# Simple usage examples

```
\label{eq:out_3} \begin{split} &\text{In[3]:= exp1 = ToSphericalCoordinates}\left[\left\{x,\,y,\,z\right\}\right] \\ &\text{Out[3]= } \left\{\sqrt{x^2+y^2+z^2} \text{ , } \text{ArcTan}\left[z,\,\sqrt{x^2+y^2}\right] \text{ , } \text{ArcTan}\left[x,\,y\right]\right\} \end{split}
```

The default output is in HoldForm to prevent evaluating and returning the original expression.

```
 \begin{aligned} &\text{In}[4]\text{:= FactorExpression}\left[\text{exp1}\right] \\ &\text{Out}[4]\text{= Block}\left[\left\{\$0\,,\,\$1\right\},\,\$0=x^2\,; \\ &\quad \$1=y^2\,; \\ &\quad \left\{\sqrt{z^2+\$0+\$1}\,,\,\text{ArcTan}\left[z\,,\,\sqrt{\$0+\$1}\,\right],\,\text{ArcTan}\left[x\,,\,y\right]\right\} \right] \\ &\text{In}[5]\text{:= exp2} = \text{FromSphericalCoordinates}\left[\left\{r\,,\,\varTheta\,,\,\phi\right\}\right] \\ &\text{Out}[5]\text{= }\left\{r\,\text{Cos}\left[\phi\right]\,\text{Sin}\left[\varTheta\right]\,,\,r\,\text{Sin}\left[\varTheta\right]\,\text{Sin}\left[\varTheta\right]\,,\,r\,\text{Cos}\left[\varTheta\right]\right\} \\ &\text{In}[6]\text{:= FactorExpression}\left[\text{exp2}\right] \\ &\text{Out}[6]\text{= Block}\left[\left\{\$2\right\},\,\$2=\text{Sin}\left[\varTheta\right]\,;\,\,&\left\{r\,\$2\,\text{Cos}\left[\varTheta\right]\,,\,r\,\$2\,\text{Sin}\left[\varTheta\right]\,,\,r\,\text{Cos}\left[\varTheta\right]\right\}\right] \end{aligned}
```

## For large expressions, the factored form generally ends up being much smaller.

```
In[7]:= exp3 = RotationTransform[\Theta, \{xr, yr, zr\}][\{x, y, z\}];
       LeafCount [exp3]
Out[8]= 5563
 In[9]:= fexp3 = FactorExpression[exp3];
       LeafCount [fexp3]
Out[10]= 919
```

# **Automatic optimization**

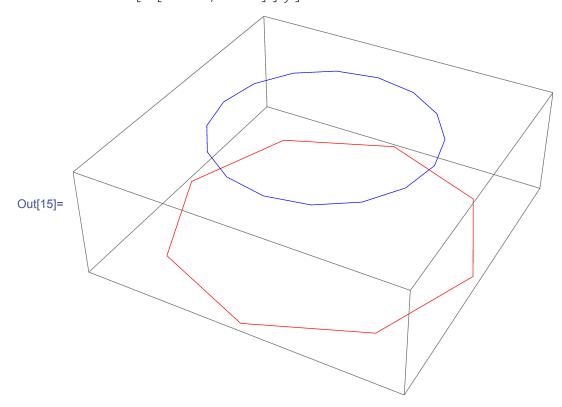
#### Define a function:

```
In[11]:= ClearAll [f];
     f[r_{-}, t_{-}] :=
       Table [r \cos[p] \sin[t], r \sin[t] \sin[p], r \cos[t]],
        {p, -Pi, Pi, Pi/4}]
      f[r_, t_, n_] :=
       Table [r \cos[p] \sin[t], r \sin[t] \sin[p], r \cos[t]],
        \{p, -Pi, Pi, Pi/n\}
```

#### Check the definition:

```
In[14]:= Definition [f]
Out[14]= f[r_, t_] :=
                \label{lem:tosep} \texttt{Table} \big[ \big\{ \texttt{rCos[p]} \; \texttt{Sin[t]} \, , \, \texttt{rSin[t]} \; \texttt{Sin[p]} \, , \, \texttt{rCos[t]} \big\} \, ,
                  \left\{ \mathbf{p}_{1}, -\pi_{1}, \pi_{2}, \frac{\pi_{3}}{4} \right\}
             f[r_, t_, n_] :=
                Table [r Cos[p] Sin[t], r Sin[t] Sin[p], r Cos[t]],
                  \left\{ \mathbf{p}_{\bullet} - \pi_{\bullet} \pi_{\bullet} \frac{\pi}{\mathbf{n}} \right\}
```

### Example output:



Use OptimizeDownValues to rewrite definitions of functions in an optimized form.

