

$$Re(\tilde{u}_t + \nabla \tilde{u} \cdot \tilde{u}) = -Re \nabla p + \mu \Delta \tilde{u} + \tilde{f} \quad \times \text{ for Stokes}$$

$$P^* = P / \tilde{p}^*$$

$$Re \rightarrow 0 \quad 0 = \mu \Delta \tilde{u} + \tilde{f} \leftarrow \begin{matrix} \text{2 eqns} \\ (2D) \end{matrix} \rightarrow u, v \text{ determined}$$

$$\boxed{\nabla \cdot \tilde{u} = 0 \times \leftarrow}$$

$$Re \tilde{u}_t = -Re \nabla \tilde{u} \cdot \tilde{u} - \nabla p + \nabla \cdot (2\mu D(\tilde{u})) + \tilde{f}$$

$$D = \frac{1}{2} (\nabla \tilde{u} + \nabla \tilde{u}^T)$$

$$\Rightarrow P(\tilde{v}, t) = \tilde{v} - \frac{\langle \tilde{v}, \nabla p \rangle}{\langle \nabla p, \nabla p \rangle} \nabla p$$

$P(\tilde{u}_t, t) = \tilde{u}_t$	←
$P(\tilde{u}, t) = \tilde{u}$	←
$P(\nabla p, t) = 0$	←

$$\Rightarrow \tilde{u}_t = P \left( -Re \nabla \tilde{u} \cdot \tilde{u} + \right)$$

$$\Rightarrow \begin{cases} \operatorname{Re} \vec{u}_t = P(-\operatorname{Re} \nabla \vec{u} \cdot \vec{u} + \nabla \cdot (2\mu D(\vec{u})) + \vec{f}, t) \\ -\nabla p = (I - P)(-\operatorname{Re} \nabla \vec{u} \cdot \vec{u} + \nabla \cdot (2\mu D(\vec{u})) + \vec{f}) \end{cases}$$

Apply to Stokes ( $\text{Re} \rightarrow 0$ )

$$\text{Apply to Stokes } (\text{Re} \rightarrow 0)$$

$$\text{Re } \bar{u}_t = P(-\text{Re} \bar{u}_{\bar{u},t} + D - Q_{\bar{u}} D(\bar{u})) + \bar{f} + \bar{u}, t) - \bar{u}$$

$$Re(\vec{u}^{n+1} - \vec{u}^n) = \int_{t_n}^{t_{n+1}} P(\dots, t) dt - \int_{t_n}^{t_{n+1}} \vec{u} dt,$$

$$\text{Re}(\tilde{u}^{n+1} - \tilde{u}^n) = P(-\text{Re}\nabla_{\tilde{u}^n, \tilde{u}^n} + \nabla \cdot (2\mu D(\tilde{u}^n)) + \tilde{f}^n + \tilde{u}^n, t_n) \Delta t$$

$$R \quad O \quad (-\bar{u}^{n+1}) \Delta t^{\leftarrow}$$



$Re \rightarrow 0$  (to Stokes)

$\vec{u}^n \approx \vec{s}$

$$\Rightarrow 0 = P(\nabla \cdot (2\mu D(\vec{u}^n)) + \vec{f}^n + \vec{u}^n, t_n) \cancel{(st - \vec{u}^{n+1})} \cancel{dt}$$

$$\Rightarrow \vec{u}^{n+1} = P(\boxed{\vec{u}^n + \nabla \cdot (2\mu D(\vec{u}^n)) + \vec{f}^n}, t_n)$$

$$\vec{u}^{n+1} = \vec{u}^* - \frac{\langle \vec{u}^*, \nabla p^n \rangle}{\langle \nabla p^n, \nabla p^n \rangle} \nabla p^n$$

$$\nabla p^n = (\underline{I} - P)(-\text{Re} \nabla \vec{u} \cdot \vec{u}^n + \nabla \cdot (2\mu D(\vec{u}^n)) + \vec{f}^n)$$

$$\nabla p^n = (I - P)(\text{Re} \nabla \vec{u} \cdot \vec{u}^n + \nabla \cdot (2\mu D(\vec{u}^n)) + \vec{f}^n + \vec{u}^n)$$

$Re \rightarrow 0$

$\vec{u}^*$

$$\nabla_{P^n} = (\mathbb{I} - P) \left( \tilde{u}^n + \nabla \cdot (2\mu D(\tilde{u}^n)) + \tilde{f}^n \right) \xrightarrow{\text{Reück}}$$

$$\nabla_{P^n} = (\mathbb{I} - P) | \tilde{u}^* \quad (\nabla \cdot P(\tilde{u}^*) = 0)$$

$$\Delta P^n = P \cdot \tilde{u}^*$$

solve as before

$$\nabla_{P^n} \cdot \hat{n} = 0$$

using pseudo inverse

$$\nabla_{P^n} = \tilde{u}^* - P(\tilde{u}^*, t_n)$$

$$= \tilde{u}^* - \tilde{u}^* + \frac{\langle \tilde{u}^*, \nabla_{P^n} \rangle}{\langle \nabla_{P^n}, \nabla_{P^n} \rangle} \nabla_{P^n} \Rightarrow \nabla_{P^n} = \frac{\langle \tilde{u}^*, \nabla_{P^n} \rangle}{\langle \nabla_{P^n}, \nabla_{P^n} \rangle} \nabla_{P^n}$$

