lib-arduino

Generated by Doxygen 1.8.15

1 lib-arduino	1
2 Data Structure Index	3
2.1 Data Structures	 3
3 File Index	5
3.1 File List	 5
4 Data Structure Documentation	7
4.1 BCD Struct Reference	 7
4.1.1 Detailed Description	 7
4.1.2 Field Documentation	 8
4.1.2.1 a	 8
4.1.2.2 b	 8
4.1.2.3 c	 8
4.1.2.4 d	 8
4.1.2.5 delay	 8
4.1.2.6 dp	 9
4.1.2.7 e	 9
4.1.2.8 f	 9
4.1.2.9 g	 9
4.1.2.10 loop	 9
4.2 Button Struct Reference	 9
4.2.1 Detailed Description	 10
4.2.2 Field Documentation	 10
4.2.2.1 fn	 10
4.2.2.2 mode	 10
4.2.2.3 pin_number	 10
4.3 bytes Struct Reference	 11
4.3.1 Field Documentation	 11
4.3.1.1 COM0	 11
4.3.1.2 COM1	 11
4.3.1.3 CS0	 11
4.3.1.4 CS1	 11
4.3.1.5 CS2	 12
4.3.1.6 WGM0	 12
4.3.1.7 WGM1	 12
4.3.1.8 WGM2	 12
4.3.1.9 WGM3	 12
4.4 Led Struct Reference	 12
4.4.1 Detailed Description	13
4.4.2 Field Documentation	13
4.4.2.1 pin_number	 13

4.4.2.2 state	13
4.5 Pin Struct Reference	13
4.5.1 Detailed Description	14
4.5.2 Field Documentation	14
4.5.2.1 _DDR	14
4.5.2.2 _OCRA	14
4.5.2.3 _OCRB	14
4.5.2.4 _PIN	14
4.5.2.5 _PORT	14
4.5.2.6 _TCCA	15
4.5.2.7 _TCCB	15
4.5.2.8 P	15
5 File Documentation	17
5.1 src/bcd.c File Reference	17
5.1.1 Function Documentation	17
5.1.1.1 bcd_clear()	17
5.1.1.2 bcd_delay()	
5.1.1.3 bcd_free()	18
5.1.1.4 bcd_set_loop()	
5.1.1.5 bcd_setup()	
5.1.1.6 bcd_show_char()	19
5.1.1.7 bcd_show_string()	20
5.2 src/button.c File Reference	
5.2.1 Function Documentation	20
5.2.1.1 btn_fired()	20
5.2.1.2 btn_pressed()	21
5.2.1.3 btn_register_fn()	21
5.2.1.4 btn_set_mode()	21
5.2.1.5 btn_setup()	22
5.3 src/delay.c File Reference	22
5.3.1 Function Documentation	22
5.3.1.1 delay_1ms()	22
5.3.1.2 delay_1us()	23
5.3.1.3 delay_ms()	23
5.3.1.4 delay_us()	23
5.4 src/include/bcd.h File Reference	23
5.4.1 Function Documentation	24
5.4.1.1 bcd_clear()	24
5.4.1.2 bcd_delay()	24
5.4.1.3 bcd_free()	25
5.4.1.4 bcd_set_loop()	25

5.4.1.5 bcd_setu	o()	 	 25
5.4.1.6 bcd_show	<u>/_</u> char()	 	 26
5.4.1.7 bcd_show	v_string()	 	 26
5.5 src/include/bcd_seven.h Fil	e Reference	 	 26
5.5.1 Macro Definition Do	cumentation	 	 29
5.5.1.1 rep_a .		 	 30
5.5.1.2 rep_b .		 	 30
5.5.1.3 rep_c .		 	 30
5.5.1.4 rep_d .		 	 30
5.5.1.5 rep_dp		 	 30
5.5.1.6 rep_e .		 	 30
5.5.1.7 rep_f .		 	 31
5.5.1.8 rep_g .		 	 31
5.5.2 Variable Documenta	ation	 	 31
5.5.2.1 SevenSeg	gmentASCII	 	 31
5.5.2.2 sseg_0		 	 31
5.5.2.3 sseg_1		 	 31
5.5.2.4 sseg_2		 	 32
5.5.2.5 sseg_3		 	 32
5.5.2.6 sseg_4		 	 32
5.5.2.7 sseg_5		 	 32
5.5.2.8 sseg_6		 	 32
5.5.2.9 sseg_7		 	 32
5.5.2.10 sseg_8		 	 33
5.5.2.11 sseg_9		 	 33
5.5.2.12 sseg_A		 	 33
5.5.2.13 sseg_a		 	 33
5.5.2.14 sseg_B		 	 33
5.5.2.15 sseg_b		 	 33
5.5.2.16 sseg_C		 	 34
5.5.2.17 sseg_c		 	 34
5.5.2.18 sseg_D		 	 34
5.5.2.19 sseg_d		 	 34
5.5.2.20 sseg_E		 	 34
5.5.2.21 sseg_e		 	 34
5.5.2.22 sseg_F		 	 35
5.5.2.23 sseg_f		 	 35
5.5.2.24 sseg_G		 	 35
5.5.2.26 sseg_H		 	 35
5.5.2.27 sseg_h		 	 35
5.5.2.28 sseg_l		 	 36

5.5.2.29 sseg_i	36
5.5.2.30 sseg_J	36
5.5.2.31 sseg_j	36
5.5.2.32 sseg_K	36
5.5.2.33 sseg_k	36
5.5.2.34 sseg_L	37
5.5.2.35 sseg_l	37
5.5.2.36 sseg_M	37
5.5.2.37 sseg_m	37
5.5.2.38 sseg_N	37
5.5.2.39 sseg_n	37
5.5.2.40 sseg_O	38
5.5.2.41 sseg_o	38
5.5.2.42 sseg_P	38
5.5.2.43 sseg_p	38
5.5.2.44 sseg_Q	38
5.5.2.45 sseg_q	38
5.5.2.46 sseg_R	39
5.5.2.47 sseg_r	39
5.5.2.48 sseg_S	39
5.5.2.49 sseg_s	39
5.5.2.50 sseg_T	39
5.5.2.51 sseg_t	
5.5.2.52 sseg_U	40
5.5.2.53 sseg_u	40
5.5.2.54 sseg_V	40
5.5.2.55 sseg_v	40
5.5.2.56 sseg_W	40
5.5.2.57 sseg_w	40
5.5.2.58 sseg_X	41
5.5.2.59 sseg_x	41
5.5.2.60 sseg_Y	41
5.5.2.61 sseg_y	41
5.5.2.62 sseg_Z	41
5.5.2.63 sseg_z	41
5.6 src/include/button.h File Reference	42
5.6.1 Typedef Documentation	42
5.6.1.1 Button_Mode	42
5.6.2 Enumeration Type Documentation	42
5.6.2.1 button_mode	42
5.6.3 Function Documentation	43
5.6.3.1 btn_fired()	43

5.6.3.2 btn_pressed()	43
5.6.3.3 btn_register_fn()	43
5.6.3.4 btn_set_mode()	44
5.6.3.5 btn_setup()	44
5.7 src/include/delay.h File Reference	44
5.7.1 Function Documentation	45
5.7.1.1 delay_1ms()	45
5.7.1.2 delay_1us()	45
5.7.1.3 delay_ms()	45
5.7.1.4 delay_us()	45
5.8 src/include/led.h File Reference	46
5.8.1 Typedef Documentation	46
5.8.1.1 Led_State	47
5.8.2 Enumeration Type Documentation	47
5.8.2.1 led_state	47
5.8.3 Function Documentation	47
5.8.3.1 led_blink()	47
5.8.3.2 led_free()	47
5.8.3.3 led_kill_light()	48
5.8.3.4 led_make_light()	48
5.8.3.5 led_setup()	48
5.8.3.6 led_switch_light()	49
5.9 src/include/macros.h File Reference	49
5.9.1 Macro Definition Documentation	49
5.9.1.1 clr_bit	49
5.9.1.2 comp_masks	49
5.9.1.3 MACROS	49
5.9.1.4 set_bit	50
5.9.1.5 swt_bit	50
5.9.1.6 tst_bit	50
5.10 src/include/pins.h File Reference	50
5.10.1 Macro Definition Documentation	51
5.10.1.1 F_CPU	51
5.10.1.2 HIGH	51
5.10.1.3 LOW	51
5.10.2 Function Documentation	51
5.10.2.1 clr_pullup()	51
5.10.2.2 digital_write()	52
5.10.2.3 set_input()	52
5.10.2.4 set_output()	52
5.10.2.5 set_pullup()	53
5.10.2.6 test_input()	53

5.10.2.7 toggle_pullup()	53
5.10.3 Variable Documentation	53
5.10.3.1 Bytes	53
5.10.3.2 Pins	54
5.11 src/include/pwm.h File Reference	54
5.11.1 Function Documentation	54
5.11.1.1 lookup_cs()	54
5.11.1.2 lookup_cs2()	55
5.11.1.3 lookup_ocr()	55
5.11.1.4 lookup_prescalar()	55
5.11.1.5 pwmwave()	55
5.11.1.6 sqrwave()	56
5.12 src/include/supersonic.h File Reference	56
5.12.1 Function Documentation	56
5.12.1.1 supersonic()	56
5.13 src/include/uart.h File Reference	57
5.13.1 Macro Definition Documentation	57
5.13.1.1 BAUD	57
5.13.1.2 F_CPU	57
5.13.2 Function Documentation	57
5.13.2.1 uart_getchar()	58
5.13.2.2 uart_init()	58
5.13.2.3 uart_putchar()	58
5.14 src/led.c File Reference	58
5.14.1 Function Documentation	58
5.14.1.1 led_blink()	58
5.14.1.2 led_free()	59
5.14.1.3 led_kill_light()	59
5.14.1.4 led_make_light()	59
5.14.1.5 led_setup()	60
5.14.1.6 led_switch_light()	60
5.15 src/pins.c File Reference	60
5.15.1 Function Documentation	61
5.15.1.1 clr_pullup()	61
5.15.1.2 digital_write()	61
5.15.1.3 set_input()	61
5.15.1.4 set_output()	62
5.15.1.5 set_pullup()	62
5.15.1.6 test_input()	62
5.15.1.7 toggle_pullup()	63
5.15.2 Variable Documentation	63
5.15.2.1 Bytes	63

Index	69
5.19.2.1 uart_io	67
5.19.2 Variable Documentation	67
5.19.1.3 uart_putchar()	67
5.19.1.2 uart_init()	67
5.19.1.1 uart_getchar()	67
5.19.1 Function Documentation	67
5.19 src/uart.c File Reference	67
5.18.1.1 supersonic()	66
5.18.1 Function Documentation	66
5.18 src/supersonic.c File Reference	66
5.17 src/README.md File Reference	66
5.16.1.6 sqrwave()	66
5.16.1.5 pwmwave()	65
5.16.1.4 lookup_prescalar()	65
5.16.1.3 lookup_ocr()	65
5.16.1.2 lookup_cs2()	64
5.16.1.1 lookup_cs()	64
5.16.1 Function Documentation	64
5.16 src/pwm.c File Reference	64
5.15.2.2 Pins	63

# **Chapter 1**

# lib-arduino

Biblioteca para utilização de módulos básicos para Arduino

# Introdução

Biblioteca desenvolvida como primeiro trabalho da disciplina de Sistemas Digitais, curso Ciência da Computação pela Universidade Estadual de Maringá. O trabalho consiste em uma bilblioteca para integração com os seguintes módulos para o microcontrolador Arduino:

- · Manipulação dos pinos E/S
- · Geração de ondas
- · Delay variável
- Interface com LED
- · Interface com botão
- Interface com Display de 7-segmentos
- · Sensor de distância

# Requisitos

A biblioteca foi desenvolvida para ambiente Linux, chip alvo Atmega328p. As dependências: avrdude

# Utilização

Crie um arquivo fonte main.c no diretorio src/exec, em seguida: make

Para utilizar a biblioteca basta incluir as arquivos header. Ex: #include "pins.h"

# Documentação

A documentação está disponível em doc/latex/refman.pdf.