Notice that tables with constant iteration limits are "unrolled", while those with parametrized limits are not.

```
In[16]:= Quiet@OptimizeDownValues[f]
\mathsf{Out} [\mathsf{16}] = \; \Big\{ \mathsf{HoldPattern} \left[ \, \mathsf{f} \left[ \, \mathsf{r}_{-}, \, \, \mathsf{t}_{-} \, \right] \, \right] \, : \to \, \mathsf{Block} \, \Big[ \,
                  \{\$107,\$108,\$109,\$110,\$111,\$112,\$113\},\$107 = Sin[t];
                 $108 = Cos[t];
                 $109 = r $108:
                 $110 = \frac{1}{\sqrt{2}};
                 $111 = r $107 $110;
                 112 = \{-r 107, 0, 109\};
                 $113 = r $107;
                 {$112, {-$111, -$111, $109}, {0, -$113, $109}, {$111,
                     -$111, $109}, {$113, 0, $109}, {$111, $111, $109},
                   \{0, \$113, \$109\}, \{-\$111, \$111, \$109\}, \$112\}
             \label{eq:holdPattern} \texttt{HoldPattern}\big[\texttt{f}\big[\texttt{r}\_\texttt{,}~\texttt{t}\_\texttt{,}~\texttt{n}\_\big]\big] :\rightarrow \texttt{Block}\big[\big\{\$114\big\}\texttt{,}~\$114 = \texttt{Sin}\big[\texttt{t}\big]\texttt{;}
                 Table [r \cos[p] $114, r $114 \sin[p], r \cos[t]],
                   \left\{\mathsf{p}, -\pi, \pi, \frac{\pi}{\mathsf{p}}\right\}\right]
```

When the option "Rewrite" is False (default), the original definition is unchanged.

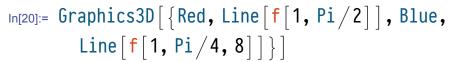
```
In[17]:= Definition [f]
Out[17]= f[r_, t_] :=
                         Table \Big[ \big\{ r \, \mathsf{Cos}[\mathsf{p}] \, \mathsf{Sin}[\mathsf{t}] \, , \, r \, \mathsf{Sin}[\mathsf{t}] \, \mathsf{Sin}[\mathsf{p}] \, , \, r \, \mathsf{Cos}[\mathsf{t}] \big\} \, ,
                             \left\{ \mathbf{p}_{\bullet} - \pi_{\bullet} \pi_{\bullet} \frac{\pi}{4} \right\}
                     f[r_, t_, n_] :=
                         \label{eq:table_sin_p} \textbf{Table} \big[ \big\{ \textbf{r} \, \textbf{Cos}[\textbf{p}] \, \, \textbf{Sin}[\textbf{t}] \, \, \textbf{,} \, \, \textbf{r} \, \textbf{Sin}[\textbf{t}] \, \, \textbf{Sin}[\textbf{p}] \, \, \textbf{,} \, \, \textbf{r} \, \textbf{Cos}[\textbf{t}] \, \big\} \, ,
                             \left\{ \mathbf{p}, -\pi, \pi, \frac{\pi}{\mathbf{n}} \right\}
```

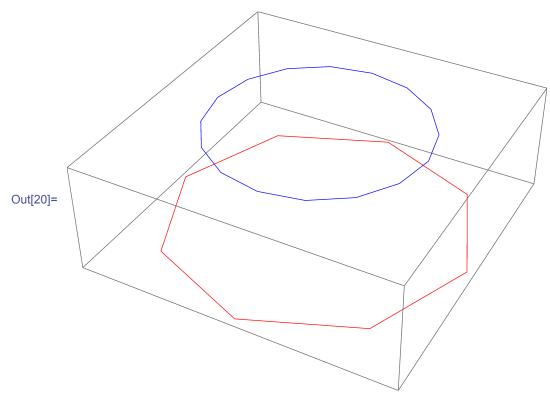
### Use "Rewrite" set to True to redefine the function.

```
In[18]:= Quiet@OptimizeDownValues[f, "Rewrite" → True]
\texttt{Out[18]=} \ \left\{ \texttt{HoldPattern} \left[ \, \texttt{f} \left[ \, \texttt{r}_{-} \text{, } \texttt{t}_{-} \, \right] \, \right] \, \Rightarrow \texttt{Block} \, \right[
                   \{\$115,\$116,\$117,\$118,\$119,\$120,\$121\},\$115 = Sin[t];
                   $116 = Cos[t];
                  $117 = r $116:
                  $118 = \frac{1}{\sqrt{2}};
                   $119 = r $115 $118:
                   120 = \{-r 115, 0, 117\};
                   $121 = r $115;
                   \{\$120, \{-\$119, -\$119, \$117\}, \{0, -\$121, \$117\}, \{\$119,
                       -$119, $117}, {$121, 0, $117}, {$119, $119, $117},
                     \{0, \$121, \$117\}, \{-\$119, \$119, \$117\}, \$120\}
              \label{eq:holdPattern} \texttt{HoldPattern}\big[\texttt{f}\big[\texttt{r}\_,\texttt{t}\_,\texttt{n}\_\big]\big] \Rightarrow \texttt{Block}\big[\big\{\$122\big\},\,\$122 = \texttt{Sin}\big[\texttt{t}\big] \texttt{;}
                  Table \big[ \big\{ r \, \mathsf{Cos} \, [p] \, \$122 \text{,} \, r \, \$122 \, \mathsf{Sin} \, [p] \text{,} \, r \, \mathsf{Cos} \big[ \, t \, \big] \big\} \text{,}
                    \left\{\mathsf{p}, -\pi, \pi, \frac{\pi}{\mathsf{n}}\right\}\right]
```

