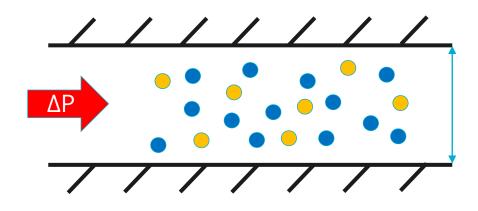


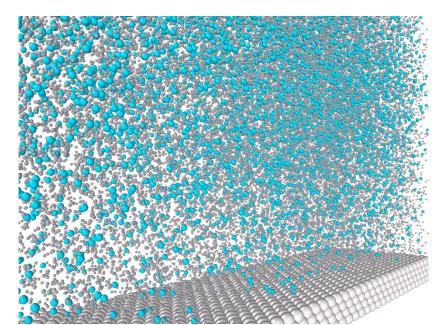
PINNs infers the Pressure of the flow over a coffee mug from Tomographic background oriented schlieren images S. Cai et al., *JFM* (2021)

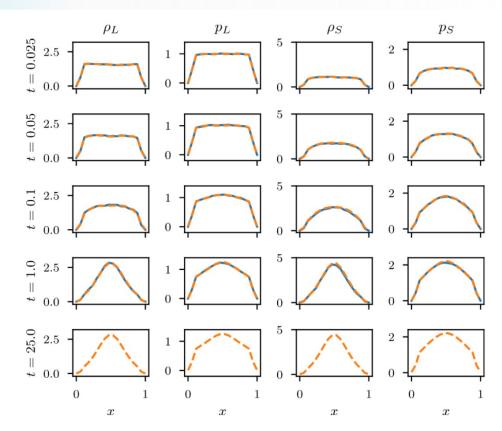




### Surrogate modeling





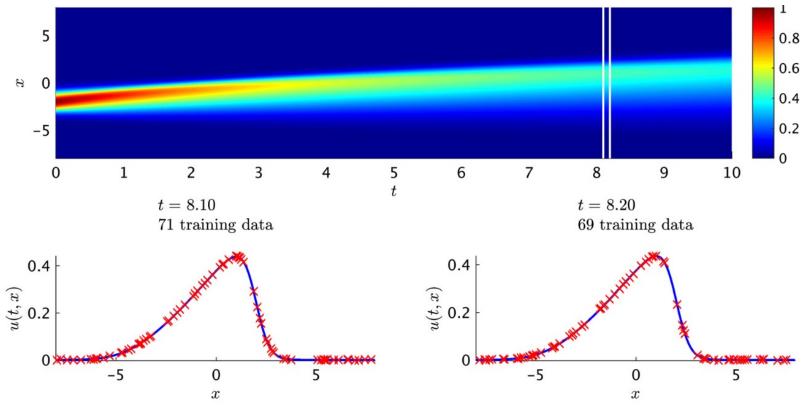


MOR-physics learns dynamics of colloidal system from molecular dynamics simulations R. Patel et al., *CMAME* (2021)





### System Identification

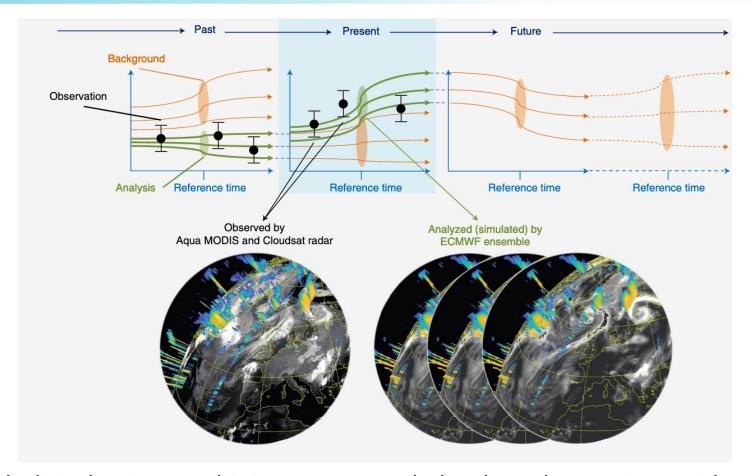


A Gaussian process is used to recover a PDE from data M. Raissi and G. Karniadakis, *JCP* (2018)





