Rami I. Hanna

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Main Focus: A creative, observant, and self-driven team player always striving to learn and contribute insightful solutions to challenging problems. Eager to expand my knowledge in robotics, mechanical and electrical engineering, and computer science seeking a unique opportunity after graduating in August 2023.

EDUCATION

Wentworth Institute of Technology

August 2019 – August 2023 | Boston, MA

B.S. Electromechanical Engineering | GPA: 3.92/4.00

Interdisciplinary degree with a focus on mechanical engineering, electrical engineering, electromechanical systems (ABET accredited)

Memberships: Institute of Electrical and Electronic Engineers (IEEE), Remotely Operated Vehicles (ROV), Robotics, Accelerate

Relevant Courses: Digital System Processing, Feedback and Controls, Fluid Dynamics, Heat Transfer, Industrial Controls, MATLAB

PROFESSIONAL EXPERIENCE

Harvard MicroRobotics Robotistic Co-op

September 2022 - Present | Allston, MA

- Developed webserver using HTML, Flask, Sockets, and MicroROS to control the robot in a teleoperated or autonomous manner.
- Investigated necessary electronic components and how to organize them in an efficient manner based on hydrostatic forces.
- Prototyped various chassis and compliant mechanisms to help robot conform to convex ship hull.
- Collaborated in designing a planetary gearbox which was used for the locomotion of our robot.

Raytheon Technologies Innovation/Robotics Co-op - Confidential Security Clearance

January 2022 – May 2022 | Andover, MA

- Automated bonding process using PLCs, Cobots, and Keyence vision systems yielding ~\$7 million ROI (Project Lead).
- Collaborated with expert automation engineers to increase factory efficiency by implementing an OCR system.
- Upgraded production line process from manual calibration to closed-loop control for increased cycle times and accuracy.
- Utilized CAD software to create modular and custom fixtures for surface mount technology equipment for various circuit cards.

DEKA Research and Development Controls Intern

April 2019 - Sept. 2019 | June 2020 - July 2021 | Manchester, NH

- Responsible for designing and running multiple electrical and mechanical (impact and thermal) tests on biomedical devices.
- Worked directly under lead Controls engineer to design and implement a PID controlled heating and cooling system to operate safely and efficiently via Modbus TCP/IP and LabVIEW.
- Designed an RFID organization system via Modbus TCP/IP and LabVIEW to track and manage subsystem components.
 - O Integrated this system to work with Python and SQL for Batch Production Records.
- Led effort to create a versatile test bench that streamlines multi-source serial data autonomously using Arduino and Python.
- Accepted greater responsibility that was quickly given to me after demonstrating understanding and capability to contribute high quality outputs.

FIRST Robotics Intern

March 2019 - June 2019 | Manchester, NH

- Innovated baseline robots for FIRST demonstration events. Created long-term solutions at competitive costs.
- Modeled 3D printed hardstops which were dynamic enough to be used with different robot models over various years.
- Contributed to source-controlled software suite, ensuring new updates did not conflict within teams.

Washington Street Café and Catering General Help

June 2012 - Present | Concord, NH

• Worked full-time in the summers in between elementary/middle school and now part-time assisting with the catering events, managing, invoices, and other necessities.

SKILLS

- Java, Python, MATLAB, C
 - o PyQT, OpenCV, Numpy, Pandas
- Arduino, Raspberry Pi
- Windows, Linux, Android
- Git and Surround version control
- Microsoft Office Suite

- Electrical wiring/Soldering
- NI cRIO PLC, LabVIEW
- AC/DC circuitry and diagrams
- E-Box Design (KiCad)
- Program and electrical debugging

- Statics and dynamics calculations
- Simple machine work
- SOLIDWORKS CSWA
- 3D Printing
- Public speaking
- Trilingual (English & Arabic, conversational Spanish)

RELEVANT ACTIVITIES & PROJECTS

Turnafit Project

Sept. 2018 - May 2021

- Developed a biomedical device to decrease blood loss on the way to a hospital by using inflation mechanisms and blood clotting technologies.
- Researched and designed prototypes which were presented to EMTs, patent lawyers, and entrepreneurs to receive feedback.

Robotics - FRC Team 5813 "Morpheus"

June 2017 - May 2019

- Worked with senior engineers and mentors: designing, building, and testing software, electrical, and mechanical subsystems.
- Used PixyCam to help the robot autonomously track its target; this program won a "Design and Innovation" award.
- Mentored team Java proficiency and provide continued assistance with the development of the robot.