### The function now has optimized defintions.

```
In[19]:= Definition [f]
Out[19]= f[r_, t_] := Block
          \{\$115,\$116,\$117,\$118,\$119,\$120,\$121\},\$115 = Sin[t];
          $116 = Cos[t];
          $117 = r $116:
          $118 = \frac{1}{\sqrt{2}};
          $119 = r $115 $118;
          120 = -r 115, 0, 117;
          $121 = r $115;
          \{\$120, \{-\$119, -\$119, \$117\}, \{0, -\$121, \$117\},\
           {$119, -$119, $117}, {$121, 0, $117}, {$119, $119, $117},
           {0, $121, $117}, {-$119, $119, $117}, $120}
       f[r_{-}, t_{-}, n_{-}] := Block[{$122}, $122 = Sin[t];
         Table
           \left\{r \cos[p] \$122, r \$122 \sin[p], r \cos[t]\right\}, \left\{p, -\pi, \pi, \frac{\pi}{n}\right\}\right]
```





#### Other options: Memoization

```
In[21]:= fibonacci [0]=0;
      fibonacci[1] = 1;
      fibonacci[n_Integer] :=
         fibonacci [n-1] + fibonacci [n-2];
In[24]:= AbsoluteTiming[fibonacci[30]]
Out[24]= \{3.63889, 832040\}
In[25]:= OptimizeDownValues [fibonacci, "Memoize" \rightarrow True,
        "Rewrite" → True];
```

```
In[26]:= AbsoluteTiming[fibonacci[30]]
Out[26]= \{0.000282578, 832040\}
```

#### Memoization as a separate function

```
In[27]:= factorial [0]=1;
      factorial [n : Integer] := factorial [n - 1] * n;
In[29]:= Memoize [factorial];
In[30]:= Definition [factorial]
Out[30]= factorial [0] := factorial [0] = 1
      factorial[n_Integer] := factorial[n] = factorial[n - 1] n
```

# Example of performance gains

Find a unit vector normal to a tetrahedron in 4D space.

```
\left\{\,e\,\mathbf{1}\,\rightarrow\,\left\{\,\mathbf{1}\,,\,\,0\,,\,\,0\,,\,\,0\,\right\}\,,\,\,e\,\mathbf{2}\,\rightarrow\,\left\{\,0\,,\,\,\mathbf{1}\,,\,\,0\,,\,\,0\,\right\}\,,\,\,e\,\mathbf{3}\,\rightarrow\,\left\{\,0\,,\,\,0\,,\,\,\mathbf{1}\,,\,\,0\,\right\}\,,
                   e4 \rightarrow \{0, 0, 0, 1\}\};
In[32]:= Sexp = Simplify nexp,
                Union[Cases[nexp, _Symbol, Infinity]] ∈ Reals];
```

```
In[33]:= tetraNormal [ \{x1_, y1_, z1_, w1_\}, \{x2_, y2_, z2_, w2_\} ]
          \{x3_{-}, y3_{-}, z3_{-}, w3_{-}\}, \{x4_{-}, y4_{-}, z4_{-}, w4_{-}\}\} :=
        Evaluate [sexp]
```

#### Find the normals to each face of a pentachoron.

```
In[34]:= pentachoron = { {x1, y1, z1, w1}, {x2, y2, z2, w2},
         \{x3, y3, z3, w3\}, \{x4, y4, z4, w4\}, \{x5, y5, z5, w5\}\};
      tetrahedra = Subsets[pentachoron, {4}];
      pentachoronFaceNormals = tetraNormal @@@ tetrahedra;
      LeafCount [pentachoronFaceNormals]
```

