Econ 432 Homework 5

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Contents

I	Part	1: Review Questions	,
	1.1	Problem 1	3
		Part (a)	3
		Part (b)	3
		Part (c)	1
	1.2	Problem 2	5
		Part (a)	5
		Part (b)	7
	1.3	Problem 3	3
		Part (a)	3
		Part (b))
		Part (c))
		Part (d))
		Part (e))
		Part (f)	l
	1.4	Problem 4	l
		Part (a)	l
		Part (b)	2
		Part (c)	3
•	ъ.		
2		II: Python Exercises	
	2.1	Problem 1	
		Part (a)	
		Part (b)	Ĺ
	2.2	Problem 2	Ĺ
		Part (a)	ĺ
		Part (b))

2.3	roblem 3	. 30
	art (a)	. 30
	art (b)	. 31
	art (c)	. 32
	art (d)	. 33
	art (e)	. 35
	art (f)	. 36

1 Part I: Review Ouestions

1.1 Problem 1

One popular concept on stock market price is called "martingale pricing", which is relevant to "rational expectations" or "efficient market hypothesis" in economic theories. A rough statement on this is that, a (log of) stock market price p_t (e.g., S&P 500 index) is supposed to reflect all the relevant information available up to time t, i.e.,

$$\mathbb{E}[p_t|\mathcal{F}_{t-1}] = p_{t-1}$$

therefore $p_t = \log P_t$ is a martingale.

Part (a)

Under martingale pricing, show that continuously compounded (cc) return for stock market priace is a martingale difference sequence (mds).

Proof

By definition, $\{d_t\}_{t=1}^T$ is a martingale difference sequence if $\mathbb{E}[d_t|\mathcal{F}_{t-1}]=0$ where $d_t\equiv Y_t-Y_{t-1}$. In our case, cc returns are defined as

$$r_t = \ln\left(\frac{P_t}{P_{t-1}}\right) = p_t - p_{t-1}$$

Therefore, applying the definition of an mds

$$\mathbb{E}[r_t|\mathcal{F}_{t-1}] = \mathbb{E}[p_t - p_{t-1}|\mathcal{F}_{t-1}] = \mathbb{E}[p_t|\mathcal{F}_{t-1}] - \mathbb{E}[p_{t-1}|\mathcal{F}_{t-1}]$$

By definition of a martingale and by properties of σ fields

$$\mathbb{E}[p_t|\mathcal{F}_{t-1}] - \mathbb{E}[p_{t-1}|\mathcal{F}_{t-1}] = p_{t-1} - p_{t-1} = 0$$

Therefore, cc returns, r_t are a MDS

Part (b)

In what follows, we assume cc returns r_t is a covariance stationary process. Prove the following statements:

- 1. If $r_t \sim iid(0,\sigma^2)$ or (independent white noise), then $r_t \sim mds(0,\sigma^2)$.
- 2. If $r_t \sim mds(0, \sigma^2)$, then $r_t \sim WN(0, \sigma^2)$ (or weak white noise).

Proof

Statement 1

 $r_t \sim iid(0,\sigma^2)$ implies that r_t is independent and identically distributed. If r_t is independent of $r_{t-j} \, \forall j$, then $\mathbb{E}[r_t | \mathcal{F}_{t-1}] = 0$. Past information has no affect on a future event. By definition, this is a martingale difference sequence.

Statement 2

For \boldsymbol{r}_t to be $WN(0,\sigma^2),$ we need to show:

$$\mathbb{E}[r_t] = 0, \quad \operatorname{Var}(r_t) = \sigma^2, \quad \operatorname{Cov}(r_t, r_{t-i}) = 0$$

If $r_t \sim mds(0,\sigma^2)$, then $\mathbb{E}[r_t|\mathcal{F}_{t-1}]=0$ and $\mathrm{Var}(r_t)=\mathbb{r}_{\mathbb{L}}^2=\sigma^2$ for all t. Therefore, show the first requirement by Law of Iterated Expectations:

$$\mathbb{E}\Big[\mathbb{E}[r_t|\mathcal{F}_{t-1}]\Big] = \mathbb{E}[0] \implies \mathbb{E}[r_t] = 0$$

The second requirement is trivially satisfied by definition of our MDS. And the last condition is satisified by

$$\begin{split} \operatorname{Cov}(r_t, r_{t-j}) &= \mathbb{E}[r_t \cdot r_{t-j}] - \mathbb{E}[r_t] \mathbb{E}[r_{t-j}] \\ &= \mathbb{E}[r_t \cdot r_{t-j}] \\ &= \mathbb{E}\Big[\mathbb{E}[r_t \cdot r_{t-j}|\mathcal{F}_{t-1}]\Big] \qquad \text{(Law of Iterated Exp.)} \\ &= \mathbb{E}\Big[r_{t-j}\mathbb{E}[r_t|\mathcal{F}_{t-1}]\Big] \\ &= \mathbb{E}[r_{t-j} \cdot 0] = 0 \end{split}$$

Hence, all three conditions are satisfied.

Part (c)

Prove the following statements:

- 1. If $\{r_t\}$ is iid, then it is strictly stationary.
- 2. If $\{r_t\}$ is strictly stationary and $\mathbb{E}[r_1^2]<\infty$, then it is covariance stationary.

Proof

Statement 1

If $\{r_t\}$ is iid, then

$$f(r_{t_1}, r_{t_2}, \dots, r_{t_k}) = f_1(r_{t_1}) \cdot f_2(r_{t_2}) \cdot \quad \cdots \quad \cdot f_t(r_{t_k})$$

by property of independence. And then by property of identical distribution

$$f(r_{t_1}, r_{t_2}, \dots, r_{t_k}) = f(r_1) \cdot f(r_2) \cdot \quad \cdots \quad \cdot f(r_k)$$

Therefore,

$$f(r_{t_1+\eta}, r_{t_2+\eta}, \dots, r_{t_k+\eta}) = f(r_1) \cdot f(r_2) \cdot \quad \cdots \quad \cdot f(r_k)$$

for any $\eta \in \mathbb{N}$. Hence $\{r_t\}$ is strictly stationary.

Statement 2

To prove covariance stationarity, we need to show that:

 $\begin{array}{ll} 1. \ \ \mathbb{E}[|r_t^2|] < \infty & \forall t \in T \\ 2. \ \ \mathbb{E}[r_t] = \mu \text{ and } \mathrm{Var}(r_t) = \sigma^2 & \forall t \in T \\ 3. \ \ \mathrm{Cov}(r_t, r_{t-j}) = \gamma_j \end{array}$

By assumption $\mathbb{E}[r_1^2] < \infty$, and since strict stationarity implies identical distribution across all time t, then condition 1 is trivially satisfied. Condition 2 is satisfied by properties of strict stationarity which imply time invariance for all higher moments if they exist.