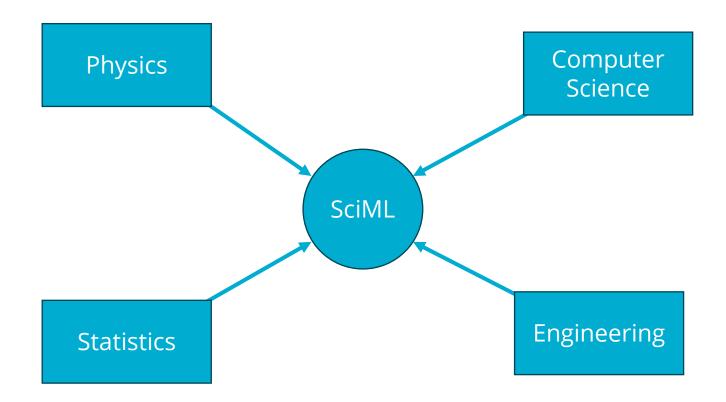
#### **Digital Twins**



An Earth digital twin - combining MODIS and Cloudsat observations with ECMWF simulations Bauer et al., *Nature Computational Science*, 2021

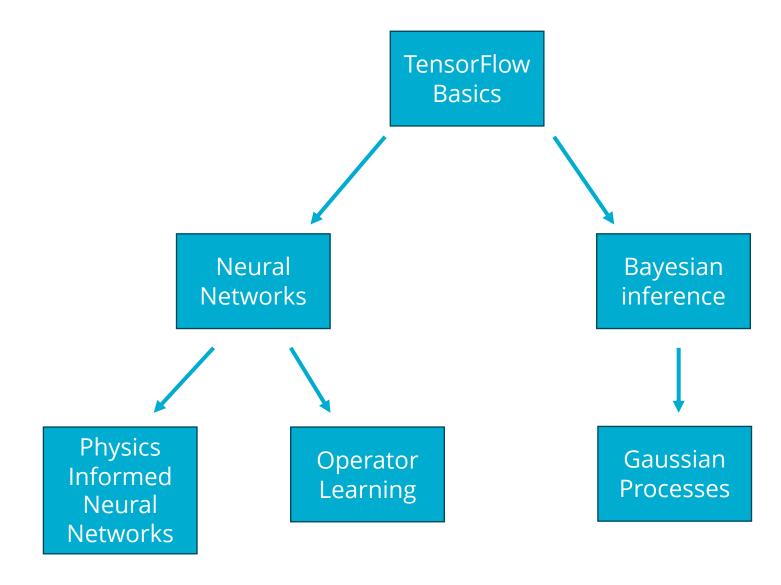
## COMPONENTS OF SCIENTIFIC MACHINE LEARNING





# **TUTORIAL TOPICS**





# **SCHEDULE**



# Day 1

| Time              | Topic   |
|-------------------|---|
| 9:00am – 9:45am   | Introduction and TensorFlow basics                    |
| 9:45am – 10:15am  | Neural networks I                                     |
| 10:15am – 10:30am | Coffee Break  |
| 10:30am – 11:30am | Neural networks II                                    |
| 11:30am – 1:30pm  | Lunch/Free Time                                       |
| 1:30pm – 4:00pm   | Physics informed neural networks and inverse problems |
| 4:00pm – 4:30pm   | Coffee Break  |
| 4:30pm – 5:00pm   | Bayesian inference and Gaussian Processes I           |

# **SCHEDULE**



Day 2

| Time              | Topic  |
|-------------------|--|
| 9:00am – 10:15am  | Bayesian Inference and Gaussian Processes II         |
| 10:15am – 10:30am | Coffee Break   |
| 10:30am – 11:30am | Operator Learning I                                  |
| 11:30am – 1:30pm  | Lunch/Free Time                                      |
| 1:30pm – 3:30pm   | Operator Learning II                                 |
| 3:30pm – 4:00pm   | Coffee Break   |
| 4:00pm – 4:30pm   | Advanced topics. Future directions. Reproducibility. |
| 4:30pm – 5:00pm   | Open Discussion                                      |

#### **TENSORFLOW OVERVIEW**



- Tensorflow linear algebra with automatic differentiation and accelerator support
- Concepts
  - Tensor data type
  - Accelerators
  - GradientTape
- Addons
  - Keras
  - Optimizers
  - Tensorflow probability