# **Autores**

Ricardo Henrique Brunetto ra94182

Thiago Kira ra78750

2 lib-arduino

# Chapter 2

# **Data Structure Index**

# 2.1 Data Structures

Here are the data structures with brief descriptions:

BCD																 							 			7
Butto	ı			 												 							 			ç
bytes				 												 							 			11
Led				 												 							 			12
Pin				 												 	 						 			13

Data Structure Index

# **Chapter 3**

# File Index

# 3.1 File List

Here is a list of all files with brief descriptions:

Src/bcd.c	17
src/button.c	20
src/delay.c	22
src/led.c	58
src/pins.c	60
src/pwm.c	64
src/supersonic.c	66
src/uart.c	67
src/include/bcd.h	23
src/include/bcd_seven.h	26
src/include/button.h	42
src/include/delay.h	44
src/include/led.h	46
src/include/macros.h	49
src/include/pins.h	50
src/include/pwm.h	54
src/include/supersonic.h	56
src/include/uart h	57

6 File Index

# Chapter 4

# **Data Structure Documentation**

# 4.1 BCD Struct Reference

```
#include <bcd.h>
```

#### **Data Fields**

```
• uint8 ta
```

Represents the display pin 'a'.

uint8\_t b

Represents the display pin 'b'.

• uint8\_t c

Represents the display pin 'c'.

uint8\_t d

Represents the display pin 'd'.

• uint8\_t e

Represents the display pin 'e'.

• uint8\_t f

Represents the display pin 'f'.

uint8\_t g

Represents the display pin 'g'.

uint8\_t dp

Represents the display pin 'dot'.

· double delay

Represents a delay between character transition.

uint8\_t loop

Stores the current display mode: 0 for unique exhibition, or any other value for cyclic exhibition.

#### 4.1.1 Detailed Description

#### Standard 7-seg Display structure

BCD implements a simple display that can be used by setting up each digital pin where display is connected. This structure contains the main functions while using a 7-seg display, providing a simple, but powerful, interface to be expanded.

# 4.1.2 Field Documentation

Represents a delay between character transition.

4.1.2.1 a
uint8_t BCD::a
Represents the display pin 'a'.
4.1.2.2 b
uint8_t BCD::b
Represents the display pin 'b'.
4.1.2.3 c
uint8_t BCD::c
Represents the display pin 'c'.
4.1.2.4 d
uint8_t BCD::d
Represents the display pin 'd'.
4.1.2.5 delay
double BCD::delay

# 4.1.2.6 dp uint8\_t BCD::dp Represents the display pin 'dot'. 4.1.2.7 e uint8\_t BCD::e Represents the display pin 'e'. 4.1.2.8 f uint8\_t BCD::f Represents the display pin 'f'. 4.1.2.9 g uint8\_t BCD::g Represents the display pin 'g'. 4.1.2.10 loop uint8\_t BCD::loop Stores the current display mode: 0 for unique exhibition, or any other value for cyclic exhibition.

The documentation for this struct was generated from the following file:

• src/include/bcd.h

# 4.2 Button Struct Reference

#include <button.h>

# **Data Fields**

• uint8\_t pin\_number

Digital pin number associated to Button.

• Button\_Mode mode

Specifies if the button waits to be released to fire action.

void(\* fn )()

Registered function, to be called whether button is fired.

# 4.2.1 Detailed Description

Standard Button Structure

This file provides a simple Button Structure, with a simple interface to basic operations involving buttons.

#### 4.2.2 Field Documentation

## 4.2.2.1 fn

```
void(* Button::fn) ()
```

Registered function, to be called whether button is fired.

#### 4.2.2.2 mode

```
Button_Mode Button::mode
```

Specifies if the button waits to be released to fire action.

## 4.2.2.3 pin\_number

```
uint8_t Button::pin_number
```

Digital pin number associated to Button.

The documentation for this struct was generated from the following file:

• src/include/button.h

# 4.3 bytes Struct Reference

```
#include <pins.h>
```

#### **Data Fields**

- volatile uint8\_t WGM0
- volatile uint8\_t WGM1
- volatile uint8\_t WGM2
- volatile uint8\_t COM0
- volatile uint8\_t COM1
- volatile uint8\_t CS0
- volatile uint8\_t CS1
- volatile uint8\_t CS2
- volatile uint8\_t WGM3

#### 4.3.1 Field Documentation

#### 4.3.1.1 COM0

volatile uint8\_t bytes::COM0

#### 4.3.1.2 COM1

volatile uint8\_t bytes::COM1

#### 4.3.1.3 CS0

volatile uint8\_t bytes::CS0

# 4.3.1.4 CS1

volatile uint8\_t bytes::CS1

# 4.3.1.5 CS2

volatile uint8\_t bytes::CS2

#### 4.3.1.6 WGM0

volatile uint8\_t bytes::WGM0

#### 4.3.1.7 WGM1

volatile uint8\_t bytes::WGM1

# 4.3.1.8 WGM2

volatile uint8\_t bytes::WGM2

#### 4.3.1.9 WGM3

volatile uint8\_t bytes::WGM3

The documentation for this struct was generated from the following file:

• src/include/pins.h

# 4.4 Led Struct Reference

#include <led.h>

# **Data Fields**

• int pin\_number

Digital pin number associated to Led.

• Led\_State state

Represents a Led State, used to control on/off functions.

4.5 Pin Struct Reference

#### 4.4.1 Detailed Description

Standard Led Structure

This file provides a simple Led Structure, with a simple interface to basic operations.

#### 4.4.2 Field Documentation

```
4.4.2.1 pin_number
```

int Led::pin\_number

Digital pin number associated to Led.

#### 4.4.2.2 state

```
Led_State Led::state
```

Represents a Led State, used to control on/off functions.

The documentation for this struct was generated from the following file:

• src/include/led.h

# 4.5 Pin Struct Reference

```
#include <pins.h>
```

## **Data Fields**

volatile uint8\_t P

Pin number associated by ATMega328p.

volatile uint8\_t \* \_PORT

Points to a PORT register (pullup)

volatile uint8\_t \* \_DDR

Points to a DDR register (data direction)

volatile uint8\_t \* \_PIN

Points to a PIN register (input signal)

volatile uint8\_t \* \_TCCA

Points to the TCCA register (PWM)

volatile uint8\_t \* \_TCCB

Points to the TCCB register (PWM)

volatile uint8\_t \* \_OCRA

Points to the OCRA register (PWM)

volatile uint8\_t \* \_OCRB

Points to the OCRB register (PWM)

# 4.5.1 Detailed Description

Standard Pin Structure

This file provides a simple Pin Structure, which contains sufficient data to allow the basic operations that involves I/O.

#### 4.5.2 Field Documentation

```
4.5.2.1 _DDR

volatile uint8_t* Pin::_DDR

Points to a DDR register (data direction)
```

```
4.5.2.2 _OCRA
```

```
volatile uint8_t* Pin::_OCRA
```

Points to the OCRA register (PWM)

```
4.5.2.3 _OCRB
```

```
volatile uint8_t* Pin::_OCRB
```

Points to the OCRB register (PWM)

#### 4.5.2.4 \_PIN

```
volatile uint8_t* Pin::_PIN
```

Points to a PIN register (input signal)

# 4.5.2.5 \_PORT

```
volatile uint8_t* Pin::_PORT
```

Points to a PORT register (pullup)

4.5 Pin Struct Reference

```
4.5.2.6 _TCCA

volatile uint8_t* Pin::_TCCA

Points to the TCCA register (PWM)

4.5.2.7 _TCCB

volatile uint8_t* Pin::_TCCB

Points to the TCCB register (PWM)
```

volatile uint8\_t Pin::P

4.5.2.8 P

Pin number associated by ATMega328p.

The documentation for this struct was generated from the following file:

• src/include/pins.h

# **Chapter 5**

# **File Documentation**

# 5.1 src/bcd.c File Reference

```
#include "bcd.h"
#include "bcd_seven.h"
```

#### **Functions**

BCD \* bcd\_setup (uint8\_t a, uint8\_t b, uint8\_t c, uint8\_t d, uint8\_t e, uint8\_t f, uint8\_t g, uint8\_t dp, double delay)

Setups a new instance of a display.

• void bcd\_show\_char (BCD \*display, char c)

Displays an ASCII character in a display.

void bcd\_set\_loop (BCD \*display, uint8\_t loop)

Sets a loop mode for a display.

void bcd\_delay (BCD \*display)

Freezes a display for a presetted delay.

void bcd\_clear (BCD \*display)

Clears a display.

void bcd\_show\_string (BCD \*display, char \*str)

Displays a string in a display, a character at a time, interleaved by a delay.

void bcd\_free (BCD \*display)

Destroys a display instance.

#### 5.1.1 Function Documentation

# 5.1.1.1 bcd\_clear()

# Clears a display.

18 File Documentation

# **Parameters**

display	Display instance.
---------	-------------------

# 5.1.1.2 bcd\_delay()

Freezes a display for a presetted delay.

#### **Parameters**

display	Display instance.
---------	-------------------

# 5.1.1.3 bcd\_free()

Destroys a display instance.

#### **Parameters**

display	Display instance.
---------	-------------------

# 5.1.1.4 bcd\_set\_loop()

Sets a loop mode for a display.

#### **Parameters**

display	Display instance.
loop	Defines a unique exhibition (0) or a cyclic exhibition (any other value).