To show condition 3, want to prove that the autocovariance of our time series is time invariant. Hence, we will show that

$$\mathrm{Cov}(r_t, r_{t-j}) = \mathrm{Cov}(r_{t+s}, r_{t+s-j}) \quad \forall \; t, j, s \in T \subseteq \mathbb{N}$$

By expectation expansion of covariance,

$$\begin{split} \operatorname{Cov}(r_t, r_{t-j}) &= \mathbb{E}\Big[(r_t - \mathbb{E}[r_t])(r_{t-j} - \mathbb{E}[r_{t-j}])\Big] = \mathbb{E}[r_t \cdot r_{t-j}] - \mu^2 \\ \operatorname{Cov}(r_{t+s}, r_{t+s-j}) &= \mathbb{E}\Big[(r_{t+s} - \mathbb{E}[r_{t+s}])(r_{t+s-j} - \mathbb{E}[r_{t+s-j}])\Big] = \mathbb{E}[r_{t+s} \cdot r_{t+s-j}] - \mu^2 \end{split}$$

where by strict stationarity, the first moment is time invariant. These expressions then implies that

$$\mathrm{Cov}(r_t, r_{t-j}) = \mathrm{Cov}(r_{t+s}, r_{t+s-j}) \iff \mathbb{E}[r_t \cdot r_{t-j}] = \mathbb{E}[r_{t+s} \cdot r_{t+s-j}]$$

By the integral expression of expectation, we show

$$\begin{split} \mathbb{E}[r_t \cdot r_{t-j}] &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} r_t r_{t-j} f(r_t, r_{t-j}) dr_t dr_{t-j} \\ \mathbb{E}[r_{t+s} \cdot r_{t+s-j}] &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} r_{t+s} r_{t+s-j} f(r_{t+s}, r_{t+s-j}) dr_{t+s} dr_{t+s-j} \end{split}$$

Then by the definition of strict stationarity, $f(r_{t+s},r_{t+s-j})=f(r_t,r_{t-j})$ which then implies the equivalence

$$\begin{split} \mathbb{E}[r_t \cdot r_{t-j}] &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} r_t r_{t-j} f(r_t, r_{t-j}) dr_t dr_{t-j} \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} r_{t+s} r_{t+s-j} f(r_t, r_{t-j}) dr_{t+s} dr_{t+s-j} \\ &= \mathbb{E}[r_{t+s} \cdot r_{t+s-j}] \end{split}$$

where the uniqueness of the integral is determined by the density function. The other variables are simply the variables of integration and can theoretically by anything (e.g., the principle of U-substitution). Therefore, since these expectations are equivalent, then the covariances are equivalent as well. Therefore, covariances are equivalent across time – time invariant $\operatorname{Cov}(r_t, r_{t-j}) = \gamma_j$.

1.2 Problem 2

Suppose that $\varepsilon_t \sim iid\ N(0,1)$. Define $Y_{1,t} \equiv \varepsilon_t \varepsilon_{t-1}$ and $Y_{2,t} \equiv \varepsilon_t + \varepsilon_{t-1} \varepsilon_{t-2}$. Show the following.

Part (a)

Prove $Y_{1,t}$ is an mds but not iid.

Proof

A stochastic process is a martingale difference sequence if the conditional expectation with respect the σ -field \mathcal{F}_{t-1} is equal to 0. Hence,

$$\mathbb{E}[Y_{1,t}|\mathcal{F}_{t-1}] = \mathbb{E}[\varepsilon_t \varepsilon_{t-1}|\mathcal{F}_{t-1}] = \varepsilon_{t-1} \mathbb{E}[\varepsilon_t] = \varepsilon \cdot 0 = 0$$

and we confirm that $Y_{1,t}$ is a mds. We show that it is not iid by showing that $Y_{1,t}^2$ and $Y_{1,t-1}^2$ are correlated.

$$\begin{split} \operatorname{Cov}(Y_{1,t}^2,Y_{1,t-1}^2) &= \mathbb{E} \Big[Y_{1,t}^2 \cdot Y_{1,t-1}^2 \Big] - \mathbb{E} [Y_{1,t}^2] \mathbb{E} [Y_{1,t-1}^2] \\ &= \mathbb{E} \Big[\varepsilon_t^2 \varepsilon_{t-1}^2 \varepsilon_{t-2}^2 \varepsilon_{t-2}^2 \Big] - \mathbb{E} \Big[\varepsilon_t^2 \varepsilon_{t-1}^2 \Big] \mathbb{E} \Big[\varepsilon_{t-1}^2 \varepsilon_{t-2}^2 \Big] \\ &= \mathbb{E} \Big[\varepsilon_t^2 \varepsilon_{t-1}^4 \varepsilon_{t-2}^2 \Big] - \mathbb{E} \Big[\varepsilon_t^2 \Big] \mathbb{E} \Big[\varepsilon_{t-1}^2 \Big] \mathbb{E} \Big[\varepsilon_{t-1}^2 \Big] \mathbb{E} \Big[\varepsilon_{t-2}^2 \Big] \\ &= \mathbb{E} \Big[\varepsilon_t^2 \Big] \mathbb{E} \Big[\varepsilon_{t-1}^4 \Big] \mathbb{E} \Big[\varepsilon_{t-2}^2 \Big] - \mathbb{E} \Big[\varepsilon_t^2 \Big] \mathbb{E} \Big[\varepsilon_{t-1}^2 \Big] \mathbb{E} \Big[\varepsilon_{t-1}^2 \Big] \mathbb{E} \Big[\varepsilon_{t-2}^2 \Big] \\ &= 1 \cdot 3 \cdot 1 - 1 \cdot 1 \cdot 1 \cdot 1 \\ &= 3 - 1 = 2 \neq 0 \end{split}$$

where we know the fourth moment of a standard normal variable is the kurtosis which is equal to 3. Hence, we show that $Y_{1,t}$ is mds but not iid

Part (b)

Prove $Y_{2,t}$ is a WN but not a mds.

