

PS#4: Calculus with space curves - Answer key

1. (AC Multi 9.7 Exercise 13) Compute the derivative of each of the following functions in two different ways: (1) use the rules provided in the theorem stated just after Activity 9.7.3, and (2) rewrite each given function so that it is stated as a single function (either a scalar function or a vector-valued function with three components), and differentiate component-wise. Compare your answers to ensure that they are the same.

(a) $\mathbf{r}(t) = \sin(t)\langle 2t, t^2, \arctan(t) \rangle$

Using the scalar product rule:

$$\begin{aligned}\frac{d\mathbf{r}}{dt} &= \left(\frac{d}{dt} \sin(t) \right) \langle 2t, t^2, \arctan(t) \rangle + \sin(t) \left(\frac{d}{dt} \langle 2t, t^2, \arctan(t) \rangle \right) \\ &= \cos(t) \langle 2t, t^2, \arctan(t) \rangle + \sin(t) \left\langle 2, 2t, \frac{1}{1+t^2} \right\rangle \\ &= \left\langle 2t \cos(t) + 2 \sin(t), t^2 \cos(t) + 2t \sin(t), \arctan(t) \cos(t) + \frac{\sin(t)}{1+t^2} \right\rangle\end{aligned}$$

And rewriting first:

$$\mathbf{r}(t) = \langle 2t \sin(t), t^2 \sin(t), \arctan(t) \sin(t) \rangle$$

$$\begin{aligned}\frac{d\mathbf{r}}{dt} &= \left\langle \left(\frac{d}{dt} 2t \right) \sin(t) + 2t \left(\frac{d}{dt} \sin(t) \right), \left(\frac{d}{dt} t^2 \right) \sin(t) + t^2 \left(\frac{d}{dt} \sin(t) \right), \left(\frac{d}{dt} \arctan(t) \right) \sin(t) + \arctan(t) \left(\frac{d}{dt} \sin(t) \right) \right\rangle \\ &= \left\langle 2t \cos(t) + 2 \sin(t), t^2 \cos(t) + 2t \sin(t), \frac{\sin(t)}{1+t^2} + \arctan(t) \cos(t) \right\rangle\end{aligned}$$

(b) $\mathbf{s}(t) = \mathbf{r}(2^t)$, where $\mathbf{r}(t) = \langle t+2, \ln(t), 1 \rangle$ – Note that $\mathbf{r}'(t) = \langle 1, \frac{1}{t}, 0 \rangle$

Using the chain rule first:

$$\begin{aligned}\mathbf{s}'(t) &= \mathbf{r}'(2^t) \frac{d}{dt} 2^t \\ &= \left\langle 1, \frac{1}{2^t}, 0 \right\rangle 2^t \ln(2) \\ &= \langle 2^t \ln(2), \ln(2), 0 \rangle\end{aligned}$$

And simplifying first:

$$\begin{aligned}\mathbf{s}(t) &= \mathbf{r}(2^t) = \langle 2^t + 2, \ln(2^t), 1 \rangle = \langle 2^t + 2, t \ln(2), 1 \rangle \\ \mathbf{s}'(t) &= \langle 2^t \ln(2), \ln(2), 0 \rangle\end{aligned}$$

(c) $\mathbf{r}(t) = \langle \cos(t), \sin(t), t \rangle \cdot \langle -\sin(t), \cos(t), 1 \rangle$

Using the dot product rule:

$$\begin{aligned}r'(t) &= \left(\frac{d}{dt} \langle \cos(t), \sin(t), t \rangle \right) \cdot \langle -\sin(t), \cos(t), 1 \rangle + \langle \cos(t), \sin(t), t \rangle \cdot \left(\frac{d}{dt} \langle -\sin(t), \cos(t), 1 \rangle \right) \\ &= \langle -\sin(t), \cos(t), 1 \rangle \cdot \langle -\sin(t), \cos(t), 1 \rangle + \langle \cos(t), \sin(t), t \rangle \cdot \langle -\cos(t), -\sin(t), 0 \rangle \\ &= [\sin^2(t) + \cos^2(t) + 1] + [-\cos^2(t) - \sin^2(t) + 0] = 1 + 1 - 1 + 0 = 1 (!!)\end{aligned}$$

And rewriting first:

$$\begin{aligned}r(t) &= \cos(t) \cdot (-\sin(t)) + \sin(t) \cdot \cos(t) + t \cdot 1 \\ r(t) &= t (!!)\end{aligned}$$

$$r'(t) = 1$$

(d) $\mathbf{r}(t) = \langle \cos(t), \sin(t), t \rangle \times \langle -\sin(t), \cos(t), 1 \rangle$

Using the cross product rule:

$$\begin{aligned}\mathbf{r}'(t) &= \left(\frac{d}{dt} \langle \cos(t), \sin(t), t \rangle \right) \times \langle -\sin(t), \cos(t), 1 \rangle + \langle \cos(t), \sin(t), t \rangle \times \left(\frac{d}{dt} \langle -\sin(t), \cos(t), 1 \rangle \right) \\ &= \langle -\sin(t), \cos(t), 1 \rangle \times \langle -\sin(t), \cos(t), 1 \rangle + \langle \cos(t), \sin(t), t \rangle \times \langle -\cos(t), -\sin(t), 0 \rangle\end{aligned}$$

The first two vectors are parallel, so their cross product is $\mathbf{0}$.

$$= \mathbf{0} + \langle \cos(t), \sin(t), t \rangle \times \langle -\cos(t), -\sin(t), 0 \rangle = \langle t \sin(t), -t \cos(t), 0 \rangle \quad (\text{Thanks, WA!})$$