# 5.1.1.5 bcd\_setup()

```
BCD* bcd_setup (

uint8_t a,

uint8_t b,

uint8_t c,

uint8_t d,

uint8_t e,

uint8_t f,

uint8_t g,

uint8_t dp,

double delay)
```

Setups a new instance of a display.

#### **Parameters**

<ul> <li>Digital pin where the display pin 'a' is plugged.</li> <li>Digital pin where the display pin 'b' is plugged.</li> <li>Digital pin where the display pin 'c' is plugged.</li> <li>Digital pin where the display pin 'd' is plugged.</li> <li>Digital pin where the display pin 'e' is plugged.</li> <li>Digital pin where the display pin 'f' is plugged.</li> <li>Digital pin where the display pin 'g' is plugged.</li> <li>Digital pin where the display pin 'g' is plugged.</li> <li>Digital pin where the dot pin of display is plugged.</li> <li>Delay between transactions, if multiple characters are going to be shown.</li> </ul>		
<ul> <li>Digital pin where the display pin 'c' is plugged.</li> <li>Digital pin where the display pin 'd' is plugged.</li> <li>Digital pin where the display pin 'e' is plugged.</li> <li>Digital pin where the display pin 'f' is plugged.</li> <li>Digital pin where the display pin 'g' is plugged.</li> <li>Digital pin where the display pin 'g' is plugged.</li> <li>Digital pin where the dot pin of display is plugged.</li> </ul>	а	Digital pin where the display pin 'a' is plugged.
<ul> <li>Digital pin where the display pin 'd' is plugged.</li> <li>Digital pin where the display pin 'e' is plugged.</li> <li>Digital pin where the display pin 'f' is plugged.</li> <li>Digital pin where the display pin 'g' is plugged.</li> <li>Digital pin where the dot pin of display is plugged.</li> </ul>	b	Digital pin where the display pin 'b' is plugged.
<ul> <li>Digital pin where the display pin 'e' is plugged.</li> <li>Digital pin where the display pin 'f' is plugged.</li> <li>Digital pin where the display pin 'g' is plugged.</li> <li>Digital pin where the dot pin of display is plugged.</li> </ul>	С	Digital pin where the display pin 'c' is plugged.
f Digital pin where the display pin 'f' is plugged. g Digital pin where the display pin 'g' is plugged. dp Digital pin where the dot pin of display is plugged.	d	Digital pin where the display pin 'd' is plugged.
<ul> <li>g Digital pin where the display pin 'g' is plugged.</li> <li>dp Digital pin where the dot pin of display is plugged.</li> </ul>	е	Digital pin where the display pin 'e' is plugged.
dp Digital pin where the dot pin of display is plugged.	f	Digital pin where the display pin 'f' is plugged.
	g	Digital pin where the display pin 'g' is plugged.
delay Delay between transactions, if multiple characters are going to be shown.	dp	Digital pin where the dot pin of display is plugged.
	delay	Delay between transactions, if multiple characters are going to be shown.

#### Returns

A pointer to display structure.

# 5.1.1.6 bcd\_show\_char()

```
void bcd_show_char ( \frac{BCD \ * \ display,}{char \ character} )
```

Displays an ASCII character in a display.

#### **Parameters**

display	Display instance.	
character	Character to be shown.	

20 File Documentation

#### 5.1.1.7 bcd\_show\_string()

```
void bcd_show_string ( \frac{\text{BCD} * display,}{\text{char} * str} )
```

Displays a string in a display, a character at a time, interleaved by a delay.

#### **Parameters**

display	Display instance.	
str	String to be shown.	

# 5.2 src/button.c File Reference

```
#include "button.h"
#include <stdlib.h>
```

#### **Functions**

• Button \* btn\_setup (uint8\_t pin\_number)

Setups a new instance of a Button.

void btn\_register\_fn (Button \*b, void \*function)

Registers a function to be called whether button is fired.

• void btn\_set\_mode (Button \*b, Button\_Mode mode)

Changes button behavior, waiting or not to be released to fire action.

void btn\_fired (Button \*b)

Verifies if a button is pressed at moment and fires it's action.

uint8\_t btn\_pressed (Button \*b)

Verifies if a button is pressed at moment.

#### 5.2.1 Function Documentation

#### 5.2.1.1 btn\_fired()

Verifies if a button is pressed at moment and fires it's action.

# Parameters

b Button instance.

#### 5.2.1.2 btn\_pressed()

```
uint8_t btn_pressed ( {\tt Button} \ * \ b \ )
```

Verifies if a button is pressed at moment.

#### **Parameters**

```
b Button instance.
```

# Returns

Returns 0 if button is not pressed, any value otherwise.

#### 5.2.1.3 btn\_register\_fn()

Registers a function to be called whether button is fired.

#### **Parameters**

b	Button instance.
function	Function pointer.

# 5.2.1.4 btn\_set\_mode()

Changes button behavior, waiting or not to be released to fire action.

#### **Parameters**

b	Button instance.	
mode	New button mode.	

22 File Documentation

#### 5.2.1.5 btn\_setup()

Setups a new instance of a Button.

**Parameters** 

number Digital pin number associated to the Button.

#### Returns

A pointer to **Button** structure.

# 5.3 src/delay.c File Reference

```
#include "delay.h"
```

#### **Functions**

```
• void delay_1us ()
```

Delays for, approximately, 1 microssecond.

• void delay\_1ms ()

Delays for, approximately, 1 millissecond.

• void delay\_us (uint32\_t time)

Delays for, approximately, a specified time, in microsseconds.

void delay\_ms (uint32\_t time)

Delays for, approximately, a specified time, in milliseconds.

#### 5.3.1 Function Documentation

# 5.3.1.1 delay\_1ms()

```
void delay_1ms (
     void )
```

Delays for, approximately, 1 millissecond.

#### 5.3.1.2 delay\_1us()

```
void delay_lus (
     void )
```

Delays for, approximately, 1 microssecond.

# 5.3.1.3 delay\_ms()

Delays for, approximately, a specified time, in milliseconds.

#### **Parameters**

```
time | Time for delay (in milliseconds)
```

#### 5.3.1.4 delay\_us()

```
void delay_us (
          uint32_t )
```

Delays for, approximately, a specified time, in microsseconds.

#### **Parameters**

time Time for delay (in microsseconds)

# 5.4 src/include/bcd.h File Reference

```
#include "pins.h"
#include <stdlib.h>
```

#### **Data Structures**

• struct BCD

24 File Documentation

#### **Functions**

BCD \* bcd\_setup (uint8\_t a, uint8\_t b, uint8\_t c, uint8\_t d, uint8\_t e, uint8\_t f, uint8\_t g, uint8\_t dp, double delay)

Setups a new instance of a display.

• void bcd\_show\_char (BCD \*display, char character)

Displays an ASCII character in a display.

void bcd show string (BCD \*display, char \*str)

Displays a string in a display, a character at a time, interleaved by a delay.

void bcd\_delay (BCD \*display)

Freezes a display for a presetted delay.

void bcd\_clear (BCD \*display)

Clears a display.

• void bcd\_set\_loop (BCD \*display, uint8\_t loop)

Sets a loop mode for a display.

void bcd\_free (BCD \*display)

Destroys a display instance.

#### 5.4.1 Function Documentation

#### 5.4.1.1 bcd\_clear()

#### Clears a display.

#### Parameters

display Displa
----------------

#### 5.4.1.2 bcd\_delay()

Freezes a display for a presetted delay.

#### **Parameters**

display	Display instance.
uispiay	Display illistance.

# 5.4.1.3 bcd\_free()

Destroys a display instance.

#### **Parameters**

display	Display instance.
---------	-------------------

#### 5.4.1.4 bcd\_set\_loop()

Sets a loop mode for a display.

#### **Parameters**

display	Display instance.
loop	Defines a unique exhibition (0) or a cyclic exhibition (any other value).

## 5.4.1.5 bcd\_setup()

```
BCD* bcd_setup (

uint8_t a,

uint8_t b,

uint8_t c,

uint8_t d,

uint8_t e,

uint8_t f,

uint8_t g,

uint8_t dp,

double delay)
```

Setups a new instance of a display.

#### **Parameters**

а	Digital pin where the display pin 'a' is plugged.
<ul> <li>b Digital pin where the display pin 'b' is plugged.</li> <li>c Digital pin where the display pin 'c' is plugged.</li> </ul>	
е	Digital pin where the display pin 'e' is plugged.

26 File Documentation

#### **Parameters**

f	Digital pin where the display pin 'f' is plugged.	
g	Digital pin where the display pin 'g' is plugged.	
dp	Digital pin where the dot pin of display is plugged.	
delay	Delay between transactions, if multiple characters are going to be shown.	

#### Returns

A pointer to display structure.

#### 5.4.1.6 bcd\_show\_char()

```
void bcd_show_char ( \frac{BCD \ * \ display,}{char \ character} )
```

Displays an ASCII character in a display.

# **Parameters**

display	Display instance.
character	Character to be shown.

# 5.4.1.7 bcd\_show\_string()

```
void bcd_show_string ( \frac{\text{BCD} * display,}{\text{char} * str} )
```

Displays a string in a display, a character at a time, interleaved by a delay.

#### **Parameters**

display	Display instance.
str	String to be shown.