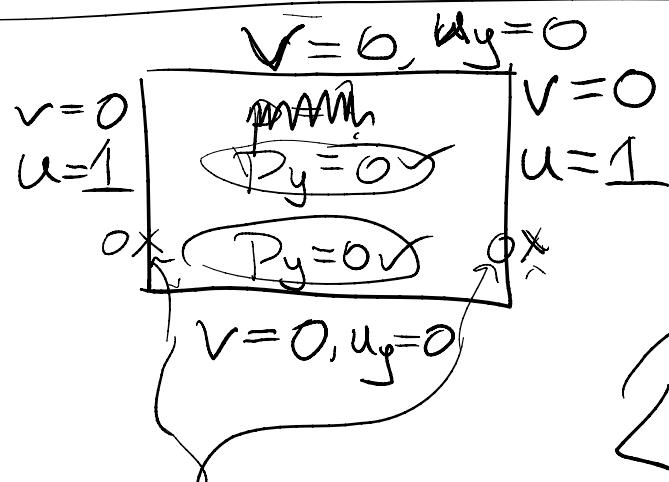
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$$1) \tilde{u}^* = \tilde{u}^n + \nabla \cdot (2\mu D(\tilde{u}^n)) + \tilde{f}^n \xleftarrow{\text{BCs?}}$$

$$2) \Delta P^n - \nabla \tilde{u}^* \leftarrow \text{BCs} \text{ are } \nabla_{P^n} \cdot \hat{n} = 0 + \text{pseudo}$$

2)  $\nabla \cdot \vec{P} = V \cdot a \leftarrow \text{BCs are } \vec{P} \cdot \hat{n} - V \text{ pseudo}$

3)  $\vec{u}^{n+1} = \vec{u}^* - \vec{P}_P^n \leftarrow \text{BCs from problem}$



$$\langle \vec{u}_t, \vec{P}_P \rangle = 0 \quad \checkmark$$

$$\Rightarrow \langle \vec{u}, \vec{P}_P \rangle = 0$$

$$\langle \vec{u}, \vec{P}_P \rangle = \iint_{\Omega} \vec{u} \cdot \vec{P}_P dV = \oint_{\partial\Omega} \vec{P}_P \cdot \hat{n} dS$$

$$= \iint_{\Omega} \vec{P}_P \cdot \hat{n} dV$$

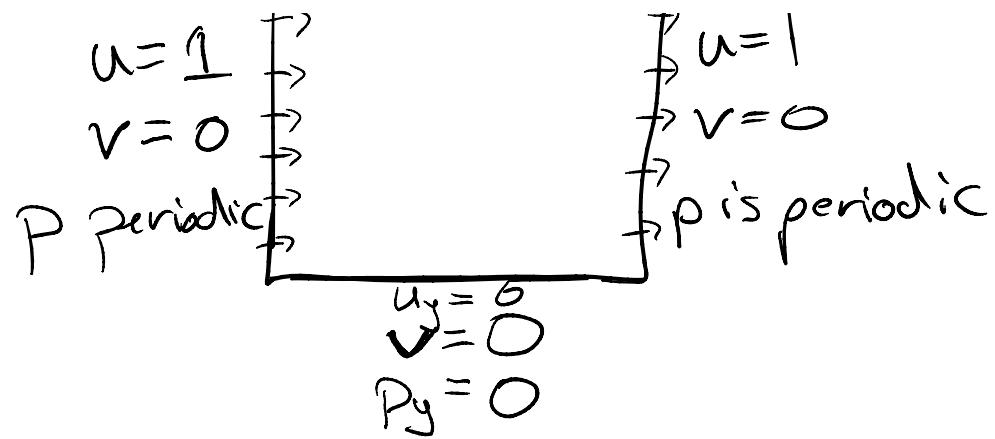
$$\vec{U}_P^n = \vec{P} \cdot \vec{u}^*$$

$$\begin{aligned} u_y &= 0 \\ V &= 0 \\ P_y &= 0 \end{aligned}$$

$$\begin{array}{c} \vec{F} \\ \uparrow \\ u=1 \end{array}$$

$$\oint_{\partial\Omega} \vec{P}_P \cdot \hat{n} = \iint_{\Omega} \vec{u}^* \cdot \hat{n} dV$$

Free-slip



Tree -> "F"

no friction