Out[37]= 10 586

## Set up a function that evaluates the original expression.

```
In[38]:= test1[\{x1_, y1_, z1_, w1_\}, \{x2_, y2_, z2_, w2_\},
           \{x3_{-}, y3_{-}, z3_{-}, w3_{-}\}, \{x4_{-}, y4_{-}, z4_{-}, w4_{-}\},
           \{x5_{-}, y5_{-}, z5_{-}, w5_{-}\}\}
        Evaluate[pentachoronFaceNormals]
```

#### Paste the output of FactorExpression into another function.

```
In[39]:= Block [ { $RecursionLimit = Infinity,
         $IterationLimit = Infinity},
       FactorExpression[pentachoronFaceNormals]]
In[40]:= ( * output removed *)
In[41]:= test2 [ \{ x1_, y1_, z1_, w1_ \}, \{ x2_, y2_, z2_, w2_ \}, 
          \{x3_{-}, y3_{-}, z3_{-}, w3_{-}\}, \{x4_{-}, y4_{-}, z4_{-}, w4_{-}\},
```

```
\{x5_{-}, y5_{-}, z5_{-}, w5_{-}\}\}
Block [$123, $124, $125, $126, $127, $128, $129, $130,
  $131, $132, $133, $134, $135, $136, $137, $138,
  $139. $140. $141. $142. $143. $144. $145. $146.
  $147, $148, $149, $150, $151, $152, $153, $154,
  $155, $156, $157, $158, $159, $160, $161, $162,
  $163, $164, $165, $166, $167, $168, $169, $170,
  $171, $172, $173, $174, $175, $176, $177, $178,
  $179, $180, $181, $182, $183, $184, $185, $186,
  $187, $188, $189, $190, $191, $192, $193, $194.
  $195, $196, $197, $198, $199, $200, $201, $202,
  $203, $204, $205, $206, $207, $208, $209, $210,
  $211, $212, $213, $214, $215, $216, $217, $218,
  $219, $220, $221, $222, $223, $224, $225, $226,
  $227, $228, $229, $230, $231, $232, $233, $234,
  $235, $236, $237, $238, $239, $240, $241, $242,
  $243, $244, $245, $246, $247, $248, $249, $250,
  $251, $252, $253, $254, $255, $256, $257, $258.
  $259, $260, $261, $262, $263, $264, $265, $266,
  $267, $268, $269, $270, $271, $272, $273, $274.
  $275, $276, $277, $278, $279, $280, $281, $282,
  $283, $284, $285, $286, $287, $288, $289, $290,
  $291, $292, $293, $294, $295, $296, $297, $298,
  $299, $300, $301, $302, $303, $304, $305, $306,
  $307, $308, $309, $310, $311, $312, $313, $314,
  $315, $316, $317, $318, $319, $320, $321, $322,
  $323, $324, $325, $326, $327, $328, $329, $330,
  $331, $332, $333, $334, $335, $336, $337, $338,
  $339, $340, $341, $342, $343, $344, $345, $346,
  $347, $348, $349, $350, $351, $352, $353, $354,
  $355, $356, $357, $358, $359, $360, $361, $362,
```

```
$363, $364, $365, $366, $367, $368, $369, $370,
 $371, $372, $373, $374, $375, $376, $377, $378,
 $379, $380, $381, $382, $383, $384, $385, $386,
 $387, $388, $389, $390, $391, $392, $393, $394,
 $395, $396, $397, $398, $399, $400, $401, $402,
 $403, $404, $405, $406, $407, $408, $409, $410,
 $411, $412, $413, $414, $123 = z1 - z5;
$124 = y1 z2:
$125 = y2 z3;
$126 = y1z5;
$127 = y4z2:
$128 = y3z1;
$129 = y4z1;
$130 = y5 z2:
$131 = -y2z1 - y3z2 - y1z3 + $124 + $125 + $128:
$132 = y2 $123:
$133 = -y5z1 - $124 + $126 + $130 + $132;
$134 = y5 z3:
$135 = y3 z4:
$136 = x1 y2;
$137 = x1z2:
$138 = x2 y3:
$139 = y1 - y5:
$140 = x1 y5:
$141 = z1 - z4;
$142 = x2z3:
$143 = z2 - z5:
$144 = y1z3:
$145 = x1 z5:
$146 = y1z4:
$147 = w1 y3 z2;
$148 = W1 y4 z3;
```