# 5.5 src/include/bcd\_seven.h File Reference

# **Macros**

• #define rep\_a 0

```
Represents the display pin 'a'.
    • #define rep_b 1
          Represents the display pin 'b'.
    • #define rep c 2
          Represents the display pin 'c'.
    • #define rep d 3
          Represents the display pin 'd'.
    • #define rep e 4
          Represents the display pin 'e'.
    • #define rep_f 5
          Represents the display pin 'f'.
    • #define rep g 6
          Represents the display pin 'g'.
    • #define rep_dp 7
          Represents the display pin 'dp'.
Variables
    • uint8 t sseg 0 [] = {6, rep a, rep b, rep c, rep d, rep e, rep f}
          Specifies pins to write '0'.
    uint8_t sseg_1 [] = {2, rep_b, rep_c}
          Specifies pins to write '1'.
    uint8_t sseg_2 [] = {5, rep_a, rep_b, rep_d, rep_e, rep_g}
          Specifies pins to write '2'.
    uint8_t sseg_3 [] = {5, rep_a, rep_b, rep_c, rep_d, rep_g}
          Specifies pins to write '3'.
    uint8_t sseg_4 [] = {4, rep_b, rep_c, rep_f, rep_g}
          Specifies pins to write '4'.
    • uint8_t sseg_5 [] = {5, rep_a, rep_c, rep_d, rep_f, rep_g}
          Specifies pins to write '5'.
    uint8_t sseg_6 [] = {6, rep_a, rep_c, rep_d, rep_e, rep_f, rep_g}
          Specifies pins to write '6'.
    • uint8_t sseg_7 [] = {3, rep_a, rep_b, rep_c}
          Specifies pins to write '7'.
    uint8_t sseg_8 [] = {7, rep_a, rep_b, rep_c, rep_d, rep_e, rep_f, rep_g}
          Specifies pins to write '8'.
    • uint8_t sseg_9 [] = {6, rep_a, rep_b, rep_c, rep_d, rep_f, rep_g}
          Specifies pins to write '9'.
    uint8_t sseg_A [] = {6, rep_a, rep_b, rep_c, rep_e, rep_f, rep_g}
          Specifies pins to write 'A'.
    uint8_t sseg_B [] = {5, rep_c, rep_d, rep_e, rep_f, rep_g}
          Specifies pins to write 'B'.
    uint8_t sseg_C [] = {4, rep_a, rep_d, rep_e, rep_f}
          Specifies pins to write 'C'.
    uint8_t sseg_D [] = {5, rep_b, rep_c, rep_d, rep_e, rep_g}
          Specifies pins to write 'D'.
    uint8_t sseg_E [] = {5, rep_a, rep_d, rep_e, rep_f, rep_g}
          Specifies pins to write 'E'.
    uint8_t sseg_F [] = {4, rep_a, rep_e, rep_f, rep_g}
          Specifies pins to write 'F'.
```

```
uint8_t sseg_G [] = {5, rep_a, rep_c, rep_d, rep_e, rep_f}
      Specifies pins to write 'G'.
uint8_t sseg_H [] = {5, rep_b, rep_c, rep_e, rep_f, rep_g}
     Specifies pins to write 'H'.
• uint8_t sseg_l [] = {2, rep_e, rep_f}
      Specifies pins to write 'I'.
uint8_t sseg_J [] = {4, rep_b, rep_c, rep_d, rep_e}
      Specifies pins to write 'J'.
uint8_t sseg_K [] = {5, rep_a, rep_c, rep_e, rep_f, rep_g}
      Specifies pins to write 'K'.
uint8_t sseg_L [] = {3, rep_d, rep_e, rep_f}
      Specifies pins to write 'L'.
uint8_t sseg_M [] = {3, rep_a, rep_c, rep_e}
      Specifies pins to write 'M'.
uint8_t sseg_N [] = {5, rep_a, rep_b, rep_c, rep_e, rep_f}
      Specifies pins to write 'N'.

    uint8_t sseg_O [] = {6, rep_a, rep_b, rep_c, rep_d, rep_e, rep_f}

      Specifies pins to write 'O'.

    uint8_t sseg_P [] = {5, rep_a, rep_b, rep_e, rep_f, rep_g}

      Specifies pins to write 'P'.

    uint8_t sseg_Q [] = {5, rep_a, rep_b, rep_d, rep_f, rep_g}

      Specifies pins to write 'Q'.
uint8_t sseg_R [] = {4, rep_a, rep_b, rep_e, rep_f}
      Specifies pins to write 'R'.
uint8_t sseg_S [] = {5, rep_a, rep_c, rep_d, rep_f, rep_g}
      Specifies pins to write 'S'.
uint8_t sseg_T [] = {4, rep_d, rep_e, rep_f, rep_g}
      Specifies pins to write 'T'.
uint8_t sseg_U [] = {5, rep_b, rep_c, rep_d, rep_e, rep_f}
      Specifies pins to write 'U'.

    uint8_t sseg_V [] = {5, rep_b, rep_c, rep_d, rep_e, rep_f}

      Specifies pins to write 'V'.
uint8_t sseg_W [] = {3, rep_b, rep_d, rep_f}
      Specifies pins to write 'W'.
uint8_t sseg_X [] = {5, rep_b, rep_c, rep_e, rep_f, rep_g}
      Specifies pins to write 'X'.
• uint8 t sseg Y [] = {5, rep b, rep c, rep d, rep f, rep g}
      Specifies pins to write 'Y'.
uint8_t sseg_Z[] = {5, rep_a, rep_b, rep_d, rep_e, rep_g}
      Specifies pins to write 'Z'.

    uint8_t sseg_a [] = {6, rep_a, rep_b, rep_c, rep_d, rep_e, rep_g}

      Specifies pins to write 'a'.
uint8_t sseg_b [] = {5, rep_c, rep_d, rep_e, rep_f, rep_g}
      Specifies pins to write 'b'.
uint8_t sseg_c [] = {3, rep_d, rep_e, rep_g}
      Specifies pins to write 'c'.
uint8_t sseg_d [] = {5, rep_b, rep_c, rep_d, rep_e, rep_g}
     Specifies pins to write 'd'.
• uint8 t sseg e [] = {6, rep a, rep b, rep d, rep e, rep f, rep g}
      Specifies pins to write 'e'.
uint8_t sseg_f [] = {4, rep_a, rep_e, rep_f, rep_g}
```

```
Specifies pins to write 'f'.
uint8_t sseg_g [] = {6, rep_a, rep_b, rep_c, rep_d, rep_f, rep_g}
      Specifies pins to write 'q'.
• uint8_t sseg_h [] = {4, rep_c, rep_e, rep_f, rep_g}
      Specifies pins to write 'h'.
• uint8_t sseg_i [] = {1, rep_e}
     Specifies pins to write 'i'.
uint8_t sseg_j [] = {2, rep_c, rep_d}
      Specifies pins to write 'j'.
uint8_t sseg_k [] = {5, rep_a, rep_c, rep_e, rep_f, rep_g}
      Specifies pins to write 'k'.
• uint8_t sseg_l [] = {2, rep_e, rep_f}
      Specifies pins to write 'I'.
uint8_t sseg_m [] = {2, rep_c, rep_e}
      Specifies pins to write 'm'.
• uint8_t sseg_n [] = {3, rep_c, rep_e, rep_g}
     Specifies pins to write 'n'.
• uint8_t sseg_o [] = {4, rep_c, rep_d, rep_e, rep_g}
      Specifies pins to write 'o'.
uint8_t sseg_p [] = {5, rep_a, rep_b, rep_e, rep_f, rep_g}
     Specifies pins to write 'p'.
uint8_t sseg_q [] = {5, rep_a, rep_b, rep_c, rep_f, rep_g}
      Specifies pins to write 'q'.
• uint8_t sseg_r[] = {2, rep_e, rep_g}
      Specifies pins to write 'r'.
uint8_t sseg_s [] = {5, rep_a, rep_c, rep_d, rep_f, rep_g}
     Specifies pins to write 's'.
uint8_t sseg_t [] = {4, rep_d, rep_e, rep_f, rep_g}
      Specifies pins to write 't'.
• uint8_t sseg_u [] = {3, rep_c, rep_d, rep_e}
     Specifies pins to write 'u'.
uint8_t sseg_v [] = {3, rep_c, rep_d, rep_e}
     Specifies pins to write 'v'.
uint8_t sseg_w [] = {2, rep_c, rep_e}
      Specifies pins to write 'w'.
uint8_t sseg_x [] = {5, rep_b, rep_c, rep_e, rep_f, rep_g}
      Specifies pins to write 'x'.
uint8_t sseg_y [] = {5, rep_b, rep_c, rep_d, rep_f, rep_g}
      Specifies pins to write 'y'.
uint8_t sseg_z [] = {5, rep_a, rep_b, rep_d, rep_e, rep_g}
      Specifies pins to write 'z'.

    const uint8_t * SevenSegmentASCII []
```

7-Seg vector that maps which pins must be turned on to draw each supported ASCII character.

### 5.5.1 Macro Definition Documentation

```
5.5.1.1 rep_a
#define rep_a 0
Represents the display pin 'a'.
5.5.1.2 rep_b
#define rep_b 1
Represents the display pin 'b'.
5.5.1.3 rep_c
#define rep_c 2
Represents the display pin 'c'.
5.5.1.4 rep_d
#define rep_d 3
Represents the display pin 'd'.
5.5.1.5 rep_dp
#define rep_dp 7
Represents the display pin 'dp'.
5.5.1.6 rep_e
#define rep_e 4
Represents the display pin 'e'.
```

```
5.5.1.7 rep_f
#define rep_f 5
Represents the display pin 'f'.
```

```
5.5.1.8 rep_g #define rep_g 6
```

Represents the display pin 'g'.

#### 5.5.2 Variable Documentation

#### 5.5.2.1 SevenSegmentASCII

```
const uint8_t* SevenSegmentASCII[]
```

#### Initial value:

7-Seg vector that maps which pins must be turned on to draw each supported ASCII character.

```
5.5.2.2 sseg_0
```

```
uint8_t sseg_0[] = {6, rep_a, rep_b, rep_c, rep_d, rep_e, rep_f}
```

Specifies pins to write '0'.

```
5.5.2.3 sseg_1
```

```
uint8_t sseg_1[] = {2, rep_b, rep_c}
```