Proof

 $Y_{2,t}$ is a White Noise process if $\mathbb{E}[Y_{2,t}]=0$, $\mathrm{Var}(Y_{2,t})=\sigma^2$, and $\mathrm{Cov}(Y_{2,t},Y_{2,s})=0$ for all $t\neq s$. We show the first condition:

$$\mathbb{E}[Y_{2,t}] = \mathbb{E}[\varepsilon_t + \varepsilon_{t-1}\varepsilon_{t-2}] = 0 + \mathbb{E}[\varepsilon_{t-1}]\mathbb{E}[\varepsilon_{t-2}] = 0$$

By the fact that ε_t is iid for all t. We can show the second condition (constant variance):

$$\begin{split} \operatorname{Var}(Y_{2,t}) &= \mathbb{E}\Big[(Y_{2,t})^2\Big] - \overbrace{\mathbb{E}[Y_{2,t}]^2}^{=0} \\ &= \mathbb{E}\Big[(\varepsilon_t + \varepsilon_{t-1}\varepsilon_{t-2})^2\Big] \\ &= \mathbb{E}\big[\varepsilon_t^2\big] + 2\mathbb{E}[\varepsilon_t\varepsilon_{t-1}\varepsilon_{t-2}] + \mathbb{E}[\varepsilon_{t-1}^2]\mathbb{E}[\varepsilon_{t-2}^2] \\ &= \operatorname{Var}(\varepsilon_t) + \mathbb{E}[\varepsilon_t]\mathbb{E}[\varepsilon_{t-1}\varepsilon_{t-2}] + \operatorname{Var}(\varepsilon_{t-1})\operatorname{Var}(\varepsilon_{t-2}) \\ &= 1 + 0 + 1 = 2 \end{split}$$

Hence, the variance is a constant $\sigma^2=2$ for all t. And lastly, to show that $Y_{2,t}$ is a white noise process, we must show that the autocovariance is 0 across time.

$$\begin{split} \operatorname{Cov}(Y_{2,t},Y_{2,s}) &= \mathbb{E} \Big[Y_{2,t} \cdot Y_{2,s} \Big] - \mathbb{E}[Y_{2,t}] \mathbb{E}[Y_{2,s}] \\ &= \mathbb{E} \Big[(\varepsilon_t + \varepsilon_{t-1} \varepsilon_{t-2}) (\varepsilon_s + \varepsilon_{s-1} \varepsilon_{s-2}) \Big] - 0 \\ &= \mathbb{E} \Big[\varepsilon_t \varepsilon_s + \varepsilon_t \varepsilon_{s-1} \varepsilon_{s-2} \varepsilon_s \varepsilon_{t-1} \varepsilon_{t-2} + \varepsilon_{t-1} \varepsilon_{t-2} \varepsilon_{s-1} \varepsilon_{s-2} \Big] \\ &= 0 \qquad \text{(By iid)} \end{split}$$

Therefore, the autocovariance is 0 across time. We have shown that $Y_{2,t}$ is a white noise process. To show that it is **not** an mds we simply show that the conditional expectation is not equal to zero.

$$\mathbb{E}[Y_{2,t}|\mathcal{F}_{t-1}] = \mathbb{E}[\varepsilon_t + \varepsilon_{t-1}\varepsilon_{t-2}|\mathcal{F}_{t-1}] = 0 + \mathbb{E}[\varepsilon_{t-1}\varepsilon_{t-2}|\mathcal{F}_{t-1}] = \varepsilon_{t-1}\varepsilon_{t-2} \neq 0$$

Hence, the process is not a mds.

1.3 Problem 3

Suppose that $\{Y_t\}$ is a covariance-stationary process generated from the AR(1) model

$$Y_t - \mu = \phi(Y_{t-1} - \mu) + \varepsilon_t$$

where $|\phi| < 1$ and $\varepsilon_t \sim iid(0, \sigma_\varepsilon^2)$.

Part (a)

Show that $\mathbb{E}[Y_t] = \mu$.

Proof

We begin by taking the expectation of both sides

$$\begin{split} \mathbb{E}[Y_t - \mu] &= \mathbb{E}\Big[\phi(Y_{t-1} - \mu) + \varepsilon_t\Big] \\ \mathbb{E}[Y_t] - \mu &= \phi \mathbb{E}[Y_{t-1}] - \phi \mu + 0 \\ \mathbb{E}[Y_t] &= \phi \mathbb{E}[Y_{t-1}] - \phi \mu + \mu \end{split}$$

We can then rearrange to get

$$\begin{split} \mathbb{E}[Y_t] - \phi \mathbb{E}[Y_{t-1}] &= -\phi \mu + \mu \\ \mathbb{E}[Y_t] (1 - \phi) &= \mu (1 - \phi) \end{split}$$

Which then implies

$$\mathbb{E}[Y_t] = \frac{\mu(1-\phi)}{1-\phi} = \mu$$

Part (b)

Show that $\operatorname{Cov}(Y_{t-j}-\mu,\varepsilon_t)=0$ for any $j\geq 1$.

Proof

We utilize the expectation representation of Covariance to show

$$\begin{split} \operatorname{Cov}(Y_{t-j} - \mu, \varepsilon_t) &= \mathbb{E}\Big[(Y_{t-j} - \mu)\varepsilon_t\Big] - \mathbb{E}[Y_{t-j} - \mu] \, \widetilde{\mathbb{E}[\varepsilon_t]} \\ &= \mathbb{E}[Y_{t-j}\varepsilon_t - \mu\varepsilon_t] = \mathbb{E}[Y_{t-j}\varepsilon_t] - \mu\mathbb{E}[\varepsilon_t] \\ &= \mathbb{E}[Y_{t-j}\varepsilon_t] = \mathbb{E}[Y_{t-j}]\mathbb{E}[\varepsilon_t] \\ &= 0 \end{split}$$

We can separate that last expectation since the error term is independent of the time series.

Part (c)

Show that $\operatorname{Var}(Y_t) = \sigma_{\varepsilon}^2 (1 - \sigma^2)^{-1}$.

Proof

We can take the variance of both sides of our AR(1) model

$$\mathrm{Var}(Y_t - \mu) = \mathrm{Var}(\phi(Y_{t-1} - \mu) + \varepsilon_t)$$

Variance is applied linearly across addition/subtraction, and the variance of a constant μ is 0. Hence

$$Var(Y_t) = Var(\phi Y_{t-1} - \phi \mu + \varepsilon_t)$$

where by properties of covariance-stationary processes, $\operatorname{Var}(Y_t) = \operatorname{Var}(Y_{t-1})$. Therefore,

$$Var(Y_t) = \phi^2 Var(Y_t) + Var(\varepsilon_t)$$

Subtracting the variance of Y_t term from the left hand side and dividing by $(1-\phi)^2$ shows

$$\operatorname{Var}(Y_t) = \sigma_{\varepsilon}^2 (1 - \sigma^2)^{-1}$$

Part (d)

Recall that $\gamma_j = \operatorname{Cov}(Y_t, Y_{t-j})$. Show that $\gamma_j = \phi \gamma_{j-1}$.

