

## Joel Samuel Rhine

Washington, DC.

202-568-2029 • [joelrhine7@gmail.com](mailto:joelrhine7@gmail.com) • [www.linkedin.com/in/joel-rhine](https://www.linkedin.com/in/joel-rhine) • [www.github.com/rhinejoel](https://www.github.com/rhinejoel) • [www.joelrhine.tech](https://www.joelrhine.tech)

*A highly skilled cross-functional Project Manager seeking opportunities in Remote-Sensing UAV Systems Development, boasting a track record of success in dynamic environments, adeptly managing risks, and consistently surpassing project deliverables.*

### Education:

- **George Washington University**, Washington, DC. May, 2019. (**GPA 3.52**) M.S. in Mechanical and Aerospace Engineering
  - On-Campus Job: Graduate Student AV Assistant, GW Law Media Center
- **Don Bosco Institute of Technology, University of Mumbai**, Mumbai, India. April, 2016. B.S. in Mechanical Engineering.

### Technical and Language Skills:

- **Tools:** Solidworks, Ansys, Makerbot 3D, MS Office Suite **Spatial Analysis Tools:** ArcGIS (Pro, Online) QGIS, Mapbox, Google Earth Engine
- **Programming:** Python (ArcPy, PyQGIS, PyQt5, SentinelSat, OSMNX), HTML, CSS (Tailwind), JavaScript (ThreeJS, React) **Envs:** Conda
- **Skills:** Analytical, Collaborative, Problem-Solving, Effective Communicator, Organized, Prioritization, Risk Management
- **Languages:** English (fluent), Hindi (fluent) **Certifications:** Working towards PMP (anticipated April 2024), Part 107 Remote Pilot (Drone Pilot)

### Work Experience:

#### Development Monitors LLC, Arlington, VA

##### Project Manager – GIS and Remote Sensing Software Development

May 2021 – Present

Technical proposal writing, schedule deliverables with measurable KPIs, develop GIS analysis software and train machine learning models

- ARTMS 2D – Led a 5-developer team throughout project life-cycle utilizing **Python GIS API, PostgreSQL, kobotoolbox/kpi, WNTR (EPANET)**. Incorporated agile deliverables and defined KPIs at each stage of the project, meeting **100% of defined objectives**
- ARTMS 3D – Automated 3D terrain modelling using Sentinel 2 imagery (**SentinelSat**), USGS DEM (**OpenTopography**) and OSM data (**OSMNx**) reducing manual 3D generation time from 30 mins (proficient) to under 2 (non-expert) – **93% faster**
- ARTMS AI - Achieved above 80% IoU for Afghanistan buildings using 4cm HR aerial test and train imagery. Reduced manual creation time of building footprints in 1 Km<sup>2</sup> from 20 mins (proficient) to under 1 min (non-expert) – **76% effective decrease in time and effort**

##### Project Manager – Remote Sensing UAV Development

Jun 2019 – April 2021

Supervise and built drones and correction systems in collaboration with Virginia Tech's Unmanned Systems Lab (USL)

- Created computer aided design (CAD) models of UAV (drone) chassis in **SolidWorks** and 3D printed using **Prusa 3D** printer
- Researched and built drone equipped with Pixhawk flight controller, planned missions in **Mission Planner** and **Piloted Drones**
- Researched and built RTK GPS components (**Ardusimple u-blox GPS, antenna, base station, and datalogger**) and equipped drone with RTK
- Generated 2D georeferenced images and 3D dem models using Open Drone Map (**ODM**) CLI

##### GIS and Remote Sensing Specialist – International Development (Contract)

July 2019 – Apr 2023

- CBDRM/EW – **The World Bank**, Afghanistan (spatial analysis of communities at risk of natural hazard) Jul 2019 – Dec 2020
- EIDA II – **German Bank of Reconstruction (KfW)**, Afghanistan Apr 2020 – Aug 2021
- GPRBA SWM, Aden Climate Resilience, QIIP 7-City – **The World Bank**, Yemen Feb 2022 – Apr 2023

### Other Relevant Work Experience

#### George Washington University, Washington DC

##### Junior Thermals and Design Engineer, GW-CubeSat

Aug 2018 – May 2019

Cube satellite part of NASA's Cube Sat Launch Initiative (CSLI) developed in collaboration with MIT and TEC University of Costa Rica

- Created **SolidWorks** CAD models for the GW-CubeSat including the on-board camera, battery pack and the cube satellite chassis
- Identified components exceeding thermal limits around the battery pack and plasma thrusters using Ansys
- Developed 3D printed prototype of the complete CubeSat and assembled using **Makerbot 3D** printer

#### University of Mumbai, Mumbai, India

##### Team Leader, Hoverbolt 1.0 (Hovercraft)

Jun 2015 – Apr 2016

Self-funded project of ten senior-year mechanical engineers to design, analyze, procure, build and test a pilot driven hovercraft

- Calculated engine lift and thrust power requirements using Bernoulli's equation. **Negotiated and procured** engines and propellers
- Designed and conducted thermal and structural analysis in **Solidworks** of the hovercraft chassis, engine mounts, propeller mounts and steering column. **Machined** propeller shafts on-site using the **Lathe** and **Milling** machines
- Built a test-rig to calculate pressure distribution under the skirt and optimized for uniform cushion pressure