Specifies pins to write '1'.

```
5.5.2.4 sseg_2
uint8_t sseg_2[] = {5, rep_a, rep_b, rep_d, rep_e, rep_g}
Specifies pins to write '2'.
5.5.2.5 sseg_3
uint8_t sseg_3[] = {5, rep_a, rep_b, rep_c, rep_d, rep_g}
Specifies pins to write '3'.
5.5.2.6 sseg_4
uint8_t sseg_4[] = {4, rep_b, rep_c, rep_f, rep_g}
Specifies pins to write '4'.
5.5.2.7 sseg_5
uint8_t sseg_5[] = {5, rep_a, rep_c, rep_d, rep_f, rep_g}
Specifies pins to write '5'.
5.5.2.8 sseg_6
uint8_t sseg_6[] = {6, rep_a, rep_c, rep_d, rep_e, rep_f, rep_g}
Specifies pins to write '6'.
5.5.2.9 sseg_7
uint8_t sseg_7[] = {3, rep_a, rep_b, rep_c}
Specifies pins to write '7'.
```

```
5.5.2.10 sseg_8
uint8_t sseg_8[] = {7, rep_a, rep_b, rep_c, rep_d, rep_e, rep_f, rep_g}
Specifies pins to write '8'.
5.5.2.11 sseg_9
uint8_t sseg_9[] = {6, rep_a, rep_b, rep_c, rep_d, rep_f, rep_g}
Specifies pins to write '9'.
5.5.2.12 sseg_A
uint8_t sseg_A[] = {6, rep_a, rep_b, rep_c, rep_e, rep_f, rep_g}
Specifies pins to write 'A'.
5.5.2.13 sseg_a
uint8_t sseg_a[] = {6, rep_a, rep_b, rep_c, rep_d, rep_e, rep_g}
Specifies pins to write 'a'.
5.5.2.14 sseg_B
uint8_t sseg_B[] = {5, rep_c, rep_d, rep_e, rep_f, rep_g}
Specifies pins to write 'B'.
5.5.2.15 sseg_b
uint8_t sseg_b[] = {5, rep_c, rep_d, rep_e, rep_f, rep_g}
Specifies pins to write 'b'.
```

```
5.5.2.16 sseg_C
uint8_t sseg_C[] = {4, rep_a, rep_d, rep_e, rep_f}
Specifies pins to write 'C'.
5.5.2.17 sseg_c
uint8_t sseg_c[] = \{3, rep_d, rep_e, rep_g\}
Specifies pins to write 'c'.
5.5.2.18 sseg_D
uint8_t sseg_D[] = {5, rep_b, rep_c, rep_d, rep_e, rep_g}
Specifies pins to write 'D'.
5.5.2.19 sseg_d
uint8_t sseg_d[] = {5, rep_b, rep_c, rep_d, rep_e, rep_g}
Specifies pins to write 'd'.
5.5.2.20 sseg_E
uint8_t sseg_E[] = {5, rep_a, rep_d, rep_e, rep_f, rep_g}
Specifies pins to write 'E'.
5.5.2.21 sseg_e
uint8_t sseg_e[] = {6, rep_a, rep_b, rep_d, rep_e, rep_f, rep_g}
Specifies pins to write 'e'.
```

```
5.5.2.22 sseg_F
uint8_t sseg_F[] = {4, rep_a, rep_e, rep_f, rep_g}
Specifies pins to write 'F'.
5.5.2.23 sseg_f
uint8_t sseg_f[] = {4, rep_a, rep_e, rep_f, rep_g}
Specifies pins to write 'f'.
5.5.2.24 sseg_G
uint8_t sseg_G[] = {5, rep_a, rep_c, rep_d, rep_e, rep_f}
Specifies pins to write 'G'.
5.5.2.25 sseg_g
uint8_t sseg_g[] = {6, rep_a, rep_b, rep_c, rep_d, rep_f, rep_g}
Specifies pins to write 'g'.
5.5.2.26 sseg_H
uint8_t sseg_H[] = {5, rep_b, rep_c, rep_e, rep_f, rep_g}
Specifies pins to write 'H'.
5.5.2.27 sseg_h
uint8_t sseg_h[] = {4, rep_c, rep_e, rep_f, rep_g}
Specifies pins to write 'h'.
```

```
5.5.2.28 sseg_l
uint8_t sseg_I[] = \{2, rep_e, rep_f\}
Specifies pins to write 'I'.
5.5.2.29 sseg_i
uint8_t sseg_i[] = {1, rep_e}
Specifies pins to write 'i'.
5.5.2.30 sseg_J
uint8_t sseg_J[] = {4, rep_b, rep_c, rep_d, rep_e}
Specifies pins to write 'J'.
5.5.2.31 sseg_j
uint8_t sseg_j[] = {2, rep_c, rep_d}
Specifies pins to write 'j'.
5.5.2.32 sseg_K
uint8_t sseg_K[] = {5, rep_a, rep_c, rep_e, rep_f, rep_g}
Specifies pins to write 'K'.
5.5.2.33 sseg_k
uint8_t sseg_k[] = {5, rep_a, rep_c, rep_e, rep_f, rep_g}
```

Specifies pins to write 'k'.

```
5.5.2.34 sseg_L
uint8_t sseg_L[] = {3, rep_d, rep_e, rep_f}
Specifies pins to write 'L'.
5.5.2.35 sseg_l
uint8_t sseg_l[] = \{2, rep_e, rep_f\}
Specifies pins to write 'I'.
5.5.2.36 sseg_M
uint8_t sseg_M[] = {3, rep_a, rep_c, rep_e}
Specifies pins to write 'M'.
5.5.2.37 sseg_m
uint8_t sseg_m[] = {2, rep_c, rep_e}
Specifies pins to write 'm'.
5.5.2.38 sseg_N
uint8_t sseg_N[] = {5, rep_a, rep_b, rep_c, rep_e, rep_f}
Specifies pins to write 'N'.
5.5.2.39 sseg_n
uint8_t sseg_n[] = {3, rep_c, rep_e, rep_g}
```

Specifies pins to write 'n'.

```
5.5.2.40 sseg_O
\label{eq:continuous_seg_0[] = {6, rep_a, rep_b, rep_c, rep_d, rep_e, rep_f}} \\
Specifies pins to write 'O'.
5.5.2.41 sseg_o
uint8_t sseg_o[] = {4, rep_c, rep_d, rep_e, rep_g}
Specifies pins to write 'o'.
5.5.2.42 sseg_P
uint8_t sseg_P[] = {5, rep_a, rep_b, rep_e, rep_f, rep_g}
Specifies pins to write 'P'.
5.5.2.43 sseg_p
uint8_t sseg_p[] = {5, rep_a, rep_b, rep_e, rep_f, rep_g}
Specifies pins to write 'p'.
5.5.2.44 sseg_Q
uint8_t sseg_Q[] = {5, rep_a, rep_b, rep_d, rep_f, rep_g}
Specifies pins to write 'Q'.
5.5.2.45 sseg_q
uint8_t sseg_q[] = {5, rep_a, rep_b, rep_c, rep_f, rep_g}
```

Specifies pins to write 'q'.

```
5.5.2.46 sseg_R
uint8_t sseg_R[] = {4, rep_a, rep_b, rep_e, rep_f}
Specifies pins to write 'R'.
5.5.2.47 sseg_r
uint8_t sseg_r[] = \{2, rep_e, rep_g\}
Specifies pins to write 'r'.
5.5.2.48 sseg_S
uint8_t sseg_S[] = {5, rep_a, rep_c, rep_d, rep_f, rep_g}
Specifies pins to write 'S'.
5.5.2.49 sseg_s
uint8_t sseg_s[] = {5, rep_a, rep_c, rep_d, rep_f, rep_g}
Specifies pins to write 's'.
5.5.2.50 sseg_T
uint8_t sseg_T[] = {4, rep_d, rep_e, rep_f, rep_g}
Specifies pins to write 'T'.
5.5.2.51 sseg_t
uint8_t sseg_t[] = {4, rep_d, rep_e, rep_f, rep_g}
Specifies pins to write 't'.
```

```
5.5.2.52 sseg_U
uint8_t sseg_U[] = {5, rep_b, rep_c, rep_d, rep_e, rep_f}
Specifies pins to write 'U'.
5.5.2.53 sseg_u
uint8_t sseg_u[] = {3, rep_c, rep_d, rep_e}
Specifies pins to write 'u'.
5.5.2.54 sseg_V
uint8_t sseg_V[] = {5, rep_b, rep_c, rep_d, rep_e, rep_f}
Specifies pins to write 'V'.
5.5.2.55 sseg_v
uint8_t sseg_v[] = {3, rep_c, rep_d, rep_e}
Specifies pins to write 'v'.
5.5.2.56 sseg_W
uint8_t sseg_W[] = {3, rep_b, rep_d, rep_f}
Specifies pins to write 'W'.
5.5.2.57 sseg_w
uint8_t sseg_w[] = {2, rep_c, rep_e}
```

Specifies pins to write 'w'.

```
5.5.2.58 sseg_X
uint8_t sseg_X[] = {5, rep_b, rep_c, rep_e, rep_f, rep_g}
Specifies pins to write 'X'.
5.5.2.59 sseg_x
uint8_t sseg_x[] = {5, rep_b, rep_c, rep_e, rep_f, rep_g}
Specifies pins to write 'x'.
5.5.2.60 sseg_Y
uint8_t sseg_Y[] = \{5, rep_b, rep_c, rep_d, rep_f, rep_g\}
Specifies pins to write 'Y'.
5.5.2.61 sseg_y
uint8_t sseg_y[] = {5, rep_b, rep_c, rep_d, rep_f, rep_g}
Specifies pins to write 'y'.
5.5.2.62 sseg_Z
uint8_t sseg_Z[] = {5, rep_a, rep_b, rep_d, rep_e, rep_g}
Specifies pins to write 'Z'.
5.5.2.63 sseg_z
uint8_t sseg_z[] = {5, rep_a, rep_b, rep_d, rep_e, rep_g}
```

Specifies pins to write 'z'.

# 5.6 src/include/button.h File Reference

```
#include "pins.h"
```

#### **Data Structures**

• struct Button

# **Typedefs**

 typedef enum button\_mode Button\_Mode Button mode options.

### **Enumerations**

• enum button\_mode { Btn\_Up = 0, Btn\_Down = 1 }

#### **Functions**

• Button \* btn\_setup (uint8\_t pin\_number)

Setups a new instance of a Button.

void btn\_register\_fn (Button \*b, void \*function)

Registers a function to be called whether button is fired.

void btn\_set\_mode (Button \*b, Button\_Mode mode)

Changes button behavior, waiting or not to be released to fire action.

void btn\_fired (Button \*b)

Verifies if a button is pressed at moment and fires it's action.

uint8\_t btn\_pressed (Button \*b)

Verifies if a button is pressed at moment.

# 5.6.1 Typedef Documentation

# 5.6.1.1 Button\_Mode

typedef enum button\_mode Button\_Mode

Button mode options.

# 5.6.2 Enumeration Type Documentation

#### 5.6.2.1 button\_mode

enum button\_mode

#### Enumerator

Btn_Up	Fires action immediately after button get pressed.
Btn_Down	Fires action when button is released.

# 5.6.3 Function Documentation

# 5.6.3.1 btn\_fired()

```
void btn_fired ( {\tt Button} \, * \, b \,\,)
```

Verifies if a button is pressed at moment and fires it's action.

#### **Parameters**

```
b Button instance.
```

# 5.6.3.2 btn\_pressed()

Verifies if a button is pressed at moment.

#### **Parameters**

```
b Button instance.
```

### Returns

Returns 0 if button is not pressed, any value otherwise.

### 5.6.3.3 btn\_register\_fn()

Registers a function to be called whether button is fired.

#### **Parameters**

b	Button instance.
function	Function pointer.

### 5.6.3.4 btn\_set\_mode()

Changes button behavior, waiting or not to be released to fire action.

### **Parameters**

b	Button instance.
mode	New button mode.

### 5.6.3.5 btn\_setup()

Setups a new instance of a Button.

# **Parameters**

number	Digital pin number associated to the Button.

### Returns

A pointer to **Button** structure.

# 5.7 src/include/delay.h File Reference

```
#include <avr/io.h>
#include <stdlib.h>
```

# **Functions**

void delay\_1us (void)

Delays for, approximately, 1 microssecond.

void delay\_1ms (void)

Delays for, approximately, 1 millissecond.

• void delay\_us (uint32\_t)

Delays for, approximately, a specified time, in microsseconds.

void delay\_ms (uint32\_t)

Delays for, approximately, a specified time, in milliseconds.

# 5.7.1 Function Documentation

### 5.7.1.1 delay\_1ms()

```
void delay_1ms (
     void )
```

Delays for, approximately, 1 millissecond.