#### TENSORFLOW VS. NUMPY



# Numpy

- import numpy as np
- Operates on np.array type
- np.zeros, np.einsum, np.arange, np.shape
- np.concat, np.sum, A.T

#### **Tensorflow**

- import tensorflow as tf
- Operates on the tf.tensor type
- tf.zeros, np.einsum, tf.arange, tf.shape
- tf.concatenate, tf.reduce\_sum, tf.transpose(A)
- Accelerator support
- Automatic differentiation



# TensorType

- Similar to numpy arrays, but with accelerator support and automatic differentiation
- Constants once instantiated cannot be modified

```
In [1]: tf.constant(4.)
Out[1]: <tf.Tensor: shape=(), dtype=float32, numpy=4.0>
```

Variables (i.e. parameters) can be reassigned values

```
In [2]: a = tf.Variable(4.)
In [3]: a.assign(3.)
Out[3]: <tf.Variable 'UnreadVariable' shape=() dtype=float32, numpy=3.0>
```

- The standard `=` operator will create a new tensor
- Accumulation operators like `+=` will give an error
- For optimization, we typically will use `assign` to update Variables (i.e. parameters)



# GradientTape

Compute gradients using the following syntax,

```
x = tf.constant(2.)
with tf.GradientTape() as tape:
    tape.watch(x)
    y = x**2
tape.gradients(y,x)
```

- GradientTape tracks operations and adjoints for backprop
  - More details in next topic
- Can only compute the gradient of a scalar
  - Will sum over first argument if it's not a scalar
- GradientTape can also be used to compute Hessians and Jacobians
  - https://www.tensorflow.org/guide/advanced\_autodiff



# Eager mode

- TensorFlow offers two computational modes
- Eager mode is the default mode
  - Behaves much like standard Python but is much slower
  - Easier to debug
  - Code so far has all been in eager mode

```
A = tf.random.normal((25,250,2500))
B = tf.random.normal((2500,250,25))
def DoubleDot(A,B):
    return tf.einsum('ijk,kjl',A,B)
```

```
In [1]: %%timeit
...: DoubleDot(A,B)
8.54 ms ± 192 µs per loop (mean ± std. dev. of 7 runs, 100 loops each)
```



### Graph mode

- Graph mode is much faster but more restrictive. To invoke Graph mode
  - 1. Write a Python function with TensorFlow operations
  - 2. Pass the function through `tf.function` or decorate one with `@tf.function`
  - 3. First run will be slow

```
DoubleDot_graph = tf.function(DoubleDot)

@tf.function(jit_compile=True)
def DoubleDot_graph2(A,B):
    return tf.einsum('ijk,kjl',A,B)
```

```
In [1]: %%timeit
    ...: DoubleDot_graph(A,B)
1.11 ms ± 146 ns per loop (mean ± std. dev. of 7 runs, 1,000 loops each)
In [2]: %%timeit
    ...: DoubleDot_graph2(A,B)
1.11 ms ± 168 ns per loop (mean ± std. dev. of 7 runs, 1,000 loops each)
```



# Just-in-time compilation

We can further speed up TensorFlow code by specifying just-in-time compilation (XLA) in tf.function,

```
@tf.function(jit_compile=True)
def DoubleDot_jit(A,B):
    return tf.einsum('ijk,kjl',A,B)

In [1]: %%timeit
    ...: DoubleDot_jit(A,B)
260 µs ± 269 ns per loop (mean ± std. dev. of 7 runs, 1,000 loops each)
```



### **Executing on accelerators**

- By default, TensorFlow will try to execute code on the GPU
- We can explicitly tell it to execute on a specific device,

```
In [1]: %%timeit
    ...: with tf.device('/CPU:0'):
    ...: DoubleDot_jit(A,B)
8.35 ms ± 80.8 µs per loop (mean ± std. dev. of 7 runs, 100 loops each)

In [2]: %%timeit
    ...: with tf.device('/GPU:0'):
    ...: DoubleDot_jit(A,B)
262 µs ± 319 ns per loop (mean ± std. dev. of 7 runs, 1,000 loops each)
```