Proof

We have the base (mean adjusted) AR(1) model:

$$Y_t - \mu = \phi(Y_{t-1} - \mu) + \varepsilon_t$$

By simple properties of multiplication, we can multiply both sides of the expression by the same value. In this case, we multiply both sides by $(Y_{t-j} - \Box)$ to get

$$(Y_{t-j} - \mu)(Y_t - \mu) = (Y_{t-j} - \mu)(\phi(Y_{t-1} - \mu) + \varepsilon_t)$$

We can then take the expectations of both sides to prove our claim

$$\mathbb{E}\Big[(Y_{t-j}-\mu)(Y_t-\mu)\Big] = \mathbb{E}\Big[(Y_{t-j}-\mu)(\phi(Y_{t-1}-\mu)+\varepsilon_t)\Big]$$

where the left hand side (by definition) is equal to the relevant covariance term

$$\begin{split} \operatorname{Cov}(Y_t, Y_{t-j}) &= \mathbb{E}\Big[(Y_{t-j} - \mu)(\phi(Y_{t-1} - \mu) + \varepsilon_t)\Big] \\ &= \mathbb{E}\Big[(Y_{t-j} - \mu)(\phi(Y_{t-1} - \mu)) + (Y_{t-j} - \mu)\varepsilon_t\Big] \\ &= \mathbb{E}\Big[(Y_{t-j} - \mu)(\phi(Y_{t-1} - \mu))\Big] + \mathbb{E}[(Y_{t-j} - \mu)\varepsilon_t] \\ &= \phi \operatorname{Cov}(Y_{t-1}, Y_{t-j}) + 0 \end{split}$$

And by definitions $\gamma_j\equiv {\rm Cov}(Y_t,Y_{t-j})$ and $\gamma_{j-1}\equiv {\rm Cov}(Y_{t-1},Y_{t-j})$ we show

$$\gamma_j = \phi \gamma_{j-1}$$

Part (e)

Using part (c) and part (d), show that $\gamma_j = \phi^j \sigma_\varepsilon^2 (1-\phi^2)^{-1}.$

Proof

By definition of covariance, we know that $\mathrm{Cov}(Y_t,Y_t)=\mathrm{Var}(Y_t)=\gamma_0$. Hence, we use the result from part (c) and (d) to show

$$\begin{split} \gamma_j &= \phi \gamma_{j-1} \\ &= \phi(\phi \gamma_{j-2}) \\ &\vdots \\ &= \phi^j \gamma_{j-j} = \phi^j \gamma_0 \\ &= \phi^j \operatorname{Var}(Y_t) \\ &= \phi^j \sigma_\varepsilon^2 (1 - \phi^2)^{-1} \end{split}$$

Part (f)

Recall that $\rho_j=\gamma_j/\gamma_0.$ Show that $\rho_j=\phi^j.$

Proof

By definition and using our result from part (e)

$$\rho_j = \frac{\gamma_j}{\gamma_0} = \frac{\phi^j \gamma_0}{\gamma_0} = \phi^j$$

1.4 Problem 4

Consider the following AR(2) model:

$$Y_t = \mu + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \varepsilon_t$$

where $\varepsilon \sim iid \; N(0,\sigma_{\varepsilon}^2).$

Part (a)

Show that the above expression can be written as

$$Y_t = \mu + \rho Y_{t-1} + \alpha_1 \Delta Y_{t-1} + \varepsilon_t$$

where $\Delta Y_{t-1} = Y_{t-1} - Y_{t-2}$.

Proof

If $\Delta Y_{t-1} = Y_{t-1} - Y_{t-2}$, then we can write $Y_{t-2} = Y_{t-1} - \Delta Y_{t-1}$. We can then substitute this expression into our AR(2) model:

$$\begin{split} Y_t &= \mu + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \varepsilon_t \\ &= \mu + \phi_1 Y_{t-1} + \phi_2 (Y_{t-1} - \Delta Y_{t-1}) + \varepsilon_t \\ &= \mu + (\phi_1 + \phi_2) Y_{t-1} - \phi_2 \Delta Y_{t-1} + \varepsilon_t \\ Y_t &= \mu + \rho Y_{t-1} + \alpha_1 \Delta Y_{t-1} + \varepsilon_t \end{split}$$

where $\rho \equiv \phi_1 + \phi_2$ and $\alpha_1 \equiv -\phi_2$.

Part (b)

Using the daily log-prices of Apple in 2021 for Y_t , we run a linear regression on the expression from part (a) and find the following:

$$Y_t = \underset{(0.0497)}{0.006} + \underset{(0.0101)}{0.9991} Y_{t-1} - \underset{(0.0640)}{0.0386} \Delta Y_{t-1} + \hat{\varepsilon}_t$$

where the numbers in parentheses are the standard errors reported in the LS regression. We are interested in testing the null hypothesis that the daily log-prices of Apple is a unit root process. Does the augmented Dickey-Fuller (ADF) test support this null under the significance level of 0.05?

Solution

We want to test the set of hypotheses

$$H_0: \rho = 1$$
 v.s. $H_1: \rho \neq 1$

using the Augmented Dickey Fuller (ADF) test. With the above regression results, we compute the ADF statistic

$$\mathrm{ADF} = \frac{\hat{\rho} - 1}{\mathrm{SE}(\hat{\rho})} = \frac{0.9991 - 1}{0.0101} \approx -0.0891 > -2.8604$$

where $DF_{0.05} = -2.8604$ is our critical value. In this case, since our test statistic is less negative than our critical value, we **fail to reject the null**. Therefore, the ADF test supports the null (unit root process) under the 5% significance level.

Part (c)

Now suppose that $\rho = 1$. Show that the expression in part (a) can be written as

$$\Delta Y_t = \mu + \alpha_1 \Delta Y_{t-1} + \varepsilon_t$$

where $\Delta Y_t = Y_t - Y_{t-1}$. Using the same data in part (b), we obtain the following results from linear regression of the above expression:

$$\Delta Y_t = \underset{(0.0010)}{0.0014} - \underset{(0.0631)}{0.0395} \ \Delta Y_{t-1} + \hat{\varepsilon}_t$$

We want to test if the daily cc return of Apple is a unit-root process. Does the Dickey-Fuller (DF) test support this null under the significance level of 0.05?

Solution

With $\rho = 1$, we can rewrite our expression as

$$\begin{split} Y_t &= \mu + \rho Y_{t-1} + \alpha_1 \Delta Y_{t-1} + \varepsilon_t \\ &= \mu + Y_{t-1} + \alpha_1 \Delta Y_{t-1} + \varepsilon_t \\ Y_t - Y_{t-1} &= \mu + \alpha_1 \Delta Y_{t-1} + \varepsilon_t \\ &\Longrightarrow \Delta Y_t = \mu + \alpha_1 \Delta Y_{t-1} + \varepsilon_t \end{split}$$

Now, we can test the set of hypotheses

$$H_0: \alpha_1=1$$
 v.s. $H_1: \alpha_1 \neq 1$

using the Dickey Fuller (DF) test. With the above regression results, we compute the DF statistic

$$\mathrm{DF} = \frac{\hat{\alpha}_1 - 1}{\mathrm{SE}(\hat{\alpha}_1)} = \frac{-0.0395 - 1}{0.0631} \approx -16.464 < -2.8604$$

where $DF_{0.05} = -2.8604$ is our critical value. In this case, since our test statistic is more negative than our critical value, we **reject the null**. Therefore, the DF test does not support the null (unit root process) under the 5% significance level.