### 5.7.1.2 delay\_1us()

```
void delay_lus (
     void )
```

Delays for, approximately, 1 microssecond.

### 5.7.1.3 delay\_ms()

Delays for, approximately, a specified time, in milliseconds.

#### **Parameters**

```
time Time for delay (in milliseconds)
```

# 5.7.1.4 delay\_us()

Delays for, approximately, a specified time, in microsseconds.

#### **Parameters**

time Time for delay (in microsseconds)

# 5.8 src/include/led.h File Reference

```
#include "pins.h"
```

#### **Data Structures**

struct Led

# **Typedefs**

typedef enum led\_state Led\_State
 Maps a possible Led state.

#### **Enumerations**

• enum led\_state { On = 1, Off = 0 }

### **Functions**

• Led \* led\_setup (int number)

Setups a new instance of a Led.

void led\_make\_light (Led \*led)

Turns on the instance Led's light.

void led\_kill\_light (Led \*led)

Turns off the instance Led's light.

void led\_switch\_light (Led \*led)

Toggles the instance Led's light.

void led\_blink (Led \*led, double time\_ms)

Blinks the instance Led's light, keeping it on and off for a specified time.

void led\_free (Led \*led)

Destroys a Led instance.

# 5.8.1 Typedef Documentation

### 5.8.1.1 Led\_State

```
typedef enum led_state Led_State
```

Maps a possible Led state.

# 5.8.2 Enumeration Type Documentation

# 5.8.2.1 led\_state

```
enum led_state
```

### Enumerator

On	Led's light is on.
Off	Led's light is off.

# 5.8.3 Function Documentation

# 5.8.3.1 led\_blink()

```
void led_blink ( \label{led_blink} \begin{tabular}{ll} Led * led, \\ & double $time\_ms$ ) \end{tabular}
```

Blinks the instance Led's light, keeping it on and off for a specified time.

#### **Parameters**

led	Led instance.
time_ms	Time interval to keep Led's light on and off.

# 5.8.3.2 led\_free()

```
void led_free ( \label{led} \begin{tabular}{ll} Led * led \end{tabular} \begin{tabular}{ll} Led * led \end{tabular} \begin{tabular}{ll} \begin{tabular}{ll} Led * led \end{t
```

Destroys a Led instance.

### **Parameters**

led Led instance.

### 5.8.3.3 led\_kill\_light()

```
void led_kill_light ( \label{led_kill_light} \mbox{Led * } led \mbox{ )}
```

Turns off the instance Led's light.

#### **Parameters**

led Led instance.

### 5.8.3.4 led\_make\_light()

```
void led_make_light (
    Led * led )
```

Turns on the instance Led's light.

### **Parameters**

led Led instance.

### 5.8.3.5 led\_setup()

```
Led* led_setup (
          int number )
```

Setups a new instance of a Led.

# **Parameters**

number Digital pin number associated to the Led.

#### Returns

A pointer to Led structure.

#### 5.8.3.6 led\_switch\_light()

```
void led_switch_light ( \label{led_switch} \begin{tabular}{l} Led * led \end{tabular}
```

Toggles the instance Led's light.

### **Parameters**

led Led instance.

# 5.9 src/include/macros.h File Reference

### Macros

```
• #define MACROS
```

```
• #define swt_bit(x, n) (x ^= (1 << n))
```

- #define  $set\_bit(x, n) (x |= (1 << n))$
- #define clr\_bit(x, n) (x &=  $\sim$ (1 << n))
- #define tst\_bit(x, n) (x&(1 << n))
- #define comp\_masks(x, y) ((1 << x) | (1 << y))

#### 5.9.1 Macro Definition Documentation

### 5.9.1.1 clr\_bit

```
#define clr_bit(  x, \\  n ) \ (x \&= \sim (1 << n))
```

### 5.9.1.2 comp\_masks

```
#define comp_masks(  x, \\  y ) \ ((1 << x) \ | \ (1 << y))
```

### 5.9.1.3 MACROS

#define MACROS

# 5.9.1.4 set\_bit

```
#define set_bit(  x, \\  n ) \ (x \models (1 << n)) \\
```

### 5.9.1.5 swt\_bit

```
#define swt_bit(  x, \\  n ) \ (x ^= (1 << n)) \\
```

# 5.9.1.6 tst\_bit

```
#define tst_bit(  x, \\  n ) \ (x&(1 << n)) \\
```

# 5.10 src/include/pins.h File Reference

```
#include <avr/io.h>
#include <avr/portpins.h>
#include <util/delay.h>
#include "macros.h"
#include <stdlib.h>
```

# **Data Structures**

- struct Pin
- struct bytes

### **Macros**

- #define F\_CPU 1600000UL
- #define HIGH 1
- #define LOW 0

#### **Functions**

```
• uint8 t set output (uint8 t number)
```

Sets a pin as a output, using its DDR.

uint8\_t set\_pullup (uint8\_t number)

Sets a pin as active, using its PORT.

• uint8\_t toggle\_pullup (uint8\_t number)

Toggles a pin activity, using its PORT.

uint8\_t test\_input (uint8\_t number)

Tests if there is an input signal on a pin, using its PIN.

uint8\_t set\_input (uint8\_t number)

Sets a pin as an input, using its DDR.

• uint8\_t clr\_pullup (uint8\_t number)

Sets a pin as inactive, using its PORT.

• uint8\_t digital\_write (uint8\_t number, int value)

Writes an integer value to a pin, using its PORT.

#### **Variables**

• Pin Pins [14]

Digital pin instances, common to all files.

• bytes Bytes [14]

Bytes instances.

# 5.10.1 Macro Definition Documentation

```
5.10.1.1 F_CPU
```

#define F\_CPU 1600000UL

### 5.10.1.2 HIGH

#define HIGH 1

### 5.10.1.3 LOW

#define LOW 0

#### 5.10.2 Function Documentation

### 5.10.2.1 clr\_pullup()

Sets a pin as inactive, using its PORT.

### **Parameters**

# 5.10.2.2 digital\_write()

Writes an integer value to a pin, using its PORT.

#### **Parameters**

number	Digital pin number.
--------	---------------------

### 5.10.2.3 set\_input()

Sets a pin as an input, using its DDR.

# **Parameters**

number	Digital pin number.

# 5.10.2.4 set\_output()

Sets a pin as a output, using its DDR.

#### **Parameters**

number	Digital pin number.

# 5.10.2.5 set\_pullup()

Sets a pin as active, using its PORT.

### **Parameters**

number	Digital pin number.
--------	---------------------

### 5.10.2.6 test\_input()

Tests if there is an input signal on a pin, using its PIN.

#### **Parameters**

number	Digital pin number.
--------	---------------------

# 5.10.2.7 toggle\_pullup()

Toggles a pin activity, using its PORT.

# **Parameters**

number	Digital pin number.
--------	---------------------

# 5.10.3 Variable Documentation

### 5.10.3.1 Bytes

bytes Bytes[14]

Bytes instances.

### 5.10.3.2 Pins

```
Pin Pins[14]
```

Digital pin instances, common to all files.

# 5.11 src/include/pwm.h File Reference

```
#include <avr/io.h>
#include <stdlib.h>
```

### **Functions**

• float lookup\_prescalar (float)

Specifies the prescalar based on frequency.

int lookup\_ocr (float)

Specifies OCR value based on frequency.

uint8\_t lookup\_cs (float)

Specifies the CS control bits value based on frequency.

void sqrwave (uint8\_t, float)

Generates square waves pulse in a pin based on frequency.

void pwmwave (uint8\_t, uint8\_t)

Generates PWM waves in a pin based on a duty cycle.

• uint8\_t lookup\_cs2 (float freq)

#### 5.11.1 Function Documentation

# 5.11.1.1 lookup\_cs()

```
uint8_t lookup_cs (
          float )
```

Specifies the CS control bits value based on frequency.

### **Parameters**

cy value (Hz)	freq
---------------	------

#### Returns

CS control bits value

# 5.11.1.2 lookup\_cs2()

# 5.11.1.3 lookup\_ocr()

```
int lookup_ocr (
          float )
```

Specifies OCR value based on frequency.

#### **Parameters**

```
freq Frequency value (Hz)
```

### Returns

OCR value

# 5.11.1.4 lookup\_prescalar()

Specifies the prescalar based on frequency.

# **Parameters**

```
freq Frequency value (Hz)
```

### Returns

Prescalar value

# 5.11.1.5 pwmwave()

```
void pwmwave (
          uint8_t ,
          uint8_t )
```

Generates PWM waves in a pin based on a duty cycle.

#### **Parameters**

pin	Pin number
dutycycle	Duty cycle value (0 $\sim$ 255)

# 5.11.1.6 sqrwave()

```
void sqrwave (
          uint8_t ,
          float )
```

Generates square waves pulse in a pin based on frequency.

### **Parameters**

pin	Pin number
freq	Frequency value (Hz)

# 5.12 src/include/supersonic.h File Reference

```
#include <avr/io.h>
#include <stdlib.h>
```

# **Functions**

int supersonic (uint8\_t, uint8\_t)
 Measures a distance based on a sonar.

# 5.12.1 Function Documentation

# 5.12.1.1 supersonic()

```
int supersonic (
          uint8_t ,
          uint8_t )
```

Measures a distance based on a sonar.

### **Parameters**

trig	Digital pin number associated to the Trigger pin.
echo	Digital pin number associated to the Echo pin.

#### Returns

Measured distance (cm) between obstacle.

# 5.13 src/include/uart.h File Reference

```
#include <stdio.h>
```

#### **Macros**

- #define F\_CPU 1600000UL
- #define BAUD 9600

# **Functions**

- void uart\_init (void)
- int uart\_putchar (char c, FILE \*stream)
- int uart\_getchar (FILE \*stream)

### 5.13.1 Macro Definition Documentation

### 5.13.1.1 BAUD

#define BAUD 9600

# 5.13.1.2 F\_CPU

#define F\_CPU 1600000UL

### 5.13.2 Function Documentation

### 5.13.2.1 uart\_getchar()

# 5.14 src/led.c File Reference

char c,

FILE \* stream )

```
#include "led.h"
```

### **Functions**

Led \* led setup (int number)

Setups a new instance of a Led.

• void led\_make\_light (Led \*led)

Turns on the instance Led's light.

void led\_kill\_light (Led \*led)

Turns off the instance Led's light.

void led\_switch\_light (Led \*led)

Toggles the instance Led's light.

void led\_blink (Led \*led, double time\_ms)

Blinks the instance Led's light, keeping it on and off for a specified time.

void led\_free (Led \*led)

Destroys a Led instance.

# 5.14.1 Function Documentation

#### 5.14.1.1 led\_blink()

Blinks the instance Led's light, keeping it on and off for a specified time.