#### TIPS AND TRICKS



- Eager mode is more robust and provides better error messages than graph mode
  - Check code in eager before switch to graph mode
  - Check code in graph mode without JIT before enabling JIT
- Avoid using numpy code and operations with side effects inside a tf.function
- Use Jupyter's built-in debugger
- Applying operations to the wrong shapes is the most common error
  - Check the shape of inputs to/outputs of operations
- TensorFlow is much less forgiving than numpy with respect to precision
  - By default float32 vs. numpy's float64
- GradientTape must be used with tf.tensor. np.array's won't trace
- You'll likely do some tensor transposing and reshaping, e.g., to use linear algebra operations,  $\mathbb{R}^{n \times m} \cong \mathbb{R}^{nm}$
- TensorFlow and numpy are not one-to-one. Check the documentation, <a href="https://www.tensorflow.org/api\_docs">https://www.tensorflow.org/api\_docs</a>

#### HANDS ON EXERCISES

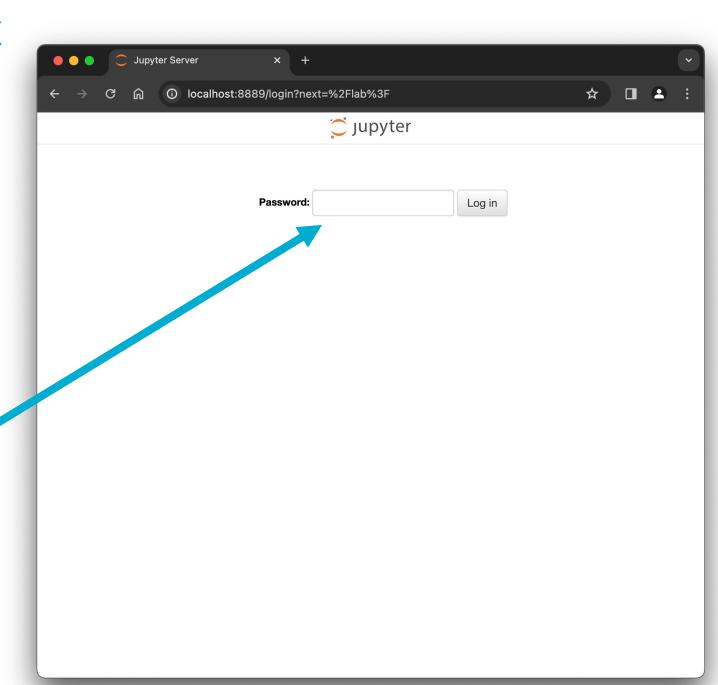
- We'll split up into 10 groups, each with an assigned instance
  - Amazon EC2 with 4 vCPUs and 1 Nvidia T40 GPU
  - Only up until tomorrow night save data offline
- We'll be using the Jupyter lab to do the exercises
  - Web browser-based development environment
  - Collaborative group members will share same Jupyter
- The instances have all been started already
- Run the following command in your terminal,

```
$ ssh -L 8888:localhost:8888 icerm2@<ip>
```

- I'll give each group their <ip>
- and in your browser, navigate to
  - http://localhost:8888 (password is icerm2024)