2 Part II: Python Exercises

2.1 Problem 1

Consider the MA(1) model:

$$Y_t = 0.05 + \varepsilon_t + \theta \varepsilon_{t-1}, \quad |\theta| < 1$$

where $\varepsilon_t \sim iid \ N(0, (0.10)^2)$.

Part (a)

Use the Python function statsmodels.tsa.arima_process.arma_generate_sample() to simulate and plot 250 observations of the MA(1), theoretical ACF (autocorrelation function) and sample ACF with $\theta=0.5$, $\theta=0.9$, and $\theta=-0.9$.

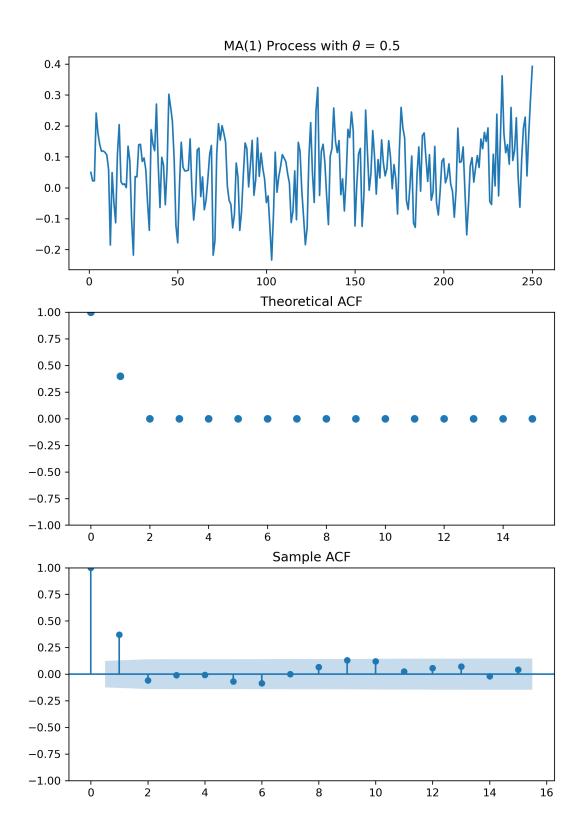
```
# Imports
import numpy as np
from statsmodels.tsa.arima_process import arma_generate_sample
import matplotlib.pyplot as plt
from statsmodels.graphics.tsaplots import plot_acf

# Figure Resolution
%matplotlib inline
plt.rcParams['figure.dpi']= 300
```

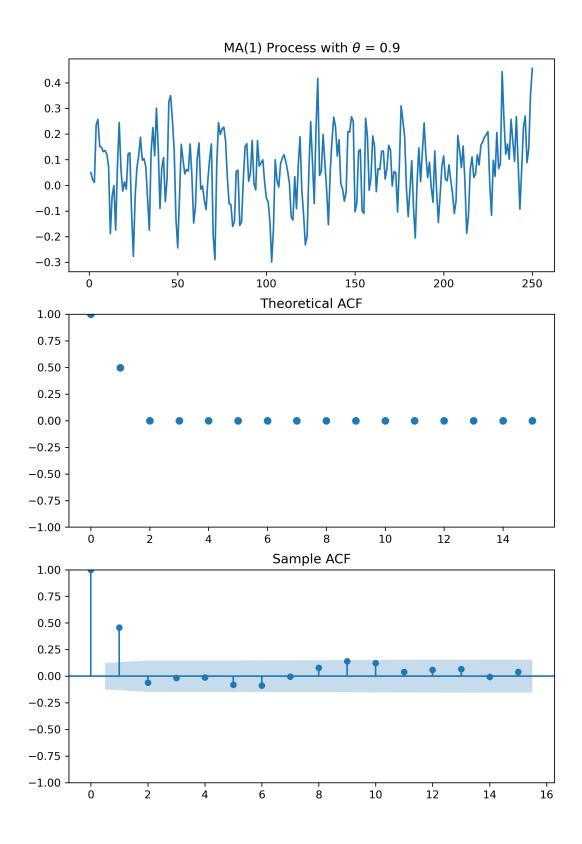
```
# Define Plotting Function
def ma1_plot(theta):
   ar = np.r_[1] \# add zero-lag
   ma = np.r_[1, theta] # add zero-lag
   y = 0.05 + arma_generate_sample(ar, ma, scale = 0.1, nsample = 250)
   fig, ax = plt.subplots(nrows = 3, ncols = 1,figsize=(8,12))
   ax[0].plot(np.arange(1, 251, 1), y) # first subgraph
   ax[0].title.set_text(
       r'MA(1) Process with $\theta$ = {}\'.format(theta)) # add the title
   theoretical_acf = [1, theta/(1+theta ** 2)] + [0] * 14
   ax[1].scatter(np.arange(0, 16, 1), theoretical_acf)
   ax[1].set_ylim([-1.0, 1.0])
   ax[1].title.set_text('Theoretical ACF')
   plot_acf(y, lags = 15, ax = ax[2]) # second subgraph
   ax[2].title.set_text('Sample ACF')
   plt.show()
```

```
# Theta = 0.5
np.random.seed(2022)
```

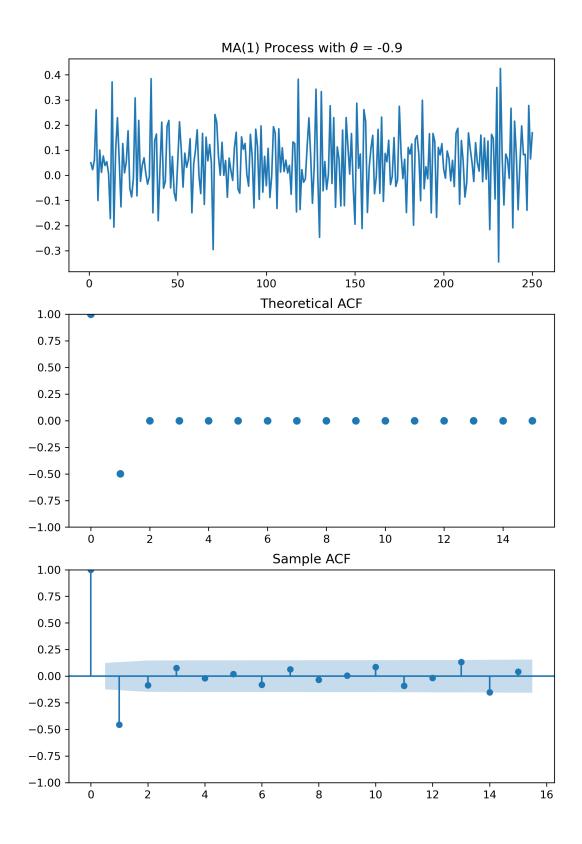
ma1_plot(0.5)



```
# Theta = 0.5
np.random.seed(2022)
ma1_plot(0.9)
```



```
# Theta = 0.5
np.random.seed(2022)
ma1_plot(-0.9)
```



Part (b)

Briefly comment on the behavior of the simulated data series.