### **Parameters**

led	Led instance.
time_ms	Time interval to keep Led's light on and off.

### 5.14.1.2 led\_free()

```
void led_free (
    Led * led )
```

Destroys a Led instance.

### **Parameters**

```
led Led instance.
```

# 5.14.1.3 led\_kill\_light()

```
void led_kill_light ( \label{led_kill_light} \mbox{Led * led })
```

Turns off the instance Led's light.

### **Parameters**

led Led instance.

### 5.14.1.4 led\_make\_light()

```
void led_make_light (
    Led * led )
```

Turns on the instance Led's light.

# **Parameters**

led Led instance.

#### 5.14.1.5 led\_setup()

```
Led* led_setup (
          int number )
```

Setups a new instance of a Led.

#### **Parameters**

number Digital pin number associated to the Led.

#### Returns

A pointer to Led structure.

### 5.14.1.6 led\_switch\_light()

```
void led_switch_light ( \label{led_switch_light} \mbox{Led } * \mbox{ led })
```

Toggles the instance Led's light.

#### **Parameters**

led Led instance.

# 5.15 src/pins.c File Reference

```
#include "pins.h"
```

### **Functions**

```
• uint8_t set_output (uint8_t number)
```

Sets a pin as a output, using its DDR.

uint8\_t set\_pullup (uint8\_t number)

Sets a pin as active, using its PORT.

uint8\_t toggle\_pullup (uint8\_t number)

Toggles a pin activity, using its PORT.

• uint8\_t test\_input (uint8\_t number)

Tests if there is an input signal on a pin, using its PIN.

uint8\_t set\_input (uint8\_t number)

Sets a pin as an input, using its DDR.

• uint8\_t clr\_pullup (uint8\_t number)

Sets a pin as inactive, using its PORT.

uint8\_t digital\_write (uint8\_t number, int value)

Writes an integer value to a pin, using its PORT.

# **Variables**

• Pin Pins []

Digital pin instances, common to all files.

• bytes Bytes []

Bytes instances.

# 5.15.1 Function Documentation

```
5.15.1.1 clr_pullup()
```

Sets a pin as inactive, using its PORT.

#### **Parameters**

number Digital pin number.	
----------------------------	--

### 5.15.1.2 digital\_write()

Writes an integer value to a pin, using its PORT.

# **Parameters**

```
number Digital pin number.
```

# 5.15.1.3 set\_input()

Sets a pin as an input, using its DDR.

# **Parameters**

number	Digital pin number.
--------	---------------------

# 5.15.1.4 set\_output()

Sets a pin as a output, using its DDR.

#### **Parameters**

number	Digital pin number.
--------	---------------------

# 5.15.1.5 set\_pullup()

Sets a pin as active, using its PORT.

#### **Parameters**

number	Digital pin number.
--------	---------------------

# 5.15.1.6 test\_input()

Tests if there is an input signal on a pin, using its PIN.

# **Parameters**

number Digital pin number.		
	number	Digital pin number.

#### 5.15.1.7 toggle\_pullup()

Toggles a pin activity, using its PORT.

#### **Parameters**

```
number Digital pin number.
```

#### 5.15.2 Variable Documentation

#### 5.15.2.1 Bytes

```
bytes Bytes[]
```

#### Initial value:

Bytes instances.

#### 5.15.2.2 Pins

```
Pin Pins[]
```

#### Initial value:

```
{
{PDO, &PORTD, &DDRD, &PIND, NULL, NULL, NULL, NULL, NULL},
{PD1, &PORTD, &DDRD, &PIND, NULL, NULL, NULL, NULL},
{PD1, &PORTD, &DDRD, &PIND, NULL, NULL, NULL, NULL},
{PD2, &PORTD, &DDRD, &PIND, NULL, NULL, NULL, NULL},
{PD3, &PORTD, &DDRD, &PIND, &TCCR2A, &TCCR2B, &OCR2A, &OCR2B},
{PD4, &PORTD, &DDRD, &PIND, NULL, NULL, NULL, NULL},
{PD5, &PORTD, &DDRD, &PIND, &TCCR0A, &TCCR0B, &OCR0A, &OCR0B},
{PD6, &PORTD, &DDRD, &PIND, &TCCR0A, &TCCR0B, &OCR0A, NULL},
{PD7, &PORTD, &DDRD, &PIND, NULL, NULL, NULL, NULL},
{PB0, &PORTB, &DDRB, &PINB, NULL, NULL, NULL, NULL},
{PB1, &PORTB, &DDRB, &PINB, NULL, NULL, NULL, NULL},
{PB1, &PORTB, &DDRB, &PINB, &TCCR1A, &TCCR1B, (uint8_t*)&OCR1A, NULL },
{PB3, &PORTB, &DDRB, &PINB, &TCCR2A, &TCCR2B, &OCR2A, NULL},
{PB4, &PORTB, &DDRB, &PINB, &TCCR2A, &TCCR2B, &OCR2A, NULL},
{PB4, &PORTB, &DDRB, &PINB, NULL, NULL, NULL, NULL},
{PB5, &PORTB, &DDRB, &PINB, NULL, NULL, NULL, NULL},
}
```

Digital pin instances, common to all files.

64 File Documentation

# 5.16 src/pwm.c File Reference

```
#include "pwm.h"
#include "pins.h"
```

#### **Functions**

float lookup prescalar (float freq)

Specifies the prescalar based on frequency.

uint8\_t lookup\_cs (float freq)

Specifies the CS control bits value based on frequency.

- uint8\_t lookup\_cs2 (float freq)
- int lookup\_ocr (float freq)

Specifies OCR value based on frequency.

• void sqrwave (uint8\_t pin, float freq)

Generates square waves pulse in a pin based on frequency.

• void pwmwave (uint8\_t pin, uint8\_t dutycycle)

Generates PWM waves in a pin based on a duty cycle.

#### 5.16.1 Function Documentation

#### 5.16.1.1 lookup\_cs()

```
uint8_t lookup_cs (
          float )
```

Specifies the CS control bits value based on frequency.

#### **Parameters**

```
freq Frequency value (Hz)
```

#### Returns

CS control bits value

#### 5.16.1.2 lookup\_cs2()

# 5.16.1.3 lookup\_ocr()

```
int lookup_ocr (
          float )
```

Specifies OCR value based on frequency.

# **Parameters**

```
freq Frequency value (Hz)
```

Returns

OCR value

# 5.16.1.4 lookup\_prescalar()

Specifies the prescalar based on frequency.

#### **Parameters**

freq	Frequency value (Hz)
------	----------------------

Returns

Prescalar value

#### 5.16.1.5 pwmwave()

```
void pwmwave (
          uint8_t ,
          uint8_t )
```

Generates PWM waves in a pin based on a duty cycle.

## **Parameters**

pin	Pin number
dutycycle	Duty cycle value (0 $\sim$ 255)

66 File Documentation

#### 5.16.1.6 sqrwave()

```
void sqrwave (
          uint8_t ,
          float )
```

Generates square waves pulse in a pin based on frequency.

#### **Parameters**

pin	Pin number
freq	Frequency value (Hz)

# 5.17 src/README.md File Reference

# 5.18 src/supersonic.c File Reference

```
#include "supersonic.h"
#include "macros.h"
#include "pins.h"
#include <util/delay.h>
```

#### **Functions**

int supersonic (uint8\_t trig, uint8\_t echo)
 Measures a distance based on a sonar.

## 5.18.1 Function Documentation

#### 5.18.1.1 supersonic()

```
int supersonic ( \label{eq:control_uint8_t} \mbox{uint8_t ,} \\ \mbox{uint8_t )}
```

Measures a distance based on a sonar.

# **Parameters**

trig	Digital pin number associated to the Trigger pin.
echo	Digital pin number associated to the Echo pin.

#### Returns

Measured distance (cm) between obstacle.

# 5.19 src/uart.c File Reference

```
#include "uart.h"
#include <avr/io.h>
#include <avr/sfr_defs.h>
#include <util/setbaud.h>
#include <stdio.h>
```

#### **Functions**

- void uart\_init (void)
- int uart\_putchar (char c, FILE \*stream)
- int uart\_getchar (FILE \*stream)

#### **Variables**

• static FILE uart\_io = FDEV\_SETUP\_STREAM(uart\_putchar, uart\_getchar, \_FDEV\_SETUP\_RW)

# 5.19.1 Function Documentation

```
5.19.1.1 uart_getchar()
```

```
int uart_getchar (
     FILE * stream )
```

#### 5.19.1.2 uart\_init()

```
void uart_init (
     void )
```

#### 5.19.1.3 uart\_putchar()

#### 5.19.2 Variable Documentation

# 5.19.2.1 uart\_io

```
FILE uart_io = FDEV_SETUP_STREAM(uart_putchar, uart_getchar, _FDEV_SETUP_RW) [static]
```

File Documentation

# Index

_DDR	bcd.c, 17
Pin, 14	bcd.h, 24
_OCRA	bcd_delay
Pin, 14	bcd.c, 18
_OCRB	bcd.h, 24
Pin, 14	bcd_free
_PIN	bcd.c, 18
Pin, 14	bcd.h, 24
_PORT	bcd_set_loop
Pin, 14	bcd.c, 18
_TCCA	bcd.h, 25
Pin, 14	bcd_setup
_TCCB	bcd.c, 18
Pin, 15	bcd.h, 25
2	bcd_seven.h
a BCD, 8	rep_a, 29
BOD, 6	rep_b, 30
b	rep_c, 30
BCD, 8	rep_d, 30
BAUD	rep_dp, 30
uart.h, 57	rep_e, <mark>30</mark>
BCD, 7	rep_f, 30
a, 8	rep_g, <mark>31</mark>
b, 8	SevenSegmentASCII, 31
c, 8	sseg_0, <mark>31</mark>
d, 8	sseg_1, <mark>31</mark>
delay, 8	sseg_2, <mark>31</mark>
dp, 8	sseg_3, <mark>32</mark>
e, 9	sseg_4, <mark>32</mark>
f, 9	sseg_5, <mark>32</mark>
g, 9	sseg_6, <mark>32</mark>
loop, 9	sseg_7, <mark>32</mark>
bcd.c	sseg_8, 32
bcd_clear, 17	sseg_9, <mark>33</mark>
bcd_delay, 18	sseg_A, <mark>33</mark>
bcd_free, 18	sseg_a, <mark>33</mark>
bcd_set_loop, 18	sseg_B, <mark>33</mark>
bcd_setup, 18	sseg_b, <mark>33</mark>
bcd_show_char, 19	sseg_C, <mark>33</mark>
bcd_show_string, 19	sseg_c, 34
bcd.h	sseg_D, <mark>34</mark>
bcd_clear, 24	sseg_d, 34
bcd_delay, 24	sseg_E, <mark>34</mark>
bcd_free, 24	sseg_e, <mark>34</mark>
bcd_set_loop, 25	sseg_F, 34
bcd_setup, 25	sseg_f, 35
bcd_show_char, 26	sseg_G, 35
bcd_show_string, 26	sseg_g, 35
bcd_clear	sseg_H, 35