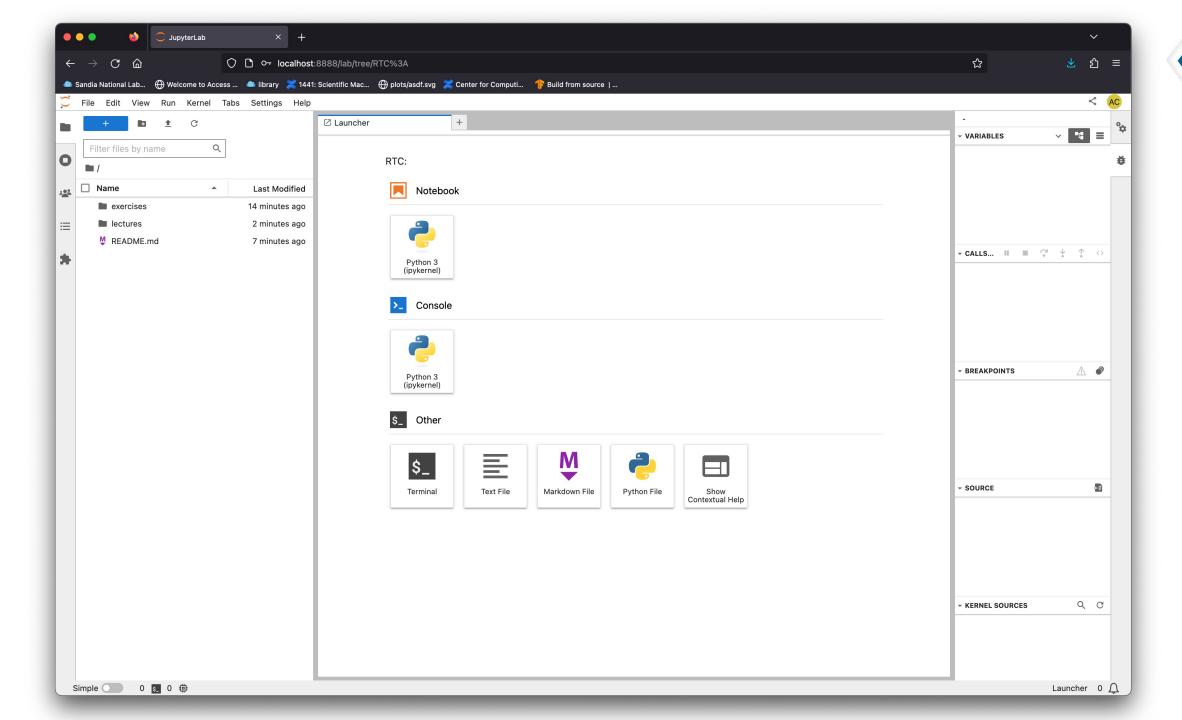
# JUPYTER NOTEBOOK



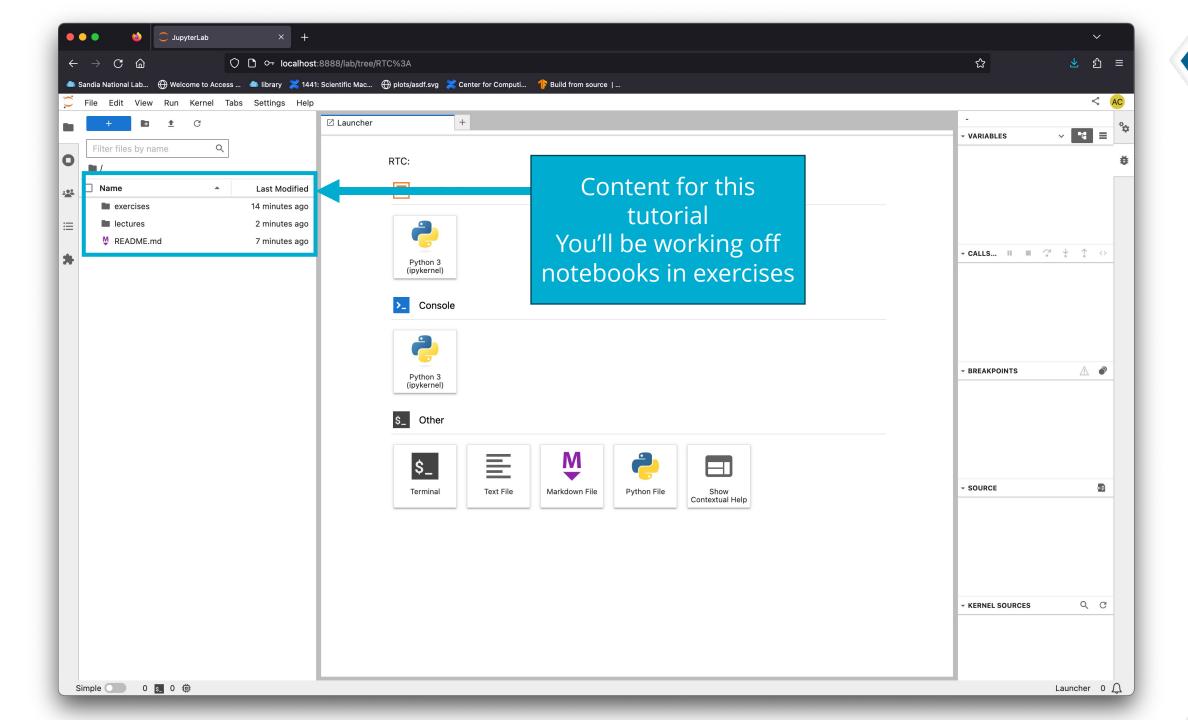


Enter Password: icerm2024

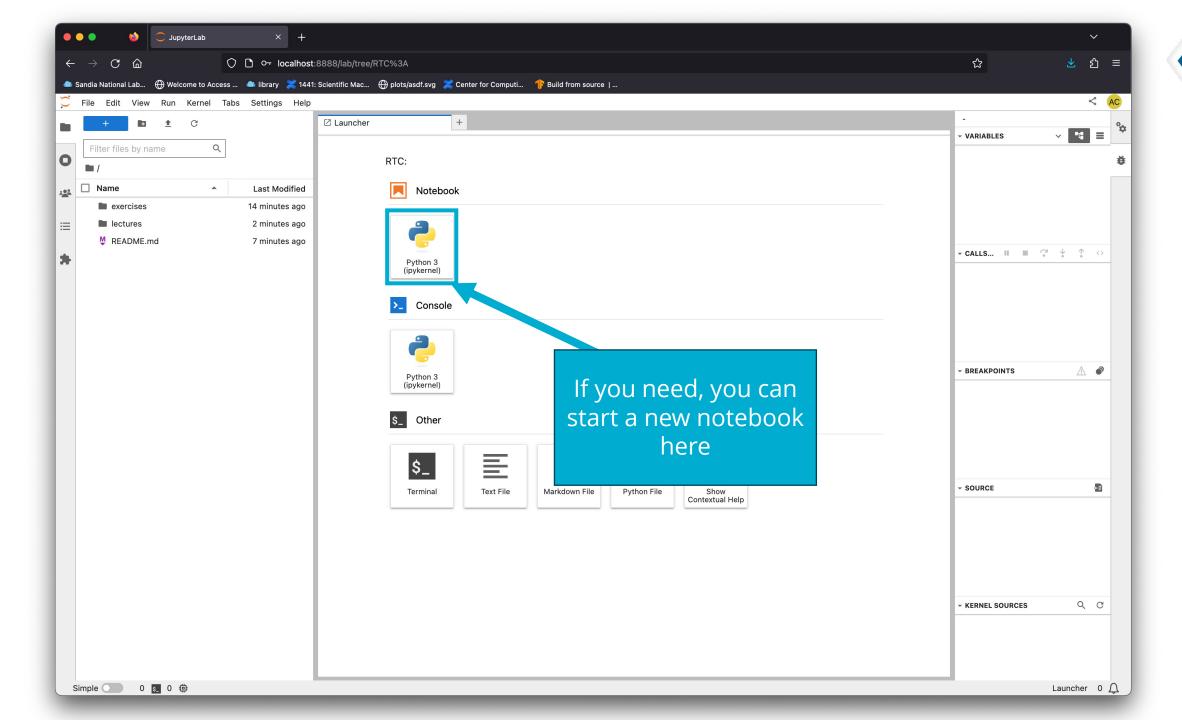