Solution

The simulated data looks to be stationary with a mean of approximately 0. Indeed, since our model is an MA(1), we can clearly see in both the theortical and sample ACF plots that our observations are only autocorrelated with 1 lag – the rest have near 0 correlation. For the model with $\theta = -0.9$, the correlation with the first lag is negative as expected. Beyond this, by properties of MA(q) models, none of them are explosive.

With larger θ values, our process takes larger values. This makes sense if we consider the function form of MA(q) models.

2.2 Problem 2

Consider the AR(1) model:

$$Y_t - 0.05 = \phi(Y_{t-1} - 0.05) + \varepsilon_t, \quad |\phi| < 1$$

where $\varepsilon_t \sim iid \ N(0, (0.10)^2)$.

Part (a)

Use the Python function statsmodels.tsa.arima_process.arma_generate_sample() to simulate and plot 250 observations of the AR(1) with $\phi = 0$, $\phi = 0.5$, $\phi = 0.9$, $\phi = 0.99$.

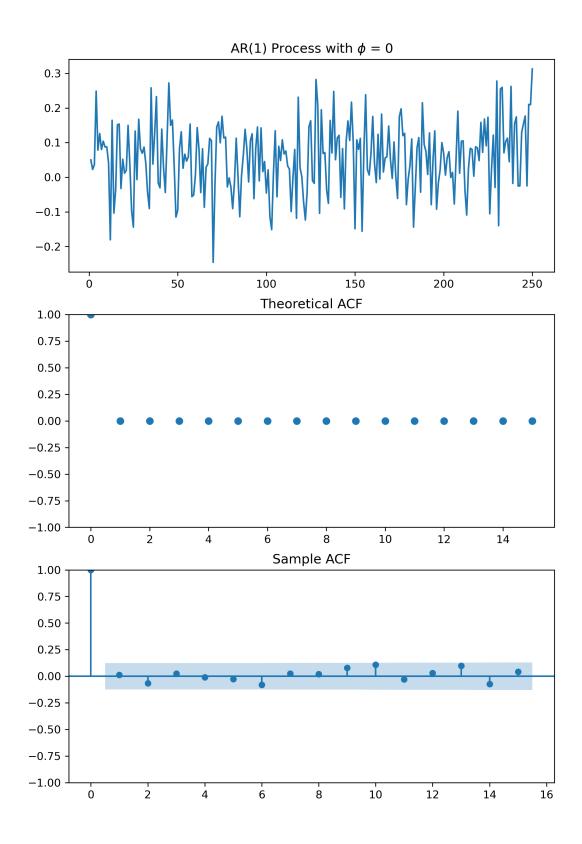
```
# Define Plotting Function
def ar1_plot(phi):
    ar = np.r_[1, -phi] # add zero-lag and negate
    # the AR parameters should have the opposite sign
    ma = np.r_[1] # add zero-lag
    y = 0.05 + arma_generate_sample(ar, ma, scale = 0.1, nsample = 250)

fig, ax = plt.subplots(nrows = 3, ncols = 1,figsize=(8,12))
    ax[0].plot(np.arange(1, 251, 1), y) # first subgraph
    ax[0].title.set_text(
        r'AR(1) Process with $\phi$ = {}'.format(phi)) # add the title
```

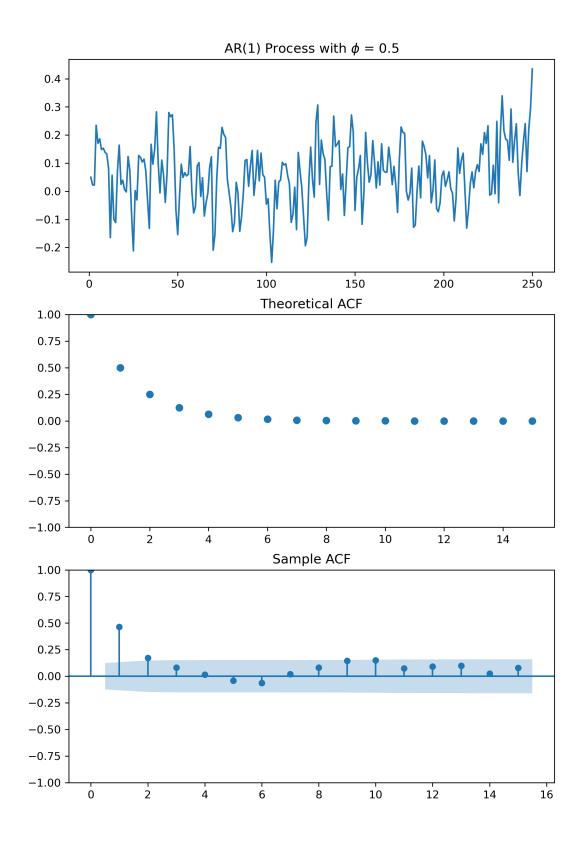
```
theoretical_acf = phi ** np.arange(0, 16, 1)
  ax[1].scatter(np.arange(0, 16, 1), theoretical_acf)
  ax[1].set_ylim([-1.0, 1.0])
  ax[1].title.set_text('Theoretical ACF')

plot_acf(y, lags = 15, ax = ax[2]) # second subgraph
  ax[2].title.set_text('Sample ACF')
  plt.show()

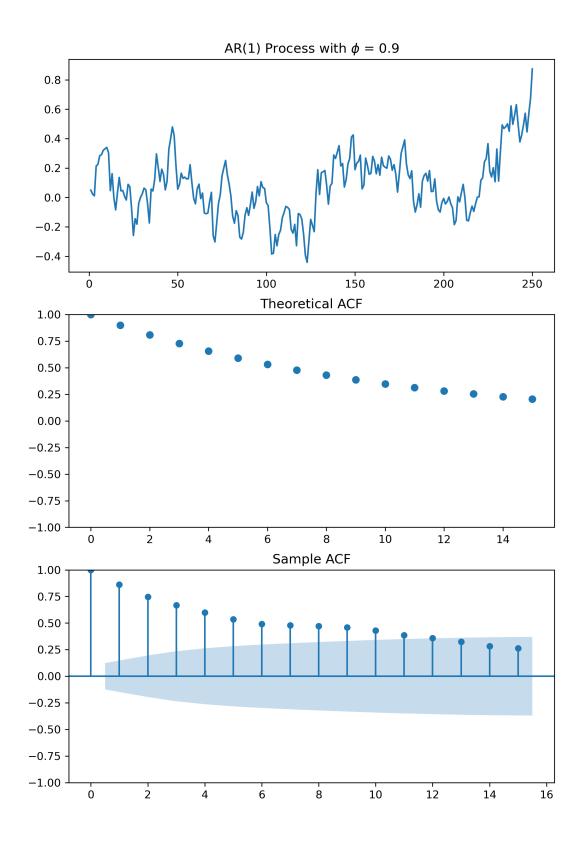
# Phi = 0
  np.random.seed(2022)
  ar1_plot(0)
```