sseg_h, <mark>35</mark>	Button, 9
sseg_I, <mark>35</mark>	fn, 10
sseg_i, <mark>36</mark>	mode, 10
sseg_J, <mark>36</mark>	pin_number, 10
sseg_j, <mark>36</mark>	button.c
sseg_K, 36	btn_fired, 20
sseg_k, 36	btn_pressed, 21
sseg_L, 36	btn_register_fn, 21
sseg_l, 37	btn_set_mode, 21
sseg_M, 37	btn_setup, 21
sseg_m, 37	button.h
sseg_N, 37	btn_fired, 43
sseg_n, 37	btn_pressed, 43
sseg_O, 37	btn_register_fn, 43
sseg_o, 38	btn_set_mode, 44
sseg_P, 38	btn_setup, 44
sseg_p, 38	Button_Mode, 42
sseg_Q, 38	button_mode, 42
sseg_q, 38	Button_Mode
sseg_R, 38	button.h, 42
sseg r, 39	button_mode
sseg_S, 39	button.h, 42
sseg_s, 39	Bytes
sseg_T, 39	pins.c, 63
sseg_t, 39	pins.h, 53
sseg_U, 39	bytes, 11
sseg_u, 40	COM0, 11
sseg_V, 40	COM1, 11
sseg_v, 40	CS0, 11
sseg_W, 40	CS1, 11
<del>-</del>	CS2, 11
sseg_w, 40	WGM0, 12
sseg_X, 40	WGM1, 12
sseg_x, 41	WGM2, 12
sseg_Y, 41	WGM3, 12
sseg_y, 41	
sseg_Z, 41	С
sseg_z, 41	BCD, 8
bcd_show_char bcd.c, 19	COM0
bcd.h, 26	bytes, 11
•	COM1
bcd_show_string	bytes, 11
bcd.c, 19 bcd.h, 26	CS0
•	bytes, 11
btn_fired	CS1
button.c, 20	bytes, 11
button.h, 43	CS2
btn_pressed	bytes, 11
button.c, 21	clr_bit
button.h, 43	macros.h, 49
btn_register_fn	clr_pullup
button.c, 21	pins.c, 61
button.h, 43	pins.h, 51
btn_set_mode	comp_masks
button.c, 21	macros.h, 49
button.h, 44	
btn_setup	d DOD 0
button.c, 21	BCD, 8
button.h, 44	delay

BCD, 8	Led_State, 46
delay.c	led_blink, 47
delay_1ms, 22	led_free, 47
delay_1us, 22	led_kill_light, 48
delay_ms, 23	led_make_light, 48
delay_us, 23	led_setup, 48
delay.h	led_state, 47
delay_1ms, 45	led_switch_light, 48
delay_1us, 45	Led_State
delay_ms, 45	led.h, 46
delay_us, 45	led_blink
delay_1ms	led.c, 58
delay.c, 22	led.h, 47
delay.h, 45	led_free
delay_1us	led.c, 59
delay.c, 22	led.h, 47
delay.h, 45	led_kill_light led.c, 59
delay_ms	led.h, 48
delay.c, 23 delay.h, 45	led_make_light
delay us	led.c, 59
delay.c, 23	led.h, 48
delay.h, 45	led_setup
digital_write	led.c, 59
pins.c, 61	led.h, 48
pins.h, 52	led state
dp	_ led.h, 47
BCD, 8	led_switch_light
,	led.c, 60
е	led.h, 48
BCD, 9	lookup_cs
	pwm.c, 64
f	pwm.h, 54
BCD, 9	lookup_cs2
F_CPU	pwm.c, 64
pins.h, 51	pwm.h, <mark>54</mark>
uart.h, 57	lookup_ocr
fn P " 10	pwm.c, 64
Button, 10	pwm.h, 55
	lookup_prescalar
g BCD, 9	pwm.c, 65
BOD, 9	pwm.h, 55
HIGH	loop
pins.h, 51	BCD, 9
p	MACROS
LOW	macros.h, 49
pins.h, 51	macros.h
Led, 12	clr bit, 49
pin_number, 13	comp masks, 49
state, 13	MACROS, 49
led.c	set_bit, 49
led_blink, 58	swt_bit, 50
led_free, 59	tst_bit, 50
led_kill_light, 59	mode
led_make_light, 59	Button, 10
led_setup, 59	5
led_switch_light, 60	P Dia 45
led.h	Pin, 15

Pin, 13	bcd_seven.h, 30
_DDR, 14	rep_c
_OCRA, 14	bcd_seven.h, 30
_OCRB, 14	rep_d
_PIN, 14	bcd_seven.h, 30
PORT, 14	rep_dp
TCCA, 14	bcd_seven.h, 30
TCCB, 15	rep_e
P, 15	bcd_seven.h, 30
pin_number	rep_f
Button, 10	bcd_seven.h, 30
Led, 13	rep_g
Pins	bcd_seven.h, 31
pins.c, 63	204_20von, 01
pins.h, 53	set_bit
pins.c	macros.h, 49
Bytes, 63	set_input
•	 pins.c, 61
clr_pullup, 61	pins.h, <mark>52</mark>
digital_write, 61	set_output
Pins, 63	pins.c, 62
set_input, 61	pins.h, 52
set_output, 62	set_pullup
set_pullup, 62	pins.c, 62
test_input, 62	
toggle_pullup, 62	pins.h, 52 SevenSegmentASCII
pins.h	_
Bytes, 53	bcd_seven.h, 31
clr_pullup, 51	sqrwave
digital_write, 52	pwm.c, 65
F_CPU, 51	pwm.h, 56
HIGH, 51	src/README.md, 66
LOW, 51	src/bcd.c, 17
Pins, 53	src/button.c, 20
set_input, 52	src/delay.c, 22
set_output, 52	src/include/bcd.h, 23
set_pullup, 52	src/include/bcd_seven.h, 26
test_input, 53	src/include/button.h, 42
toggle_pullup, 53	src/include/delay.h, 44
pwm.c	src/include/led.h, 46
lookup_cs, 64	src/include/macros.h, 49
lookup_cs2, 64	src/include/pins.h, 50
lookup_ocr, 64	src/include/pwm.h, 54
lookup_prescalar, 65	src/include/supersonic.h, 56
pwmwave, 65	src/include/uart.h, 57
sqrwave, 65	src/led.c, 58
pwm.h	src/pins.c, 60
lookup_cs, 54	src/pwm.c, 64
lookup_cs2, 54	src/supersonic.c, 66
lookup_csz, 54	src/uart.c, 67
lookup_prescalar, 55	sseg_0
	bcd_seven.h, 31
pwmwave, 55	sseg 1
sqrwave, 56	bcd_seven.h, 31
pwmwave	sseg_2
pwm.c, 65	bcd_seven.h, 31
pwm.h, 55	sseg_3
ren a	bcd_seven.h, 32
rep_a bcd_seven.h, 29	sseg_4
	bcd_seven.h, 32
rep_b	DOU_357511.11, 32

_	
sseg_5	sseg_M
bcd_seven.h, 32	bcd_seven.h, 37
sseg_6	sseg_m
bcd_seven.h, 32	bcd_seven.h, 37
sseg_7	sseg_N
bcd_seven.h, 32	bcd_seven.h, 37
sseg_8	sseg_n
bcd_seven.h, 32	bcd_seven.h, 37
sseg_9	sseg_O
bcd_seven.h, 33	bcd_seven.h, 37
sseg_A	sseg_o
bcd_seven.h, 33	bcd_seven.h, 38
sseg_a	sseg_P
bcd_seven.h, 33	bcd_seven.h, 38
sseg_B	sseg_p
bcd_seven.h, 33	bcd_seven.h, 38
sseg_b	sseg_Q
bcd_seven.h, 33	bcd_seven.h, 38
sseg_C	sseg_q
bcd_seven.h, 33	bcd_seven.h, 38
sseg_c	sseg R
bcd_seven.h, 34	bcd_seven.h, 38
sseg_D	sseg_r
bcd_seven.h, 34	bcd_seven.h, 39
sseg_d	sseg_S
bcd_seven.h, 34	bcd_seven.h, 39
sseg_E	sseg_s
bcd_seven.h, 34	bcd_seven.h, 39
sseg_e	sseg_T
bcd_seven.h, 34	bcd_seven.h, 39
sseg_F	sseg_t
bcd_seven.h, 34	bcd_seven.h, 39
sseg_f	sseg_U
bcd_seven.h, 35	bcd_seven.h, 39
sseg_G	sseg_u
bcd_seven.h, 35	bcd_seven.h, 40
sseg_g	sseg_V
bcd_seven.h, 35	bcd_seven.h, 40
sseg_H	sseg_v
bcd_seven.h, 35	bcd_seven.h, 40
sseg_h	sseg_W
bcd_seven.h, 35	bcd_seven.h, 40
sseg_l	sseg_w
bcd_seven.h, 35	bcd_seven.h, 40
sseg_i	sseg_X
bcd_seven.h, 36	bcd_seven.h, 40
sseg_J	sseg_x
bcd_seven.h, 36	bcd_seven.h, 41
sseg_j	sseg_Y
bcd_seven.h, 36	bcd_seven.h, 41
sseg_K	sseg_y
bcd_seven.h, 36	bcd_seven.h, 41
sseg_k	sseg_Z
bcd_seven.h, 36	bcd_seven.h, 41
sseg_L	sseg_z
bcd_seven.h, 36	bcd_seven.h, 41
sseg I	state
bcd_seven.h, 37	Led, 13
	-, -

```
supersonic
    supersonic.c, 66
    supersonic.h, 56
supersonic.c
    supersonic, 66
supersonic.h
    supersonic, 56
swt_bit
     macros.h, 50
test_input
    pins.c, 62
    pins.h, 53
toggle_pullup
    pins.c, 62
    pins.h, 53
tst_bit
    macros.h, 50
uart.c
    uart_getchar, 67
    uart init, 67
    uart_io, 67
    uart_putchar, 67
uart.h
    BAUD, 57
    F_CPU, 57
    uart_getchar, 57
    uart_init, 58
    uart_putchar, 58
uart_getchar
    uart.c, 67
    uart.h, 57
uart_init
    uart.c, 67
    uart.h, 58
uart_io
    uart.c, 67
uart_putchar
    uart.c, 67
    uart.h, 58
WGM0
    bytes, 12
WGM1
    bytes, 12
WGM2
    bytes, 12
WGM3
```

bytes, 12