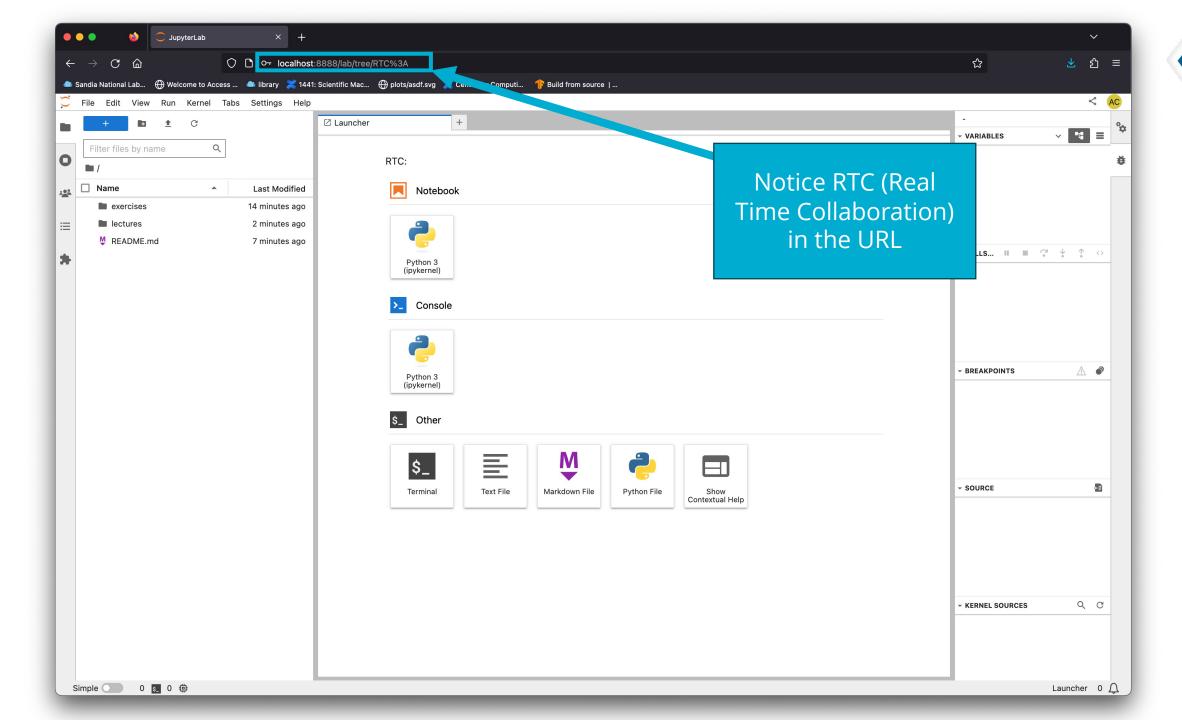




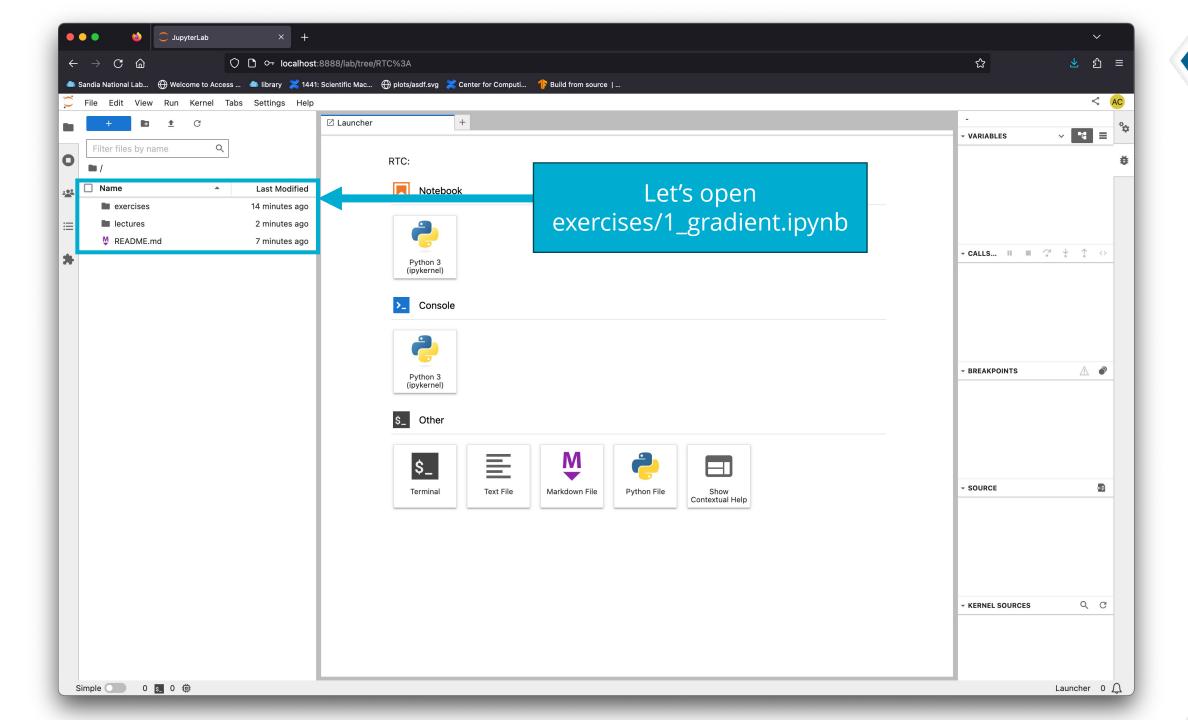












#### **EXERCISE**



- Follow the previous slides to open the exercises/1\_gradient.ipynb notebook
- Compute the gradient of Ax for a random matrix, A, and vector, x
- Experiment with tf.function, jit, and running on the CPU/GPU
- Experiment with Jupyter's debugger