And finding the cross product first:

$$\begin{aligned}\mathbf{r}(t) &= \langle \sin(t) - t \cos(t), -t \sin(t) - \cos(t), \sin^2(t) + \cos^2(t) \rangle = \langle \sin(t) - t \cos(t), -t \sin(t) - \cos(t), 1 \rangle \\ \mathbf{r}'(t) &= \frac{d}{dt} \langle \sin(t) - t \cos(t), -t \sin(t) - \cos(t), 1 \rangle \\ &= \langle \cos(t) - (1 \cos(t) + t(-\sin(t))), -(1 \sin(t) + t \cos(t)) - (-\sin(t)), 0 \rangle \\ &= \langle t \sin(t), -t \cos(t), 0 \rangle\end{aligned}$$

2. (AC Multi 9.7 Exercise 18) A central force is one that acts on an object so that the force \mathbf{F} is parallel to the object's position \mathbf{r} . Since Newton's Second Law says that an object's acceleration is proportional to the force exerted on it, the acceleration \mathbf{a} of an object moving under a central force will be parallel to its position \mathbf{r} . For instance, the Earth's acceleration due to the gravitational force that the sun exerts on the Earth is parallel to the Earth's position vector (see figure in the textbook).

- (a) If an object of mass m is moving under a central force, the angular momentum vector is defined to be $\mathbf{L} = m\mathbf{r} \times \mathbf{v}$. Assuming the mass is constant, show that the angular momentum is constant by showing that $\frac{d\mathbf{L}}{dt} = \mathbf{0}$.

Some stuff to keep track of:

- m is a constant scalar;
- \mathbf{r} is a variable vector (depends on t);
- \mathbf{v} is a variable vector (depends on t).

Seems like the natural thing to do is to use the product rule to compute $\frac{d\mathbf{L}}{dt}$:

$$\frac{d\mathbf{L}}{dt} = \frac{d}{dt} [m\mathbf{r} \times \mathbf{v}] = \frac{d}{dt} [m\mathbf{r}] \times \mathbf{v} + m\mathbf{r} \times \frac{d}{dt} [\mathbf{v}]$$

Well, the derivative of position is velocity, and the derivative of velocity is acceleration:

$$= [m\mathbf{v}] \times \mathbf{v} + m\mathbf{r} \times \mathbf{a}$$

Now we're getting somewhere. Remember that the cross product of two parallel vectors is $\mathbf{0}$. $m\mathbf{v}$ is certainly parallel to \mathbf{v} , and we're assuming in the context of the problem that \mathbf{a} is parallel to \mathbf{r} , so it's also parallel to $m\mathbf{r}$.

$$= \mathbf{0} + \mathbf{0} = \mathbf{0}.$$

Cool, so that tells us that \mathbf{L} is a constant vector.

- (b) Explain why $\mathbf{L} \cdot \mathbf{r} = 0$.

\mathbf{L} was defined as the cross product of $m\mathbf{r}$ and \mathbf{v} , so it's perpendicular to both of those. Since m is a scalar, $m\mathbf{r}$ points in the same direction as \mathbf{r} , so if \mathbf{L} is perpendicular to $m\mathbf{r}$, it's also perpendicular to \mathbf{r} . Therefore, their dot product is zero.

- (c) Explain why we may conclude that the object is constrained to lie in the plane passing through the origin and perpendicular to \mathbf{L} .

The equation $\mathbf{L} \cdot \mathbf{r} = 0$ reminds me of the vector equation of a plane, with \mathbf{L} as the (constant) normal vector and \mathbf{r} playing the role of $\overrightarrow{PP_0}$. Since \mathbf{r} 's initial point is the origin, we thus have the plane that's perpendicular to \mathbf{L} and passing through the origin.

(Another way to see this: Certainly all the position vectors are perpendicular to \mathbf{L} . Also, certainly all the position vectors emanate from the origin. Also, we've just found that \mathbf{L} is constant. So the only way this is going to happen is if all the position vectors lie in the **same** plane – specifically, the plane containing the origin and perpendicular to the constant vector \mathbf{L} .)

3. (AC Multi 9.8 Exercise 14) Consider the standard helix parameterized by $\mathbf{r}(t) = \cos(t)\mathbf{i} + \sin(t)\mathbf{j} + t\mathbf{k}$.

- Recall that the unit tangent vector $\mathbf{T}(t)$ is the vector tangent to the curve at time t that points in the direction of motion and has length 1. Find $\mathbf{T}(t)$.
- Explain why the fact that $|\mathbf{T}(t)| = 1$ implies that \mathbf{T} and \mathbf{T}' are orthogonal vectors for every value of t .
- For the given function \mathbf{r} with unit tangent vector $\mathbf{T}(t)$ (from part (a)), determine $\mathbf{N}(t) = \frac{1}{|\mathbf{T}'(t)|} \mathbf{T}'(t)$.
- What geometric properties does $\mathbf{N}(t)$ have? How long is this vector, and how is it situated in comparison to $\mathbf{T}(t)$?
- Let $\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$, and compute $\mathbf{B}(t)$ in terms of your results in (a) and (c).
- What geometric properties does $\mathbf{B}(t)$ have? How long is this vector, and how is it situated in comparison to $\mathbf{T}(t)$ and $\mathbf{N}(t)$?
- Sketch a plot of the given helix, and compute and sketch $\mathbf{T}\left(\frac{\pi}{2}\right)$, $\mathbf{N}\left(\frac{\pi}{2}\right)$, and $\mathbf{B}\left(\frac{\pi}{2}\right)$.