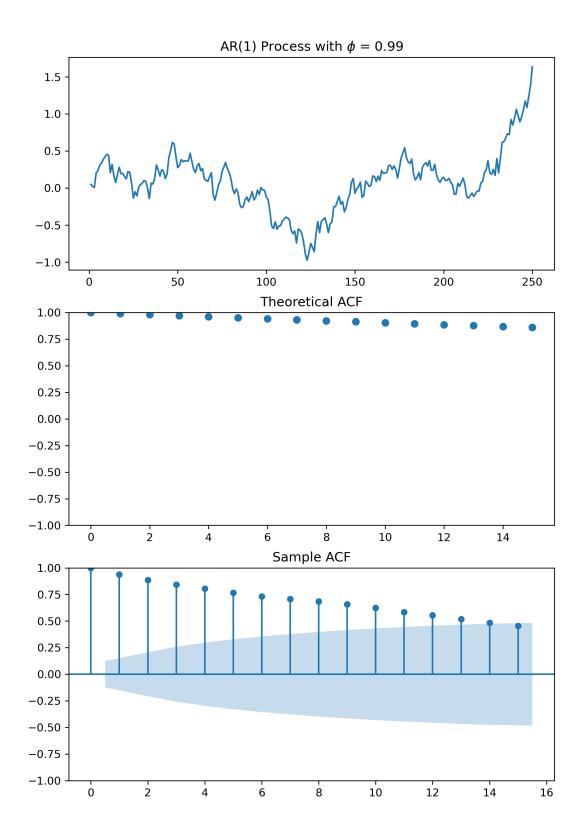
```
# Phi = 0.5
np.random.seed(2022)
ar1_plot(0.5)
```



```
# Phi = 0.9
np.random.seed(2022)
ar1_plot(0.9)
```



```
# Phi = 0.99
np.random.seed(2022)
ar1_plot(0.99)
```



Part (b)

Comment on the behavior of the simulated data series. Which series is close to nonstationary (or persistent) time series?

Solution

The AR(1) process with $\phi=0$ seems to be a stationary process centered around 0.05. Since the coefficient is 0, the modeled time series is not correlated with any of the observations that come before it.

The process with $\phi = 0.5$ begins to demonstrate the autocorrelation we would hope for in an AR(1) process. Namely, there is moderate correlation with the first lag and approximately weak correlation with the second lag. The process itself still looks stationary.

The processes with $\phi=0.9$ and $\phi=0.99$ begin to closely resemble a nonstationary (persistent) time series. They do not appear to have a constant mean across time and there also seems to be some volatility clustering. In these processes, the ACF shows significant autocorrelation across many (10+) lags.

2.3 Problem 3

This exercise uses weekly data of Coca-Cola Co (KO) from the first week of January, 2010 to the first week of March, 2021. Use the adjusted closing prices to compute weekly cc returns. For all the sample auto-correlation functions (ACFs), set the maximum lag to 10.

Part (a)

From the sample ACF, can we claim that the cc returns are white noise? Conduct the Ljung-Box test (with lag = 10) and explain your findings. (Hint: for the level- α ? Ljung-Box test, we reject the null hypothesis if the p-value is less than α ?. Otherwise, we reject the alternative hypothesis.)

```
end = "2021-03-06",
    interval = '1wk')
df.reset_index(inplace = True) # convert index into a column
```

[********* 100%********* 1 of 1 completed

```
df['Date'] = pd.to_datetime(df['Date']) # convert the strings to dates
cc = np.log(df['Adj Close']/df['Adj Close'].shift(1))
cc = np.array(cc)[1:]

# Ljung Box Test
acorr_ljungbox(cc, lags=[10], return_df=True)
```

	lb_stat	lb_pvalue		
10	23.987804	0.007633		

A Ljung-Box statistic of 23.988 implies that we would reject the null at the 1% significance level. This means that we reject the null hypothesis that our process is stationary. Therefore, we cannot claim that our cc returns are white noise since the autocorrelation is not zero (implies dependent time series process).

Part (b)

Estimate an MA(1) model using the cc returns. From the sample ACF of the fitted residuals, can we claim that MA(1) models the (linear) dependence of the cc returns appropriately?

```
from statsmodels.tsa.arima.model import ARIMA
res = ARIMA(cc, order=(0, 0, 1)).fit() # fit the MA(1) model
acorr_ljungbox(res.resid, lags=[10], return_df=True)
```

	lb_stat	lb_pvalue
10	21.1688	0.019947

With a Ljung-Box statistic of 21.1688, we can reject the null (uncorrelated time series process) at the 5% level. Since the autocorrelations are not 0, then we can claim that there is some linear dependence between cc returns.

Part (c)

Find the optimal lag $\hat{q}_{\rm opt}$ if we want to use MA(q) to model the cc returns. Then use teh data to estimate MA($\hat{q}_{\rm opt}$). Do we reject the null hypothesis that $\theta_j=0$ for each $j=1,\ldots,\hat{q}_{\rm opt}$?