```
$149 = w2 $144:
$150 = W1 \times 3 \times 2:
$151 = W2 \times 1 \times 3;
$152 = W1 \times 4 \times 3;
$153 = x4 y2;
$154 = x3 y1;
$155 = -x2y1 - x3y2 - x1y3 + $136 + $138 + $154;
$156 = W2 y5 z1;
$157 = W1 y2 z5;
$158 = W2 y3 z5;
$159 = W2 \times 5 y1;
$160 = W1 \times 2 \times 5;
$161 = W2 \times 3 \times 5;
$162 = x5 y2:
$163 = x2 $139:
$164 = -x5y1 - $136 + $140 + $162 + $163;
$165 = W1 y5 z4;
$166 = y2 z4;
$167 = W1 \times 5 \text{ y4};
$168 = x4 y1:
$169 = W3 y4 z5;
$170 = W3 \times 4 \times 5:
$171 = x5 y3:
$172 = x3 y4;
$173 = y2 $141;
$174 = -$124 + $127 - $129 + $146 + $173:
$175 = x4z2:
$176 = x3z1:
$177 = x4z1;
$178 = x5 z2:
$179 = -y2z1 + $124 - $127 + $129 - $146 + $166;
$180 = y3$$123;
```

```
$181 = -y4z3 - $128 + $129 + $135 + $144 - $146;
$182 = -y5z1 + $126 + $134 - $144 + $180;
$183 = y2 z5:
$184 = -y3z2 - y4z3 + $125 + $127 + $135 - $166;
$185 = y3$$143:
$186 = -$125 - $130 + $134 + $183 + $185;
$187 = x1 y4 z3;
$188 = W1 \times 3 \times 22;
$189 = y3$$137:
$190 = W2 \times 1 \times 23:
$191 = v1 $142:
$192 = W1 \times 4 \times 23:
$193 = -x2z1 - x3z2 - x1z3 + $137 + $142 + $176;
$194 = x2 y5 z1:
$195 = W2 \times 5 \times 21;
$196 = z5 $136;
$197 = W1 \times 2 \times 25:
$198 = z5 $138;
$199 = W2 \times 3 \times 25:
$200 = x2 $123:
$201 = -x5z1 - $137 + $145 + $178 + $200;
$202 = 24 $140:
$203 = W1 \times 5 Z4:
$204 = z5 $172:
$205 = W3 \times 4 \times 25:
$206 = x5 z3:
$207 = x3 z4:
$208 = x1z3:
$209 = x1 z4;
$210 = -21 + 25;
$211 = W2 $129:
$212 = W4 $131;
```

```
$213 = W2 $135:
$214 = w1 $166:
$215 = W3 $174:
$216 = -w^2 y^4 z^3 - w^1 $125 - w^1 $127 - w^2 $128 - w^1 $135 -
  w2 $146 + $147 + $148 + $149 + $211 + $212 + $213 +
  $214 + $215:
$217 = W1 \times 2 \text{ y4};
$218 = x2 $129;
$219 = W1 \times 2 \times 24;
$220 = W4 $155:
$221 = x2 $135;
$222 = W2 $177:
$223 = y1 - y4:
$224 = 24 $136:
$225 = W2 $207:
$226 = W2 $168;
$227 = W2 $172;
$228 = x1 y4;
$229 = x2 $223;
$230 = -$136 + $153 - $168 + $228 + $229:
$231 = W3 $230:
$232 = -w2 \times 4 y3 - w1 \$138 + \$150 + \$151 + \$152 - w1 \$153 -
  w2 $154 - w1 $172 + $217 + $220 + $226 + $227 - w2 $228 + $231:
$233 = W2 \times 4 \times 23;
$234 = w1 $175;
$235 = W2 $209:
$236 = x1 $127;
$237 = y4 $142:
$238 = x2 $146;
$239 = w5 $131;
$240 = W3 $133:
$241 = w1 $134;
```

```
$242 = -w1 \, v3 \, z5 - w1 \, $125 - w2 \, $126 - w2 \, $128 - w1 \, $130 - w2 \, $128 - w2 \, 
        w2 $134 + $147 + $149 + $156 + $157 + $158 + $239 +
        $240 + $241:
$243 = w5 $155:
$244 = x1 $134:
$245 = w1 $206:
$246 = W3 $164:
$247 = w1 $171:
$248 = -W1 \times 3 \times 5 - W1 \times 138 - W2 \times 140 + \times 150 + \times 151 -
        w2 $154 + $159 + $160 + $161 - w1 $162 - w2 $171 +
        $243 + $246 + $247:
$249 = W1 \times 3 \times 25:
$250 = y3$$145:
$251 = w2 y4 z5:
$252 = w1 $127;
$253 = w4 $133:
$254 = w2 $146;
$255 = W5 $179:
$256 = -w2 y5 z4 - w1 y4 z5 - w2 $126 - w1 $130 + $156 +
        $157 + $165 - $211 - $214 + $251 + $252 + $253 + $254 + $255
$257 = W2 \times 4 \times 5;
$258 = W2 \times 4 \times 25:
$259 = x2 y4 z5:
$260 = w1 $153:
$261 = x2 z4;
$262 = W4 $164:
$263 = x2 y4;
$264 = w2 $228:
$265 = -x2y1 + $136 - $153 + $168 - $228 + $263;
$266 = $\times 5$ $265:
$267 = -w2 \times 5 \times 4 - w1 \times 4 \times 5 - w2 \times 5140 + \$159 + \$160 -
         W1 $162 + $167 - $217 - $226 + $257 + $260 + $262 +
```

```
$264 + $266:
$268 = W2 \times 5 Z4:
$269 = y5 $261:
$270 = W3 y5 z1;
$271 = W1 y3 z5;
$272 = W3 $146:
$273 = W5 $181:
$274 = W4 $182:
$275 = -w3 y5 z4 - w1 y4 z5 - w3 $126 - w3 $129 - w1 $135 +
  $148 + $165 + $169 - $241 + $270 + $271 + $272 + $273 + $274;
$276 = W3 \times 5 \times 1:
$277 = W1 \times 3 \times 5:
$278 = x3 $139:
$279 = x1 y3:
$280 = W3 $228:
$281 = -x5y1 + $140 + $171 + $278 - $279;
$282 = -x4 y3 - $154 + $168 + $172 - $228 + $279;
$283 = W4 $281;
$284 = W5 $282:
$285 = -w3 \times 5 \times 4 - w1 \times 4 \times 5 - w3 \times 140 + \$152 + \$167 -
  w3 $168 + $170 - w1 $172 - $247 + $276 + $277 + $280 +
  $283 + $284:
$286 = W2 \text{ y4 z3}:
$287 = W2 y5 z4;
$288 = W3 $130:
$289 = W3 $166:
$290 = w5 $184;
$291 = w4 $186;
$292 = -w3 y5 z4 - w3 $127 - w2 $134 + $158 + $169 -
  w3 $183 - $213 - $251 + $286 + $287 + $288 + $289 +
  $290 + $291:
$293 = W2 \times 4 \times 3;
```

```
$294 = W2 \times 5 \times 4:
$295 = W3 $162:
$296 = v2 - v5:
$297 = -x3y2 - x4y3 + $138 + $153 + $172 - $263;
$298 = W3 $263:
$299 = x2 y5;
$300 = W5 $297
$301 = x3$$296:
$302 = -$138 - $162 + $171 + $299 + $301:
$303 = W4 $302:
$304 = -w3 \times 5 \times 4 - w3 \times 5153 + \$161 + \$170 - w2 \times 5171 - 
  $227 - $257 + $293 + $294 + $295 + $298 - w3 $299 +
  $300 + $303:
$305 = $216^2:
$306 = $232^2:
$307 = W4 $193:
$308 = x4 $131:
$309 = x2 $141:
$310 = x3 $174:
\$311 = -\$137 + \$175 - \$177 + \$209 + \$309:
\$312 = -x1 \$125 - x2 \$128 - x1 \$135 + \$187 + \$189 + \$191 +
  $218 + $221 + $224 - $236 - $237 - $238 + $308 + $310;
$313 = W3 $311:
$314 = $312^2:
$315 = -w1$142 - w2$176 + $188 + $190 + $192 - w1$207 +
  $219 + $222 + $225 - $233 - $234 - $235 + $307 + $313
$316 = $315^2:
$317 = $305 + $306 + $314 + $316;
$318 = \frac{1}{\sqrt{$317}};
$319 = $242^2:
```

```
$320 = $248^2:
$321 = w5 $193:
$322 = x5 $131;
$323 = W3 $201:
$324 = x3 $133:
$325 = -w1 $142 - w2 $145 - w2 $176 - w1 $178 + $188 +
  $190 + $195 + $197 + $199 - w2 $206 + $245 - $249 +
  $321 + $323:
$326 = -x1$125 - x2$126 - x2$128 - x1$130 - x2$134 +
  $189 + $191 + $194 + $196 + $198 + $244 - $250 + $322 + $324;
$327 = $325^2;
$328 = $326^2;
$329 = $319 + $320 + $327 + $328;
$330 = ____;
$331 = $256^2;
$332 = $267^2;
$333 = W4 $201:
$334 = x4 $133:
$335 = -x2z1 + $137 - $175 + $177 - $209 + $261;
$336 = x5 $179:
$337 = $\times 5 $335$:
$338 = -x2$126 - x1$130 - y4$145 + $194 + $196 + $202 -
  $218 - $224 + $236 + $238 + $259 - $269 + $334 + $336;
$339 = -w1 \times 4 \times 25 - w2 \times 5145 - w1 \times 5178 + \times 5195 + \times 5197 +
  $203 - $219 - $222 + $234 + $235 + $258 - $268 + $333 + $337;
$340 = $338^2:
$341 = $339^2:
$342 = $331 + $332 + $340 + $341;
```