Solution

SARIMAX Results

Dep. Variable: y				No.	Observations	:	583	
Model: SARIMAX(0, 0, 1)			1)	Log	Likelihood		1373.729	
Date:	Tı	ie, 14 Mar 2	2023	AIC			-2741.459	
Time:		19:34	1:33	BIC			-2728.354	
Sample:		0	HQIC			-2736.351		
		-	583					
Covariance Ty	pe:		opg					
=========					========			
	coef	std err		z	P> z	[0.025	0.975]	
intercept	0.0016	0.001	 1	.631	0.103	-0.000	0.004	
ma.L1	-0.0784	0.019	-4	.128	0.000	-0.116	-0.041	
sigma2	0.0005	1.39e-05	37	.712	0.000	0.000	0.001	
Ljung-Box (L1) (Q):			.01	Jarque-Bera	-====== (JB):	======================================	:===	
				.94	Prob(JB):	(02)		0.00
Heteroskedasticity (H):			2	.13	Skew:		-1	.55

Prob(H) (two-sided): 0.00 Kurtosis: 13.45

Warnings:

[1] Covariance matrix calculated using the outer product of gradients (complex-step).

It seems that the optimal number of lags for our model is MA(q) model is 1.

```
# Model Coefficients
Est_html = MA_Est.summary().tables[1].as_html()
table = pd.read_html(Est_html, header=0, index_col=0)[0]
coef = table.iloc[:, 0].values
se = table.iloc[:, 1].values
p_vals = table.iloc[:, 3].values
print(coef)
print(se)
```

```
[ 0.0016 -0.0784 0.0005]
[1.00e-03 1.90e-02 1.39e-05]
```

The above values are the coefficient and standard error values for the MA(1) model. Namely, we see a negative coefficient for the lag.

```
print((coef - 0)/se)
print(p_vals) # more precise
```

```
[ 1.6 -4.12631579 35.97122302]
[0.103 0. 0. ]
```

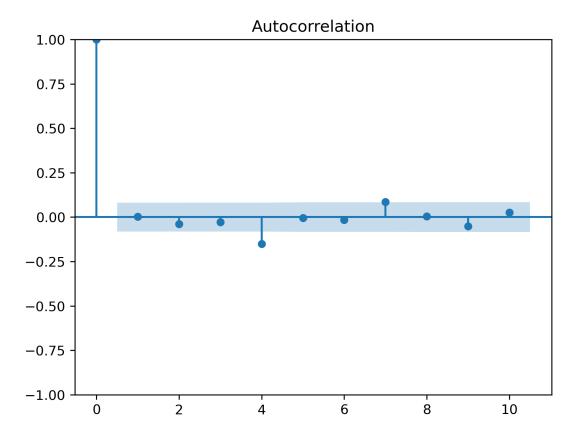
From the above printout and table, we see that the intercept is not statistically significant. However, all other terms seem to be statistically significant. Therefore, we can reject the null that $\theta_1=0$.

Part (d)

Find the sample ACF of the fitted residuals from part (c). From the sample ACF of the fitted residuals, can we claim that $MA(\hat{q}_{opt})$ models the (linear) dependence of the cc returns appropriately?

```
# Plotting
plt.figure()
plot_acf(MA_Est.resid(), lags = 10)
plt.show()
#Ljung-Box
print(acorr_ljungbox(MA_Est.resid(), lags=[10], return_df=True))
```

<Figure size 1920x1440 with 0 Axes>



```
lb_stat lb_pvalue
10 21.189621 0.019809
```

Based on the Ljung-Box statistic, we can reject the null hypothesis (stationarity) at the 5% level. Therefore, yes, we can claim that there is linear dependence.

Part (e)

Find the optimal lags \hat{p}_{opt} and \hat{q}_{opt} if we want to use ARMA(p,q) to model the cc returns. Then use the data to estimate ARMA(\hat{p}_{opt} , \hat{q}_{opt}). From the sample ACF of the fitted residuals, can we claim that ARMA(\hat{p}_{opt} , \hat{q}_{opt}) models the (linear) dependence of the cc returns appropriately?

Solution

SARIMAX Results

DAILTIMA RESULUS							
Dep. Variable:			У	No.	Observations	:	583
Model: SARIMAX(1, 0,		, 2)	Log	Likelihood		1377.945	
Date:	Τι	ıe, 14 Mar	2023	AIC			-2745.890
Time:		19:4	5:04	BIC			-2724.049
Sample:			0	HQIC	;		-2737.377
_		_	583				
Covariance Ty	pe:		opg				
=======	coef	std err	=====	z	P> z	[0.025	0.975]
intercept	0.0001	7.46e-05	1	.875	0.061	-6.31e-06	0.000
ar.L1	0.9122	0.044	20	.758	0.000	0.826	0.998
ma.L1	-0.9839	0.052	-19	.012	0.000	-1.085	-0.883
ma.L2	0.0226	0.026	0	.854	0.393	-0.029	0.074
sigma2	0.0005	1.82e-05	29	.862	0.000	0.001	0.001
Ljung-Box (L1) (Q):			 0	.20	Jarque-Bera	(JB):	2770.92
Prob(Q):			0	.65	Prob(JB):		0.00
Heteroskedasticity (H):			2	.09	Skew:		-1.62
Prob(H) (two-	•		0	.00	Kurtosis:		13.18

Warnings:

[1] Covariance matrix calculated using the outer product of gradients (complex-step).

```
# Ljung-Box
print(acorr_ljungbox(ARMA_Est.resid(), lags=[10], return_df=True))
```

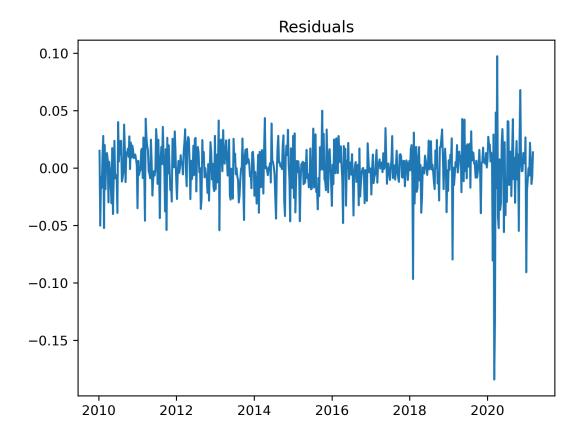
```
lb_stat lb_pvalue
10 17.633248 0.061474
```

Since the Ljung-Box is relatively small, we **cannot** reject the null at the 5% level. Therefore, no we cannot say that the model has a significant linear dependence for the cc returns.

Part (f)

Depict the fitted residuals from the estimation of ARMA(\hat{p}_{opt} , \hat{q}_{opt}) in part (e). Based on the picture, can we claim that ARMA(\hat{p}_{opt} , \hat{q}_{opt}) is a good model for the cc returns?

```
# Plotting
plt.plot(df['Date'].iloc[1:], ARMA_Est.resid())
plt.title('Residuals')
plt.show()
```



The residuals do seem to be stable around 0, therefore we can say that the ARMA model we selected is a good model for the cc returns. cc return is the first difference of log price, so it may be mean stationary. This plot seems to imply this as well; as well as the Ljung-Box test from part (e).