\$343 = 
$$\frac{1}{\sqrt{$342}}$$
;

\$344 =  $w3 \times 5 \times 21$ ;

\$345 =  $x3 \times 146$ ;

\$346 =  $\$275^2$ ;

\$347 =  $\$285^2$ ;

\$348 =  $x3 \times 123$ ;

\$349 =  $y5 \times 176$ ;

\$350 =  $-x4 \times 23 - \$176 + \$177 + \$207 + \$208 - \$209$ ;

\$351 =  $x5 \times 181$ ;

\$352 =  $w3 \times 209$ ;

\$353 =  $x4 \times 182$ ;

\$354 =  $-x5 \times 21 + \$145 + \$206 - \$208 + \$348$ ;

\$355 =  $-x3 \times 126 - x3 \times 129 - x1 \times 135 - y4 \times 145 + \$187 + \$202 + \$204 - y5 \times 207 - \$244 + \$250 + \$345 + \$349 + \$351 + \$353$ ;

\$356 =  $w5 \times 350$ ;

\$357 =  $\$355^2$ ;

\$358 =  $w4 \times 354$ ;

\$359 =  $-w3 \times 5 \times 24 - w1 \times 4 \times 25 - w3 \times 145 - w3 \times 177 + \$192 + \$203 + \$205 - w1 \times 207 - \$245 + \$249 + \$344 + \$352 + \$356 + \$358$ ;

\$360 =  $\$359^2$ ;

\$361 =  $\$346 + \$347 + \$357 + \$360$ ;

\$363 =  $w3 \times 178$ ;

\$364 =  $x3 \times 130$ ;

\$365 =  $\$292^2$ ;

\$366 =  $\$304^2$ :

```
$367 = x2z5:
$368 = x3$$166:
$369 = -x3z2 - x4z3 + $142 + $175 + $207 - $261:
$370 = x5 $184:
$371 = W3 $261;
$372 = x4 $186:
$373 = x3 $143:
$374 = -x3$127 - x2$134 - x3$183 + $198 + $204 -
            y5 $207 - $221 + $237 - $259 + $269 + $364 + $368 +
            $370 + $372:
$375 = $w5$$369:
$376 = $374^2:
\$377 = -\$142 - \$178 + \$206 + \$367 + \$373;
$378 = W4 $377:
$379 = -w3 \times 5 \times 24 - w3 \times 175 + \$199 + \$205 - w2 \times 206 - w3 \times 175 + \$199 + \$205 - w2 \times 199 + \$205 - w3 \times 199 + w3 \times 
            $225 + $233 - $258 + $268 + $363 - w3 $367 + $371 +
            $375 + $378;
$380 = $379^2:
$381 = $365 + $366 + $376 + $380;
$382 = \frac{1}{\sqrt{$381}};
$383 = x2z1:
$384 = x3 z2;
$385 = y2z1:
$386 = y3 z2;
$387 = x5 z1:
$388 = y5 z1:
$389 = w1 $142:
$390 = W2 $176;
$391 = w1 $207;
$392 = -z1 + z4:
```

```
$393 = -$137 - $142 - $176 + $208 + $383 + $384;
$394 = x1 $125:
$395 = x2 $128:
$396 = x1 $135:
$397 = -$124 - $125 - $128 + $144 + $385 + $386;
$398 = W2 $145:
$399 = W1 $178:
$400 = W2 $206;
$401 = x2 $210;
$402 = $137 - $145 - $178 + $387 + $401;
$403 = x2 $126:
$404 = x1 $130:
$405 = x2 $134:
$406 = y2 $210:
$407 = $124 - $126 - $130 + $388 + $406;
$408 = W1 \times 4 \times 25;
$409 = y4 $145:
$410 = W3 \times 5 Z4;
$411 = x4 z3:
$412 = y4 z3:
$413 = y5 $207:
$414 = -22 + 25:
{ \$216 \$318,
  $318 (-$188 - $190 - $192 - $219 - $222 - $225 + $233 +
      $234 + $235 + $389 + $390 + $391 +
      w3 (\$137 - \$175 + \$177 - \$209 + x2 \$392) + w4 \$393),
  $232 $318.
  $318 (-$187 - $189 - $191 - $218 - $221 - $224 + $236 +
      $237 + $238 + x3 ($124 - $127 + $129 - $146 + y2 $392) +
      $394 + $395 + $396 + \times 4$397)
 {$242 $330,
```

```
$330 (-$188 - $190 - $195 - $197 - $199 - $245 + $249 +
    \$389 + \$390 + w5 \$393 + \$398 + \$399 + \$400 + w3 \$402
$248 $330.
$330 (-$189 - $191 - $194 - $196 - $198 - $244 + $250 +
    394 + 395 + x5 + 397 + 403 + 404 + 405 + x3 + 407
{$256 $343,
$343 (-$195 - $197 - $203 + $219 + $222 - $234 - $235 -
    $258 + $268 +
    w5 (-$137 + $175 - $177 + $209 - $261 + $383) +
    $398 + $399 + w4 $402 + $408), $267 $343,
$343 (-$194 - $196 - $202 + $218 + $224 - $236 - $238 -
    $259 + $269 +
    x5 (-$124 + $127 - $129 + $146 - $166 + $385) +
    $403 + $404 + x4 $407 + $409)}
$275 $362,
$362 (w3 $145 + w3 $177 - $192 - $203 - $205 + $245 -
    $249 - $344 - $352 +
    w4 (-$145 - $206 + $208 + x3 $210 + $387) + $391 +
    $408 + $410 +
    w5 ($176 - $177 - $207 - $208 + $209 + $411)),
$285 $362,
$362 (x3 $126 + x3 $129 - $187 - $202 - $204 + $244 -
    $250 - $345 - $349 +
    x4 (-$126 - $134 + $144 + y3 $210 + $388) + $396 +
    $409 + x5 ($128 - $129 - $135 - $144 + $146 + $412) +
    $413)},
$292 $382,
$382 (w3 $175 - $199 - $205 + $225 - $233 + $258 -
    $268 - $363 + w3 $367 - $371 + $400 + $410 +
```

```
w5 (-$142 - $175 - $207 + $261 + $384 + $411) +
   w4 ($142 + $178 - $206 - $367 + x3 $414)),
$304 $382.
$382 (x3 $127 + x3 $183 - $198 - $204 + $221 - $237 +
   $259 - $269 - $364 - $368 + $405 +
   x5 (-$125 - $127 - $135 + $166 + $386 + $412) +
   $413 + x4 ($125 + $130 - $134 - $183 + y3 $414))}}
```

The "Output" option allows a compiled function to be returned instead of a Block in HoldForm. This is currently experimental and assumes all symbols are Real.

```
In[42]:= CEXD =
       Block[{$RecursionLimit = Infinity,
         $IterationLimit = Infinity},
        FactorExpression pentachoronFaceNormals,
         "Output" → CompiledFunction]]
Out[42]= CompiledFunction
```

```
Argument count: 20
                                                        {_Real, _Real, _
```

```
In[43]:= test3 [ \{ x1_, y1_, z1_, w1_ \}, \{ x2_, y2_, z2_, w2_ \}, 
           \{x3_{-}, y3_{-}, z3_{-}, w3_{-}\}, \{x4_{-}, y4_{-}, z4_{-}, w4_{-}\},
           \{x5_{-}, y5_{-}, z5_{-}, w5_{-}\}\}
        \mathsf{cExp}[w1, w2, w3, w4, w5, x1, x2, x3, x4, x5, y1, y2,
         y3, y4, y5, z1, z2, z3, z4, z5
```

#### Run some timing tests.

```
In[44]:= testParams = RandomReal [\{-1, 1\}, \{5, 4\}];
In[45]:= \{t1, res1\} =
        SetPrecision[RepeatedTiming[test1[testParams], 3],
          $MachinePrecision];
      t1
Out[46]= 0.002212249823404273
In[47]:= \{t2, res2\} =
        SetPrecision[RepeatedTiming[test2[testParams], 3],
          $MachinePrecision];
      t2
Out[48]= 0.0007356430387412677
In[49]:= \{t3, res3\} =
        SetPrecision[RepeatedTiming[test3[testParams], 3],
          $MachinePrecision];
      t3
Out[50]= 0.00002148350944493357
```

Using FactorExpression can yield modest performance gains (about 3x faster in this example). For much larger expressions, the performance increase can get rather ridiculous (several orders of magnitude).

```
In[51]:= t1/t2
Out[51]= 3.007232729598821
ln[52] = t1/t3
Out[52]= 102.9743221923169
```

The results are also correct in case you were wondering.

```
In[53]:= Chop@Total Abs Flatten res1 - res2]]]
Out[53]= 0
In[54]:= Chop@Total Abs Flatten res1 - res3]]
Out[54]= 0
```